Cheat Sheet: AI Models for NLP

Package/Method	Description	Code example
PyTorch/Embedding and EmbeddingBag	Embedding is a class that represents an embedding layer. It accepts token indices and produces embedding vectors. EmbeddingBag is a class that aggregates embeddings using mean or sum operations. EmbeddingBag are part of the torch.nn module. The code example shows how you can use Embedding and EmbeddingBag in PyTorch.	<pre># Defining a data set dataset = ["1 like cats", "1 hate dogs", "1 hate dogs", "1 mimpartial to hippos" "1 mimpartial to hippos" "1 mimpartial to hippos" "1 mimpartial to hippos" "1 for data sample in data iter: yield tokens(data_letr): for data_sample in data_iter: yield tokens(data_letr): for data_sample in data_sample) data_iter = iter(dataset) vocab = build vocab_from_iterator(yield_tokens(data_iter)) #Tokenizing and generating indices input_ids=lambda_si[torch.tensor(vocab(tokenizer(data_sample))) for data_sample in dataset] index=input_ids=lambda_si[torch.tensor(vocab(tokenizer(data_sample))) for data_sample in dataset] index=input_ids=lambda_si[torch.tensor(vocab(tokenizer(data_sample))) for data_sample in dataset] index=input_ids=lambdding_layer.pecifying the dimension size for the embeddings, #determining the embedding layer, specifying the dimension size for the embeddings, #determining the embedding layer, specifying the dimension size for the embedding layer embedding = len(vocab) n_embedding =</pre>
Batch function	Defines the number of samples that will be propagated through the network.	<pre>def collate_batch(batch): target_list, context_list, offsets = [], [], [0] for _context, _target in batch: target_list.append(vocab[_target]) processed_context = torch.tensor(text_pipeline(_context), dtype=torch.int64) context_list.append(processed_context) offsets.append(processed_context.size(0)) target_list = torch.tensor(target_list, dtype=torch.int64) offsets = torch.tensor(offsets[:-1]).cumsum(dim=0) context_list = torch.cat(context_list) return target_list.to(device), context_list.to(device), offsets.to(device) BATCH_SIZE = 64 # batch size for training dataloader_cbow = DataLoader(cobw_data, batch_size=BATCH_SIZE, shuffle=True, collate_fn=collate_batch</pre>
Forward pass	Refers to the computation and storage of intermediate variables (including outputs) for a neural network in order from the input to the output layer.	<pre>def forward(self, text):</pre>
	Leverages large-scale data for word embeddings. It	<pre>from torchtext.vocab import GloVe,vocab # Creating an instance of the 6B version of Glove() model glove_vectors_6B = GloVe(name = '6B') # you can specify the model with the following format: GloVe(nam # Build vocab from glove_vectors vocab = vocab(glove_vectors_6B.stoi, 0,specials=('<unk>', '<pad>')) vocab.set_default_index(vocab["<unk>"])</unk></pad></unk></pre>

Stanford's pre- trained GloVe	can be integrated into PyTorch for improved NLP tasks such as classification.	
vocab	The vocab object is part of the PyTorch torchtext library. It maps tokens to indices. The code example shows how you can apply the vocab object to tokens directly.	<pre># Takes an iterator as input and extracts the next tokenized sentence. Creates a list of token indice def get_tokenized_sentence_and_indices(iterator): tokenized_sentence = next(iterator) token_indices = [vocab[token] for token in tokenized_sentence] return tokenized_sentence, token_indices # Returns the tokenized sentences and the corresponding token indices. Repeats the process. tokenized_sentence, token_indices = get_tokenized_sentence_and_indices(my_iterator) next(my_iterator) # Prints the tokenized sentence and its corresponding token indices. print("Tokenized Sentence:", tokenized_sentence) print("Token Indices:", token_indices)</pre>
Special tokens in PyTorch: <eos> and <bos></bos></eos>	Tokens introduced to input sequences to convey specific information or serve a particular purpose during training. The code example shows the use of bos> and <eos> during tokenization. The <bos> token denotes the beginning of the input sequence, and the <eos> token denotes the end.</eos></bos></eos>	<pre># Appends <bos> at the beginning and <eos> at the end of the tokenized sentences # using a loop that iterates over the sentences in the input data tokenizer_en = get_tokenizer('spacy', language='en_core_web_sm') tokens = [] max_length = 0 for line in lines: tokenized_line = tokenizer_en(line) tokenized_line = ['<bos>'] + tokenized_line + ['<eos>'] tokens.append(tokenized_line) max_length = max(max_length, len(tokenized_line))</eos></bos></eos></bos></pre>
Special tokens in PyTorch: <pad></pad>	Tokens introduced to input sequences to convey specific information or serve a particular purpose during training. The code example shows the use of <pad> token to ensure all sentences have the same length.</pad>	<pre># Pads the tokenized lines for i in range(len(tokens)): tokens[i] = tokens[i] + ['<pad>'] * (max_length - len(tokens[i]))</pad></pre>
Cross entropy loss	A metric used in machine learning (ML) to evaluate the performance of a classification model. The loss is measured as the probability value between 0 (perfect model) and 1. Typically, the aim is to bring the model as close to 0 as possible.	<pre>from torch.nn import CrossEntropyLoss model = TextClassificationModel(vocab_size,emsize,num_class) loss fn = CrossEntropyLoss() predicted_label = model(text, offsets) loss = criterion(predicted_label, label)</pre>

