Food Deserts or Food Oases? Predicting Grocery Store Locations in Hamilton, Ontario

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Abstract

This is the abstract.

It consists of two paragraphs.

Keywords: Grocery stores, Food environments, Hamilton

1. Introduction and Background

Food is a necessity for human beings. In urban areas or large cities, residents typically rely on grocery stores for their daily food needs. Geographic access to grocery stores and affordable food plays an important role in promoting a healthy diet and has implications for personal health (Caspi et al., 2012; Minaker, 2016; Kirkpatrick et al., 2014). The ease of accessing grocery stores and obtaining the needed food is thus an important topic for both public health and urban planning.

There is extensive literature on food access that examines this topic (Christian, 2012; Widener et al., 2015; Farber et al., 2014; Widener et al., 2017). These analyses mostly focus on the demand side, where consumers navigate and choose which retailers to purchase from. However, a gap exists in studying how retailers choose the locations of their stores to serve the market or the demand.

In this paper, I utilize open-source data from the 2021 Canadian Census (Statistics Canada, 2022) and OpenStreetMap (OpenStreetMap contributors, 2017) to examine the spatial pattern of grocery store locations, using Hamilton, Ontario, as a case study. The research question is: What areas in Hamilton have more or fewer grocery stores compared to other areas?

2. Data and Methods

2.1. Study Area

My study area is the City of Hamilton, located on the west side of Lake Ontario in the province of Ontario. It has a population of 569353 according to the 2021 Canadian census (Statistics Canada, 2022). The Niagara Escarpment runs through the middle of the city, dividing it into two parts. Figure 1 below shows the study area.

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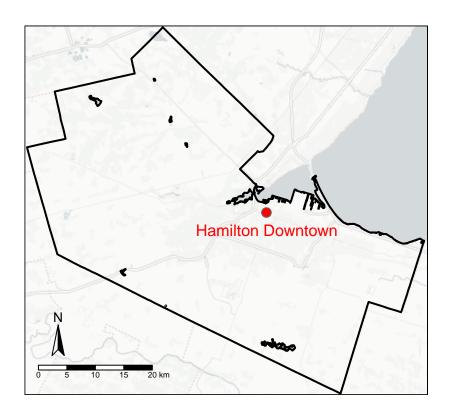


Figure 1: Study Area: Hamilton, Ontario

2.2. Data Sources

I utilize three data sources in this paper, as shown in the Table 1 below. I gathered grocery store locations in Hamilton from OpenStreetMap (OpenStreetMap contributors, 2017) via the Overpass API (OpenStreetMap Wiki, 2024). The Hamilton Street Railway (HSR) Fall 2024 GTFS static data were downloaded from Open Hamilton (City of Hamilton, 2024). The dissemination area (DA) spatial data and 2021 Canadian census variables were obtained from Statistics Canada (2022) through the cancensus package in R (von Bergmann et al., 2022).

Name	Source	URL	Accessed Date
Grocery Stores	OpenStreetMap contributors (2017)	https://overpass-turbo.eu/index.html	2024-10-04
in Hamilton			
HSR Fall 2024	City of Hamilton (2024)	https://opendata.hamilton.ca/GTFS-Static/	2024-10-04
GTFS Static			
Dissemination	Statistics Canada (2022)	https://censusmapper.ca/api	2024-11-16
Area and Cen-			
sus Data in			
Hamilton			

Table 1: Data Sources

To facilitate reproducibility and open science, all the data used in this paper have been packaged into an R package (Yin, 2024), which is hosted on GitHub. You can access it at https://github.com/zehuiyin/geog712package.

2.3. Methodology

The grocery store locations in Hamilton were intersected and aggregated to the census dissemination areas. The dependent variable of interest is the count of grocery stores in each dissemination area in Hamilton. There are 891 dissemination areas in Hamilton; however, due to data missingness, only 876 of them are used in the regression analysis. A considerable portion of the dissemination areas in our sample do not contain any grocery stores. Therefore, standard count models such as Poisson regression would be invalid due to the excessive zero values. To model this variable of interest, I fit a hurdle model and a zero-inflated negative binomial regression model with spatially lagged dependent variables.

