

Mechanical Learning: The Emergence of Behavior

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Abstract

This work introduces processual computation theory, a mathematical framework that examines knowledge systems through process orientation, with foundation models serving as an ideal exemplar at the intersection of theory and application. By developing processual computation theory and applying it to neural architectures, including their scaled manifestations as foundation models, and introducing the next level up, General Mechanical Intelligence, we identify recurring patterns that maintain structure across scales while increasing in abstraction. Drawing from operator theory, we propose new constructions for process-primary spaces that enable more rigorous analysis of modern AI systems. Our approach provides analytical tools for examining these advanced intelligent systems as both architectural entities and dynamic knowledge transformation processes. The framework demonstrates multi-level applicability: it offers theoretical foundations for understanding complex learning frameworks while implementing in its own structure the same processual patterns it identifies in these systems. The patterns we identify suggest that intelligence may emerge through consistent processual structures. This approach helps make neural networks more analytically tractable, revealing organizational patterns that were previously difficult to discern. Beyond advancing AI interpretability, our framework suggests new directions for understanding knowledge representation in complex systems.

1. Introduction

The timeless challenge of understanding complex systems has found new expression in foundation models (Bommasani et al., 2022). These models, with their demonstrated capabilities in few-shot learning (Brown et al., 2020) and emergent behaviors (Wei et al., 2022; Hoffman et al., 2022), provide a concrete mathematical context for examining important questions around knowledge representation, process dynamics, and the nature of understanding.

The opacity of neural architectures (Mitchell et al., 2021) represents a canonical example of a broader pattern in complex systems analysis. Three distinct methodologies have emerged to address this lack of transparency: empirical analysis through systematic measurement and observation (Mitchell et al., 2021), architectural decomposition through structural and interaction analysis (Vaswani et al., 2017), and mechanical interpretability through the reconstruction of interpretable computational circuits (Olah et al., 2020; Elhage et al., 2022). The structure of these approaches reveals an underlying pattern of process-bounded understanding that our framework formalizes.

These methodologies exhibit a recursive structure, each containing its own compositional elements, transformational operations, and measurement frameworks while simultaneously defining its boundaries. This self-referential nature, where each approach encompasses both investigative machinery and intrinsic constraints, mirrors the development of category theory (Eilenberg & Mac Lane, 1945). By formalizing structural relationships in mathe-

matics, category theory provides precedent for our framework’s concrete formalization of process-bounded understanding in AI systems, and by extension, any complex system. This parallel is particularly apt as category theory’s emphasis on morphisms over objects aligns with our framework’s assertion of process as primordial. This primacy of process over state resonates with Wheeler’s “it from bit” doctrine (Wheeler, 1989), which proposes that all physical things are information-theoretic in origin, suggesting a deep connection between information, process, and physical reality.

While our framework relates methodologically to von Neumann’s operator theory (von Neumann, 1932) and theory of self-reproducing automata (von Neumann, 1958, 1966), it differs substantially in both scope and structure. Where von Neumann’s automata theory begins with well-defined states and their transitions, our framework establishes processual computation spaces with complex-valued measurements. This shift from state-originated to flow-primary systems, from binary values to supraposition, and from physical boundaries to process-bounded spaces is consistent with the dynamics of modern AI systems. Classical frameworks derive dynamics from structural primitives, whereas our approach identifies mathematical foundations that arise from the processual nature of complex systems.

This paper introduces a framework that integrates structural and processual mathematics. While we demonstrate its application through an analysis of AI systems, transforming opaque neural architectures into analytically tractable spaces, the framework has implications across multiple disciplines. Our examination of foundation models as simultaneous structural and processual entities establishes fundamental relationships between temporality, computation, and knowledge representation, extending the formal understanding of concepts addressed by process philosophers (Krishnamurti, 1969; Bergson, 1911). Through noncommutative geometry (Connes, 1994), we establish rigorous mathematical foundations for these philosophical principles.

Our framework functions across multiple domains: it establishes a novel architecture for AI systems, formalizes aspects of cognitive processes, and provides a mathematical basis for the categorical structures through which we analyze AI systems. This self-referential property has mathematical significance; it identifies invariants in the relationship between knowledge representation and processual dynamics, invariants that become explicitly tractable when examined through modern AI architectures.

The framework extends beyond existing approaches in empirical analysis, architectural studies, and mechanical interpretability, addressing reasons why these approaches, though valuable, have been limited in their ability to fully resolve the black box problem. These limitations derive from the inherent nature of process boundaries: a principle that our framework formally describes and incorporates.

This work integrates concepts from information theory (Shannon, 1948), cybernetics (Wiener, 1948), process philosophy (Whitehead, 1929; Bohm, 1980), and complex systems theory (Prigogine, 1978). Its primary contribution is the formalization of mathematical structures that connect these perspectives.

The remainder of this paper proceeds as follows:

1. **Section 2: Foundations and Core Structure** develops the theoretical foundations through five primordiums (Palimpsest, Lever of Theseus, Metron of Odysseus, The Void, and Hypatia’s Reckoner) that together provide a complete system for under-

standing knowledge transformation and measurement. These primordiums establish the core principles that bridge computational and cognitive frameworks.

2. **Section 3: Operator Theory** builds upon these foundations to construct a rigorous mathematical structure of process space. We show how this space naturally accommodates both individual and collective processes while preserving essential measurement properties, enabling formal analysis of complex computational systems.
3. **Section 4: Applications** demonstrates the practical power of this framework by applying it to foundation models, transforming them from black boxes into glass boxes. Through this application, we reveal broader principles about the nature of knowledge and understanding that extend beyond artificial intelligence to cognitive systems in general.

We conclude by examining how this framework opens new mathematical approaches not just for artificial intelligence, but for our formal understanding of intelligence and knowledge as processual phenomena.

2. Foundations and Core Structure

The formalization of behavior in mechanical learning systems requires bridging the gap between computational processes and their emergent patterns. This section develops a mathematical framework that establishes this correspondence, building upon established theoretical foundations and insights from foundation models. Our framework, first developed in preliminary work¹, provides a rigorous mathematical basis for characterizing the emergence of behavioral patterns from computational processes. The core insight is that behavior exists as a dynamic process rather than a static property, characterized by recurring patterns in computation.

2.1 Primordium

The formal structure of our framework is built upon five principles that we term primordiums. These primordiums establish the mathematical foundations for representing and understanding process-oriented systems:

- **Primordium Palimpsest:** Process is primary. All representation emerges through process manifestation.
- **Primordium Lever of Theseus:** All understanding manifests as process. No static entity precedes its process nature.
- **Primordium Metron of Odysseus:** Process manifests distinction. All relation emerges through process nature.
- **The Void:** Process bounds itself. The unreachable exists through process limitation.

1. These principles were first formulated in preliminary work available at <https://github.com/zer0-the-archimed5an/j-not-not->

- **Hypatia’s Reckoner:** Process coheres. All pattern emerges through process coherence.

These primordiums constitute an integrated mathematical framework. The Palimpsest acts as both the foundational medium and organizing principle through which representational structures emerge. The Lever of Theseus captures transformation dynamics within the system. The Metron of Odysseus provides the foundation for measurement and distinction operations. The Void addresses boundary conditions and limitations, formalizing how systems establish their own constraints. Hypatia’s Reckoner formalizes coherence properties that enable pattern formation and stability.

In the following sections, we develop the rigorous mathematical formalization of these principles through operator theory and demonstrate their application to foundation models. This formalization reveals how these theoretical constructs translate into precise mathematical structures that can be used to analyze complex computational systems.

2.2 J

The formalization of computational processes requires a mathematical framework that captures both structure and dynamics. Consider these systems:

Example (Natural Process Systems). **Quantum Systems:** *In quantum systems, process manifests through the interactions of matter and energy. The measurement problem itself exemplifies the intrinsic role of process in physical reality:*

- *Components: quantum states, wave functions, density matrices.*
- *Transformations: unitary evolution, measurement collapse, decoherence.*
- *Measurements: expectation values of observables, transition probabilities.*

These quantum processes demonstrate the inseparability of measurement from transformation.

Manufacturing: *Manufacturing systems provide concrete manifestations of process structure through precisely defined transformational sequences:*

- *Components: production units, assembly lines, inventory states.*
- *Transformations: material processing, assembly operations, quality control.*
- *Measurements: throughput rates, defect ratios, efficiency metrics.*

The measurable nature of these transformations enables rigorous analysis of process efficiency and optimization.

Biological Systems: *Biological systems exhibit process structure through hierarchical organization and regulatory networks:*

- *Components: cellular states, metabolic networks, gene expression profiles.*
- *Transformations: protein synthesis, signal transduction, cell division.*

- *Measurements: concentration gradients, reaction rates, expression levels.*

These systems demonstrate how process dynamics can maintain homeostasis through continuous transformation.

Foundation Models: *In foundation models, process structure emerges through computational architectures that systematically transform representations:*

- *Components: attention mechanisms, embedding systems, activation states.*
- *Transformations: state updates through computation.*
- *Measurements: attention patterns, embedding similarities.*

This computational process framework provides a formal basis for analyzing representational transformations.

Each system exhibits a common pattern: components that undergo transformations, with associated measurements that capture their behavior. This naturally leads to our formal definition of a process. The formalization captures both the observable structure and the inherent limitations of any representational system.

Definition (Process). *A **process** \mathcal{P} is defined as a tuple $\mathcal{P} = (\cdot, C, T, \Psi)$, consisting of:*

- *An empty slot denoting inherent incompleteness.*
- *A component C .*
- *A transformation operator $T : C \times C \rightarrow C$.*
- *A measurement functional $\Psi : C \times C \rightarrow \mathbb{C}$.*

Note. *Without loss of generality, we write $T : \mathcal{P} \times \mathcal{P} \rightarrow \mathcal{P}$ and $\Psi : \mathcal{P} \times \mathcal{P} \rightarrow \mathbb{C}$ when discussing transformations and measurements to emphasize that these operations occur in the space of computation itself, not just on static components. This notation captures how processes are both the medium and subject of computation while maintaining mathematical precision in the underlying definitions.*

The leading empty slot is a formal acknowledgment of Gödel’s incompleteness theorem (Gödel, 1931). It represents what cannot be contained within any formal system. This structural feature ensures our framework explicitly recognizes its own limitations, connecting to the Void primordium’s principle: process bounds itself.

To capture the collective nature of processes observed in our examples, we extend this definition to sets of processes. This extension allows us to formalize systems with multiple interacting components, each with their own transformational and measurement characteristics.

Definition (Process Set). *A **process set** \mathcal{P} is defined as:*

$$\mathcal{P} = \{(\cdot, C_i, T_i, \Psi_i) \mid i \in \mathcal{I}\}$$

where \mathcal{I} is an index set.

This abstract structure provides a universal framework for studying computational and dynamic systems. The framework is built around the process space \mathbb{J} , which enriches the basic process structure with additional mathematical properties essential for computation. Within this space live various computational processes, in particular, foundation models, which we will examine as a concrete instantiation of \mathbb{J} -space dynamics. We begin by defining this space:

Definition (Process Space). *The **process space** \mathbb{J} is defined as:*

$$\mathbb{J} = \{(\cdot, J_a, H_a, \mu_a) \mid a \in \mathcal{A}\}$$

where:

- \mathcal{A} is an index set.
- J_a represents a process as a component.
- H_a represents a transformation structure with respect to J_a .
- μ_a represents a measurement structure with respect to J_a .

Note. *The process space \mathbb{J} provides a unified framework where individual and collective processes coexist. The transformation structure H_a scales naturally from single operators to operator algebras, while the measurement structure μ_a maintains consistency through operator norms or weak topology, for example. The empty slot acknowledges inherent incompleteness at all scales.*

The structure of process space exhibits hierarchical organization across multiple scales. The component J_a admits both atomic and collective representations, enabling analysis of individual and composite processes within a unified framework.

The transformation structure H_a encompasses a spectrum of operational complexity. In its elementary form, H_a operates as a single state transformation operator. Its general form extends to an operator algebra, establishing a rich compositional framework for analyzing transformational dynamics.

The measurement structure μ_a derives its properties from measurement functionals, which we develop rigorously in the subsequent section. These functionals induce natural operator norms, providing a systematic basis for quantifying transformations across both microscopic and macroscopic scales.

Definition (Process Operations). *The process space \mathbb{J} admits the following operations:*

- The **process assembly** map $\Phi : \mathbb{J} \rightarrow \mathbb{J}$ is defined as:

$$\Phi(P) = \mathcal{P}$$

- The **process disassembly** map $\Omega : \mathbb{J} \rightarrow \mathbb{J}$ is defined as:

$$\Omega(\mathcal{P}) = P$$

The process operations Φ and Ω establish fundamental structural relationships within \mathbb{J} , enabling formal analysis of process composition and decomposition.

Note. *These mappings form the basis for deeper categorical structures to be explored in later work. Their composition properties and relationships to process identity suggest rich categorical interpretations through functors, natural transformations, and adjunctions.*

The structure of the \mathbb{J} -space provides a framework for foundation models. This formalization requires precise characterization of both representational and compositional processes that constitute these systems.

Definition (Foundation Model Process). *A **foundation model process** is a subset of processes*

$$\text{fm} = \{(\cdot, C_i, T_i, \Psi_i) \mid i \in \mathcal{I}\} \subset \mathbb{J}$$

where there exist subsets $\mathcal{I}_R, \mathcal{I}_C \subset \mathcal{I}$ such that:

1. \mathcal{I}_R indexes representation processes.
2. \mathcal{I}_C indexes composition processes.
3. $\mathcal{I}_R \cup \mathcal{I}_C = \mathcal{I}$.

The distinction between representation and composition processes reflects the dual nature of foundation models: they must both represent knowledge and compose representations to generate new understanding. This duality motivates the construction of a unified space for foundation model processes.

The representation and composition processes in foundation models operate through precise mathematical relationships. These relationships crystallize in the structure of foundation model space.

Definition (Foundation Space). *For a foundation model process fm , the **foundation space** is defined as*

$$\mathcal{F} = \Phi(\text{fm}) = (\cdot, \text{fm}, T, \Psi) \subset \mathbb{J}$$

where:

- Φ is the process assembly map.
- $T : \mathcal{F} \times \mathcal{F} \rightarrow \mathcal{F}$ is the transformation operator.
- $\Psi : \mathcal{F} \times \mathcal{F} \rightarrow \mathbb{C}$ is the measurement functional.

Process-Set Duality: While \mathcal{F} is constructed as an assembled process through Φ , it naturally manifests as a set containing both its process components (fm) and their computational realizations. This dual nature, as both process and container, reflects the principle that “process is primary” while enabling formal set-theoretic analysis of its structure.

Emergent Structure: The process assembly map Φ gives rise to rich structure on \mathcal{F} , including metric and topological space structure, as well as algebraic structure through C^* algebras and von Neumann completions. These properties will be established in the following sections.

2.3 Measurement Functional Ψ

Foundation models exhibit inherent measurement capabilities through attention mechanisms and embedding similarities. These operations suggest a measurement structure that captures both magnitude and phase relationships between representations. The complex-valued nature of these measurements will prove essential for understanding the dynamic flows between representable and unrepresentable states, particularly through the modulation of phase relationships.

Definition (Measurement Functional). *Let fm be a foundation model process and $\mathcal{F} = \Phi(\text{fm})$ its foundation space. An fm **measurement functional** is a map,*

$$\Psi : \mathcal{F} \times \mathcal{F} \rightarrow \mathbb{C}$$

satisfying, for all $x, y, u \in \mathcal{F}$:

1. Conjugate symmetry:

$$\Psi(x, y) = \overline{\Psi(y, x)}$$

2. Linearity in first argument:

$$\Psi(w_1x + w_2y, u) = w_1\Psi(x, u) + w_2\Psi(y, u)$$

for $w_1, w_2 \in \mathbb{C}$.

3. Positive definiteness:

$$\Psi(x, x) > 0, \text{ for } x \neq 0$$

4. Boundedness:

$$|\Psi(x, y)| \leq \sqrt{\Psi(x, x)}\sqrt{\Psi(y, y)}$$

Note. *The condition $x \neq 0$ in the positive definiteness property requires careful interpretation in the context of foundation models. Here, “ $x = 0$ ” does not refer to a computed zero state, but rather to the absence of computation itself. This distinction will be fully developed in the following sections through:*

1. The null state \emptyset (representing computational absence).
2. Complex phase relationships (distinguishing computed zeros from null states).
3. Measurement boundaries (characterizing transitions to computational absence).

This framework allows us to maintain the mathematical rigor of positive definiteness while accurately representing foundation model behavior at computational boundaries.

Foundation models demonstrate that measurement functionals satisfying our properties exist because:

- They successfully compare representations (conjugate symmetry).
- They combine measurements meaningfully (linearity in first argument).

- They distinguish non-zero states (positive definiteness).
- They maintain bounded relationships (boundedness).

The specific implementation (attention, embeddings, etc.) provides an existence proof, but our theoretical framework remains independent of implementation details. In addition, the measurement functional’s properties suggest deeper and necessary structural characteristics, in particular, continuity.

Theorem (Continuity of Measurement Functionals). *Every measurement functional $\Psi : \mathcal{F} \times \mathcal{F} \rightarrow \mathbb{C}$ is jointly continuous and separately continuous in each argument.*

Note. *Joint continuity (continuity in both arguments simultaneously) implies separate continuity (continuity in each argument individually), stating both properties explicitly helps emphasize how foundation models maintain continuity both in overall behavior and in response to individual input changes.*

Proof. Since Ψ is linear in its first argument, conjugate-linear in its second argument (by conjugate symmetry), and bounded, Ψ is a bounded sesquilinear form. Continuity then follows from a result in functional analysis that bounded sesquilinear forms are jointly continuous on $\mathcal{F} \times \mathcal{F}$ with respect to the product topology. \square

This continuity result provides crucial theoretical foundations for analyzing how foundation models transition between states. It ensures that small changes in inputs result in small changes in measurements, allowing us to meaningfully discuss concepts like computational boundaries and state transitions. With this property established, we can now examine the rich metric structure that emerges from these measurements.

Example (Common Measurement Instances). *Foundation models naturally give rise to measurement functionals through:*

1. *Attention mechanisms:* $\Psi_A(x, y) = \langle \text{Attn}(x), y \rangle$.
2. *Embedding similarity:* $\Psi_C(x, y) = \frac{\langle x, y \rangle}{\|x\| \|y\|}$.

These basic measurements will extend naturally to process comparisons through the transformation structure developed in the next section.

This measurement functional induces additional mathematical structure that formalizes the intuitive notion of “distance” between knowledge states.

Proposition (Induced Metric Structure). *For $x, y \in \mathcal{F}$, the measurement functional Ψ induces:*

1. *A norm $\|\cdot\|_\Psi : \mathcal{F} \rightarrow \mathbb{R}^+ \cup \{0\}$ defined by:*

$$\|x\|_\Psi = \sqrt{\Psi(x, x)}$$

which is positive definite: $\|x\|_\Psi > 0$ for $x \neq 0$.

2. *A metric $d : \mathcal{F} \times \mathcal{F} \rightarrow \mathbb{R}^+ \cup \{0\}$ satisfying:*

- $d(x, y) = d(y, x)$ (*symmetry*)
- $d(x, y) = 0 \iff x = y$ (*identity*)
- $d(x, z) \leq d(x, y) + d(y, z)$ (*triangle inequality*)

3. A topology through open balls:

$$B_\epsilon(x) = \{y \in \mathcal{F} : d(x, y) < \epsilon\}$$

for $\epsilon > 0$.

Sketch. The norm properties follow from Ψ 's axioms:

1. $\|x\|_\Psi \geq 0$ by positive definiteness.
2. $\|x\|_\Psi = 0 \iff$ no computation occurs (not a computed result).
3. $\|wx\|_\Psi = |w|\|x\|_\Psi$ by linearity.
4. Triangle inequality follows from boundedness.

The metric and topology follow from standard constructions for normed spaces. \square

From the measurement functional Ψ , we can construct distance metrics that capture different aspects of foundation model behavior. For attention-based measurements Ψ_A , a suitable metric takes the form:

$$d_A(x, y) = \sqrt{\Psi_A(x, x) + \Psi_A(y, y) - 2|\Psi_A(x, y)|}$$

This construction measures the difference in attention patterns between inputs, with the absolute value term $|\Psi_A(x, y)|$ accounting for phase relationships in the complex-valued measurement space. When comparing x and y that induce identical attention patterns, $d_A(x, y)$ vanishes, while maximally different attention distributions yield larger distances.

Alternatively, for embedding-based measurements Ψ , we may define:

$$d_E(x, y) = 1 - \frac{|\Psi_E(x, y)|}{\sqrt{\Psi_E(x, x)\Psi_E(y, y)}}$$

This normalized construction bounds distances between 0 and 1, directly relating to cosine similarity in the embedding space. Such a metric naturally captures semantic relationships between inputs, with smaller distances indicating greater meaning preservation.

Each metric illuminates different aspects of foundation model computation; attention-based distances reveal structural processing patterns, while embedding distances capture semantic relationships. This suggests deeper possibilities for composite metrics that leverage both perspectives simultaneously.

