





TTM-210

DIGITAL CONTROLLER



TTM-214



TTM-215



TTM-217



TTM-219

CONTROLLER TTM-210

Features

Controllability is improved with the New PID Algorithm

- 1) The time it takes from the control start until it is stabilized has been
- ②The jump-less control function which controls the occurrence of overshoot after the disturbance has been incorporated.
 ③3-kinds of PID control is selectable.

Full multiple input

With just one unit, it can accommodate different types of input such as thermocouples (13 types), platinum resistance temperature sensor (2 types), voltage (5 types), current (1 type).

Sampling cycle

Speed-up to 200mS has been realized.

A liquid crystal display has been incorporated for the display

①The indication range has been extended to 5-digit display. ②Realization of various indications with 11 segment display. ③LED is used for the back-light.

PV indication auto-change

The Process value (PV) display condition can be set at Lighting, Flashing (high speed), Flashing (low speed), relative to the set value (SV).

The TTM-210 series is made compact with depth of 59.7 mm (for TTM-214), 65 mm (for TTM-215, 217, 219). Moreover, the protrusive portion for the panel side attachment is only 2 mm. (TTM-214: 2.5mm)

Loader communication function

This function is most appropriate for the set-up work of the parameters. Cable: optional (sold separately)
Software: optional (provided free-of-charge downloadable from our

Extensive output type Relay contact, SSR drive, open collector, voltage (5 types) and current.

Enhanced optional function

①CT input (max. of 2-points), ②Event input (max. of 4-points), ③Event output (max. of 7-points, however, when all 7-points are used, the control output will not be available for use)

●External standards (TTM-214 only)

Conforms to CE markings
UL, c-UL markings have been acquired.

*TTM-215/217/219 Pending application

Protection structure (TTM-214 only)

Corresponds to "IP66".

Valve position proportionality control

A function has been incorporated enabling the unit to carry out valve position proportionality control without the feedback resistance.

Blind function

The system can be configured so that only the specific parameters are displayed from the set of parameters.

Simplified programmable controlling function

A max. of 8-step program control is possible.

Simple timer function (3-point stand-alone)

A control of "Control start or stop after a lapse of certain time" is possible with a single unit. An independent use as a timer (event output ON/OFF) is possible.

Priority screen

Indication/Setting is possible without shifting to parameter screen by indicating the necessary parameter screen with operation mode screen. (max. 16 screens)

Digital PV filter

A filter can be applied with software in response to sudden changes of input value.

Manual control

Manual output function will enable the application of various instrumentation systems.

● Communication function (RS485: Dedicated protocol / MODBUS)

A communication distance can be extended to a maximum of 500 meters, and up to 31 units can be connected simultaneously. With one host computer, a centralized monitoring such as "collection of all data", "changes of various setting value" is possible from a distant

Soft-start function

During the PID control mode, in the READY→RUN mode (or when the power is turned ON), a limit can be applied for a certain period of time to the operation volume.

Delay timer (available during ON/OFF control only)

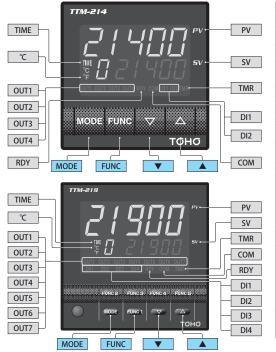
During ON/OFF control, the minimum duration time can be set independently for ON & OFF regardless of the control. This function is useful for any equipment which is not suited for frequent ON/OFF switching, or may be used as protection for the freezing equipment.

This function monitors the measured value and operation volume, and detects the abnormality in the control loop.

■Bank automatic switching function

This is a function which switches the bank automatically according to the input value (PV, SV). It optimizes the control parameters.

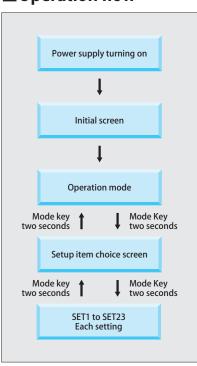
Front Panel



OUT1	Output1 monitor (appears during output)
OUT2	Output2 monitor (appears during output)
OUT3	Output3 monitor (appears during output)
OUT4	Output4 monitor (appears during output)
OUT5	Output5 monitor (appears during output)
OUT6	Output6 monitor (appears during output)
OUT7	Output7 monitor (appears during output)
RDY	RDY lamp (It appears in the state of Ready)
COM	COM lamp (It blinks during communication)
DI1	DI1 monitor (It appears when DI1 operates)
DI2	DI2 monitor (It appears when DI2 operates)
DI3	DI3 monitor (It appears when DI3 operates)
DI4	DI4 monitor (It appears when DI4 operates)
TMR	TIMER lamp (It appears when timer operates)
TIME	Appears when the setting is at "Timer".
°C /°F	It appears when the setting is at "Temperature".
PV	Measured value indication, Character indication, Timer set-up time indication
SV	Set value indication, Operation quantity indication, Timer remaining time indication
MODE	Mode key It is used when changing a screen.
FUNC	Function key It executes functions that are already set.
A	Up key It is used when making a setting value increase It is used when changing input setting mode
•	Down Key It is used when making a setting value decrease It is used when changing parameter screen
%OUT6 is no	ot available for TTM-217

*OUT6 is not available for TTM-217.

