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APDE: Charpit: F(p,q,u,x,y) = 0 with u_x = p, u_y = q, \dot{x} = F_p, \dot{y} = F_q. Then via F_x, F_y, \& p_y = q_x \rightarrow q_y
                  p_{\tau} = -F_x - pF_u, \ q_{\tau} = -F_y - qF_u, u_{\tau} = pF_p + qF_q. Also, u0_s = p_0x0_s + q_0y0_s; F_0 = 0 - last 2 needed to show u defined on \Gamma. Riemann: \int_D RLu - uL^*R = \int_D \partial_x (Ru_y + auR) + \partial_y (-uR_x + buR) = 0
                    \int_{\partial D} dy (Ru_y + Rau) + dx (uR_x - buR). Expand over triangle going B-P-A (B at bottom right) \rightarrow need
                   R_x = bR@y = \eta, R_y = aR@x = \xi, R(P) = 1, L^*R = 0. Also ensure IVP to get R_y, R_x! Canonical:
                  For au_{xx} + 2bu_{xy} + cu_{yy} = f, we need Cauchy-Kowalevski s.t. first derivs defined: x' := \frac{dx}{ds} s.t. on \Gamma p'_0 = x'_0 u_{xx} + y'_0 u_{xy}, q'_0 = x'_0 u_{xy} + y'_0 u_{yy}. Use these 3, solve det A!=0 s.t. ay'_0^2 - 2bx'_0 y'_0 + cx'_0^2 \neq 0. Solve quadratic s.t. b^2 > ac \rightarrow b, b^2 < ac \rightarrow e, b^2 = ac \rightarrow p. H: \lambda_1, \lambda_2 \rightarrow \xi, \eta. E: \lambda = \lambda_R \pm i\lambda_I; \lambda_R \rightarrow \xi, \lambda_I \rightarrow \eta.
                   P: \lambda_1 \to \xi, choose \eta independent e.g. xy, x^2. Green's Fn: For u_{xx} + u_{yy} + au_x + bu_y + cu = f we have \int_D GLu - uL^*G = \int_D (u_xG)_x + (u_yG)_y - (uG_x)_x - (uG_y)_y + (auG)_x + (buG)_y = \int_D \nabla \cdot (u_nG - uG_n) + (uG_yG)_y + (uG_
                    \nabla \cdot ((a \, b)^T \hat{n} G u) = \int_{\partial D} u_n G - u G_n + (a \, b)^T \hat{n} G. NB \hat{n} = (dy, -dx). Also note for quarter plane if we have
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                   G_x(0,y)=0, G(x,0)=0 then we have same sign at \xi_1=(-x,y), opposite sign at \xi_2=(x,-y), and for
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                   the third we reflect \xi_2 across y axis so we have an opposite sign to \xi at \xi_3 = (-x, -y). Types: Quasi-
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                    Coeffs don't depend on highest order derives Semi: Coeffs depend on x, y. Causality: For a n-dim prob,
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                   we have n characteristics. Shock intersects 2n. \exists k outgoing, 2n-k ingoing. Also have n R-H relations,
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                   so 3n-k pieces of info. Unknowns are n components of \vec{u} on both sides of shock & slope \Rightarrow 2n+1
                   unknowns. We demand 3n - k = 2n + 1 so k = n - 1 outgoing characterisites.
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                  SAM: Dists: Need linearity and continuity: \exists N, C \text{ s.t. } |(u, \phi)| \leq C \sum_{m \leq N} \max_{\epsilon [-X, X]} |\phi^{(m)}|
NLA: Cholesky For matrix [a_{11}, w^*; w, K] = R_1^T \left[ I, 0; 0, K - \frac{ww^*}{a_{11}} \right] [\alpha, w^*/\alpha; 0, I] we have a decomp:
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                  for k = [1, m-1]: for j = [k+1, m] R_{j,j:m} = R_{j,j:m} - \frac{R_{k,j}}{R_{k,k}} R_{k,j:m} endfor R_{k,k:m} = \frac{R_{k,k:m}}{\sqrt{R_{k,k}}} end-
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                   for. \frac{m^3}{3}. Householder for k = [1, n] : x = A_{k:m,k}; v_k = sgn(x) ||x|| e_k + x; v_k = \frac{v_k}{||v_k||} for j = [k, n]
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                  A_{k:m,j} = A_{k:m,j} - 2v_k \left[v_k^* A_{k:m,j}\right] \text{ endfor endfor.} \quad \frac{2mn^2}{3}. \quad \text{LU } U = A, L = I \text{ for } k = [1, m-1]: \text{ for } j = [k+1, m] \ U_{j,k:m} = U_{j,k:m} - \frac{U_{jk}}{U_{kk}} U_{k,k:m} \text{ endfor endfor.} \quad \frac{2m^3}{3}. \quad \text{MG-S } V = A; \text{for } i = [1, n]: \\ r_{ii} = \|v_i\|; q_i = \frac{v_{ii}}{v_{ii}}; \text{for } j = [i+1, n] \ v_j = v_j - (q_i^T v_j)q_i; r_{ij} = q_i^T v_j \text{ endfor endfor.} \quad 2mn^2. \quad \text{Givens} \\ 3mn^2 \text{ SVD:} = \sum_{i=1}^{r:=\min m, n} u_i \sigma_i v_i^T.
