PROJECT.

Name: Zeel Patel

Student number: 400443666

```
import pandas as pd
import os
file name = "Food Delivery Time Prediction Case Study.xlsx"
directory_path = "/Users/apple/Desktop/DATASCI FINAL PROJECT/"
file path = os.path.join(directory path, file name)
# Load the dataset into a pandas DataFrame
df = pd.read excel(file path)
# Display the first few rows of the DataFrame
df.head(11)
      ID Delivery_person_ID
                              Delivery_person_Age
Delivery_person_Ratings \
             INDORES13DEL02
    4607
                                               37
4.9
             BANGRES18DEL02
1
    B379
                                               34
4.5
2
    5D6D
             BANGRES19DEL01
                                               23
4.4
3
                                               38
   7A6A
            COIMBRES13DEL02
4.7
4
    70A2
             CHENRES12DEL01
                                               32
4.6
5
    9BB4
              HYDRES09DEL03
                                               22
4.8
           RANCHIRES15DEL01
                                               33
6
    95B4
4.7
7
              MYSRES15DEL02
    9EB2
                                               35
4.6
8
    1102
              HYDRES05DEL02
                                               22
4.8
9
    CDCD
              DEHRES17DEL01
                                               36
4.2
              KOCRES16DEL01
                                               21
10 D987
4.7
    Restaurant_latitude Restaurant longitude
Delivery location latitude \
              22.\overline{7}45049
                                     75.892471
22.765049
```

.3.043041	12.913041	77.683237	
	12.914264	77.678400	
2.924264	11.003669	76.976494	
1.053669	12.972793	80.249982	
.3.012793	17.431668	78.408321	
17.461668 5	23.369746	85.339820	
3.479746	12.352058	76.606650	
2.482058	17.433809	78.386744	
7.563809			
0.397968	30.327968	78.046106	
0 0.043064	10.003064	76.307589	
	location_longitude	Type_of_order	Type_of_vehicle
ime_taken(mi	n) 75.912471	Snack	motorcycle
4	77.813237	Snack	scooter
3	77.688400	Drinks	motorcycle
6	77.026494		motorcycle
1	80.289982		scooter
0			
6	78.438321		motorcycle
0	85.449820		scooter
2	76.736650	Meal	motorcycle
4	78.516744	Buffet	motorcycle
	78.116106	Snack	motorcycle
6 9	76.347589	Meal	motorcycle
tdroning uppo	coccary columns		
	<i>cessary columns.</i> ['ID', 'Delivery_p	erson_ID'], axi	is= <mark>1</mark>)

```
from sklearn.preprocessing import OneHotEncoder
encoder = OneHotEncoder(drop='if binary')
encoded features = encoder.fit transform(df[['Type of order',
'Type of vehicle']])
# Convert the encoded features into a DataFrame
encoded df = pd.DataFrame(encoded features.toarray(),
columns=encoder.get_feature_names_out(['Type_of_order',
'Type of vehicle']))
df = pd.concat([df, encoded df], axis=1)
# Drop the original categorical columns
df = df.drop(['Type of order', 'Type of vehicle'], axis=1)
#Getting an idea of the shape fo the dataset
print("Shape of DataFrame:", df.shape)
df.head(11)
Shape of DataFrame: (45593, 15)
    Delivery person Age Delivery person Ratings Restaurant latitude
/
0
                     37
                                              4.9
                                                              22.745049
                     34
                                                              12.913041
1
                                              4.5
2
                     23
                                              4.4
                                                              12.914264
3
                     38
                                              4.7
                                                              11.003669
                     32
                                              4.6
                                                              12.972793
                     22
5
                                              4.8
                                                              17.431668
                                              4.7
6
                     33
                                                              23.369746
                     35
                                              4.6
                                                              12.352058
                     22
                                              4.8
8
                                                              17,433809
9
                     36
                                              4.2
                                                              30.327968
                                              4.7
10
                     21
                                                              10.003064
                          Delivery_location_latitude \
    Restaurant_longitude
0
               75.892471
                                            22.765049
1
               77.683237
                                            13.043041
```

2 77.678 3 76.976 4 80.249 5 78.408 6 85.339 7 76.606 8 78.386 9 78.046 10 76.307	5494 9982 3321 9820 5650 5744 5106	12.9242 11.0536 13.0127 17.4616 23.4797 12.4826 17.5638 30.3979	569 793 568 746 958 309
Delivery location	longitude Time	taken(min)	Type_of_order_Buffet
\			,
0 0.0	75.912471	24	
1	77.813237	33	
0.0	77.688400	26	
0.0	77.000400	20	
3	77.026494	21	
1.0	80.289982	30	
0.0			
5 1.0	78.438321	26	
6	85.449820	40	
0.0 7	76.736650	32	
0.0	70.730030	32	
8	78.516744	34	
1.0	78.116106	46	
0.0		22	
10 0.0	76.347589	23	
Type_of_order_Dri Type_of_order_Snack	.nks Type_of_ord \	der_Meal	
0	0.0	0.0	1.0
1	0.0	0.0	1.0
2	1.0	0.0	0.0
3	0.0	0.0	0.0
4	0.0	0.0	1.0
5	0.0	0.0	0.0
6	0.0	1.0	0.0
U	0.0	1.0	U.U

7	0.0	1.0	0.0
8	0.0	0.0	0.0
9	0.0	0.0	1.0
10	0.0	1.0	0.0
10	0.0	-10	0.0
Type_of_0 1 2 3 4 5 6 7 8 9 10	_vehicle_bicycle Ty 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.	pe_of_vehicle_electric_scoot	ter \ 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.
0 1 2 3 4 5 6 7 8 9	vehicle_motorcycle 1.0 0.0 1.0 1.0 0.0 1.0 1.0 1.0 1.0 1.0	Type_of_vehicle_scooter 0.0 1.0 0.0 0.0 1.0 0.0 1.0 0.0 0.0 0.0	
#Finding the df.describe	e basic statistics of	the dataset	
Delix Restaurant_l count 45593.000000	latitude \ 45593.000000	very_person_Ratings 45593.000000	
mean 17.017729	29.544075	4.632367	
std 8.185109	5.696793	0.327708	
min 30.905562	15.000000	1.000000	-
25%	25.000000	4.600000	