■Operation flow





■Standard specifications

Input type	Thermocouple		L, WRe5-26, PR40-20, PL			
	RTD Current/voltage				ires must have the same resistance)] VDC, 0 to 10VDC, 0 to 10mVDC (input resistance $1M\Omega$ or more)	
Display (LCD)	PV/character display) backlight, luminous co		vbc, o to rovbc, o to romvbc (input resistance rivitz or more)	
Display (ECD)	1 Tycharacter display	TTM-214/215 5-digits, character height 10mm				
		TTM-217 5-digits, character height 13mm				
	CM/settles disclar	TTM-219 5- digits, character height 20mm LCD display (with LED backlight, luminous color is Green)				
	SV/setting display	1 7 7				
		TTM-217 5-digits, character height 8mm TTM-219 5- digits, character height 10mm				
	Aux. display portion		backlight, luminous co			
		TTM-214/215 5-digits, character height 7mm TTM-217 5-digits, character height 8mm TTM-219 5- digits, character height 10mm				
	Various displays				DI1, DI2, DI3, DI4, TMR) Item displayed changes depending on their size.	
Control	PID	Proportional band (P1		0.1 to 200.0% of set	<u> </u>	
	(with auto-tuning) (with self-tuning)	Proportional band Ol	Proportional band OUT2 side (P2) 0.10 to 10.00 times (with respect to the main control proportional band)			
	(with sen-tuning)	Integral time (I)		0 to 3600 seconds (i	ntegral action OFF at "0")	
		Differential time (D)			lifferential action OFF at "0")	
		Proportion cycle (T1,	T2)	0.1 to 120.0 seconds		
		Dead band (DB)		Temperature input	-999.9 to 999.9 or -999 to 999 (°C)	
	ON/OFF	Cantual cancitivity (C	1. (2)	Analog input	-9999 to 9999 (digits) (decimal point position is specified position)	
	ON/OFF	Control sensitivity (C1	1, (2)	Temperature input Analog input	0.0 to 999.9 or 0 to 999 (°C) 0 to 9999 (digits) (decimal point position is specified position)	
	Output 1/2 OFF point	Position selection set	tina	SV unit setting High		
	output 1/2 of 1 point	Position setting	ung	Temperature input		
				Analog input	-9999 to 9999 (digits) (decimal point position is specified position)	
Control output	Relay contact	250VAC 3A (resistance	e load) 1a contact poin			
	SSR driving voltage	0 to 12VDC (load resis	<u>.</u>			
	Open collector	26.4VDC 100mA				
	Current		esistance 600Ω or less)			
	Voltage				nce 1K Ω or more), 1 to 5VDC (load resistance 1K Ω or more)	
			stance 1KΩ or more), 0	to 10mV DC (load resis	tance 500KΩ or more)	
Sampling cycle		0.2 seconds		T. (2-2)		
Setting & instruction accuracy	Thermocouple	K, J, T, E, R, S, B, N		±(0.3% + 1 digit) of However, ±3°C bety	the instruction value or $\pm 2^\circ$ C whichever is bigger (23°C $\pm 10^\circ$ C) ween -100° C to 0° C, $\pm 4^\circ$ C between -200 to -100° C. No stipulation below 400° C	
(At ambient temp. 23℃				However, ± 3 C between -100 C to 0 C, ± 4 C between -200 to -100 C. No stipulation below 400 lin B-thermocouple.		
±10℃)		U, L		±(0.3% + 1 digit) of	the instruction value or $\pm 4^\circ\!C$ whichever is bigger (23 $^\circ\!C\!\pm\!10^\circ\!C$). $\pm 6^\circ\!C$ below 0 $^\circ\!C$.	
		WRe5-26			the instruction value or $\pm 4^{\circ}\text{C}$ whichever is bigger (23°C $\pm 10^{\circ}\text{C}$).	
		PR40-20			accuracy stipulation below 800°C .	
		PLII		$\pm (0.3\% + 1 \text{ digit})$ of the instruction value or $\pm 2^{\circ}\text{C}$ whichever is bigger		
	RTD	Pt100, JPt100			the instruction value or ±0.9°C whichever is bigger (23°C±10°C)	
	Current/voltage	0 to 1VDC, 0 to 5VDC 1 to 5VDC, 0 to 10VDC	Σ.	±0.3%±1 digit (23	$C\pm 10^{\circ}C$) of the set limiter span	
		4 to 20mA DC				
Memory element		EEPROM				
Input power supply			%, +10%) 50/60Hz, AC/			
Weight			FM-215: 210gms., TTM-2		-	
Power consumption Accessories			manual and attachmen) TTM-215/217/219: 100 to 240VAC (less than 11VA), AC/DC 24V (less than 5W)	
Standard ambient temp. & hu	ımidity range	23°C±10°C , 45 to 75°		iii.		
(warranty range such as accur	racy)	· ·				
Usable ambient temp. & hum	· · ·	0 to 50°C, 20 to 85%				
Storage ambinet temp. & hun			reezing, non-condensir	3	3.	
Function	Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2)	Upper limit (MLH1, M	LH2)	Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%)	
	(METT) MEET, METZ, MEEZ,	Lauran limit (MILL 1 MI	11.2)	Analog output	MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%)	
		Lower limit (MLL1, MLL2)		Digital output		
				Analog output		
	UP/DOWN setting of manipulated	0.0 to 549.9 (%) (Fund	tion OFF with 0 0% cott	Analog output	-10.0 to MLH1 (%), -10.0 to MLH2 (%)	
	UP/DOWN setting of manipulated variable change ratio limiter	0.0 to 549.9 (%) (Fund	tion OFF with 0.0% sett			
	variable change ratio limiter Manipulated variable setting in time of	Digital output	0.0 to 100.0 (%)			
	variable change ratio limiter Manipulated variable setting in time of malfunction	Digital output Analog output		ting)	-10.0 to MLH1 (%), -10.0 to MLH2 (%)	
	variable change ratio limiter Manipulated variable setting in time of	Digital output	0.0 to 100.0 (%)	Temperature input	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C°C	
	variable change ratio limiter Manipulated variable setting in time of malfunction	Digital output Analog output Upper limit (SLH)	0.0 to 100.0 (%)	Temperature input Analog input	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C*(SLL+50) to SV setting range upper limit (digit)	
	variable change ratio limiter Manipulated variable setting in time of malfunction	Digital output Analog output	0.0 to 100.0 (%)	Temperature input Analog input Temperature input	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C'(SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5.0) ("V	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH)	Digital output Analog output Upper limit (SLH) Lower limit (SLL)	0.0 to 100.0 (%) -10.0 to 110.0 (%)	Temperature input Analog input Temperature input Analog input Analog input	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C'(SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) ('V') SV setting range lower limit to (SLH-5.0) (digit)	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control	0.0 to 100.0 (%) -10.0 to 110.0 (%)	Temperature input Analog input Temperature input Analog input Analog input mer 1 operation, timer	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C°C (SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5.0) (°C	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH)	Digital output Analog output Upper limit (SLH) Lower limit (SLL)	0.0 to 100.0 (%) -10.0 to 110.0 (%)	Temperature input Analog input Temperature input Analog input Analog input Analog input	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C'(SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) ('V') SV setting range lower limit to (SLH-5.0) (digit)	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control	0.0 to 100.0 (%) -10.0 to 110.0 (%) start, manual control, ti Type A (normal PID or Type B (over-shoot su	Temperature input Analog input Temperature input Analog input Analog input Analog input	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C'(SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5.0) (digit) SV setting range lower limit to (SLH-50) (digit) 2 operation, timer 3 operation	
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	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting	start, manual control, ti Type A (normal PID c. Type B (over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Feverse action Normal action Primary auto-tuning Primary self-tuning (6 Secondary self-tuning [6 Secondary auto-tuning Secondary self-tuning [6	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer ontrol) urbance suppression function) urbance suppression function on: weak on: medium ion: strong (Primary PID/during por ng (Primary PID/during por)	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C ¹) (SLL+5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) (¹) SV setting range lower limit to (SLH-5.0) (digit) 2 operation, timer 3 operation setting range lower limit to (SLH-5.0) (digit) consistent of the setting range lower limit to (SLH-5.0) (digit) consistent of the setting range upper limit (C ²) SV setting range lower limit to (SLH-5.0), SV setting range upper limit (C ²) SV setting range lower limit to (SLH-5.0), (digit) consistent of the setting range upper limit (C ²) SV setting range upper limit (digit) SV setting range upper limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range lower limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range lower limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range upper limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range upper limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range upper limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range