Članovi tima: • Draško Petrović Lazar Lemić • Sale Bojić Saša Nedeljković Jelena Jelenković Jelena Katić Željko Simić Šef tima: • Lazar Lemić Datumi sastanka: • 24.12.2020. u 13:00 • 28.12.2020. U 17:00 Formalna specifikacija(Tim 3) Protivpožarni sistem $std_critical_temp = 65$ TEMP_SENSOR curr_temp?: Q temp_critical_level: \mathbb{Q} temp_critical_min = 45.0 $temp_critical_max = 100.0$ temp_sensor_active: {true, false} temp_critical_min <= curr_temp? <= temp_critical_max temp_critical_min <= temp_critical_level<= temp_critical_max temp_sensor_active \Leftrightarrow curr_temp?>= temp_critical TEMP_SENSOR_INIT ΔTEMP_SENSOR temp_critical_level' = std_critical_temp SET_CRITICAL_TEMP ΔTEMP_SENSOR new_critical_temp?: ℚ temp_critical_min <= new_critical_temp? <= temp_critical_max temp_critical_level' = new_critical_temp?

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SMOKE SENSOR
               smoke_sensor_active: {true, false}
def_{co}_{target_1} = 50
def_{co}_{target_2} = 100
                     CO_SENSOR
               curr_co_level: N
               co_target_1: N
               co_target_2: N
               co_sensor_active: {true, false}
               co_level: {low, med, high}
               co_level = low \Leftrightarrow o >= curr_co_level >= co_target_1
               co_level = med \Leftrightarrow co_target_1 > curr_co_level >= co_target_2
                co_level = high ⇔ curr_co_level > co_target_2
                     CO_SENSOR_INIT
               \DeltaCO_SENSOR
               co_target_1' = def_co_target_1
                co_target_2' = def_co_target_2
                     SET_CO_TARGET_1
               \DeltaCO_SENSOR
               new_co_target_1?: N
               0 < new_co_target_1? < co_target_2</pre>
                co_target_1' = new_co_target_1?
                     SET_CO_TARGET_2
               \DeltaCO_SENSOR
               new_co_target_2?: N
               co_target_1 < new_co_target_2?</pre>
                co_target_2' = new_co_target_2?
                     LIFT_SENSOR
               lift_floor?: ℤ
               lift_occupied?: {true, false}
                     FRONT_DOOR
               locked = {true, false}
                     SET_LIFT_OVERRIDE
               ΔLIFT_SENSOR
               lift_override_active: {true, false}
               lift\_floor \neq o \land lift\_occupied = true \land lift\_override\_active = true \Rightarrow lift\_floor' = o \Leftrightarrow lift\_floor' 
               lift_override_active' = false
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WATER_SENSOR
   water level percent: Q
   min_water_level_percent: Q
   water_critical = {true, false}
   min_water_level_percent= 15.0
   0.0 <= water_level_percent<= 100.0
   water critical = water level percent <= min water level percent
    MAIN_POWER_SENSOR
   main_pow_active: {true, false}
    AUX_POWER_SENSOR
   ΔMAIN_POWER_SENSOR
   aux_pow_level_percent: Q
   aux_critical_level: Q
   aux_pow_active: {true, false}
   aux_pow_critical: {true, false}
   aux_pow_active = true \iff main_pow_active = false
   aux_critical_level= 15.0
   aux_pow_critical = true \iff aux_pow_level_percent <= aux_critical_level
   0.0 >= aux_pow_level_percent >= 100.0
    VENT_SYSTEM
   vent_active: {true, false}
    SPRINKLERS_SYSTEM
   sprinklers_active: {true, false}
    SET_SPRINKLERS_ACTIVE
   ΔSPRINKLERS_SYSTEM
   ETEMP_SENSOR
   ESMOKE_SENSOR
   sprinklers_active = true ⇔ smoke_sensor_active = true ∧ temp_sensor_active = true
    ALARM_LIGHT
   light_active = {true, false}
def_temp_alarm_sound = 1
def_co_alarm_sound = 2
def_smoke_alarm_sound = 3
def_combined_alarm_sound = 4
def_alarm_single_intensity = 5
def_alarm_combined_intensity = 10
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ALARM
alarm armed: {true, false}
alarm_active: {true, false}
alarm_single_intensity: {1..10}
alarm combined intensity: {1..10}
alarm_sound: {1..8}
number_of_active_alarms: N
alarm\_armed = false \Rightarrow alarm\_active = false
 MANUAL_ALARM_ARMING
ΔALARM
arm_switch_position: {up, down}
arm alarm switch?: {up, down}
alarm_armed = true ∧ arm_alarm_switch ≠ arm_switch_position ⇒ alarm_armed = false ∧
arm_switch_position' = arm_alarm_switch
alarm_armed = false ∧ arm_alarm_switch ≠ arm_switch_position⇒ alarm_armed = true ∧
arm_switch_position' = arm_alarm_switch
 MANUAL_ALARM_ACTIVATION
\DeltaALARM
alarm_switch_position: {up, down}
activate_alarm_switch?: {up, down}
alarm_active = true ∧ activate_alarm_switch ≠ alarm_switch_position ⇒ alarm_active = false ∧
alarm_switch_position' = activate_alarm_switch
alarm_active = false \land activate_alarm_switch \neq alarm_switch_position \Rightarrow alarm_active = true \land
alarm_switch_position' = activate_alarm_switch
 ALARM_INIT
ΔALARM
alarm_armed = true
alarm_active = false
alarm_single_intensity = def_alarm_single_intensity
alarm_combined_intensity= def_alarm_combined_intensity
number_of_active_alarms = o
 ALARM_SOUNDS
temp_alarm_sound: {1..5}
co_alarm_sound: {1..5}
smoke_alarm_sound: {1..5}
combined_alarm_sound: {1..5}
water_alarm_sound = 6
aux_power_alarm_sound = 7
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pri to aux alarm sound = 8