12.9332				-
50%	29.000000		4.700000	9
18.5469 75%	34.000000		4.80000	1
22.7281			7100000	,
max	50.000000		6.000000	9
30.9140	57			
	Restaurant longitud	o Dolive	ery_location_lat:	itude \
count	45593.00000		45593.00	
mean	70.23133			55186
std	22.88364			35122
min	-88.36621			10000
25% 50%	73.17000 75.89849			38453 33934
75%	78.04409			35049
max	88.43345			54057
			-	
	<pre>Delivery_location_l order Buffet \</pre>	ongitude	Time_taken(min)	
count		3.000000	45593.000000)
45593.0		3.00000	15555100000	
mean		0.845702	26.294607	7
0.24740		1 110010	0. 20200	-
std 0.43151		1.118812	9.383806)
0.43131 min		0.010000	10.00000)
0.00000				
25%		3.280000	19.000000	9
0.00000		6.002574	26 00000	
50% 0.00000		0.002574	26.00000	י
75%		8.107044	32.000000	9
0.00000				
max		8.563452	54.000000	Ð
1.00000	Θ			
	Type of order Drink	s Type	of_order_Meal	Type of order Snack
\	,	_		·
count	45593.0000	00	45593.000000	
45593.0 mean	0.2483	70	0.251311	
0.25295		20	0.231311	
std	0.4320	48	0.433771	
0.43471				
min	0.0000	00	0.000000	
0.00000 25%		00	0 00000	
0.00000	0.0000	00	0.00000	
50%	0.0000	00	0.000000	

```
0.000000
                     0.000000
                                           1.000000
75%
1.000000
                     1.000000
                                           1.000000
max
1.000000
       Type_of_vehicle_bicycle
                                  Type_of_vehicle_electric_scooter
                    45593.000000
count
                                                         45593.000000
                        0.001491
                                                             0.083653
mean
                        0.038591
std
                                                             0.276870
min
                        0.000000
                                                             0.000000
25%
                        0.000000
                                                             0.000000
50%
                        0.000000
                                                             0.000000
75%
                        0.000000
                                                             0.000000
max
                        1.000000
                                                             1.000000
       Type of vehicle motorcycle
                                      Type of vehicle scooter
                       45593.000000
                                                  45593.000000
count
                                                       0.335051
mean
                           0.579804
                           0.493596
                                                       0.472014
std
min
                           0.000000
                                                       0.00000
25%
                           0.000000
                                                       0.000000
50%
                           1.000000
                                                       0.000000
75%
                           1.000000
                                                       1.000000
                           1.000000
                                                       1.000000
max
#checking for null values
df.isnull().sum()
Delivery person Age
                                       0
Delivery_person Ratings
                                       0
Restaurant latitude
                                       0
Restaurant_longitude
                                       0
Delivery location latitude
                                       0
Delivery_location_longitude
                                       0
Time taken(min)
                                       0
Type of order Buffet
                                       0
Type_of_order_Drinks
                                       0
                                       0
Type_of order Meal
Type_of_order_Snack
                                       0
Type of vehicle bicycle
                                       0
Type of vehicle electric scooter
                                       0
Type of vehicle motorcycle
                                       0
Type of vehicle scooter
                                       0
dtype: int64
# Import necessary libraries
from geopy.distance import geodesic
import pandas as pd
```

```
# EDA: for deriving the distance, we use Vincenty Formula.
# Define function to calculate distance between two points in miles
def get distance(row):
    point1 = (row['Restaurant latitude'], row['Restaurant longitude'])
    point2 = (row['Delivery location latitude'],
row['Delivery_location_longitude'])
    return geodesic(point1, point2).miles
# Calculate distance for all points and store in a new column
'Distance miles'
df['Distance miles'] = df.apply(get distance, axis=1)
# Display the first few rows of the DataFrame with the Distance miles
column
print(df.head())
   Delivery person Age Delivery person Ratings
Restaurant_latitude
                    37
                                             4.9
                                                             22.745049
                                             4.5
1
                    34
                                                             12.913041
2
                    23
                                             4.4
                                                             12.914264
3
                    38
                                             4.7
                                                             11.003669
                    32
                                             4.6
                                                             12.972793
   Restaurant_longitude
                         Delivery_location_latitude \
0
              75.892471
                                           22.765049
              77.683237
                                           13.043041
1
2
              77,678400
                                           12.924264
3
              76.976494
                                           11.053669
4
              80.249982
                                           13.012793
   Delivery location longitude Time taken(min) Type of order Buffet
                                                                     0.0
0
                     75.912471
                                              24
1
                     77.813237
                                              33
                                                                     0.0
                                                                     0.0
2
                     77,688400
                                              26
3
                     77.026494
                                              21
                                                                     1.0
                                              30
                                                                     0.0
                     80.289982
   Type of order Drinks
                          Type of order Meal
                                                Type of order Snack \
0
                     0.0
                                           0.0
                                                                  1.0
```

1 2 3 4	0.0 1.0 0.0 0.0	0.0 0.0 0.0 0.0	1.0 0.0 0.0 1.0
7	0.0	0.0	1.0
Type_of_ 0 1 2 3	vehicle_bicycle 0.0 0.0 0.0 0.0 0.0	Type_of_vehicle_elec	tric_scooter \
Type_of_ Distance_mi	_vehicle_motorcycl les	e Type_of_vehicle_s	cooter
0	1	.0	0.0
1.876999 1	0	.0	1.0
12.516738	1	0	0.0
2 0.962935	1	. 0	0.0
3 4.830848	1	.0	0.0
4.030040	0	.0	1.0
3.851195			
#observe th df.head(11)		the distance_miles co	lumn
df.head(11) Deliver		the distance_miles co ivery_person_Ratings	
df.head(11)		_	
<pre>df.head(11) Deliver \</pre>	ry_person_Age Del	ivery_person_Ratings	Restaurant_latitude
<pre>df.head(11) Deliver \ 0</pre>	ry_person_Age Del 37	ivery_person_Ratings 4.9	Restaurant_latitude 22.745049
<pre>df.head(11) Deliver \ 0 1</pre>	ry_person_Age Del 37 34	ivery_person_Ratings 4.9 4.5	Restaurant_latitude 22.745049 12.913041
<pre>df.head(11) Deliver \ 0 1 2</pre>	ry_person_Age Del 37 34 23	ivery_person_Ratings 4.9 4.5 4.4	Restaurant_latitude 22.745049 12.913041 12.914264
<pre>df.head(11) Deliver \ 0 1 2 3</pre>	ry_person_Age Del. 37 34 23 38	ivery_person_Ratings 4.9 4.5 4.4 4.7	Restaurant_latitude 22.745049 12.913041 12.914264 11.003669
<pre>df.head(11) Deliver 0 1 2 3 4</pre>	ry_person_Age Del. 37 34 23 38 32	ivery_person_Ratings 4.9 4.5 4.4 4.7 4.6	Restaurant_latitude 22.745049 12.913041 12.914264 11.003669 12.972793
<pre>df.head(11) Deliver 0 1 2 3 4 5</pre>	ry_person_Age Del. 37 34 23 38 32 22	ivery_person_Ratings 4.9 4.5 4.4 4.7 4.6 4.8	Restaurant_latitude 22.745049 12.913041 12.914264 11.003669 12.972793 17.431668
df.head(11) Deliver 0 1 2 3 4 5	ry_person_Age Del. 37 34 23 38 32 22 33	ivery_person_Ratings 4.9 4.5 4.4 4.7 4.6 4.8	Restaurant_latitude 22.745049 12.913041 12.914264 11.003669 12.972793 17.431668 23.369746
<pre>df.head(11) Deliver 0 1 2 3 4 5 6 7</pre>	ry_person_Age Del. 37 34 23 38 32 22 33 35	ivery_person_Ratings 4.9 4.5 4.4 4.7 4.6 4.8 4.7 4.6	Restaurant_latitude 22.745049 12.913041 12.914264 11.003669 12.972793 17.431668 23.369746 12.352058

0 1 2	Restaurant_longitude 75.892471 77.683237 77.678400	Delivery_loc	22.765049 13.043041 12.924264	\
0 1 2 3 4 5 6 7	76.976494 80.249982 78.408321		11.053669 13.012793 17.461668	
8	85.339820 76.606650 78.386744		23.479746 12.482058 17.563809	
9 10	78.046106 76.307589		30.397968 10.043064	
\	Delivery_location_lor	ngitude Time_	taken(min) Typ	e_of_order_Buffet
0	75.	912471	24	
0.0		813237	33	
0.0		688400	26	
0.0	77 .	026494	21	
1.0	80.	289982	30	
0.0	78.	438321	26	
1.0	85.	449820	40	
0.0	76.	736650	32	
0.0	78.	516744	34	
1.0		116106	46	
0.0		347589	23	
0.0	Type of order Drinks	Type_of_ord	Jor Mool	
	e_of_order_Snack \			1.0
0	0.6		0.0	1.0
1	0.6		0.0	1.0
2	1.6)	0.0	0.0
3	0.0)	0.0	0.0