Optimization	Method to reduce losses in a model.	<pre>optimizer = torch.optim.SGD(model.parameters(), lr=0.1) scheduler = torch.optim.lr_scheduler.StepLR(optimizer, 1.0, gamma=0.1) optimizer.zero_grad() predicted_label = model(text, offsets) loss = criterion(predicted_label, label) loss.backward() torch.nn.utils.clip_grad_norm_(model.parameters(), 0.1) optimizer.step()</pre>
sentence_bleu()	NLTK (or Natural Language Toolkit) provides this function to evaluate a hypothesis sentence against one or more reference sentences. The reference sentences must be presented as a list of sentences where each reference is a list of tokens.	<pre>from nltk.translate.bleu_score import sentence_bleu def calculate_bleu_score(generated_translation, reference_translations): # Convert the generated translations and reference translations into the expected format for sentence references = [reference.split() for reference in reference_translations] hypothesis = generated_translation.split() # Calculate the BLEU score bleu_score = sentence_bleu(references, hypothesis) return bleu_score reference_translations = ["Asian man sweeping the walkway .", "An asian man sweeping the walkway .", "Ableu_score = calculate_bleu_score(generated_translation, reference_translations)</pre>
Encoder RNN model	The encoder-decoder seq2seq model works together to transform an input sequence into an output sequence. Encoder is a series of RNNs that process the input sequence individually, passing their hidden states to their next RNN.	<pre>class Encoder(nn.Module): definit(self, vocab_len, emb_dim, hid_dim, n_layers, dropout_prob): super()init() self.hid_dim = hid_dim self.n_layers = n_layers self.embedding = nn.Embedding(vocab_len, emb_dim) self.lstm = nn.LSTM(emb_dim, hid_dim, n_layers, dropout = dropout_prob) self.dropout = nn.Dropout(dropout_prob) def forward(self, input_batch): embed = self.dropout(self.embedding(input_batch)) embed = embed.to(device) outputs, (hidden, cell) = self.lstm(embed) return hidden, cell</pre>
Decoder RNN model	The encoder-decoder seq2seq model works together to transform an input sequence into an output sequence. The decoder module is a series of RNNs that autoregressively generates the translation as one token at a time. Each generated token goes back into the next RNN along with the hidden state to generate the next token of the output sequence until the end token is generated.	<pre>class Decoder(nn.Module): definit(self, output_dim, emb_dim, hid_dim, n_layers, dropout): super()init() self.output_dim = output_dim self.hid_dim = hid_dim self.hid_dim = hid_dim self.n_layers = n_layers self.embedding = nn.Embedding(output_dim, emb_dim) self.lstm = nn.LSTM(emb_dim, hid_dim, n_layers, dropout = dropout) self.fc_out = nn.Linear(hid_dim, output_dim) self.softmax = nn.Logsoftmax(dim=1) self.dropout = nn.Dropout(dropout) def forward(self, input, hidden, cell): input = input.unsqueeze(0) embedded = self.dropout(self.embedding(input)) output, (hidden, cell) = self.lstm(embedded, (hidden, cell)) prediction_logit = self.softmax(prediction_logit) return prediction, hidden, cell</pre>

```
class SkipGram Model(nn.Module):
                                                           _init__(self, vocab_size, embed_dim):
                                                    super(SkipGram_Model, self).__init__()
                                                    # Define the embeddings layer
                                                    self.embeddings = nn.Embedding(num_embeddings=vocab_size, embedding_dim=embed_dim)
                                                   # Define the fully connected layer
self.fc = nn.Linear(in_features=embed_dim, out_features=vocab_size)
                                                    # Perform the forward pass
                                                   def forward(self, text):
# Pass the input text through the embeddings layer
                                                    out = self.embeddings(text)
                                                   # Pass the output of the embeddings layer through the fully connected layer # Apply the ReLU activation function out = torch.relu(out) out = self.fc(out)
                         Predicts
                         surrounding
                                                    return out
model_sg = SkipGram_Model(vocab_size, emsize).to(device)
                         context words
                         from a specific
                                                    # Sequence generation function
Skip-gram model
                         target word. It
                                                    CONTEXT SIZE = 2
                        predicts one
                                                    skip_data = []
                                                    for i in range(CONTEXT_SIZE, len(tokenized_toy_data) - CONTEXT_SIZE):
                        context word at
                                                         context =
                        a time from a
                                                         [tokenized_toy_data[i - j - 1] for j in range(CONTEXT_SIZE)] # Preceding words
+ [tokenized_toy_data[i + j + 1] for j in range(CONTEXT_SIZE)] # Succeeding words)
                        target word.
