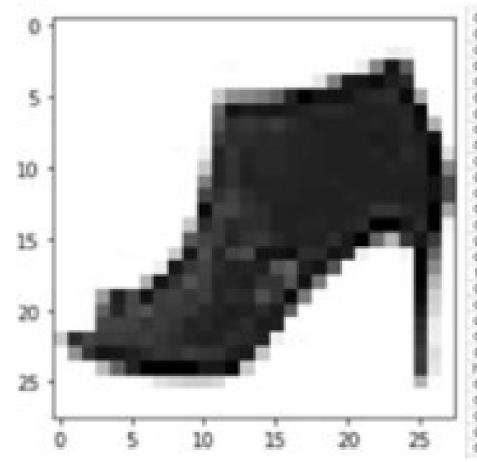
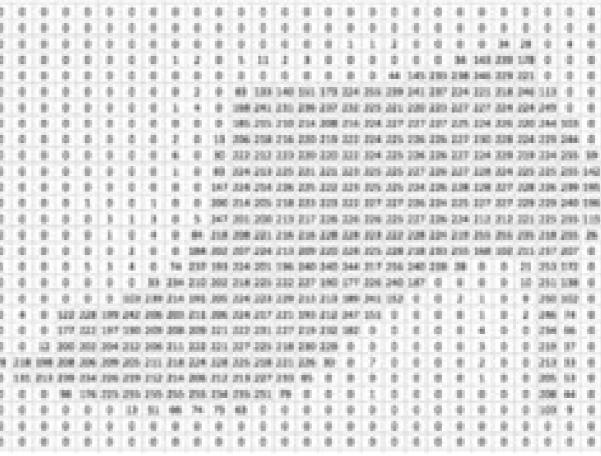
# Convolutional Neural Network for FASHION MNIST DATASET





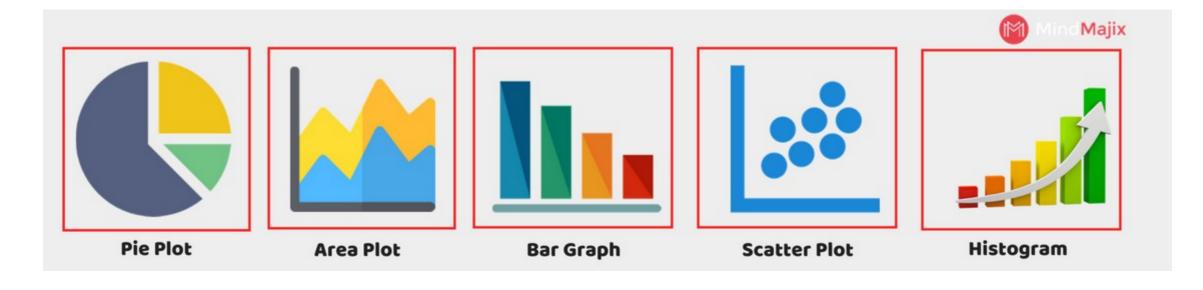


0 2 15 0 0 11 10 0 0 0 0 9 0 4 60 157 238 255 255 177 12 0 10 16 UE 238 255 244 245 243 250 249 255 222 10 10 C 12 170 255 255 244 254 255 253 245 255 249 253 251 FRE 52 0 10 13 282 255 255 7 6 W 287 252 235 E8 (SIME 236 243 255 188 0 4 5 6 7 1 252 255 248 244 0 13 11 255 255 245 255 182 181 248 252 242 208 5 HU 251 255 241 255 247 255 241 162 17 4 55 251 255 246 254 253 255 80 17 4 176 255 255 255 248 252 255 244 255 182 10 34 0 28 206 252 246 251 241 100 24 110 255 245 255 194 3 255 232 230 mag 0 68 255 250 88 0 53 3 13 182 251 245 61 CHO 251 241 255 230 EB 55 19 110 217 248 253 259 52 10 to RESTRICTED 255 250 248 255 255 248 248 EEE 0, 450 353 233 255 252 347 0 0 0 0 14

Label	Description	Examples
0	T-Shirt/Top	
1	Trouser	
2	Pullover	
3	Dress	
4	Coat	
5	Sandals	BERRESTANDE JUNE SAND
6	Shirt	THE TARREST AND THE TARREST AN
7	Sneaker	
8	Bag	
9	Ankle boots	

