$$e = 1.602 \times 10^{-19} \text{ C} \qquad \mu_o = 4\pi \times 10^{-7} \frac{\text{Wb}}{\text{Am}} \qquad c = 3.00 \times 10^{3} \frac{m}{s}$$

$$F = G \frac{m_1 m_2}{r^2} \qquad \bar{g} = G \frac{M}{r^2} \hat{r} \qquad U = -G \frac{m_1 m_2}{r} \qquad \bar{F} = m\bar{g}$$

$$v = \lambda f \qquad f = \frac{1}{T} \qquad \omega = \frac{2\pi}{T} \qquad k = \frac{2\pi}{\lambda} \qquad y(x,t) = A\cos(\omega t \mp kx) \qquad v = \sqrt{\frac{T}{\mu}}$$

$$\bar{E} = \frac{1}{4\pi\varepsilon_o} \frac{q}{r^2} \hat{r} \qquad d\bar{E} = \frac{1}{4\pi\varepsilon_o} \frac{dq}{r^2} \hat{r} \qquad F = \frac{1}{4\pi\varepsilon_o} \frac{|q_1 q_2|}{r^2}$$

$$\bar{E} = \frac{\bar{F}_o}{q_o} \qquad p = qd \qquad \bar{\tau} = \bar{p} \times \bar{E} \qquad U = -\bar{p} \cdot \bar{E}$$

$$\Phi_E = \int \bar{E} \cdot d\bar{A} \qquad \Phi_E = \oint \bar{E} \cdot d\bar{A} = \frac{Q_{ow}}{\varepsilon_o} \qquad E = \frac{1}{2\pi\varepsilon_o} \frac{\lambda}{r}$$

$$E = \frac{\sigma}{2\varepsilon_o} \qquad E = \frac{\sigma}{\varepsilon_o} \qquad E = \frac{1}{4\pi\varepsilon_o} \frac{Qr}{r}$$

$$W_{a \to b} = -\Delta U \qquad U = \frac{1}{4\pi\varepsilon_o} \frac{qq_o}{r} \qquad U = \frac{q_o}{4\pi\varepsilon_o} \sum_{i=r_i} \frac{q_i}{r_i} \qquad U = \frac{1}{4\pi\varepsilon_o} \int_{r_i} \frac{Qq}{r}$$

$$V = \frac{U_o}{q_o} = \frac{1}{4\pi\varepsilon_o} \frac{q}{r} \qquad V = \frac{1}{4\pi\varepsilon_o} \sum_{i=r_i} \frac{q_i}{r_i} \qquad V = \frac{1}{4\pi\varepsilon_o} \int_{r_i} \frac{dq}{r}$$

$$V_a - V_b = \int_{\sigma}^{b} \bar{E} \cdot d\bar{A} \qquad V = \frac{\lambda}{2\pi\varepsilon_o} \ln \frac{r_o}{r} \qquad V = \frac{\lambda}{2\pi\varepsilon_o} \ln \frac{R}{r} \qquad V = \frac{1}{4\pi\varepsilon_o} \int_{r_o} \frac{Q}{\sqrt{x^2 + a^2}}$$

$$C = \frac{Q}{V_{ob}} \qquad C = \frac{A\varepsilon_o}{d} \qquad C = 4\pi\varepsilon_o \frac{r_o r_o}{r_o r_o} \qquad \frac{C}{L} = \frac{2\pi\varepsilon_o}{\ln(r_o r_o)}$$

$$\frac{1}{C_{oq}} = \frac{1}{L_i} + \frac{1}{L_2} + \frac{1}{L_3} + \dots \qquad C_{eq} = C_1 + C_2 + C_3 + \dots$$

$$U = \frac{Q^2}{2C} = \frac{1}{2}CV^2 = \frac{1}{2}QV \qquad u = \frac{1}{2}\varepsilon_o E^2 \qquad \varepsilon = K\varepsilon_o$$

$$I = \frac{dQ}{dt} \qquad \rho = \frac{E}{J} \qquad \rho(T) = \rho_o [1 + \alpha(T - T_o)] \qquad R = \frac{\rho L}{A} \qquad V = R$$

$$R(T) = R_o [1 + \alpha(T - T_o)] \qquad \xi = V_{ob} \qquad V_{ob} = \xi - Ir \qquad P = V_{ob}I = I^2R = \frac{V_{ob}^2}{R}$$

$$R_{oq} = R_i + R_2 + R_3 + \dots \qquad \frac{1}{R_{oq}} = \frac{1}{R_i} + \frac{1}{R_2} + \frac{1}{R_3} + \dots \qquad V_{rior} = V_{ob}I = I^2R = V_{ob}^2$$