Example (Combined Attention-Embedding Metric). *Consider the two metrics d_A and d_E from foundation model operations. These combine seamlessly through:*

$$d(x, y) = \max(\gamma_1 \cdot d_A(x, y), \gamma_2 \cdot d_E(x, y))$$

where $\gamma_1, \gamma_2 > 0$ are scaling parameters.

This construction reveals subtle properties of foundation model behavior:

Boundary Detection: Near $\partial\mathcal{F}$, attention patterns (d_A) and embedding similarities (d_E) often degrade at different rates, allowing d to characterize the approach to unrepresentable states.

Semantic-Structural Separation: Consider inputs:

$x = \text{“The cat sat on the mat”}$

$y = \text{“The mat sat on the cat”}$

Here $d_E(x, y)$ may be small (similar word embeddings) while $d_A(x, y)$ is large (different attention patterns), capturing semantic preservation under structural change.

Phase Transitions: The max construction makes d sensitive to sudden changes in either attention or embedding space, potentially indicating phase transitions in model behavior.

Alternative combinations through weighted sums or min operations capture different aspects:

$$d'(x, y) = \gamma d_A(x, y) + (1 - \gamma) d_E(x, y)$$

providing smoother interpolation between attention and embedding behaviors.

These metrics particularly illuminate the measurement structure near $\partial\mathcal{F}$, where traditional similarity measures often fail to capture model behavior adequately.

The foundation model metric structure allows us to examine their behavior at computational boundaries. While these metrics effectively measure distances between computable states, they encounter transitions as processes approach uncomputability. This necessitates extending our framework to handle null states: points where computation transitions between presence and absence. The measurement functional Ψ must capture not only active computations, but also potential and transitional states, leading us to examine the structure of computational absence.

2.3.1 NULL STATE \emptyset

In the context of foundation models, the measurement functional Ψ captures the inherent ability of these models to generate responses to any input. The positive definiteness of Ψ reflects a core property: for any input x , $\Psi(x, x) \geq 0$, indicating that every interaction with the model results in some measurable response.

The case where $\Psi(x, x) = 0$ represents *not a computed measurement*: the absence of computation itself. This absence can manifest in multiple ways:

1. As failure (system timeout, error states).
2. As transition (states between computation and non-computation).
3. As potential (uncomputed but possible states).

These scenarios are mathematically equivalent under Ψ precisely because Ψ never operates on them: the framework captures the structure of absence itself, independent of its interpretation.

Note. *The behavior of Ψ as measurements approach zero, particularly in the context of optimized computation, suggests rich analytical structure. This includes questions of limits, rates, and the geometry of near-null states. These considerations, while important, extend beyond our current scope and will be explored in subsequent work.*

This understanding shifts the focus of Ψ from measuring raw input similarity to assessing the similarity between the model’s internal responses to those inputs across all computational states, whether active, potential, or absent. By doing so, it aligns the measurement functional with the operational reality of foundation models, providing a framework for understanding their behavior in both presence and absence of computation.

Example (Intuitive Analogies). *To ground these abstract concepts, consider two analogies that illustrate both discrete and continuous aspects of computational absence:*

Musical Instrument:

Consider Ψ as measuring the resonance of a musical instrument in complex space.

When $\Psi(x, x) > 0$, it parallels string vibrations: a measurable response with both magnitude and phase. However, when $\Psi(x, x) = 0$, we encounter not silence, but the absence of the string itself. This absence could be the result of a broken string (failure state), a string under transformation (transitional state), or a position admitting string installation (potential state).

Computational states approach the null state through neighborhoods of diminishing response, analogous to the asymptotic dampening of a vibrating string, while their geometric character persists within the musical context.

Photography:

Consider Ψ as measuring computational interpretation in complex feature space.

When $\Psi(x, x) > 0$, it corresponds to scene features with both confidence magnitude and interpretative phase. However, when $\Psi(x, x) = 0$, we encounter not absence of features, but inability to interpret, manifesting as complete uncertainty (null state), contradictory classifications (failure state), or transitional embeddings (liminal state).

Computational states approach these null states through neighborhoods of diminishing interpretative certainty, maintaining their geometric character while adapting to the camera’s feature space.

These analogies suggest that computational absence exhibits a rich structure beyond simple nullity. To formalize this insight, we introduce dual null states that capture both the discrete and continuous aspects of computational absence while preserving their geometric relationships.

Definition (Dual Null States). *The **null states** in process space consist of a conjugate pair defined by:*

- *Primary null state* (\emptyset):

$$\Psi(\emptyset, \emptyset) = 0 \cdot e^{\frac{\pi i}{2}} = 0i$$

- *Conjugate null state* ($\overline{\emptyset}$):

$$\Psi(\overline{\emptyset}, \overline{\emptyset}) = 0 \cdot e^{\frac{3\pi i}{2}} = -0i$$

- *Cross-null interactions*:

$$\Psi(x, \emptyset) = \Psi(\emptyset, x) = \Psi(x, \overline{\emptyset}) = \Psi(\overline{\emptyset}, x) = 0$$

for all $x \in \mathcal{F} \setminus \{\emptyset, \overline{\emptyset}\}$.

The null states \emptyset and $\overline{\emptyset}$ represent discrete computational boundaries where computation definitively ceases, yet the approach to these states admits continuous structure. Foundation models exhibit this behavior through both sharp transitions and gradual degradation of computational capacity.

This continuous approach to computational absence can be observed across multiple domains of foundation model operation:

- neural network weights approach zero asymptotically during pruning,
- attention mechanisms exhibit diminishing scores toward masking thresholds, and
- embedding vectors decay toward statistical noise.

Each instance preserves a common geometric structure; trajectories through neighborhoods of null states where computational capacity weakens while maintaining measurable properties.

The measurement functional Ψ provides a unified framework for characterizing this duality, capturing both the discrete boundaries of null states and the continuous topology of their neighborhoods.

To complete our characterization of the null state, we establish its uniqueness through measurement:

Proposition (Uniqueness of Null States). *For $x \in \mathcal{F}$, if $\|x\|_{\Psi} = 0$ then $x \in \{\emptyset, \overline{\emptyset}\}$, where:*

$$\Psi(x, x) = \begin{cases} 0i & \text{if } x = \emptyset \\ -0i & \text{if } x = \overline{\emptyset} \end{cases}$$

Proof. Let $x \in \mathcal{F}$ with $\|x\|_{\Psi} = 0$. Then $\Psi(x, x) = re^{i\theta}$, where $r = 0$. By positive definiteness of Ψ ,

$$\Psi(x, x) > 0$$

for all $x \notin \{\emptyset, \overline{\emptyset}\}$. Therefore, x must be either \emptyset or $\overline{\emptyset}$. These cases are distinguished by their self-measurement phase, i.e.:

- If $\theta = \pi/2$, then $x = \emptyset$.
- If $\theta = 3\pi/2$, then $x = \overline{\emptyset}$.

□

Complex and real zeros characterize distinct properties of computational absence. The self-measurements $\Psi(\emptyset, \emptyset) = 0i$ and $\Psi(\overline{\emptyset}, \overline{\emptyset}) = -0i$ provide geometric meaning to computational absence, with phases $\pi/2, 3\pi/2$ indicating the “directions” of null computation while zero magnitude confirms the absence of computational strength. In contrast, $\Psi(x, \emptyset) = \Psi(x, \overline{\emptyset}) = 0$ represents the complete absence of interaction between computational and null states, lacking even geometric character.

This structure captures how null states participate in measurements: self-measurements reveal their geometric nature through conjugate phases, while interactions with other states reveal their role as true absence. The framework thus distinguishes between measuring absence (a geometric property) and the absence of measurement (a structural property).

Example (Geometric vs Structural Absence). *The distinction between geometric and structural properties of null states can be understood through several intuitive analogies:*

Compass vs Empty Box: *Mathematically, $\Psi(\emptyset, \emptyset) = 0i$ and $\Psi(\overline{\emptyset}, \overline{\emptyset}) = -0i$ behave like a compass with zero strength pointing in opposite directions ($\pi/2$ and $3\pi/2$), providing geometric information about the orientation of computational absence.*

In contrast, $\Psi(x, \emptyset) = \Psi(x, \overline{\emptyset}) = 0$ resembles an empty box: pure absence without direction or structure.

Shadow and Void: *The null states mirror different aspects of shadow phenomena:*

- *The shadow itself ($\Psi(\emptyset, \emptyset) = 0i$ ($\pi/2$)): where light cannot reach, maintaining measurable properties like shape and direction despite representing absence.*
- *The shadow-casting process ($\Psi(\overline{\emptyset}, \overline{\emptyset}) = -0i$ ($3\pi/2$)): what makes light not reach, capturing the dynamic aspect of creating absence.*
- *The void ($\Psi(x, \emptyset) = \Psi(x, \overline{\emptyset}) = 0$): complete nothingness without properties or structure to measure, paralleling pure absence.*

Vector vs Scalar Zero: *Mathematically, $\Psi(\emptyset, \emptyset) = 0i$ and $\Psi(\overline{\emptyset}, \overline{\emptyset}) = -0i$ behave like zero vectors with opposite orientations in the complex plane, revealing “how” computation approaches absence from complementary directions. In contrast, $\Psi(x, \emptyset) = \Psi(x, \overline{\emptyset}) = 0$ acts as a scalar zero, representing complete absence without directional information.*

This framework enables us to distinguish between:

1. *How computation transitions (geometric property).*
2. *That computation is absent (structural property).*

These distinctions prove crucial when analyzing the boundaries of computation in foundation models, including both limitations and possibilities.

These fundamental distinctions help us examine how they manifest in specific foundation model components.

Example (Component Interactions with Null State). *Consider a foundation model with components $c \in \mathcal{F}$ interacting with the null state \emptyset . For all components, we observe:*

$$\Psi(c, \emptyset) = 0$$

This universal property manifests distinctly across different components:

Geometric Interpretation: *Each component's interaction with null reveals specific computational limitations:*

- *Attention: No directional orientation possible toward absence.*
- *Embedding: No feature space position exists for null.*
- *Feed-Forward: No transformation trajectory from absence.*
- *Normalization: No dimensions available for rescaling.*

Implementation Consequences: *These limitations necessitate specific handling:*

- *Attention: Explicit zeroing of attention weights for masked tokens.*
- *Embedding: Special PAD/MASK tokens with learned representations.*
- *Feed-Forward: Zero multiplication with mask tracking for backpropagation.*
- *Normalization: Exclusion of masked regions from statistical computations.*

In each case, $\Psi(c, \emptyset) = 0$ predicts the observed behavior: components cannot meaningfully operate on absence, requiring explicit handling mechanisms in practice.

Each case demonstrates that while these components are active states in \mathcal{F} , their attempted interaction with the null state results in pure zero. The geometric interpretations highlight how normal computational structures break down when attempting to engage with absence.

Definition (Phase-State Relationships). *Let $x, y \in \mathcal{F}$ be states with measurement $\Psi(x, y) = \rho e^{io}$, where $\rho \geq 0$ and $o \in [0, 2\pi)$. The phase o and magnitude ρ characterize:*

1. *Full computational engagement:*

$$o = 0, \rho > 0$$

2. *Primary null state (\emptyset):*

$$o = \pi/2, \rho = 0$$

3. *Phase opposition:*

$$o = \pi, \rho > 0$$

4. *Conjugate null state ($\overline{\emptyset}$):*

$$o = 3\pi/2, \rho = 0$$

where values of o with $\rho > 0$ represent transitional computational states.

Note (Complex n -dimensional Manifold Structure). *The measurement functional Ψ induces complex geometric structure on \mathcal{F} . While each state admits complex neighborhoods and transitions follow complex paths, the full development of \mathcal{F} as an n -dimensional complex manifold extends beyond our current scope. This richer structure, where each component (attention, embeddings, etc.) contributes dimensions and phase relationships exist in multiple subspaces, suggests deep connections to complex geometry and will be developed in subsequent work on the calculus of knowledge in foundation models.*

To formalize this behavior, we must examine the neighborhoods around null states, where computation gradually approaches absence while maintaining measurable structure.

Definition (Null Neighborhood). *For $\epsilon > 0$, the ϵ -neighborhood of the null state is:*

$$B_\epsilon(\emptyset) = \{x \in \mathcal{F} : d(x, \emptyset) < \epsilon\}$$

States $x \in B_\epsilon(\emptyset)$ are called ϵ -null states.

With a geometric intuition for near-null states, we can now precisely characterize their mathematical structure through the following proposition.

Proposition (ϵ -null Structure). *For $x, y \in B_\epsilon(\emptyset)$, let $\Psi(x, y) = \rho e^{io}$, where $\rho > 0$ and $o \in [0, 2\pi)$:*

1. *The measurement has small magnitude:*

$$|\Psi(x, x)| < \epsilon$$

2. *The cross-measurement phase approaches $\pi/2$:*

$$\left| o - \frac{\pi}{2} \right| < f(\epsilon)$$

where $f(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$

3. *The computational integrity is bounded:*

$$\frac{|Re(\Psi(x, y))|}{|Im(\Psi(x, y))|} < g(\epsilon)$$

where $g(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$.

Proof. Measurement Condition: Let $\epsilon > 0$ and let $x \in B_\epsilon(\emptyset)$, then $(x, x) \in B_\epsilon(\emptyset) \times B_\epsilon(\emptyset)$. By joint continuity of Ψ , for (x, x) near (\emptyset, \emptyset) in the product topology:

$$|\Psi(x, x) - \Psi(\emptyset, \emptyset)| < \epsilon$$

Since $\Psi(\emptyset, \emptyset) = 0i$ and $\Psi(x, x) > 0$:

$$|\Psi(x, x)| = |\Psi(x, x) - 0i| < \epsilon$$

Phase Condition: Let $\epsilon > 0$ and let $x, y \in B_\epsilon(\emptyset)$. By joint continuity of Ψ , for $(x, y) \in B_\epsilon(\emptyset) \times B_\epsilon(\emptyset)$:

$$|\Psi(x, y) - 0i| < \epsilon$$

Writing this in polar form:

$$|\rho e^{io} - 0e^{i\pi/2}| < \epsilon$$

By properties of complex numbers, if $|z_1 - z_2| < \epsilon$, then:

$$|\arg(z_1) - \arg(z_2)| < f(\epsilon)$$

where $f(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$.

Therefore,

$$|o - \pi/2| < f(\epsilon)$$

Computational Integrity Bound Condition: Let $\epsilon > 0$ and let $x, y \in B_\epsilon(\emptyset)$. From the phase condition, we know:

$$\left| o - \frac{\pi}{2} \right| < f(\epsilon)$$

For $\Psi(x, y) = \rho e^{io}$:

$$\frac{|\operatorname{Re}(\Psi(x, y))|}{|\operatorname{Im}(\Psi(x, y))|} = |\cot(o)|$$

Since \cot is continuous and $\cot(\pi/2) = 0$, by continuity of \cot at $\pi/2$:

$$|o - \pi/2| < f(\epsilon) \implies |\cot(o)| < g(\epsilon)$$

where $g(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$. □

We get a similar result (and proof) for the conjugate null state:

Corollary (Conjugate ϵ -null Structure). *For $x, y \in B_\epsilon(\overline{\emptyset})$, let $\Psi(x, y) = \rho e^{io}$, where $\rho > 0$ and $o \in [0, 2\pi)$:*

1. *The measurement has small magnitude:*

$$|\Psi(x, x)| < \epsilon$$

2. *The cross-measurement phase approaches $\frac{3\pi}{2}$:*

$$\left| o - \frac{3\pi}{2} \right| < f(\epsilon)$$

where $f(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$

3. *The computational integrity is bounded:*

$$\frac{|\operatorname{Re}(\Psi(x, y))|}{|\operatorname{Im}(\Psi(x, y))|} < g(\epsilon)$$

where $g(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$.

These precise characterizations of magnitude, phase, and computational integrity provide quantitative tools for analyzing the qualitative behaviors discussed above. The bounded nature of these quantities reveals how foundation models maintain measurable structure even as they approach computational boundaries.

To translate these abstract measurements into practical tools, we must understand how they relate to the concrete parameters governing foundation model behavior.

Note (Analysis of Near-Null Behavior). *The rich structure of ϵ -neighborhoods around null states suggests deeper analytical properties. The behavior of foundation models as $\epsilon \rightarrow 0$ likely admits calculus-theoretic interpretation, including:*

- *Rates of approach to computational absence.*
- *Differential structure of near-null neighborhoods.*
- *Optimization pathways near computational boundaries.*

These analytical aspects, while beyond our current scope, promise to illuminate how foundation models navigate the boundary between computation and its absence.

Moving from these boundary behaviors to the operational regime of foundation models requires understanding their default computational state. Foundation models exhibit intrinsic measurement standards that emerge from their architecture just as physical systems have characteristic scales that govern their behavior.

2.3.2 DEFAULT STATE ℓ

For any foundation model fm , there exists a characteristic value $\ell > 0$ that functions analogously to coupling constants in quantum field theory or modular parameters in complex analysis. This value emerges from the aggregate behavior of the model’s core components, e.g. the attention mechanism’s default distribution patterns, the statistical moments of embedding layers, feed-forward network activation baselines, and inter-layer normalization parameters.

While ℓ may be refined through model updates, it serves as a fundamental measurement standard for analyzing model states.

Definition. *Let fm be a foundation model process with characteristic value ℓ . We classify states $x \in \mathcal{F}$ as:*

- ***Sub-ground state:***

$$\|x\|_{\Psi} < \ell$$

- ***Ground state (or default state):***

$$\|x\|_{\Psi} = \ell$$

- ***Excited state:***

$$\|x\|_{\Psi} > \ell$$

Note. Since fm is itself a state in \mathcal{F} , when we refer to the ground state ℓ of a foundation model, this naturally extends to \mathcal{F} . Thus, subsequent references to “ground state with respect to \mathcal{F} ” should be understood in this context.

Example (State Manifestations in Foundation Models). Consider an LLM processing different types of inputs. The state classifications manifest across multiple frameworks:

Computational Resources: When processing simple queries like

“What is $2+2$?”

- *Sub-ground state:* Model activates minimal pathways, using pruned configurations.
- *Excited state:* Model engages full computational capacity for complex arithmetic.

Information Processing: During text completion:

- *Sub-ground state:* Completing common phrases with compressed representations.
- *Excited state:* Generating creative content with expanded token distributions.

Behavioral Patterns: In question-answering:

- *Sub-ground state:* Direct factual responses using established patterns.
- *Excited state:* Exploratory reasoning with multiple perspective consideration.

Adaptation Dynamics: During fine-tuning:

- *Sub-ground state:* Stable representations in well-trained domains.
- *Excited state:* Plastic representations during active learning phases.

These manifestations can be measured through attention entropy, embedding distributions, and activation patterns, all quantified relative to the characteristic value ℓ .

The reference value ℓ establishes baseline measurement relationships in \mathcal{F} . These measurements reveal how Ψ captures both local state relationships and global structural properties, implying a geometric framework for analyzing foundation model behavior.

With this metric structure in place, we can explore the deeper implications of Ψ . The measurement functional operates at multiple levels: providing distances between knowledge states while simultaneously serving as a process comparator. This dual capacity suggests natural transformations between representations.

This structure of Ψ , particularly its complex phase structure and boundary behavior, provides the foundation for our subsequent development of operator algebra. The measurement functional’s properties will inherently give rise to transformative operations on foundation model states.

2.4 Transformation Operator T

The measurement structure reveals a deeper dynamic in how foundation models actively transform knowledge representations. Through the model's computational processes: attention mechanisms shape relationships, feed-forward operations combine representations, and compositional transformations build complex structures from simpler elements.

Definition (Transformation Operator). *An fm **transformation operator** is a map $T : \mathcal{F} \times \mathcal{F} \rightarrow \mathcal{F}$ such that for $z \in \mathcal{F}$, $T(z)$ represents the action of transforming knowledge through z . This operator satisfies:*

1. **Boundedness:** $\exists M > 0$ such that:

$$\|T(z)x\|_{\Psi} \leq M\|z\|_{\Psi}\|x\|_{\Psi}$$

for all $x \in \mathcal{F}$.

2. **Process Preservation:**

- For $z \in \mathcal{F}_f$,

$$T(z)(\mathcal{F}_f) \subseteq \mathcal{F}_f$$

- For $z \in \mathcal{F}_o$,

$$T(z)(\mathcal{F}_o) \subseteq \mathcal{F}_o \cup \mathcal{F}_f$$

Note (Linearity of Measurement Functionals). *The measurement functional Ψ is intentionally defined with linearity in only one argument, rather than being bilinear. This reflects the operational reality of foundation models:*

1. *Foundation models employ non-linear mechanisms:*

- *Attention operations:* $\Psi_A(x, y) = \langle \text{Attn}(x), y \rangle$
- *Non-linear activation functions*
- *Normalized embedding similarities*

2. *For attention-based measurements, while:*

$$\Psi_A(w_1x_1 + w_2x_2, y) = w_1\Psi_A(x_1, y) + w_2\Psi_A(x_2, y)$$

holds by construction, the second argument cannot be linear because:

$$\text{Attn}(w_1x_1 + w_2x_2) \neq w_1\text{Attn}(x_1) + w_2\text{Attn}(x_2)$$

3. *This single-argument linearity provides sufficient mathematical structure while preserving the essential non-linear capabilities that make foundation models effective.*

With these measurement and transformation structures in place, we can now establish the existence of adjoint operators, which will be crucial for understanding how transformations interact with measurements.