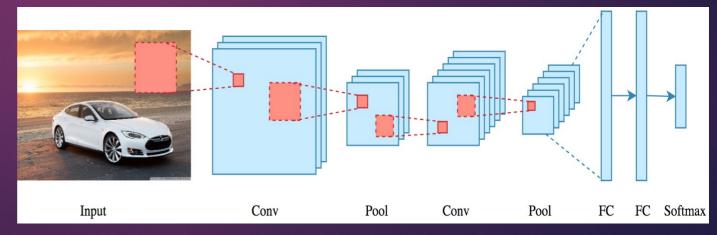
# Matplotlib

**Matplotlib** is a Python 2D plotting library that produces high-quality charts and figures, which helps us visualize extensive data to understand better. Pandas is a handy and useful data-structure tool for analyzing large and complex data. And **pyplot** function makes some change to a figure: e.g., creates a figure, creates a plotting area in a figure, plots some lines in a plotting area, decorates the plot with labels, etc.



# CONVOLUTIONAL NEURAL NETWORK

- Convolutional Neural Networks or CNN is a type of deep neural networks that are efficient at extracting meaningful information from visual imagery.
- The role of the CNN is to reduce the images into a form that is easier to process, without losing features that are critical for getting a good prediction.



# Parameters in CNN

- **filters:** Integer, the dimensionality of the output space (i.e. the number of output filters in the convolution).
- **kernel\_size**: An integer or tuple/list of 2 integers, specifying the height and width of the 2D convolution window. Can be a single integer to specify the same value for all spatial dimensions.
- **strides:** The amount by which the filter shifts is the stride
- **padding:** one of "valid" or "same" (case-insensitive). "valid" means no padding. "same" results in padding with zeros evenly to the left/right or up/down of the input such that output has the same height/width dimension as the input. Padding is simply a process of adding layers of zeros to our input images so as to avoid the problems
- **activation**: Activation function to use. If you don't specify anything, no activation is applied