 $G = 6.67 \times 10^{-11} \frac{\text{Nm}^2}{\text{kg}^2}$ 

 $k = \frac{1}{4\pi\varepsilon} = 8.988 \times 10^9 \frac{\text{Nm}^2}{\text{C}^2}$   $\varepsilon_o = 8.854 \times 10^{-12} \frac{\text{C}^2}{\text{Nm}^2}$ 

$$\begin{split} \vec{F} &= q\vec{v}\times\vec{B} & \Phi_g = \int \vec{B}\cdot d\vec{A} & \oint \vec{B}\cdot d\vec{A} = 0 \qquad R = \frac{mv}{|q|B} \\ v &= \frac{E}{B} \qquad F = l\vec{l}\times\vec{B} \qquad d\vec{F} = ld\vec{l}\times\vec{B} \qquad F = lLB\sin\theta \\ \tau &= lAB\sin\phi \qquad \vec{\tau} = \vec{\mu}\times\vec{B} \qquad U = -\vec{\mu}\cdot\vec{B} \qquad \vec{B} = \frac{\mu_o}{4\pi}\frac{q\vec{v}\times\vec{F}}{4\pi} \\ d\vec{B} &= \frac{\mu_o}{4\pi}\frac{ld\vec{l}\times\vec{F}}{r^3} \qquad B = \frac{\mu_o l}{2m} \qquad B_c = \frac{\mu_o la^2}{2(x^2+a^2)^{\frac{N}{2}}} \qquad \int \vec{B}\cdot d\vec{l} = \mu_o l_{no} \\ B_c &= \frac{\mu_o Nl}{2a} \qquad B_s = \frac{\mu_o la^2}{2(x^2+a^2)^{\frac{N}{2}}} \qquad \int \vec{B}\cdot d\vec{l} = \mu_o l_{no} \\ \vec{E} &= -N\frac{d\Phi_n}{dt} \qquad \mathcal{E} = vBL \qquad \oint \vec{E}\cdot d\vec{l} = -\frac{d\Phi_n}{dt} \qquad i_n = s\frac{d\Phi_F}{dt} \\ \int \vec{B}\cdot d\vec{l} &= \mu_e \left[i_c + v_c \frac{d\Phi_F}{dt}\right]_{no} \qquad \mathcal{E}_s = -M\frac{di_s}{dt} \qquad \mathcal{E}_1 = -M\frac{di_s}{dt} \qquad \mathcal{E}_2 = -L\frac{di}{dt} \\ U &= \frac{1}{2}II^2 \qquad u &= \frac{B^2}{2\mu_o} \qquad i = \frac{\vec{E}}{R}(1-e^{-B^2/2}) \qquad \tau = \frac{L}{R} \qquad \omega = \frac{1}{\sqrt{LC}} \\ i &= I\cos\omega \qquad I_{RdS} &= \frac{I}{\sqrt{2}} \qquad V_{RdS} = \frac{V}{\sqrt{2}} \qquad V_R = IR \qquad V_L = IX_L \\ X_L &= \omega L \qquad V_C = IX_C \qquad X_C = \frac{1}{\omega C} \qquad V = IZ \\ Z &= \sqrt{(X_L - X_C)^2 + R^2} \qquad \tan\phi = \frac{X_L - X_C}{R} \qquad P_{no} = I_{noo}V_{noo}\cos\phi \qquad \cos\phi = \frac{R}{Z} \\ \omega_s &= \frac{1}{\sqrt{LC}} \qquad \omega = 2\pi f \qquad \frac{V_s}{V_1} = \frac{N_s}{N_1} \qquad V_t I_1 = V_s I_2 \\ v &= f\lambda \qquad c = \frac{1}{\sqrt{s_o}\mu_o} \qquad E = cB \qquad E(x,t) = E_{max}\cos(\omega t - kx) \\ B(x,t) &= B_{max}\cos(\omega t - kx) \qquad \vec{S} = \frac{1}{\mu_o}\vec{E}\times\vec{B} \qquad I = S_{no} \qquad p_{nol} = \frac{I}{c} \qquad p_{nol} = \frac{2I}{c} \\ \sin\theta_{crit} &= \frac{n_s}{n_1} \qquad I = \frac{1}{2}I_s \qquad I_2 = I_1\cos^2\theta \qquad \tan\theta_F = \frac{n_s}{n_1} \\ f &= \frac{1}{2}R \qquad \frac{1}{d_o} + \frac{1}{d_o} = \frac{1}{d_o} \qquad d\sin\theta = (m+\frac{1}{2})\lambda \\ \sin\theta &= m\lambda \qquad d\sin\theta = m\lambda \qquad 2d\sin\theta = m\lambda \\ \sin\theta &= m\lambda \qquad 2d\sin\theta = m\lambda \\ \end{cases} \qquad 2d\sin\theta = m\lambda \end{aligned}$$