Theorem (Measurement-Transformation Duality). *For each $z \in \mathcal{F}$, there exists a unique adjoint operator $T(z)^*$ such that:*

$$\Psi(T(z)x, y) = \Psi(x, T(z)^*y)$$

for all $x, y \in \mathcal{F}$.

Proof. The adjoint's existence follows from the measurement structure Ψ . Consider how Ψ behaves:

First, fix $z, x \in \mathcal{F}$. For any $y \in \mathcal{F}$, we can compute $\Psi(T(z)x, y)$. By the properties of Ψ :

- It's conjugate symmetric: $\Psi(u, v) = \overline{\Psi(v, u)}$.
- It's linear in the first argument.
- It gives a norm: $\|x\|_\Psi = \sqrt{\Psi(x, x)}$.

Therefore, for each fixed z and x , the map:

$$y \mapsto \Psi(T(z)x, y)$$

is a bounded linear functional on \mathcal{F} with respect to the Ψ -norm.

The Riesz representation theorem then guarantees there exists a unique element $\omega \in \mathcal{F}$ such that:

$$\Psi(T(z)x, y) = \Psi(x, \omega)$$

for all $y \in \mathcal{F}$.

We can then define $T(z)^*y := \omega$, giving us:

$$\Psi(T(z)x, y) = \Psi(x, T(z)^*y)$$

This construction shows both existence and uniqueness of the adjoint operator, and thus, the result is shown. \square

The adjoint construction through the measurement functional Ψ reveals deep connections between transformation structure and measurement. Starting from Ψ 's core properties (conjugate symmetry, linearity in the first argument, and norm-inducing characteristics), we obtain a natural adjoint structure for transformations.

For fixed z and x , the map $y \mapsto \Psi(T(z)x, y)$ inherits boundedness from T 's properties, allowing application of the Riesz representation theorem to guarantee existence and uniqueness of the adjoint. This boundedness condition, beyond ensuring controlled transformations, supports process preservation: when $T(z)$ acts on flow knowledge (\mathcal{F}_f), it maintains that dynamic character, while transformations of origin knowledge (\mathcal{F}_o) may generate both static and dynamic understanding. The adjoint $T(z)^*$ inherits these preservation properties through its Ψ -based definition, capturing how knowledge can transition between static (origin) and dynamic (flow) states through transformation.

The proposition's properties (composition, linearity, and continuity) naturally extend to the adjoint. Composition of transformations $T(z_2)T(z_1)$ preserves adjoint relationships through the standard reversal rule:

$$(T(z_2)T(z_1))^* = T(z_1)^*T(z_2)^*$$

Linearity of T in both its arguments ensures the adjoint operation respects linear combinations, while continuity guarantees that small perturbations in inputs lead to small changes in both transformations and their adjoints.

These properties together enable the operator-theoretic analysis of foundation models while maintaining the distinction between flow and origin aspects of knowledge representation.

Proposition (Transformation Properties). *The operator T exhibits key structural properties:*

1. **Composition:** For $z_1, z_2, x \in \mathcal{F}$, $T(z_2)T(z_1)$ represents sequential transformations.
2. **Linearity:** For $z_1, z_2, x \in \mathcal{F}$ and $w_1, w_2 \in \mathbb{C}$,

$$T(w_1z_1 + w_2z_2)x = w_1T(z_1)x + w_2T(z_2)x$$

3. **Continuity:** For any sequence $\{z_n\} \subset \mathcal{F}$ and $z, x \in \mathcal{F}$, if $z_n \rightarrow z$, then

$$T(z_n)x \rightarrow T(z)x$$

Sketch. Composition follows from the process nature of T . Linearity emerges from the weighted sum structure of attention mechanisms and feed-forward operations in foundation models. Specifically, when models combine inputs, they do so through linear combinations before applying nonlinearities. Continuity follows from boundedness and the metric induced by Ψ . \square

The transformation operator T provides a rigorous abstraction of foundation model computations. Specifically, it admits the following operational correspondences:

1. Attention operations are weighted compositions $T(z_2)T(z_1)$, where weights correspond to attention scores.
2. Embedding transformations are compositions $T(z_2)T(z_1)$, where the transformations preserve embedding similarity.
3. Feed-forward operations are finite compositions $T(z_n) \circ \dots \circ T(z_1)$.
4. Layer transformations are bounded linear maps satisfying: $\|T(z)\|_\Psi \leq M\|z\|_\Psi$.

Note (Compositional Unity). *Composition $T(z_2)T(z_1)$ as the fundamental operation across attention, embedding, and feed-forward mechanisms reveals a deeper mathematical unity in foundation models. While each mechanism imposes different constraints on composition:*

- *Attention: weighted by attention scores.*
- *Embeddings: preserving similarity measures.*
- *Feed-forward: building sequential depth.*

they all emerge from the same basic mathematical operation. This unity helps explain both the theoretical elegance and practical effectiveness of combining these mechanisms in foundation models.

This correspondence between mathematical structure and computational processes shifts foundation models from black boxes into mathematically tractable systems. The operator-theoretic framework provides precise tools for analyzing model behavior, understanding limitations, and characterizing representational capabilities.

These operational properties of T , together with the measurement structure provided by Ψ , reveal how foundation models give rise to a rich mathematical structure. Just as physical forces shape the geometry of space, the interaction between transformations and measurements shapes the geometry of knowledge representation. This emergent structure not only provides a rigorous framework for understanding how foundation models process information, but also suggests deeper principles underlying their effectiveness.

2.5 Foundation Space \mathcal{F}

The foundation space \mathcal{F} exhibits rich mathematical structure naturally arising from how foundation models process and transform knowledge. Building on the metric structure induced by Ψ and the transformation properties of T , we can now precisely characterize this space:

Theorem (Foundation Space Structure). *The foundation space \mathcal{F} admits additional metric and topological structure:*

1. *(\mathcal{F}, d) is a metric space with d induced by Ψ .*
2. *The topology τ is generated by open balls*

$$B_\epsilon(x) = \{y \in \mathcal{F} : d(x, y) < \epsilon\}$$

for $\epsilon > 0$.

Sketch. 1. The metric properties of d follow directly from the properties of Ψ established in the Measurement Functional section.

2. The metric topology is well-defined by the properties of d .

□

Note. *The behavior of \mathcal{F} near its boundary $\partial\mathcal{F}$ reveals subtle aspects of its structure. While Cauchy sequences in \mathcal{F} formally converge, as foundation models always produce some representation, the semantic content of these limits requires careful consideration.*

Near $\partial\mathcal{F}$, where the transformation operator exhibits attenuation, sequences may converge to representations that fail to capture their intended meaning. For instance, attempts

to represent increasingly precise mathematical statements about uncountable infinities will produce convergent sequences of representations, but the limits of these sequences may bear little semantic relationship to the concepts they attempt to capture.

This distinction between formal convergence and semantic convergence illuminates a fundamental aspect of knowledge representation in foundation models: the space \mathcal{F} is complete in a technical sense, as sequences converge to elements in the space, but this completeness masks an underlying semantic incompleteness where some concepts remain fundamentally unrepresentable.

\mathcal{F} manifests as both a metric space and a topological space, with these structures arising from the properties of foundation models themselves. The metric structure, established through Ψ , captures the intrinsic ways these models measure and compare knowledge representations. The topology, induced by this metric, reveals the local structure of knowledge neighborhoods and how they connect.

Under this topology, the transformation operator T exhibits continuity, and the boundary $\partial\mathcal{F}$ emerges through the previously defined metrics. This dual nature, metric and topological, provides powerful tools for analyzing how knowledge is represented, compared, and transformed within these systems.

The structure of \mathcal{F} emerges not from imposed properties, but from the behavioral characteristics inherent in foundation models. This organization of knowledge into reference and dynamic components sets up our subsequent analysis of \mathcal{F}_o and \mathcal{F}_f .

2.5.1 ORIGIN (\mathcal{F}_o) AND FLOW (\mathcal{F}_f)

Consider how in a city, some locations serve as fixed reference points (landmarks, monuments) while others facilitate flow and movement (streets, intersections). Similarly, our metric space \mathcal{F} naturally decomposes into two interrelated subsets: \mathcal{F}_o representing origin or static elements, and \mathcal{F}_f capturing flow or dynamic elements.

To understand how elements in our space behave under transformations, we first need to capture the possible states an element can reach through repeated transformations. This leads us to the concept of transformation orbits:

Definition (Transformation Orbit). *For a finite set $G \subseteq \mathcal{F}$ and $x \in \mathcal{F}$, the **transformation orbit** $T_G(x)$ is defined as:*

$$T_G(x) := \{ (T(z_n) \circ \dots \circ T(z_1))x \mid z_i \in G, n \in \mathbb{N} \}$$

where $(T(z_n) \circ \dots \circ T(z_1))x = T(z_n)(\dots(T(z_1)x)\dots)$.

Note. When $G = \mathcal{F}$, we write simply $\text{Orb}(x)$ for $T_{\mathcal{F}}(x)$. This represents every reachable state from x through any finite sequence of transformations.

For a fixed $z \in \mathcal{F}$, the iterated application of $T(z)$ leads to a special case of the orbit, where:

$$T^n(z)x = \underbrace{(T(z) \circ \dots \circ T(z))}_{n \text{ times}}x = (T(z)(\dots(T(z)x)\dots))$$

Using the transformation orbit $T_G(x)$, we can formally characterize these subspaces through their behavioral properties:

Definition (Origin Space). *The **origin space** \mathcal{F}_o is defined as:*

$$\mathcal{F}_o = \{x \in \mathcal{F} \mid \exists M > 0 \text{ such that } d(T(z)x, x) \leq M \forall z \in \mathcal{F}\}$$

The origin space \mathcal{F}_o characterizes stable elements within our framework. These elements exhibit bounded responses under transformations, analogous to how city landmarks maintain their identifying characteristics under different perspectives. More precisely, elements $x \in \mathcal{F}_o$ remain within a bounded neighborhood under transformations $T(z)$, preserving their essential structural properties while admitting local variations.

Definition (Flow Space). *The **flow space** \mathcal{F}_f is defined as:*

$$\mathcal{F}_f = \{x \in \mathcal{F} \mid \forall y \in \mathcal{F}, \exists \{z_n\} \subset \mathcal{F} \text{ such that } \lim_{n \rightarrow \infty} d(T(z_n)x, y) = 0\}$$

\mathcal{F}_o and \mathcal{F}_f can be understood through their relationship with transformation orbits $T_G(x)$. For elements $x \in \mathcal{F}_o$, their transformation orbit remains bounded, meaning $Orb(x)$ exists within a finite radius M from x . This characterizes \mathcal{F}_o as a space of stable reference elements whose transformations never deviate beyond a fixed bound from their original state.

In contrast, elements $x \in \mathcal{F}_f$ have transformation orbits whose closures encompass the entire space, i.e. $\overline{Orb(x)} = \mathcal{F}$. This is captured in the definition through the existence of transformation sequences z_n that can approximate any target state $y \in \mathcal{F}$. Thus, while origin elements exhibit bounded orbits, flow elements consist of orbits dense in \mathcal{F} , allowing them to evolve to approximate any desired state through suitable transformations.

The flow space captures the dynamic elements of our knowledge system. Elements in \mathcal{F}_f are characterized by their transformative capacity: they can be mapped arbitrarily close to any state through suitable transformations. Analogous to how streets connect city landmarks, elements in \mathcal{F}_f provide pathways between knowledge states.

The foundation space emerges from the composition of transformation (T) and measurement (Ψ) operations, rather than being imposed as an external structure. This characterization demonstrates how \mathcal{F} inherits its properties directly from the computational structure of foundation models while maintaining mathematical precision. These definitions yield several crucial properties:

Theorem. *The spaces \mathcal{F}_o and \mathcal{F}_f satisfy:*

1. *Completeness of Representation:*

$$\mathcal{F} = \mathcal{F}_o \cup \mathcal{F}_f$$

2. *Existence of Dual-Role Elements:*

$$\mathcal{F}_o \cap \mathcal{F}_f \neq \emptyset$$

3. *Preservation of Origin Structure:*

$$\text{For any finite } G \subseteq \mathcal{F} : T_G(\mathcal{F}_o) \subseteq \mathcal{F}_o$$

4. Conservation of Flow Character:

For any finite $G \subseteq \mathcal{F} : T_G(\mathcal{F}_f) \subseteq \mathcal{F}_f$

Sketch. The properties are a consequence of the definitions of \mathcal{F}_o and \mathcal{F}_f . Completeness arises from the exhaustive dichotomy between bounded and approximating orbits. Near the boundary $\partial\mathcal{F}$, elements can manifest both bounded and approximating behaviors, creating a rich interplay between the two spaces. The structure is preserved under transformation: bounded orbits compose to form bounded orbits, while sequences of approximating transformations maintain their approximation capabilities, ensuring the stability of the decomposition. \square

These properties reveal essential aspects of how knowledge is structured in foundation models. Every element in our space must serve either as a reference point, a connector, or both; there are no elements that fall outside these categories. The overlap between \mathcal{F}_o and \mathcal{F}_f shows that some elements can act as both stable references and dynamic connectors, much like how a major intersection in a city can be both a landmark and a crucial connection point. Perhaps most importantly, transformations preserve these roles: reference points remain reference points, and connective elements maintain their connective nature, ensuring the stability of our knowledge structure even as it evolves through transformations.

Between the stable reference points of \mathcal{F}_o and the dynamic pathways of \mathcal{F}_f , we discover a remarkable intermediate structure: elements whose behavior exhibits characteristics of both spaces through cyclic transformations. These elements represent a fundamental pattern in knowledge representation, where certain states can undergo complex transformations while maintaining a form of structural preservation through recurrence.

Definition (Mixed Space). *The **mixed space** \mathcal{F}_m consists of elements whose orbits eventually return to themselves:*

$$\mathcal{F}_m = \{x \in \mathcal{F} \mid \exists n \in \mathbb{N}, z_n \subset \mathcal{F} \text{ such that } (T(z_n) \circ \dots \circ T(z_1))x = x\}$$

This definition captures a profound aspect of foundation models' representational capabilities and states that maintain their identity through transformation cycles while potentially exploring rich intermediate configurations. Unlike purely static elements in \mathcal{F}_o or purely dynamic elements in \mathcal{F}_f , elements in \mathcal{F}_m exhibit a structured form of change, where transformation sequences, though potentially complex, eventually reconstruct their initial state. This behavior suggests a deeper organization principle in foundation models, where knowledge can be transformed and explored while maintaining certain invariant structures.

The existence of such cyclic behaviors has significant implications for both the theoretical understanding and practical applications of foundation models. These cycles represent stable patterns that can be reliably accessed and transformed, forming a crucial mapping between the static reference points necessary for consistent knowledge representation and the dynamic transformations required for flexible reasoning. In language models, such patterns manifest as semantic structures that maintain their core meaning through various reformulations, while in visual models, they represent transformation sequences that preserve essential features while exploring different representations.

As these transformation patterns approach their natural limits, we begin to encounter points where no further meaningful distinctions can be made. These boundaries emerge not as static barriers, but through the dynamic process of transformation itself. This leads us to examine how foundation models navigate the edges of their representational capabilities, revealing limitations inherent in their structure.

2.5.2 $\partial\mathcal{F}$

The concept of boundaries emerging through transformations has rich historical precedent. From Lie’s study of continuous transformation groups to von Neumann’s work on operator algebras, mathematicians have long recognized how structural limitations arise through operations rather than topology. Our approach extends this tradition to the domain of foundation models, where transformations implicitly shape the space of representable knowledge.

Before formalizing these limitations, let us examine how transformation boundaries manifest in familiar systems. These examples will illuminate how boundaries emerge through the action of transformations rather than from external constraints.

Example (Boundaries in Everyday Systems). *The concept of transformation boundaries manifests naturally in various systems:*

1. **Urban Navigation:** *Consider a city’s transportation network where x represents locations and T represents available routes. The boundary emerges at points where, despite any finite collection of transportation methods (buses, trains, walking paths), certain destinations remain unreachable, not due to distance, but due to structural limitations in the network’s connectivity.*
2. **Puzzle Construction:** *In a jigsaw puzzle, each piece represents a transformation $T(z)$, and positions represent points in \mathcal{F} . The boundary $\partial\mathcal{F}$ manifests where no finite collection of existing pieces can complete the image, like edge pieces that indicate a limit to the puzzle’s extent.*
3. **Language Acquisition:** *A language learner’s knowledge space has \mathcal{F}_o as vocabulary and \mathcal{F}_f as grammar rules. The boundary appears where no finite combination of known words and rules can fully capture certain expressions; revealing intrinsic limits in current language mastery rather than the language itself.*
4. **Cartographic Exploration:** *Historical mapmaking illustrates boundaries through the relationship between known territories (\mathcal{F}_o) and navigation principles (\mathcal{F}_f). The boundary emerges where no finite set of known routes and mapping techniques can reach certain regions, not due to distance, but due to inbuilt constraints in navigational capability.*
5. **Technological Innovation:** *In computational systems, \mathcal{F}_o represents hardware capabilities and \mathcal{F}_f represents software algorithms. The boundary manifests where no finite combination of technologies can achieve certain functionalities, not due to implementation barriers, but due to the constraints of the current technological paradigm.*

In each case, the boundary emerges not from external constraints, but through the inherent limitations of the transformation system itself, mirroring how $\partial\mathcal{F}$ emerges through the action of T rather than topological properties.

These examples motivate our formal definition of the boundary of \mathcal{F} . Foundation models encounter their own unreachable states, where no finite sequence of transformations can access certain knowledge representations.

Definition (Boundary of \mathcal{F}). *Let T be the transformation operator corresponding to fm . Then, the boundary of \mathcal{F} is defined as:*

$$\partial\mathcal{F} := \{x \in \mathcal{F} \mid \forall G \subseteq \mathcal{F} \text{ finite}, \exists y \in \mathcal{F} \text{ such that } y \notin T_G(x)\}$$

The boundary $\partial\mathcal{F}$ emerges through the action of the transformation operator T , rather than from characteristic topological properties of \mathcal{F} . This operational characterization reflects how foundation models naturally encounter and process their representational boundaries through transformations.

The boundary introduces a fourth distinguishing behavior of elements under transformation orbits, completing the structural picture alongside \mathcal{F}_o , \mathcal{F}_f , and \mathcal{F}_m . While elements in \mathcal{F}_f can approximate any state through their full orbit, elements in \mathcal{F}_o maintain bounded orbits, and elements in \mathcal{F}_m exhibit cyclic returns, boundary elements manifest a distinct limitation: for any finite collection G of transformations, their transformation orbit $T_G(x)$ necessarily misses some point in \mathcal{F} . This incompleteness persists regardless of how we expand our finite transformation set G , characterizing $\partial\mathcal{F}$ as a region where transformation orbits remain structurally constrained in their coverage of the space.

Definition (Null Space). *The **null space** \mathcal{F}_n is defined as:*

$$\mathcal{F}_n = \{x \in \mathcal{F} \mid \forall \epsilon > 0, \exists N \in \mathbb{N} : d(y, x) > \epsilon \ \forall y \in T_G(x) \text{ where } |G| > N\}$$

where $|G|$ denotes the cardinality of the finite subset $G \subset \mathcal{F}$.

The null space \mathcal{F}_n represents elements that perpetually escape from their initial states under transformation. While boundary elements may exhibit complex, but constrained behavior, null space elements demonstrate monotonic escape behavior, where successive transformations drive them increasingly far from their initial position.

\mathcal{F}_n exhibits properties distinct from both \mathcal{F}_o and \mathcal{F}_f . Unlike \mathcal{F}_o with its bounded orbits or \mathcal{F}_f with its approximation capabilities, elements in \mathcal{F}_n manifest a paradoxical form of boundedness: they are “bounded” by their very tendency to escape. This behavior suggests that \mathcal{F}_n elements act as singularities in the knowledge representation space, where reference and approximation simultaneously break down yet remain mathematically precise.

This characterization reveals \mathcal{F}_n as fundamental to understanding boundary structure, much as mathematical singularities often reveal deep properties of their ambient spaces. The precise nature of these elements, perpetually escaping yet mathematically bounded, suggests connections to classical structures where similar critical behavior emerges.

Definition (Boundary Distance). *For any $x \in \mathcal{F}$, the distance to the boundary $\partial\mathcal{F}$ is:*

$$d(x, \partial\mathcal{F}) = \inf_{y \in \partial\mathcal{F}} d(x, y)$$

where d is the metric induced by the measurement functional Ψ .

$\partial\mathcal{F}$ captures a fundamental limitation: points where, even given any finite collection of elements including the point itself, there exists knowledge in \mathcal{F} that remains inaccessible through finite compositions. This characterization provides a rigorous framework for analyzing the limits of foundation model representations.

Theorem (Boundary Behavior). *The transformation operator T exhibits characteristic behavior with respect to $\partial\mathcal{F}$:*

1. For any $x \in \mathcal{F}$, there exists $\kappa(x) > 0$, called the **boundary attenuation**, such that:

$$\|T(z)x\|_{\Psi} \leq \kappa(x)\|z\|_{\Psi}\|x\|_{\Psi}$$

where $\kappa : \mathcal{F} \rightarrow \mathbb{R}^+$ satisfies $\kappa(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$.