upper limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range upper limit to (SLH-5.0), SV setting range upper limit to (SLH-5.0) SV setting range upper limit to (SLH-5.0), SV setting r	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting (MV1G, MV2G)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting 0.0 to 1000.0 (%)	start, manual control, ti Type A (normal PID c. Type B (over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Feverse action Normal action Primary auto-tuning Primary self-tuning (6 Secondary self-tuning [6 Secondary auto-tuning Secondary self-tuning [6	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer ontrol) uppression function) urbance suppression fu non: weak on: medium on: strong (Primary PID/during po rg (Primary PID/during po rg (Primary PID/during go rg	CSLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (CN (SLL+5.0) to SV setting range upper limit (digit)	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting 0.0 to 1000.0 (%) Temperature input	start, manual control, ti Type A (normal PID c. Type B (over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Feverse action Normal action Primary auto-tuning Primary self-tuning (6 Secondary self-tuning [6 Secondary auto-tuning Secondary self-tuning [6	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer outportsion function) urbance suppression function) urbance suppression function urbance suppression urbance	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C ⁰ (SLL+5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) (³ SV setting range lower limit to (SLH-5.0) (digit) 2 operation, timer 3 operation setting range lower limit to (SLH-5.0) (digit) 10 operation 10 oper	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction 0-point setting (PVS)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting U.O. to 1000.0 (%) Temperature input Analog input	start, manual control, ti Type A (normal PID c. Type B (over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Feverse action Normal action Primary auto-tuning Primary self-tuning (f Secondary self-tuning Primary/secondary auto-tuning Primary/secondary auto-tuning	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer ontrol) uppression function) urbance suppression fu non: weak on: medium on: strong (Primary PID/during po rg (Primary PID/during po rg (Primary PID/during go rg	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C°C (SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) (°C (SLL+50) to SV setting range lower limit to (SLH-5) (digit) 2 operation, timer 3 operation SV setting range lower limit to (SLH-50) (digit) 2 operation, timer 3 operation Successive the setting range upper limit (C°C (SLH-50), SV setting range lower limit to (SLH-5) (°C (SLH-50), SV setting range upper limit (C°C (SLH-50), SV setting range upper limit (GSLH-50), SV setting range upper limit (C°C (SLH-50), SV setting range upper limit (C°C (SLH-50), SV setting range upper limit (GSLH-50), SV setting range upper lim	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction 0-point setting (PVS) PV correction Gain setting (PVG)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting U.O. to 1000.0 (%) Temperature input Analog input 0.500 to 2.000 (times)	start, manual control, ti Type A (normal PID c. Type B (over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Feverse action Normal action Primary auto-tuning Primary self-tuning (f Secondary self-tuning Primary/secondary auto-tuning Primary/secondary auto-tuning	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer outportsion function) urbance suppression function) urbance suppression function urbance suppression urbance	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C°C (SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) (°C (SLH-50)) to SV setting range lower limit to (SLH-5.0) (digit) 2 operation, timer 3 operation (SLH-50) (digit) 2 operation, timer 3 operation (SLH-50) (digit) 3 operation (SLH-50) (digit) (digit) (SLH-50) (digit) (SLH-50) (digit) (digi	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction 0-point setting (PVS)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input O.500 to 2.000 (times) 0.0 to 99.9 (seconds)	start, manual control, ti Type A (normal PID c. Type B (over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Over-shoot suppessic Feverse action Normal action Primary auto-tuning Primary self-tuning (f Secondary self-tuning Primary/secondary auto-tuning Primary/secondary auto-tuning	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer ontrol) uppression function) urbance suppression fu non: weak on: medium on: strong (Primary PID/during po primary PID/during po ng (Primary PID/during po ng (Pri	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C°C (SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) (°C (SV setting range lower limit to (SLH-50) (digit) 2 operation, timer 3 operation (SLH-50) (digit) 2 operation, timer 3 operation (SLH-50) (digit) 3 operation (SLH-50) (digit) (digit) (SLH-50) (digit) (digit	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction 0-point setting (PVS) PV correction Gain setting (PVG) PV input filter (PDF)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input 0.500 to 2.000 (times) 0.0 to 110.0 (%) (func) 0.0 to 10.0 (%) (func)	start, manual control, ti Type A (normal PID or Type B (over-shoot su Type C (external distu Over-shoot suppessic Over-shoot suppession Over-shoot	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer outportsion function) urbance suppression function) urbance suppression function urbance suppression urbanc	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C°C (SLL+5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) (°C (SLH-5.0)), SV setting range lower limit to (SLH-5.0) (digit) 2 operation, timer 3 operation SV setting range lower limit to (SLH-5.0) (digit) 2 operation, timer 3 operation Successive the setting range upper limit (C°C (SLH-5.0), SV setting range upper limit (G°C (SLH-5.0), SV settin	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction 0-point setting (PVS) PV correction Gain setting (PVG) PV input filter (PDF) Anti-reset wind up Manual reset (PBB)	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input 0.500 to 2.000 (times) 0.0 to 110.0 (%) (func) 0.0 to 100.0 (%) (if the 0.0 to 100.0 (%).	start, manual control, ti Type A (normal PID co Type B (over-shoot suppressi Over-shoot suppressi Over-shoot suppressi Reverse action Primary auto-tuning Primary self-tuning (F Secondary auto-tuning Primary self-tuning	Temperature input Analog input Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer ontrol) urbance suppression function) urbance suppression function urbance suppression function in weak on: medium on: strong (Primary PID/during po primary PID/during po g (Primary PID/during po g (Primary PID/during po g (Primary PID/during po g (Primary PID/during) g (Primary PID/during) g (Trimary PID/during) uto-tuning (Primary PID — 9999 to 9999 (digi	CSLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C'G (SLL+5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5.0) (digit) SV setting range lower limit to (SLH-5.0) (digit) SV setting range lower limit to (SLH-5.0) (digit) Coperation, timer 3 operation Strict	
	variable change ratio limiter Manipulated variable setting in time of malfunction Set limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction 0-point setting (PVS) PV correction Gain setting (PVG) PV input filter (PDF) Anti-reset wind up	Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control: PID type Type B mode Normal / reverse action setting Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input Analog input 0.500 to 2.000 (times) 0.0 to 190.9 (seconds) 0.0 to 110.0 (%) (func) 0.0 to 100.0 (%) (func) 0.0 to 100.0 (%) (func) 0.0 to 100.0 (%)	start, manual control, ti Type A (normal PID or Type B (over-shoot su Type C (external distu Over-shoot suppessic Over-shoot suppession Over-shoot	Temperature input Analog input Temperature input Analog input Temperature input Analog input mer 1 operation, timer on propersion function) urbance suppression function) urbance suppression function urbance suppression urba	-10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL+5.0) to SV setting range upper limit, (SLL+5) to SV setting range upper limit (C°C (SLL+50) to SV setting range upper limit (digit) SV setting range lower limit to (SLH-5.0), SV setting range lower limit to (SLH-5) (°C (SV setting range lower limit to (SLH-50) (digit) 2 operation, timer 3 operation (SLH-50) (digit) 2 operation, timer 3 operation (SLH-50) (digit) 3 operation (SLH-50) (digit) (digit) (SLH-50) (digit) (digit	

