

# Object Oriented Programming II



## ***Algorithms and Data Structures***

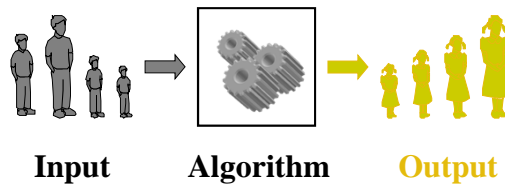
*Analysis*

Singly and double linked lists

Stacks, Queues, Sequences

Iterators

## Analysis of Algorithms



## Important Concepts



- Running time
- Pseudo-code
- Counting primitive operations
- Asymptotic notation
- Asymptotic analysis
- Case study

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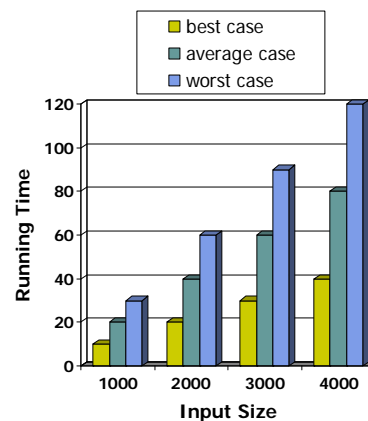
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## Running Time



- The running time of an algorithm varies with the input and typically grows with the input size
- Average case difficult to determine
- We focus on the worst case running time
  - Easier to analyze
  - Crucial to applications such as games, finance and robotics



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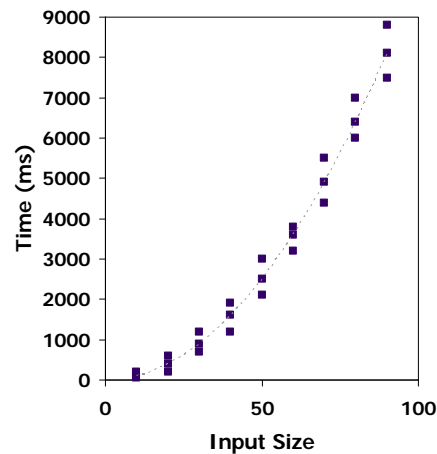
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## Experimental Studies



- Write a program implementing the algorithm
- Run the program with inputs of varying size and composition
- Use a method like `System.currentTimeMillis()` to get an accurate measure of the actual running time
- Plot the results



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## Limitations of Experiments



- It is necessary to implement the algorithm, which may be difficult
- Results may not be indicative of the running time on other inputs not included in the experiment.
- In order to compare two algorithms, the same hardware and software environments must be used

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## Theoretical Analysis



- Uses a high-level description of the algorithm instead of an implementation
- Takes into account all possible inputs
- Allows us to evaluate the speed of an algorithm independent of the hardware/software environment

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## Pseudocode



- High-level description of an algorithm
- More structured than English prose
- Less detailed than a program
- Preferred notation for describing algorithms
- Hides program design issues

Example: find max  
element of an array

**Algorithm** *arrayMax*(*A*, *n*)

**Input** array *A* of *n* integers

**Output** maximum element of *A*

*currentMax*  $\leftarrow A[0]$

**for** *i*  $\leftarrow 1$  **to** *n*  $- 1$  **do**

**if** *A*[*i*] > *currentMax* **then**

*currentMax*  $\leftarrow A[i]$

**return** *currentMax*

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## Pseudocode Details



- Control flow
  - if ... then ... [else ...]
  - while ... do ...
  - repeat ... until ...
  - for ... do ...
  - Indentation replaces braces
- Method declaration
 

**Algorithm** *method* (*arg* [, *arg*...])

    Input ...

