ECE408 /CS483/CSE408 Spring 2020

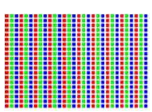
Applied Parallel Programming

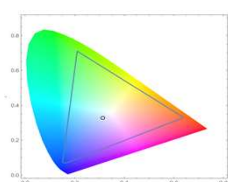
Lecture 2: Introduction to CUDA C and Data Parallel Programming

Objective

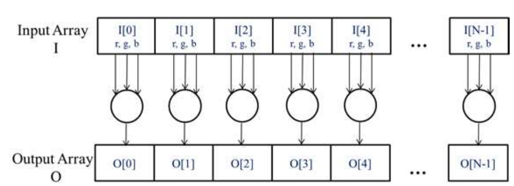
- To learn the basic concept of data parallel computing
- To learn the basic features of the CUDA C programming interface

A Data Parallel Computation Example: Conversion of a color image to grey–scale image



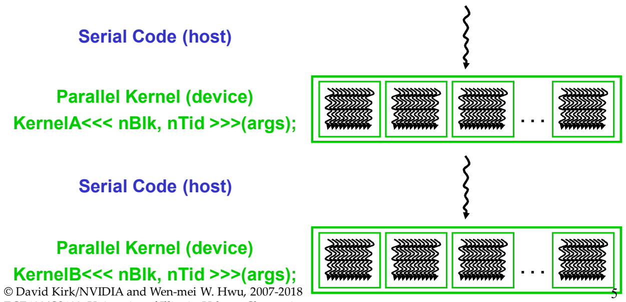


The pixels can be calculated independently of each other



CUDA/OpenCL – Execution Model

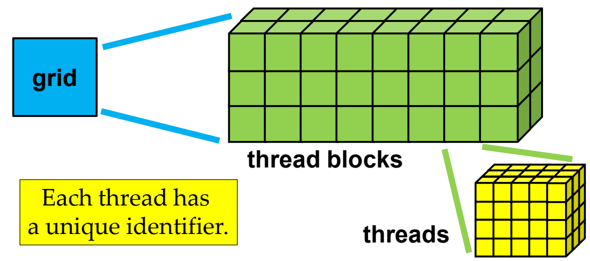
- Integrated host+device app C program
  - Serial or modestly parallel parts in **host** C code
  - Highly parallel parts in **device** SPMD kernel C code



5

Logical Execution Model for CUDA

- Each CUDA kernel
  - is executed by a **grid**,
  - a 3D array of **thread blocks**, which are
  - 3D arrays of **threads**.

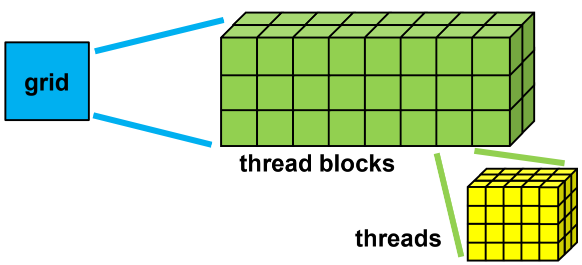


Each thread has a unique identifier.

6

Single Program, Multiple Data

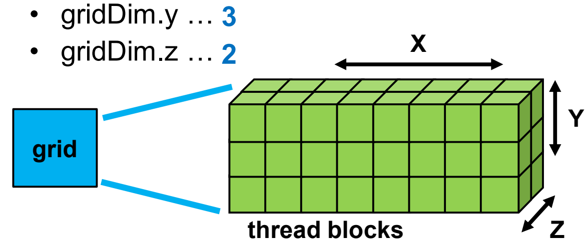
- Each thread
  - executes the **same program**
  - on **distinct data inputs**,
  - a single-program, multiple-data (**SPMD**) model



7

gridDim Gives Number of Blocks

- Number of blocks in each dimension is
  - gridDim.x … **8**
  - gridDim.y … **3**
  - gridDim.z … **2**

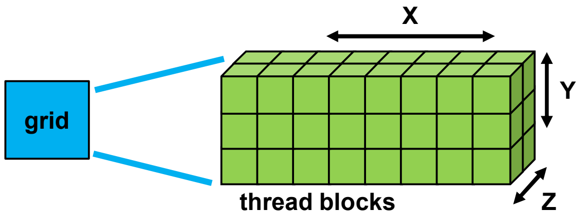


For 2D (and 1D grids), simply use grid dimension 1 for Z (and Y).