The zero-inflated negative binomial regression model follows Equations 1 and 2 below (NCSS Statistical Software, n.d.). The variable specification in the hurdle model is exactly the same as in the zero-inflated negative binomial regression model. The hurdle model is set up with the zero component as a binomial logit model and the count component as a truncated negative binomial logit model. I decided to use negative binomial regression instead of Poisson regression because the count distribution is highly skewed, making it unlikely that the mean and variance would be the same for my variable of interest. Additionally, due to the large number of zeros in my sample, the zero-inflated regression is preferred, as it can generate zero values from two sources, unlike the hurdle model, which generates zeros from only one source.

$$Pr(GroceryStore_i = j) = \begin{cases} \pi_i + (1 - \pi_i)g(GroceryStore_i = 0) & \text{if } j = 0\\ (1 - \pi_i)g(GroceryStore_i) & \text{if } j > 0 \end{cases}$$
 (1)

$$logit(\pi) = \rho \mathbf{W} Grocery Store + \tilde{\mathbf{x}} \tilde{\boldsymbol{\beta}}$$

$$log\{E[g(Grocery Store)]\} = \rho \mathbf{W} Grocery Store + \mathbf{x} \boldsymbol{\beta}$$

$$g(Grocery Store_i) \text{ is the negative binomial distribution}$$
(2)

W: a row-normalized queen contiguity matrix

3. Results

3.1. Descriptive Statistics

Based on the bar chart in Figure 2, the distribution of the number of grocery stores in dissemination areas in Hamilton is highly skewed, with a large number of dissemination areas having no grocery stores. According to Figure 3, most grocery stores are located near the centre of Hamilton, within the Niagara Escarpment. There are also some dissemination areas at the edge of the city with grocery stores. In the right plot, the number of HSR bus stops per square kilometre is classified into three categories: low (0 to 50th percentile), middle (50th to 75th percentile), and high (75th to 100th percentile). The area with the highest transit service is also in the centre of Hamilton. Beyond the Niagara Escarpment, there are few transit stops.

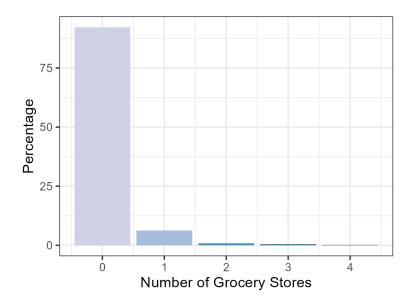


Figure 2: Number of Grocery Stores in Dissemination Areas in Hamilton

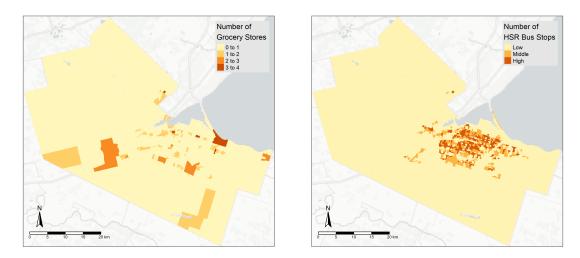


Figure 3: Number of Grocery Stores (left) and HSR Bus Stops (right) at Dissemination Areas in Hamilton, Ontario

3.2. Regression Results

The regressions are estimated using the maximum likelihood method with the R package pscl (Zeileis et al., 2008). The hurdle model has a McFadden pseudo R^2 of 0.15, while the zero-inflated negative binomial regression model has a McFadden pseudo R^2 of 0.17. Table 2 below presents the regression results.

Both models have the same variable specification. Almost all the variables in the hurdle model's zero component are significant, while no variables in its count component are significant. Meanwhile, the zero-inflated negative binomial regression model has significant variables in both the zero and count components. Considering that the pseudo R^2 for the zero-inflated model is also higher than that of the hurdle model, the zero-inflated model provides a better fit compared to the hurdle model. Therefore, in the following sections, I will focus on interpreting the zero-inflated model.

The zero component in the zero-inflated negative binomial regression is a binary logit model predicting the probability of zero inflation. Thus, a positive coefficient indicates that the variable is contributing