4	0.0	0.0	1.0
5	0.0	0.0	0.0
6	0.0	1.0	0.0
7	0.0	1.0	0.0
8	0.0	0.0	0.0
9	0.0	0.0	1.0
10	0.0	1.0	0.0
Type_of_vehicle_0 1 2 3 4 5 6 7 8 9 10 Type_of_vehicle_Distance_miles	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	_vehicle_electric_s _of_vehicle_scooter	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
0	1.0	0.	Θ
1.876999 1	0.0	1.0	0
12.516738 2	1.0	0.0	
0.962935			
3 4.830848	1.0	0.0	Θ
4 3.851195	0.0	1.	0
5	1.0	0.	Θ
2.859678 6	0.0	1.0	Θ
10.300400 7	1.0	0.0	
12.529942			
8 12.390278	1.0	0.0	Θ
9 6.382392	1.0	0.	0

```
10
                           1.0
                                                    0.0
3.870755
from sklearn.preprocessing import MinMaxScaler
# Define the columns to scale
'Delivery location latitude',
'Delivery_location_longitude',
                   'Distance miles', 'Time taken(min)']
# Initialize the MinMaxScaler
scaler = MinMaxScaler()
# Fit and transform the data
df scaled = df.copy()
df_scaled[columns_to_scale] =
scaler.fit_transform(df_scaled[columns_to_scale])
df scaled.head(11)
   Delivery person Age Delivery person Ratings Restaurant latitude
/
0
              0.628571
                                          0.78
                                                           0.867857
1
              0.542857
                                          0.70
                                                           0.708814
2
              0.228571
                                          0.68
                                                           0.708834
3
              0.657143
                                          0.74
                                                           0.677928
              0.485714
                                          0.72
                                                           0.709780
                                          0.76
5
              0.200000
                                                           0.781908
                                          0.74
                                                           0.877963
6
              0.514286
              0.571429
                                          0.72
                                                           0.699739
8
              0.200000
                                          0.76
                                                           0.781942
9
              0.600000
                                          0.64
                                                           0.990519
10
              0.171429
                                          0.74
                                                           0.661742
                         Delivery_location_latitude \
   Restaurant_longitude
0
               0.929067
                                          0.732992
               0.939196
                                          0.419824
1
2
               0.939168
                                          0.415998
```

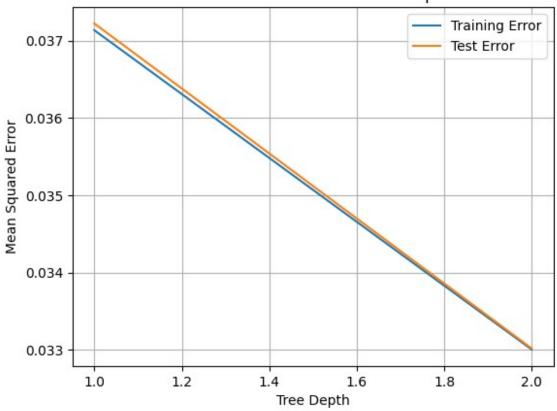
4 6 6 6 7 8 9 6 9	0.935198 0.953713 0.943297 0.982502 0.933106 0.943175 0.941248 0.931415	0.355 0.418 0.562 0.756 0.401 0.565 0.978 0.323	850 158 014 753 448 866
Delivery_loca	ation_longitude	Time_taken(min)	Type_of_order_Buffet
0	0.857137	0.318182	
0.0	0.878602	0.522727	
0.0	0.877192	0.363636	
0.0	0.869718	0.250000	
1.0	0.906571	0.454545	
0.0 5	0.885661	0.363636	
1.0			
6 0.0	0.964839	0.681818	
7 0.0	0.866444	0.500000	
8 1.0	0.886546	0.545455	
9	0.882022	0.818182	
10	0.862051	0.295455	
0.0			
Type_of_order Type_of_order_Sna	ack \	of_order_Meal	
0	0.0	0.0	1.0
1	0.0	0.0	1.0
2	1.0	0.0	0.0
3	0.0	0.0	0.0
4	0.0	0.0	1.0
5	0.0	0.0	0.0
6	0.0	1.0	0.0

7	0.0	1.0	0.0
8	0.0	0.0	0.0
9	0.0	0.0	1.0
10	0.0	1.0	0.0
Type_of_vehicle_b 1 2 3 4 5 6 7 8 9 10 Type_of_vehicle_m Distance_miles 0	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	cle_electric_scoot vehicle_scooter 0.0	er \ 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.
0.000079 1	0.0	1.0	
0.000948 2	1.0	0.0	
0.000004 3	1.0	0.0	
0.000320 4	0.0	1.0	
0.000240 5	1.0	0.0	
0.000159 6	0.0	1.0	
0.000767			
7 0.000949	1.0	0.0	
8 0.000938	1.0	0.0	
9 0.000447	1.0	0.0	
10 0.000242	1.0	0.0	
	election import train_	test solit	
_		_	
# Spill the data into	features (X) and tar	get variable (y)	

```
X = df_scaled.drop('Time_taken(min)', axis=1) # Features
y = df scaled['Time taken(min)'] # Target variable
# Split the data into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.3, random state=42)
#base model for dt and qb
import pandas as pd
import numpy as np
from sklearn.metrics import mean squared error, mean absolute error
def model_01(model, X_train, y_train, X_test, y_test):
    # Let's calculate some metric MSE
    ypredict train = model.predict(X train)
    ypredict test = model.predict(X test)
    metric = []
    # Mean Squared Error (MSE)
    mse train = mean squared error(y train, ypredict train)
    mse_test = mean_squared_error(y_test, ypredict_test)
    # Create a DataFrame to store the metrics
    df = pd.DataFrame({
        'Metric': ['MSE (Mean Squared Error)'],
        'Train': [mse train],
        'Test': [mse test]
    })
    return df, ypredict train, ypredict test
#decision tree (1,3)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.tree import DecisionTreeRegressor
from sklearn.metrics import mean squared error
dt model = DecisionTreeRegressor()
dt model.fit(X train, y train)
metric df dt, ypredict train dt, ypredict test dt = model 01(dt model,
X train, y train, X test, y test)
print("Decision Tree Model:")
print(metric df dt)
depths = range(1,3) # Adjust the range of depths as needed
train errors = [mean squared error(y train,
DecisionTreeRegressor(max depth=depth, random state=42).fit(X train,
```

