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NLA: Golub for k = 1 : m, n: u_k = (sgn(b_{k,k}) || b_{k:m,k} || e_1 + b_{k:m,k}); u_k := \hat{u}_k; U_k := I - 2u_k u_k^T;
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      B_{k:m,k:n} := U_k B_{k:m,k:n}; U = [I_{k-1,k-1}, 0; 0, U_k]; \text{for } j = 1 : m, n-1: \ v_k^T := sgn(b_{k,k+1}) \|b_{k,k+1:n}\| e_1 + u_k B_{k:m,k:n} \|b_{k,k+1:n}\| e_1 + u_k B_{k,k+1:n} \|b_{k,k+1:n}\| e_1 + u_k 
      b_{k:m,k}; V_k := I - 2v_k v_k^T; B_{1:m,k+1:n} = B_{1:m,k+1:n} V_k; V = [I_{k,k}, 0; 0, V_k] endfor endfor; 2 \cdot (2mn^2 - 2n^3/3)
      Householder for k = [1, n]: x = A_{k:m,k}; v_k = sgn(x) ||x|| e_k + x; v_k = \frac{v_k}{\|v_k\|} for j = [k, n] A_{k:m,j} = [k, n]
      A_{k:m,j} - 2v_k [v_k^* A_{k:m,j}] endfor endfor. 2mn^2 - \frac{2n^3}{3}. MG-S V = A; for i = [1,n]: r_{ii} = ||v_i||; q_i = \frac{v_i}{r_{ii}}; for
      j = [i+1, n] \ v_j = v_j - (q_i^T v_j) q_i; r_{ij} = q_i^T v_j \text{ endfor endfor. } 2mn^2.  Arnoldi: q_1 := \hat{b}; q_{k+1} h_{k+1,k} = 0
      Aq_k - \sum_{i=1}^k q_i h_{ik}; \ h_{ik} = q_i^T(Aq_k); \ h_{k+1,k} := \|v\| \to AQ_k := Q_k H_k + q_{k+1}[0 \dots h_{k+1,k}]. Givens
      3mn^2 \text{ SVD:} = \sum_{i=\min m,n}^{r_i + r_i + r_i} u_i \sigma_i v_i^T. \text{ C-F: } \sigma_i(A)\sigma_n(B) \leq \sigma_i(AB) \leq \sigma_i(A)\sigma_1(B) \text{ QR Algo: } A_{k+1} = 0
      Q_k^T A_k Q_k \to A_{k+1} = (Q^{(k)})^T A Q^{(k)}. \text{ Next } A^{k-1} = (Q_1 \dots Q_{k-1})(R_{k-1} \dots R_1), \text{ so } A_k = Q_k R_k = (Q^{(k-1)})^T A Q^{(k-1)} \text{ so } Q^{(k-1)} A_k = A Q^{(k-1)}. \text{ So } A^k = (A Q^{(k-1)}) R^{(k-1)} = Q^{(k)} R^{(k)} \text{ as } A_k = Q_k R_k.
      Krylov: Usually want x_k - x_0 \in \mathcal{K}_k. Also note to show CG span properties first show \{r_k\} \subset \{p_k\} etc
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      then show \{p_k\} LI. GMRES: \min \|AQ_k y - b\|_2 \to \min \|H_k y - \|b\|e_1\|. Bound \|r_k\| = \|Mp(\Lambda)M^{-1}r_0\|
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      GMRES Conv: If x_k = p_{k-1}(A)b have \min ||Ax_k - b|| = \min_{p(0)=1} ||Ap_{k-1}(A)b - b|| \le k_2(A)||p(\Lambda)b||
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      with p(0) = 1 CG Bound: With c = x - x_0, c_k = x_k - x_0 s.t. r_k = A(c - c_k) we have r_k^T v =
      0 \ \forall \ v \in \mathcal{K}_k \text{ so } v^t A(c - c_k) = 0, \text{ s.t. } y = c_k = \arg\min \|c - y\|_A. \text{ WTS } e_k = e_0 p_k(A) \text{ with } p(0) = 1,
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      and write e_0 := \sum \gamma_i v_i with Av_i = \lambda_i v_i \rightarrow \|e_k\|_A = \min_{p_k, p(0)=1} \max |p(\lambda_i| \|e_0\|_A CG Conver-
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      gence: ||e_k||_A = \min_{p(0)=1} ||p_k(A)e_0|| = \min_{p_k(A)} \max |p_k(\lambda)| ||e_0|| \to \le 2 \left( (\sqrt{k_2} - 1)/(\sqrt{k_2} + 1) \right)^k; need
      \alpha := 2(\lambda_1 + \lambda_2) Cheb: T_k(x) = \frac{1}{2}(z^k + z^{-k}); 2xT_k = T_{k+1} + T_{k-1} Cheb Shift: Choose p(x) = T_{k+1} + T_{k-1}
