Instruction Selection

15-411/15-611 Compiler Design

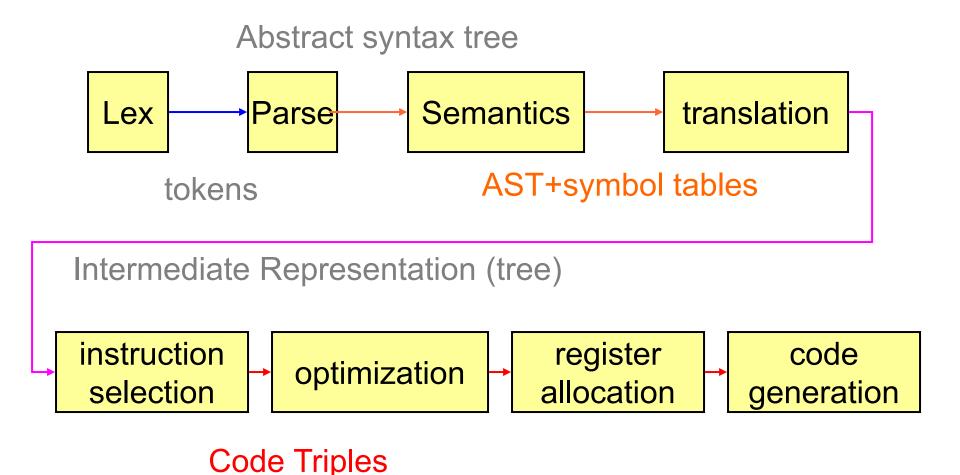
Seth Copen Goldstein

September 10, 2020

Today

- Context
- Abstract Assembly
- AST \rightarrow IR
- Maximal Munch
- Issues
- Simple SSA
- x86 and 2-adr Instructions

Cartoon Compiler



Simple Source Language

- A language of assignments, expressions, and a return statement.
- Straight-line code
- Basically lab1 subset of C0

Simple Source Language

program :=
$$s_1$$
; s_2 ; ... s_n ;