■ Standard specifications (Continued)

Function	Timer driving mode (TMF)	Three points. 0 min. 00 sec to 99 min. 59 sec. Accuracy: ±(1.5%+0.5 sec.) of the set time Function: auto-start, manual start, event st		repetition: 0 to 99 times (unlimited times at 0)	
	Delay timer (FDT)	0 to 99 (min.). Primary/secondary control common.			
	Decimal point shifting (DP)	Indication below decimal point: with/without			
	Manual control	Manual control is possible (balance-less, but	ump-less)		
	RUN/READY	Switching of RUN/READY is possible			
	Blind function	Any of the parameter screen can be set to	non-display mode.		
	Auto-tuning coefficient (ATG)	0.1 to 10.0 (times)			
	Auto-tuning sensitivity (ATC)	Temperature input	0.0 to 999.9 or 0 to 99	99 (℃)	
		Analog input	0 to 9999 (digit)		
	Function key	program mode: program start/stop", "AT st	tart/AT stop", "timer sta	on type setting • • • fixed value operation mode: control mode (MD)/control stop (RdY)/ rt/rest", "screen backward", "ENT", "bank switching", "MD/MANUAL", "SV/MV screen ", "step forward", "pause", "SET22 recall function (SET22 shortcut function)". Press time	
	Priority screen	Any of the parameter screen can be indicated on the operation mode screen (max. 16-points)			
	Lock function (LOC)	8 modes [OFF, ALL lock, operation mode lock, lock except operation mode, ALL lock (RUN only), operation mode lock (RUN only), lock except operation mode (RUN only), set lock (RUN only)]			
	Self-diagnostic function	EEPROM data check (Err0), A/D converter a	ction check (Err1), auto	-tuning check (Err2), built-in watchdog timer.	
	Ramp function	Action	It sets the SV variance	per minute when the SV is changed.	
		Setting range	Temperature input	0.0 to 999.9 (°C /min.) (ramp function OFF at 0.0)	
			Analog input	0 to 9999 (digit/min.) (ramp function OFF at 0)	
		Setting unit	Temperature input	0.1℃ /min.	
			Analog input	1 digit/min.	
	Valve function	Motor stroke time	0.1 to 999.9 (sec.)		
		Motor drive dead band 0.0 to 100.0 (sec.)			
	Default setting mode	Password setting, blind screen temporary in This mode requires password. Make sure t	recall setting, set value o take note of the pass	back-up, set value initialization. word.	
	Bank setting	Parameter can be set from SET 1 to 23 (max	x. 16-points)		
	Soft-start (primary control)	Output setting	MLL1 to MLH1 (%)		
		Time setting	00:00 to 499.59 (min.	: sec.) Function OFF with 00:00 (min.: sec.) setting	
	Programmed operation function	Max. 8-steps. Execution condition 3-kinds	step, soak 1 & 2). Powe	r failue guarantee function.	
	Bank automatic switching function	Max. 8-zones switching. Input type 3-kinds	(SV, Ramp SV, PV)		

■Option specifications

Auxiliary Output	Relay contact	250VAC 1A (resistan	ce load) 1a contact poir	nt Min. load 5VDC 100mA	
(Max. 5-points)	Open collector	26.4VDC 100mA			
	Setting range (Upper and Lower	Temperature input	-1999.9 to 2999.9、-	−1999 to 2999 (°C)	
	limit)	Analog input	-19999 to 29999 (dig	git)	
	Sensitivity	Temperature input 0.0 to 999.9, 0 to 999 (°C)			
		Analog input	0 to 9999 (digit)		
	Delay timer	0 to 9999 (seconds)			
DI Input (Max. 4-points)	Functions	START (at closed cor	itact point: START), Time	e MD/READY (at closed contact point: R : MANUAL), Reverse Operation / Norma er STOP/START (at closed contact point ing during program mode, pause. Intel	EADY), at program mode START/STOP (at closed contact point: STOP), AUTO/ i Operation (at closed contact point: NORMAL OPERATION), Auto-Tuning STOP/ : START), Constant Operation Mode / Program Mode (at closed contact point: clock at open contact point.
	Input specification	No voltage contact p	point. Active switching i	is possible at the time of the input.	
	Minimum input time	200mS			
	When ON electric current	Maximum 10mADC			
	When OFF electric current	Maximum 6VDC			
	Permissible resist. value bet. terminals	When ON: Maximum	1 333Ω, When OFF: Min	imum 500KΩ	
CT input	Measurement electric current range	0.0 to 50.0A			
(2 points)	Setting electric current range		· · · · · · · · · · · · · · · · · · ·	ever, the function is turning off at 0.0.	
	Setting accuracy	±5% (0.1A or less is			
	Wire break detection	ON time of control o			
	Welding detection	OFF time of control	output above 300mS		
Communication		Communication			Loader communication
	Communication standard	RS-485 (1:31)			TTL (1:1)
	Communication terminal	Terminal block			Loader communication dedicated terminal (φ 2.5 3-pin mini-jack)
	Protocol	· · · · · · · · · · · · · · · · · · ·	ocol/MODBUS (RTU)/M	ODBUS (ASCII)	TOHO exclusive protocol/MODBUS (RTU)/MODBUS (ASCII)
	Direction of information	Half duplex			Half duplex
	Synchronous system	Asynchronous			Asynchronous
	Transmission code	ASCII			ASCII
	Interface	RS-485 (two lines)			TTIL level
	Transmission speed	2400, 4800, 9600, 19	200, 38400bps		2400, 4800, 9600, 19200, 38400bps
	Communication distance	500m			
	Response delay time	0 to 250mS			0 to 250mS
	Communication switching	· · · · · · · · · · · · · · · · · · ·	enable/Simultaneous te	emperature rise master/Simultaneous t	•
	Character	Start bit: 1 bit fixed			Start bit: 1 bit fixed
		Stop bit: 1/2 bit			Stop bit: 1/2 bit
			f ASCII 7 bits fixed f RTU 8 bits fixed		Data length: 7/8 bit *MODBUS: In case of ASCII 7 bits fixed In case of RTU 8 bits fixed
		Parity: None/Even no			Parity: None/Even number/Odd number
		BCC check: without/			BCC check: without/with * In case of MODBUS BCC Check is invalid
		Address: 1 to 99 stat	ions		Address: 1 to 99 stations * In case of MODBUS 1 to 247 stations
Transfer output	Function setting			tput, MV1 (main manipulated variable)	output, MV2 (sub-manipulated variable) output, control SV (Set Value). Reciprocal
		Scaling upper limit setting	Temperature input	Scaling lower limit to 2999.9 (°C), scaling lower limit to 9999	ling lower limit to 2999 (°C). However, for the thermocouples (R, S, B, WRe5-26 (°C).
			Analog input	Scaling lower limit to 29999 (digit)	
		Scaling lower limit	Temperature input	3 1 3 1 3 1	
		setting	Analog input	- 19999 to scaling upper limit (digit)	