8

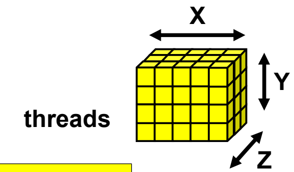
blockIdx is Unique for Each Block

- Each block has a unique index tuple
  - blockIdx.x (from 0 to (gridDim.x – 1))
  - blockIdx.y (from 0 to (gridDim.y – 1))
  - blockIdx.z (from 0 to (gridDim.z – 1))



blockDim: # of Threads per Block

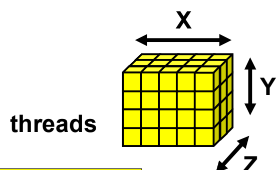
- Number of blocks in each dimension is
  - blockDim.x … **5**
  - blockDim.y … **4**
  - blockDim.z … **3**



For 2D (and 1D blocks), simply use block dimension 1 for Z (and Y).

threadIdx Unique for Each Thread

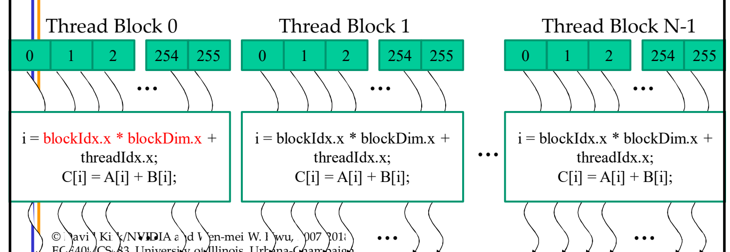
- Each thread has a unique index tuple
  - threadIdx.x (from 0 to (blockDim.x – 1))
  - threadIdx.y (from 0 to (blockDim.y – 1))
  - threadIdx.z (from 0 to (blockDim.z – 1))



threadIdx tuple is unique to each thread **WITHIN A BLOCK.**

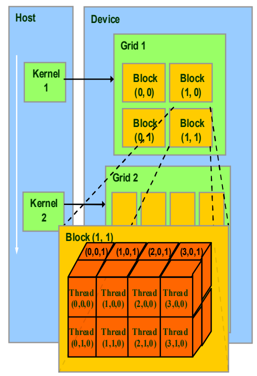
Thread Blocks: Scalable Cooperation

- Threads within a block cooperate via **shared memory, atomic operations** and **barrier synchronization** (to be covered later)
- Threads in different blocks cooperate less.

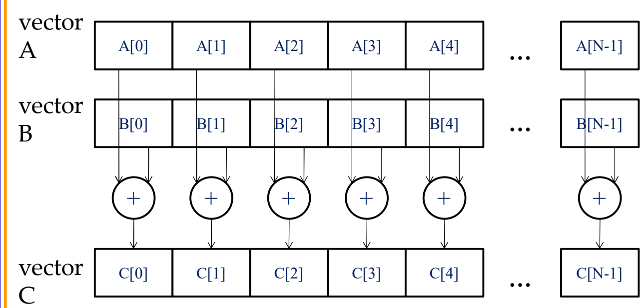


blockIdx and threadIdx

- Thread block and thread organization
  - simplifies memory addressing
  - when processing multidimensional data
    - Image processing
    - Vectors, matrices, tensors
    - Solving PDEs on volumes
    - …