    Output ...
- Method call
 

*var.method* (*arg* [, *arg*...])
- Return value
 

**return** *expression*
- Expressions
  - ← Assignment (like = in Java)
  - = Equality testing (like == in Java)
  - $n^2$  Superscripts and other mathematical formatting allowed

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## Primitive Operations



- Basic computations performed by an algorithm
- Identifiable in pseudocode
- Largely independent from the programming language
- Exact definition not important (we will see why later)
- Examples:
  - Evaluating an expression
  - Assigning a value to a variable
  - Indexing into an array
  - Calling a method
  - Returning from a method

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## Counting Primitive Operations



- By inspecting the pseudocode, we can determine the maximum number of primitive operations executed by an algorithm, as a function of the input size

<b>Algorithm</b> <i>arrayMax</i> ( <i>A</i> , <i>n</i> )	# operations
<i>currentMax</i> ← <i>A</i> [0]	2
<b>for</b> <i>i</i> ← 1 <b>to</b> <i>n</i> − 1 <b>do</b>	2 + <i>n</i>
<b>if</b> <i>A</i> [ <i>i</i> ] > <i>currentMax</i> <b>then</b>	2( <i>n</i> − 1)
<i>currentMax</i> ← <i>A</i> [ <i>i</i> ]	2( <i>n</i> − 1)
{ increment counter <i>i</i> }	2( <i>n</i> − 1)
<b>return</b> <i>currentMax</i>	1
	<b>Total</b> 7 <i>n</i> − 1

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## Estimating Running Time



- Algorithm *arrayMax* executes  $7n - 1$  primitive operations in the worst case
- Define
  - a* Time taken by the fastest primitive operation
  - b* Time taken by the slowest primitive operation
- Let  $T(n)$  be the actual worst-case running time of *arrayMax*. We have
 
$$a(7n - 1) \leq T(n) \leq b(7n - 1)$$
- Hence, the running time  $T(n)$  is bounded by two linear functions

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## Growth Rate of Running Time



- Changing the hardware/ software environment
  - Affects  $T(n)$  by a constant factor, but
  - Does not alter the growth rate of  $T(n)$
- The linear growth rate of the running time  $T(n)$  is an intrinsic property of algorithm **arrayMax**

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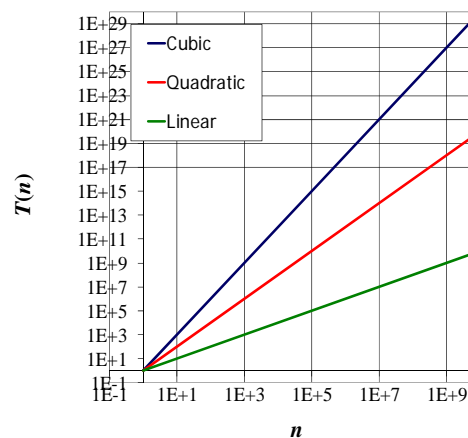
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## Growth Rates



- Growth rates of functions:
  - Linear  $\approx n$
  - Quadratic  $\approx n^2$
  - Cubic  $\approx n^3$
- In a log-log chart, the slope of the line corresponds to the growth rate of the function



## Big-Oh Notation



- Useful to be able to estimate the CPU or memory resources an algorithm requires.
- "complexity analysis" attempts to characterize the relationship between the size of the data and resource usage with a simple formula.
- This can be useful if you are testing a program with a small amount of data, but later production runs will be with large data sets.

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## Big-Oh Notation ...



- **Notation**
  - The "O" stands for "order of".
- **Dominance**
  - Big-oh notation is only concerned with what happens for very large values of  $N$ , only the largest term in the formula is needed.
  - E.g. the number of operations in some sorts is  $N^2 - N$ . For large values,  $N$  is insignificant compared to  $N^2$ , therefore  $O(N)$  is  $N^2$ , and the  $N$  term is ignored.

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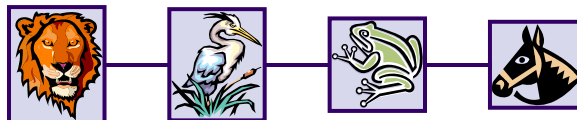
## Big-Oh Notation...



- **Best, worst, and average cases**
- **Typical Orders**
  - Often people characterize the complexity as *constant*  $O(1)$ , *logarithmic*  $O(\log N)$ , *linear*  $O(N)$ , *polynomial*  $O(N^k)$ , *exponential*  $O(2^N)$ . Here is a table of some typical cases. This uses logarithms to base 2, but these are simply proportional to logarithms in other base.