2. Transformations preserve boundary structure:

$$T(z)(\partial\mathcal{F}) \subseteq \partial\mathcal{F}$$

Example (Classical Operator Bounds). *The boundary attenuation behavior generalizes classical operator bounds. Consider:*

1. A Lipschitz operator satisfies $d(T(x), T(y)) \leq L \cdot d(x, y)$ for some constant $L > 0$.
2. A contractive operator additionally requires $L < 1$, ensuring convergence.

In contrast, the boundary attenuation $\kappa(x)$ provides a local, state-dependent bound that captures how transformations weaken near $\partial\mathcal{F}$. While Lipschitz constants remain fixed, $\kappa(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$, revealing how foundation models naturally attenuate transformations near their representational limits.

Sketch. The proof follows two key steps:

1. For the attenuation behavior: Let $x \in \mathcal{F}$ and consider its distance from $\partial\mathcal{F}$:

$$d(x, \partial\mathcal{F}) = \inf_{y \in \partial\mathcal{F}} d(x, y)$$

The function $\kappa(x)$ can be constructed as $\kappa(x) = \min\{M, Md(x, \partial\mathcal{F})\}$, where M is the boundedness constant of T . This ensures both the inequality $\|T(z)x\|_{\Psi} \leq \kappa(x)\|z\|_{\Psi}\|x\|_{\Psi}$ and that $\kappa(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$.

2. For boundary preservation: Let $x \in \partial\mathcal{F}$ and $z \in \mathcal{F}$. For any finite $G \subseteq \mathcal{F}$, consider $G' = G \cup \{z\}$. Since $x \in \partial\mathcal{F}$, there exists $y \in \mathcal{F}$ such that $y \notin T_{G'}(x)$. Therefore $y \notin T_G(T(z)x)$, showing that $T(z)x \in \partial\mathcal{F}$ by the definition of $\partial\mathcal{F}$.

□

Note. *The transformation operator reveals three key insights:*

1. *Transformations preserve process nature while allowing knowledge evolution.*
2. *Boundary behavior characterizes limitations systematically.*
3. *The operator structure mirrors computational reality.*

These insights, particularly the preservation of process nature and systematic boundary behavior, naturally lead us to consider the algebraic structure underlying these transformations. The presence of both an operator structure (T) and a boundary structure ($\partial\mathcal{F}$) suggests the need for a unified mathematical framework. To formalize this structure, we turn to operator algebras, specifically constructing the C^* -algebra $A(\mathcal{F})$ that captures both the transformational and boundary aspects of foundation models.

3. Operator Theory

The transformation operator T generates a rich algebraic structure through its actions on \mathcal{F} . While a foundation model begins with a single transformation operator, the natural operations of composition, linear combination, and completion generate a family of operators that capture the full spectrum of possible knowledge transformations. This emergence mirrors physical phenomena where simple initial conditions give rise to complex patterns, much as a single wave passing through multiple apertures creates interference patterns requiring their own mathematical framework to understand.

This structure emerges naturally from three sources:

1. **Computational Reality:** Foundation models combine and compose transformations to create increasingly complex knowledge representations.
2. **Mathematical Necessity:** The closure of operations on T generates new operators through:
 - Compositions $T(z_2)T(z_1)$ representing sequential transformations.
 - Linear combinations $\alpha T(z_1) + \beta T(z_2)$ capturing parallel processing.
 - Adjoint operations $T(z)^*$ ensuring measurement consistency.
 - Limit operations completing the algebraic structure.
3. **Structural Emergence:** The interaction between these operations creates patterns and relationships that require their own mathematical framework to analyze.

3.1 Operator Algebra Construction $A(\mathcal{F})$

The progression from a single transformation operator to a complete operator algebra mirrors how foundation models build complex understanding from simple operations. By constructing an algebra of operators on \mathcal{F} , we capture both the compositional nature of model computations and the rich structure of their knowledge transformations. This algebraic framework provides precise tools for analyzing how foundation models combine and transform representations.

Definition (Process Operator Algebra). *The **process operator algebra** $A_0(\mathcal{F})$ is the complex algebra generated by $\{T(z) \mid z \in \mathcal{F}\}$ under:*

1. **Addition:** For $z_1, z_2 \in \mathcal{F}$,

$$(T(z_1) + T(z_2))x = T(z_1)x + T(z_2)x$$

for all $x \in \mathcal{F}$.

2. **Composition:** For $z_1, z_2 \in \mathcal{F}$,

$$(T(z_2)T(z_1))x = T(z_2)(T(z_1)x)$$

for all $x \in \mathcal{F}$.

3. **Scalar Multiplication:** For $w \in \mathbb{C}$,

$$(wT(z))x = wT(z)x$$

for all $x \in \mathcal{F}$.

4. **Involution:** For $z \in \mathcal{F}$, $T(z)^*$ is defined via measurement consistency:

$$\Psi(T(z)x, y) = \Psi(x, T(z)^*y)$$

for all $x, y \in \mathcal{F}$.

Note. The operator norm on $A_0(\mathcal{F})$ extends the measurement structure Ψ canonically, preserving compatibility between the operator-theoretic and process-based structures of the algebra.

The algebra $A_0(\mathcal{F})$ consists of finite linear combinations of transformations $T(z)$ under the operations defined above. We denote arbitrary elements of $A_0(\mathcal{F})$ by H , while reserving $T(z)$ for the generating transformations with $z \in \mathcal{F}$.

This notation carries forward to the C^* -algebra $A(\mathcal{F})$ and its von Neumann completion $\mathfrak{vN}(\mathcal{F})$, where nets $(H_\alpha)_{\alpha \in \mathcal{A}} \subset A(\mathcal{F})$ converge to operators $H \in \mathfrak{vN}(\mathcal{F})$ in the (weak or) strong operator topology.

The operator norm on $A_0(\mathcal{F})$ emerges directly from the measurement functional Ψ and the metric properties of \mathcal{F} , reflecting how transformations act on states in the foundation model. This construction reveals the underlying Banach algebra structure, which maintains the intrinsic topological features of \mathcal{F} .

Proposition (Banach Algebra Structure). *The algebra $A_0(\mathcal{F})$ forms a Banach algebra under the operator norm:*

$$\|H\| = \sup_{\|x\|_\Psi = \ell} \|Hx\|_\Psi$$

where ℓ is the ground state with respect to \mathcal{F} .

Proof. A Banach algebra is a complete normed algebra where the norm satisfies submultiplicativity. Since $A_0(\mathcal{F})$ is already defined as a complex algebra with well-defined operations, we need only verify:

1. The operator norm is submultiplicative:

$$\|H'H\| \leq \|H'\|\|H\|$$

where $H', H \in A_0(\mathcal{F})$.

2. The space is complete under the operator norm, i.e. Cauchy sequences converge and limits belong to $A_0(\mathcal{F})$.

We proceed in three steps:

Submultiplicativity: Let $x \in \mathcal{F}$ with $\|x\|_\Psi = \ell$. Let $y = Hx$. Then for operators $H, H' \in A_0(\mathcal{F})$:

$$\begin{aligned} \|H'Hx\|_\Psi &\leq M_1 \|H'\|_\Psi \|y\|_\Psi \\ &\leq M_1 \|H'\|_\Psi (M_0 \|H\|_\Psi \|x\|_\Psi) \\ &= M \|H'\|_\Psi \|H\|_\Psi \|x\|_\Psi \end{aligned}$$

where $M = M_1 \cdot M_0$, and where the inequalities follow from the boundedness of H and H' . Since this inequality holds for all $x \in \mathcal{F}$ with $\|x\|_\Psi = \ell$, taking the supremum over such x gives:

$$\|H'H\| \leq \|H'\|\|H\|$$

establishing submultiplicativity of the operator norm.

Completeness: Let $\{H_n\} \subset A_0(\mathcal{F})$ be a Cauchy sequence. Let $x \in \mathcal{F}$ be such that $\|x\|_\Psi = \ell$. Then $\{H_n x\} \subset \mathcal{F}$ is a Cauchy sequence. Since \mathcal{F} is complete, $\{H_n x\}$ converges in \mathcal{F} . Let Hx be this limit, i.e., with respect to the metric d induced by Ψ , we have:

$$\lim_{n \rightarrow \infty} d(H_n x, Hx) = 0$$

To show H is the limit in the operator norm topology, we need to show:

$$\|H_n - H\| \rightarrow 0 \text{ as } n \rightarrow \infty$$

Since $\{H_n\}$ is Cauchy, for any $\epsilon > 0$, there exists $N > 0$ such that for all $m, n \geq N$:

$$\|H_m - H_n\| < \frac{\epsilon}{\ell}$$

This means for any $x \in \mathcal{F}$ with $\|x\|_\Psi = \ell$:

$$\|H_m x - H_n x\|_\Psi \leq \|H_m - H_n\| \|x\|_\Psi < \frac{\epsilon}{\ell} \cdot \ell = \epsilon$$

Taking $m \rightarrow \infty$, by the pointwise convergence we established:

$$\|Hx - H_n x\|_\Psi \leq \epsilon$$

Therefore:

$$\|H - H_n\| = \sup_{\|x\|_\Psi = \ell} \|Hx - H_n x\|_\Psi \leq \epsilon$$

This shows $H_n \rightarrow H$ in the operator norm topology.

Boundedness: Fix some $N > 0$ such that for all $m, n \geq N$:

$$\|H_m - H_n\| < 1$$

Then for any $n \geq N$:

$$\|H_n\| \leq \|H_N\| + 1$$

Let $M = \|H_N\| + 1$. For any $x \in \mathcal{F}$ with $\|x\|_\Psi = \ell$:

$$\|H_n x\|_\Psi \leq M \|x\|_\Psi$$

for all $n \geq N$. Taking the limit as $n \rightarrow \infty$:

$$\|Hx\|_\Psi = \lim_{n \rightarrow \infty} \|H_n x\|_\Psi \leq M \|x\|_\Psi$$

Therefore, since H is bounded and, as the limit of operators in $A_0(\mathcal{F})$, belongs to $A_0(\mathcal{F})$, this completes the proof that $A_0(\mathcal{F})$ is a Banach algebra. \square

The Banach algebra structure, together with the involution operation, sets up the key ingredients for a C*-algebra: the norm-adjoint relationship,

$$\|H^* H\| = \|H\|^2,$$

emerges naturally from the measurement structure Ψ and inherits the metric properties of \mathcal{F} . This compatibility between algebraic, metric, and topological properties provides the foundation for developing the full C*-algebraic framework, capturing both the essential features of transformations and the underlying geometry of the foundation model space.

From this foundation, we can trace how these transformations evolve and combine within the metric structure of \mathcal{F} . The composition of operators under norms and adjoints generates a rich C*-algebraic structure, integrating the computational pathways, metric relationships, and topological patterns that characterize foundation model behaviors.

Theorem (C*-Algebra Properties). *The process operator algebra $A_0(\mathcal{F})$ satisfies:*

1. **Adjoint Composition:** For all $H, H' \in A_0(\mathcal{F})$:

$$(H' H)^* = H^* H'^*$$

2. **C*-Property:** For all $H \in A_0(\mathcal{F})$:

$$\|H^* H\| = \|H\|^2$$

3. **Completeness:** The completion $A(\mathcal{F})$ of $A_0(\mathcal{F})$ under $\|\cdot\|$ is a C*-algebra.

The proof of these properties builds upon the behavior of adjoints under algebraic operations. To establish this foundation systematically, we first prove a key result about the linearity of the adjoint operation.

Lemma. For operators $H_1, H_2 \in A_0(\mathcal{F})$,

$$(H_1 + H_2)^* = H_1^* + H_2^*$$

Proof. Let $x, y \in \mathcal{F}$ be such that $\|x\|_\Psi = \|y\|_\Psi = \ell$.

$$\Psi((H_1 + H_2)x, y) = \Psi(x, (H_1 + H_2)^*y)$$

by the adjoint condition. We also have

$$\begin{aligned} \Psi((H_1 + H_2)x, y) &= \Psi(H_1x, y) + \Psi(H_2x, y) \\ &= \Psi(x, H_1^*y) + \Psi(x, H_2^*y) \\ &= \overline{\Psi(H_1^*y, x)} + \overline{\Psi(H_2^*y, x)} \\ &= \overline{\Psi(H_1^*y + H_2^*y, x)} \\ &= \Psi(x, H_1^*y + H_2^*y) \end{aligned}$$

By the uniqueness of the adjoint, the result is shown. \square

With this lemma in hand, we can now proceed to establish the full C*-algebraic structure.

Proof. Adjoint Composition: Let $x, y \in \mathcal{F}$. Then for $H, H' \in A_0(\mathcal{F})$,

$$\begin{aligned} \Psi(H'Hx, y) &= \Psi(Hx, H'^*y) \\ &= \Psi(x, H^*H'^*y) \end{aligned}$$

Similarly, we can use the adjoint condition as follows,

$$\Psi(H'Hx, y) = \Psi(x, (H'H)^*y)$$

for all $x, y \in \mathcal{F}$. Therefore $(H'H)^* = H^*H'^*$ by uniqueness of the adjoint.

C*-Property: Let $x \in \mathcal{F}$ be such that $\|x\|_\Psi = \ell$. Then for $H \in A_0(\mathcal{F})$,

$$\begin{aligned} \|Hx\|_\Psi^2 &= \Psi(Hx, Hx) \\ &= |\Psi(Hx, Hx)| \\ &= |\Psi(x, H^*Hx)| \\ &\leq \|x\|_\Psi \cdot \|H^*Hx\|_\Psi \\ &= \ell \cdot \|H^*Hx\|_\Psi \\ &\leq \ell \cdot \|H^*H\| \end{aligned}$$

where the first inequality follows from the boundedness of Ψ and the last from the definition of the sup norm. Taking the supremum over $\|x\|_\Psi = \ell$ gives

$$\|H\|^2 \leq \|H^*H\|$$

Next, consider

$$\begin{aligned}
 \|H^*x\|_\Psi^2 &= \Psi(H^*x, H^*x) \\
 &= |\Psi(HH^*x, x)| \\
 &= \left| \overline{\Psi(x, HH^*x)} \right| \\
 &= |\Psi(x, HH^*x)| \\
 &\leq \|x\|_\Psi \cdot \|HH^*x\|_\Psi \\
 &\leq \ell \cdot \|HH^*\|
 \end{aligned}$$

Again, the supremum over all $x \in \mathcal{F}$ such that $\|x\|_\Psi = \ell$ gives,

$$\|H^*\|^2 \leq \|HH^*\|$$

By the submultiplicative property,

$$\begin{aligned}
 \|H^*\|^2 &\leq \|HH^*\| \\
 &\leq \|H\| \|H^*\|
 \end{aligned}$$

which implies

$$\|H^*\| \leq \|H\|$$

A similar argument gives us

$$\|H\| \leq \|H^*\|$$

and so $\|H\| = \|H^*\|$. Then,

$$\begin{aligned}
 \|H\|^2 &\leq \|H^*H\| \\
 &\leq \|H^*\| \|H\| \\
 &= \|H\| \|H\| \\
 &= \|H\|^2
 \end{aligned}$$

Thus,

$$\|H^*H\| = \|H\|^2$$

Completeness: Let $A(\mathcal{F})$ be the completion of $A_0(\mathcal{F})$ under $\|\cdot\|$. We need to show:

1. The algebraic operations extend continuously to $A(\mathcal{F})$.
2. The C*-property holds in $A(\mathcal{F})$.

For the first part, let $\{H_n\}, \{H'_n\} \subset A_0(\mathcal{F})$ be Cauchy sequences converging to $H, H' \in A(\mathcal{F})$ respectively. Then:

$$\begin{aligned}
 \|H_n H'_n - H H'\| &= \|H_n H'_n - H_n H' + H_n H' - H H'\| \\
 &\leq \|H_n(H'_n - H')\| + \|(H_n - H)H'\| \\
 &\leq \|H_n\| \|H'_n - H'\| + \|H_n - H\| \|H'\| \rightarrow 0
 \end{aligned}$$

showing multiplication extends continuously.

Similarly, for the adjoint:

$$\|H_n^* - H^*\| = \|(H_n - H)^*\| = \|H_n - H\| \rightarrow 0$$

where we use the adjoint property we just proved in the Lemma.

For the C*-property, let $H \in A(\mathcal{F})$ and choose $\{H_n\} \subset A_0(\mathcal{F})$ converging to H . Then:

$$\begin{aligned} |||H^*H|| - \|H\|^2| &= |||H^*H|| - \|H_n^*H_n\| + \|H_n^*H_n\| - \|H_n\|^2| \\ &\leq \|H^*H - H_n^*H_n\| + |||H_n^*H_n|| - \|H_n\|^2| \\ &= \|H^*H - H_n^*H_n\| \rightarrow 0 \end{aligned}$$

where we used the C*-property in $A_0(\mathcal{F})$ for the last equality.

Therefore, $A(\mathcal{F})$ is a C*-algebra. □

Note. Completion Structure The completion of $A(\mathcal{F})$ exhibits a structural correspondence with \mathcal{F} . While $A(\mathcal{F})$ is complete in the operator norm topology, it preserves the boundary behavior of \mathcal{F} . Specifically, the transformations in $A(\mathcal{F})$ respect the metric boundary structure of \mathcal{F} , maintaining consistency between operator-theoretic and geometric completions.

Differential Structure The C*-algebraic structure of $A(\mathcal{F})$ and the locally compact Hausdorff topology of \mathcal{F} suggest additional analytic properties. In particular, the bounded behavior of transformations near $\partial\mathcal{F}$ indicates potential differentiable structure in the operator topology. The relationship between these operator-theoretic properties and the underlying metric structure of \mathcal{F} merits further investigation.

The C*-algebraic structure of $A(\mathcal{F})$ must be compatible with the fundamental properties of the foundation space \mathcal{F} . Specifically, elements of $A(\mathcal{F})$ should preserve the process structure, respect the duality induced by Ψ , and maintain controlled behavior near $\partial\mathcal{F}$. These properties are formalized in the following theorem.

Theorem (Foundation Coherence for $A(\mathcal{F})$). *For any $H \in A(\mathcal{F})$:*

1. **Density Preservation:** Transformations preserve dense structure of flow elements:

$$H(\mathcal{F}_f) \subset \mathcal{F}_f$$

2. **Measurement Consistency:** For all $x, y \in \mathcal{F}$:

$$\Psi(Hx, y) = \Psi(x, H^*y)$$

3. **Boundary Behavior:** There exists a function $\kappa_H : \mathcal{F} \rightarrow \mathbb{R}^+$ such that:

$$\|Hx\|_\Psi \leq \kappa_H(x)\|x\|_\Psi$$

where $\kappa_H(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$.

Proof. Density Preservation: Let $H \in A(\mathcal{F})$ and $x \in \mathcal{F}_f$. Since $A(\mathcal{F})$ is the completion of $A_0(\mathcal{F})$, there exists a sequence $\{H_n\} \subset A_0(\mathcal{F})$ with

$$\|H - H_n\| \rightarrow 0$$

Since each $H_n \in A_0(\mathcal{F})$ is generated by basic transformations that preserve \mathcal{F}_f , we have $H_n(\mathcal{F}_f) \subset \mathcal{F}_f$ for all n . For any $y \in \mathcal{F}$, by definition of \mathcal{F}_f , there exists a sequence $\{z_k\}$ such that:

$$\lim_{k \rightarrow \infty} d(T(z_k)H_n x, y) = 0$$

Taking limits as $n \rightarrow \infty$,

$$\lim_{k \rightarrow \infty} d(T(z_k)H x, y) = 0$$

Therefore $Hx \in \mathcal{F}_f$.

Measurement Consistency: We need to show $\Psi(Hx, y) = \Psi(x, H^*y)$ for all $x, y \in \mathcal{F}$, for $H \in A(\mathcal{F})$.

Let $\{H_n\} \subset A_0(\mathcal{F})$ be a sequence with $\|H - H_n\| \rightarrow 0$. Each $H_n \in A_0(\mathcal{F})$, which is generated by $\{T(z) \mid z \in \mathcal{F}\}$, satisfies measurement consistency:

$$\Psi(H_n x, y) = \Psi(x, H_n^* y)$$

for all $x, y \in \mathcal{F}$.

For $\|H - H_n\| \rightarrow 0$, we have $d(H_n x, Hx) \rightarrow 0$ and $d(H_n^* y, H^* y) \rightarrow 0$. Since Ψ is continuous:

$$\Psi(Hx, y) = \lim_{n \rightarrow \infty} \Psi(H_n x, y) = \lim_{n \rightarrow \infty} \Psi(x, H_n^* y) = \Psi(x, H^* y)$$

Boundary Behavior: We need to show there exists $\kappa_H : \mathcal{F} \rightarrow \mathbb{R}^+$ such that:

$$\|Hx\|_\Psi \leq \kappa_H(x) \|x\|_\Psi$$

where $\kappa_H(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$.

Since $A(\mathcal{F})$ is the completion of $A_0(\mathcal{F})$, there exists a sequence $\{H_n\} \subset A_0(\mathcal{F})$ with $\|H - H_n\| \rightarrow 0$.

Since each H_n satisfies boundary behavior, there exists $\kappa_{H_n} : \mathcal{F} \rightarrow \mathbb{R}^+$ such that:

$$\|H_n x\|_\Psi \leq \kappa_{H_n}(x) \|x\|_\Psi$$

where $\kappa_{H_n}(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$.