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      T_k([2x-b-a]/[b-a])/T_k([-b-a]/[b-a]) s.t. p(0) = 1. Then p \le 1/|T_k([-b-a]/[b-a])| \le 1/|T_k([-b-a]/[b-a])|
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      2\left(\left[\sqrt{\kappa}-1\right]/\left[\sqrt{\kappa}+1\right]\right)^k CG Conditions: To show r_{k+1}^T r_k = 0 first show p_k^T A p_k = p_k^T A r_k via \beta then show
      p_k^T r_k = r_k^T r_k via p_{k-1}^T r_k = 0. Preconditioning: For GMRES solve MAx = Mb with MA eigvals clus-
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      tered far from 0, well conditioned. E.g. if A = LU do (LU)^{-1}. For CG, A = A^T difficult so want M^TM \approx
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       A^{-1}. So want M^TAMy = M^Tb, same properties. \mathbf{MP}: \sigma(G) \in [\sqrt{m} - \sqrt{n}, \sqrt{m} + \sqrt{n}] \to k_2 = O(1)
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      Sketch: with GA\hat{x} = Gb, and via C - F \|G[A, b][v, -1]^T\| \le (s + \sqrt{n+1}) \|R[v, -1]^T\|, similar for lower
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       bound via MP \to ||A\hat{x} - b|| \le (\sqrt{s} + \sqrt{n+1})/(\sqrt{s} - \sqrt{n+1})||Ax - b|| Blend: solve ||(A\tilde{R}^{-1})y - b|| = 0
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      via CG; k_2(A\tilde{R}^{-1}) = O(1) with GA = \tilde{Q}\tilde{R} PROOF: A = QR; GA = GQR = \hat{G}R. Let \hat{G} = \hat{Q}\hat{R} so
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      GA = \hat{Q}\hat{R}R = \hat{Q}(\hat{R}R) \to \tilde{R}^{-1} = R^{-1}\hat{R}^{-1} \to k_2(A\tilde{R}^{-1}) = k_2(\hat{R}^{-1}) = O(1) by MP. O(mn) to solve via
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      normal HMT: For X = n \times r let AX = QR, then if A = U_r \Sigma_r V_r^T, span(Q) = \text{span}(U_r) so \hat{A} = QQ^T A is a
      rank r approximant. HMT Proof: Goal ||A - \hat{A}|| = O(1)||A - A_r||. Have (I - QQ^T)AX = 0 so A - \hat{A} = 0
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      (A_n - QQ^T)A(I_n - XM^T) = 0 \ \forall M^T. Choose M^T = (V^TX)^{\dagger}V^T, V \in n \times \hat{r} \le r. Let XM^T = P s.t. A(I - QQ^T)A(I_n - XM^T) = 0
      P(P) = A(I - VV^T)(I - P). So ||A - \hat{A}|| = ||(I_m - QQ^T)U_A\Sigma_A[\tilde{V}_{\hat{r}}^T, \tilde{V}_{\hat{r}+1}^T]^T(I - VV^T)(I - P)||. If V = A(I - VV^T)(I - P)
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      \tilde{V}_r \text{ then } = \left\| (I_m - QQ^T)U_A \Sigma_A[0, \tilde{V}_{\hat{r}+1}]^T (I - P) \right\| \le \|\Sigma_{\hat{r}+1}\| \|I_n - XM^T\|. \text{ Now note } \|I_n - XM^T\| = 0
       \left\|I_n - X(\tilde{V}_r^T X)^{\dagger} \tilde{V}_r^T \right\| \le 1 + \|X\| \left\| (\tilde{V}_r^T X)^{\dagger} \right\|. Now \|X\| \le \sqrt{n} + \sqrt{r} by MP, and \left\| (\tilde{V}_r^T X)^{\dagger} \right\| = \sigma_n (\tilde{V}_r^T X)^{-1} \le 1 + \|X\| \left\| (\tilde{V}_r^T X)^{\dagger} \right\|.