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## Lists and Sequences



## Important Concepts



- Singly linked list
- Position ADT and List ADT
- Doubly linked list
- Sequence ADT
- Implementations of the sequence ADT
- Iterators

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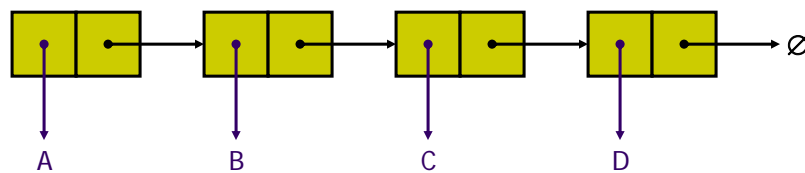
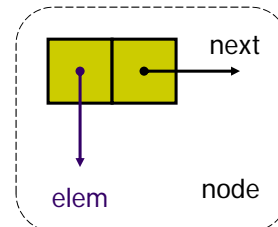
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## Singly Linked List



- A singly linked list is a concrete data structure consisting of a sequence of nodes
- Each node stores
  - element
  - link to the next node



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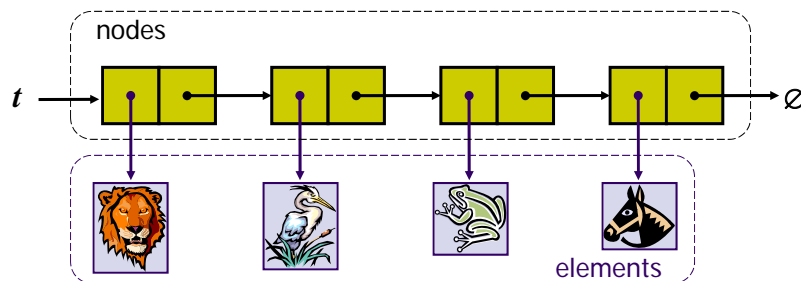
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## Stack with a Singly Linked List



- We can implement a stack with a singly linked list
- The top element is stored at the first node of the list
- The space used is  $O(n)$  and each operation of the Stack ADT takes  $O(1)$  time



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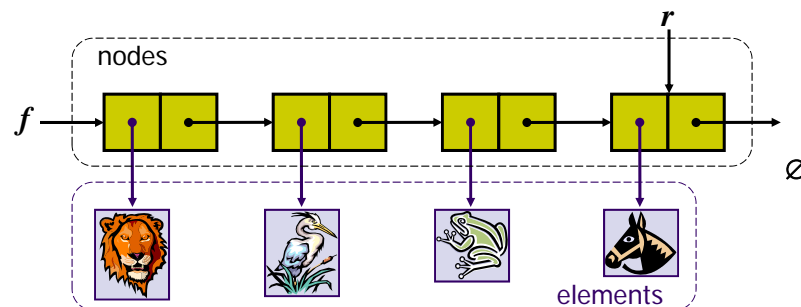
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## Queue with a Singly Linked List



- We can implement a queue with a singly linked list
  - The front element is stored at the first node
  - The rear element is stored at the last node
- The space used is  $O(n)$  and each operation of the Queue ADT takes  $O(1)$  time



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## Position ADT

<<interface>>



- The **Position** ADT models the notion of place within a data structure where a single object is stored
- It gives a unified view of diverse ways of storing data, such as
  - a cell of an array
  - a node of a linked list
- Just one method:
  - object **element()**: returns the element stored at the position

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## List ADT

<<interface>>



- |  |   |
|--|---|
| <ul style="list-style-type: none"> <li>• The <b>List</b> ADT models a sequence of positions storing arbitrary objects</li> <li>• It establishes a before/after relation between positions</li> <li>• Generic methods:           <ul style="list-style-type: none"> <li>• <b>size()</b>, <b>isEmpty()</b></li> </ul> </li> <li>• Query methods:           <ul style="list-style-type: none"> <li>• <b>isFirst(p)</b>, <b>isLast(p)</b></li> </ul> </li> </ul> | <p>Accessor methods:</p> <ul style="list-style-type: none"> <li>• <b>first()</b>, <b>last()</b></li> <li>• <b>before(p)</b>, <b>after(p)</b></li> </ul> <p>Update methods:</p> <ul style="list-style-type: none"> <li>• <b>replaceElement(p, o)</b>, <b>swapElements(p, q)</b></li> <li>• <b>insertBefore(p, o)</b>, <b>insertAfter(p, o)</b></li> <li>• <b>insertFirst(o)</b>, <b>insertLast(o)</b></li> <li>• <b>remove(p)</b></li> </ul> |
|--|---|

