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NS: Classifications: Node: \lambda_i \in \mathbb{R}, \Pi \lambda_i > 0 Centre: \lambda_i = \pm ib Focus: \lambda_i = a \pm ib Hyperbolic: \operatorname{Re}(\lambda)
      \neq 0 \rightarrow \text{hyperbolic.} If all \lambda < 0 for \text{Spec}(Df(x_0)) then A-Stable Invariant Set: \phi_t(S) \subseteq S Lim
     Pts: \omega pt. if \lim_{t\to\infty}\phi(x)=p, i.e. flows tend to p. \alpha pt. if \lim_{t\to-\infty}\phi(x)=p. Attracting Set:
      A set A \subseteq S if \exists neighbourhood U s.t. \phi(U) \subseteq U \forall t \geq 0, and A = \cap_{t>0} \phi(U) Dense Orbits: If
     \forall \epsilon > 0, x \in A \text{ with } A \text{ an attracting set, } \exists \tilde{x} \in \Gamma s.t. |x - \tilde{x}| < \epsilon. \text{ I.e. a dense orbit goes as close as}
     needed to any point within A Attractor: An attracting set with a dense orbit. Lyapunov Stable: If
     \forall \epsilon > 0, \exists \ \delta > 0 \text{s.t.} \forall \ x \in B_{\delta}, t \geq 0, \phi(t) \in B_{\delta} \text{ (i.e. points stay close within region)}. Asymptotically
      Stable: If L-Stable and \exists \ \delta > 0 s.t. \phi(x) \to x_0 \forall x \in B_\delta Lyapunov F'n: V(x_0) = 0, V(x) > 0 \forall \ x \neq x_0.
      Then if V < 0 \to A-Stable, or if V \le 0 L-Stable. Stable Manifold: If spectrum of Df(x_0) has k
      eigvals with positive real parts, and n-k with negative, then \exists an n-k dim manifold tangent to E^s
      s.t. for all t > 0 \phi(W^s_{loc}) \subseteq W^s_{loc}, and \forall x \in W^s_{loc}\phi(x) \to x_0 as time increases. Repeat for k-dim unstable
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      manifold but for negative time. Then, define e.g. global stable manifold by W^s(x_0) := \bigcup_{t < 0} \phi_t(W^s_{loc}).
      Note that we search backwards in time for stable, and forwards for unstable! Centre Manifold: If
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     x_0 not hyperbolic (0 real part), then E^c is the centre subspace. Then \exists W^c parallel to E^c, of class
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     C^r, and invariant under flow. Want bifurcation at \mu = 0, so with change of variables first find eigences
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      v_1, v_2. Then, construct P := [v_1, v_2] s.t. \vec{x} = P\vec{\xi}. Solve for \vec{\xi} and then expand with \eta = h(\xi, \tilde{\mu})
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      Transcritical Bifurcation: Always two points, change type at origin. E.g. \dot{x} = \mu x - x^2 Saddle-
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      Node: E.g. \dot{x} = \mu - x^2 Bifurcation begins to exist at origin. Supercritical: E.g. \dot{x} = \mu x - x^3, where
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      stable \to 2\times stable and one unstable. Subcritical: E.g. \dot{x} = -\mu x + x^3, where unstable \to 2\times unstable
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      and one stable. General co-dim 1: If \dot{x} = f then \dot{x} = \mu f_u + 0.5x^2 f_{xx} + x\mu f_{x\mu} + 0.5\mu^2 f_{\mu\mu}. Generally
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      this is a saddle-node but if f_u = 0 we have \dot{x} = x\mu f_{x\mu} + 0.5x^2 f_{xx}, which is a transcritical. However if
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     x = -x then \dot{x} = x(\mu f_{x\mu} + \ldots) + x^3(f_{xxx}/6 + \ldots) \to \text{pitchfork}. Saddle-node stable under perturbations!
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     HomoClinic Orbits Sum of roots of cubic = - coeff. of x^2
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      FPDE: Types: 1^{st}:\exists scale s.t. solution found, not so for 2^{nd}. Heat: \ddot{T}=u(\ddot{T}_{\infty}-\ddot{T}_{-\infty})+\ddot{T}_{-\infty} Oil
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     Spread: Dims: x = x_f + \varepsilon \xi, t = \tau Ground Spread: (1 - s)\phi h_t + Q_x = 0; Q \sim -hh_x, 0 < x_s < x_f. Have
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     h(x_f) = 0, h_t(x_s) = 0, and hh_x|_{x=0,x_f} = 0 (i.e. no flux at centre and front), and h, hh_x cont. at joint.
