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APDE: Charpit: F(p, q, u, x, y) = 0 with u_x = p, u_y = q, \dot{x} = F_p, \dot{y} = F_q. Then via F_x, F_y, \& p_y = q_x \rightarrow p_\tau = -F_x - pF_u, q_\tau = -F_y - qF_u, u_\tau = pF_p + qF_q. Also, u_0 = p_0 x_0 + q_0 y_0; F_0 = 0 - last 2 needed to show u defined on Γ. Laplacian: In 2D : r^{-1}(rf_r)_r + r^{-2}f_{\theta\theta}. In 3D : r^{-2}(r^2f_r)_r + r^{-2}f_{\theta\theta}.
        r^{-2}\sin^{-2}(\theta)f_{\phi\phi}+r^{-2}\sin^{-1}(\theta)\left(\sin(\theta)f_{\theta}\right)_{\theta} Riemann: For u_{xy}+au_{x}+bu_{y}+cu=f we have \int_{D}RLu-uL^{*}R^{2}dt
         =\int_{D}\partial_{x}\left(Ru_{y}+auR\right)+\partial_{y}\left(-uR_{x}+buR\right)=\int_{\partial D}dy\left(Ru_{y}+Rau\right)+dx\left(uR_{x}-buR\right). Expand over trian-
        gle going B-P-A (B at bottom right) \rightarrow need R_x = bR@y = \eta, R_y = aR@x = \xi, R(P) = 1, L^*R = 0. Also ensure IVP to get R_y, R_x! R-H: Derived via P_x\psi + Q_y\psi = R\psi \rightarrow \int_D \left(P_x\psi\right)_x + \left(Q_y\psi\right)_y \left(=\int_\Gamma \psi P dy - \psi Q dx\right)
        \int_{D} P\psi_{x} + Q\psi_{y} + R\psi = \int_{D_{1} + D_{2}} P\psi_{x} + Q\psi_{y} + R\psi, \text{ where } \int_{D_{i}} = \int_{D_{i}} (P\psi)_{x} + (Q\psi)_{y}^{"} + \psi (R - P_{x} - Q_{y})
        So \int_{\Gamma} \psi P dy - \psi Q dx = \int_{\Gamma + C_1 - C_2} \psi P dy - \psi Q dx and so \int_{C_1 + C_2} \psi P dy - \psi Q dx = 0 \to dy/dx = [Q]_{-}^{+} / [P]_{-}^{+}
         Canonical: For au_{xx}+2bu_{xy}+cu_{yy}=f, we need Cauchy-Kowalevski s.t. first derive defined: x':=\frac{dx}{ds} s.t.
        on \Gamma p'_0 = x'_0 u_{xx} + y'_0 u_{xy}, q'_0 = x'_0 u_{xy} + y'_0 u_{yy}. Use these 3, solve det A!=0 s.t. ay'_0^2 - 2bx'_0 y'_0 + cx'_0^2 \neq 0. Solve
         quadratic s.t. b^2 > ac \to h, b^2 < ac \to e, b^2 = ac \to p. H: \lambda_1, \lambda_2 \to \xi, \eta. E: \lambda = \lambda_R \pm i\lambda_I; \lambda_R \to \xi, \lambda_I \to \eta.
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        P: \lambda_1 \to \xi, choose \eta independent e.g. xy, x^2. Green's Fn: For u_{xx} + u_{yy} + au_x + bu_y + cu = f we have
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         \int_{D} GLu - uL^{*}G = \int_{D} (u_{x}G)_{x} + (u_{y}G)_{y} - (uG_{x})_{x} - (uG_{y})_{y} + (auG)_{x} + (buG)_{y} = \int_{D} \nabla \cdot (u_{n}G - uG_{n}) + (u_{y}G)_{y} + (u_{y}G)_{y}
         \nabla \cdot ((a\ b)^T \hat{n} G u) = \int_{\partial D} u_n G - u G_n + (a\ b)^T \hat{n} G. NB \hat{n} = (dy, -dx). Also note for quarter plane if we have
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         G_x(0,y) = 0, G(x,0) = 0 then we have same sign at \xi_1 = (-x,y), opposite sign at \xi_2 = (x,-y), and for
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         the third we reflect \xi_2 across y axis so we have an opposite sign to \xi at \xi_3 = (-x, -y). Types: Quasi-
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         Coeffs don't depend on highest order derives Semi: Coeffs depend on x, y. Causality: For a n-dim prob.
