ECE408 Spring 2020

Applied Parallel Programming

Lecture 18: Parallel Sparse Methods

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Sparse Matrix

- · Many real-world systems are sparse in nature
 - Linear systems described as sparse matrices
- Solving sparse linear systems
 - Traditional inversion algorithms such as Gaussian elimination can create too many "fill-in" elements and explode the size of the matrix
 - Iterative Conjugate Gradient solvers based on sparse matrix-vector multiplication is preferred
- Solution of PDE systems can be formulated into linear operations expressed as sparse matrixvector multiplication

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Objective

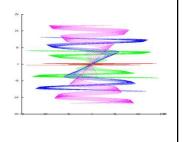
- To learn the key techniques for compacting input data in parallel sparse methods for reduced consumption of memory bandwidth
 - better utilization of on-chip memory
 - fewer bytes transferred to on-chip memory
 - Better utilization of global memory
 - Challenge: retaining regularity

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Sparse Data Motivation for Compaction

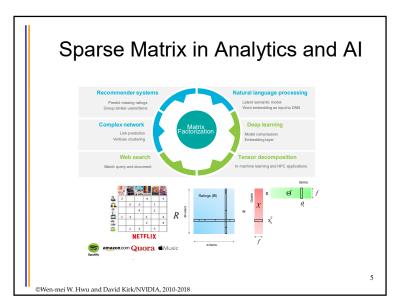
- Many real-world inputs are sparse/non-uniform
- Signal samples, mesh models, transportation networks, communication networks, etc.



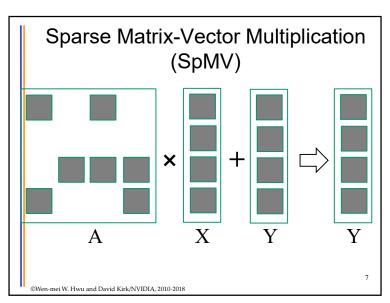
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Science Area	Number of Teams	Codes	Struct Grids	Unstruct Grids	Dense Matrix	Sparse Matrix	N- Body	Monte Carlo	FFT	PIC	Sig I/O
Climate and Weather	3	CESM, GCRM, CM1/WRF, HOMME	Х	Х		Х		Х			Χ
Plasmas/ Magnetosphere	2	H3D(M),VPIC, OSIRIS, Magtail/UPIC	Х				Х		Х		Х
Stellar Atmospheres and Supernovae	5	PPM, MAESTRO, CASTRO, SEDONA, ChaNGa, MS-FLUKSS	X			х	Х	X		Х	X
Cosmology	2	Enzo, pGADGET	Х			Х	Х				
Combustion/ Turbulence	2	PSDNS, DISTUF	Х						Х		
General Relativity	2	Cactus, Harm3D, LazEV	Х			Х					
Molecular Dynamics	4	AMBER, Gromacs, NAMD, LAMMPS				Х	Х		Х		
Quantum Chemistry	2	SIAL, GAMESS, NWChem			Х	Х	Х	Х			Χ
Material Science	3	NEMOS, OMEN, GW, QMCPACK			Х	Х	Х	Х			
Earthquakes/ Seismology	2	AWP-ODC, HERCULES, PLSQR, SPECFEM3D	Х	X			Х				Χ
Quantum Chromo Dynamics	1	Chroma, MILC, USQCD	Х		Х	Х					
Social Networks	1	EPISIMDEMICS									
Evolution	1	Eve									
Engineering/System of Systems	1	GRIPS,Revisit						Х			6
Comput@Bitmomei W. Htwu and David Kirk/NVIDIA, 2010-2018 X						Х			Χ		Χ

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Challenges

- Compared to dense matrix multiplication, SpMV
 - Is irregular/unstructured
 - Has little input data reuse
 - Benefits little from compiler transformation tools
- · Key to maximal performance

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- Maximize regularity (by reducing divergence and load imbalance)
- Maximize DRAM burst utilization (layout arrangement)