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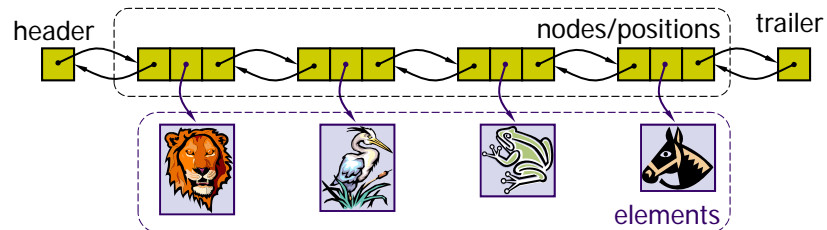
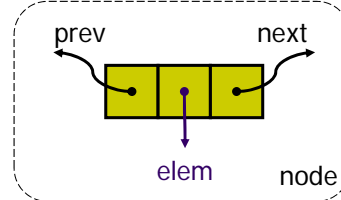
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## Doubly Linked List



- A doubly linked list provides a natural implementation of the List ADT
- Nodes implement Position and store:
  - element
  - link to the previous node
  - link to the next node
- Special **trailer** and **header** nodes



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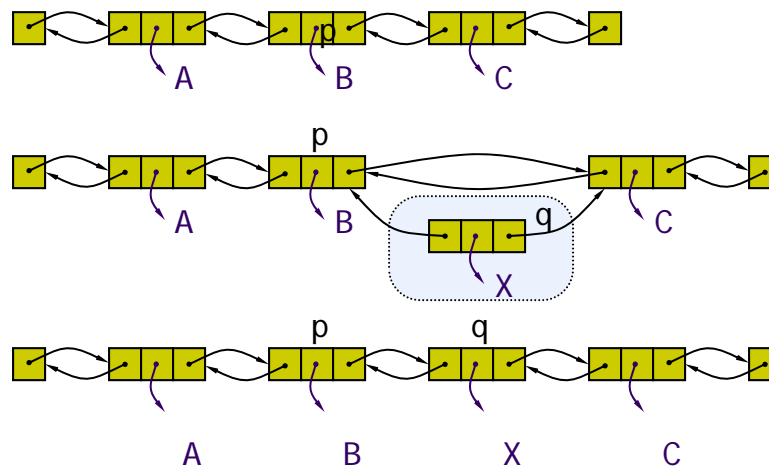
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## Insertion



- We visualize operation **insertAfter(p, X)**, which returns position q



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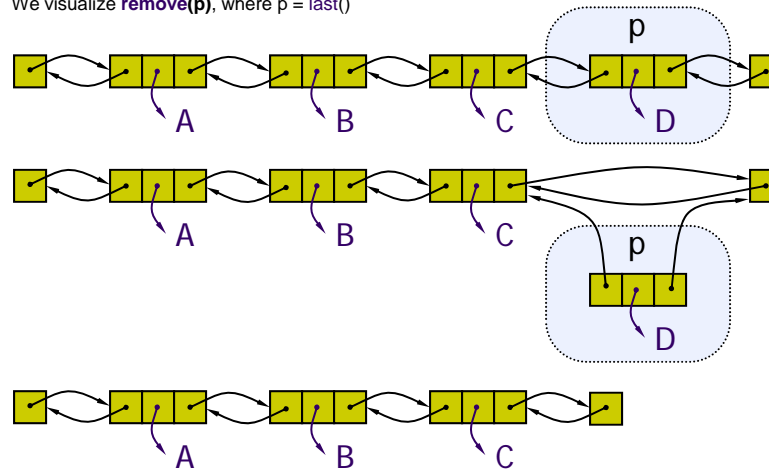
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## Deletion



