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NS: Inverse 2 \times 2: For A := [a, b; c, d], A^{-1} := \frac{1}{ad - bc}[d, -b; -c, a] Adj A: Adj(A) is A^{-1}*\det(A) Radial:
      r\dot{r} = x\dot{x} + y\dot{y}, \ \dot{\theta} = \left[\tan^{-1}(y/x)\right]' = \frac{x\dot{y} - \dot{x}y}{x^2 + y^2} Classifications: Node: \lambda_i \in \mathbb{R}, \Pi\lambda_i > 0 Centre: \lambda_i = \pm ib
      Focus: \lambda_i = a \pm ib Hyperbolic: \text{Re}(\lambda) \neq 0 \rightarrow \text{hyperbolic}. If all \lambda < 0 for \text{Spec}(Df(x_0)) then A-Stable
       Invariant Set: \phi_t(S) \subseteq S Lim Pts: \omega pt. if \lim_{t\to\infty} \phi(x) = p, i.e. flows tend to p. \alpha pt. if
      \lim_{t\to-\infty}\phi(x)=p. Attracting Set: A set A\subseteq S if \exists neighbourhood U s.t. \phi(U)\subseteq U \forall t\geq 0, and
       A = \bigcap_{t>0} \phi(U) Dense Orbits: If \forall \epsilon > 0, x \in A with A an attracting set, \exists \tilde{x} \in \Gamma s.t. | x - \tilde{x}| < \epsilon.
      I.e. a dense orbit goes as close as needed to any point within A Attractor: An attracting set with a
      dense orbit. Lyapunov Stable: If \forall \epsilon > 0, \exists \ \delta > 0s.t. \forall \ x \in B_{\delta}, t \geq 0, \phi(t) \in B_{\delta} (i.e. points stay close
      within region). Asymptotically Stable: If L-Stable and \exists \ \delta > 0 s.t. \phi(x) \to x_0 \forall x \in B_{\delta} Lyapunov
      F'n: V(x_0) = 0, V(x) > 0 \forall x \neq x_0. Then if V < 0 \rightarrow \text{A-Stable}, or if V \leq 0 L-Stable. Stable
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      Manifold: If spectrum of Df(x_0) has k eigvals with positive real parts, and n-k with negative, then
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      \exists an n-k dim manifold tangent to E^s s.t. for all t>0 \phi(W^s_{loc})\subseteq W^s_{loc}, and \forall x\in W^s_{loc}\phi(x)\to x_0 as
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       time increases. Repeat for k-dim unstable manifold but for negative time. Then, define e.g. global stable
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       manifold by W^s(x_0) := \bigcup_{t < 0} \phi_t(W^s_{loc}). Note that we search backwards in time for stable, and forwards
       for unstable! Centre Manifold: If x_0 not hyperbolic (0 real part), then E^c is the centre subspace.
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      Then \exists W^c parallel to E^c, of class C^r, and invariant under flow. Want bifurcation at \mu = 0, so with
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       change of variables first find eigvecs v_1, v_2. Then, construct P := [v_1, v_2] s.t. \vec{x} = P\vec{\xi}. NOTE: first v_i
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       in P is always associated with Re(\lambda) = 0. Solve for \vec{\xi} and then expand with \eta = h(\xi, \tilde{\mu}) Alt. Centre
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      Manifold: If vector v_1 \sim E^c = [a, b]^T then we have y = bx/a (e.g. [1, 1]^T \to y = x. If bifurcation
      at \mu = \alpha then have \mu = \tilde{\mu} + \alpha s.t. bifurcation when \tilde{\mu} = 0. Then have \dot{x}(x, y, \tilde{\mu}) = \dots etc. Next, set
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      up y = h(x, \tilde{\mu}) = bx/a + b_1\tilde{\mu} + b_2\tilde{\mu}^2 + a_2x^2 + c_2\tilde{\mu}x and proceed as usual but at \tilde{\mu} = 0, s.t. y is along
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      E^c. Transcritical Bifurcation: Always two points, change type at origin. E.g. \dot{x} = \mu x - x^2 Saddle-
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      Node: E.g. \dot{x} = \mu - x^2 Bifurcation begins to exist at origin. Supercritical: E.g. \dot{x} = \mu x - x^3, where
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      stable \to 2\times stable and one unstable. Subcritical: E.g. \dot{x} = -\mu x + x^3, where unstable \to 2\times unstable
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      and one stable. General co-dim 1: If \dot{x} = f then \dot{x} = \mu f_u + 0.5x^2 f_{xx} + x\mu f_{x\mu} + 0.5\mu^2 f_{\mu\mu}. Generally
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      this is a saddle-node but if f_u = 0 we have \dot{x} = x\mu f_{x\mu} + 0.5x^2 f_{xx}, which is a transcritical. However
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      if flows invariant under x = -x (reflectional symmetry) then \dot{x} = x(\mu f_{x\mu} + \ldots) + x^3(f_{xxx}/6 + \ldots) \rightarrow
      pitchfork. Saddle-node stable under perturbations! Homoclinic Orbits Sum of roots of cubic = - coeff.