sequence of statements

$$s := v = e$$

return e

e := 0

l v

 $\mathsf{e}_1 \oplus \mathsf{e}_2$

⊕ := + | - | * | / | %

assignment

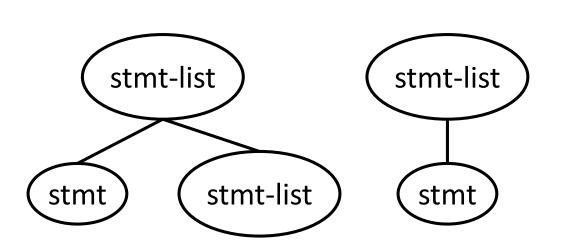
return

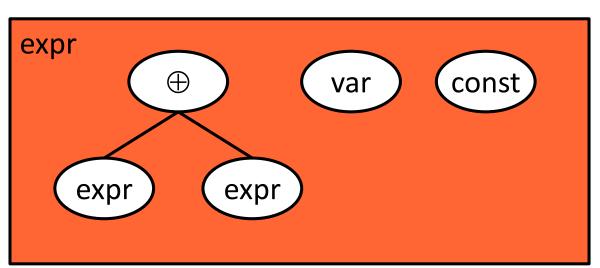
constant

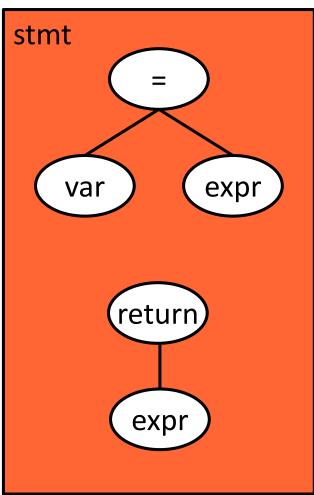
variable

binary operation

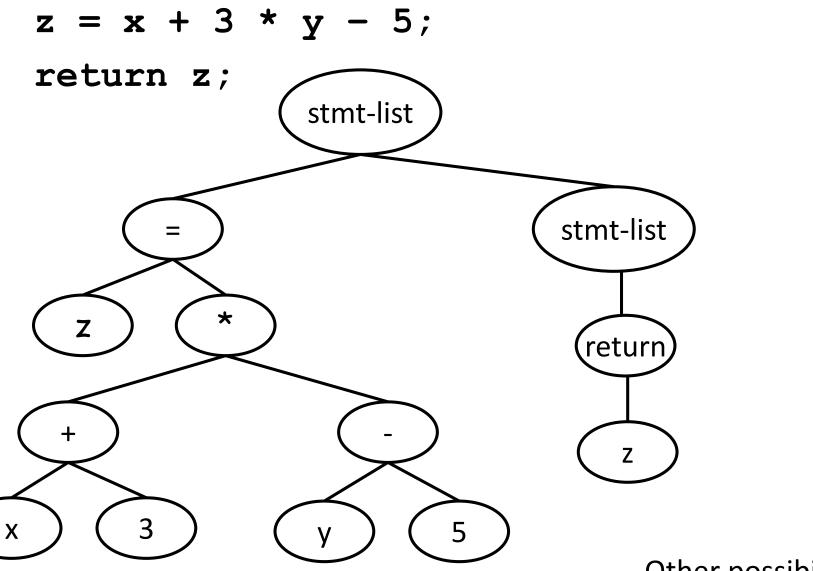
Abstract Syntax Tree







Example



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Abstract Assembly as IR

- Lowering of AST
- Facilitate
 - Analysis & optimizations
 - Translation to actual assembly

In today's world aka registers

• Features:

- Unlimited number of "temporaries" -
- May not restrict how memory is used
- Simple operations
- May not restrict how constants are used
- May specify certain "special registers"

Abstract Assembly as IR

• Features:

- Unlimited number of "registers" (aka "temps")
- May (or may not) restrict how memory is used
- Simple operations
- May not restrict how constants are used
- May specify certain "special registers"

• Form:

 $dest \leftarrow src_1 operator src_2$

dest ← operator src₁
operator

src can be:

- constant
- temp
- special register
- memory

Abstract Assembly

program :=
$$i_1 i_2 ... i_n$$

seq of instructions

$$i := d \leftarrow s$$

$$| d \leftarrow s_1 \oplus s_2$$

$$d := t$$

move

binop

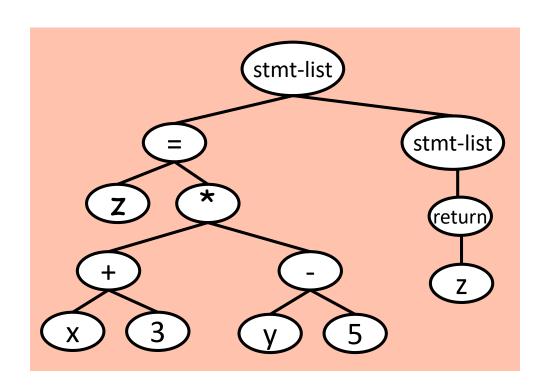
return what is in rax

intermediate

temporary

register

Example Goal



$$t1 \leftarrow x + 3$$

$$t2 \leftarrow y - 5$$

$$z \leftarrow t1 * t2$$

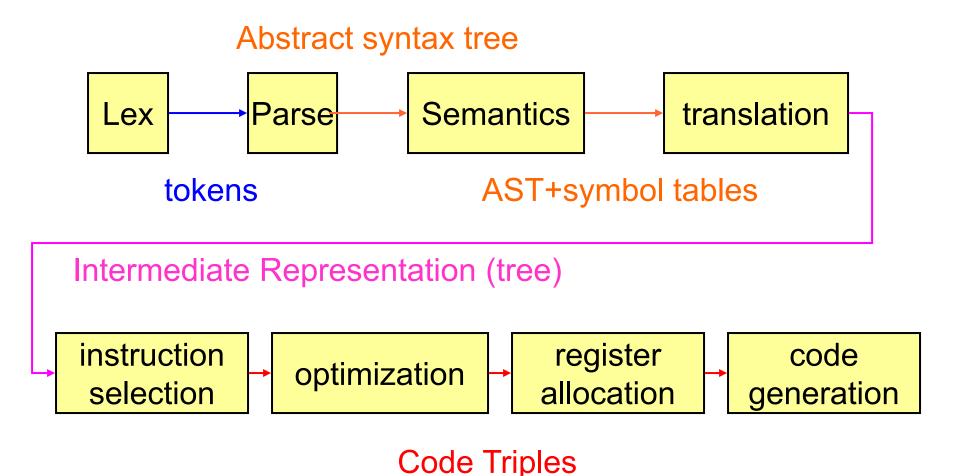
$$rax \leftarrow z$$

$$return$$

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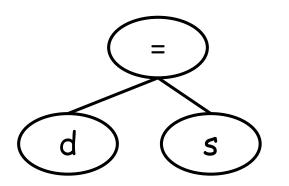