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ALARM_SOUNDS_INIT
ΔALARM_SOUNDS
temp_alarm_sound = def_temp_alarm_sound
co_alarm_sound= def_co_alarm_sound
smoke_alarm_sound = def_smoke_alarm_sound
combined_alarm_sound = def_combined_alarm_sound
 SET ALARM SINGLE INTENSITY
\DeltaALARM
new_alarm_intensity?: N
1 >= new_alarm_intensity > alarm_combined_intensity
alarm_single_intensity = new_alarm_intensity?
 SET_ALARM_COMBINED_INTENSITY
\DeltaALARM
new\_alarm\_intensity?: N
alarm_single_intensity > new_alarm_intensity >= 10
alarm_combined_intensity = new_alarm_intensity?
 ACTIVATE_ALARM
\DeltaALARM
ΔALARM_LIGHT
ΔFRONT_DOOR
SET_LIFT_OVERRIDE
locked' = false;
alarm_active' = true
light_active' = true
 CHECK_TEMP
\DeltaALARM
EALARM_SOUNDS
ETEMP_SENSOR
temp_sensor_active = true \Leftrightarrow alarm_sound' = temp_alarm_sound
number_of_active_alarms > 1 ⇔ alarm_sound' = combined_alarm_sound
alarm_active' = true
 CHECK_SMOKE
\DeltaALARM
EALARM SOUNDS
ESMOKE_SENSOR
smoke sensor active = true ⇔ alarm sound' = smoke alarm sound
number_of_active_alarms > 1 ⇔ alarm_sound' = combined_alarm_sound
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alarm active' = true

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CHECK_WATER_LEVEL
\DeltaALARM
EWATER_SENSOR
EALARM_SOUNDS
water_critical = true ⇔ alarm_sound' = water_alarm_sound ∧ number_of_active_alarms' =
number_of_active_alarms + 1
number_of_active_alarms > 1 ⇔ alarm_sound' = combined_alarm_sound
alarm_active' = true
 CHECK_CO_LEVEL
\DeltaALARM
EALARM_SOUNDS
ECO_SENSOR
ΔVENT_SYSTEM
co_level = high ⇔ alarm_sound' = co_alarm_sound ∧ vent_active' = true
number_of_active_alarms > 1 ⇔ alarm_sound' = combined_alarm_sound
alarm_active' = true
 CHECK_POWER_LEVEL
\DeltaALARM
EALARM_SOUNDS
EMAIN_POWER_SENSOR
EAUX_POWER_SENSOR
main_pow_active = false \iff alarm_sound' = pri_to_aux_alarm_sound
aux_pow_critical = true ⇔ alarm_sound' = aux_power_alarm_sound
number_of_active_alarms > 1 ⇔ alarm_sound' = combined_alarm_sound
alarm_active' = true
 LOGS
unix_time?: №1
temp_logs : seq (N1 \times \mathbb{Z})
co_{logs} : seq (N1 \times \mathbb{Z})
 LOGS_INIT
\DeltaLOGS
temp_logs = <>
co_logs = <>
 LOGS_APPEND_TEMP
ΔLOGS
ETEMP_SENSOR
temp_logs' = temp_logs \cap <(unix_time, curr_temp)>
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LOGS_APPEND_CO		
ΔLOGS		
ECO_SENSOR		
$co_{logs'} = co_{logs} \cap <(unix_{time}, curr_{co_{level}})>$		
 _ FIRE_PREVENTION_SYSTEM		
CHECK_TEMP ∨ CHECK_SMOKE	E V CHECK_CO_LEVEL V CHECK_WATER_LEVEL V	
CHECK_POWER_LEVEL v LOGS_	$_$ APPEND $_$ TEMP \lor LOGS $_$ APPEND $_$ CO	