- We visualize **remove(p)**, where  $p = \text{last}()$



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## Performance



- In the implementation of the List ADT by means of a doubly linked list
  - The space used by a list with  $n$  elements is  $O(n)$
  - The space used by each position of the list is  $O(1)$
  - All the operations of the List ADT run in  $O(1)$  time
  - Operation `element()` of the Position ADT runs in  $O(1)$  time

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## Sequence ADT

<<interface>>



- The **Sequence** ADT is the union of the Vector and List ADTs
- Elements accessed by
  - Rank, or
  - Position
- Generic methods:
  - **size()**, **isEmpty()**
- Vector-based methods:
  - **elemAtRank(r)**, **replaceAtRank(r, o)**, **insertAtRank(r, o)**, **removeAtRank(r)**
- List-based methods:
  - **first()**, **last()**, **before(p)**, **after(p)**, **replaceElement(p, o)**, **swapElements(p, q)**, **insertBefore(p, o)**, **insertAfter(p, o)**, **insertFirst(o)**, **insertLast(o)**, **remove(p)**
- Bridge methods:
  - **atRank(r)**, **rankOf(p)**

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## Applications of Sequences



- The Sequence ADT is a basic, general-purpose, data structure for storing an ordered collection of elements
- Direct applications:
  - Generic replacement for stack, queue, vector, or list
  - small database (e.g., address book)
- Indirect applications:
  - Building block of more complex data structures

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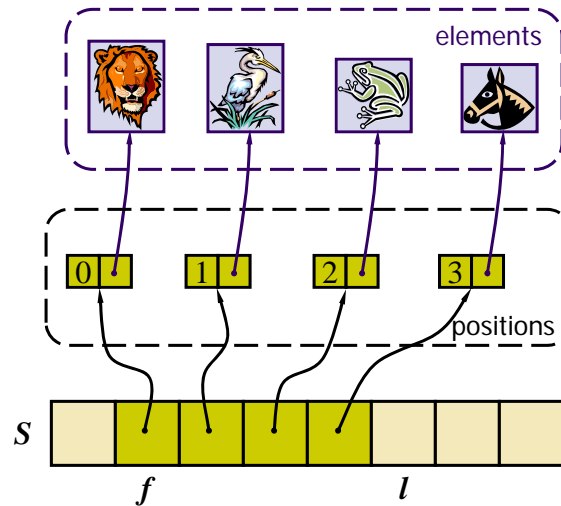
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## Array-based Implementation



- We use a circular array storing positions
- A position object stores:
  - Element
  - Rank
- Indices  $f$  and  $l$  keep track of first and last positions



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## Sequence Implementations



Operation	Array	List
size, isEmpty	1	1
atRank, rankOf, elemAtRank	1	$n$
first, last, before, after	1	1
replaceElement, swapElements	1	1
replaceAtRank	1	$n$
insertAtRank, removeAtRank	$n$	$n$
insertFirst, insertLast	1	1
insertAfter, insertBefore	$n$	1
remove	$n$	1

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## Iterators



- An iterator abstracts the process of scanning through a collection of elements
- Methods of the `ObjectIterator` ADT (<<interface>>):
  - `object object()`
  - `boolean hasNext()`
  - `object nextObject()`
  - `reset()`
- Extends the concept of Position by adding a traversal capability
- Implementation with an array or singly linked list
- An iterator is typically associated with an another data structure
- We can augment the Stack, Queue, Vector, List and Sequence ADTs with method:
  - `ObjectIterator elements()`
- Two notions of iterator:
  - snapshot: freezes the contents of the data structure at a given time
  - dynamic: follows changes to the data structure

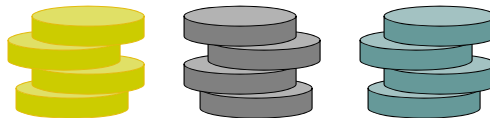
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## Stacks



## Important Concepts



- The Stack ADT
- Applications of Stacks
- Array-based implementation
- Growable array-based stack

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## Abstract Data Types (ADTs)