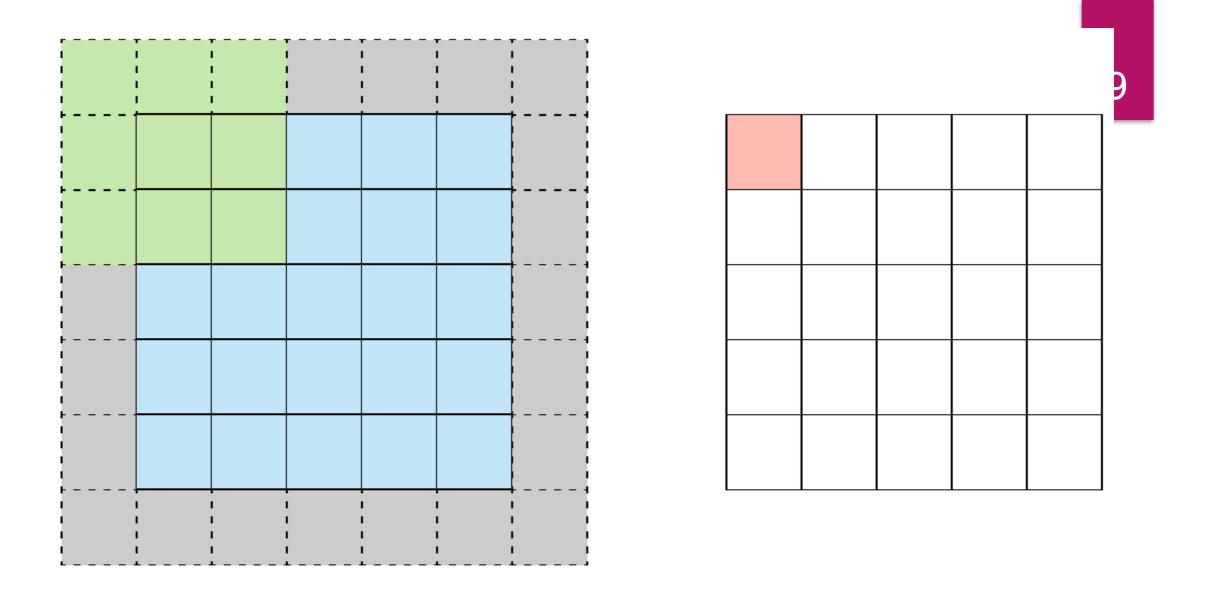
CNN layer working

1x1	1x0	1x1	0	0
0x0	1x1	1x0	1	0
0x1	0x0	1x1	1	1
0	0	1	1	0
0	1	1	0	0

4	

Input x Filter

Feature Map

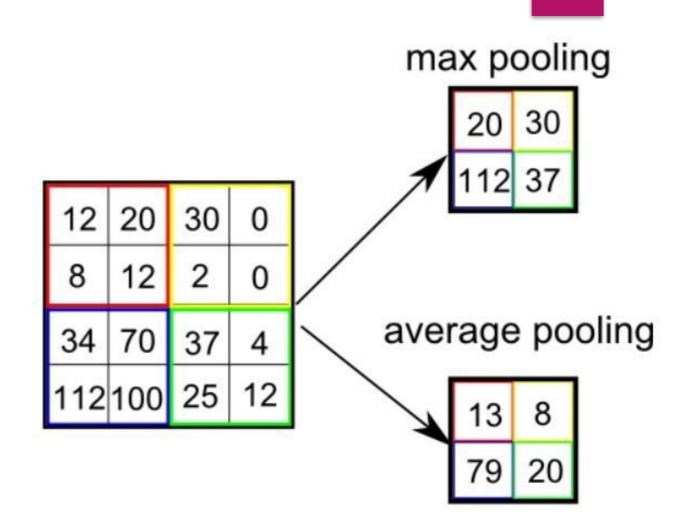


Stride 1 with Padding

Feature Map

# **POOLING LAYER:**

- Similar to the Convolutional Layer, the Pooling layer is responsible for reducing the spatial size of the Convolved Feature.
- This is to decrease the computational power required to process the data by reducing the dimensions.
- There are two types of pooling average pooling and max pooling.



# **DENSE LAYER**

The dense layer is a neural network layer that is connected deeply, which means each neuron in the dense layer receives input from all neurons of its previous layer. The dense layer is found to be the most commonly used layer in the models.

### **Keras Dense Layer Parameters**

Let us see main parameters of dense layer function of Keras below -

### 1. Units

The **most basic parameter** of all the parameters, it uses positive integer as it value and represents the **output size** of the layer.

It is the unit parameter itself that plays a major role in the **size of the weight matrix** along with the **bias vector**.

### 2. Activation

The activation parameter is helpful in applying the element-wise activation function in a dense layer. By default, Linear Activation is used but we can alter and switch to any one of many options that Keras provides for this.

# **ACTIVATION FUCNTIONS - RELU, SOFTMAX**

### **RELU:**

The **rectified linear activation function** or **ReLU** for short is a piecewise linear function that will output the input directly if it is positive, otherwise, it will output zero. It has become the default activation function for many types of neural networks because a model that uses it is easier to train and often achieves better performance.

### **SOFTMAX:**

The softmax function squashes the outputs of each unit to be between 0 and 1, just like a sigmoid function. But it also divides each output such that the total sum of the outputs is equal to 1 (check it on the figure above).

The output of the softmax function is equivalent to a categorical probability distribution, it tells you the probability that any of the classes are true.

# STEPS INVOLVED

- Import all the libraries ,packages
- Load the data from tensorflow or keras
- Split the data
- Pre-process the data into the appropriate form

   a) normalize
- Start creating model
- Add all the layers sequentially
- Compile, train and validate
- Predict and print the predicted labels with respective objects

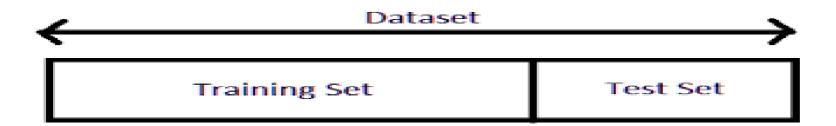
# Importing dataset and splitting

### LOADING DATASET

tf.keras.datasets.cifar10.load\_data()
 Or
keras.datasets.cifar10.load\_data()

### SPLITTING OF DATASET

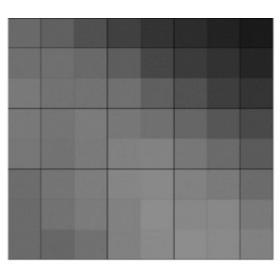
Further the data is splitted into training and testing set based on size of the dataset .