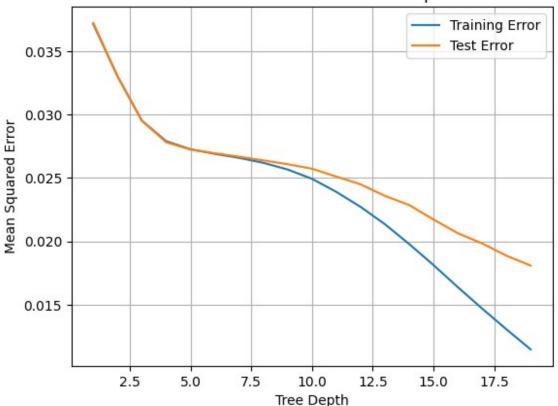
```
y train).predict(X train)) for depth in depths]
test errors = [mean squared error(y test,
DecisionTreeRegressor(max depth=depth, random state=42).fit(X train,
y_train).predict(X_test)) for depth in depths]
plt.plot(depths, train_errors, label='Training Error')
plt.plot(depths, test_errors, label='Test Error')
plt.xlabel('Tree Depth')
plt.ylabel('Mean Squared Error')
plt.title('Model Performance vs. Tree Depth')
plt.legend()
plt.grid(True)
plt.show()
# Find the depths with the lowest training and test errors
best train depth = depths[np.argmin(train errors)]
best test depth = depths[np.argmin(test errors)]
print(f"Best Depth for Training Error: {best train depth}")
print(f"Best Depth for Test Error: {best test depth}")
Decision Tree Model:
                     Metric
                                Train
                                           Test
0 MSE (Mean Squared Error)
                             0.000377
                                       0.011473
```





```
Best Depth for Training Error: 2
Best Depth for Test Error: 2
#decision tree (1,20)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.tree import DecisionTreeRegressor
from sklearn.metrics import mean squared error
dt model = DecisionTreeRegressor()
dt model.fit(X train, y train)
metric_df_dt, ypredict_train_dt, ypredict_test_dt = model_01(dt_model,
X train, y train, X test, y test)
print("Decision Tree Model:")
print(metric df dt)
depths = range(1,20) # Adjust the range of depths as needed
train errors = [mean squared error(y train,
DecisionTreeRegressor(max_depth=depth, random_state=42).fit(X_train,
y train).predict(X train)) for depth in depths]
test errors = [mean squared error(v test,
DecisionTreeRegressor(max depth=depth, random state=42).fit(X train,
y train).predict(X test)) for depth in depths]
plt.plot(depths, train errors, label='Training Error')
plt.plot(depths, test errors, label='Test Error')
plt.xlabel('Tree Depth')
plt.ylabel('Mean Squared Error')
plt.title('Model Performance vs. Tree Depth')
plt.legend()
plt.grid(True)
plt.show()
# Find the depths with the lowest training and test errors
best train depth = depths[np.argmin(train errors)]
best test depth = depths[np.argmin(test errors)]
print(f"Best Depth for Training Error: {best train depth}")
print(f"Best Depth for Test Error: {best test depth}")
Decision Tree Model:
                     Metric
                                Train
                                           Test
  MSE (Mean Squared Error)
                             0.000377 0.011454
```

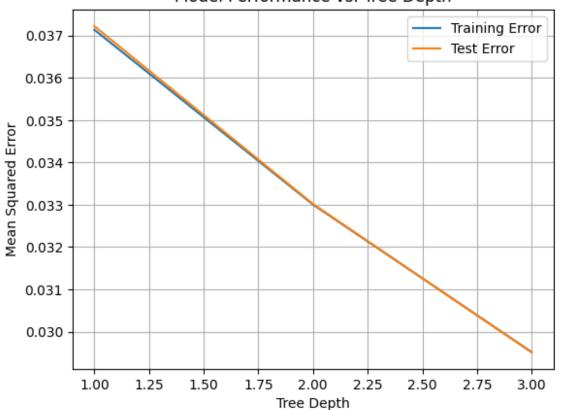




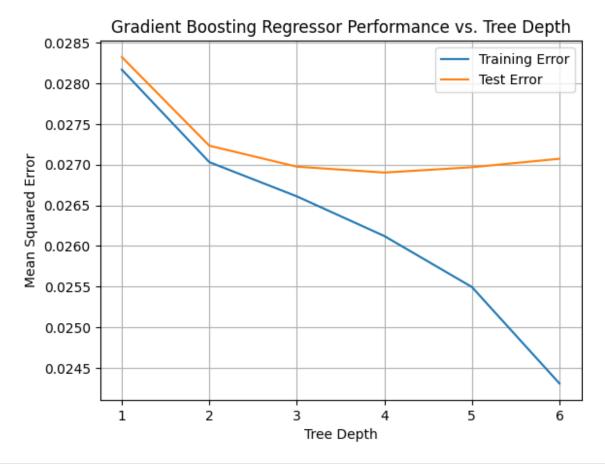
```
Best Depth for Training Error: 19
Best Depth for Test Error: 19
#decision tree (1,4)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.tree import DecisionTreeRegressor
from sklearn.metrics import mean_squared_error
dt model = DecisionTreeRegressor()
dt model.fit(X train, y train)
metric df dt, ypredict train dt, ypredict test dt = model 01(dt model,
X train, y train, X test, y test)
print("Decision Tree Model:")
print(metric df dt)
depths = range(1,4) # Adjust the range of depths as needed
train_errors = [mean_squared_error(y_train,
DecisionTreeRegressor(max depth=depth, random state=42).fit(X train,
y train).predict(X train)) for depth in depths]
test_errors = [mean_squared_error(y test,
```

```
DecisionTreeRegressor(max depth=depth, random state=42).fit(X train,
y train).predict(X test)) for depth in depths]
plt.plot(depths, train_errors, label='Training Error')
plt.plot(depths, test errors, label='Test Error')
plt.xlabel('Tree Depth')
plt.ylabel('Mean Squared Error')
plt.title('Model Performance vs. Tree Depth')
plt.legend()
plt.grid(True)
plt.show()
# Find the depths with the lowest training and test errors
best train depth = depths[np.argmin(train errors)]
best test depth = depths[np.argmin(test errors)]
print(f"Best Depth for Training Error: {best_train_depth}")
print(f"Best Depth for Test Error: {best test depth}")
Decision Tree Model:
                     Metric
                                Train
                                           Test
  MSE (Mean Squared Error)
                             0.000377
                                       0.011377
```



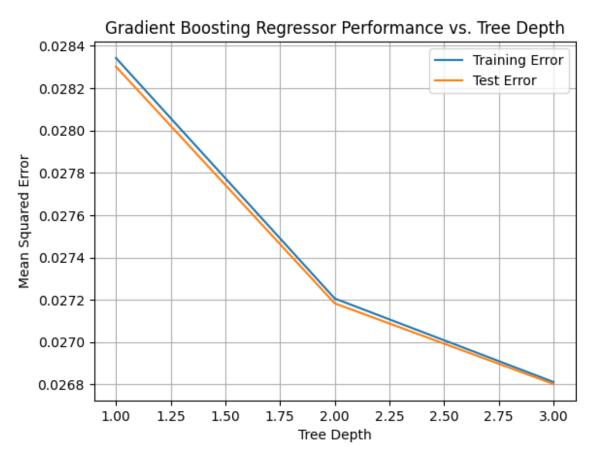


```
Best Depth for Training Error: 3
Best Depth for Test Error: 3
# Gradient boosting (1,7)
from sklearn.ensemble import GradientBoostingRegressor
from sklearn.metrics import mean squared error, mean absolute error
import numpy as np
ab model = GradientBoostingRegressor()
gb model.fit(X train, y train)
metric_df_gb, ypredict_train_gb, ypredict_test_gb = model 01(gb model,
X_train, y_train, X_test, y_test)
print("Gradient Boosting Model:")
print(metric df gb)
depths = range(1, 7) # Adjust the range of depths as needed
train errors = [mean squared error(y train,
GradientBoostingRegressor(max depth=depth).fit(X train,
y train).predict(X train)) for depth in depths]
test errors = [mean squared error(y test,
GradientBoostingRegressor(max depth=depth).fit(X train,
y train).predict(X test)) for depth in depths]
plt.plot(depths, train_errors, label='Training Error')
plt.plot(depths, test errors, label='Test Error')
plt.xlabel('Tree Depth')
plt.ylabel('Mean Squared Error')
plt.title('Gradient Boosting Regressor Performance vs. Tree Depth')
plt.legend()
plt.grid(True)
plt.show()
# Find the depths with the lowest training and test errors
best train depth = depths[np.argmin(train errors)]
best test depth = depths[np.argmin(test errors)]
print(f"Best Depth for Training Error: {best train depth}")
print(f"Best Depth for Test Error: {best test depth}")
Gradient Boosting Model:
                     Metric
                               Train
                                          Test
0 MSE (Mean Squared Error) 0.02661 0.026978
```



```
Best Depth for Training Error: 6
Best Depth for Test Error: 4
# Gradient boosting (1,4)
from sklearn.ensemble import GradientBoostingRegressor
from sklearn.metrics import mean squared error, mean absolute error
import numpy as np
gb model = GradientBoostingRegressor()
gb model.fit(X train, y train)
metric_df_gb, ypredict_train_gb, ypredict_test_gb = model_01(gb_model,
X train, y train, X test, y test)
print("Gradient Boosting Model:")
print(metric df gb)
depths = range(1, 4) # Adjust the range of depths as needed
train errors = [mean squared error(y train,
GradientBoostingRegressor(max depth=depth).fit(X train,
y train).predict(X train)) for depth in depths]
test errors = [mean squared error(y test,
GradientBoostingRegressor(max depth=depth).fit(X train,
```

```
y train).predict(X test)) for depth in depths]
plt.plot(depths, train errors, label='Training Error')
plt.plot(depths, test_errors, label='Test Error')
plt.xlabel('Tree Depth')
plt.ylabel('Mean Squared Error')
plt.title('Gradient Boosting Regressor Performance vs. Tree Depth')
plt.legend()
plt.grid(True)
plt.show()
# Find the depths with the lowest training and test errors
best train depth = depths[np.argmin(train errors)]
best test depth = depths[np.argmin(test errors)]
print(f"Best Depth for Training Error: {best train depth}")
print(f"Best Depth for Test Error: {best test depth}")
Gradient Boosting Model:
                                Train
                                           Test
  MSE (Mean Squared Error)
                             0.026812 0.026802
```



