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APDE: Charpit: F(p,q,u,x,y) = 0 with u_x = p, u_y = q, \dot{x} = F_p, \dot{y} = F_q. Then via F_x, F_y, \& p_y = q_x \rightarrow p_\tau = -F_x - pF_u, q_\tau = -F_y - qF_u, u_\tau = pF_p + qF_q. Also, u0_s = p_0x0_s + q_0y0_s; F_0 = 0 - last 2 needed to show u defined on \Gamma. Riemann: \int_D RLu - uL^*R = \int_D \partial_x (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_x + buR) = \int_D dx (Ru_y + auR) + \partial_y (-uR_
                 \int_{\partial D} dy (Ru_y + Rau) + dx (uR_x - buR). Expand over triangle going B-P-A (B at bottom right) \rightarrow need
               R_x = bR@y = \eta, R_y = aR@x = \xi, R(P) = 1, L^*R = 0. Also ensure IVP to get R_y, R_x! Canonical:
               For au_{xx} + 2bu_{xy} + cu_{yy} = f, we need Cauchy-Kowalevski s.t. first derive defined: x' := \frac{dx}{ds} s.t. on \Gamma p'_0 = x'_0 u_{xx} + y'_0 u_{xy}, q'_0 = x'_0 u_{xy} + y'_0 u_{yy}. Use these 3, solve det A! = 0 s.t. ay'_0^2 - 2bx'_0 y'_0 + cx'_0^2 \neq 0. Solve quadratic s.t. b^2 > ac \rightarrow h, b^2 < ac \rightarrow e, b^2 = ac \rightarrow p. H: \lambda_1, \lambda_2 \rightarrow \xi, \eta. E: \lambda = \lambda_R \pm i\lambda_I; \lambda_R \rightarrow \xi, \lambda_I \rightarrow \eta.
               P: \lambda_1 \to \xi, choose \eta independent e.g. xy, x^2. Green's Fn: For u_{xx} + u_{yy} + au_x + bu_y + cu = f we have \int_D GLu - uL^*G = \int_D (u_xG)_x + (u_yG)_y - (uG_x)_x - (uG_y)_y + (auG)_x + (buG)_y = \int_D \nabla \cdot (u_nG - uG_n) + (uG_yG)_x + (uG_
                \nabla \cdot ((a\ b)^T \hat{n} G u) = \int_{\partial D} u_n G - u G_n + (a\ b)^T \hat{n} G. NB \hat{n} = (d\ y, -dx). Also note for quarter plane if we have
               G_x(0,y) = 0, G(x,0) = 0 then we have same sign at \xi_1 = (-x,y), opposite sign at \xi_2 = (x,-y), and for
                the third we reflect \xi_2 across y axis so we have an opposite sign to \xi at \xi_3 = (-x, -y). Types: Quasi-
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                 Coeffs don't depend on highest order derives Semi: Coeffs depend on x, y. Causality: For a n-dim prob,
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                we have n characteristics. Shock intersects 2n. \exists k outgoing, 2n-k ingoing. Also have n R-H relations,
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                so 3n-k pieces of info. Unknowns are n components of \vec{u} on both sides of shock & slope \Rightarrow 2n+1
                unknowns. We demand 3n - k = 2n + 1 so k = n - 1 outgoing characterisites.
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                SAM: Dists: Need linearity and continuity: \exists N, C \text{ s.t. } |(u,\phi)| \leq C \sum_{m \leq N} \max_{\in [-X,X]} |\phi^{(m)}|. OR
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               \lim_{n\to\infty}(u,\phi_n)=(u,\lim_{n\to\infty}\phi_n) for a sequence \phi_n\to 0 as n\to\infty. Orthog: \int_0^\pi\sin(kx)\sin(jx)=\frac{\pi}{2}\delta_{kj}
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                same for cos.