# PRE-PROCESSING - NORMALIZATION

- In image processing, **normalization** is a process that changes the range of pixel intensity values.
- **Normalization** is an important step which ensures that each input parameter (pixel, in this case) has a similar data distribution. This makes convergence faster while training the network
- Most probably the images are converted to gray scale as the pixels range will be 0-255 only

107	98	82	66	53	46	36	28
113	113	107	95	72	61	52	39
123	116	116	114	97	83	64	54
122	118	125	121	114	103	87	75
119	116	124	130	132	121	108	92
110	118	127	135	138	131	124	114
108	116	125	131	141	137	136	123
108	104	114	130	139	141	139	130



### IMPORTING LAYERS and ADDING LAYERS

### FROM KERAS

```
from keras.models import Sequential
from keras.layers import Dense, Dropout, Conv2D, MaxPool2D, Flatten
```

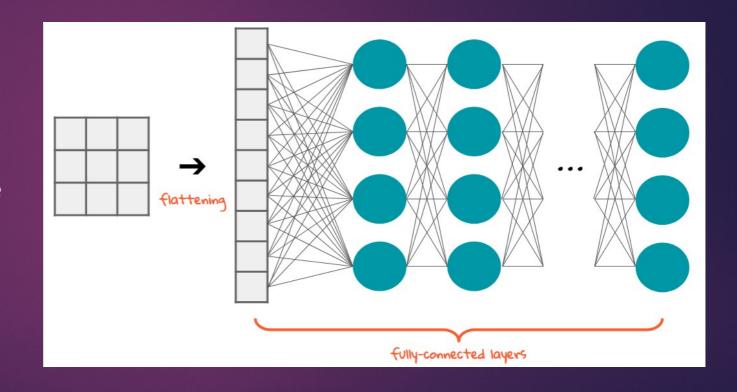
### From tensorflow

```
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, Conv2D, Dropout, Flatten,
MaxPooling2D
```

We add layer my using add () function in sequential order as we chose sequential model

# FLATTEN LAYER

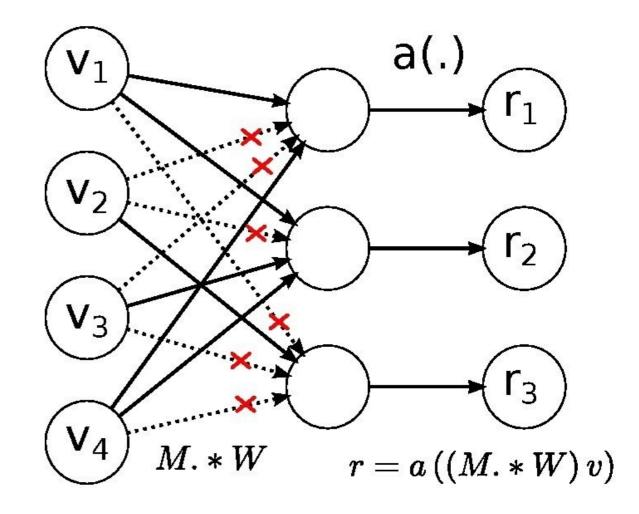
- Flattening is converting the data into a 1-dimensional array for inputting it to the next layer. We flatten the output of the convolutional layers to create a single long feature vector.
- And it is connected to the final classification model, which is called a fullyconnected layer

