How to Increase Computational Efficiency for PReLU in CUDA — OneFlow Performance Optimization

```
destamp": "2017-06-03T18:42:18 of the state of the state
```

Written by Zekang Zheng; Translated by Yanjun Hu, Jiali Shen

PReLU is an activation function that is frequently used in InsightFace. It has two operating modes: PReLU(1) and PReLU(channels). For the latter, PReLU is equivalent to a binary

broadcast operation. In this article, we are going to talk about optimizing the broadcast operations in CUDA.

PReLU is an activation function that is frequently used in InsightFace. It has two operating modes:

- PReLU(1). The shape of the weight alpha is (1,
). In this case, PReLU is equivalent to an
 elementwise operation.
- 2. PReLU(channels). The shape of the weight alpha is (channels,), and its size is the same as that of the "C" in the (N, C, H, W) of input tensor. In this case, PReLU is equivalent to a binary broadcast operation.

InsightFace adopts the second mode of PReLU. We wrote about how to optimize CUDA elementwise operationsbefore. Today, we are going to talk about optimizing the broadcast operations in CUDA.

1 Naïve implementation

Here is a naïve implementation. Firstly, get the index of the current element-"x" in the loop. Secondly, infer the index of the corresponding alpha weight. Thirdly, return results by seeing if "x">0: if "x">0, return "x"; if "x"<0, return "alpha*x". The code is as follows:

Note:

 inner_size refers to the product of the values of the dimensions following the channel dimension. Take the NCHW format as an example: inner_size=H*W. • alpha_size refers to the size of the channel dimension.

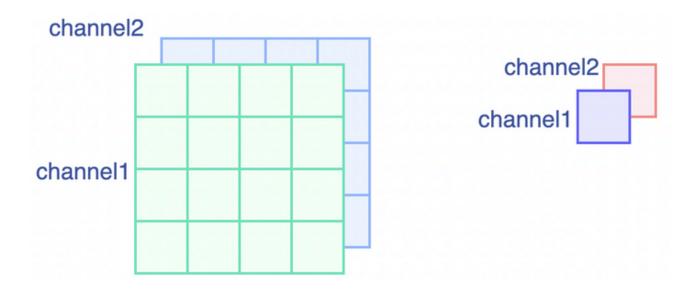
In CUDA, integer division comes with high computational costs. As you can find in the CUDA Toolkit Documentation (Chapter 5.4.1 Arithmetic Instructions):

Integer division and modulo operation are costly as they compile to up to 20 instructions.

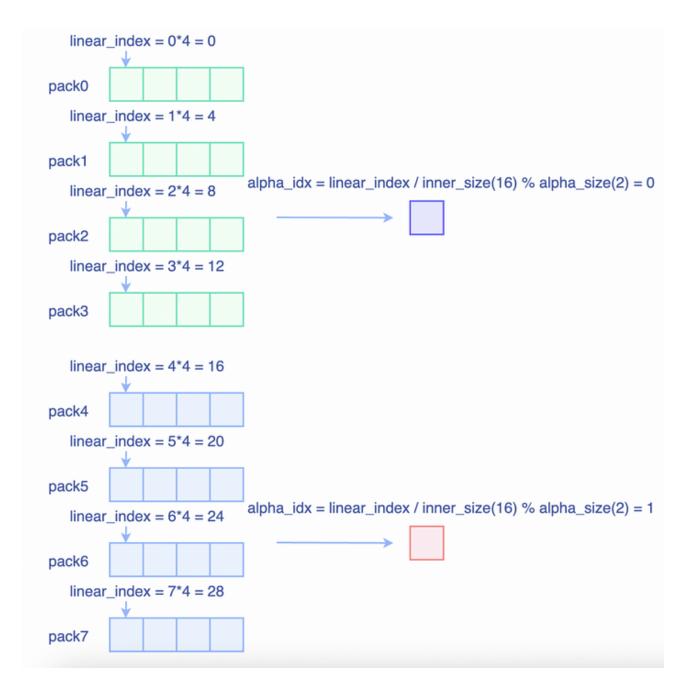
Calculating the index of alpha involves one integer division and one modulo operation. These computations represent half of the workload of the kernel. Thus, in what follows, we are going to tell you how to reduce integer divisions and modulo operations while increasing read/write bandwidth using a vectorized method.

2 Optimizing by PackType vectorization

Here is a simple case: if the tensor shape being input is (1,2,4,4), then its operating mode will be PReLU(2).



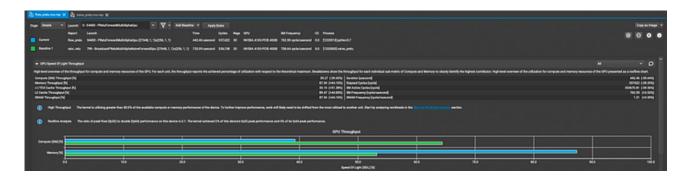
What's obvious is that the input on H and W dimensions is continuous. In this situation, if inner_size is divisible by pack size, the elements in a pack will be applied to the same alpha weight, just as the following figure shows:



In this way, vectorization operations are advisable to improve the read/write bandwidth utilization. And the elements in each pack only need to be calculated once, which cuts down considerable computations, since we no longer need to calculate the elements one by one. The code is as follows:

Let's compare the results before and after an optimization operation offered by Nsight Compute. After testing data (96, 64, 112, 112) on the A100-40GB GPU, we got the performance results of two kernels as shown in the following figure: the blue

one is optimized by vectorization, while the green one is naively implemented. It's clear that an optimization operation efficiently reduces 20%-30% of calculations and boosts throughput by 30%. Besides, the optimized kernel's bandwidth is up to 1350GB/s, which gets very close to A100's theoretical limit.



However, not all tensor shapes support a vectorization operation. If the inner_size cannot be divisible by its corresponding pack_size, the shape can only settle for a naive implementation.

3 Benchmark

When conducting a benchmark test on the NVIDIA A100–40GB GPU, we compared the performance of OneFlow and PyTorch when they deal with different tensor shapes in the InsightFace library. And the testing result is as follows:

shape	OneFlow Time	OneFlow Bandwidth	PyTorch Time	PyTorch Bandwidth
96x64x112x112	442us	1350GB/s	857us	700GB/s
96x64x56x56	110.3us	1240GB/s	220us	635GB/s
96x128x28x28	56.93us	1060GB/s	114us	550GB/s
96x256x14x14	30.27us	766.2GB/s	61.41us	393GB/s
96x512x7x7	39.58us	244GB/s	35us	271GB/s

We can see that OneFlow, empowered by the optimized activation function-PReLU, delivers better performance than PyTorch by nearly 200% in most conditions. As for the last testing example, the tensor shape is so special that a vectorization optimization doesn't work, so OneFlow performs on a par with PyTorch.