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NLA: Cholesky For matrix [a_{11}, w^*; w, K] = R_1^T \left[ I, 0; 0, K - \frac{ww^*}{a_{11}} \right] \left[ \alpha, w^* / \alpha; 0, I \right] we have a decomp: for k = [1, m - 1]: for j = [k + 1, m] R_{j,j:m} = R_{j,j:m} - \frac{R_{kj}}{R_{kk}} R_{k,j:m} endfor R_{k,k:m} = \frac{R_{k,k:m}}{\sqrt{R_{kk}}} end-
      for. \frac{m^3}{3}. Householder for k = [1, n] : x = A_{k:m,k}; v_k = sgn(x) ||x|| e_k + x; v_k = \frac{v_k}{\|v_k\|} for j = [k, n]
      A_{k:m,j} = A_{k:m,j} - 2v_k [v_k^* A_{k:m,j}] endfor endfor. \frac{2mn^2}{3}. LU U = A, L = I for k = [1, m-1]: for
      j = [k+1,m] \ U_{j,k:m} = U_{j,k:m} - \frac{U_{jk}}{U_{kk}} U_{k,k:m} endfor endfor. \frac{2m^3}{3}. MG-S V = A;for i = [1,n] : r_{ii} = ||v_i||; q_i = \frac{v_i}{r_{ii}}; for j = [i+1,n] \ v_j = v_j - (q_i^T v_j) q_i; r_{ij} = q_i^T v_j endfor endfor. 2mn^2. Givens 3mn^2 SVD:
        = \underbrace{\sum_{i}^{r:=\min} {}^{m,n}}_{} u_{i} \sigma_{i} v_{i}^{T}. \  \, \textbf{Bounds:} \  \, \left\|ABB^{-1}\right\| \geq \|AB\| \|B^{-1}\| \rightarrow \|A\| / \|B^{-1}\| \geq \|AB\|. \  \, \textbf{Norms:} \|A\|_{F} = \underbrace{\sum_{i}^{r:=\min} {}^{m,n}}_{} u_{i} \sigma_{i} v_{i}^{T}. \  \, \textbf{Bounds:} \  \, \left\|ABB^{-1}\right\| \geq \|AB\| \|B^{-1}\| \rightarrow \|A\| / \|B^{-1}\| \geq \|AB\|. 
       \sqrt{\sum_{i} (\sigma_{i})^{2}} = \sqrt{Tr(AA^{T})}, \|A\|_{\infty} = \text{max row sum.} Low-Rank: For A \in \mathbb{R}^{m \times n} \min \|A - B\| = 1
      \|A - A_r\|. Proof via B := B_1 B_2^T with B_1 \in \mathbb{R}^{m \times r}; \exists W s.t. B_2^T W = 0 with \text{null}(W) \geq n - r. Then
      \exists x_V, x_W s.t. V_{r+1} x_V = -W x_W. So ||A - B|| = ||AW|| \ge ||AV_{r+1} x_V|| \ge \sigma_{r+1} For reverse B := A_r
      Courant: \sigma_i = \max_{\dim(S)=i} \{ \min_x \|\ddot{A}x\|/\|x\| \}. Proof via V_i = [v_i \dots v_n], so \dim(S) + \dim(V_i) = n+1
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      so \exists w \in S \cap V_i. Then ||Aw|| \leq \sigma_i. For reverse take w = v_i when S = [v_1 \dots v_i] Schur: Take
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      Av_1 = \lambda_1 v_1; construct U_1 = [v_1, V_{\perp}] \to AU_1 = U_1[e_1, X]. Repeat. Back Subst: For Ux = y we have
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      x_{n-i} = (y_{n-i} - \sum_{n=i+1}^{n} u_{n-i,j} x_j) / u_{n-i,n-i}; O(i) per iteration so O(n^2) total. Backwards Stable:
      When \hat{f}(x) = f(x + \Delta x) with \|\Delta x\|/\|x\| \le O(\varepsilon) Conditioning \kappa_2(A) = \sigma_1/\sigma_n = \|A\| \|A^{-1}\|
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       NPDE: Hyperbolic: Implicit: (A - B, A) = \frac{1}{2}(\|A\|^2 - \|B\|^2) + \frac{1}{2}\|A - B\|^2 (time), (-D_x^+ D_x^- U^{m+1}, -D_x^- U^{m+1})
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      U^{m+1}-U^m = (D_x^-U^{m+1}-D_x^-U^m, D_x^-U^{m+1}) (space). Explicit: 1st rewrite in terms of D_t^{+-}(\Delta t)^{-2}U_i^m +