- An abstract data type (ADT or <<interface>>) is an abstraction of a data structure
- An ADT specifies:
  - Data stored
  - Operations on the data
  - Error conditions associated with operations
- Example: ADT modeling a simple stock trading system
  - The data stored are buy/sell orders
  - The operations supported are
    - order **buy**(stock, shares, price)
    - order **sell**(stock, shares, price)
    - void **cancel**(order)
  - Error conditions:
    - Buy/sell a nonexistent stock
    - Cancel a nonexistent order

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## The Stack ADT

<<interface>>



- The **Stack** ADT stores arbitrary objects
- Insertions and deletions follow the last-in first-out scheme
- Think of a spring-loaded plate dispenser
- Main stack operations:
  - **push(object)**: inserts an element
  - **object pop()**: removes and returns the last inserted element
- Auxiliary stack operations:
  - **object top()**: returns the last inserted element without removing it
  - **integer size()**: returns the number of elements stored
  - **boolean isEmpty()**: indicates whether no elements are stored

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## Exceptions



- Attempting the execution of an operation of ADT may sometimes cause an error condition, called an exception
- Exceptions are said to be “thrown” by an operation that cannot be executed
- In the Stack ADT, operations **pop** and **top** cannot be performed if the stack is empty
- Attempting the execution of **pop** or **top** on an empty stack throws an **EmptyStackException**

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## Applications of Stacks



- Direct applications
  - Page-visited history in a Web browser
  - Undo sequence in a text editor
  - Chain of method calls in the Java Virtual Machine
- Indirect applications
  - Auxiliary data structure for algorithms
  - Component of other data structures

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## Method Stack in the JVM

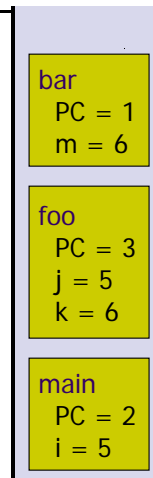


- The Java Virtual Machine (JVM) keeps track of the chain of active methods with a stack
- When a method is called, the JVM pushes on the stack a frame containing
  - Local variables and return value
  - Program counter, keeping track of the statement being executed
- When a method ends, its frame is popped from the stack and control is passed to the method on top of the stack

```
main() {
    int i = 5;
    foo(i);
}
```

```
foo(int j) {
    int k;
    k = j+1;
    bar(k);
}
```

```
bar(int m) {
    ...
}
```



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## Array-based Stack



- A simple way of implementing the Stack ADT uses an array
- We add elements from left to right
- A variable keeps track of the index of the top element

**Algorithm *size()***  
**return  $t + 1$**

**Algorithm *pop()***  
**if *isEmpty()* then**  
     **throw *EmptyStackException***  
**else**  
      $t \leftarrow t - 1$   
     **return  $S[t + 1]$**



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## Array-based Stack (cont.)



- The array storing the stack elements may become full
- A push operation will then throw a *FullStackException*
  - Limitation of the array-based implementation
  - Not intrinsic to the Stack ADT

**Algorithm *push(o)***  
**if  $t = S.length - 1$  then**  
     **throw *FullStackException***  
**else**  
      $t \leftarrow t + 1$   
      $S[t] \leftarrow o$



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## Performance and Limitations



- Performance
  - Let  $n$  be the number of elements in the stack
  - The space used is  $O(n)$
  - Each operation runs in time  $O(1)$
- Limitations
  - The maximum size of the stack must be defined a priori and cannot be changed
  - Trying to push a new element into a full stack causes an implementation-specific exception

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## Growable Array-based Stack



- In a push operation, when the array is full, instead of throwing an exception, we can replace the array with a larger one
- How large should the new array be?
  - incremental strategy: increase the size by a constant  $c$
  - doubling strategy: double the size

```

Algorithm push( $o$ )
  if  $t = S.length - 1$  then
     $A \leftarrow$  new array of
      size ...
    for  $i \leftarrow 0$  to  $t$  do
       $A[i] \leftarrow S[i]$ 
     $S \leftarrow A$ 
   $t \leftarrow t + 1$ 
   $S[t] \leftarrow o$ 

```

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## Stack Interface in Java



- Java interface corresponding to our Stack ADT
- Requires the definition of class `EmptyStackException`
- Different from the built-in Java class `java.util.Stack`

```
public interface Stack {
    public int size();
    public boolean isEmpty();
    public Object top()
        throws EmptyStackException;
    public void push(Object o);
    public Object pop()
        throws EmptyStackException;
}
```