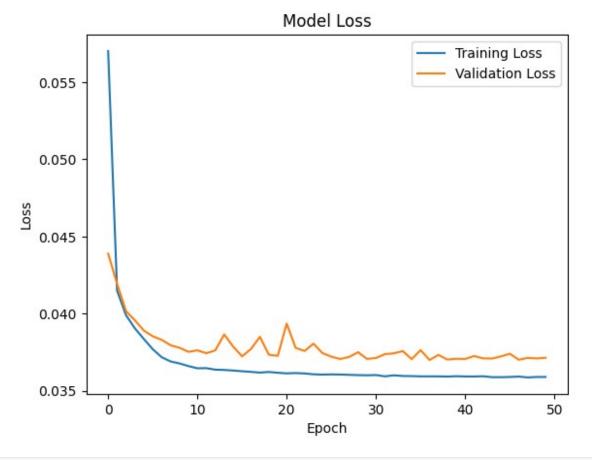
Best Depth for Training Error: 3
Best Depth for Test Error: 3

```
# Small neural network model
model 04 = Sequential([
    Dense(10, activation='relu', input shape=(X train.shape[1],)),
    Dense(1)
])
# Compile the model
model 04.compile(optimizer='rmsprop', loss='mean squared error')
# Train the model
history small model = model 04.fit(X train, y train, epochs=50,
batch size=128, validation split=0.2)
Epoch 1/50
228/228 -
                          -- 1s 2ms/step - loss: 0.0766 - val loss:
0.0439
Epoch 2/50
228/228 -
                            - 0s 1ms/step - loss: 0.0418 - val loss:
0.0419
Epoch 3/50
                            - 0s 1ms/step - loss: 0.0399 - val loss:
228/228 -
0.0402
Epoch 4/50
228/228 -
                            - 0s 2ms/step - loss: 0.0387 - val_loss:
0.0396
Epoch 5/50
228/228 -
                            - 0s 2ms/step - loss: 0.0390 - val_loss:
0.0389
Epoch 6/50
228/228 –
                            - 0s 1ms/step - loss: 0.0376 - val loss:
0.0385
Epoch 7/50
228/228 -
                           - 0s 2ms/step - loss: 0.0375 - val loss:
0.0383
Epoch 8/50
                            - 0s 1ms/step - loss: 0.0373 - val loss:
228/228 -
0.0380
Epoch 9/50
228/228 -
                            - 1s 2ms/step - loss: 0.0366 - val_loss:
0.0378
Epoch 10/50
228/228 -
                             Os 1ms/step - loss: 0.0368 - val loss:
0.0375
Epoch 11/50
228/228 –
                            - 0s 2ms/step - loss: 0.0370 - val loss:
0.0376
Epoch 12/50
                            - 0s 2ms/step - loss: 0.0364 - val loss:
228/228 -
0.0374
Epoch 13/50
```

```
228/228 -
                            - 1s 3ms/step - loss: 0.0365 - val loss:
0.0376
Epoch 14/50
228/228 -
                            Os 2ms/step - loss: 0.0362 - val loss:
0.0387
Epoch 15/50
                             Os 1ms/step - loss: 0.0362 - val loss:
228/228 -
0.0379
Epoch 16/50
228/228 -
                            - 1s 2ms/step - loss: 0.0357 - val loss:
0.0372
Epoch 17/50
228/228 -
                             1s 2ms/step - loss: 0.0360 - val loss:
0.0377
Epoch 18/50
                             Os 1ms/step - loss: 0.0364 - val loss:
228/228 -
0.0385
Epoch 19/50
                             Os 2ms/step - loss: 0.0362 - val loss:
228/228 -
0.0373
Epoch 20/50
228/228 -
                             Os 1ms/step - loss: 0.0361 - val loss:
0.0373
Epoch 21/50
                             Os 1ms/step - loss: 0.0360 - val loss:
228/228 —
0.0394
Epoch 22/50
                             Os 1ms/step - loss: 0.0360 - val loss:
228/228 —
0.0378
Epoch 23/50
                             Os 1ms/step - loss: 0.0359 - val loss:
228/228 —
0.0376
Epoch 24/50
228/228 -
                             Os 1ms/step - loss: 0.0361 - val loss:
0.0381
Epoch 25/50
228/228 —
                            Os 1ms/step - loss: 0.0364 - val loss:
0.0374
Epoch 26/50
228/228 -
                             Os 1ms/step - loss: 0.0360 - val loss:
0.0372
Epoch 27/50
                            - 0s 2ms/step - loss: 0.0362 - val_loss:
228/228 -
0.0371
Epoch 28/50
228/228 -
                             0s 1ms/step - loss: 0.0361 - val_loss:
0.0372
Epoch 29/50
228/228 -
                             Os 1ms/step - loss: 0.0355 - val loss:
```

```
0.0375
Epoch 30/50
228/228 —
                            - 1s 2ms/step - loss: 0.0359 - val loss:
0.0371
Epoch 31/50
228/228 -
                             Os 2ms/step - loss: 0.0364 - val loss:
0.0371
Epoch 32/50
228/228 -
                             Os 1ms/step - loss: 0.0355 - val loss:
0.0374
Epoch 33/50
228/228 -
                             0s 1ms/step - loss: 0.0362 - val_loss:
0.0374
Epoch 34/50
228/228 -
                            - 0s 2ms/step - loss: 0.0360 - val_loss:
0.0376
Epoch 35/50
228/228 —
                            - 0s 2ms/step - loss: 0.0364 - val loss:
0.0371
Epoch 36/50
                             Os 1ms/step - loss: 0.0367 - val loss:
228/228 -
0.0376
Epoch 37/50
228/228 -
                             Os 2ms/step - loss: 0.0357 - val loss:
0.0370
Epoch 38/50
228/228 -
                             Os 2ms/step - loss: 0.0359 - val_loss:
0.0373
Epoch 39/50
228/228 -
                            Os 2ms/step - loss: 0.0363 - val loss:
0.0370
Epoch 40/50
228/228 —
                             Os 1ms/step - loss: 0.0363 - val loss:
0.0371
Epoch 41/50
                            - 0s 1ms/step - loss: 0.0356 - val loss:
228/228 —
0.0371
Epoch 42/50
228/228 -
                             Os 1ms/step - loss: 0.0359 - val loss:
0.0373
Epoch 43/50
228/228 -
                            - 1s 2ms/step - loss: 0.0361 - val_loss:
0.0371
Epoch 44/50
                             Os 1ms/step - loss: 0.0351 - val_loss:
228/228 –
0.0371
Epoch 45/50
                            - 0s 1ms/step - loss: 0.0353 - val loss:
228/228 -
0.0372
```

```
Epoch 46/50
                          — 0s 1ms/step - loss: 0.0360 - val loss:
228/228 -
0.0374
Epoch 47/50
                           - 0s 2ms/step - loss: 0.0360 - val loss:
228/228 —
0.0370
Epoch 48/50
228/228 —
                           - 0s 2ms/step - loss: 0.0359 - val loss:
0.0371
Epoch 49/50
228/228 —
                           - 0s 1ms/step - loss: 0.0361 - val loss:
0.0371
Epoch 50/50
                           - 0s 2ms/step - loss: 0.0360 - val loss:
228/228 —
0.0371
import matplotlib.pyplot as plt
# Calculate test loss
test loss = model 04.evaluate(X test, y test)
print("Test Loss:", test loss)
# Calculate MSE for training data
mse train = mean squared error(y train, model 04.predict(X train))
print("Mean Squared Error (MSE) for training data:", mse_train)
# Calculate MSE for test data
mse_test = mean_squared_error(y_test, model_04.predict(X_test))
print("Mean Squared Error (MSE) for test data:", mse_test)
# Plot training loss
plt.plot(history small model.history['loss'], label='Training Loss')
# Plot validation loss
plt.plot(history small model.history['val loss'], label='Validation
Loss')
plt.title('Model Loss')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.legend()
plt.show()
                       ---- 0s 1ms/step - loss: 0.0360
428/428 —
Test Loss: 0.03607228398323059
1140/1140 ---
                              1s 981us/step
Mean Squared Error (MSE) for training data: 0.03607497909798289
428/428 —
                         0s 968us/step
Mean Squared Error (MSE) for test data: 0.03609767022159636
```



```
#neural network model
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense
from sklearn.metrics import mean squared error
from sklearn.metrics import mean absolute error
import numpy as np
num features = X train.shape[1]
# Define the model architecture
model 02 = Sequential([
    Dense(128, activation='relu', input_shape=(num_features,)),
    Dense(64, activation='relu'),
    Dense(1)
1)
# Compile the model
model 02.compile(optimizer='adam', loss='mean squared error')
# Train the model
history = model_02.fit(X_train, y_train,
```