■Option Specifications (Continued)

Remote SV Input	Input Type (Current/Voltage Multi-Input)	0 to 1VDC, 0 to 5VDC, 1~	5VDC, 0 to 10VDC, 4 to 20mADC
	Measurement/Range of Setting	-19999 to +29999 (deci	mal point can be set at any location)
	Range of Display (Full Scale: Range	0 to 1VDC, 0 to 5VDC,	High Limit: +12% of full scale
	of FSL2 to FSH2)	0 to 10VDC	Low Limit: Maximum of -2% of full scale
		1 to 5VDC, 4 to 20mADC	High Limit: +12% of full scale
			Low Limit: — 12% of full scale
	Resolution	±0.3% of full scale+1 di	git
	Display scaling Upper limit (FSH2)/Lower limit (FSL2)	Upper limit (FSH2): FSL2 t Lower limit (FSL2): SV set	o SV setting range upper limit. ting range lower limit to FSH2 (digit)
	Display Resolution Performance	20000 or less	
	PV Correction Zero-Point Setting (PVS2)	-9999 to 9999 (digit)	
	PV Correction Gain Setting (PVG2)	0.500 to 2.000 (Multiple)	
	PV Input Filter (PDF2)	0.0 to 99.9 (seconds)	
	Local/Remote Switch	Local, remote 1 (scaling v Remote 2 (scaling with FS	

■Input and scale range

Thermocouple		Measurement/measurement range	Indication resolution
K	℃	-200.0 to 1372.0	1℃∕0.1℃
J	℃	-200.0 to 1200.0	1℃∕0.1℃
Т	℃	-200.0 to 400.0	1℃∕0.1℃
E	℃	-200.0 to 1000.0	1℃∕0.1℃
R	℃	-50.0 to 1768	1℃
S	℃	-50.0 to 1768	1℃
В	℃	-0.0 to 1800	1℃
N	℃	-200.0 to 1300.0	1℃∕0.1℃
U	℃	-200.0 to 400.0	1℃∕0.1℃
L	℃	-200.0 to 900.0	1℃∕0.1℃
WRe5-26	℃	0 to 2300	1℃
PR40-20	℃	0 to 1880	1℃
PLII	°C	0.0 to 1390.0	1℃∕0.1℃

RTD		Measurement/measurement range	Indication resolution
Pt100 (JIS/IEC)	℃	-200.0 to 850.0	1℃ ∕ 0.1℃
JPt100 (JIS)	°C	-200.0 to 510.0	1℃∕0.1℃

Current and voltage	Measurement/measurement range	Indication resolution
0 to 1VDC		
0 to 5VDC		
1 to 5VDC	- 19999 to 29999 Indication width is less than	A decimal point position can
0 to 10VDC	20000.	be changed arbitrarily.
0 to 10mVDC		
4 to 20mADC		

■Timer operation mode

Start mode

1	Auto start
2	Manual start
3	SV start
4	DI1 start
5	DI2 start
6	DI3 start
7	DI4 start
8	Event 1 start
9	Event 2 start
10	Event 3 start
11	Event 4 start
12	Event 5 start
13	Event 6 start
14	Event 7 start
15	Step start
16	Soak start

^{*} Each Start has ON delay/OFF Delay

ON delay: After time-up control stop or event output OFF OFF delay: After time-up control stop or event output ON

■Output connection setting

•
Main output
Sub-output
Event output
RUN output
RDY output
Timer1 output
Timer1 output at on delay
Timer1 output at off delay
Timer1 output at on + off delay
Timer2 output
Timer2 output at on delay
Timer2 output at off delay
Timer2 output at on + off delay
Timer3 output
Timer3 output at on delay
Timer3 output at off delay
Timer3 output at on + off delay
Transmission output (When OUT1 and OUT2 are Analog output)
End output

■Point of contact output mode

Event function 1

	Function
0	Without
1	Deflection upper and
	lower limit
2	Deflection upper limit
3	Deflection lower limit
4	Deflection range
5	Absolute value upper
	and lower limit
<u>5</u>	Absolute value upper limit
7	Absolute value lower limit
8	Absolute value range
	Additional function
0 1 2 3 4	Without
1	Retain
2	Standby sequence
3	Delay timer
ų	Retain + Standby
	sequence
5	Retain + Delay timer
5	Standby sequence +
U	Delay timer
7	Retain+ Standby
	sequence + Delay timer
	Control linkage function
0	All mode
2	RUN/MAN mode only
2	RUN mode only

Event function 2

	Function
0	Without
1	With
	Additional function
0	Without
1	Retain
2	Delay timer
3	Retain + Delay timer
C	ontrol linkage function
0	All mode
1	RUN/MAN mode only
Ż	RUN mode only

Event function 3 (CT abnormal)

(Ci abnormal)								
	Function							
0	Without							
2	CT1 abnormal							
∠ CT2 abnormal								
3	CT1 abnormal + CT2							
	abnormal							
	Additional function							
0	Without							
1	/ Retain							
2	Delay timer							
3	Retain + Delay timer							
(Control linkage function							
[] All mode								
1	RUN/MAN mode only							
∠ RUN mode only								

Event function 4 (Loop wire break)

	Function							
	 Without							
	/ With							
		Additional function						
	WithoutRetain							

^{*}Event polarity function available

$\textbf{Output functional allotment} \quad (\bigcirc : \textbf{Allotment is possible}, \ \times : \textbf{Impossible})$

•								
Outrout torong	Contro	output	Auxiliary output					
Output types	Output1	Output2	Output3	Output4	Output5	Output6	Output7	
Main output (Heating)	0	0	0	0	0	0	0	
Auxiliary output (Cooling)	0	0	0	0	0	0	0	
Transmission	0	0	×	×	×	×	×	
Event output	0	0	0	0	0	0	0	
RUN, READY output	0	0	0	0	0	0	0	
Timer output	0	0	0	0	0	0	0	
End output	0	0	0	0	0	0	0	

The function allotment setting is possible for each output.