Vector Addition – Conceptual View



Vector Addition – Traditional C Code

```
// Compute vector sum C = A+B
void vecAdd(float* A, float* B, float* C, int n)
{
  for (i = 0, i < n, i++)
    C[i] = A[i] + B[i];
}

int main()
{
    // Memory allocation for A_h, B_h, and C_h
    // I/O to read A_h and B_h, N elements
    …
    vecAdd(A_h, B_h, C_h, N);
}
```

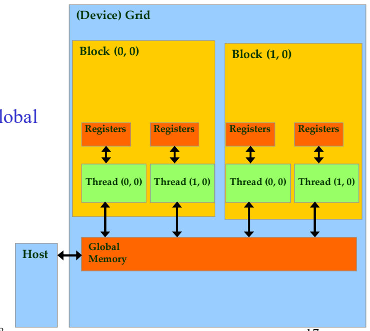

Heterogeneous Computing vecAdd Host Code

```
#include <cuda.h>
void vecAdd(float* A, float* B, float* C, int n)
{
      int size = n* sizeof(float);
      float *A_d, *B_d, *C_d;
   …
1. // Allocate device memory for A, B, and C
   // copy A and B to device memory

2. // Kernel launch code – to have the device
   // to perform the actual vector addition

3. // copy C from the device memory
   // Free device vectors
}
```

Partial Overview of CUDA Memories

- Device code can:
  - R/W per-thread registers
  - R/W per-grid global memory
- Host code can
  - Transfer data to/from per grid global memory

We will cover more later.

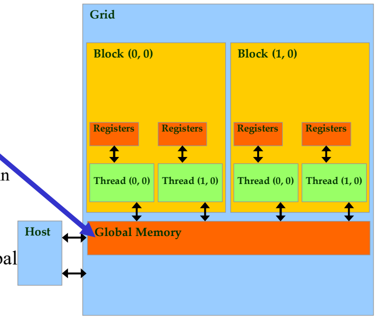


 17

17

CUDA Device Memory Management API functions

- cudaMalloc()
  - Allocates object in the device global memory
  - Two parameters
    - **Address of a pointer** to the allocated object
    - **Size of** the allocated object in terms of bytes
- cudaFree()
  - Frees object from device global memory
    - **Pointer** to freed object

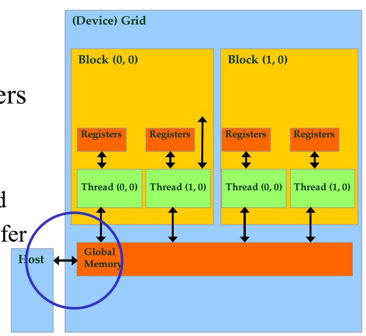


 18

18

Host-Device Data Transfer API functions

- cudaMemcpy()
  - memory data transfer
  - Requires four parameters
    - Pointer to destination
    - Pointer to source
    - Number of bytes copied
    - Type/Direction of transfer



 19

19

```
void vecAdd(float* A, float* B, float* C, int n)
{
      int size = n * sizeof(float);
      float *A_d, *B_d, *C_d;

1. // Transfer A and B to device memory
   // (error-checking omitted)
    cudaMalloc((void **) &A_d, size);
    cudaMemcpy(A_d, A, size, cudaMemcpyHostToDevice);
    cudaMalloc((void **) &B_d, size);
    cudaMemcpy(B_d, B, size, cudaMemcpyHostToDevice);

   // Allocate device memory for
    cudaMalloc((void **) &C_d, size);

2. // Kernel invocation code – to be shown later
    …
3. // Transfer C from device to host
    cudaMemcpy(C, C_d, size, cudaMemcpyDeviceToHost);
   // Free device memory for A, B, C
    cudaFree(A_d); cudaFree(B_d); cudaFree (C_d);
}
```

 20

20

Example: Vector Addition Kernel

Device Code

```
// Compute vector sum C = A+B
// Each thread performs one pair-wise addition
__global__
void vecAddKernel(float* A_d, float* B_d, float* C_d, int n)
{
    int i = blockIdx.x * blockDim.x + threadIdx.x ;
    if(i<n) C_d[i] = A_d[i] + B_d[i];
}
int vectAdd(float* A, float* B, float* C, int n)
{
   // A_d, B_d, C_d allocations and copies omitted
   // Run ceil(n/256) blocks of 256 threads each
    vecAddKernel<<<ceil(n/256.0), 256>>>(A_d, B_d, C_d, n);
}
```