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      \frac{c^2(\Delta t)^2}{4}D_x^{+-}((\Delta t)^{-2}U_i^m) - c^2D_x^{+-}(U_i^{m+1} + 2U_i^m + U_i^{m-1}). Then use (D(A-B), A+B) = (DA, A)-
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      (DB,B); (D(A+B),A-B)=(DA,A)-(DB,B) by multiplying by U^{m+1}-U^{m-1}. Finally WTS
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      \|V_m\|^2 - \frac{c^2(\Delta t)^2}{4} \|D_x^- V^m\|^2 \ge 0. Done by noticing: \|D_x^- V^m\|^2 = \sum_i^J \Delta x |D_x^- V_j^m|^2 = 1/\Delta x \sum_i^J \Delta x |D_x^- V_j^m|^2
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      (V_j^m - V_{j-1}^m)^2 \le 2/\Delta x \sum_i^J (V_j^m)^2 + (V_{j-1}^m)^2 = 4/\Delta x^2 \sum_i^{J-1} \Delta x (V_j^m)^2 Max Principle: For -\Delta u = f \le 0 \to \max u \in \partial D. First show contradiction assuming LU = f < 0, then try some auxillary function
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      \psi = U + \alpha \left( T_{\max} \right) g\left( x_i, y_i \right) \text{ s.t. } L\psi < 0 \text{ so } \max \psi = \max_{\epsilon \in \partial D} \psi. \text{ Gets } \max e_{i,j}; \text{ change to } -\alpha \text{ for } \min e_{i,j}. 
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      F Ineq: ||V||_h^2 \le c_\star ||D_x^- V||^2 Weak Deriv: w is a weak derivative of u if \int dx \, wv = (-1)^{|\alpha|} \int dx \, u(D^\alpha v) Parseval: \int dk \, \hat{u}(k)v(k) = \int dk \, v(k) \left(\int dx \, u(x)e^{-ixk}\right) = \int dx \, u(x) \left(\int dk \, v(k)e^{-ixk}\right) = \int dx \, u(x)\hat{v}(x).
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      Now v(k) := \overline{\hat{u}(k)} = \overline{F[u(k)]} = \overline{\int dk \, u(k) e^{-ixk}} = \int dk \, \overline{u(k)} e^{ixk} = 2\pi F^{-1} \, \left| \overline{u(k)} \right| \Rightarrow \hat{v}(x) = 2\pi \overline{u(x)} Itera-
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      tive: If U^{j+1} = U^j - \tau (AU^j - F) \to U - U^j = (I - \tau A)^j (U - U^0) so ||U - U^j|| \le ||I - \tau A||^j ||U - U^0||
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      ||I - \tau A|| = \sigma_1 = |\lambda_1| as symmetric. If \lambda \in [\alpha, \beta] then \lambda_1 \leq \max\{|1 - \tau \alpha|, |1 - \tau \beta|\}. Attained when \tau = 2/(\alpha + \beta) \to \lambda_1 = \frac{\beta - \alpha}{\beta + \alpha}. For -u'' + cu = f we have \lambda_k = c + \frac{4}{h^2} \sin^2\left(\frac{k\pi h}{2}\right). Lower bound via noting
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      \sin(y) \ge \frac{2\sqrt{2}}{\pi}y at y = \frac{\pi}{4} \to \lambda_k \ge c + 8 Errors: (AV, V)_h \ge ||D_x^- V||_h^2 & PF Ineq \to (AV, V)_h \ge ||V||_h^2/c_\star
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      Then (AV, V)_h (1 + c_{\star}) \ge ||V||_{1,h}^2 \to (AV, V)_h \ge c_0 ||V||_{1,h}^2. Now c_0 ||V||_{1,h}^2 \le (AV, V)_h \le ||f||_h ||V||_h \le ||f||_h ||V||_{1,h} \to ||V||_{1,h} \le ||f||_h /c_0. (Use f := AV \to ||e||_{1,h} \le ||T||_h /c_0)
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