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        we have n characteristics. Shock intersects 2n. \exists k outgoing, 2n-k ingoing. Also have n R-H relations,
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        so 3n-k pieces of info. Unknowns are n components of \vec{u} on both sides of shock & slope \Rightarrow 2n+1
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        unknowns. We demand 3n - k = 2n + 1 so k = n - 1 outgoing characterisites.
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        SAM: Dists: Need linearity and continuity: \exists N, C \text{ s.t. } |(u,\phi)| \leq C \sum_{m \leq N} \max_{\in [-X,X]} |\phi^{(m)}|. OR
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        \lim_{n\to\infty}(u,\phi_n)=(u,\lim_{n\to\infty}\phi_n) for a sequence \phi_n\to 0 as n\to\infty. Orthog: \int_0^\pi\sin(kx)\sin(jx)=\frac{\pi}{2}\delta_{kj}
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         same for cos.
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NLA: Cholesky For matrix [a_{11}, w^*; w, K] = R_1^T \left[ I, 0; 0, K - \frac{ww^*}{a_{11}} \right] [\alpha, w^*/\alpha; 0, I] we have a decomp:
        for k = [1, m-1]: for j = [k+1, m] R_{j,j:m} = R_{j,j:m} - \frac{R_{kj}}{R_{kk}} R_{k,j:m} endfor R_{k,k:m} = \frac{R_{k,k:m}}{\sqrt{R_{kk}}} end-
        for. \frac{m^3}{3}. Householder for k = [1, n] : x = A_{k:m,k}; v_k = sgn(x) ||x|| e_k + x; v_k = \frac{v_k}{||v_k||} for j = [k, n]
        A_{k:m,j} = A_{k:m,j} - 2v_k [v_k^* A_{k:m,j}] endfor endfor. \frac{2mn^2}{3}. LU U = A, L = I for k = [1, m-1]: for
        j = [k+1, m] \ U_{j,k:m} = U_{j,k:m} - \frac{U_{jk}}{U_{kk}} U_{k,k:m} endfor endfor. \frac{2m^3}{3}. MG-S V = A; for i = [1, n] : r_{ii} = [1, n]
        \|v_i\|; q_i = \frac{v_i}{r_{ii}}; for j = [i+1,n] v_j = v_j^T - (q_i^T v_j)q_i; r_{ij} = q_i^T v_j endfor endfor. 2mn^2. Givens 3mn^2 SVD:
          = \sum_{i}^{r:=\min m,n} u_{i} \sigma_{i} v_{i}^{T}. \  \, \mathbf{Bounds:} \  \, \left\|ABB^{-1}\right\| \geq \|AB\| \left\|B^{-1}\right\| \rightarrow \|A\|/\left\|B^{-1}\right\| \geq \|AB\|. \  \, \mathbf{Norms:} \|A\|_{F} = \sum_{i}^{r:=\min m,n} u_{i} \sigma_{i} v_{i}^{T}. \  \, \mathbf{Bounds:} \  \, \left\|ABB^{-1}\right\| \geq \|AB\| \left\|B^{-1}\right\| \rightarrow \|A\|/\left\|B^{-1}\right\| \geq \|AB\|. \  \, \mathbf{Norms:} \|A\|_{F} = \sum_{i}^{r:=\min m,n} u_{i} \sigma_{i} v_{i}^{T}. 