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      Application: \sigma_i([A_1; A_2]) \ge \max(\sigma_i(A_1), \sigma_i(A_2)) Schur: Take Av_1 = \lambda_1 v_1; construct U_1 = [v_1, V_{\perp}] \rightarrow
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      AU_1 = U_1[e_1, X]. Repeat. Conditioning \kappa_2(A) = \sigma_1/\sigma_n = ||A|| ||A^{-1}|| Similarity: A \to P^{-1}AP, same
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      \lambda. Pseud-Inv: A^{\dagger} = V \Sigma^{-1} U^T
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      CO: G-N: \vec{x}_{k+1} = \vec{x}_k - \frac{\nabla f_k}{J^T J}, with J := \text{Jacobian of } r(x) Linesearch Convergence: Show x_{k+1} - x_* = \frac{\nabla f_k}{J^T J}
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      \Psi(x_k) - x_* = \Psi(x_* + e_k) - x_* and taylor expand. SD: ||x_{k+1} - x_*|| \le (k_2(H) - 1)/(k_2(H) + 1)||x_k - x_*||
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      with H hessian. Also note with EXACT linesearch for quadratic, H(x - x_*) = -s. Rayleigh:
       \frac{s^T H s}{\|x\|^2} \le \|H\| bArm: To show existence of \alpha, have \phi(\alpha) = f(x_k + \alpha_k s_k), \psi(\alpha) = \phi(\alpha) - \phi(0)
      \beta \alpha \phi'(0) \leq 0, show \psi'(0) = (1-\beta)\phi'(0) \leq 0 \rightarrow \psi(\alpha) \downarrow \text{ with } \alpha. BFGS: To show H_{k+1} \geq 0 nec.
      \gamma^T \delta > 0. Suff via \gamma, \delta LI \rightarrow use \|\cdot\|_H \rightarrow \gamma^{\overline{T}} \delta > 0. Quad Penalty Meth With y = -c/\sigma, \|\nabla_{\sigma}\Phi\| \le \epsilon^k, \sigma^k \rightarrow 0, x \rightarrow x_*, \nabla c(x_*) LI, then y \rightarrow y_*, x \rightarrow KKT, if f, c \in C^1. Also need J_*^T full row rank.
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      PROOF: If y_* := J_*^{\dagger} \nabla f_* \to \|y_k - y_*\| = \|J_*^{\dagger} \nabla f_* - y_k\| \le \|J_k^{\dagger} \nabla f_k - J_*^{\dagger} \nabla f_*\| + \|J_k^{\dagger} \nabla f_k - y_k\|. Next
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       \left\|J_k^{\dagger} \nabla f_k - y_k\right\| \leq \left\|J_k^{\dagger}\right\| \left\|\nabla_{\sigma} \Phi\right\| \to 0. \text{ Also, } \nabla f_* - J_*^T y_* \to 0, \text{ and } c_{k \to *} = -\sigma^{k \to *} y_{k \to *} = 0 \text{ so } x_* \to KKT
      Quad Pen. Meth Newt Have w = (J\Delta x + c)/\sigma so [\nabla^2 f, J^T; J, -\sigma I][\Delta x, w]^T = -[\nabla f, c] Trust
      Region Radius: \rho_k := (f(x_k) - f(x_k + s_k))/(f(x_k) - m_k(s_k)) TR-Method: If \rho \geq 0.9 then dou-
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      ble radius, update step x_{k+1} = x_k + s_k. If \rho \geq 0.1 then same radius, update step. If \rho small shrink
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      radius, don't update step. Cauchy: Is the point on gradient which minimises the quadratic model
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within TR. Want m_k(s_k) \leq m_k(s_{kc}), where s_{kc} := -\alpha_{kc} \nabla f(x_k), and \alpha_{kc} := \arg \min m_k (\alpha \nabla f(x_k))
         subject to \|\alpha \nabla f\| \leq \Delta, i.e. \alpha_{max} := \Delta/\|\nabla f\|. Calculation of Cauchy: We want to prove cauchy
         model decrease i.e. f(x_k) - m_k(s_k) \ge f(x_k) - m_k(s_{kc}) \ge 0.5 \|\nabla f_k\| \min \left\{ \Delta_k, \frac{\|\nabla f_k\|}{\|\nabla^2 f_k\|} \right\}. First define