21

Example: Vector Addition Kernel

```
// Compute vector sum C = A+B
// Each thread performs one pair-wise addition
__global__
void vecAddKernel(float* A_d, float* B_d, float* C_d, int n)
{
    int i = blockIdx.x * blockDim.x + threadIdx.x;
    if(i<n) C_d[i] = A_d[i] + B_d[i];
}
```

Host Code

```
int vecAdd(float* A, float* B, float* C, int n)
{
 // A_d, B_d, C_d allocations and copies omitted
 // Run ceil(n/256) blocks of 256 threads each
  vecAddKernel<<<ceil(n/256.0),256>>>(A_d, B_d, C_d, n);
}
```

22

22

More on Kernel Launch

Equivalent Host Code

```
int vecAdd(float* A, float* B, float* C, int n)
{
 // A_d, B_d, C_d allocations and copies omitted
 // Run ceil(n/256) blocks of 256 threads each
  dim3 DimGrid(n/256, 1, 1);
  if (0 != (n % 256)) { DimGrid.x++; }
  dim3 DimBlock(256, 1, 1);

  vecAddKernel<<<DimGrid,DimBlock>>>(A_d, B_d, C_d, n);
}
```

- Any call to a kernel function is asynchronous from CUDA 1.0 on, explicit synch needed for blocking

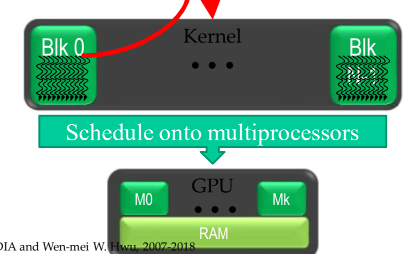
23

23

Kernel execution in a nutshell

```
__host__
void vecAdd()
{
  dim3 DimGrid(ceil(n/256.0),1,1);
  dim3 DimBlock(256,1,1);

vecAddKernel<<<DimGrid,DimBlock>>>
(A_d,B_d,C_d,n);
}
```

```
__global__
void vecAddKernel(float *A_d,
     float *B_d, float *C_d, int n)
{
   int i = blockIdx.x * blockDim.x
       + threadIdx.x;

   if( i<n ) C_d[i] = A_d[i]+B_d[i];
}
```



24

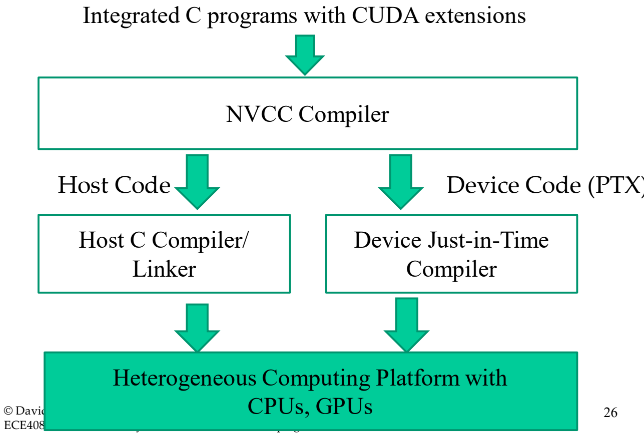
24

More on CUDA Function Declarations

	Executed on the:	Only callable from the:
`__device__ float DeviceFunc()`	device	device
`__global__ void KernelFunc()`	device	host
`__host__ float HostFunc()`	host	host

- `__global__` defines a kernel function
  - Each "__" consists of two underscore characters
  - A kernel function must return `void`
- `__device__` and `__host__` can be used together

Compiling A CUDA Program



QUESTIONS?