Alternatives abound

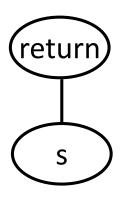
Translating AST to IR

- Converting from tree structured IR to sequence of instructions
 - Create temporary locations to store values
 - choose which operations we want
 - can combine or
 - breakup original operations
- Match portions of tree and convert to triple

Tree Patterns (aka Tiles)

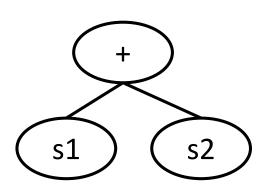


$$d \leftarrow s$$



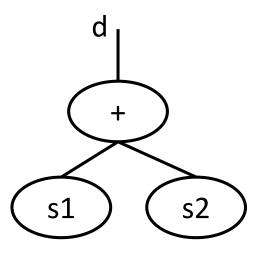
$$rax \leftarrow s$$
 ret

Tree Patterns

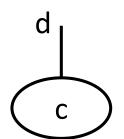


?
$$\leftarrow s_1 + s_2$$

Tree Patterns

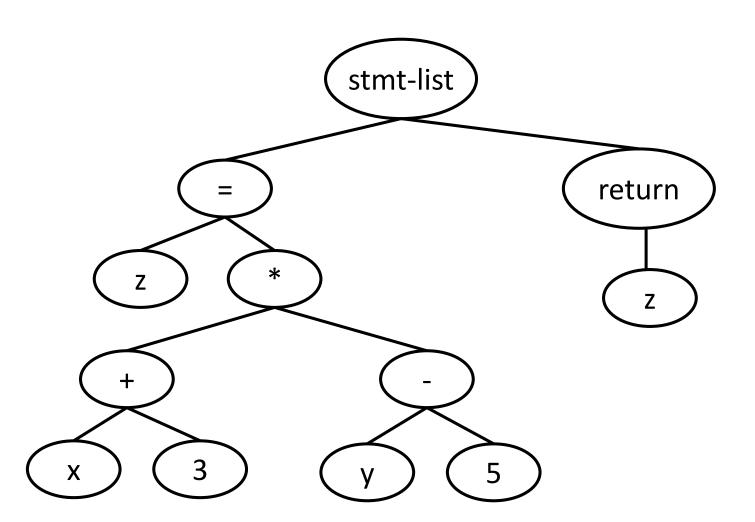


$$d \leftarrow s_1 + s_2$$

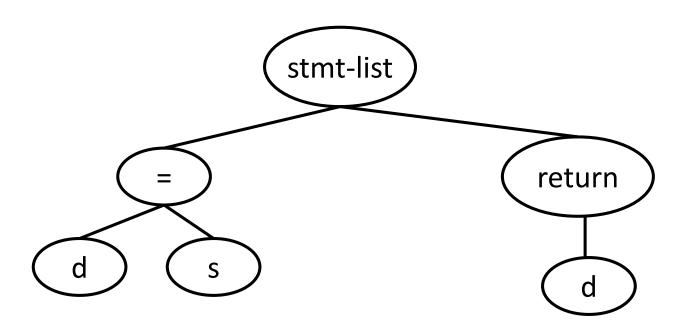


$$\mathsf{d} \leftarrow \mathsf{c}$$

Tiling a Tree



Better Tiles



Better or worse?