	Hurdle model	Zero-inflated model
Count model: Spatial lag of grocery store count	-2.05	-2.99***
	(2.37)	(0.84)
Count model: Percentage of population aged below 24 years old	-0.06	0.03
	(0.11)	(0.04)
Count model: Percentage of population aged above 65 years old	-0.02	0.02
	(0.05)	(0.02)
Count model: Percentage of population don't know official language	-0.11	-0.03
	(0.26)	(0.10)
Count model: Percentage of population don't speak official language at home	0.08	0.17**
	(0.12)	(0.06)
Count model: Percentage of population live in single detached houses	-0.01	-0.01^{-}
	(0.02)	(0.01)
Count model: Percentage of population have annual total income less than 40K	$0.02^{'}$	-0.03
	(0.09)	(0.03)
Count model: Percentage of population have annual total income more than 100K	-0.04	-0.02
	(0.10)	(0.04)
Count model: Percentage of population that are married or live in common-law	0.02	0.03
O. I.I.	(0.08)	(0.03)
Count model: Natural log of (population density $+1$)	-0.59	-0.38*
Contract of the contract of th	(0.37)	(0.17)
Count model: Natural log of distance from DA centroid to Hamilton downtown	-0.25	-0.50^{**}
	(0.43)	(0.19)
Zero model: Spatial lag of grocery store count	$0.02^{'}$	-8.62^{*}
	(0.58)	(3.38)
Zero model: Percentage of population don't speak official language at home	0.10**	0.14
00	(0.03)	(0.11)
Zero model: Percentage of population that are married or live in common-law	-0.04^{*}	0.11
G r r	(0.02)	(0.07)
Zero model: Natural log of (population density $+1$)	0.73*	-1.71^{*}
	(0.29)	(0.74)
Zero model: Number of HSR bus stops (50-75 percentile)	2.15***	-2.73****
(((((((((((((((((((((0.43)	(0.72)
Zero model: Number of HSR bus stops (75-100 percentile)	1.55**	-1.50^{*}
((0.49)	(0.74)
Zero model: Natural log of area size in square kilometres	1.39***	-2.36**
	(0.29)	(0.76)
AIC	522.36	508.91
Log Likelihood	-240.18	-233.45
Num. obs.	876	876

^{***}p < 0.001; **p < 0.01; *p < 0.05; `p < 0.1

Table 2: Regression results

positively or increasing the probability of a specific dissemination area having zero grocery stores, while a negative coefficient suggests the opposite. The count component in the model is a negative binomial regression predicting the number of grocery stores in a dissemination area. Therefore, a positive coefficient indicates that an increase in the variable's value is associated with an increase in the expected count of grocery stores in that specific dissemination area.

The spatial lagged term of grocery store counts is a significant negative predictor in both components of the model. This indicates that a higher number of grocery stores in neighbouring dissemination areas would lower the number of grocery stores in the specific dissemination area, while it would reduce the probability that the specific dissemination area would have zero grocery stores. Thus, it has a non-monotonic effect on grocery store counts. Similarly, the natural log of population density plus one also has a significant negative effect on both components of the model. Additionally, the percentage of the population that does not speak an official language at home is significantly positively associated with more grocery stores. The percentage of the population living in single detached houses and the natural log of distance from the dissemination area centroid to Hamilton downtown both decrease the expected number of grocery stores in the dissemination area.

Regarding the zero component, the 50-75 percentile and 75-100 percentile in the number of HSR bus stops are significantly associated with a lower probability of having zero grocery stores compared to the reference category (0-50 percentile). Meanwhile, as the area size of the dissemination area increases, the probability of having zero grocery stores decreases.

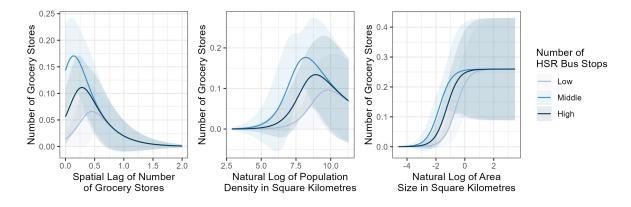


Figure 4: Conditional Prediction Plot for the Zero-inflated Negative Binomial Regression Model

Figure 4 above shows the prediction plot for the zero-inflated model. The spatial lagged term and population density exhibit non-monotonic effects on grocery store counts. As the number of grocery stores in neighboring dissemination areas increases, holding all else constant, the expected grocery store count first increases and then decreases. Similarly, as the population density in the dissemination area increases, the expected grocery store count first increases and then decreases.

Dissemination areas with the number of HSR bus stops in the 50-75th percentile have the highest average grocery store count compared to the other two levels. It is not surprising that dissemination areas with the lowest transit access have the lowest expected grocery store count.

The model predicts that as the size of the dissemination area increases from approximately 0.14 to 1 square kilometres, holding all else constant, there would be an expected increase in the grocery store count. However, as the area size further increases or decreases, the grocery store count does not change significantly.

4. Discussion and Conclusion

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