                                                    target = tokenized_toy_data[i]
    skip_data.append((target, context))
skip_data=[('i', ['wish', 'i', 'was', 'little']), ('was', ['i', 'wish', 'little', 'bit'])],...
                                                   def collate fn(batch):
                                                         target_list, context_list = [], []
                                                         for _context, _target in batch:
                                                              _context, _target in bacch.
target_list.append(vocab[_target])
context_list.append(vocab[_context])
                                                         target_list = torch.tensor(target_list, dtype=torch.int64)
context_list = torch.tensor(context_list, dtype=torch.int64)
return target_list.to(device), context_list.to(device)
                         Processes the
                         list of samples
                         to form a batch.
collate_fn
                         The batch
                         argument is a
                         list of all your
                         samples.
                                                    def train_model(model, dataloader, criterion, optimizer, num_epochs=1000):
                                                    # List to store running loss for each epoch
                                                    epoch_losses = []
                                                    for epoch in tqdm(range(num_epochs)):
                                                    # Storing running loss values for the current epoch running_loss = 0.0
# Using tqdm for a progress bar
                                                    for idx, samples in enumerate(dataloader):
                         Trains the
                                                    optimizer.zero_grad()
                         model for a
                                                    # Check for EmbeddingBag layer in the model CBOW
                         specified
                                                    if any(isinstance(module, nn.EmbeddingBag) for _, module in model.named_modules()):
                        number of
                                                    target, context, offsets = samples
                        epochs. It also
                                                    predicted = model(context, offsets)
# Check for Embedding layer in the model skip gram
                        includes a
                                                    elif any(isinstance(module, nn.Embedding) for _, module in model.named_modules()):
                         condition to
                                                    target, context = samples
                         check whether
                                                    predicted = model(context)
                         the input is for
                                                    loss = criterion(predicted, target)
Training function
                         skip-gram or
                                                    loss.backward()
                                                    torch.nn.utils.clip_grad_norm_(model.parameters(), 0.1)
                         CBOW. The
                                                    optimizer.step()
running_loss += loss.item()
                         output of this
                         function
                                                    # Append average loss for the epoch
                         includes the
                                                    epoch_losses.append(running_loss / len(dataloader))
                         trained model
                                                    return model, epoch_losses
                         and a list of
                         average losses
                         for each epoch.
                                                    class CBOW(nn.Module):
                                                    # Initialize the CBOW model
                                                    def __init__(self, vocab_size, embed_dim, num_class):
    super(CBOW, self).__init__()
# Define the embedding layer using nn.EmbeddingBag
                                                    self.embedding = nn.EmbeddingBag(vocab_size, embed_dim, sparse=False)
                                                    # Define the fully connected layer
                                                    self.fc = nn.Linear(embed_dim, vocab_size)
```

CBOW model	Utilizes context words to predict a target word and generate its embedding.	<pre>def forward(self, text, offsets): # Pass the input text and offsets through the embedding layer out = self.embedding(text, offsets) # Apply the ReLU activation function to the output of the first linear layer out = torch.relu(out) # Pass the output of the ReLU activation through the fully connected layer return self.fc(out) vocab_size = len(vocab) emsize = 24 model_cbow = CBOW(vocab_size, emsize, vocab_size).to(device)</pre>
Training loop	Enumerates data from the DataLoader and, on each pass of the loop, gets a batch of training data from the DataLoader, zeros the optimizer's gradients, and performs an inference (gets predictions from the model for an input batch).	<pre>for epoch in tqdm(range(1, EPOCHS + 1)): model.train() cum_loss=0 for idx, (label, text, offsets) in enumerate(train_dataloader): optimizer.zero_grad() predicted_label = model(text, offsets) loss = criterion(predicted_label, label) loss.backward() torch.nn.utils.clip_grad_norm_(model.parameters(), 0.1) optimizer.step() cum_loss+loss.item() cum_loss list.append(cum_loss) accu_val = evaluate(valid_dataloader) acc_epoch.append(accu_val) if accu_val > acc_old: acc_old= accu_val torch.save(model.state_dict(), 'my_model.pth')</pre>