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## Array-based Stack in Java



```
public class ArrayStack
    implements Stack {
    // holds the stack elements
    private Object S[];
    // index to top element
    private int top = -1;
    // constructor
    public ArrayStack(int capacity) {
        S = new Object[capacity];
    }
}
```

```
public Object pop()
    throws EmptyStackException {
    if isEmpty()
        throw new EmptyStackException
            ("Empty stack: cannot pop");
    Object temp = S[top];
    // facilitates garbage collection
    S[top] = null;
    top = top - 1;
    return temp;
}
```

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# Queues



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## The Queue ADT

&lt;&lt;interface&gt;&gt;



- The **Queue** ADT stores arbitrary objects
- Insertions and deletions follow the **first-in first-out** scheme
- **Insertions are at the rear** of the queue and **removals are at the front** of the queue
- Main queue operations:
  - **enqueue(object)**: inserts an element at the end of the queue
  - **object dequeue()**: removes and returns the element at the front of the queue
- Auxiliary queue operations:
  - **object front()**: returns the element at the front without removing it
  - **integer size()**: returns the number of elements stored
  - **boolean isEmpty()**: indicates whether no elements are stored
- Exceptions
  - Attempting the execution of dequeue or front on an empty queue throws an **EmptyQueueException**

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## Applications of Queues



- Direct applications
  - Waiting lists, bureaucracy
  - Access to shared resources (e.g., printer)
  - Multiprogramming
- Indirect applications
  - Auxiliary data structure for algorithms
  - Component of other data structures

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## Array-based Queue

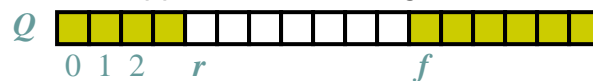


- Use an array of size  $N$  in a circular fashion
- Two variables keep track of the front and rear
  - $f$  index of the front element
  - $r$  index immediately past the rear element
- Array location  $r$  is kept empty

normal configuration



wrapped-around configuration



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## Queue Operations



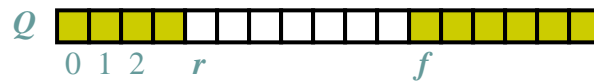
- We use the modulo operator (remainder of division)

**Algorithm *size()***

**return**  $(N - f + r) \bmod N$

**Algorithm *isEmpty()***

**return**  $(f = r)$



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## Queue Operations (cont.)



- Operation enqueue throws an exception if the array is full
- This exception is implementation-dependent

**Algorithm *enqueue(o)***

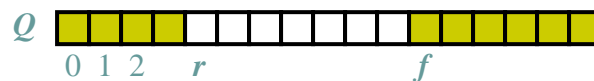
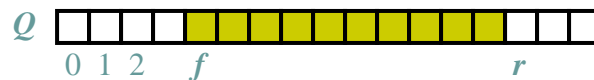
**if**  $size() = N - 1$  **then**

**throw** *FullQueueException*

**else**

$Q[r] \leftarrow o$

$r \leftarrow (r + 1) \bmod N$



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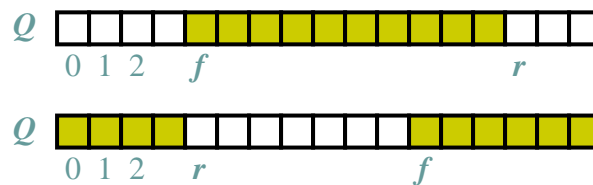
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## Queue Operations (cont.)