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      FPDE: Types: 1^{st}: \exists scale s.t. solution found, not so for 2^{nd}. Heat: \hat{T} = u(\hat{T}_{\infty} - \hat{T}_{-\infty}) + \hat{T}_{-\infty} Oil
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      Spread: Dims: x = x_f + \varepsilon \xi, t = \tau Ground Spread: (1-s)\phi h_t + Q_x = 0; Q \sim -hh_x, 0 < x_s < x_f. Have
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      h(x_f) = 0, h_t(x_s) = 0, and hh_x|_{x=0,x_f} = 0 (i.e. no flux at centre and front), and h, hh_x cont. at joint.
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      Expansions: Let \xi = z + \epsilon \eta for perturbations Scale: Try x = x_f + \epsilon \xi for groundwater Stefan: S_0 = \frac{1}{2} \sum_{j=1}^{n} \frac{1}{j} \sum_{j=1}^{
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      C\left(T_{1}-T_{m}\right)/L, condition = \rho L\dot{s}=kT_{x}|_{s-}^{s+} 1ph Stefan: Bar = T_{h}|liq|_{s}sol|INS. Use T=T_{m}+(T_{1}-T_{m})u
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      s.t. S_0 u_t = u_{xx}, u = 1 @ x = 0, \{\dot{s} = -u_x, u = 0\} @ x = s, s(0) = 0. Sim. sol is s = \beta \sqrt{t}, f = f(x/\sqrt{t})
      2ph Stefan: Use T = T_m + (T_1 - T_m)u s.t. S_0 u_t = u_{xx} @ 0 < x < s, (S_0/\kappa)u_t = u_{xx} @ s < x < s, (S_0/\kappa)u_t = u_{xx} 
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      1, u = 1 @ x = 0, u_x = 0 @ x = 1, \{\dot{s} = Ku_x|_{s_+} - u_x|_{s_-}, u = 0\} @ x = s, \{s = 0, u = -\theta\} @ x = 0. \text{ Here } u_x = 0, u = 0, u = 0\}
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      \theta := (T_m - T_0)/(T_1 - T_m), \kappa := c_1 k_1/(c_2 k_2), K := k_2/k_1 \text{ Sim. sol is } s = \beta \sqrt{t}, f = f(x/\sqrt{t}) 2-Dim:
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      U_n = \hat{n} \cdot u = K(u_2)_n - (u_1)_n. If x = f(y,t) then \hat{n} := \nabla(x-f) = [1,-f_y]^T/\sqrt{1+f_y^2} Welding:
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      Have 0 < s_2 < s_1. Have cold x = a, no flux x = 0. \theta = 1 in liquid. In mush \rho L\theta_t = J^2/\sigma, CoE
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       \to \theta \rho L \dot{s} + k T_x |_{s_-}^{s_+} = 0. Have \theta cont. (= 0) at s_1. I.e. we have S_0 u_t = u_{xx} + q, u_x = 0 @ x = 0, u = 0
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       -1 @ x = 1, \theta = 0 @ x = s_1. Also \theta_t = q in mush.