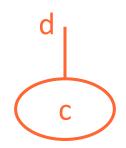
rax ← s return

Today

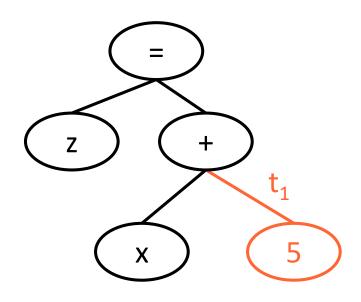
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- recursively match tree
- At each step, pick "best" tile

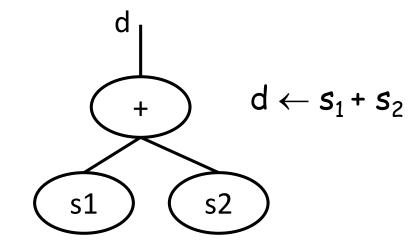
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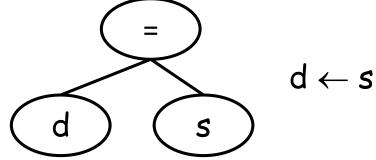




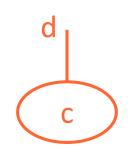


$$t_1 \leftarrow 5$$

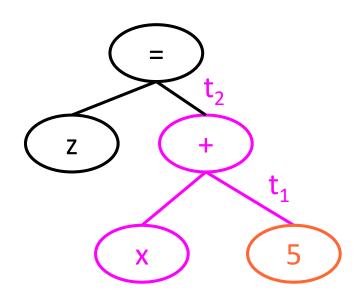




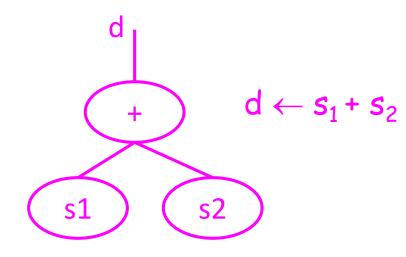
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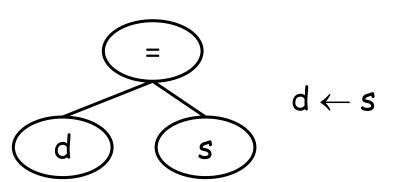




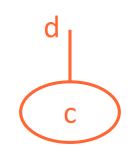


$$t_1 \leftarrow 5$$
 $t_2 \leftarrow x + t_1$

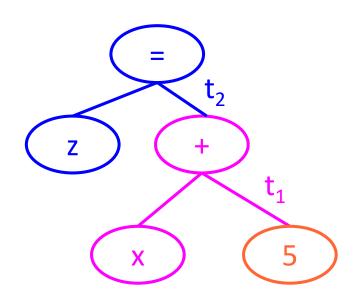


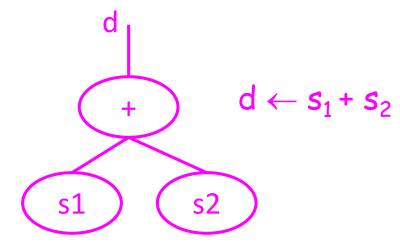


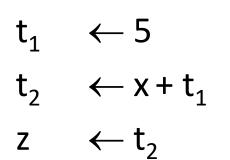
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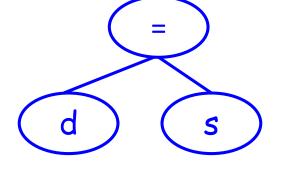






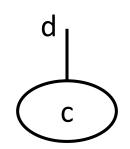




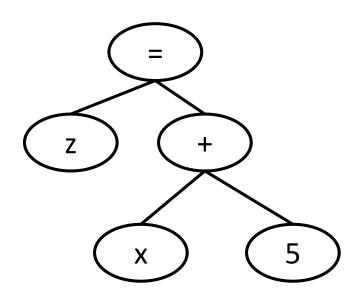


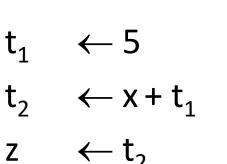
 $d \leftarrow s$

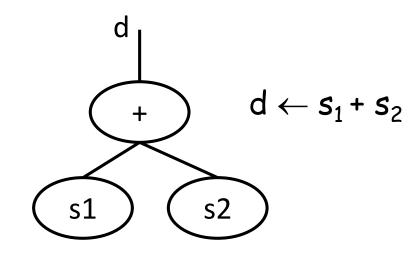
- recursively match tree
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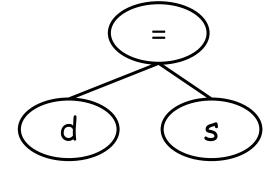












 $d \leftarrow s$

- recursively match tree
- At each step, pick "best" tile
- need to indicate what destinations are
 - choose either to supply destination
 - or generate a destination