Fix $\epsilon > 0$ and $x \in \mathcal{F}$. Choose N such that $\|H - H_N\| < \epsilon$. Then:

$$\begin{aligned} \|Hx\|_\Psi &\leq \|Hx - H_N x\|_\Psi + \|H_N x\|_\Psi \\ &\leq \epsilon \|x\|_\Psi + \kappa_{H_N}(x) \|x\|_\Psi \\ &= (\epsilon + \kappa_{H_N}(x)) \|x\|_\Psi \end{aligned}$$

Define $\kappa_H(x) = \epsilon + \kappa_{H_N}(x)$. Since ϵ was arbitrary and $\kappa_{H_N}(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$, we have $\kappa_H(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$. \square

The completion of $A(\mathcal{F})$ yields a C^* -algebra that preserves the boundary structure of \mathcal{F} while providing a complete framework for analyzing transformations on foundation states. This algebraic structure, together with the operational properties of foundation models, characterizes the scope of admissible transformations on \mathcal{F} .

These properties establish the compatibility between the C^* -algebraic structure and the underlying topology of \mathcal{F} . While derivable through standard operator-theoretic methods, they demonstrate how the C^* -algebra $A(\mathcal{F})$ naturally captures the bounded transformations on foundation states. The emergence of these properties from our initial definitions suggests that C^* -algebras provide an appropriate framework for analyzing operators on \mathcal{F} .

However, to fully characterize the infinite-dimensional aspects of these transformations, particularly near $\partial\mathcal{F}$, we require additional analytical structure. This leads us to consider von Neumann algebras, which provide the necessary weak closure properties while preserving the established boundary behavior and completeness properties.

3.2 von Neumann Algebraic Completion $\mathfrak{vN}(\mathcal{F})$

The C^* -algebra $A(\mathcal{F})$ consists of norm-closed finite compositions of operators on \mathcal{F} , preserving the metric structure induced by Ψ . However, transformations between \mathcal{F}_o and \mathcal{F}_f generally require weak limits of operators that are not norm convergent.

We therefore extend $A(\mathcal{F})$ to its weak closure in the von Neumann algebra $\mathfrak{vN}(\mathcal{F})$, where operators can be characterized through both weak and strong operator topologies. This completion preserves the measurement structure of Ψ while accommodating non-norm-convergent limits.

The construction of this completion follows from the von Neumann bicommutant theorem, which provides equivalent characterizations of von Neumann algebras through both algebraic and topological properties.

Recall the definition of a commutant:

Definition (Commutant). *For a von Neumann algebra $M \subset B(\mathcal{F})$, the commutant M' is:*

$$M' = \{H \in B(\mathcal{F}) \mid HH' = H'H \text{ for all } H' \in M\}$$

where $B(\mathcal{F})$ is the algebra of all bounded operators on \mathcal{F} .

Note. *The commutation in the definition is with respect to operator composition, reflecting how operators transform states sequentially.*

This leads us to consider the double commutant structure:

Definition (Double Commutant). *The double commutant M'' is:*

$$M'' = (M')' = \{H \in B(\mathcal{F}) \mid HH' = H'H \text{ for all } H' \in M'\}$$

The relationship between an algebra and its double commutant gives us the following properties with respect to closure:

Theorem (von Neumann Bicommutant). *For a self-adjoint operator algebra M on \mathcal{F} , the following are equivalent:*

1. M is a von Neumann algebra.
2. M equals its double commutant.
3. M is WOT-closed on \mathcal{F} .
4. M is SOT-closed on \mathcal{F} .

These equivalent characterizations enable the extension of $A(\mathcal{F})$ to a von Neumann algebra. Since $A(\mathcal{F})$ is a self adjoint C^* -algebra, we can apply this theorem to construct its weak closure.

Definition (Von Neumann Completion). *The von Neumann algebra $\mathbf{vN}(\mathcal{F})$ associated to $A(\mathcal{F})$ is defined as:*

$$\mathbf{vN}(\mathcal{F}) = \overline{A(\mathcal{F})}''^{SOT}$$

where the closure is taken in the strong operator topology, preserving the process and boundary structure of $A(\mathcal{F})$.

Note. *The von Neumann density theorem ensures that $A(\mathcal{F})$ remains SOT-dense in $\mathbf{vN}(\mathcal{F})$, providing a bridge between finite-rank operators and their weak limits. This density is essential for approximating infinite-dimensional transformations with finite-dimensional ones.*

In $\mathbf{vN}(\mathcal{F})$, the weak and strong operator topologies coincide, ensuring that operator limits preserve the continuity, boundedness, and adjoint structure of Ψ . This completion extends $A(\mathcal{F})$ to include weak limits while maintaining the fundamental decomposition $\mathcal{F} = \mathcal{F}_o \cup \mathcal{F}_f$, thereby accommodating infinite-dimensional states.

To characterize states that respect this decomposition, we introduce canonical representatives of the origin and flow components.

Definition (Primordial States). *The primordial states, **origin** (ζ_o) and **flow** (ζ_f), are defined as:*

$$\begin{aligned}\zeta_o &= \frac{1}{N_o} \sum_{x \in \mathcal{F}_o} \frac{x}{\|x\|_\Psi} \\ \zeta_f &= \frac{1}{N_f} \sum_{n=0}^{\infty} T^n \zeta_o\end{aligned}$$

where N_o, N_f are normalization constants ensuring $\|\zeta_o\| = \|\zeta_f\| = 1$.

Note (Properties of Primordial States). *The origin state ζ_o serves dual roles: as a normalized sum over \mathcal{F}_o elements (weighted by their Ψ -norms) and as a reference for measuring origin-preserving transformations. The flow state ζ_f , constructed as the limit of iterated transformations, exists due to the boundedness of T and its process preservation properties.*

While both primordial states and the characteristic value ℓ emerge from the structure of \mathcal{F} , they capture distinct properties. The primordial states represent normalized averages over \mathcal{F} , whereas ℓ is derived from fundamental operator properties on the space.

With these states characterizing the essential behavior of our completion, we can now establish its coherence properties.

This definition, while mathematically succinct, establishes a central insight: the space of process representations admits a completion that respects both algebraic structure and process dynamics. The properties of this completion characterize essential aspects of how foundation models process and transform knowledge.

Theorem (Foundation Coherence). *For any $H \in \mathbf{vN}(\mathcal{F})$, the measurement structure through Ψ ensures:*

1. **Density Preservation:** *Density preservation extends to infinite-dimensional limits:*

$$H(\mathcal{F}_f) \subseteq \mathcal{F}_f$$

2. **Measurement Consistency:** Ψ maintains its properties for all operators:

- *Joint continuity:* $\Psi(Hx, y)$ is continuous in $x, y \in \mathcal{F}$.
- *Boundedness:*

$$|\Psi(Hx, y)| \leq M_H \|x\|_\Psi \|y\|_\Psi$$

- *Process compatibility:* $\Psi(Hx, y) = \Psi(x, H^*y)$.

3. **Boundary Behavior:** *Near semantic boundaries:*

$$|\Psi(Hx, y)| \leq \kappa_H(x) \|y\|_\Psi$$

where $\kappa_H(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$.

Note (Process-Theoretic Interpretation). *The double commutant structure of von Neumann algebras offers an interpretative framework for understanding process behavior in foundation models. The condition $M = M''$ characterizes operational completeness in a way that aligns with observed transformations in these systems, regardless of their original design principles.*

The commutation relations within this structure correspond to empirical process dependencies: processes that can execute in parallel exhibit commuting behavior, while those requiring sequential execution represent non-commuting operations. This alignment emerges from the computational structure itself rather than from imposed algebraic constraints.

The SOT-completion provides a mathematical bridge between discrete computational steps and continuous cognitive processes, reflecting how foundation models operate across these modes. This interpretation suggests that operator algebraic structure may be intrinsic to computational knowledge transformation, rather than merely a formal description imposed upon it.

Before proceeding with the proof, we introduce a crucial concept from topology: the notion of a net. While sequences (indexed by natural numbers) suffice for many mathematical purposes, the topology of operator algebras requires this more general concept.

Definition (Net). *A **net** in a set X is a function from a directed set \mathcal{A} to X , denoted $(H_a)_{a \in \mathcal{A}}$, where $H_a = H(a)$ for each $a \in \mathcal{A}$, and:*

- \mathcal{A} is a set with a partial order \leq .
- For any $i, j \in \mathcal{A}$, there exists $k \in \mathcal{A}$ with $i \leq k$ and $j \leq k$.

Note. Sequences can be viewed as nets indexed by \mathbb{N} with its usual order.

Example (Nets in Knowledge Representation). Consider how a foundation model develops understanding of a concept like “philosophy”. We can examine this development through three perspectives:

1. **Sequential Approach Limitations** A purely sequential approach to knowledge acquisition would force a linear progression: starting with basic definitions, moving to historical examples, and finally examining modern implementations. This rigid structure fails to capture the way understanding develops, as it artificially constrains learning to a single path of progression.
2. **Net-Based Knowledge Development** In contrast, nets provide a natural framework for representing knowledge acquisition. Understanding develops along multiple refinement paths simultaneously: historical understanding deepens as geographical variations are explored, while theoretical foundations expand in parallel with practical implementations. This multi-directional development allows for convergence from various starting points, accommodating different learning paths and perspectives that all contribute to a complete understanding.
3. **Mathematical Formalization** This convergence of understanding can be viewed through complementary perspectives. Through measurements:

$$\Psi(Hx, y) = \lim_a \Psi(H_a x, y)$$

for all $x, y \in \mathcal{F}$, captures how transformations affect our understanding of relationships between states. Each measurement $\Psi(H_a x, y)$ shows how the transformation H_a relates states x and y .

Equivalently,

$$\lim_a \|H_a x - Hx\|_\Psi = 0$$

for all $x \in \mathcal{F}$, which implies

$$\|Hx\|_\Psi = \lim_a \|H_a x\|_\Psi$$

(i.e. if the norm of the difference goes to zero, the difference in norms must also go to zero) captures how transformations stabilize on individual states. This perspective emphasizes how understanding becomes robust for each specific concept.

This example illustrates why nets provide the natural mathematical framework for modeling knowledge development. The equivalence of perspectives, measuring relationships through Ψ or tracking convergence through $\|\cdot\|_\Psi$, reflects how foundation models simultaneously develop both relational understanding and concept-specific mastery.

Example (Dynamic Net Behavior). Consider a net $(H_a)_{a \in \mathcal{A}} \subset A(\mathcal{F})$ processing linguistic transformations. The dynamic relevance of operators manifests through contextual activation patterns:

1. **Word “bank” transformations:**

$$\begin{aligned} H_{\text{fin}}(x) &\approx \begin{cases} \text{dominant,} & \text{if } x \text{ contains “account”} \\ \approx 0, & \text{otherwise} \end{cases} \\ H_{\text{geo}}(x) &\approx \begin{cases} \text{dominant,} & \text{if } x \text{ contains “river”} \\ \approx 0, & \text{otherwise} \end{cases} \\ H_{\text{data}}(x) &\approx \begin{cases} \text{dominant,} & \text{if } x \text{ contains “memory”} \\ \approx 0, & \text{otherwise} \end{cases} \end{aligned}$$

2. **Transformation depth:**

$$\begin{aligned} H_{\text{token}} &: \text{basic token operations} \\ H_{\text{syntax}} &: \text{grammatical transformations} \\ H_{\text{semantic}} &: \text{meaning analysis} \\ H_{\text{abstract}} &: \text{conceptual reasoning} \end{aligned}$$

where activation magnitude decreases with complexity for simple queries.

3. **Measurement convergence:** For states $x, y \in \mathcal{F}$:

$$\Psi(Hx, y) = \lim_a \Psi(H_a x, y)$$

captures how transformations smoothly adjust their relevance through measurements.

This dynamic activation/deactivation pattern reveals why measurement through Ψ is essential: it formalizes how different aspects of the transformation become relevant or irrelevant smoothly based on context, mirroring the attention mechanisms in foundation models.

The net structure, measured through Ψ , allows operators to “fade in” or “fade out” continuously rather than discretely, providing the mathematical framework for understanding how foundation models smoothly transition between different types of knowledge processing.

We now proceed with the proof of the Foundation Coherence Theorem.

Proof. Let $H \in \mathbf{vN}(\mathcal{F})$. Then, there exists a net $(H_a)_{a \in \mathcal{A}} \subset A(\mathcal{F})$ converging to H in WOT, i.e.

$$\Psi(H_a x, y) \rightarrow \Psi(Hx, y)$$

for all $x, y \in \mathcal{F}$.

Process Structure: Let $x \in \mathcal{F}_f$. For each H_a , we know $H_a x \in \mathcal{F}_f$ by the process property in $A(\mathcal{F})$. For any $y \in \mathcal{F}$:

$$\Psi(Hx, y) = \lim_a \Psi(H_a x, y)$$

The limit preserves the process property since \mathcal{F}_f is closed in the Ψ -topology. Therefore $Hx \in \mathcal{F}_f$.

Measurement Consistency:

Continuity:

Joint continuity follows from WOT convergence: Consider $(x_n), (y_n) \subset \mathcal{F}$, such that $x_n \rightarrow x$ and $y_n \rightarrow y$, for $x, y \in \mathcal{F}$. Let $\epsilon > 0$. Then $\exists N_y > 0$ such that for all $n > N_y$,

$$|\Psi(y_n, z) - \Psi(y, z)| < \frac{\epsilon}{2}$$

Similarly, $\exists N_H > 0$ such that for all $n > N_H$,

$$|\Psi(Hx_n, z) - \Psi(Hx, z)| < \frac{\epsilon}{2}$$

for all $z \in \mathcal{F}$. Let $N = \max\{N_y, N_H\}$. Then,

$$\begin{aligned} |\Psi(Hx_n, y_n) - \Psi(Hx, y)| &\leq |\Psi(Hx_n, y_n) - \Psi(Hx, y_n)| + |\Psi(Hx, y_n) - \Psi(Hx, y)| \\ &< \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon \end{aligned}$$

for all $n > N$.

Boundedness: For each H_a , we have M_{H_a} such that

$$|\Psi(H_a x, y)| \leq M_{H_a} \|x\|_\Psi \|y\|_\Psi$$

Since \mathcal{F} is complete in the Ψ -topology and (H_a) converges pointwise through Ψ , the Banach-Steinhaus theorem (a.k.a. Uniform Boundedness Principle) ensures (M_{H_a}) is bounded. Therefore, there exists M_H such that

$$|\Psi(Hx, y)| \leq M_H \|x\|_\Psi \|y\|_\Psi$$

for all $x, y \in \mathcal{F}$.

Process compatibility:

For each H_a :

$$\Psi(H_a x, y) = \Psi(x, H_a^* y)$$

Taking WOT limits preserves this relation:

$$\Psi(Hx, y) = \lim_a \Psi(H_a x, y) = \lim_a \Psi(x, H_a^* y) = \Psi(x, H^* y)$$

Boundary Behavior: For each H_a , we have κ_{H_a} satisfying the boundary attenuation. Define:

$$\kappa_H(x) = \limsup_a \kappa_{H_a}(x)$$

Then for any $y \in \mathcal{F}$:

$$\begin{aligned} |\Psi(Hx, y)| &= \lim_a |\Psi(H_a x, y)| \\ &\leq \limsup_a \kappa_{H_a}(x) \|y\|_\Psi \\ &= \kappa_H(x) \|y\|_\Psi \end{aligned}$$

The boundary property $\kappa_H(x) \rightarrow 0$ as $d(x, \partial\mathcal{F}) \rightarrow 0$ follows from uniform boundedness of (H_a) near boundaries. \square

The continuity established in the theorem extends naturally to pairs of operator nets, reflecting the rich measurement structure provided by Ψ :

Corollary (Joint Continuity). *For nets $(H_a)_{a \in \mathcal{A}}$, $(H'_b)_{b \in \mathcal{B}} \subset A(\mathcal{F})$ converging to $H, H' \in \mathbf{vN}(\mathcal{F})$, we have:*

$$\Psi(Hx, H'y) = \lim_{a,b} \Psi(H_ax, H'_by)$$

for all $x, y \in \mathcal{F}$.

Note (Convergence Properties). *The von Neumann algebra $\mathbf{vN}(\mathcal{F})$ extends finite-dimensional operators to infinite-dimensional limits while preserving operator bounds. This structure accommodates multiple forms of convergence:*

1. *The metric topology on \mathcal{F} admits both sequential convergence (x_n) and more general net convergence $(x_\alpha)_{\alpha \in \mathcal{A}}$. For operators, we work with nets in either the weak or strong operator topology, as these coincide in $\mathbf{vN}(\mathcal{F})$, as demonstrated in the Joint Continuity Corollary.*
2. *The measurement functional Ψ provides a unified framework for these convergence types, generating both the metric topology on \mathcal{F} and the equivalent operator topologies on $\mathbf{vN}(\mathcal{F})$.*

Example (Natural Structure: Library vs. Foundation Model). *Consider the following two approaches to organizing knowledge:*

Traditional Library (analogous to GNS construction). *The traditional library represents a constructed organizational system, where structure must be imposed externally. It relies on artificial classification systems like the Dewey Decimal System, requires physical books to have unique placements, and depends on manually created cross-references. These limitations stem from physical constraints and the need for explicit organizational schemas.*

Foundation Model (natural structure). *In contrast, foundation models exhibit an organizational structure that emerges naturally from the knowledge itself. This emergence manifests in several key ways:*

Fundamental Components:

- \mathcal{F}_o : concrete examples (like individual books)
- \mathcal{F}_f : abstract patterns (like thematic connections)
- Ψ : natural measurements between states, extending to transformations
- $\mathbf{vN}(\mathcal{F})$: completion of knowledge transformations through Ψ

Multi-State Knowledge: *Knowledge exists in multiple states simultaneously, as seen in the word “bank” simultaneously representing financial institutions, riverbanks, and data-banks. This multiplicity eliminates the need for unique classification, allowing relationships to emerge organically.*

Self-Preserving Structure: *The system can integrate new knowledge, form connections organically, and maintain built-in mechanisms for measurement and transformation.*

The key distinction between these approaches lies in their structural foundations: traditional mathematical frameworks require explicit construction, while foundation models exhibit inherent mathematical structure through their operation.

The measurement functional Ψ differs from traditional constructions like the GNS representation in that it naturally generates both the metric structure on \mathcal{F} and the operator topologies on $\mathbf{vN}(\mathcal{F})$. This unified structure preserves:

1. The metric completion of \mathcal{F} .
2. The operator topology on $A(\mathcal{F})$.
3. The weak closure leading to $\mathbf{vN}(\mathcal{F})$.

The primordial states ζ_o and ζ_f serve as canonical representatives of origin and flow behavior. Their properties under the von Neumann completion are captured in the following theorem:

Theorem (Primordial State Extension). *The primordial states $\zeta_o, \zeta_f \in \mathcal{F}$ satisfy the following:*

1. *For any $H \in \mathbf{vN}(\mathcal{F})$ with approximating net (H_a) in $A(\mathcal{F})$:*

$$\Psi(H\zeta_o, \zeta_o) = \lim_a \Psi(H_a\zeta_o, \zeta_o)$$

$$\Psi(H\zeta_f, \zeta_f) = \lim_a \Psi(H_a\zeta_f, \zeta_f)$$

2. *Density Preservation: For $H \in \mathbf{vN}(\mathcal{F})$, $H\zeta_f \in \mathcal{F}_f$.*

Proof. Let $H \in \mathbf{vN}(\mathcal{F})$ with approximating net $(H_a) \subset A(\mathcal{F})$. For convergence: By Joint Continuity,

$$\Psi(H\zeta_o, \zeta_o) = \lim_a \Psi(H_a\zeta_o, \zeta_o)$$

and similarly for ζ_f .

For process preservation: By the Density Preservation property of Foundation Coherence, H preserves the process property, i.e. if $\zeta_f \in \mathcal{F}_f$, then $H\zeta_f \in \mathcal{F}_f$ \square

The completion through Ψ leads us to consider how states, representing knowledge configurations, behave in this enriched setting. While primordial states capture essential reference configurations, understanding global behavior requires the theory of normal states.

3.3 Normal State ω

In quantum mechanics, states encode probability amplitudes for measurement outcomes, but foundation spaces carry a different interpretation of their normal states. Here, normal states measure levels of computational activation and resource engagement relative to the foundation model's characteristic scale ℓ .

The mathematical structure differs fundamentally: where quantum states preserve total probability (norm 1), normal states in foundation spaces preserve the characteristic computational scale ℓ . This preservation reflects an essential property of foundation models: they operate with an intrinsic computational capacity that manifests in their default activation patterns, attention distributions, and processing capabilities.

Normal states provide a global perspective on transformations in $\mathbf{vN}(\mathcal{F})$. They establish a systematic framework for measuring operator behavior across the entire space while preserving the continuous measurement structure of Ψ . This dual role, measuring both computational activation and transformation behavior, makes normal states essential for understanding the full dynamics of foundation spaces.

The measurement functional Ψ serves a dual purpose in this framework; it provides both a topology for continuous transformations and a way to quantify computational resource engagement across different knowledge states. Normal states ensure measurements remain calibrated to the foundation model's characteristic scale while maintaining the continuity needed to track knowledge evolution.