        \sqrt{\sum_{i} (\sigma_{i})^{2}} = \sqrt{Tr(AA^{T})}, \|A\|_{\infty} = \text{max row sum.} Low-Rank: For A \in \mathbb{R}^{m \times n} \min \|A - B\| = 1
        ||A - A_r||. Proof via B := B_1 B_2^T with B_1 \in \mathbb{R}^{m \times r}; \exists W s.t. B_2^T W = 0 with \text{null}(W) \geq n - r. Then
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        \exists x_V, x_W s.t. V_{r+1} x_V = -W x_W. So ||A - B|| = ||AW|| \ge ||AV_{r+1} x_V|| \ge \sigma_{r+1} For reverse B := A_r
        Courant: \sigma_i = \max_{\dim(S)=i} \{\min_x ||Ax||/||x||\}. Proof via V_i = [v_i \dots v_n], so \dim(S) + \dim(V_i) = n+1
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        so \exists w \in S \cap V_i. Then ||Aw|| \leq \sigma_i. For reverse take w = v_i when S = [v_1 \dots v_i] Schur: Take
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        Av_1 = \lambda_1 v_1; construct U_1 = [v_1, V_{\perp}] \to AU_1 = U_1[e_1, X]. Repeat. Back Subst: For Ux = y we have
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        x_{n-i} = (y_{n-i} - \sum_{n-i+1}^{n} u_{n-i,j} x_j) / u_{n-i,n-i}; O(i) per iteration so O(n^2) total. Backwards Stable:
        When \hat{f}(x) = f(x + \Delta x) with ||\Delta x|| / ||x|| \le O(\varepsilon) Conditioning \kappa_2(A) = \sigma_1 / \sigma_n = ||A|| ||A^{-1}||
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        NPDE: Hyp Impl: (A - B, A) = \frac{1}{2}(\|A\|^2 - \|B\|^2) + \frac{1}{2}\|A - B\|^2 with A := U^{m+1} - U^m, B := U^m - U^{m-1}
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         (T); (-D_x^+ D_x^- U^{m+1}, U^{m+1} - U^m) = (D_x^- U^{m+1} - D_x^- U^m, D_x^- U^{m+1}) (X). Then \frac{1}{2\Delta t^2} (\|U^{m+1} - U^m\|^2 - \|U^m - U^{m-1}\|^2) + \frac{\Delta t^2}{2\Delta t^2} \|U^{m+1} - 2U^m + U^{m-1}\|^2 + \frac{c^2}{2} (\|D_x^- U^{m+1}\|^2 - \|D_x^- U^m\|^2) + 
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        \frac{c^2 \Delta t^2}{2 \Delta t^2} \left\| D_x^- (U^{m+1} - U^m) \right\|^2 = (f, U^{m+1} - U^m). \text{ Then } M^2(U^m) := \left\| \frac{U^m - U^{m-1}}{\Delta t} \right\|^2 + c^2 \left\| D_x^- U^{m+1} \right\|^2. \text{ Write } M^2(U^m) = \left\| \frac{U^m - U^{m-1}}{\Delta t} \right\|^2 + c^2 \left\| D_x^- U^{m+1} \right\|^2.
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        green as \leq \|f\| \|U^{m+1} - U^m\| = \sqrt{\Delta t T} \|f\| \sqrt{\frac{\Delta t}{T}} \|\frac{U^{m+1} - U^m}{\Delta t}\| \leq \frac{\Delta t T}{2} \|f\|^2 + \frac{\Delta t}{2T} \|\frac{U^{m+1} - U^m}{\Delta t}\|^2. Then
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        (1 - \frac{\Delta t}{T})M^2(U^m) \le M^2(U^{m-1}) + \Delta t T \|f\|^2 \to M^2(U^m) \le (1 + \frac{2\Delta t}{T})M^2(U^{m-1}) + 2\Delta t T \|f\|^2. Use
        a_m \le \alpha^m a_0 + \sum_{k=1}^m \alpha^{m-k} b_k so M^2 \le e^2 M^2(U^0) + 2e^2 T \sum_{k=1}^m \Delta t \|f\|^2 Hyp Expl: 1st rewrite in terms of
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        D_t^{+-}(\Delta t)^{-2}U_j^m + \frac{c^2(\Delta t)^2}{4}D_x^{+-}((\Delta t)^{-2}U_j^m) - c^2D_x^{+-}\left(U_j^{m+1} + 2U_j^m + U_j^{m-1}\right). \text{ Then use } (D(A-B), A+B) = (DA, A) - (DB, B); (D(A+B), A-B) = (DA, A) - (DB, B) \text{ by multiplying by } U^{m+1} - U^{m-1}.