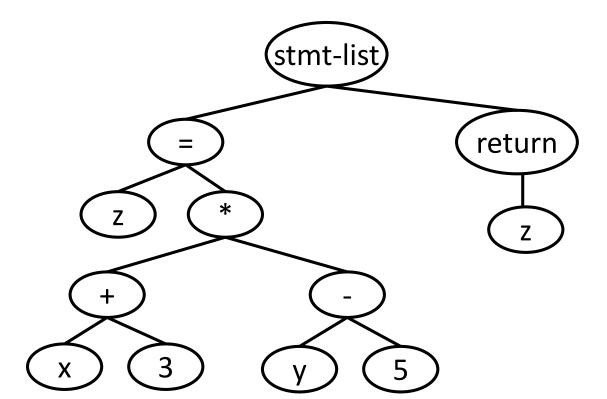
codegen

е	codegen(d, e)
С	$d \leftarrow c$
V	$d \leftarrow x$
$e_1 \oplus e_2$	codegen(t_1 , e_1) codegen(t_2 , e_2) $d \leftarrow t_1 \oplus t_2$

S	codegen(s)
v = e	codegen(v, e)
return e	codegen(rax, e) return

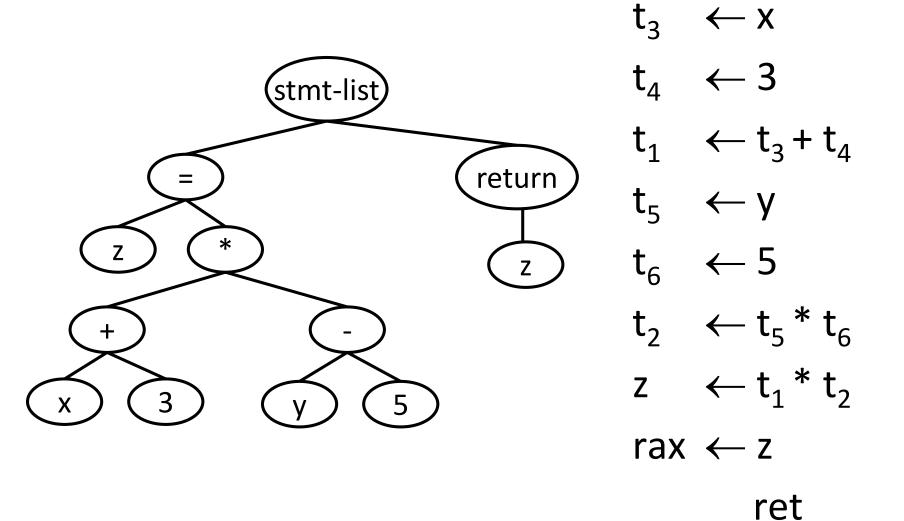
Example

e	codegen(d, e)
С	$d \leftarrow c$
V	$d \leftarrow x$
${\bf e_1} \oplus {\bf e_2}$	$\begin{aligned} & \text{codegen}(t_1 , e_1) \\ & \text{codegen}(t_2 , e_2) \\ & \text{d} \leftarrow t_1 \oplus t_2 \end{aligned}$

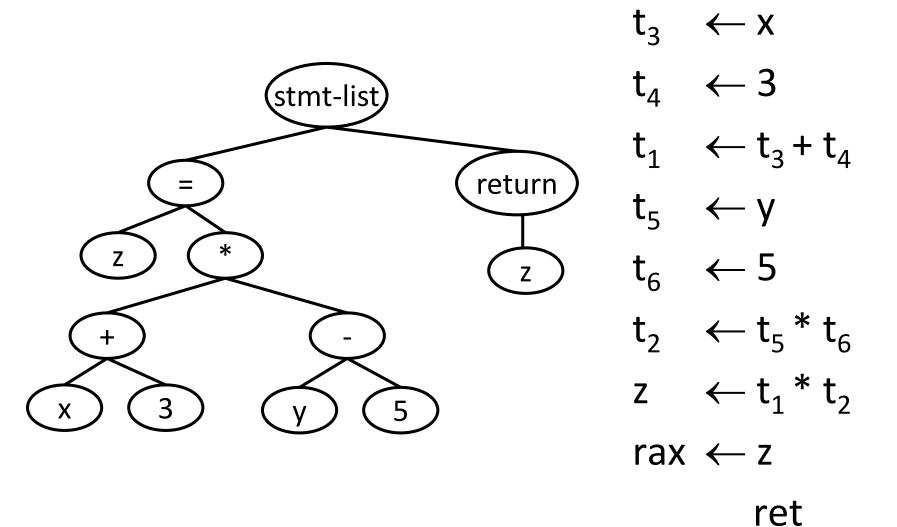


S	codegen(s)
v = e	codegen(v, e)
return e	codegen(rax, e) return

Result



How Can we Improve this?



