

The left 3D points estimated:

-0.38337	-0.49649	-0.36043	-0.24101	-0.42501	-0.52487	-0.38522	-0.3036
0.58728	0.42881	0.41926	0.56176	0.68036	0.53561	0.50649	0.65476
0.71805	0.77632	0.8439	0.79944	0.63536	0.69014	0.77278	0.70741

The right 3D points estimated:

0.9141	0.78099	0.83133	0.93211	0.85198	0.7593	0.78503	0.87755
0.17218	0.090988	-0.070418	0.0092743	0.23916	0.17341	0.040365	0.11274
0.41461	0.62627	0.56604	0.4039	0.50258	0.6509	0.62532	0.47656

Virtual camera parameters for the generated images:

Image 1:

$O1 = [-1535.21; 1720.84; 1693.22];$

$O2 = [-1694.56; -142.25; 1585.19];$

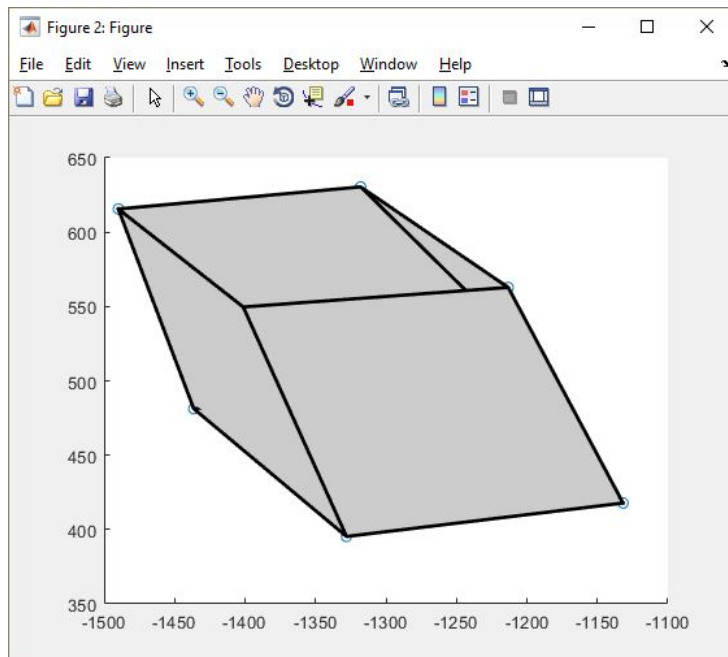


Image 2:

O1 = [-1200; 1520; 1700];

O2 = [-1820; -200; 1000];

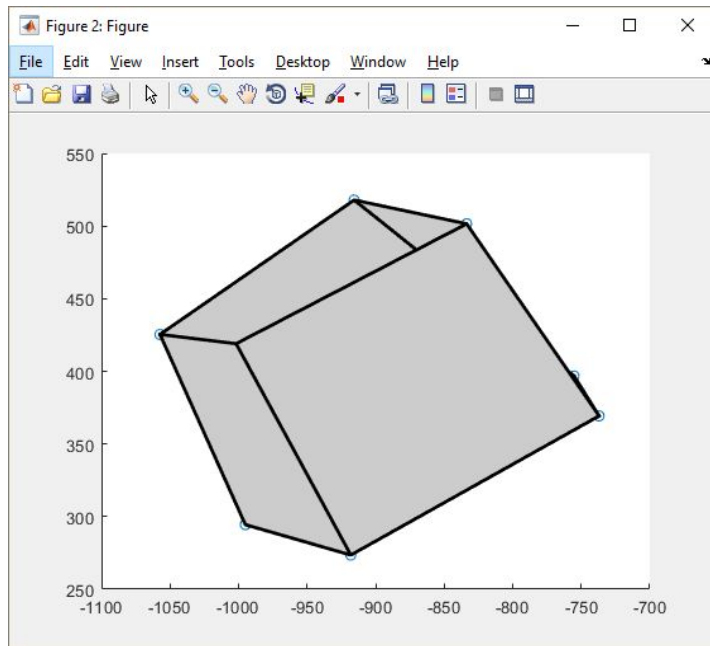


Image 3:

O1 = [1200; 1520; 1100];

O2 = [-1120; -200; 1000];