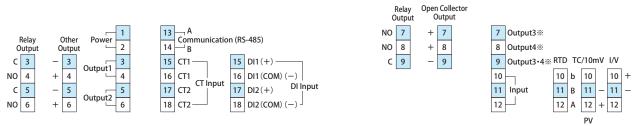
Example) When the output 1, 2 is RR model (relay output is 2-points).

By setting, they can be switched to "2-point Control Output) or "1-point Control Output, 1-point Event Output".

■Wiring

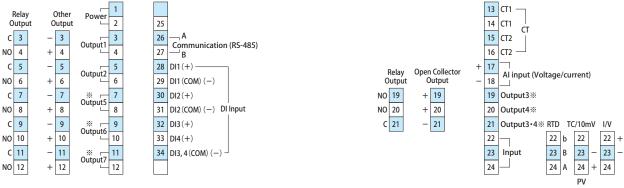
% Please use less than 6mm width terminal

TTM-214



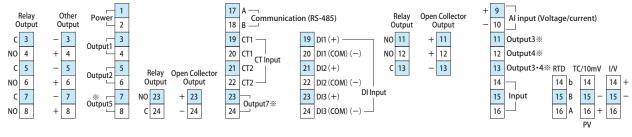
^{*} Output 3 and 4 (Terminals 7 to 9) are possible to select from either relay output or open collector.

TTM-215, 219



^{*} Output 3 to 7 (Terminals 19 to 21 and 7 to 12) are possible to select from either relay output or open collector.

TTM-217



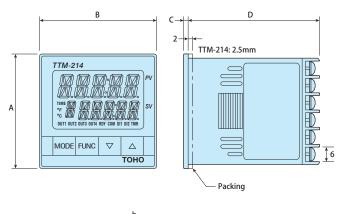
 $[\]divideontimes$ Output 3 to 5 and 7 (Terminals 11 to 13, 7 to 8, 23 to 24) are possible to select from either relay output or open collector.

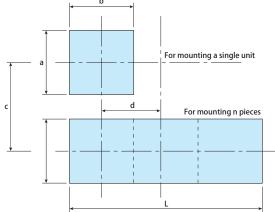
■Terminal explanation

•							
Communication	Please connect A & B terminals correctly. (Please use a converter when it is not RS-485)						
Output	Relay contact point C: Common, No: Normal open						
	SSR drive	Please connect directly to INPUT $+$ & $-$ at SSR side.					
	Transmission, Open collector Take note of polarities + & — when making connections.						
CT input	Please connect a specified current transformer directly. (CTL-6-P-H)						
PV input/ Al input	Thermocouple Current/voltage Take note of polarities + & — when making connections.						
	RTD	Take note of the terminals A, B & b when making connections.					
DI	COM: Common (The polarity can be switched)						
Al input	Take note of polarities + & — when making connections.						
Power	In case of 24VDC, the polarity assignment shall be terminal no. ①: (+), terminal no. ②: (-)						



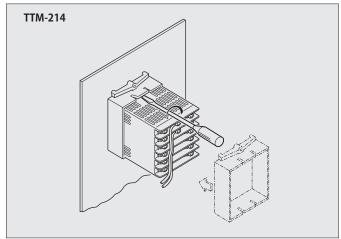
■Dimensions

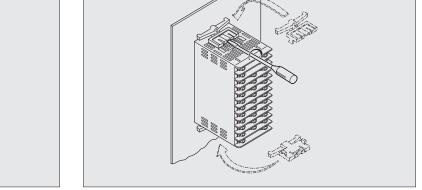




Model	a		b		С	d	Α	В	С	D	L	
TTM-214	45	+0.6 -0	45	+0.6 -0	60	48	48	48	2.5	59.7	(Bxn-3)	+0.6 -0
TTM-215	92	+0.6 -0	45	+0.6 -0	120	48	96	48	2	65	(Bxn-3)	+1 -0
TTM-217	68	+0.6 -0	68	+0.6 -0	90	72	72	72	2	65	(Bxn-3)	+1 -0
TTM-219	92	+0.6 -0	92	+0.6 -0	120	96	96	96	2	65	(Bxn-3)	+1 -0

■Panel Installation





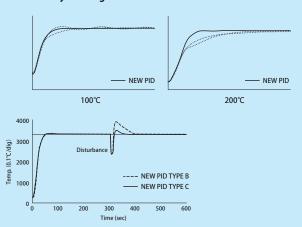
TTM-215、217、219

Insert the tip of the flat head screwdriver between the controller body and the clip of the attachment, then rotate the screwdriver to suspend the clip, and remove the attachment.

 $^{* \ \ \, \}text{How to remove the attachment}$

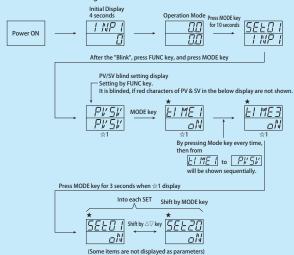
Advanced Features

●PID control by new algorithm



BLIND Function Setting

Transition to blind setting mode



Content of the above items marked with ★

- In the blind mode, "on" or "off" will appear below each character (SV indication portion).
- 2. The change of characters in the blind mode is done by pressing the "FUNC" key.
- 3. To end the blind setting mode, turn OFF the power first.

By the key operation, screen of your choice will not appear.

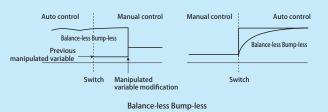
Please note that when the SV setting screen is made not to appear also, only the PV will appear during the normal indication mode.

● Auto (RUN) / Manual function

The auto control and the manual control, they can be switched by the front key. Manual operation is the function that is not concerned with the situation of a deviation, but can set up and output the output for control arbitrarily (manipulation variable).

The system can be operated manually in the time of the system trial run and so on, when to check of final control element (a valve, heater, etc.) of operation is performed, when the sensor breaks down by any chance, or when usual control can't be done.

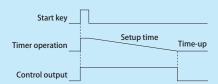
There is the Balance-less Bump-less function, which holds down sudden change of control output when switching the automatic control and manual control mutually. Furthermore, it stops damage on the peripheral equipment by sudden change and the bad influence to a control system. So, you can operate in comfort.



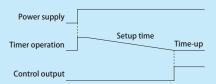
Timer function

- 1. In the case of bread baking oven
- •Put dough in the oven, and push the start key to the timer.
- ●The temperature is controlled by the heater and so on for the timer setup time.
- After timer count end control is stopped automatically

(It is used when making control STOP after the timer count ends.)

