

Lecture 24

Monday, 28 March 2022 1:38 PM

Problem: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $f \in \mathcal{C}^1$; f is a convex function
 [Tut Sheet 8.] On set of feasible points

$$\Omega = \{\underline{x} \in \mathbb{R}^n : h(\underline{x}) = 0\} \quad \left(\begin{array}{l} h: \mathbb{R}^n \rightarrow \mathbb{R}^m \\ \Omega \text{ is convex} \end{array} \right)$$

Let $\exists \underline{x}^* \in \Omega$ & $\underline{\lambda}^* \in \mathbb{R}^m$ such that
 $\leftarrow Df(\underline{x}^*) + \underline{\lambda}^{*T} Dh(\underline{x}^*) = \underline{0}^T$.

Then \underline{x}^* is a global minimizer of f .

Proof: (Thm 22.4)
Convexity f is convex on Ω
 $\Leftrightarrow \forall \underline{x}, \underline{y} \in \Omega,$
 $f(\underline{y}) \geq f(\underline{x}) + Df(\underline{x})(\underline{y} - \underline{x})$

Let $\underline{x}, \underline{x}^* \in \Omega$. Since f is convex and $f \in \mathcal{C}^1$,
 $f(\underline{x}) \geq f(\underline{x}^*) + Df(\underline{x}^*)(\underline{x} - \underline{x}^*)$

Lagrange condtn

$$\Rightarrow f(\underline{x}) \geq f(\underline{x}^*) - \underbrace{\underline{\lambda}^{*T} Dh(\underline{x}^*)(\underline{x} - \underline{x}^*)}_{\text{---}}$$

$\underline{x}^*, \underline{x} \in \Omega$; Ω is convex

$$\Rightarrow (1-\alpha) \underline{x}^* + \alpha \underline{x} \in \Omega \quad \alpha \in [0, 1].$$

$$\Rightarrow h((1-\alpha)\underline{x}^* + \alpha \underline{x}) = 0$$

$$\Rightarrow \underline{h}(\underline{x}^* + \alpha(\underline{x} - \underline{x}^*)) = 0$$

$\dots \xrightarrow{\alpha=0} \underline{x}^* \dots \xrightarrow{\alpha=1} \underline{x} \dots$

$$\Rightarrow \underline{h}(\underline{x} + \alpha(\underline{x} - \underline{x}^*)) = 0$$

$$\Rightarrow \frac{\underline{\lambda}^{*\top} \underline{h}(\underline{x}^* + \overbrace{\alpha(\underline{x} - \underline{x}^*)}) - \underline{\lambda}^{*\top} \underline{h}(\underline{x}^*)}{\alpha} = 0$$

Take limit as $\alpha \rightarrow 0$; $\underline{\lambda}^{*\top} D\underline{h}(\underline{x}^*)(\underline{x} - \underline{x}^*) = 0$.

Hence $f(\underline{x}) \geq f(\underline{x}^*) \quad \forall \underline{x} \in \Omega$
 $\Rightarrow \underline{x}^*$ is a global min.

Problem 11 Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $f \in C^1$ is convex on

$\Omega = \{ \underline{x} \in \mathbb{R}^n : \underline{h}(\underline{x}) = 0, g(\underline{x}) \leq 0 \}$; $h: \mathbb{R}^m \rightarrow \mathbb{R}^m$,
 $g: \mathbb{R}^n \rightarrow \mathbb{R}^p$, $h, g \in C^1$, Ω is convex.

Suppose $\exists \underline{x}^* \in \Omega$, $\underline{\lambda}^* \in \mathbb{R}^m$ and $\underline{\mu}^* \in \mathbb{R}^p$ s.t.

$$(i) \quad \underline{\mu}^* \geq 0$$

$$(ii) \quad Df(\underline{x}^*) + \underline{\lambda}^{*\top} Dh(\underline{x}^*) + \underline{\mu}^{*\top} Dg(\underline{x}^*) = 0$$

$$(iii) \quad \underline{\mu}^{*\top} g(\underline{x}^*) = 0.$$

Then \underline{x}^* is a global minimizer of f over Ω .