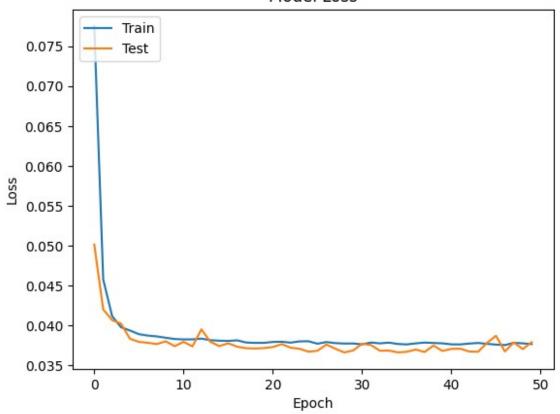
```
validation data=(X test, y test),
                    batch size=64,
                    epochs=50,
                    verbose=1.
                    shuffle=True)
2024-04-26 11:29:06.512277: I
tensorflow/core/platform/cpu feature guard.cc:210] This TensorFlow
binary is optimized to use available CPU instructions in performance-
critical operations.
To enable the following instructions: AVX2 FMA, in other operations,
rebuild TensorFlow with the appropriate compiler flags.
Epoch 1/50
/Library/Frameworks/Python.framework/Versions/3.12/lib/python3.12/
site-packages/keras/src/layers/core/dense.py:85: UserWarning: Do not
pass an `input shape`/`input dim` argument to a layer. When using
Sequential models, prefer using an `Input(shape)` object as the first
layer in the model instead.
  super(). init (activity regularizer=activity regularizer,
**kwarqs)
499/499 —
                        2s 2ms/step - loss: 0.0524 - val loss:
0.0375
Epoch 2/50
499/499 —
                          -- 1s 2ms/step - loss: 0.0369 - val loss:
0.0367
Epoch 3/50
                           - 1s 3ms/step - loss: 0.0376 - val loss:
499/499 -
0.0367
Epoch 4/50
                           — 1s 2ms/step - loss: 0.0366 - val loss:
499/499 -
0.0358
Epoch 5/50
                           - 1s 2ms/step - loss: 0.0355 - val loss:
499/499 -
0.0359
Epoch 6/50
499/499 -
                           — 1s 2ms/step - loss: 0.0362 - val loss:
0.0353
Epoch 7/50
499/499 —
                        --- 1s 2ms/step - loss: 0.0352 - val loss:
0.0352
Epoch 8/50
499/499 —
                           — 1s 2ms/step - loss: 0.0350 - val loss:
0.0348
Epoch 9/50
499/499 -
                         --- 1s 3ms/step - loss: 0.0346 - val loss:
0.0384
Epoch 10/50
```

```
499/499 -
                            - 2s 4ms/step - loss: 0.0353 - val loss:
0.0351
Epoch 11/50
499/499 -
                             1s 2ms/step - loss: 0.0343 - val loss:
0.0352
Epoch 12/50
499/499 -
                             1s 2ms/step - loss: 0.0344 - val loss:
0.0352
Epoch 13/50
499/499 -
                             1s 2ms/step - loss: 0.0346 - val loss:
0.0344
Epoch 14/50
499/499 —
                             1s 2ms/step - loss: 0.0343 - val loss:
0.0348
Epoch 15/50
499/499 -
                             1s 3ms/step - loss: 0.0344 - val loss:
0.0342
Epoch 16/50
                             1s 2ms/step - loss: 0.0343 - val loss:
499/499 -
0.0355
Epoch 17/50
499/499 -
                             1s 2ms/step - loss: 0.0342 - val loss:
0.0341
Epoch 18/50
                             1s 2ms/step - loss: 0.0338 - val loss:
499/499 -
0.0345
Epoch 19/50
499/499 —
                             1s 2ms/step - loss: 0.0338 - val loss:
0.0341
Epoch 20/50
                             1s 2ms/step - loss: 0.0343 - val loss:
499/499 —
0.0342
Epoch 21/50
499/499 -
                             1s 2ms/step - loss: 0.0334 - val loss:
0.0340
Epoch 22/50
499/499 —
                             1s 2ms/step - loss: 0.0338 - val loss:
0.0344
Epoch 23/50
                             1s 2ms/step - loss: 0.0341 - val loss:
499/499 -
0.0338
Epoch 24/50
499/499 -
                            - 1s 2ms/step - loss: 0.0338 - val_loss:
0.0336
Epoch 25/50
499/499 -
                             1s 2ms/step - loss: 0.0331 - val_loss:
0.0341
Epoch 26/50
499/499 -
                            - 1s 2ms/step - loss: 0.0330 - val loss:
```

```
0.0340
Epoch 27/50
499/499 —
                             1s 2ms/step - loss: 0.0334 - val loss:
0.0344
Epoch 28/50
499/499 -
                             1s 3ms/step - loss: 0.0337 - val loss:
0.0336
Epoch 29/50
                             1s 2ms/step - loss: 0.0327 - val loss:
499/499 -
0.0338
Epoch 30/50
499/499 -
                             1s 2ms/step - loss: 0.0332 - val_loss:
0.0340
Epoch 31/50
499/499 -
                             1s 2ms/step - loss: 0.0333 - val_loss:
0.0336
Epoch 32/50
499/499 —
                             1s 3ms/step - loss: 0.0332 - val loss:
0.0335
Epoch 33/50
                             1s 2ms/step - loss: 0.0334 - val loss:
499/499 -
0.0333
Epoch 34/50
                             1s 2ms/step - loss: 0.0335 - val loss:
499/499 -
0.0340
Epoch 35/50
499/499 -
                             1s 2ms/step - loss: 0.0331 - val_loss:
0.0334
Epoch 36/50
499/499 -
                             1s 2ms/step - loss: 0.0332 - val loss:
0.0333
Epoch 37/50
499/499 —
                             2s 3ms/step - loss: 0.0330 - val loss:
0.0332
Epoch 38/50
                             1s 2ms/step - loss: 0.0330 - val loss:
499/499 —
0.0331
Epoch 39/50
499/499 -
                             1s 2ms/step - loss: 0.0326 - val loss:
0.0336
Epoch 40/50
499/499 -
                             1s 2ms/step - loss: 0.0328 - val_loss:
0.0340
Epoch 41/50
                             1s 2ms/step - loss: 0.0332 - val_loss:
499/499 -
0.0335
Epoch 42/50
499/499 -
                            - 1s 2ms/step - loss: 0.0332 - val loss:
0.0332
```

```
Epoch 43/50
                          -- 1s 2ms/step - loss: 0.0327 - val loss:
499/499 -
0.0335
Epoch 44/50
                           - 1s 2ms/step - loss: 0.0327 - val loss:
499/499 —
0.0330
Epoch 45/50
499/499 -
                            - 1s 2ms/step - loss: 0.0328 - val loss:
0.0331
Epoch 46/50
499/499 —
                            - 1s 2ms/step - loss: 0.0328 - val loss:
0.0330
Epoch 47/50
499/499 —
                           - 1s 2ms/step - loss: 0.0326 - val loss:
0.0332
Epoch 48/50
499/499 -
                           - 1s 2ms/step - loss: 0.0328 - val loss:
0.0341
Epoch 49/50
                            - 1s 3ms/step - loss: 0.0333 - val loss:
499/499 -
0.0331
Epoch 50/50
499/499 —
                         --- 1s 2ms/step - loss: 0.0330 - val loss:
0.0340
#test loss and plot for nn
# calculate test loss
loss = model 02.evaluate(X test, y test, verbose=0)
print("Test Loss:", loss)
# Calculate MSE for training data
mse_train = mean_squared_error(y_train, model_02.predict(X train))
print("Mean Squared Error (MSE) for training data:", mse train)
# Calculate MSE for test data
mse test = mean squared error(y test, model 02.predict(X test))
print("Mean Squared Error (MSE) for test data:", mse test)
plt.plot(history.history['loss'])
plt.plot(history.history['val loss'])
plt.title('Model Loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
Test Loss: 0.03255172073841095
1140/1140 —
                             - 1s 1ms/step
Mean Squared Error (MSE) for training data: 0.03238161095349632
                          0s 1ms/step
Mean Squared Error (MSE) for test data: 0.03257640276547331
<matplotlib.legend.Legend at 0x13a6dc170>
```