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     Expansions: Let \xi = z + \epsilon \eta for perturbations Scale: Try x = x_f + \epsilon \xi for groundwater Stefan: S_0 = \epsilon \xi
     C\left(T_1-T_m\right)/L, condition = \rho L\dot{s}=kT_x|_{s-}^{s-} 1ph Stefan: Bar = T_h|liq|_s sol|INS. Use T=T_m+(T_1-T_m)u
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     s.t. S_0 u_t = u_{xx}, u = 1 @ x = 0, \{\dot{s} = -u_x, u = 0\} @ x = s, s(0) = 0. Sim. sol is s = \beta \sqrt{t}, f = f(x/\sqrt{t})
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     2ph Stefan: Use T = T_m + (T_1 - T_m)u s.t. S_0u_t = u_{xx} @ 0 < x < s, (S_0/\kappa)u_t = u_{xx} @ s < x < 1, u = 1 @ x = 0, u_x = 0 @ x = 1, {<math>\dot{s} = Ku_x|_{s_+} - u_x|_{s_-}, u = 0} @ x = s, \{s = 0, u = -\theta\} @ x = 0. Here
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     \theta := (T_m - T_0)/(T_1 - T_m), \kappa := c_1 k_1/(c_2 k_2), K := k_2/k_1 \text{ Sim. sol is } s = \beta \sqrt{t}, f = f(x/\sqrt{t}) \text{ 2-Dim:}
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     U_n = \hat{n} \cdot u = K(u_2)_n - (u_1)_n. If x = f(y,t) then \hat{n} := \nabla (x-f) = [1,-f_y]^T/\sqrt{1+f_y^2} Welding:
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     Have 0 < s_2 < s_1. Have cold x = a, no flux x = 0. \theta = 1 in liquid. In mush \rho L\theta_t = J^2/\sigma, CoE
       	heta 	het
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       -1 @ x = 1, \theta = 0 @ x = s_1. Also \theta_t = q in mush.
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      FMM: Integral Constraint If J[y] = \int F dx with \int G dx = C then \tilde{J}[y] = \int F - \lambda G dx Hamiltonian:
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     H:=y'F_{y'}-F\to H'=-F_x. If F=F(y,y) then H=C Hamilton's Eqs: p:=F_{y'},q=y
     and so p' = -H_q, q' = H_p Free Boundary: J[y,b] = \int_a^b F(x,y,y')dx where b free. Expand with
     y + \epsilon \eta, b + \epsilon \beta \to J = J_0 + \epsilon \left\{ \int_a^b \eta F_y + \eta' F_{y'} dx + \beta F(b, y(b), y'(b)) \right\} \text{If } y(b) = d \to d = y(b + \epsilon \beta) + \epsilon \eta(b + \epsilon \beta) = 0
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     y(b) + \epsilon(\beta y'(b) + \eta(b)) so \eta(b) = -\beta y'(b). IVP on integral so \beta [F - y'F_{y'}]_{x=b} + \int (\ldots) = 0 so F = y'F_{y'}
     at free boundary. Control: Have \int \xi h_x + \eta h_u dt = 0, \dot{\xi} = \xi f_x + \eta f_u. Sub for \eta, IVP s.t. \frac{d}{dt} \frac{h_u}{f_u} = h_x - f_x \frac{h_u}{f_u}
42
     and \dot{x} = f Hamiltonian (Control): H := f \frac{h_u}{f_u} - h s.t. \dot{H} = \frac{h_u}{f_u} f_t - h_t \to \text{autonomous if } h_t = f_t = 0
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     Fredholm Alt Integ Eqs. For y = f + \int K(x,t)y(t)dt we have ONE (N) has a unique sol y = 0 if f = 0
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      and adjoint has unique sol, or TWO (H) as sols y_1 \dots y_r iff \forall solutions to H^*, z_i, we have \langle f, z_i \rangle = 0. EX:
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     Solve y = f + \lambda \int \sin(x+t)y(t)dt. Unique sol iff (H) has trivial sol \to X_1 = \int y \cos(t) = \int \cos(t)y_H(t) \to \int \sin(x+t)y(t)dt.
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      solve [1, -\lambda \pi; -\lambda \pi, 1][X_1, X_2]^T = [0, 0]^T \to \text{unique sol if } \lambda \neq \pm 1/\pi. In this case X_1 = \int \cos(x) y_N(x) =
      \lambda \pi X_2 + \int f(x) \cos(x), and similar for X_2. Invert matrix and solve. If non-unique sol, then find sols to
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      (H) first. If \lambda = 1/\pi then X_1 = X_2 = X so Ly = y - \pi^{-1}(\sin(x) + \cos(x)) \int \cos(x)y(x)dx with sols
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     y = c_1(\sin(x) + \cos(x)) by inspection. Problem self adjoint so Ly = 0 = L^*w so need \int f(x)w(x) = 0
     i.e. \int f(x)(\sin(x)+\cos(x))=0, repeat for \lambda=-1/\pi. Then y=y_p(x)+\sum_i y_{h,i}(x) Fred Diff Eq. For
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      nonunique sol to exist, need \langle Ly, w \rangle = \langle f, w \rangle \forall ws.t.L^*w = 0
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