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A Simple Parallel SpMV

 Row 0
 3
 0
 1
 0
 Thread 0

 Row 1
 0
 0
 0
 0
 Thread 1

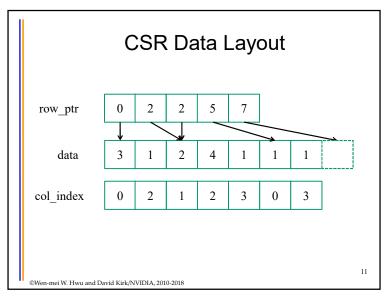
 Row 2
 0
 2
 4
 1
 Thread 2

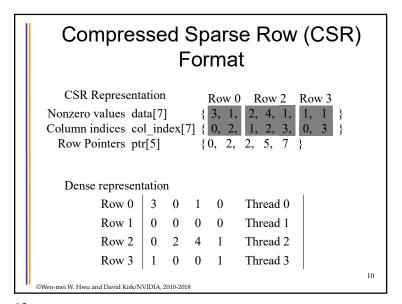
 Row 3
 1
 0
 0
 1
 Thread 3

· Each thread processes one row

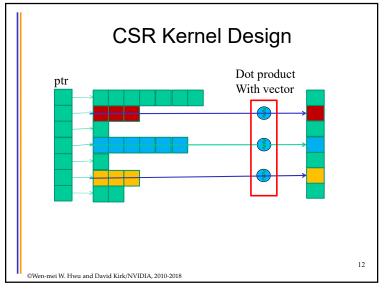
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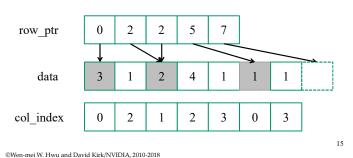


A Parallel SpMV/CSR Kernel (CUDA) __global__ void SpMV_CSR(int num rows, float *data, int *col index, int *row ptr, float *x, float *y) { int row = blockIdx.x * blockDim.x + threadIdx.x; if (row < num rows) { float dot = 0; 4. int row start = row ptr[row]; 6. int row end = row ptr[row+1]; for (int elem = row start; elem < row end; elem++) { 8. dot += data[elem] * x[col index[elem]]; 9. y[row] = dot;Row 0 Row 2 Row 3 Nonzero values data[7] Column indices col index[7] Row Pointers row ptr[5] $\{0, 2, 2, 5, 7\}$ ©Wen-mei W. Hwu and David Kirk/NVIDIA, 2010-2018

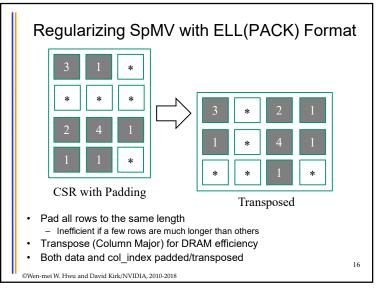
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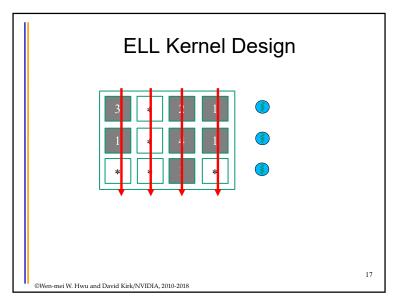
CSR Kernel Memory Divergence (Uncoalesced Accesses)

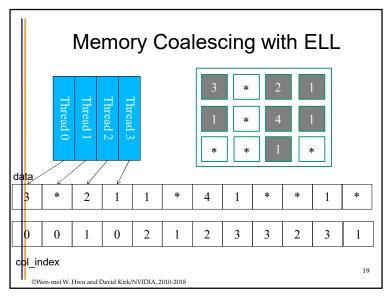
- Adjacent threads access non-adjacent memory locations
 - Grey elements are accessed by all threads in iteration 0



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```
A parallel SpMV/ELL kernel

1. _global__ void SpMV_ELL(int num_rows, float *data, int *col_index, int num_elem, float *x, float *y) {

2. int row = blockIdx.x * blockDim.x + threadIdx.x;

3. if (row < num_rows) {

4. float dot = 0;

5. for (int i = 0; i < num_elem; i++) {

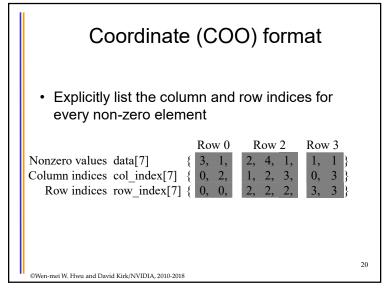
6. dot += data[row+i*num_rows]*x[col_index[row+i*num_rows]];

}

7. y[row] = dot;

}

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COO Allows Reordering of Elements

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1. for (int i = 0; i < num_elem; row++)
2. y[row_index[i]] += data[i] * x[col_index[i]];

a sequential loop that implements SpMV/COO
```