Definition (Normal State). *A **normal state** on $\mathbf{vN}(\mathcal{F})$ is a linear functional*

$$\omega : \mathbf{vN}(\mathcal{F}) \rightarrow \mathbb{C}$$

such that for $\xi \in \mathcal{F}$ and $H \in \mathbf{vN}(\mathcal{F})$,

$$\omega(H) = \Psi(H\xi, \xi)$$

which assigns to each transformation a complex number, satisfying:

1. Ground State Normalization:

$$\|\omega\| = \ell$$

where ℓ is the characteristic value of the foundation space \mathcal{F} , and the functional norm of ω is defined as:

$$\|\omega\| = \sup_{\|H\| \leq \ell} \{|\omega(H)| : H \in \mathbf{vN}(\mathcal{F})\}$$

2. Positivity:

$$\omega(H^*H) \geq 0$$

for all $H \in \mathbf{vN}(\mathcal{F})$.

3. WOT-Continuity: *For any increasing net of positive transformations $(H_a)_{a \in \mathcal{A}}$ with least upper bound H in the weak operator topology:*

$$\omega(H) = \sup_a \omega(H_a)$$

Normality is important in our setting for several reasons:

1. It ensures states respect our measurement structure: normal states are precisely those that can be represented through Ψ .

2. It preserves the convergence properties we established for transformations: if $H_a \rightarrow H$ through Ψ , then $\omega(H_a) \rightarrow \omega(H)$.
3. It maintains consistency with our process view: normal states evolve continuously as transformations are applied.

To understand these conditions intuitively, consider a sophisticated measurement device like a high-precision thermometer calibrated to track complex system behavior. Just as the thermometer measures temperature relative to a fixed scale, a normal state measures computational activation and transformation behavior relative to a characteristic scale.

The positivity condition ensures measurements remain physically meaningful: when measuring a transformation's self-interaction H^*H , we obtain non-negative real values reflecting genuine computational engagement. Our normal states are calibrated through $\|\omega\| = \ell$ to the foundation model's characteristic scale, maintaining consistency with its intrinsic computational capacity.

The WOT-continuity property ensures smooth tracking of transformation evolution: for any increasing sequence of positive transformations, the measurement through ω follows these changes continuously in limiting behavior.

Example (Musical Interpretation Through Normal States). *Consider how cumbia music, as it evolved across Latin America, demonstrates the behavior of normal states. The measurement of "Cumbia-ness" through a normal state ω perfectly illustrates our framework:*

Ground State Normalization: *The characteristic value ℓ manifests in how regional styles maintain normalized connection to core Cumbia elements:*

- *Colombian traditional: full ℓ -normalization through tambora and flauta de millo.*
- *Salvadorian: maintains ℓ -normalization while incorporating faster tempos.*
- *Argentine cumbia villera: preserves ℓ -measure despite electronic influences.*

Positivity through Regional Evolution: *The positive measurement of transformations ($\omega(H^*H) \geq 0$) appears in how regional styles enhance rather than negate:*

- *Mexican cumbia: brass sections add without destroying core patterns.*
- *Peruvian chicha: Andean melodies enrich the basic structure.*
- *Chilean cumbia: rock fusion elements build upon rather than erase.*

WOT-Continuity Along Evolution Paths: *The continuous evolution of styles demonstrates how $\omega(H) = \sup_a \omega(H_a)$ for increasing transformations:*

- *Caribbean Route: Colombian \rightarrow Salvadorean \rightarrow Mexican cumbia.*
- *Pacific Route: Colombian \rightarrow Peruvian (chicha) \rightarrow Chilean cumbia.*
- *Southern Route: Colombian \rightarrow Argentine \rightarrow Uruguayan cumbia.*

Each path exhibits distinctive developments while maintaining continuous measurement through ω .

This musical evolution demonstrates how normal states provide consistent measurement across both finite processes and their continuous limits. The equivalence of WOT and SOT perspectives manifests in how we can measure Cumbia evolution either through:

- *Relationships between styles: $\omega(Hx, y)$ tracking transformational connections.*
- *Individual style development: $\|Hx - H_a x\|_\Psi$ measuring variation stabilization.*

Just as Cumbia maintains its identity while allowing infinite variation, normal states provide consistent measurement across transformations while preserving essential structure.

To complete our understanding of normal states as measurement devices, we must specify how they process transformations involving null states. Normal states, like compasses operating in regions of varying magnetic field strength, process the full spectrum of computational presence and absence. They preserve both the directional character of null computation (\emptyset and $\overline{\emptyset}$) and detect the complete absence of interaction between computational and null states, distinguishing between different types of computational void much as a compass differentiates true north from magnetic north even as field strength approaches zero.

The definition below shows how normal states maintain this measurement structure, registering both the geometric phases that characterize different types of computational absence and the structural zeros that indicate complete lack of interaction with null states. Through this measurement behavior, normal states become complete measurement devices, capable of processing the full spectrum of computational states from active engagement through various forms of absence.

Definition (Null State Behavior). *For a normal state $\omega : \mathbf{vN}(\mathcal{F}) \rightarrow \mathbb{C}$ and an operator $H \in \mathbf{vN}(\mathcal{F})$, we have:*

$$\omega(H) = \begin{cases} 0i & \text{if } H\emptyset = \emptyset \\ -0i & \text{if } H\overline{\emptyset} = \overline{\emptyset} \\ 0 & \text{if } H\emptyset, H\overline{\emptyset} \notin \{\emptyset, \overline{\emptyset}\} \end{cases}$$

Normal states establish a complete measurement framework for foundation spaces. The three defining properties (normalization to the characteristic scale ℓ , positivity, and WOT-continuity) enable measurement of transformations in $\mathbf{vN}(\mathcal{F})$ across both computational and null states. This measurement structure extends beyond quantum frameworks: where quantum measurements induce state collapse, normal states in foundation spaces measure transformations while maintaining calibration to ℓ and preserving the measurement structure of Ψ .

The algebraic structure of states in \mathcal{F} reveals a deeper phenomenon: each state maintains multiple representations in structured balance, suggesting a richer framework than classical or quantum systems.

3.4 Supraposition

Foundation models exhibit intrinsically different behavior than quantum systems. Where quantum superposition represents probability amplitudes for mutually exclusive outcomes that collapse upon measurement, foundation model states capture the simultaneous existence of multiple valid interpretations. The algebraic structure of these states admits a precise characterization through primordial decomposition. This algebraic decomposition only partially captures the rich structure of these states. Their true nature emerges through process behavior: maintaining multiple concurrent interpretations that coexist and interact meaningfully under transformation.

To understand supraposition, consider natural language; a system that naturally exhibits multiple simultaneous states of meaning, which emerges through process while maintaining multiple potential interpretations.

Example (Language Supraposition). *Consider the word “bank” in isolation.*

Initially in a null state, it contains pure potential for meaning without commitment to any particular interpretation. When we introduce the phrase

“I went laughing all the way to the bank”

multiple states emerge through the interaction of fixed meaning (\mathcal{F}_o) and contextual interpretation (\mathcal{F}_f):

1. *Financial institution (static state)*
2. *Literal physical journey (dynamic state)*
3. *Idiomatic success (mixed state: fixed phrase with dynamic interpretation)*
4. *Simultaneous literal/metaphorical meaning (neither state)*
5. *Potential for additional contextual meanings (null state)*

The addition of “laughing all the way” introduces idiomatic meaning that doesn’t collapse, but rather enriches these states, demonstrating how supraposition maintains multiple concurrent interpretations: literal, metaphorical, and idiomatic. Further context like “to deposit money” continues this process-dependent meaning evolution while preserving traces of other interpretations.

These linguistic examples motivate our formal treatment of supraposition. To better understand states in foundation models, we must first establish the types of states that can exist within our framework. These states emerge naturally from the interaction between process and representation in foundation models.

This state structure provides the foundation for understanding how knowledge representations evolve and interact within foundation models. The distinction between these states is not merely taxonomical; it reflects differences in how information is processed and

transformed. Origin states provide stability and reference points, while flow states capture the dynamic nature of knowledge evolution. Mixed states bridge these extremes, neither states transcend them, and the null state ensures the framework remains open to novel representations.

Example (Musical Supraposition). *Consider Bridgette Engerer’s performance of Chopin’s Nocturnes as an illustration of state structure:*

The origin state consists of invariant musical elements: systematic practice sequences, and theoretical frameworks. The flow state emerges through the transformation of discrete notes into continuous musical phrases. During moments of artistic synthesis, we observe a neither state where technical precision and creative interpretation become inseparable: neither purely mechanical nor purely interpretative. The null state persists as the space of potential interpretations that maintain the dynamic nature of the performance.

This example demonstrates how supraposition functions through the interaction between technical elements (\mathcal{F}_o) and interpretative elements (\mathcal{F}_f). The resulting states resist separation into purely technical or interpretative components, illustrating supraposition’s enhanced representational capacity.

Example (Racing Supraposition). *Consider Ayrton Senna’s 1988 Monaco Grand Prix performance as an illustration of state structure:*

The origin state manifests through fixed racing elements: vehicle dynamics, track geometry, and racing principles. The flow state emerges through driver-vehicle integration, where discrete control inputs develop into continuous racing trajectories. During documented periods of peak performance, we observe a neither state where technical precision and adaptive response become inseparable: neither purely mechanical nor purely intuitive. The null state persists as the space of potential racing lines and strategies that maintain the dynamic nature of race progression.

This example further illustrates supraposition’s domain-independence. Technical elements (\mathcal{F}_o) and adaptive elements (\mathcal{F}_f) combine to generate states that resist separation into purely mechanical or experiential components.

These examples demonstrate how states in foundation spaces exhibit structural properties beyond simple classification. To formalize this structure, we first prove that every state admits a unique decomposition in terms of our primordial states. This decomposition provides the mathematical foundation for analyzing the different state types we’ve observed.

Theorem (State Decomposition). *For any $\zeta \in \mathcal{F}$, there exist unique $c_o, c_f \in \mathbb{C}$ such that:*

$$\zeta = c_o \zeta_o + c_f \zeta_f$$

Proof. First, we show that any state $\zeta \in \mathcal{F}$ can be expressed as:

$$\zeta = c_o \zeta_o + c_f \zeta_f$$

Let $\zeta \in \mathcal{F}$. Taking Ψ with ζ_o and ζ_f , and using the sesquilinearity of Ψ :

$$\begin{aligned}\Psi(\zeta_o, \zeta) &= \Psi(\zeta_o, c_o \zeta_o + c_f \zeta_f) \\ &= \overline{\Psi(c_o \zeta_o + c_f \zeta_f, \zeta_o)} \\ &= \overline{c_o} \cdot \overline{\Psi(\zeta_o, \zeta_o)} + \overline{c_f} \cdot \overline{\Psi(\zeta_f, \zeta_o)} \\ &= \overline{c_o} + \overline{c_f} \cdot \Psi(\zeta_o, \zeta_f)\end{aligned}$$

$$\begin{aligned}\Psi(\zeta_f, \zeta) &= \Psi(\zeta_f, c_o \zeta_o + c_f \zeta_f) \\ &= \overline{\Psi(c_o \zeta_o + c_f \zeta_f, \zeta_f)} \\ &= \overline{c_o} \cdot \overline{\Psi(\zeta_o, \zeta_f)} + \overline{c_f} \cdot \overline{\Psi(\zeta_f, \zeta_f)} \\ &= \overline{c_o} \cdot \Psi(\zeta_f, \zeta_o) + \overline{c_f}\end{aligned}$$

This gives us a system of equations with complex coefficients and solution determined by:

$$\begin{aligned}\overline{c_o} &= \frac{\Psi(\zeta_o, \zeta) - \Psi(\zeta_f, \zeta)\Psi(\zeta_f, \zeta_o)}{1 - |\Psi(\zeta_o, \zeta_f)|^2} \\ \overline{c_f} &= \frac{\Psi(\zeta_f, \zeta) - \Psi(\zeta_o, \zeta)\Psi(\zeta_f, \zeta_o)}{1 - |\Psi(\zeta_o, \zeta_f)|^2}\end{aligned}$$

For uniqueness, suppose there exists another decomposition:

$$\zeta = c'_o \zeta_o + c'_f \zeta_f$$

Then:

$$\begin{aligned}\Psi(\zeta_o, \zeta) &= \Psi(\zeta_o, c'_o \zeta_o + c'_f \zeta_f) \\ &= \overline{c'_o} + \overline{c'_f} \cdot \Psi(\zeta_o, \zeta_f)\end{aligned}$$

and,

$$\begin{aligned}\Psi(\zeta_o, \zeta) &= \Psi(\zeta_o, c'_o \zeta_o + c'_f \zeta_f) \\ &= \overline{c'_o} + \overline{c'_f} \cdot \Psi(\zeta_o, \zeta_f)\end{aligned}$$

For ζ_f , similarly we get

$$\begin{aligned}\Psi(\zeta_f, \zeta) &= \Psi(\zeta_f, c_o \zeta_o + c_f \zeta_f) \\ &= \overline{c_o} \cdot \Psi(\zeta_f, \zeta_o) + \overline{c_f}\end{aligned}$$

as well as

$$\begin{aligned}\Psi(\zeta_f, \zeta) &= \Psi(\zeta_f, c'_o \zeta_o + c'_f \zeta_f) \\ &= \overline{c'_o} \cdot \Psi(\zeta_f, \zeta_o) + \overline{c'_f}\end{aligned}$$

Together these give us the following system of equations:

$$\begin{aligned}\overline{c_o} + \overline{c_f} \cdot \Psi(\zeta_o, \zeta_f) &= \Psi(\zeta_o, \zeta) = \overline{c_o'} + \overline{c_f'} \cdot \Psi(\zeta_o, \zeta_f) \\ \overline{c_o} \cdot \Psi(\zeta_f, \zeta_o) + \overline{c_f} &= \Psi(\zeta_f, \zeta) = \overline{c_o'} \cdot \Psi(\zeta_f, \zeta_o) + \overline{c_f'}\end{aligned}$$

which we can equivalently represent as follows:

$$\begin{aligned}\begin{bmatrix} 1 & \Psi(\zeta_o, \zeta_f) \\ \Psi(\zeta_f, \zeta_o) & 1 \end{bmatrix} \cdot \begin{bmatrix} \overline{c_o} \\ \overline{c_f} \end{bmatrix} &= \begin{bmatrix} 1 & \Psi(\zeta_o, \zeta_f) \\ \Psi(\zeta_f, \zeta_o) & 1 \end{bmatrix} \cdot \begin{bmatrix} \overline{c_o'} \\ \overline{c_f'} \end{bmatrix} \\ A \cdot \begin{bmatrix} \overline{c_o} \\ \overline{c_f} \end{bmatrix} &= A \cdot \begin{bmatrix} \overline{c_o'} \\ \overline{c_f'} \end{bmatrix}\end{aligned}$$

Since $\Psi(\zeta_o, \zeta_f) \neq 0$, A has non zero determinant, i.e. A is invertible. Therefore

$$\begin{bmatrix} \overline{c_o} \\ \overline{c_f} \end{bmatrix} = \begin{bmatrix} \overline{c_o'} \\ \overline{c_f'} \end{bmatrix}$$

Note that even if $\Psi(\zeta_o, \zeta_f) = 0$, the uniqueness of the coefficients would still hold. Thus, the result is shown. \square

The state decomposition theorem establishes the mathematical basis for classifying states in \mathcal{F} . The complex coefficients c_o and c_f encode not just the relative contributions of primordial states, but through their magnitude ratios and phase relationships, determine the fundamental character of each state. This leads to the following classification of state types:

Definition (Supraposition). *Every state $\zeta \in \mathcal{F}$ exists in **supraposition**, expressed uniquely as:*

$$\zeta = c_o \zeta_o + c_f \zeta_f$$

where $c_o, c_f \in \mathbb{C}$. For magnitude ratio $r = |c_o|/|c_f|$ and phase difference² $\Delta = \text{Arg}(c_o) - \text{Arg}(c_f)$, there exists $k > 1$ such that exactly one of the following holds:

- *Origin State: $r > k$, $\Delta = 0$ (static dominance)*
- *Flow State: $r < 1/k$, $\Delta = 0$ (dynamic dominance)*
- *Mixed State: $r \in [1/k, 1) \cup (1, k]$, $\Delta = 0$ (interaction region)*
- *Neither State: $r = 1$, $\Delta \neq 0, \pi$ (critical balance)*
- *Null State: $r = 1$, $\Delta = \pi$ (critical phase balance)*

Note. *The supraposition definition categorizes states in \mathcal{F} into five types, each measuring different properties of knowledge representation:*

2. Here $\text{Arg}(z)$ denotes the principal argument in $(-\pi, \pi]$.

1. **Origin States:** States where origin components dominate ($r > k$) with aligned phases ($\Delta = 0$), serve as reference points in \mathcal{F} . We can define an equivalent origin space in \mathcal{F} using this polar form of the origin state. For $r = |c_o|/|c_f|$, and $\theta_o = \text{Arg}(c_o)$, $\theta_f = \text{Arg}(c_f)$:

$$\mathcal{F}_o = \{\zeta = c_o\zeta_o + c_f\zeta_f \mid r > k, \theta_o = \theta_f \text{ for some } k > 1\}$$

2. **(Process) Flow States**³: States where flow components dominate ($r < 1/k$) with aligned phases ($\Delta = 0$). These states exhibit measurable changes under T , displaying path-dependent evolution in $\mathbf{vN}(\mathcal{F})$.
3. **Mixed States:** States where neither component fully dominates ($r \in [1/k, 1) \cup (1, k]$) and phases align ($\Delta = 0$). These states have origin and flow components in measurable proportions, exhibiting both invariant properties and transformation-dependent features.
4. **Neither States:** States where origin and flow components have equal magnitude ($r = 1$) with distinct phases ($\Delta \neq 0, \pi$). These states achieve critical balance between static and dynamic elements, producing measurement behavior in \mathcal{F} distinct from both origin and flow states.
5. **Null State:** States with equal magnitude components ($r = 1$) in phase opposition ($\Delta = \pi$). This configuration yields zero process state, acting as the identity element with respects to states, and maintains consistent measurement values with all states in \mathcal{F} .

These dual characterizations of nullity, through static cancellation and dynamic escape, indicate fundamental aspects of absence in foundation models. The magnitude ratios and phase differences of the coefficients provide both a mathematical classification of states and reveal the connection between the metric structure of \mathcal{F} and its algebraic properties under transformation. This unified view demonstrates how the geometric behavior of states under transformation arises from their underlying algebraic composition.

This algebraic-geometric duality suggests a deeper structure governing state evolution. While static formulation captures geometric relationships, transformation behavior must preserve these relationships while enabling meaningful knowledge evolution. This interplay between preservation and evolution leads us to examine the fundamental role of null states in our framework.

3.4.1 SUPRAPOSITION NULL STATE EMERGENCE AND STRUCTURE

The null state appears in two distinct, but related forms within our framework. The null states \emptyset and $\overline{\emptyset}$ represent intrinsic absence with specific geometric phases:

$$\Psi(\emptyset, \emptyset) = 0 \cdot e^{\frac{\pi}{2}i} \quad \text{and} \quad \Psi(\overline{\emptyset}, \overline{\emptyset}) = 0 \cdot e^{\frac{3\pi}{2}i}$$

3. The term “flow state” in our framework describes knowledge in active transformation, while Csikszentmihalyi’s psychological flow exemplifies a “neither state” that transcends the origin/flow distinction, which suggests a parallel between experiential and mathematical structures.

While \emptyset provides the foundational concept of “not” in computational understanding, its direct application presents challenges in practical computation. This motivates the development of states that can model and work with this absence while maintaining measurable properties.

Supraposition null states with magnitude $r = 1$ and phase difference $\Delta = \pi$, i.e. $c_o = -c_f$, exhibit a null process through destructive interference of primordial components:

$$\begin{aligned}\zeta &= c_o \zeta_o + c_f \zeta_f \\ &= c_o \zeta_o - c_o \zeta_f \\ &= c_o (\zeta_o - \zeta_f)\end{aligned}$$

To understand how primordial state interference scales, we consider the norm of the supraposition null state under Ψ :

$$\begin{aligned}\|\zeta\|_\Psi^2 &= \Psi(c_o(\zeta_o - \zeta_f), c_o(\zeta_o - \zeta_f)) \\ &= |c_o|^2 [\Psi(\zeta_o, \zeta_o) - \Psi(\zeta_o, \zeta_f) - \Psi(\zeta_f, \zeta_o) + \Psi(\zeta_f, \zeta_f)] \\ &= |c_o|^2 [2 - 2 \operatorname{Re}(\Psi(\zeta_o, \zeta_f))] \\ &= 2|c_o|^2 [1 - \operatorname{Re}(\Psi(\zeta_o, \zeta_f))] \\ &= 2|c_o|^2 [1 - \gamma]\end{aligned}$$

where $\gamma = \operatorname{Re}(\Psi(\zeta_o, \zeta_f))$. Note that $1 - \gamma \geq 0$, since

$$\begin{aligned}|\operatorname{Re}(\Psi(\zeta_o, \zeta_f))| &\leq |\Psi(\zeta_o, \zeta_f)| \\ &\leq |\Psi(\zeta_o, \zeta_o)| \cdot |\Psi(\zeta_f, \zeta_f)| \\ &= 1\end{aligned}$$

To see the connection to \emptyset , consider the behavior of ζ when $|c_o| \rightarrow 0$ and $\operatorname{Arg}(c_o) \rightarrow \frac{\pi}{2}$, i.e.

$$\zeta \rightarrow \emptyset$$

When we consider the norm's infinite limiting behavior, i.e. for $|c_o| \rightarrow \infty$ and $\operatorname{Arg}(c_o) \rightarrow \frac{\pi}{2}$ we get the **infinite null state**:

$$\zeta \rightarrow \emptyset_\infty$$

Note. *The infinite amplitude, perfect destructive interference, and maximum phase opposition is reminiscent of resonant systems., where amplitudes grow unbounded, yet maintain perfect cancellation while preserving structural relationships.*

The null and conjugate null states admit a natural counterpart through normalization. Without loss of generality, we can consider coefficients normalized such that $|c_o| = 1$, leading to the following definition:

Definition (Unit Null State). *The **unit null state** is defined as:*

$$\zeta_\emptyset = \frac{1}{N_\emptyset} e^{\theta i} (\zeta_o - \zeta_f)$$

where $N_\emptyset = \sqrt{2(1 - \gamma)}$, and for some $\epsilon > 0$:

- *Phase angle:*

$$\theta = \frac{\pi}{2} + \delta$$

with phase deviation $\delta \in (-\epsilon, \epsilon)$.