How Can we Improve this?

- Investigate generating a source operand
- Special cases
- Don't bother?

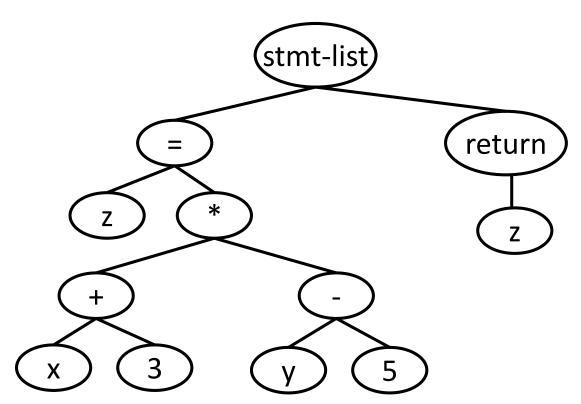
Generating Sources

е	codegen(d, e)	up
С		С
V		V
$e_1 \oplus e_2$	$t_1 = codegen(e_1)$ $t_2 = codegen(e_2)$ $t \leftarrow t_1 \oplus t_2$	t

S	codegen(s)
v = e	$v \leftarrow codegen(e)$
return e	rax ← codegen(e) return

Example

е	codegen(d, e)	up
С		С
V		V
$e_1 \oplus e_2$	$t_1 = codegen(e_1)$ $t_2 = codegen(e_2)$ $t \leftarrow t_1 \oplus t_2$	t



S	codegen(s)
v = e	$v \leftarrow codegen(e)$
return e	rax ← codegen(e) return

Special Cases

е	codegen(d, e)
С	d ← c
V	$d \leftarrow x$
c⊕e ₂	codegen(t_2 , e_2) d \leftarrow c \oplus t ₂
$e_1 \oplus c$	codegen(t_1 , e_1) d $\leftarrow t_1 \oplus c$
$v \oplus e_2$	codegen(t_2 , e_2) d \leftarrow v \oplus t_2
$e_1 \oplus v$	$codegen(t_1, e_1)$ $d \leftarrow t_1 \oplus v$
$e_1 \oplus e_2$	codegen(t_1 , e_1) codegen(t_2 , e_2)
	d ← Generally not reco

The "don't bother" case

What should we really do?

```
t_3 \leftarrow x
t_4 \leftarrow 3
t_1 \leftarrow t_3 + t_4
t_s \leftarrow y
t_6 \leftarrow 5
t_2 \leftarrow t_5 * t_6
z \leftarrow t_1 * t_2
rax \leftarrow z
             ret
```

е	codegen(d, e)
С	$d \leftarrow c$
V	$d \leftarrow x$
c⊕e ₂	codegen(t_2 , e_2) d \leftarrow c \oplus t ₂
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v⊕e ₂	codegen(t_2 , e_2) d \leftarrow v \oplus t_2
$e_1 \oplus v$	$codegen(t_1, e_1)$ $d \leftarrow t_1 \oplus v$
$e_1 \oplus e_2$	codegen(t_1 , e_1) codegen(t_2 , e_2) $d \leftarrow t_1 \oplus t_2$