      FMM: Integral Constraint If J[y] = \int F dx with \int G dx = C then \tilde{J}[y] = \int F - \lambda G dx Hamiltonian:
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      H:=y'F_{y'}-F \rightarrow H'=-F_x. If F=F(y,\dot{y}) then H=C Hamilton's Eqs: p:=F_{y'},q=y
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      and so p' = -H_q, q' = H_p Free Boundary: J[y, b] = \int_a^b F(x, y, y') dx where b free. Expand with y + \epsilon \eta, b + \epsilon \beta \to J = J_0 + \epsilon \left\{ \int_a^b \eta F_y + \eta' F_{y'} dx + \beta F(b, y(b), y'(b)) \right\} If y(b) = d \to d = y(b + \epsilon \beta) + \epsilon \eta(b + \epsilon \beta) = 0
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      y(b) + \epsilon(\beta y'(b) + \eta(b)) so \eta(b) = -\beta y'(b). IVP on integral so \beta [F - y'F_{y'}]_{x=b} + \int (\ldots) = 0 so F = y'F_y
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      at free boundary. Control: Have \int \xi h_x + \eta h_u dt = 0, \dot{\xi} = \xi f_x + \eta f_u. Sub for \eta, IVP s.t. \frac{d}{dt} \frac{h_u}{f_u} = h_x - f_x \frac{h_u}{f_u} and \dot{x} = f Hamiltonian (Control): H := f \frac{h_u}{f_u} - h s.t. \dot{H} = \frac{h_u}{f_u} f_t - h_t \rightarrow \text{autonomous if } h_t = f_t = 0.
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      Fredholm Alt Integ Eqs. For y = f + \int K(x,t)y(t)dt we have ONE (N) has a unique sol y = 0 if f = 0
      and adjoint has unique sol, or TWO (H) as sols y_1 \dots y_r iff \forall solutions to H^*, z_i, we have \langle f, z_i \rangle = 0
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       GENERAL CASE: Have y = f + \lambda AG_1 + \lambda BG_2. Solve for system [\alpha_1, \alpha_2; \alpha_3, \alpha_4][A, B]^T = [\gamma_1, \gamma_2]^T with
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      NONUNIQUE sols for \lambda = \lambda_*. Now for \lambda = \lambda_*, want to solve L^*w = 0 and show this is orthogonal to RHS.
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      First solve [\alpha_1, \alpha_2; \alpha_3, \alpha_4][A, B]^T = [0, 0]^T. Then we have w = \lambda_* A(F(G_1, G_2)). Check if \int fw = 0. If so,
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      return to NONHOM case and solve [\alpha_1, \alpha_2; \alpha_3, \alpha_4]_{\lambda_*}[A, B]^T = [\gamma_1, \gamma_2]^T to get B = -\frac{\alpha_1}{\alpha_2}A + \frac{\gamma_1}{\alpha_2}. Sub this
      into y = f + \lambda_* A G_1 + \lambda_* B(A) G_2. EX: Solve y = 1 - x^2 + \lambda \int (1 - 5x^2 t^2) y(t) dt = 1 - x^2 + \lambda A - 5\lambda B x^2. Have
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A := \int y_N(t) = \int 1 - x^2 + \lambda A + \dots = \lambda A - \frac{5\lambda}{3} + \frac{2}{3}. \text{ Repeat for } B \text{ s.t. } [1 - \lambda, 5\lambda/3; -\lambda/3, 1 + \lambda][A, B]^T = [2/3, 2/15]^T. \text{ Unique sols if } \lambda \neq \pm \frac{3}{2} \to \text{try when } \lambda_* = \frac{-3}{2}. \text{ Have } L^*w_H = \lambda A - 5\lambda_*Bx^2 \to A := \int \lambda_* A - 5\lambda_*Bx^2, \text{ and } B := \int \dots \text{ Both give consistent results } A = B \text{ so } w_H = \lambda_* A (1 - 5x^2). \text{ Check that } A = B \text{ so } w_H = \lambda_* A (1 - 5x^2).
\int w_H(x)(1-x^2)=0, so we have shown nullspace of adj. orthog. to RHS. Note that we may also find
[A, B] for adjoint quicker via [1-\lambda, 5\lambda/3; -\lambda/3, 1+\lambda]_{\lambda_*}[A, B]^T = [0, 0]^T. Lastly, return to (N), and having
verified \lambda_* permits a solution, solve [1 - \lambda, 5\lambda/3; -\lambda/3, 1 + \lambda]_{\lambda_*}[A, B]^T = [2/3, 2/15]^T \rightarrow A - B = 4/15
when \lambda = -3/2. Sub this into y = 1 - x^2 \dots for solution. Fred Diff Eq. For nonunique sol to exist,
need < Ly, w > = < f, w > \forall ws.t.L^*w = 0
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