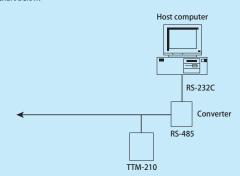


- 2. In case of packing machine and industrial machine, which control is started after the completing the preparation of the peripheral device
 - ●The count of the timer begins from point that turns on the power supply.
 - ●The control output stops during timer setting time
 - The control starts automatically after the timer count ends. (It is used when making control starts after the timer count ends.)



Communication function

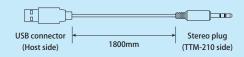
 A connection example with the personal computer
 Centralized supervision with the personal computer is possible with the connection like the chart below.



Loader communication



**Loader cable specification
 [Appearance and structure]



[Standard and performance]

USB I/F standard	USB Specification 2.0 Conforming		
DTE (Personal computer side) speed	Up to 38400bps		
Connector specification	Personal computer side: USB		
	Temperature Controller side : φ 2.5mm Stereo plug		

[Model]

TTM-LOADER

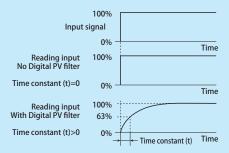


Digital PV filter

It is the function to realize the CR filter effect on the software by performing primary delay operation to the measured value (PV).

The effect of the filter can be set by the time constant.

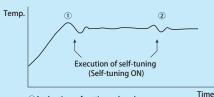
(Time constant is the time that the PV value reaches up to about 63% when the input changes on the step.)



The use of Digital PV filter

- 1) Removal of high frequency noise --- The influence of a noise when an electric noise joining an input is mitigated.
- 2) A response can be delayed against the sudden change of the input.

Self-tuning PID



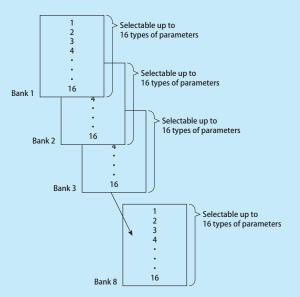
 $\ensuremath{\textcircled{\scriptsize{1}}}\xspace\ensuremath{\mbox{At}}\xspace$ the time of setting value change

②At the time of the temperature change by disturbance, and at the time of generation

Bank function

TTM-210 series has a bank function which stores up to 16 types of selected parameters in each of 8 banks

Different temperature control with one unit can be realized with the presetting of the corresponding parameters in each bank and by simply switching the bank through key operation, DI, or communication without changing the temperature setting and the PID values each time.



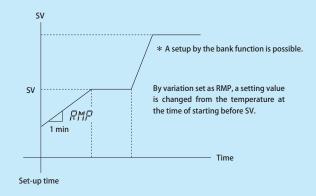
Ramp function

It is a function to give PV value an inclination against the changes of SV value. In the actual action, the "dummy" set value is made to change gradually, and the control is done against the "dummy" set value.

The variation per minute of SV is set.

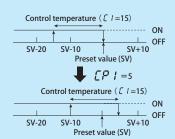
The effect of the ramp function is best exercised when sudden changes of control result is not acceptable due to the characteristics of physical object to be controlled, or, when the changing process (inclination) of the control result of the physical object becomes important.

Please note that this function changes only the SV, therefore, if great effect is expected on the PV, the expected result may not be obtained.



OFF point position movement of ON/OFF control

When the OFF point position movement is set to 0, the OFF point is the set value position.



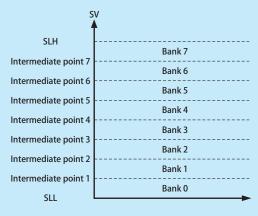
Above is when the OFF point position shift is set at (+5). The actual set value does not vary with above figures, but the position, as ON/OFF, moves (+5) towards the upper side. When the position is moved towards the minus side, the OFF point will move in reverse direction to the positions indicated above.

Bank auto-switching function

• It is a function in which the bank automatically switches by PV / SV.

By setting the desired value to each bank, an optimized parameter can be created in each temperature range.

Example) PID values during the PID control can be set differently in each bank.



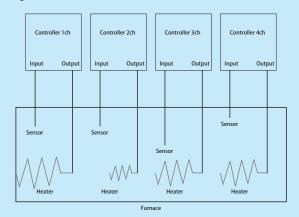
Simultaneous temperature rise function

■Simultaneous temperature rise

• When simultaneous temperature rise control is exerted by multi-channels using the RS-485 communication function, a master and slave are determined beforehand. This permits reaching the respective goal values at the same time regardless of the characteristic of each channel.

The channel, in which the time from the start of control to the reach to the goal value is the longest, is specified as a master. The other channels are specified as slaves.

• The simultaneous temperature rise function is started at the start of run (including the power ON time) or a change of setting value, and is ended when the master reaches the goal value.



How to use

- 1. Perform communication protocol settings to the TOHO protocol.
- 2. In the communication changeover setting, set the channel, in which the temperature reaches the goal value latest, to the simultaneous temperature rise master, and then set the other channels to the simultaneous temperature rise slaves.
- 3. Set the main control sensitivity.

During a simultaneous temperature rise, the slave side exerts ON/OFF control for the current temperature of the master. Accordingly, set the sensitivity to a level that does not cause chattering.

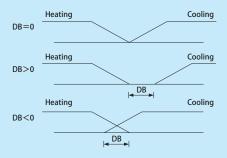
Note: Precautions on use

- 1. Perform auto tuning for each channel as required.
- 2. When using the simultaneous temperature rise function, do not perform communication with the outside.

Heating / Cooling

By allotting main output and secondary output to 2 output points respectively, heating and cooling control would be possible.

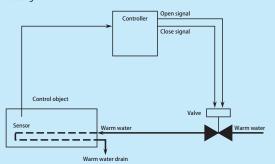
With the DB (Dead Band) setting, a range can be set between the heating output and the cooling output.



Position proportional control

■Position proportional control

- According to the operation amount required for PID control, the valve opening is changed by outputting an open signal or close signal to the valve on the basis of the valve motor stroke time, so that the flow rate is adjusted, thereby controlling the target temperature. The control can be exerted without feedback resistance.
- The valve motor stroke time means the time from the full opening of the valve till its full closing.



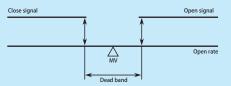
· Valve motor drive dead band

In position proportional control, the open signal or close signal is output so that the operation amount of the regulator may agree with the opening of the valve.

It is necessary to refrain from performing an open/close changeover operation frequently in consideration of the service life of the valve.

A dead band is provided at the open signal/close signal output changeover point.