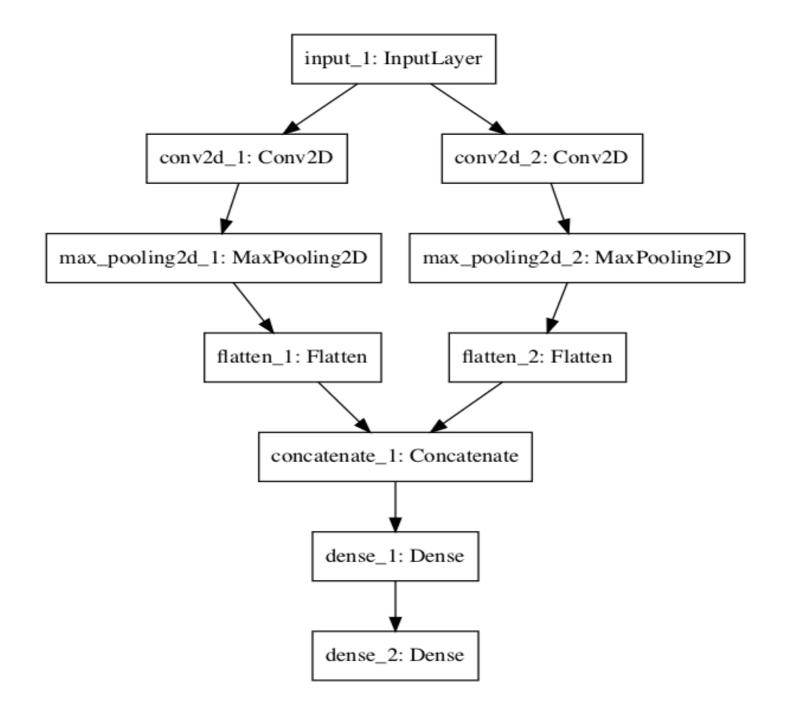


Dropout is a way to regularize the neural network. During training, it may happen that neurons of a particular layer may always become influenced only by the output of a particular neuron in the previous layer. In that case, the neural network would overfit.

Dropout prevents overfitting and regularizes by randomly cutting the connections (also known as dropping the connection) between neurons in successive layers during training

# Dropout





# Compiling model

**Compile** defines the loss function, the optimizer and the metrics. It has nothing to **do** with the weights and you can **compile** a **model** as many times as you want without causing any problem to pretrained weights. You need a **compiled model** to train (because training uses the loss function and the optimizer

```
compile(
  optimizer,
  loss = None,
  metrics = None,
  loss_weights = None,
  sample_weight_mode = None,
  weighted_metrics = None,
  target_tensors = None
)
```

The important arguments are as follows —loss function,Optimizer,metrics

### LOSS:

The error for the current state of the model must be estimated repeatedly. This requires the choice of an error function, conventionally called a **loss function**, that can be used to estimate the loss of the model so that the weights can be updated to reduce the loss on the next evaluation.

### **METRICS:**

**Metrics** is used to evaluate the performance of your model. It is similar to loss function, but not used in training process. Keras provides quite a few metrics as a module, **metrics** and they are as follows

- •accuracy
- binary accuracy
- categorical\_accuracy
- sparse categorical accuracy

### **OPTIMIZER:**

**Optimization** is an important process which optimize the input weights by comparing the prediction and the loss function. Keras provides quite a few optimizer as a module, *optimizers*.

Adam is the **best optimizers**. If one wants to train the **neural network** in less time and more efficiently than Adam is the **optimizer**.

```
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, Conv2D, Dropout,
Flatten, MaxPooling2D
model = Sequential()
model.add(Conv2D(28, kernel_size=(3,3), input_shape=input_sh
ape))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Flatten())
model.add(Dense(128, activation=tf.nn.relu))
model.add(Dropout(0.2))
model.add(Dense(10, activation=tf.nn.softmax))
```

# TRAINING MODEL

- model.fit(X\_train, Y\_train, batch\_size=128, epochs=20, validation\_data=(X\_test, Y\_test))
- the **batch size** is a number of samples processed before the **model** is updated.
- The number of epochs is the number of complete passes through the training dataset.
- The **size** of a **batch** must be more than or equal to one and less than or equal to the number of samples in the training dataset.

# EVALUATE, PREDICT

### **EVALUATE:**

Evaluating the model requires that you first choose a holdout dataset used to evaluate the model. This should be data not used in the training process so that we can get an unbiased estimate of the performance of the model when making predictions on new data.

model.evaluate(X\_test, Y\_test)

### **PREDICT**

Making a prediction is the final step in the life-cycle. It is why we wanted the model in the first place.

It requires you have new data for which a prediction is required, e.g. where you do not have the target values.

model.predict(X\_test[100:105])

