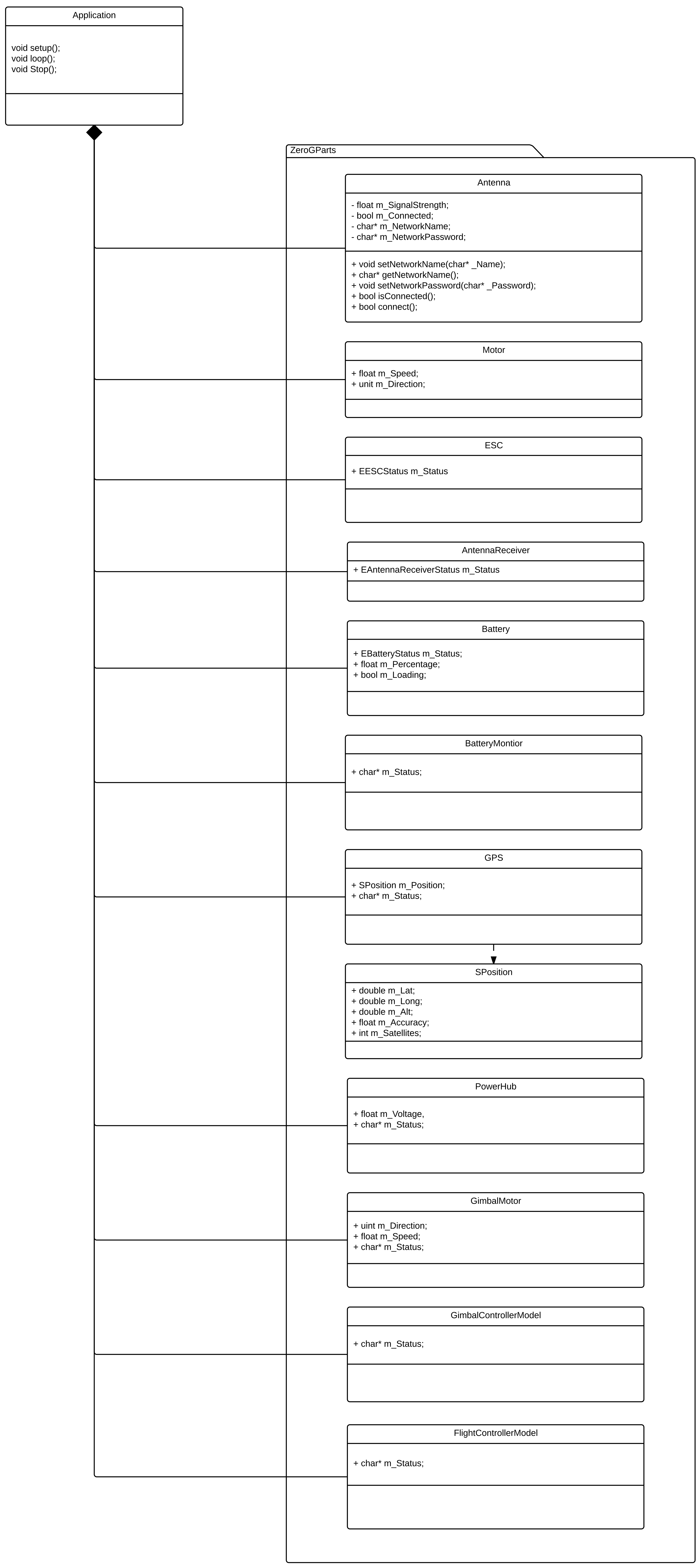

Application

```
void setup();
void loop();
void Stop();
```

ZeroGParts

Antenna

```
- float m_SignalStrength;
- bool m_Connected;
- char* m_NetworkName;
- char* m_NetworkPassword;
```

```
+ void setNetworkName(char* _Name);
+ char* getNetworkName();
+ void setNetworkPassword(char* _Password);
+ bool isConnected();
+ bool connect();
```

Motor

```
+ float m_Speed;
+ unit m_Direction;
```

ESC

```
+ EESCStatus m_Status
```

AntennaReceiver

```
+ EAntennaReceiverStatus m_Status
```

Battery

```
+ EBatteryStatus m_Status;
+ float m_Percentage;
+ bool m_Loading;
```

BatteryMontior

```
+ char* m_Status;
```

GPS

```
+ SPosition m_Position;
+ char* m_Status;
```

SPosition

```
+ double m_Lat;
+ double m_Long;
+ double m_Alt;
+ float m_Accuracy;
+ int m_Satellites;
```

PowerHub

```
+ float m_Voltage,
+ char* m_Status;
```

GimbalMotor

```
+ uint m_Direction;
+ float m_Speed;
+ char* m_Status;
```

GimbalControllerModel

```
+ char* m_Status;
```

FlightControllerModel

```
+ char* m_Status;
```