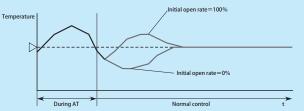
In this area, both open signal output and close signal output are stopped to reduce frequent open/close changeover operations.



• Initial opening after the end of AT

It is possible to set the operation amount just after the end of auto tuning in order to restrict undershoot just after this end.

Example) Response after the end of AT



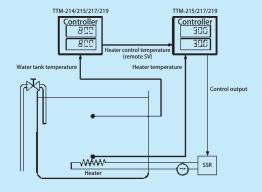
●Remote SV

Signals from external sources become the controller parameters.

• Cascade control using remote SV

Cascade control is where the control signal for a single controller is applied to other controllers, and the controller that receives control signals from an external source convert those signals into parameters for control purposes.

As shown in the illustration above, cascade control can be achieved with the use of two controllers.

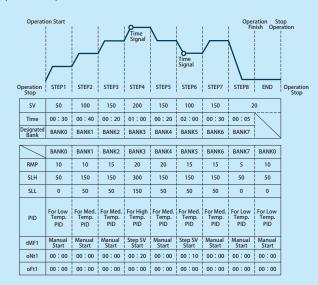


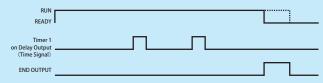


OSIMPLIFIED PROGRAM CONTROL FUNCTION

- Programmed operation with maximum of 8-steps available.
- It's possible to set Time Signal output and End Signal output.
- Maximum of 16 parameters, such as PID, can be changed at the respective steps since it is possible to switch the bank at the respective steps.
- With compensatory function for power failure

Operation Example)





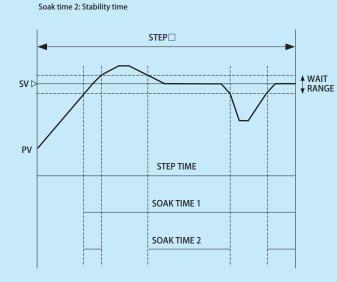
RMP: Ramp function setting
 SLH: Upper limit setting for SV limite
 SLL: Lower limit setting for SV limite
 PID: PID constants setting

tMF1: Timer1 function setting oNt1: ON delay time for timer1 oft1: OFF delay time for timer1

STEP TIME

It's possible to select from step time, soak time 1, soak time 2.

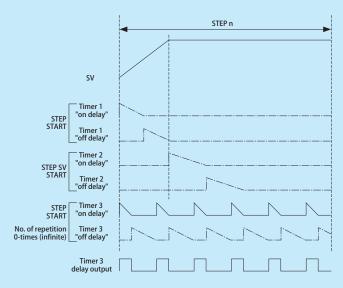
Step time: Time of the entire steps Soak time 1: Time after SV has reached



TIME SIGNAL OUTPUT

Time Signal output is possible by using another timer which is different from the simplified program control.

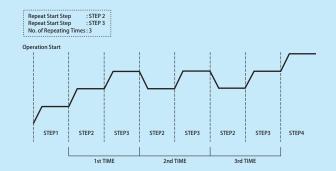
Configuration Sample)



REPEAT OPERATION

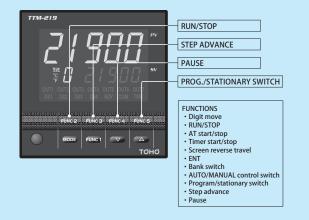
It is possible to repeat the operation. Not only full repeat but also partial one are available by setting.

Operation Example)

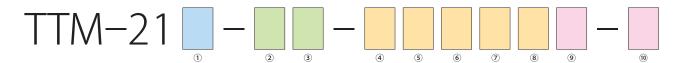


OTHERS

Pause and step advance operation can be done by the key operation, the FUNC key and DI.



■Ordering Information (Model Configurations)



(1)	Model		4	48×48							
			5	96×48							
			7	72×72							
			9	96×96							
(2)	Output 1		N	No J Voltage 0 to 5VDC							
	output 1		R	Relay point of contact		F	Voltage 1 to 5VDC				
			P	Voltage for SSR driving		G	Voltage 0 to 10VDC				
			A	Open collector			Current 4 to 20mADC				
			К	Voltage 0 to 1VDC		Н	Voltage 0 to 10mVDC				
3	Output 2		N	No		J	Voltage 0 to 5VDC				
	·		R	Relay point of contact		F	Voltage 1 to 5VDC				
			Р	Voltage for SSR driving		G	Voltage 0 to 10VDC				
			A	Open collector		ı	Current 4 to 20mADC				
			К	Voltage 0 to 1VDC		Н	Voltage 0 to 10mVDC				
4	Output 3、4		Α	Open collector							
			R	Relay point of contact	Same for the remote controllers on all models						
(5)	Output 5, 6		Α	Open collector	Not selectable for 214						
			R	Relay point of contact	217 cannot select output 6						
6	Output 7		Α	Open collector Not selectable for 214							
			R	Relay point of contact Not selectable under TTM-217 when option W (DI3) is reauired.							
7	Al input		Υ	Remote SV input (voltage/current only) Not selectable for TTM-214							
8	Option 214 Selection		ST	CT1, 2							
			SV	CT1, DI2	·						
			UV	DI1, 2	,						
	217 Selection			CT1, 2							
			SV	CT1, DI2							
			UV	DI1, 2							
			STW	CT1, 2 DI3 (output 7 not selectable							
			SVW	CT1, DI2, 3 (output 7 not selectab							
			UVW	DI1, 2, 3 (output 7 not selectable)							
		215, 219 Selection	ST	CT1, 2							
			SV	CT1, DI2							
			UV	DI1, 2							
			SVW	CT1, DI2, 3, 4							
			UVW	DI1, 2, 3, 4							
			STUV	CT1, 2 DI1, 2							
			STUVW	CT1, 2 DI1, 2, 3, 4							
9	Communicati		М	Communications (RS-485)							
10	Power Supply	/		100 to 240V (free power)							
			L	24VAC/DC							

^{*} Parameters up to output 2 must be selected.

* Specifications apply in accordance with the sequence of selection for output 3 and upwards.

Example: TTM-219-PR-RUVW

P: Output 1: SSR drive voltage

R: Output 2: Relay connection

R: Output 3, 4: Relay connection (does not select output 5 and 6)

UVW: DI1, 2, 3, 4

★Output 3 and 4 must be selected when output 5 and 6 are required.

 \bigstar Output 3 and 4 and output 5 and 6 must be selected when output 7 is required.

 \ast Option W only consists of DI3 when TTM-217 has been selected.

(The option W under 215, 219 selection refers to DI3, 4.)

*CTL-6-P-H is added when CT is selected. (2pcs are added when 2 CTs are selected.)

 $\ast\,\text{CT}$ cannot be selected when only analog has been selected for the output.

