

# Math 2700.009

## Notes

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**Note:-**

- If  $V$  is a vector space,  $\mathcal{B}$  is a basis if it is both linearly independent and  $\text{span}(\mathcal{B}) = V$ .
- $\dim(V)$  is the size of a basis for  $V$ .

**Definition 0.0.1**

If  $W$  is a subspace of  $V$  then  $\dim(W)$  is the size of a linearly independent set of vectors from which  $W$  is spanned.

**Definition 0.0.2**

Vector space  $V$  is finite dimensional if it has a finite basis, and otherwise  $V$  is infinite dimensional.

## 0.1 Rules of Basis'

- If  $\mathcal{E} \subseteq V$  is a set of fewer than  $\dim(V)$  vectors, then  $\mathcal{E}$  does not span  $V$ .
- If  $\mathcal{E}$  has more vectors than  $\dim(V)$ , it cannot be linearly independent. Otherwise  $V$  has a basis of size  $\geq \dim(V)$ .
- If  $\mathcal{B}$  has  $\dim(V)$  vectors and is linearly independent, then it also spans.

**Example 0.1.1**

Show

$$\left\{ \begin{pmatrix} x \\ x+y \\ y \end{pmatrix} : x, y \in \mathbb{R} \right\} \text{ is a subspace}$$

**Solution:**

$$\begin{aligned} &= \left\{ x \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} : x, y \in \mathbb{R} \right\} \\ &= \text{span} \left( \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right) \end{aligned}$$

## 0.2 Linear Transformation

**Definition 0.2.1**

If  $V, W$  are vector spaces, a linear transformation from  $V$  to  $W$  is a function  $T : V \rightarrow W$  so that:

- 1) if  $\vec{x}, \vec{y} \in V$  then  $T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$
- 2) if  $\vec{x} \in V$  and  $c \in \mathbb{R}$  then  $T(c\vec{x}) = cT(\vec{x})$

**Example 0.2.1**

$$T : \mathbb{R} \rightarrow \mathbb{R}$$

**Example 0.2.2**

$$T : \mathbb{R}^n \rightarrow \mathbb{R}^k$$

$$T(\vec{x}) = A\vec{x} \text{ Where } A \in \mathbb{R}^{k \times n}$$

**Example 0.2.3**

$$T : C([0, 1]) \rightarrow C([0, 1])$$

**Solution:**  $T(f) = \int f(x)dx$  where the constant of integration is zero

**Note:-**

The set of functions on  $[0, 1]$  which are differentiable on  $(0, 1)$  and continuous at the endpoints and whose derivative is continuous is called  $C^1([0, 1])$

**Proposition 0.2.1**

If  $T : V \rightarrow W$  is a linear transformation, then

$$T(\vec{0}^V) = \vec{0}^W$$

**Proof:** Prop 0.2.1

$$T(\vec{0}^V) = T(\vec{0}^V + \vec{0}^V) = T(\vec{0}^V) + T(\vec{0}^V)$$

$$\text{So } T(\vec{0}^V) - T(\vec{0}^V) = T(\vec{0}^V) + T(\vec{0}^V) - T(\vec{0}^V)$$

$$\text{And thus } \vec{0}^W = \vec{0}^V$$

**Definition 0.2.2**

If  $T : V \rightarrow W$  is a linear transformation:

- $\ker(T) = \{\vec{v} \in V : T(\vec{v}) = \vec{0}\}$
- $\text{ran}(T) = \{\vec{w} \in W : \vec{w} = T(\vec{v}) \text{ for some } \vec{v} \in V\}$

**Note:-**

$$T : \mathbb{R}^n \rightarrow \mathbb{R}^k$$

$$T(\vec{x}) = A\vec{x}$$

We sometimes write  $\ker(A)$  for  $\ker(T)$  and  $\text{ran}(A)$  for  $\text{ran}(T)$

**Proposition 0.2.2**

$T : V \rightarrow W$  is a linear transformation then  $\ker(T)$  is a subspace of  $V$ , and  $\text{ran}(T)$  is a subspace of  $W$

**Proof:** Prop 0.2.2

$$- \vec{0}^V \in \ker(T) \text{ because } T(\vec{0}^V) = \vec{0}^W$$

$$- \text{If } \vec{x}, \vec{y} \in \ker(T), \text{ then } T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y}) = \vec{0}^W + \vec{0}^W = \vec{0}^W \text{ so } \vec{x} + \vec{y} \in \ker(T)$$

$$- \text{If } \vec{x} \in \ker(T) \text{ and } c \in \mathbb{R}, T(c\vec{x}) = cT(\vec{x}) = c\vec{0}^W = \vec{0}^W \text{ so } c\vec{x} \in \ker(T)$$

**Definition 0.2.3: nullity**

If  $T : V \rightarrow W$  is a linear transformation, the nullity of  $T$  is  $\dim(\ker(T))$  and the rank of  $T$  ( $\text{rank}(T)$ ) is  $\dim(\text{ran}(T))$