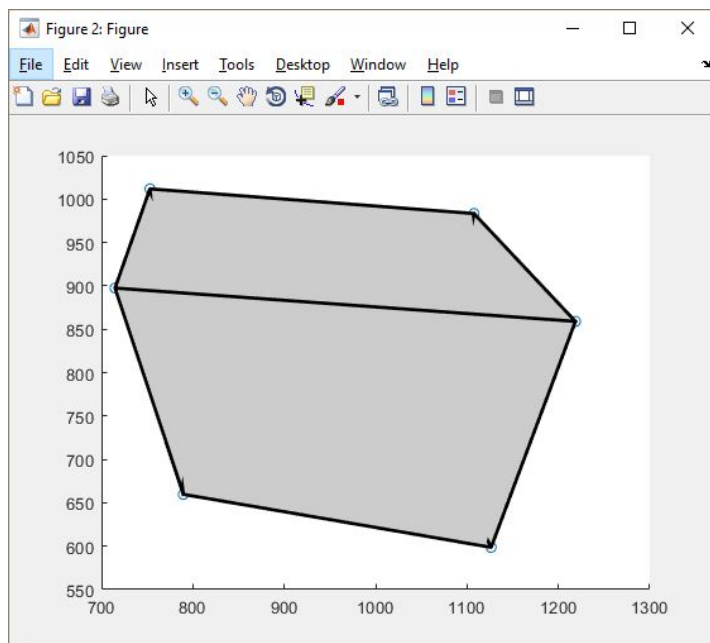


Image 4:

$O1 = [1200; 1420; 1000];$

$O2 = [-1050; -200; 1000];$

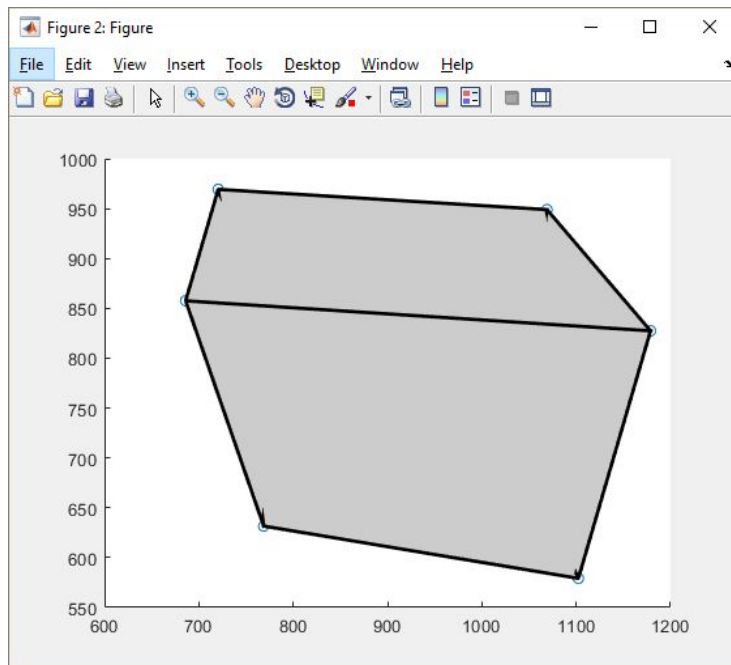


Image 5:

$O1 = [-1200; 0; 1100];$

$O2 = [-1120; -500; 1070];$

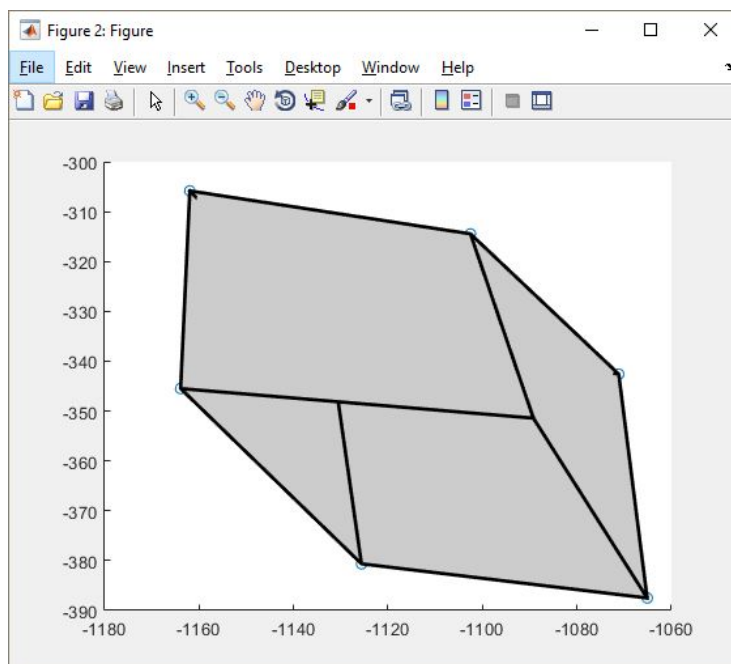


Image 6:

$O1 = [-1000; 0; 700];$

$O2 = [1120; -100; 1070];$