         \Psi(\alpha) := m_k(-\alpha \nabla f) \text{ s.t. } \Psi := f_k - \alpha \|f_k\|^2 - 0.5\alpha^2 H_k, \text{ with } H_k := \left[\nabla f_k\right]^T \left[\nabla^2 f_k\right] \left[\nabla f_k\right]. \text{ N.B. that}
         \alpha_{min} := \frac{\|\nabla f_k\|^2}{H_k} \text{ if } H_k > 0, \text{ from } \Psi'(0) < 0. \text{ Now A: If } H_k \leq 0 \text{ then we have } \Psi(\alpha) \leq f_k - \alpha \|\nabla f_k\|^2 \to \alpha_{kc} = \alpha_{max}. \text{ So, we have } f_k - m_{s_k} \geq f_k - m_{s_{kc}} \geq \|\nabla f_k\| \Delta_k \geq 0.5 \|\nabla f_k\| \min\left\{\Delta_k\right\}. \text{ Now B.i. If } H_k > 0 \to \alpha_{kc} = \alpha_{min}. \text{ Here } f_k - m_{s_{kc}} = \alpha_{kc} \|\nabla f\|^2 - 0.5\alpha_{kc}^2 H_k = \frac{\|\nabla f\|^4}{2H_k} \geq \frac{\|\nabla f\|}{2} \min\left\{\frac{\|\nabla f\|}{\|\nabla^2 f\|}\right\} \text{ via } f_k = \frac{\|\nabla f\|^4}{2H_k} = \frac{\|\nabla f\|^4}
         C-S. Now B.ii: If H_k > 0 \to \alpha_{kc} = \alpha_{max}. Here \Delta/\|\nabla f\| \le \|\nabla f\|^2/H_k \to \alpha_{kc}H_k \le \|\nabla f\|^2. So f_k - m_{kc} = -\alpha_{kc}\|\nabla f\|^2 + \frac{\alpha_{kc}^2}{2}H_k \ge \frac{\|\nabla f\|^2}{2}\alpha_{kc} \ge 0.5\|\nabla f\|\min\{\Delta_k\} TR-Global Convergence: If m_k(s_k) \le m_k(s_{kc}) then either \exists k \ge 0 s.t. \nabla f_k = 0 or \lim \|\nabla f\| \to 0. Further, require f \in C^2,
         bounded below and also \nabla f L-cont. PROOF: Using def of \rho, f_k - f_{k+1} \geq \frac{0.1}{2} \|\nabla f_k\| \min \{\ldots\} from
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         above. Let \|\nabla^2 f\| := L, and assuming \|\nabla f\| \ge \epsilon we have f_k - f_{k+1} \ge 0.05 \frac{c}{L} \epsilon^2 assuming TR has a
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         lower bound c\epsilon/L. Then sum over all successful jumps s.t. f_0 - f_{lower} \ge \sum_{i \in \mathbb{S}} f_i - f_{i+1} \ge |\mathbb{S}| \frac{0.05c\epsilon^2}{L}
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         Solving TR Prob: Solve secular ||s||^{-1} - \Delta^{-1} = 0. KKT Feasibility: Need s^T J \geq 0, J_E^T s = 0, and
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         s^T \nabla f < 0. KKT Conditions: REMEMBER c \geq 0, \lambda \geq 0! First Order KKT (Equality): If we
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         have x_* local min, then let x = x_* + \alpha s. Then we have c_i(x(\alpha)) \to 0 = c_i(x_*) + \alpha s^T J \to s^T J = 0.
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         Further, we have f(x) = f(x_*) + \alpha s^T \nabla f \to \alpha s^T \nabla f \geq 0. Repeat for negative \alpha s.t. s^T \nabla f = 0. By
         Rank-Nullity (assuming J_E(x_*) full rank), we have \nabla f_* = J_*^T y + s_* for some y_*, which then implies
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         (after s^T from LHS) that ||s_*|| = 0, so \nabla f_* = J_*^T y_*. KKT 2nd Order If we have min f with c(x) \geq 0,
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         2^{nd} order conditions are that s^T \nabla^2 \mathcal{L} s \geq 0 for all s \in \mathcal{A}, with \mathcal{A} defined s.t. EITHER s^T J_i = 0 \ \forall \ i \ \text{s.t.}
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         \lambda_i > 0, c_i = 0, OR s^T J_i \ge 0 \ \forall i s.t. \lambda_i = 0, c_i = 0, for J, c, \lambda evaluated at x_* For EQUALITY constraints
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         instead need positive definite \forall s s.t. J^T s = 0 Convex Problems \hat{x} = KKT \Rightarrow \hat{x} = \arg\min f(x).