Model Loss



```
#nn model with regularization
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, Dropout
from tensorflow.keras import regularizers
num_features = X_train.shape[1]
# Define the model architecture with regularization
model 03 = Sequential([
    Dense(128, activation='relu',
kernel regularizer=regularizers.l2(0.001),
input_shape=(num_features,)),
    Dropout(0.2), # Dropout layer with a dropout rate of 20%
    Dense(64, activation='relu',
kernel regularizer=regularizers.l2(0.001)),
    Dropout(0.2), # Dropout layer with a dropout rate of 20%
    Dense(1)
])
# Compile the model
model 03.compile(optimizer='adam', loss='mse')
```

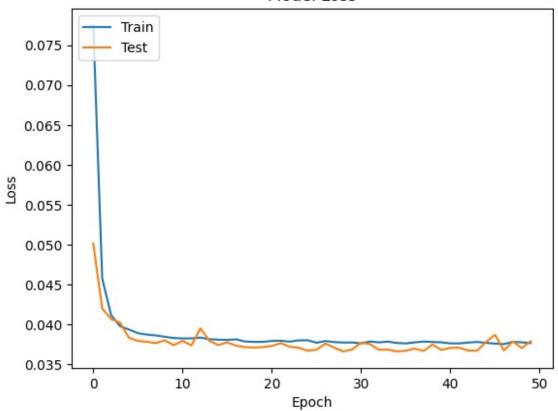
```
# Train the model
history = model 03.fit(X train, y train, validation data=(X test,
y test), epochs=50, batch size=64, verbose=1)
Epoch 1/50
/Library/Frameworks/Python.framework/Versions/3.12/lib/python3.12/
site-packages/keras/src/layers/core/dense.py:85: UserWarning: Do not
pass an `input shape`/`input dim` argument to a layer. When using
Sequential models, prefer using an `Input(shape)` object as the first
layer in the model instead.
  super(). init (activity regularizer=activity regularizer,
**kwarqs)
570/570 —
                         3s 2ms/step - loss: 0.1060 - val loss:
0.0501
Epoch 2/50
                          -- 1s 2ms/step - loss: 0.0485 - val loss:
570/570 -
0.0420
Epoch 3/50
570/570 —
                           - 1s 2ms/step - loss: 0.0417 - val loss:
0.0407
Epoch 4/50
570/570 -
                            - 1s 2ms/step - loss: 0.0402 - val loss:
0.0402
Epoch 5/50
570/570 -
                           - 1s 2ms/step - loss: 0.0395 - val loss:
0.0383
Epoch 6/50
570/570 -
                            - 1s 2ms/step - loss: 0.0394 - val loss:
0.0379
Epoch 7/50
                            - 2s 3ms/step - loss: 0.0384 - val loss:
570/570 -
0.0378
Epoch 8/50
570/570 -
                           — 1s 2ms/step - loss: 0.0385 - val loss:
0.0377
Epoch 9/50
570/570 —
                           — 1s 2ms/step - loss: 0.0383 - val loss:
0.0380
Epoch 10/50
570/570 -
                           - 2s 2ms/step - loss: 0.0384 - val loss:
0.0374
Epoch 11/50
570/570 —
                            - 1s 2ms/step - loss: 0.0384 - val loss:
0.0380
Epoch 12/50
570/570 -
                           — 1s 2ms/step - loss: 0.0384 - val loss:
0.0374
```

```
Epoch 13/50
                            - 1s 2ms/step - loss: 0.0386 - val loss:
570/570 -
0.0395
Epoch 14/50
570/570 —
                            - 2s 3ms/step - loss: 0.0383 - val loss:
0.0380
Epoch 15/50
570/570 -
                             - 1s 3ms/step - loss: 0.0378 - val loss:
0.0374
Epoch 16/50
570/570 —
                             1s 2ms/step - loss: 0.0386 - val loss:
0.0378
Epoch 17/50
570/570 —
                             - 1s 2ms/step - loss: 0.0381 - val loss:
0.0374
Epoch 18/50
570/570 —
                             - 1s 2ms/step - loss: 0.0380 - val loss:
0.0372
Epoch 19/50
                              2s 3ms/step - loss: 0.0379 - val loss:
570/570 -
0.0371
Epoch 20/50
570/570 <del>-</del>
                            - 1s 2ms/step - loss: 0.0377 - val loss:
0.0372
Epoch 21/50
570/570 —
                             2s 3ms/step - loss: 0.0381 - val_loss:
0.0373
Epoch 22/50
570/570 -
                             1s 2ms/step - loss: 0.0380 - val loss:
0.0377
Epoch 23/50
570/570 -
                             1s 2ms/step - loss: 0.0377 - val loss:
0.0372
Epoch 24/50
570/570 -
                             1s 2ms/step - loss: 0.0381 - val loss:
0.0371
Epoch 25/50
                            - 1s 2ms/step - loss: 0.0387 - val loss:
570/570 -
0.0367
Epoch 26/50
570/570 —
                            - 1s 2ms/step - loss: 0.0377 - val loss:
0.0368
Epoch 27/50
570/570 —
                             - 1s 2ms/step - loss: 0.0377 - val loss:
0.0376
Epoch 28/50
570/570 —
                            - 1s 2ms/step - loss: 0.0383 - val loss:
0.0371
Epoch 29/50
```

```
570/570 -
                            - 1s 2ms/step - loss: 0.0375 - val loss:
0.0366
Epoch 30/50
570/570 -
                            1s 2ms/step - loss: 0.0377 - val loss:
0.0369
Epoch 31/50
                             1s 2ms/step - loss: 0.0378 - val loss:
570/570 -
0.0377
Epoch 32/50
570/570 -
                            - 1s 2ms/step - loss: 0.0381 - val loss:
0.0376
Epoch 33/50
570/570 -
                             1s 2ms/step - loss: 0.0377 - val loss:
0.0368
Epoch 34/50
                            1s 2ms/step - loss: 0.0378 - val loss:
570/570 -
0.0369
Epoch 35/50
                            - 1s 2ms/step - loss: 0.0380 - val loss:
570/570 -
0.0366
Epoch 36/50
570/570 -
                             1s 2ms/step - loss: 0.0376 - val loss:
0.0367
Epoch 37/50