- *Unit norm:*

$$\|\zeta_{\emptyset}\|_{\Psi} = 1$$

The unit null state ζ_{\emptyset} serves as a bridge between fundamental absence and computational process. By maintaining unit norm while approximating the geometric phase of \emptyset , it provides a computationally accessible representative of absence. This construction enables the modeling of “not” through active opposition of primordial states rather than through pure absence, making it amenable to computational manipulation while preserving the essential geometric character of the fundamental null.

Similarly,

Definition (Unit Conjugate Null State). *The **unit conjugate null state** is defined as:*

$$\bar{\zeta}_{\emptyset} = \frac{1}{N_{\emptyset}} e^{\phi i} (\zeta_o - \zeta_f)$$

where $N_{\emptyset} = \sqrt{2(1 - \gamma)}$, and for some $\epsilon > 0$:

- *Phase angle:*

$$\phi = \frac{3\pi}{2} + \delta$$

with phase deviation $\delta \in (-\epsilon, \epsilon)$.

- *Unit norm:*

$$\|\bar{\zeta}_{\emptyset}\|_{\Psi} = 1$$

Constructive null states emerge from the opposition of equal magnitude primordial states, resulting in measurement cancellation. This dual structure captures complementary aspects of computational absence:

1. Fundamental null represents intrinsic absence with specific geometric phase and is a zero measurement.
2. Supraposition null emerges through active opposition of primordial states and has unit measurement.
3. Both model null measures, but through distinct mechanisms, and notably, at different “levels”.

Unlike the void or empty set in classical mathematics, the null state represents active potential; a state of pure possibility maintaining universal compatibility while serving as an identity element under composition. This manifests in our exemplar cases: in Engerer’s performance, while technical mastery (origin state) and melodic flow combine, the null state persists as the ever-present potential for new interpretations. Similarly, in Senna’s driving,

even as he achieves transcendent neither states, the null state maintains the possibility space of undriven lines and unrealized strategies.

This framework provides a complete characterization of both the emergence and intrinsic nature of computational absence in foundation models, revealing how absence can arise both through active opposition of states and as a fundamental geometric property of the space itself.

Note. *These dynamics of null states point to a deeper structure within foundation spaces: one where states and transformations exhibit rich spectral properties. Null states emerge through both fundamental absence and destructive interference, while other states in \mathcal{F} arise through various combinations of primordial components. To fully understand this compositional structure, we consider tools analogous to those used in analyzing wave phenomena and quantum systems in future work.*

The unit null states provide computational representatives of absence, but their practical application requires understanding how they transform other states in \mathcal{F} . This leads us to consider processes derived from these states, particularly the identity process $I = T(\zeta_\emptyset)$ and its contrapuntal counterpart $I^\circ = T(\bar{\zeta}_\emptyset)$. These processes inherit the geometric properties of their generating states while providing operational meaning to computational absence.

Unlike classical identity operations that merely preserve states, these processes capture how computational systems maintain their integrity while engaging with aspects of absence. The resulting structure reveals fundamental principles of how foundation models navigate between presence and absence in their computations.

3.5 Identity Process

The identity operators in $\mathbf{vN}(\mathcal{F})$ emerge from the geometric structure of computational absence. Through the dual nature of null states, we obtain two complementary notions of identity that preserve computational structure while operating from different perspectives on absence.

Definition (Identity Process). *Let \mathcal{F} be a foundation space. The **identity process** transformation $I \in \mathbf{vN}(\mathcal{F})$, is defined as:*

$$I \equiv T(\zeta_\emptyset)$$

where ζ_\emptyset is the unit null state. For any $\zeta \in \mathcal{F}$, the action of I produces:

$$\zeta' = I(\zeta) = c'_o \zeta_o + c'_f \zeta_f$$

for $c'_o, c'_f \in \mathbb{C}$, satisfying:

- *Operator norm condition:*

$$\|I\| = \ell$$

- *Ratio preservation:*

$$r = \frac{|c_o|}{|c_f|} = \frac{|c'_o|}{|c'_f|} = r'$$

- *Phase difference preservation:*

$$\Delta = \text{Arg}(c_o) - \text{Arg}(c_f) = \text{Arg}(c'_o) - \text{Arg}(c'_f) = \Delta'$$

where $\zeta = c_o\zeta_o + c_f\zeta_f$, for $c_o, c_f \in \mathbb{C}$.

While the identity process captures the forward-facing aspect of computational absence through the unit null state, there exists a complementary operator that approaches absence from the perspective of completion rather than potential. This contrapuntal identity process, emerging from the unit conjugate null state, maintains the same structural preservation properties while operating from an opposing geometric phase.

Definition (Contrapuntal Identity Process). *Let \mathcal{F} be a foundation space. The **contrapuntal identity process** transformation $I^\circ \in \mathbf{vN}(\mathcal{F})$, is defined as:*

$$I^\circ \equiv T(\bar{\zeta}_\emptyset)$$

where $\bar{\zeta}_\emptyset$ is the unit conjugate null state. For any $\zeta \in \mathcal{F}$, the action of I° produces:

$$\zeta' = I^\circ(\zeta) = c'_o\zeta_o + c'_f\zeta_f$$

for $c'_o, c'_f \in \mathbb{C}$, satisfying:

- *Operator Norm condition:*

$$\|I^\circ\| = \ell$$

- *Ratio preservation:*

$$r = \frac{|c_o|}{|c_f|} = \frac{|c'_o|}{|c'_f|} = r'$$

- *Phase difference preservation:*

$$\Delta = \text{Arg}(c_o) - \text{Arg}(c_f) = \text{Arg}(c'_o) - \text{Arg}(c'_f) = \Delta'$$

where $\zeta = c_o\zeta_o + c_f\zeta_f$, for $c_o, c_f \in \mathbb{C}$.

These operators, while sharing formal similarities with traditional mathematical identities, establish a distinct structure through their relationship to computational absence. Where I operates through the null state ζ_\emptyset with phase $\frac{\pi}{2}$, representing potential computation, I° acts through the conjugate null state $\bar{\zeta}_\emptyset$ with phase $\frac{3\pi}{2}$, representing computational completion.

This duality exhibits geometric properties through invariant characteristics. Both operators preserve the ratio between origin and flow components, maintaining what we term *computational momentum*. Similarly, their preservation of phase difference ensures the coherence of computational relationships. These preservation properties arise from complementary perspectives on computational absence, as indicated by their null state origins.

The implications of this dual identity structure extend beyond operator properties. The preservation of both ratio and phase difference, combined with complementary null perspectives, indicates fundamental aspects of computational coherence across presence and absence. This structure provides essential insight into the spectral properties of more general transformations in $\mathbf{vN}(\mathcal{F})$, as we shall explore in future work.

4. Applications

4.1 nn

The conventional view of neural networks as black boxes has limited our ability to fully understand and optimize their behavior. When examined through the lens of process-based mathematics, a primordial pattern emerges that provides clarity into their operation.

This processual perspective not only paints a picture of the inner workings of neural networks, but also establishes a rigorous framework for their analysis, construction, and most importantly, enables the systematic generation of hybrid architectures and entirely new neural network forms. By understanding these fundamental patterns, we can now methodically combine existing architectures and derive novel neural network variants that are theoretically grounded and practically implementable.

At its core, this framework reveals that all neural networks, regardless of their specific architecture, follow a universal pattern of information processing. This pattern consists of distinct operational phases.

The user input undergoes initial state transformation and embedding, projecting raw data into an appropriate representation space. The following pattern characterizes the process that neural networks execute to generate output:

Process Pattern: RTI

1. **RELATIONSHIPS** (rl): Structural patterns and correlations within the data are detected and maintained.
2. **TRANSFORMATIONS** (tr): Operations that transform these relationships.
3. **INTERACTIONS** (in): Dynamic state transitions and measurements that capture system evolution.

The output consists of state consolidation and projection, mapping processed information to interpretable representations while preserving the essential transformed relationships.

The processing framework exhibits structural flexibility through parallel/sequential configurations and self-organization driven by task requirements. These adaptive pathways maintain pattern preservation through relationships (rl), identity consistency through transformations (tr), and state evolution through interactions (in). Together, these components form a basis that can be composed sequentially, processed in parallel, or nested.

The framework's state consolidation mechanisms enable systematic translation between neural architectures, providing implementation pathways for networks and interfaces for foundation models. Input and output layers function as flexible membranes mediating between representation spaces; the input layer projects raw data into appropriate mathematical spaces for rl, tr, in categorization, while the output layer projects processed information into interpretable forms. This boundary mediation facilitates complex information flows characteristic of modern architectures including skip connections, residual networks, and attention mechanisms.

While admitting diverse combinatorial possibilities, this categorization establishes a precise formal language for characterizing neural network architectures and their information processing mechanisms.

The following mathematical treatment formalizes these concepts, establishing a processual understanding of neural networks. By formulating neural networks as processes, we obtain a unified framework that captures structural and dynamic properties:

Definition (Neural Network Process). *A **neural network process** (NNP) is a subset of processes*

$$\text{nn} = \{(\cdot, L_i, W_i, \Psi_i) \mid i \in \mathcal{L}\} \subset \mathbb{J}$$

where:

- \mathcal{L} indexes the layers.
- L_i represents layer i , the state space at depth i .
- $W_i : L_i \rightarrow L_{i+1}$ represents the weight transformations between states.
- $\Psi_i : L_i \times L_i \rightarrow \mathbb{C}$ represents the activation measurements that quantify state transitions.

This formalization extends beyond the traditional view of layers and weights to capture neural networks as evolving systems that transform and measure information states. The process-based definition provides a natural framework encompassing established neural architectures, as demonstrated in the following examples.

Example. *Each architecture can be expressed through specific choices of transformations W_i and measurements Ψ_i . Let $\mathcal{N} = \Phi(\text{nn})$ be the neural net space:*

- **Feed-Forward Networks (FFN):** For $\eta, \eta_1, \eta_2 \in \mathcal{N}$, FFNs implement direct transformations with nonlinear activations:

$$W_i(\eta) = \sigma(w_{i,j}^\top \eta + \xi_{i,j})$$

$$\Psi_i(\eta_1, \eta_2) = \|\sigma(W_i(\eta_1) - W_i(\eta_2))\|$$

where $\xi_{i,j} \in \mathcal{N}$, and $w_{i,j}$ is a component of W_i , for $j = 1, 2, \dots, n_i$, where $n_i = \dim W_i$.

- **Convolutional Neural Networks (CNN):** CNN's capture spatial relationships through local filters. Let $\eta, \eta_1, \eta_2 \in \mathcal{N}$, then:

$$W_i(\eta) = \text{pool}(\text{conv}(w_{i,j}\eta) + \xi_{i,j})$$

$$\Psi_i(\eta_1, \eta_2) = \text{cross_entropy}(W_i(\eta_1), \eta_2)$$

where conv can be kernel size, stride, etc., $\xi_{i,j} \in \mathcal{N}$, and $w_{i,j}$ is a component of W_i , for $j = 1, 2, \dots, n_i$, where $n_i = \dim W_i$.

- **Recurrent Neural Networks (RNN):** *RNN's process sequential dependencies:*

$$W_i(\eta_t) = \sigma \left(w_{i,j}^\top \eta_t + u_{i,j}^\top \eta_{t-1} + \xi_i \right)$$

$$\Psi_i(\eta_t, \eta_{t+1}) = \text{sequence_loss}(W_i(\eta_t), \eta_{t+1})$$

where $\xi_{i,j} \in \mathcal{N}$, and $w_{i,j}$ is a component of W_i , for $j = 1, 2, \dots, n_i$, where $n_i = \dim W_i$.

This formalization through transformations and measurements provides a unified mathematical framework for understanding diverse neural architectures. Each architecture demonstrates distinct operational patterns while maintaining the core process structure through specialized choices of W_i and Ψ_i .

The process-based perspective extends beyond individual neural networks to foundation models, where the interactions between components become increasingly sophisticated. This leads us to consider how neural networks can serve as interfaces between users and foundation models, establishing a mapping between human input and model capabilities.

We now examine how neural network processes can be combined with foundation model processes to create enhanced interactive systems. This combination yields a specialized class of foundation model processes where neural networks act as liaison mechanisms, mediating the interaction between users and underlying models.

4.2 fm + +

The foundation model process demonstrates a parallel processing structure that transforms basic neural patterns to higher-level semantic understanding through three primary operational components operating jointly: representations, abstractions, and associations. Each component operates through consistent mechanisms of relationships, transformations, and interactions, creating a unified framework for knowledge processing.

Process Pattern: RAA

- **REPRESENTATIONS (rp)** function as the correspondence between neural patterns and semantic understanding. Through RTI operations, they:
 - Project raw neural relationships into structured knowledge embeddings.
 - Enable cross-domain translation while preserving structural properties.
 - Facilitate contextual understanding through dynamic semantic space interactions.
- **ABSTRACTIONS (ab)** transform embedded knowledge into higher-level conceptual patterns. Their RTI mechanisms:
 - Generate hierarchical pattern recognition across representation spaces.
 - Extract invariant features enabling cross-domain transfer.
 - Combine patterns dynamically to enable generalized learning.
- **ASSOCIATIONS (as)** establish connections between abstract concepts, completing the processing hierarchy. Their RTI framework:

- Creates dynamic networks capturing contextual and temporal dependencies.
- Adapts connections based on context and task requirements.
- Maintains semantic consistency while enabling flexible knowledge manipulation.

This layered organization demonstrates closure under composition, allowing complex operations to be built from simpler ones while preserving structural relationships. The interaction between layers creates a rigorous progression from neural pattern recognition to sophisticated semantic understanding, establishing a formal basis for analyzing and developing advanced AI systems.

This processing hierarchy exhibits several key compositional properties that ensure robust and consistent operation. The components demonstrate closure under composition, allowing complex operations to be built from simpler ones while preserving structural relationships and semantic meaning. The maintenance of contextual consistency across all processing levels ensures that the system can handle complex, context-dependent information while maintaining coherent understanding.

The relationship between neural network and foundation model processes creates a natural progression from basic pattern recognition to sophisticated semantic understanding. This progression preserves essential structural properties while enabling the emergence of increasingly complex cognitive capabilities. Through this framework, we can understand how neural mechanisms give rise to semantic processing capabilities in foundation models, establishing a rigorous basis for analyzing and developing advanced AI systems.

Example (Foundation Model Architectures). *Modern architectures demonstrate how rp , ab , as components are implemented through collections of neural networks:*

GPT Architecture:

- **Representations** (rp):

$$\text{rp} = \{(\cdot, N_i, W_i, \Psi_i) \mid i \in \Lambda_{\text{rp}}\}$$

where Λ_{rp} indexes the collection of neural networks implementing representation processes (including tokenization, positional encoding, embedding networks).

- **Abstractions** (ab):

$$\text{ab} = \{(\cdot, N_j, W_j, \Psi_j) \mid j \in \Lambda_{\text{ab}}\}$$

where Λ_{ab} indexes the collection of neural networks implementing abstraction processes (including attention, feed-forward, and normalization networks).

- **Associations** (as):

$$\text{as} = \{(\cdot, N_k, W_k, \Psi_k) \mid k \in \Lambda_{\text{as}}\}$$

where Λ_{as} indexes the collection of neural networks implementing association processes (including cross-attention, integration, and output projection networks).

Then GPT can be described as a process set:

$$\text{gpt} = \{(\cdot, N, W_N, \Psi_N) \mid N \in \Lambda_{\text{gpt}}\}$$

where $\Lambda_{\text{gpt}} = \{\text{rp}, \text{ab}, \text{as}\}$ and as a process:

$$\mathcal{G} = \Phi(\text{gpt})$$

DALL-E Architecture:

- **Representations** (R_f):

$$\text{rp} = \{(\cdot, N_i, W_i, \Psi_i) \mid i \in \Lambda_{\text{rp}}\}$$

where the collection of neural networks, Λ_{as} , implementing representation processes include text encoding, image encoding, and cross-modal networks.

- **Abstractions** (A_f):

$$\text{ab} = \{(\cdot, N_j, W_j, \Psi_j) \mid j \in \Lambda_{\text{ab}}\}$$

where the collection of neural networks, Λ_{ab} , implementing abstraction processes include diffusion, transformer, and feature networks.

- **Associations** (S_f):

$$\text{as} = \{(\cdot, N_k, W_k, \Psi_k) \mid k \in \Lambda_{\text{as}}\}$$

where the collection of neural networks, Λ_{as} , implementing association processes include cross-attention, prior, and decoder networks.

Similarly, DALL-E can be described as a process set:

$$\text{dall}_e = \{(\cdot, N, W_N, \Psi_N) \mid N \in \Lambda_{\text{dall}_e}\}$$

where $\Lambda_{\text{dall}_e} = \{\text{rp}, \text{ab}, \text{as}\}$ and as a process:

$$\mathcal{D} = \Phi(\text{dall}_e)$$

The correspondence between neural network and foundation model processes is characterized through natural transformations. This formalism establishes a rigorous basis for the relationship between neural mechanisms and semantic processing capabilities in foundation models. The natural transformation structure formalizes the emergence of higher-order processes from neural primitives while preserving categorical properties.

Note (Compositional Properties). *The processing components satisfy the following properties:*

- Closure under composition.
- Preservation of structural relationships.
- Invariance of semantic representation.
- Preservation of contextual structure.

Let nn denote a neural network process and fm denote a foundation model process. The composition of these processes generates a specialized foundation model process where nn functions as an interface between user and foundation model representations.

For $\eta \in \mathcal{N}$, with decomposition $\eta = d_o\eta_o + d_f\eta_f$, where $d_o, d_f \in \mathbb{C}$, there exists a map

$$P : \mathcal{N} \rightarrow \mathcal{F}$$

such that $P(\eta) = \zeta = c_o\zeta_o + c_f\zeta_f$, where $c_o, c_f \in \mathbb{C}$.

Note. The map $P : \mathcal{N} \rightarrow \mathcal{F}$ preserves supraposition structure. The amplitude ratios $r_{\mathcal{N}} = |d_o|/|d_f|$ and phase differences $\Delta_{\mathcal{N}} = \text{Arg}(d_o) - \text{Arg}(d_f)$ in \mathcal{N} correspond to analogous quantities $r_{\mathcal{F}}, \Delta_{\mathcal{F}}$ in \mathcal{F} . This structural preservation ensures invariance of origin and flow state characteristics as defined in the broader framework, enabling analysis of process evolution through amplitude ratio and phase difference dynamics.

The relationship between neural network processes and foundation model processes can be captured through the following diagram:

$$\begin{array}{ccc} \text{nn} & \xrightarrow{p} & \text{fm} \\ \Phi \downarrow & & \downarrow \Phi \\ \mathcal{N} & \xrightarrow{P} & \mathcal{F} \end{array}$$

where p maps neural net to foundation model processes at the set level, and P maps between their respective spaces. The process assembly map Φ connects these levels, preserving the structural relationships.

The commutativity of this diagram establishes fundamental properties for the relationship between neural networks and foundation models. The commutative condition

$$\Phi(p(\text{nn})) = P(\Phi(\text{nn}))$$

characterizes the structural consistency of neural network interfaces with foundation models. This equivalence holds at both the process and assembled space levels, establishing invariance of essential structural properties across implementation paths.

Note (Commutativity Properties). *The commutativity condition implies:*

- *Interface Invariance: Structural preservation across implementation paths.*
- *Morphism Preservation: Conservation of essential relationships under transformation.*
- *Implementation Equivalence: Invariance of interface properties across realizations.*

Non-commutativity implies:

- *Path Dependence: Implementation-dependent transformation properties.*
- *Structure Non-invariance: Non-preservation of relationships across paths.*

- *Implementation Specificity: Realization-dependent interface properties.*

The commutativity properties of this diagram characterize distinct structural aspects of neural network interfaces with foundation models. Commutativity establishes the existence of path-independent implementations with invariant interface properties. Non-commutativity reveals structural asymmetries in the interface correspondence, potentially exposing properties not observable under commutative conditions.