- Operation dequeue throws an exception if the queue is empty
- This exception is specified in the queue ADT

**Algorithm *dequeue()***  
**if** *isEmpty()* **then**  
     **throw** *EmptyQueueException*  
**else**  
      $o \leftarrow Q[f]$   
      $f \leftarrow (f + 1) \bmod N$   
     **return**  $o$



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## Growable Array-based Queue



- In an enqueue operation, when the array is full, instead of throwing an exception, we can replace the array with a larger one
- Similar to what we did for an array-based stack
- The enqueue operation has amortized running time
  - $O(n)$  with the incremental strategy
  - $O(1)$  with the doubling strategy

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## Queue Interface in Java



- Java interface corresponding to our Queue ADT
- Requires the definition of class `EmptyQueueException`
- No corresponding built-in Java class

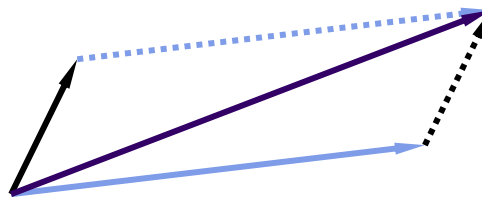
```
public interface Queue {
    public int size();
    public boolean isEmpty();
    public Object front()
        throws EmptyQueueException;
    public void enqueue(Object o);
    public Object dequeue()
        throws EmptyQueueException;
}
```

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## Vectors



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## Important Concepts



- The Vector ADT
- Array-based implementation

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## The Vector ADT

<<interface>>



- The **Vector** ADT extends the notion of array by storing a sequence of arbitrary objects
- An element can be accessed, inserted or removed by specifying its rank (number of elements preceding it)
- An exception is thrown if an incorrect rank is specified (e.g., a negative rank)
- Main vector operations:
  - **object elemAtRank(integer r)**: returns the element at rank r without removing it
  - **object replaceAtRank(integer r, object o)**: replace the element at rank with o and return the old element
  - **insertAtRank(integer r, object o)**: insert a new element o to have rank r
  - **object removeAtRank(integer r)**: removes and returns the element at rank r
- Additional operations **size()** and **isEmpty()**

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## Applications of Vectors



- Direct applications
  - Sorted collection of objects (elementary database)
- Indirect applications
  - Auxiliary data structure for algorithms
  - Component of other data structures

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## Array-based Vector



- Use an array  $V$  of size  $N$
- A variable  $n$  keeps track of the size of the vector (number of elements stored)
- Operation  $elemAtRank(r)$  is implemented in  $O(1)$  time by returning  $V[r]$



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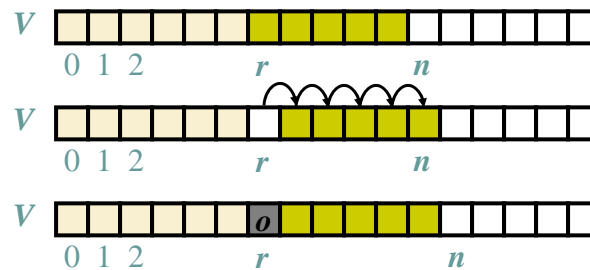
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## Insertion



- In operation **insertAtRank**( $r, o$ ), we need to make room for the new element by shifting forward the  $n - r$  elements  $V[r]$ , ...,  $V[n - 1]$
- In the worst case ( $r = 0$ ), this takes  $O(n)$  time



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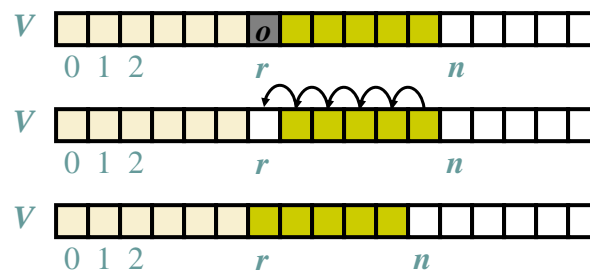
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## Deletion



- In operation **removeAtRank**( $r$ ), we need to fill the hole left by the removed element by shifting backward the  $n - r - 1$  elements  $V[r + 1]$ , ...,  $V[n - 1]$
- In the worst case ( $r = 0$ ), this takes  $O(n)$  time



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## Performance



- In the array based implementation of a Vector
  - The space used by the data structure is  $O(n)$
  - **size**, **isEmpty**, **elemAtRank** and **replaceAtRank** run in  $O(1)$  time
  - **insertAtRank** and **removeAtRank** run in  $O(n)$  time
- If we use the array in a circular fashion, **insertAtRank**(0) and **removeAtRank**(0) run in  $O(1)$  time
- In an **insertAtRank** operation, when the array is full, instead of throwing an exception, we can replace the array with a larger one