                            1s 2ms/step - loss: 0.0377 - val loss:
570/570 —
0.0370
Epoch 38/50
570/570 —
                            - 1s 2ms/step - loss: 0.0387 - val loss:
0.0367
Epoch 39/50
570/570 —
                            - 1s 2ms/step - loss: 0.0382 - val loss:
0.0375
Epoch 40/50
570/570 -
                             1s 2ms/step - loss: 0.0377 - val loss:
0.0368
Epoch 41/50
570/570 —
                             1s 2ms/step - loss: 0.0374 - val loss:
0.0371
Epoch 42/50
                             1s 2ms/step - loss: 0.0376 - val loss:
570/570 -
0.0371
Epoch 43/50
                            - 1s 2ms/step - loss: 0.0378 - val_loss:
570/570 -
0.0367
Epoch 44/50
570/570 -
                             1s 2ms/step - loss: 0.0376 - val_loss:
0.0367
Epoch 45/50
570/570 -
                            - 1s 2ms/step - loss: 0.0381 - val loss:
```

```
0.0378
Epoch 46/50
570/570 —
                           — 1s 2ms/step - loss: 0.0379 - val loss:
0.0387
Epoch 47/50
                             1s 3ms/step - loss: 0.0381 - val loss:
570/570 -
0.0368
Epoch 48/50
                            - 1s 2ms/step - loss: 0.0373 - val loss:
570/570 -
0.0379
Epoch 49/50
570/570 -
                            - 1s 2ms/step - loss: 0.0381 - val_loss:
0.0370
Epoch 50/50
570/570 -
                          -- 1s 2ms/step - loss: 0.0379 - val_loss:
0.0379
# test loss and plot for nn modoel with regularization
loss = model 03.evaluate(X test, y test, verbose=0)
print("Test Loss:", loss)
# Calculate MSE for train data
mse_train = mean_squared_error(y_train, model_03.predict(X_train))
print("Mean Squared Error (MSE) for training data:", mse_train)
# Calculate MSE for test data
mse_test = mean_squared_error(y_test, model_03.predict(X_test))
print("Mean Squared Error (MSE) for test data:", mse_test)
plt.plot(history.history['loss'])
plt.plot(history.history['val loss'])
plt.title('Model Loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
Test Loss: 0.0379117876291275
1140/1140 -
                              1s 1ms/step
Mean Squared Error (MSE) for training data: 0.03676896880396006
428/428 —
                          1s 2ms/step
Mean Squared Error (MSE) for test data: 0.036910547859390866
```





```
from sklearn.ensemble import BaggingRegressor
# Combine predictions using Bagging
bagging models = [dt model, gb model, model 02, model 04]
bagging predictions = np.mean(np.stack([model.predict(X test) for
model in bagging models], axis=0), axis=0)
# Evaluate Bagging performance
bagging mse = mean squared error(y test, bagging predictions)
print("Bagging Model:")
print("Mean Squared Error (MSE):", bagging mse)
428/428 -
                            - 0s 1ms/step
428/428 -
                            - 1s 1ms/step
ValueError
                                          Traceback (most recent call
last)
Cell In[74], line 5
      3 # Combine predictions using Bagging
      4 bagging models = [dt model, gb model, model 02, model 04]
```

```
---> 5 bagging predictions = np.mean(np.stack([model.predict(X test)
for model in bagging models], axis=0), axis=0)
      8 # Evaluate Bagging performance
      9 bagging mse = mean squared error(y test, bagging predictions)
File
/Library/Frameworks/Python.framework/Versions/3.12/lib/python3.12/
site-packages/numpy/core/shape base.py:449, in stack(arrays, axis,
out, dtype, casting)
    447 shapes = {arr.shape for arr in arrays}
    448 if len(shapes) != 1:
--> 449 raise ValueError('all input arrays must have the same
shape')
    451 result ndim = arrays[0].ndim + 1
    452 axis = normalize axis index(axis, result ndim)
ValueError: all input arrays must have the same shape
print("Shape of predictions from model 02:",
model 02.predict(X test).shape)
print("Shape of predictions from model 04:",
model 04.predict(X test).shape)
print("Shape of predictions from DecisionTreeRegressor:",
dt model.predict(X test).shape)
print("Shape of predictions from GradientBoostingRegressor:",
gb model.predict(X test).shape)
                       ---- Os 1ms/step
428/428 —
Shape of predictions from model 02: (13678, 1)
428/428 — Os 980us/step
Shape of predictions from model 04: (13678, 1)
Shape of predictions from DecisionTreeRegressor: (13678,)
Shape of predictions from GradientBoostingRegressor: (13678,)
# Stack predictions from all models
all predictions = [model.predict(X test).flatten() for model in
[model 02, model 04, dt model, gb model]]
# Calculate mean predictions
bagging predictions = np.mean(np.stack(all predictions, axis=0),
axis=0)
# Evaluate Bagging performance
bagging_mse = mean_squared_error(y_test, bagging_predictions)
print("Bagging Mean Squared Error (MSE):", bagging mse)
428/428 — — — 0s 1ms/step
428/428 — — 0s 1ms/step
Bagging Mean Squared Error (MSE): 0.030721526234414275
```