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APDE: Charpit: F(p, q, u, x, y) = 0 with u_x = p, u_y = q, \dot{x} = F_p, \dot{y} = F_q. Then via F_x, F_y, \& p_y = q_x \rightarrow p_\tau = -F_x - pF_u, q_\tau = -F_y - qF_u, u_\tau = pF_p + qF_q. Also, u_0 = p_0 x_0 + q_0 y_0; F_0 = 0 - last 2 needed to show u defined on Γ. Laplacian: In 2D : r^{-1}(rf_r)_r + r^{-2}f_{\theta\theta}. In 3D : r^{-2}(r^2f_r)_r + r^{-2}f_{\theta\theta}.
        r^{-2}\sin^{-2}(\theta)f_{\phi\phi}+r^{-2}\sin^{-1}(\theta)\left(\sin(\theta)f_{\theta}\right)_{\theta} Riemann: For u_{xy}+au_{x}+bu_{y}+cu=f we have \int_{D}RLu-uL^{*}R^{2}dt
         =\int_{D}\partial_{x}\left(Ru_{y}+auR\right)+\partial_{y}\left(-uR_{x}+buR\right)=\int_{\partial D}dy\left(Ru_{y}+Rau\right)+dx\left(uR_{x}-buR\right). Expand over trian-
        gle going B-P-A (B at bottom right) \rightarrow need R_x = bR@y = \eta, R_y = aR@x = \xi, R(P) = 1, L^*R = 0. Also ensure IVP to get R_y, R_x! R-H: Derived via P_x\psi + Q_y\psi = R\psi \rightarrow \int_D \left(P_x\psi\right)_x + \left(Q_y\psi\right)_y \left(=\int_\Gamma \psi P dy - \psi Q dx\right)
        \int_{D} P\psi_{x} + Q\psi_{y} + R\psi = \int_{D_{1} + D_{2}} P\psi_{x} + Q\psi_{y} + R\psi, \text{ where } \int_{D_{i}} = \int_{D_{i}} (P\psi)_{x} + (Q\psi)_{y}^{"} + \psi (R - P_{x} - Q_{y})
        So \int_{\Gamma} \psi P dy - \psi Q dx = \int_{\Gamma + C_1 - C_2} \psi P dy - \psi Q dx and so \int_{C_1 + C_2} \psi P dy - \psi Q dx = 0 \to dy/dx = [Q]_{-}^{+} / [P]_{-}^{+}
         Canonical: For au_{xx}+2bu_{xy}+cu_{yy}=f, we need Cauchy-Kowalevski s.t. first derive defined: x':=\frac{dx}{ds} s.t.
        on \Gamma p'_0 = x'_0 u_{xx} + y'_0 u_{xy}, q'_0 = x'_0 u_{xy} + y'_0 u_{yy}. Use these 3, solve det A!=0 s.t. ay'_0^2 - 2bx'_0 y'_0 + cx'_0^2 \neq 0. Solve
         quadratic s.t. b^2 > ac \to h, b^2 < ac \to e, b^2 = ac \to p. H: \lambda_1, \lambda_2 \to \xi, \eta. E: \lambda = \lambda_R \pm i\lambda_I; \lambda_R \to \xi, \lambda_I \to \eta.
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        P: \lambda_1 \to \xi, choose \eta independent e.g. xy, x^2. Green's Fn: For u_{xx} + u_{yy} + au_x + bu_y + cu = f we have
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         \int_{D} GLu - uL^{*}G = \int_{D} (u_{x}G)_{x} + (u_{y}G)_{y} - (uG_{x})_{x} - (uG_{y})_{y} + (auG)_{x} + (buG)_{y} = \int_{D} \nabla \cdot (u_{n}G - uG_{n}) + (u_{y}G)_{y} + (u_{y}G)_{y}
         \nabla \cdot ((a\ b)^T \hat{n} G u) = \int_{\partial D} u_n G - u G_n + (a\ b)^T \hat{n} G. NB \hat{n} = (dy, -dx). Also note for quarter plane if we have
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         G_x(0,y) = 0, G(x,0) = 0 then we have same sign at \xi_1 = (-x,y), opposite sign at \xi_2 = (x,-y), and for
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         the third we reflect \xi_2 across y axis so we have an opposite sign to \xi at \xi_3 = (-x, -y). Types: Quasi-
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         Coeffs don't depend on highest order derives Semi: Coeffs depend on x, y. Causality: For a n-dim prob.
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        we have n characteristics. Shock intersects 2n. \exists k outgoing, 2n-k ingoing. Also have n R-H relations,
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        so 3n-k pieces of info. Unknowns are n components of \vec{u} on both sides of shock & slope \Rightarrow 2n+1
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        unknowns. We demand 3n - k = 2n + 1 so k = n - 1 outgoing characterisites.
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        SAM: Dists: Need linearity and continuity: \exists N, C \text{ s.t. } |(u,\phi)| \leq C \sum_{m \leq N} \max_{\in [-X,X]} |\phi^{(m)}|. OR
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        \lim_{n\to\infty}(u,\phi_n)=(u,\lim_{n\to\infty}\phi_n) for a sequence \phi_n\to 0 as n\to\infty. Orthog: \int_0^\pi\sin(kx)\sin(jx)=\frac{\pi}{2}\delta_{kj}
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         same for cos.
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