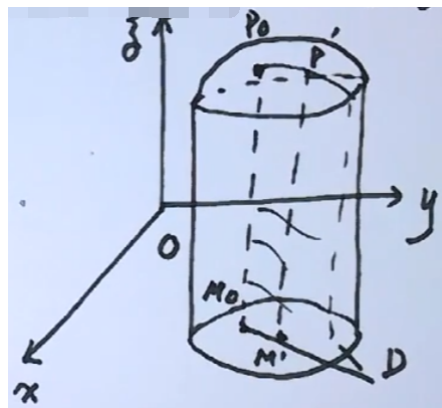
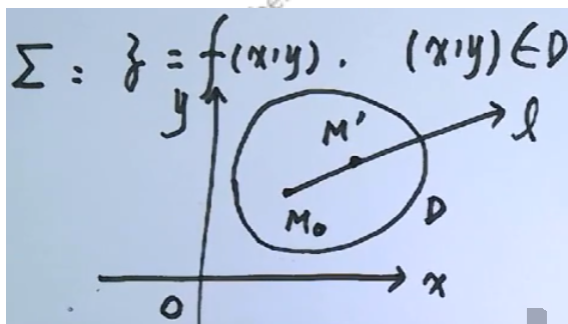


# 方向导数与梯度

$$\Sigma: z = f(x, y), (x, y) \in D, M_0(x_0, y_0) \in D$$



在 $l$ 上取 $M'(x_0 + \Delta x, y_0 + \Delta y) \in l$

$$\rho = |M_0 M'| = \sqrt{(\Delta x)^2 + (\Delta y)^2}$$

$$\Delta z = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0)$$

$$\frac{\Delta z}{\rho}$$

## 方向导数

1.  $z = f(x, y) ((x, y) \in D), M_0(x_0, y_0) \in D$ , 在 $xoy$ 面内由 $M_0$ 作射线 $l$ ,

$$M'(x_0 + \Delta x, y_0 + \Delta y) \in l, \rho = \sqrt{(\Delta x)^2 + (\Delta y)^2}$$

$$\Delta z = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0)$$

若  $\lim_{\rho \rightarrow 0} \frac{\Delta z}{\rho} \exists$ , 称此极限为  $z = f(x, y)$  在  $M_0$  处沿射线

$l$  的方向导数, 记  $\frac{\partial z}{\partial l} |_{M_0}$

2.  $u = f(x, y, z) ((x, y, z) \in \Omega), M_0 \in \Omega$

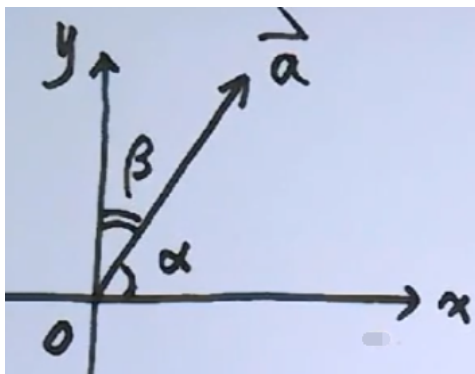
过  $M_0$  作射线  $l, M'(x_0 + \Delta x, y_0 + \Delta y, z_0 + \Delta z) \in l$

$$\rho = \sqrt{(\Delta x)^2 + (\Delta y)^2 + (\Delta z)^2}$$

$$\Delta u = f(x_0 + \Delta x, y_0 + \Delta y, z_0 + \Delta z) - f(x_0, y_0, z_0)$$

若  $\lim_{\rho \rightarrow 0} \frac{\Delta u}{\rho} \exists$ , 称此极限为  $f(x, y, z)$  在  $M_0$  处沿射线  $l$

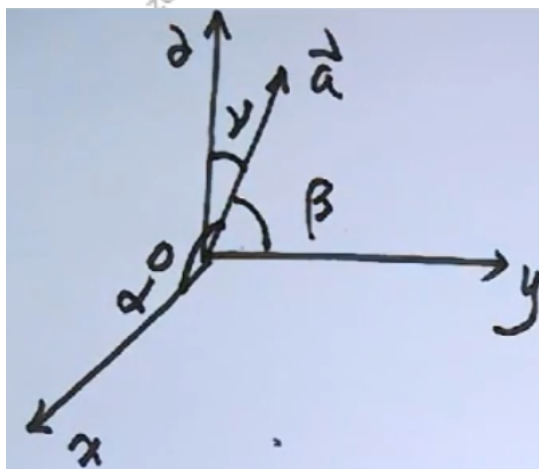
的方向导数, 记  $\frac{\partial u}{\partial l} |_{M_0}$



1.  $\alpha, \beta$  为  $\vec{a}$  的方向角

$\cos \alpha, \cos \beta$  为  $\vec{a}$  的方向余弦

$$\text{设 } \vec{a} = \{a_1, b_1\}, \vec{a}^o = \left\{ \frac{a_1}{\sqrt{a_1^2 + b_1^2}}, \frac{b_1}{\sqrt{a_1^2 + b_1^2}} \right\} = \{\cos \alpha, \cos \beta\}$$



$$2. \vec{a} = \{a_1, b_1, c_1\}, |\vec{a}| = \sqrt{a_1^2 + b_1^2 + c_1^2}$$

$$\vec{a}^o = \left\{ \frac{a_1}{|\vec{a}|}, \frac{b_1}{|\vec{a}|}, \frac{c_1}{|\vec{a}|} \right\} = \{\cos \alpha, \cos \beta, \cos \gamma\}$$

$$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$$

## 如何计算方向导数?

### 二元

$z = f(x, y), M_0(x_0, y_0) \in D$ , 过  $M_0$  作射线  $l$

方向角为  $\alpha, \beta$  :

$$\frac{\partial z}{\partial l} \Big|_{M_0} = \frac{\partial z}{\partial x} \Big|_{M_0} \cdot \cos \alpha + \frac{\partial z}{\partial y} \Big|_{M_0} \cdot \cos \beta$$