Constant Propagation

Copy Propagation

Constant Propogation

$$t_{3} \leftarrow x$$

$$t_{4} \leftarrow 3$$

$$t_{1} \leftarrow t_{3} + t_{4} = 3$$

$$t_{5} \leftarrow y$$

$$t_{6} \leftarrow 5$$

$$t_{2} \leftarrow t_{5} * t_{6} = 5$$

$$z \leftarrow t_{1} * t_{2}$$

$$rax \leftarrow z$$

$$ret$$

Copy Propogation



$$\begin{array}{ccc} t_1 & \leftarrow t_3 x + 3 \\ \hline t_5 & \leftarrow y \end{array}$$

$$t_2 \leftarrow t_5 y * 5$$
 $z \leftarrow t_1 * t_2$
 $rax \leftarrow z$
 ret

Have to be careful

Constant propagation:

$$x \leftarrow 5$$

$$y \leftarrow x - 4$$

$$x \leftarrow y + 7$$

$$z \leftarrow x$$

• Copy Propagation:

$$x \leftarrow y$$

$$z \leftarrow x + 7$$

Have to be careful

- Constant propagation:
 - Can't just replaceall x's with 5
 - Stop if x is redefined

• Copy Propagation:

$$x \leftarrow 5$$

$$y \leftarrow x - 4$$

$$x \leftarrow y + 7$$

$$z \leftarrow x$$

$$x \leftarrow y$$

$$z \leftarrow x + 7$$

Have to be careful

- Constant propagation:
 - Can't just replace all x's with 5
 - Stop if x is redefined

- Copy Propagation:
 - Can't just replace all x's with y's
 - Stop if x or y is redefined

$$x \leftarrow 5$$

$$y \leftarrow x - 4$$

$$x \leftarrow y + 7$$

$$z \leftarrow x$$

$$x \leftarrow y$$

$$z \leftarrow x + 7$$

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Static Single Assignment

- Must keep track of what definition each use refers to in order to properly do constant/copy propagation.
- Much simpler if only one definition for each name.
- SSA: Each name is assigned in only one location.

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Static Single Assignment

- Must keep track of what definition each use refers to in order to properly do constant/copy propogation.
- Much simpler if only one definition for each name.
- SSA: Each name is assigned in only one location.
- Easy for fresh temporaries
- What about variables?

- Give each variable a version number.
- Scan code in program order
- Whenever we encounter a definition, increment the version number
- Whenever we encounter a use, use the most recently assigned version number.

$$x \leftarrow 5$$
 $x_0 \leftarrow 5$
 $y \leftarrow x - 4$ $y \leftarrow x - 4$
 $x \leftarrow y + 7$ $x \leftarrow y + 7$
 $z \leftarrow x$ $z \leftarrow x$

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$$x \leftarrow 5$$
 $x_0 \leftarrow 5$
 $y \leftarrow x - 4$ $y_0 \leftarrow x_0 - 4$
 $x \leftarrow y + 7$ $x_1 \leftarrow y_0 + 7$
 $z \leftarrow x$ $z_0 \leftarrow x_1$

Now easy

- Constant progpogation:
 - Can replace all x_0 with 5.

$$x_0 \leftarrow 5$$
 $y_0 \leftarrow x_0 - 4$
 $x_1 \leftarrow y_0 + 7$
 $z_0 \leftarrow x_1$

- Copy Propogation:
 - Can replace all x_0 with y_0

$$x_0 \leftarrow y_0$$

$$y_1 \leftarrow u_0 - 4$$

$$z_0 \leftarrow x_0 + 7$$

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How to real assembly on x86

x86 doesn't have 3 address instructions!

$$d \leftarrow s_1 + s_2$$

How to real assembly on x86

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Triples	2-adr	x86
$d \leftarrow s_1 + s_2$	$d \leftarrow s_1 \\ d \leftarrow d + s_2$	MOVx s ₁ , d ADDx s ₂ , d

How to real assembly on x86

x86 doesn't have 3 address instructions!

Triples	2-adr	x86
$d \leftarrow s_1 + s_2$	$d \leftarrow s_1 \\ d \leftarrow d + s_2$	MOVx s ₁ , d ADDx s ₂ , d

All kinds of special register requirements

$$d \leftarrow s_1 * s_2$$

What about edx?

Triples	2-adr	x86
$d \leftarrow s_1 * s_2$	$d \leftarrow s_1 \\ d \leftarrow d * s_2$	MOVL s ₁ , rax IMUL s ₂ MOVL rax, d

From AST to Machine Assembly

- Implied Approach:
 - AST → Triples using unlimited temporaries
 - Map temporaries to registers/memory
 - Lower Triples to real assembly
- What about Interaction between registers and instructions?
- Cost model?
- KISS:
 - Keep things simple, but
 - Prepare for other passes to fix things up.