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        Finally WTS ||V_m||^2 - \frac{c^2(\Delta t)^2}{4}||D_x^-V^m||^2 \ge 0. Done by noticing: ||D_x^-V^m||^2 = \sum_i^J \Delta x |D_x^-V_j^m|^2 = \frac{1}{\Delta x} \sum_i^J \left(V_j^m - V_{j-1}^m\right)^2 \le 2/\Delta x \sum_i^J (V_j^m)^2 + (V_{j-1}^m)^2 = 4/\Delta x^2 \sum_i^{J-1} \Delta x \left(V_j^m\right)^2. Eventually show
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        N^{2}(U^{m}) := \left( \left( I + \frac{c^{2} \Delta t^{2}}{2} D_{x}^{+-} \right) \frac{U^{m+1} - U^{m}}{\Delta t}, \frac{U^{m+1} - U^{m}}{\Delta t} \right) + c^{2} \left\| D_{x}^{-} \frac{U^{m+1} + U^{m}}{2} \right\|^{2} \to N^{2}(U^{m}) = N^{2}(U^{m-1}) + C^{2}(U^{m}) = N^{2}(U^{m}) + C^{2}(U^{m}) + C^{2}(U^{m}) = N^{2}(U^{m}) + C^{2}(U^{m}) + C^{2}(U^{m}) = N^{2}(U^{m}) + C^{2}(U^{m}) + C^{
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        (f, U^{m+1} - U^m) Max Principle: For -\Delta u = f \leq 0 \to \max u \in \partial D. First show contradiction as-
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        suming LU = f < 0, then try some auxillary function \psi = U + \alpha(T_{\text{max}}) g(x_i, y_i) s.t. L\psi < 0
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        so \max \psi = \max_{\in \partial D} \psi. Gets \max e_{i,j}; change to -\alpha for \min e_{i,j}. P-F Ineq: \|V\|_h^2 \le c_\star \|D_x^-V\|^2
        Weak Deriv: w is a weak derivative of u if \int dx \, wv = (-1)^{|\alpha|} \int dx \, u(D^{\alpha}v) Parseval: \int dk \, \hat{u}(k)v(k) = 0
31
        \int dk \, v(k) \left( \int dx \, u(x) e^{-ixk} \right) = \int dx \, u(x) \left( \int dk \, v(k) e^{-ixk} \right) = \int dx \, u(x) \hat{v}(x). \text{ Now } v(k) := \overline{\hat{u}(k)} = \overline{F[u(k)]} = \overline{F[u(k)]}
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        \overline{\int dk \, u(k) e^{-ixk}} = \int dk \overline{u(k)} e^{ixk} = 2\pi F^{-1} \left| \overline{u(k)} \right| \Rightarrow \hat{v}(x) = 2\pi \overline{u(x)} Iterative: If U^{j+1} = U^j - \tau \left( AU^j - F \right)
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        U - U^j = (I - \tau A)^j (U - U^0) so ||U - U^j|| \le ||I - \tau A||^j ||U - U^0||. ||I - \tau A|| = \sigma_1 = |\lambda_1| as symmet-
34
        ric. If \lambda \in [\alpha, \beta] then \lambda_1 \leq \max\{|1 - \tau \alpha|, |1 - \tau \beta|\}. Attained when \tau = 2/(\alpha + \beta) \to \lambda_1 = \frac{\beta - \alpha}{\beta + \alpha}. For
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         -u''+cu=f we have \lambda_k=c+\frac{4}{h^2}\sin^2\left(\frac{k\pi h}{2}\right). Lower bound via noting \sin(y)\geq \frac{2\sqrt{2}}{\pi}y at y=\frac{\pi}{4}\to\lambda_k\geq c+8
36
        Errors: (AV, V)_h \ge ||D_x^- V||_h^2 & PF Ineq \to (AV, V)_h \ge ||V||_h^2/c_{\star}. Then (AV, V)_h (1 + c_{\star}) \ge ||V||_{1,h}^2 \to ||V||_{1,h}^2
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        (AV, V)_h \ge c_0 \|V\|_{1,h}^2. Now c_0 \|V\|_{1,h}^2 \le (AV, V)_h \le \|f\|_h \|V\|_h \le \|f\|_h \|V\|_{1,h} \to \|V\|_{1,h} \le \|f\|_h / c_0. (Use
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        f := AV \to \|e\|_{1,h} \le \|T\|_h/c_0
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