$z = (x^2 + y^2)^{xy}$  在  $(1, 1)$  处从  $(1, 1)$  指向  $(0, 2)$  的方向导数.

$$\text{解: } z = e^{xy \ln(x^2+y^2)}, \frac{\partial z}{\partial x} = (x^2 + y^2)^{xy} \cdot [y \ln(x^2 + y^2) + \frac{2x^2 y}{x^2 + y^2}]$$

$$\frac{\partial z}{\partial y} = (x^2 + y^2)^{xy} \cdot [x \ln(x^2 + y^2) + \frac{2xy^2}{x^2 + y^2}]$$

$$\frac{\partial z}{\partial x} \big|_{(1,1)} = 2(\ln 2 + 1), \frac{\partial z}{\partial y} \big|_{(1,1)} = 2(\ln 2 + 1)$$

从(1, 1)指向(0, 2)的向量为 $\{-1, 1\}$

$$\cos \alpha = -\frac{1}{\sqrt{2}}, \cos \beta = \frac{1}{\sqrt{2}}$$

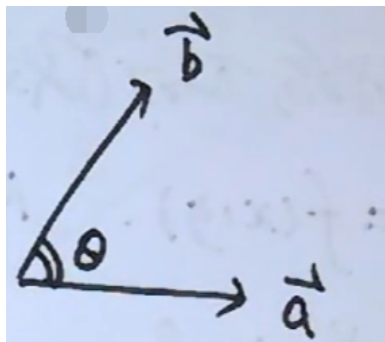
$$\frac{\partial z}{\partial l} \big|_{(1,1)} = 2(\ln 2 + 1) \cdot \left(-\frac{1}{\sqrt{2}}\right) + 2(\ln 2 + 1) \cdot \frac{1}{\sqrt{2}} = 0$$

### 三元

$u = f(x, y, z), M_0 \in \Omega$ , 过 $M_0$ 作射线 $l$ , 方向余弦为 $\cos \alpha, \cos \beta, \cos \gamma$

$$\frac{\partial u}{\partial l} \big|_{M_0} = \frac{\partial u}{\partial x} \big|_{M_0} \cdot \cos \alpha + \frac{\partial u}{\partial y} \big|_{M_0} \cdot \cos \beta + \frac{\partial u}{\partial z} \big|_{M_0} \cdot \cos \gamma$$

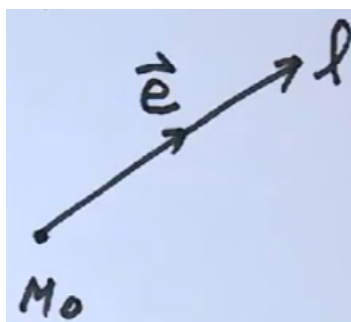
### 梯度



$$\vec{a} = \{a_1, b_1, c_1\}, \vec{b} = \{a_2, b_2, c_2\}$$

$$\vec{a} \cdot \vec{b} = |\vec{a}| \cdot |\vec{b}| \cdot \cos \theta$$

$$\vec{a} \cdot \vec{b} = a_1 a_2 + b_1 b_2 + c_1 c_2$$



$u = f(x, y, z), M_0 \in \Omega$ , 过  $M_0$  作射线  $l$ , 方向余弦  $\cos \alpha, \cos \beta, \cos \gamma$

$$\{\cos \alpha, \cos \beta, \cos \gamma\} = \vec{e}$$

$$\frac{\partial u}{\partial l} \big|_{M_0} = \frac{\partial u}{\partial x} \big|_{M_0} \cdot \cos \alpha + \frac{\partial u}{\partial y} \big|_{M_0} \cdot \cos \beta + \frac{\partial u}{\partial z} \big|_{M_0} \cdot \cos \gamma$$

$$= \left\{ \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z} \right\}_{M_0} \cdot \{\cos \alpha, \cos \beta, \cos \gamma\}$$

$$= \left\{ \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z} \right\}_{M_0} \cdot \vec{e}$$

$$= \sqrt{\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial u}{\partial z}\right)^2} \big|_{M_0} \cdot \cos \theta$$

当  $\cos \theta = 1$ , 或  $\theta = 0$ , 即  $l$  的方向与  $\left\{ \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z} \right\}_{M_0}$  同向时,

$$\frac{\partial u}{\partial l} \big|_{M_0} \text{ 取最大值 } \sqrt{\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial u}{\partial z}\right)^2} \big|_{M_0}$$

$$\text{记 } \left\{ \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z} \right\}_{M_0} \triangleq \text{grad} u \big|_{M_0}$$

$u = f(x, y, z)$  在  $M_0$  处的梯度

$$\frac{\partial u}{\partial l} \big|_{M_0} = \text{grad} u \big|_{M_0} \cdot \vec{e}$$

$$= \sqrt{\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial u}{\partial z}\right)^2} \big|_{M_0} \cdot \cos \theta$$

当  $\theta = 0$ , 即  $l$  的方向与梯度同向, 函数增长速度最快