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                  NPDE: Hyperbolic: Implicit: (A - B, A) = \frac{1}{2}(\|A\|^2 - \|B\|^2) + \frac{1}{2}\|A - B\|^2 (time), (-D_x^+ D_x^- U^{m+1}, U^{m+1} - U^m) = (D_x^- U^{m+1} - D_x^- U^m, D_x^- U^{m+1}) (space). Explicit: 1st rewrite in terms of D_t^{+-}(\Delta t)^{-2} U_j^m + (\Delta t)^{-2}
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                  \frac{c^2(\Delta t)^2}{4}D_x^{+-}((\Delta t)^{-2}U_j^m) - c^2D_x^{+-}(U_j^{m+1} + 2U_j^m + U_j^{m-1}). \text{ Then use } (D(A-B), A+B) = (DA, A) - (DB, B); (D(A+B), A-B) = (DA, A) - (DB, B) \text{ by multiplying by } U^{m+1} - U^{m-1}. \text{ Finally WTS}
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                   ||V_m||^2 - \frac{c^2(\Delta t)^2}{4} ||D_x^- V^m||^2 \ge 0. \text{ Done by noticing: } ||D_x^- V^m||^2 = \sum_i^J \Delta x |D_x^- V_j^m|^2 = 1/\Delta x \sum_i^J (V_j^m - V_{j-1}^m)^2 \le 2/\Delta x \sum_i^J (V_j^m)^2 + (V_{j-1}^m)^2 = 4/\Delta x^2 \sum_i^{J-1} \Delta x \left(V_j^m\right)^2 \text{ Max Principle: For } -\Delta u = f \le 0. 
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                  0 \to \max u \in \partial D P-F Ineq: ||V||_h^2 \le c_\star ||D_x^- V||^2 Weak Deriv: w is a weak derivative of u if \int dx \, wv = 0
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                  \left|(-1)^{|\alpha|}\int dx u(D^{\alpha}v) \text{ Parseval: } \int dk \ \hat{u}(k)v(k) = \int dk v(k) \left(\int dx \ u(x)e^{-ixk}\right) = \int dx u(x) \left(\int dk \ v(k)e^{-ixk}\right) = \int
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                    \int dx \, u(x)\hat{v}(x). \quad \text{Now } v(k) := \frac{\hat{u}(k)}{\hat{u}(k)} = \frac{1}{F[u(k)]} = 
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                  \hat{v}(x) = 2\pi \overline{u(x)} Iterative: If U^{j+1} = U^j - \tau \left(AU^j - F\right) \to U - U^j = (I - \tau A)^j \left(U - U^0\right) so \|U - U^j\| \le T
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                   \|I - \tau A\|^j \|U - U^0\|. \|I - \tau A\| = \sigma_1 = |\lambda_1| \text{ as symmetric. If } \lambda \in [\alpha, \beta] \text{ then } \lambda_1 \leq \max\{|1 - \tau \alpha|, |1 - \tau \beta|\}
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                   Attained when \tau = 2/(\alpha + \beta) \to \lambda_1 = \frac{\beta - \alpha}{\beta + \alpha}. For -u'' + cu = f we have \lambda_k = c + \frac{4}{h^2} \sin^2\left(\frac{k\pi h}{2}\right). Lower
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                   bound via noting \sin(y) \ge \frac{2\sqrt{2}}{\pi}y at y = \frac{\pi}{4} \to \lambda_k \ge c + 8
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