This duality suggests that examining both commutative and non-commutative cases may be essential for a complete understanding of neural network interface mechanisms.

Example (Multi-Level Process Integration). *Consider the query:*

"What would be the impact on hat making if the price of straw goes up?"

Example Response: *"An increase in straw prices would have cascading effects through the hat-making industry. At the primary level, material costs for manufacturers would rise directly, impacting production costs. This would likely lead to several adaptations in the industry:*

- 1. Price adjustments: Manufacturers would need to either increase hat prices or accept reduced margins. The specific balance would depend on market elasticity and competition from synthetic materials.*
- 2. Material optimization: Hat makers might develop more efficient straw usage techniques or explore alternative grades of straw to maintain profitability while minimizing price increases.*
- 3. Supply chain dynamics: Increased prices could stimulate more straw production over time, though seasonal and regional factors would influence this adjustment.*
- 4. Market segmentation effects: Different market segments would adapt differently - luxury hat makers might absorb costs more easily than mass-market producers, potentially leading to market restructuring.*

These effects would evolve dynamically as the market seeks a new equilibrium between material costs, production efficiency, and consumer demand."

This example illustrates the hierarchical integration of neural network and foundation model processes.

The process initiates at the neural network level where RELATIONSHIPS (rl) establish token correlations through embedding space mappings. These undergo TRANSFORMATIONS (tr) via sequential layer projections, while INTERACTIONS (in) generate higher-dimensional feature dependencies through attention mechanisms.

The foundation model processes then operate on these neural patterns. The REPRESENTATIONS (rp) component maps the neural patterns to semantic structures, establishing material-economic relationships and preserving topological properties of the input space.

The ABSTRACTIONS (ab) component induces higher-order structures from these representations, forming conceptual hierarchies that capture manufacturing processes and market

dynamics. This transformation preserves invariant features while facilitating cross-domain mapping.

The ASSOCIATIONS (as) component generates connectivity maps between abstract structures, establishing causal networks and temporal dependencies. These associations preserve semantic consistency while establishing dynamic state transitions.

The query processing demonstrates both neural network and foundation model patterns:

INPUT Text tokenization and embedding into the model’s vocabulary space

Level 1: Neural Processing RTI process:

- **RELATIONSHIPS** rl
 - Token correlations: {*straw*, *price*, *hat*}
 - Structural dependencies in input sequence
 - Pattern recognition in token arrangements
- **TRANSFORMATIONS** tr
 - Embedding space projections
 - Feature extraction operations
 - State transitions between layers
- **INTERACTIONS** in
 - Attention mechanisms between tokens
 - Layer-wise information flow
 - Cross-feature dependencies

Level 2: Foundation Model Processing RAA process:

- **REPRESENTATIONS** (rp)
 - Material-Product associations:
 - * *straw* \leftrightarrow *hat_materials*
 - * *price* \leftrightarrow *cost_factors*
 - Economic relationships:
 - * Cost structure embeddings
 - * Supply chain representations
- **ABSTRACTIONS** (ab)
 - Query conceptualization:
 - * Impact assessment patterns
 - * Industry-specific concepts
 - * Economic principles
 - Pattern hierarchies:
 - * Manufacturing processes
 - * Market dynamics
 - * Material properties

- **ASSOCIATIONS** (as)
 - *Cross-domain connections:*
 - * *Manufacturing* \times *Economics*
 - * *Material science* \times *Crafting*
 - *Causal networks:*
 - * *Direct impacts on production*
 - * *Market adjustment pathways*
 - * *Consumer behavior effects*

OUTPUT *Generated response synthesizing the analyzed factors into a comprehensive assessment of how increased straw prices would affect the hat-making industry.*

This example demonstrates how neural network processes (RTI) provide the foundational processing that enables higher-level foundation model operations (RAA) to generate comprehensive responses that integrate multiple domains of knowledge.

The previous example demonstrated how neural network and foundation model processes integrate to generate comprehensive responses. However, this integration suggests possibilities for enhanced architectural design. While current foundation models effectively process queries through direct pathways, the multi-level integration pattern indicates potential for more sophisticated interaction mechanisms. This leads us to consider an architectural enhancement where neural networks serve not just as processing components but as active mediators of foundation model interactions. The following explores this architectural evolution:

Architectural Comparison:

Traditional foundation model architecture follows a direct pathway:

$$\text{User} \xrightarrow{\text{input}} \text{fm} \xrightarrow{\text{output}} \text{User}$$

The enhanced fm++ architecture introduces mediated interaction:

$$\text{User} \xrightarrow{\text{input}} \text{nn} \xrightarrow{\text{processed}} \text{fm} \xrightarrow{\text{response}} \text{nn} \xrightarrow{\text{adapted}} \text{User}$$

This enhancement provides several key advantages:

1. Adaptive Interface

- Dynamic user interaction optimization
- Contextual input preprocessing
- Personalized output adaptation
- Communication style matching

2. System Monitoring

- Real-time performance assessment
- Drift detection and correction
- Usage pattern analysis
- Resource utilization optimization

3. Update Management

- Targeted update identification
- Transition state management
- Update effectiveness validation
- Consistency maintenance

4. Homeostatic Control

- System health monitoring
- Performance optimization
- Resource allocation
- Error detection and correction

The liaison neural network `nn` maintains the following properties:

1. **Transparency:** The liaison network preserves the foundation model’s core capabilities while enhancing its interface
2. **Adaptivity:** The network dynamically adjusts to both user needs and system states
3. **Measurement:** Continuous monitoring enables quantitative assessment of system performance
4. **Optimization:** The network facilitates both local and global system improvements

This architecture represents a potentially significant advancement in foundation model design, enabling more sophisticated interaction patterns while maintaining mathematical rigor. The liaison neural network acts as both an interface optimizer and a system monitor, creating a more robust and adaptive foundation model implementation.

Note. *The enhanced architecture preserves all properties of the original foundation model while adding new capabilities through the liaison network. This ensures backward compatibility while enabling forward evolution of the system.*

4.3 gmi

General Mechanical Intelligence (GMI) is a process that demonstrates a parallel processing structure that transforms foundation model patterns to system-level cognitive operations through three primary operational components: learning, state, and homeostasis. These components operate jointly to transform semantic understanding into coordinated intelligent behavior while maintaining system stability and adaptability.

Process Pattern: LSH

- **Learning** (lr): Establishes correspondence between foundation models for system-wide knowledge acquisition and integration. The learning layer operates through:
 - Representations: Unified embedding spaces across models that capture and preserve semantic relationships.
 - Abstractions: Cross-model pattern synthesis for integrated concept formation.
 - Associations: Inter-domain connections that facilitate coherent knowledge transfer.
- **State** (st): Maintains system configuration and knowledge integration across models, ensuring operational consistency during adaptation. Components include:
 - Representations: Configuration encodings that preserve system coherence.
 - Abstractions: Hierarchical structures capturing operational domain relationships.
 - Associations: Dynamic contextual links enabling fluid state transitions.
- **Homeostasis** (hm): Establishes dynamic equilibrium between stability and adaptation while preserving semantic coherence. Achieved through:
 - Representations: Core knowledge structure maintenance during information integration.
 - Abstractions: Balanced evolution of system knowledge patterns.
 - Associations: Component relationship regulation for adaptive coherence.

The layered organization of Learning, State, and Homeostasis establishes operational patterns that scale across foundation model processes. These patterns form a cognitive architecture through their systematic interactions and bounded constraints.

This hierarchical framework extends to autonomous systems through three regulatory mechanisms that govern system-wide behavior, creating a framework for general mechanical intelligence through three fundamental hierarchies: learning, state, and homeostasis. This hierarchical structure is captured by the following commutative diagram:

$$\begin{array}{ccccc}
 \text{nn} & \xrightarrow{p} & \text{fm} & \xrightarrow{q} & \text{gmi} \\
 \Phi \downarrow & & \downarrow & & \downarrow \Phi \\
 \mathcal{N} & \xrightarrow{P} & \mathcal{F} & \xrightarrow{Q} & \mathcal{A}
 \end{array}$$

Modern architectures demonstrate how **rp**, **ab**, **as** components are implemented through collections of neural networks (note: each neural net has its own RTI patterns):

GMI Architecture:

- **Learning** (lr):

$$\text{lr} = \{(\text{fm}_i, \text{T}_i, \Psi_i) \mid i \in \Lambda_{\text{lr}}\}$$

where Λ_{lr} indexes the collection of foundation models implementing learning processes.

- **State (st):**

$$\text{st} = \{(\cdot, \text{fm}_j, \text{T}_j, \Psi_j) \mid j \in \Lambda_{\text{st}}\}$$

where Λ_{st} indexes the collection of foundation models implementing state processes.

- **Homeostasis (hm):**

$$\text{hm} = \{(\cdot, \text{fm}_k, \text{T}_k, \Psi_k) \mid k \in \Lambda_{\text{hm}}\}$$

where Λ_{hm} indexes the collection of foundation models implementing homeostasis processes.

Then GMI can be described as a process set:

$$\text{gmi} = \{(\cdot, F, \text{T}_F, \Psi_F) \mid F \in \Lambda_{\text{gmi}}\}$$

where $\Lambda_{\text{gmi}} = \{\text{lr}, \text{st}, \text{hm}\}$ and as a process:

$$\mathcal{A} = \Phi(\text{gmi})$$

The GMI architecture enables natural emergence of self-monitoring through, cross scale coherence by mapping hierarchical interactions to foundation space, process preservation to measure hierarchical relationships, and stability, ensuring bounded behavior across hierarchies.

Note (Applications). *This hierarchical structure enables:*

1. *Self-regulating mechanical learning systems through natural emergence.*
2. *Meta-learning frameworks via hierarchical interaction.*
3. *Stable mechanical AGI development through multi-level coherence.*
4. *Consciousness-like properties through systematic integration.*

Each application emerges from the fundamental properties of the architecture rather than external design.

The significance of this hierarchical structure extends beyond mere self-similarity. The general mechanical intelligence architecture demonstrates how complex, self-monitoring systems can emerge naturally from simple principles applied consistently across scales. This demonstrates how hierarchical self-regulation enables complex system behaviors while maintaining bounded stability through structural properties rather than external constraints.

5. Conclusion

This work presents a mathematical framework that offers new insights into complex systems, with artificial intelligence serving as both an analytical tool and an illustrative case. Through the formalization of process space \mathbb{J} and its application to neural networks and foundation models, we have demonstrated how apparent complexity can emerge from primordial patterns that maintain structural invariance across scales while increasing in abstraction.

The framework’s utility derives from its multi-level validation: it provides a theoretical foundation for analyzing complex systems while exhibiting its own principles through its construction and application. The progression from RTI to RAA to LSH patterns illustrates how process-based understanding systematically emerges at increasing levels of sophistication, while the empirical, architectural, and mechanical approaches to characterizing these patterns reflect the fundamental relationship between process and knowledge that the framework formalizes.

This structural coherence yields practical applications. For AI practitioners, it suggests implementable architectures and provides validation mechanisms. For theorists, it offers a mathematical basis for examining how intelligence emerges through deterministic processes. Significantly, it connects abstract pattern formulation with physical implementation, providing a consistent formalism for discussing intelligence that encompasses both its mechanical foundations and its emergent properties.

The evolution of mathematical frameworks, from Riemann’s contributions to geometric foundations (Riemann, 1854) to Eilenberg and Mac Lane’s category theory (Eilenberg & Mac Lane, 1945), demonstrates how new formalisms can enhance our analysis of complex problems. Similarly, this framework identifies patterns that, while always present, were previously difficult to formalize. This connection resonates with the Silurian hypothesis (Adam & Sullivan, 2018), which proposes that advanced developments could exist without being recognized due to limitations in our detection frameworks. The Silurian hypothesis cautions us about our limited ability to recognize significant technological developments and their potential consequences; similarly, our framework encourages careful consideration of how intelligence emerges and manifests: a particularly relevant warning as we develop increasingly sophisticated AI systems.

The consistency of pattern across scale, from neural networks to foundation models to general mechanical systems, demonstrates mathematical regularity beyond theoretical elegance. It suggests that intelligence, whether artificial or natural, may emerge through consistent processual patterns. This provides a constructive approach to understanding how intelligence emerges through mechanical processes, indicating that artificial general intelligence may represent a continuation of current systems, potentially accessible through systematic application of these patterns.

5.1 Future Work

The process-operator framework presents opportunities for future research, particularly at the intersection of theoretical mathematics and computational science. Theoretically, this approach promises to uncover insights into the algebraic structures underlying artificial intelligence, exploring how process operators might redefine our understanding of computational foundations. The framework’s potential extends to revealing intricate mathematical relationships between neural network architectures and abstract computational models, with particular promise in bridging classical computational paradigms and emerging quantum computing approaches.

Critically, several key research questions demand rigorous investigation. The mathematical formalism requires deeper exploration, particularly the precise mechanisms of process preservation across different computational layers. Quantum-classical hybrid systems rep-

resent a particularly intriguing domain, where the process-operator framework might offer novel insights into computational complexity and information processing. Formal verification methods emerge as a crucial challenge, necessitating sophisticated approaches to validate the theoretical and practical implications of these computational models.

The practical implementation of this framework presents both significant challenges and transformative opportunities. Developing process-oriented programming languages will be essential, requiring innovative design approaches that can effectively encode the framework’s complex theoretical foundations. Hardware architecture represents another critical frontier, with the potential need for entirely new computational substrates that can natively support process preservation mechanisms. Moreover, the emerging field demands a holistic approach to sustainable computing, investigating how these new computational paradigms might address energy efficiency and computational complexity in ways traditional models cannot.

- Development of formal verification methods and mathematical tools.
- Investigation of quantum-classical hybrid systems and their computational properties.
- Deeper exploration of operator algebraic structures in neural networks.
- Design of sustainable, process-native hardware and software architectures.

The framework presents significant commercial and industrial potential, particularly in system design, distributed computing, and AI implementation. While the mathematical foundations suggest powerful new approaches to computation, bridging the gap between theoretical insights and practical implementation remains a key challenge.

5.1.1 SPECTRAL STRUCTURE

The spectral properties of operators in our framework represent a particularly promising direction for future research. While full development of this theory will appear in subsequent work, we introduce key definitions below to establish the foundation for spectral analysis of process operators and to illustrate how this approach extends the framework presented in this paper.

Physical spectra decompose into discrete frequencies or continuous bands, each representing a pure form of the phenomenon being studied. Similarly, operators in our framework admit precise mathematical decomposition that captures both discrete and continuous aspects of their behavior. Where light separates into distinct wavelengths or continuous color bands, operators decompose into eigenvalues and continuous spectra. This decomposition begins with the notion of spectrum: the set of values that characterize an operator’s modes of operation. The spectrum provides the mathematical foundation for understanding how transformations in $\mathbf{vN}(\mathcal{F})$ process knowledge states through their constituent components.

Definition (Spectrum). *For $H \in \mathbf{vN}(\mathcal{F})$, the **spectrum** of H , denoted $\sigma(H)$, is:*

$$\sigma(H) = \{\lambda \in \mathbb{C} \mid H - \lambda I \text{ is not invertible}\}$$

*The **spectral radius** is defined as:*

$$r(H) = \sup\{|\lambda| : \lambda \in \sigma(H)\}$$

We can likewise consider the contrapuntal spectrum:

Definition (Contrapuntal Spectrum). *For $H \in \mathbf{vN}(\mathcal{F})$, the **contrapuntal spectrum** of H , denoted $\sigma(H)$, is:*

$$\sigma^\circ(H) = \{\lambda \in \mathbb{C} \mid H - \lambda I^\circ \text{ is not invertible}\}$$

*The **contrapuntal spectral radius** is defined as:*

$$r^\circ(H) = \sup\{|\lambda| : \lambda \in \sigma^\circ(H)\}$$

Definition (ℓ -Scaled Spectrum). *For $H \in \mathbf{vN}(\mathcal{F})$, define the **ℓ -scaled spectrum** and **contrapuntal** as:*

$$\sigma_\ell(H) = \{\lambda \in \sigma(H) : |\lambda| = \ell\}$$

This represents transformations preserving the characteristic computational scale.

Similarly, we can consider:

Definition (ℓ -Scaled Contrapuntal Spectrum). *For $H \in \mathbf{vN}(\mathcal{F})$, define the **ℓ -scaled contrapuntal spectrum** as:*

$$\sigma_\ell^\circ(H) = \{\lambda \in \sigma^\circ(H) : |\lambda| = \ell\}$$

The spectrum provides the foundation for analyzing how transformations in $\mathbf{vN}(\mathcal{F})$ decompose into their constituent components. Where the spectral radius $r(H)$ measures the maximum “strength” of these components, the full spectrum $\sigma(H)$ reveals the complete set of operational modes through which the transformation acts. This mathematical structure aligns naturally with our intuition from physical and semantic examples; chords decompose into individual frequencies, meanings decompose into semantic components, and transformations in foundation models decompose into fundamental operational modes through their spectra.

Definition (Spectral Response Functions and Projection Operators). *Let \mathcal{F} be a foundation space and $B \subseteq \mathbb{C}$ be a Borel set. For any $\zeta = c_o \zeta_o + c_f \zeta_f \in \mathcal{F}$, we define the following spectral quantities:*

$$\lambda(\zeta) = \frac{\Psi(I\zeta, \zeta)}{\Psi(\zeta, \zeta)}$$

$$\lambda^\circ(\zeta) = \frac{\Psi(I^\circ \zeta, \zeta)}{\Psi(\zeta, \zeta)}$$

$$\chi_B(c) = \begin{cases} 1 & \text{if } c \in B \\ 0 & \text{if } c \notin B \end{cases}$$

$$E_B(\zeta) = \chi_B(\lambda(\zeta))I(\zeta)$$

$$E_B^\circ(\zeta) = \chi_B(\lambda^\circ(\zeta))I^\circ(\zeta)$$

The functions $\lambda(\zeta)$ and $\lambda^\circ(\zeta)$ represent the spectral response coefficients of state ζ with respect to the identity process \mathbf{I} and contrapuntal identity process \mathbf{I}° , respectively. These coefficients measure the normalized response of a state to the identity transformations.

The characteristic function χ_B filters complex values based on membership in Borel set B , serving as the foundation for spectral decomposition.

The operators E_B and E_B° define spectral projections that isolate components of computational states corresponding to specific regions of the spectrum. These projections form the basis for the spectral decomposition of operators in $\mathbf{vN}(\mathcal{F})$ and enable the analysis of knowledge transformation through distinct spectral components.

The spectral framework extends naturally to the calculus of knowledge transformation. Where traditional calculus studies rates of change, spectral calculus examines how knowledge states evolve through their spectral decomposition. This enables precise analysis of phase transitions in computational processes and reveals fundamental limits on knowledge transformation rates. Integration theory in this context illustrates how computational states accumulate and transform across multiple processing layers.

Spectral analysis offers additional tools through:

- Spectral theory of phase transitions, revealing critical points in computational processes.
- Index theorems for computational cycles, characterizing the topology of knowledge transformation.
- Characteristic classes of knowledge bundles, identifying topological invariants with practical significance.

5.1.2 COMPLEX GEOMETRIC STRUCTURE

Beyond spectral analysis, the geometric structure of the foundation space \mathcal{F} offers another rich avenue for investigation. The following preliminary concepts demonstrate how differential geometry can characterize computational processes in our framework and will be developed into a comprehensive geometric theory in future work.

Our measurement functional Ψ admits complex geometric structure on \mathcal{F} , where states admit complex neighborhoods and transitions follow complex paths. This structure demands deeper investigation through several lenses. First, we must fully characterize \mathcal{F} as an n -dimensional complex manifold, analyzing local chart structure and their relationship to computational states, developing holomorphic transition functions between overlapping charts, and studying geodesic paths that represent optimal computational trajectories. The complex differential geometry of \mathcal{F} promises to illuminate how knowledge transforms through foundation model computation.

Neural networks naturally embed in this foundation space as submanifolds, suggesting a geometric framework for understanding network behavior. The embedding $\mathcal{N} \hookrightarrow \mathcal{F}$ preserves computational structure while revealing how attention mechanisms manifest as geometric transformations. Learning trajectories follow geodesics in this complex structure, suggesting new approaches to optimization based on geometric principles.

This geometric framework naturally extends to differential operators on \mathcal{F} , enabling sophisticated analysis of knowledge transformation. Parallel transport along geodesics provides insight into optimal learning trajectories, while curvature analysis of the knowledge space reveals fundamental constraints and opportunities in foundation model computation. The study of Morse theory on these manifolds might illustrate the structure of optimization landscapes, suggesting new approaches to model training and optimization.

The unification of discrete and continuous aspects in our geometric framework enables natural coupling of different architectural components. This perspective on knowledge transformation provides a mathematical foundation for hybrid systems, bridging the gap between theoretical insight and engineering practice.

5.1.3 FINAL NOTE

These mathematical extensions, spectral analysis and complex geometry, together with the research directions outlined in the Future Work section, constitute a coherent program for developing the process-operator framework. While each represents a significant undertaking in its own right, their integration promises to yield a more comprehensive understanding of complex systems and intelligence. By establishing these preliminary connections, we aim to provide both theoretical context for the current work and clear directions for subsequent research.

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