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         Proof via f \geq f(\hat{x}) + \nabla f^T(x - \hat{x}) so f \geq f(\hat{x}) + \hat{y}^T A(x - \hat{x}) + \sum_{i \in I} \lambda_i J_i^T(x - \hat{x}). Choose Ax = b,
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        and note that c_i concave s.t. \lambda_i J_i^T(\hat{x})(x-\hat{x}) \geq \lambda_i (c_i(x)-c_i(\hat{x})) = \lambda_i c_i(x) \geq 0 \rightarrow f(x) \geq f(\hat{x}). Log-Barrier Global Convergence: (for f - \sum \mu \log(c_i)) With f \in C^1, \lambda_{ik} = \frac{\mu_k}{c_{ik}}, \|\nabla f_u(x_k)\| \leq \epsilon_k, \mu_k \rightarrow 0, x_k \rightarrow x_*. Also, \nabla c(x_*)LI \ \forall \ i \in \mathcal{A} (active constraints). Then x_* KKT and \lambda \rightarrow \lambda_*. PROOF:
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         Have J_A^{\dagger}(x_*) = (J_A(x_*)J_A(x_*)^T)^{-1}J_A(x_*). Also, c_A = 0, c_I > 0. So \lambda = \mu/c \to 0 so \lambda_I = 0 as
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         c_I > 0. Next \|\nabla f_k - J_{Ak}\lambda_{Ak}\| \le \|\nabla f_k - J_k^T\lambda_k\| + \|\lambda_I\|M_1 = \|\nabla f_{\mu k}\| \to 0. Now \|J_A^{\dagger}\nabla f_k - \lambda_{kA}\| \le \|\nabla f_k\| + \|\Delta_I\|M_1 = \|\nabla f_{\mu k}\| \to 0.
          ||J_A^{\dagger}|| ||\nabla f_k - J_{Ak}^T \lambda_{Ak}|| \to 0. So with triangle ineq ||\lambda_{kA} - J_{Ak}^{\dagger} \nabla f_k + J_{Ak}^{\dagger} \nabla f_k - \lambda_{A*}|| \to 0, via cont. of
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         \nabla f and J^{\dagger}. Thus \lambda_{Ak} \to \lambda_{A*} \geq 0. Combine s.t. \nabla f_k - J_{Ak}^T \lambda_{AK} with k \to * so get KKT. Primal-Dual Newton: Have \nabla f = J^T \lambda, C(x) \lambda = \mu e so [\nabla^2 \mathcal{L}, -J^T; \Lambda J, C][dx, d\lambda]^T = -[\nabla f - J^T \lambda, C\lambda - \mu e]^T
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         Augmented Lagrangian: Same result as QUAD PEN METH but x \to x_* if \sigma \to 0 for bounded u_k
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         or u_k to y_* for bounded \sigma_k. Proof via ||c_k|| \le \sigma_k ||y_k - y_*|| + \sigma_k ||u_k - y_*||. If u_k bounded then \to 0 as
         \sigma \to 0, else trivially if u_k \to y_* then to 0. GLM Global Convergence: With f \in C^1, \nabla f L-Cont,
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         and f bdd below, then \nabla f_l = 0 or \liminf \left\{ \frac{|\nabla f^T s|}{\|s\|}, |s^T \nabla f| \right\} to 0. In non-trivial case, via bArmijo,
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         f_k - f_{k+1} \ge -\beta \alpha_k s_k^T \nabla f_k = \beta \alpha_k |s_k^T \nabla f_k|. Sum s.t. f_0 - f_{k+1} \ge \beta \sum_k \alpha_k |s_k^T \nabla f_k|, so term in sum to 0. For
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         all k successful we then have \alpha_k |s_k^T \nabla f_k| \ge \frac{(1-\beta)\tau}{L} \left( \frac{|s_k^T \nabla f_k|}{\|s_k\|} \right)^2 \ge 0 so squared term to 0. For unsuccessful
         steps \alpha_k \geq \alpha_0 so no norm term. Convergence Newton LSearch: Need f \in \mathbb{C}^2 then if H_k (hessian)
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         bdd above and below, so \lambda_n \leq \lambda(H_k) \leq \lambda_1. So \left| s_k^T \nabla f_k \right| \geq \lambda_1^{-1} \|\nabla f_k\|^2. Also \|s_k\|^2 \leq \lambda_n^{-2} \|\nabla f_k\|^2. Thus
         \lim \min \left\{ \lambda_n \lambda_1^{-1} \| \boldsymbol{\nabla} f \|, \lambda_1^{-1} \| \boldsymbol{\nabla} f \|^2 \right\} \to 0 from GLM Convergence Thm.
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