Proof: Proceed as in the previous result.

$$Df(\underline{x}^*) = - \underline{\lambda}^{*\top} Dh(\underline{x}^*) - \underline{\mu}^{*\top} Dg(\underline{x}^*).$$

$$f(\underline{x}) \geq f(\underline{x}^*) - \underbrace{\underline{\lambda}^{*\top} Dh(\underline{x}^*)(\underline{x} - \underline{x}^*)}_{\text{"0"}} - \underbrace{\underline{\mu}^{*\top} Dg(\underline{x}^*)(\underline{x} - \underline{x}^*)}_{\text{"0"}}$$

(as in the last result).

(as in the last result).

$$f(\underline{x}) \geq f(\underline{x}^*) + (\text{+ve})$$

$$(1-\alpha)\underline{x}^* + \alpha\underline{x} \in \Omega \quad \left\{ \begin{array}{l} \text{if } \Omega \text{ is convex.} \\ g((1-\alpha)\underline{x}^* + \alpha\underline{x}) \leq 0 \end{array} \right.$$

$$g(\underline{x}^* + \alpha(\underline{x} - \underline{x}^*)) \leq 0$$

$$\cancel{\alpha > 0 \text{ (by condtn (i))}} \quad \text{by condtn (iii)}$$

$$\underline{\mu}^{*\top} g(\underline{x}^* + \alpha(\underline{x} - \underline{x}^*)) - \cancel{\underline{\mu}^{*\top} g(\underline{x}^*)} \leq 0$$

$$\lim_{\alpha \rightarrow 0} \frac{\underline{\mu}^{*\top} g(\underline{x}^* + \alpha(\underline{x} - \underline{x}^*)) - \cancel{\underline{\mu}^{*\top} g(\underline{x}^*)}}{\alpha} \leq 0$$

$$\underline{\mu}^{*\top} Dg(\underline{x}^*) (\underline{x} - \underline{x}^*) \leq 0.$$

$$\Rightarrow f(\underline{x}) \geq f(\underline{x}^*) \quad \forall \underline{x} \in \Omega.$$

Example: Linear programming problem in Standard form.

I. maximize $\underline{c}^T \underline{x}$ _{$n \times 1$}
 s.t. $A \underline{x} = \underline{b}$ _{$m \times n$}
 $\underline{x} \geq 0$

II. maximize $\underline{c}^T \underline{x}$
 s.t. $A \underline{x} \leq \underline{b}$
 $\underline{x} \geq 0$

Write KKT conditions:

I. $\min -\underline{c}^T \underline{x}$
 s.t. $A \underline{x} - \underline{b} = 0$
 $-\underline{x} \leq 0$

$$\begin{aligned} \rightarrow f(\underline{x}) &= -\underline{c}^T \underline{x} = -c_1 x_1 - c_2 x_2 - \dots - c_n x_n \\ \rightarrow h(\underline{x}) &= A \underline{x} - \underline{b} = 0. \quad [\text{m condtn}] \\ g(\underline{x}) &= -\underline{x} \leq 0. \quad [\text{n condtn}] \end{aligned}$$

KKT conditions

$\underline{x}^* \rightarrow$ no restriction on sign

KKT conditions

$\underline{x}^* \rightarrow$ no restriction on sign
 $\underline{\mu}^* \geq 0$

Primal feasibility

$$\begin{bmatrix} A\underline{x}^* = \underline{b} \\ \underline{x}^* \geq 0 \end{bmatrix}$$

$$\begin{aligned} g_1(\underline{x}) &= -x_1 & \nabla g_1 &= \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \\ \vdots \\ g_n(\underline{x}) &= -x_n & \nabla g_n &= \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \end{aligned}$$

Stationarity

$$Df(\underline{x}^*) + \underline{\lambda}^{*T} D h(\underline{x}^*) + \underline{\mu}^{*T} Dg(\underline{x}^*) = \underline{0}$$

$$\boxed{\underline{\lambda}^{*T} A - \underline{\mu}^{*T} = \underline{c}^T}$$

$$\begin{aligned} \underline{\mu}^{*T} &= [\mu_1, \dots, \mu_n] \\ Dg(\underline{x}^*) &= \begin{bmatrix} -1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & -1 \end{bmatrix} \end{aligned}$$

Complementarity

$$\underline{\mu}^{*T} \underline{x} = 0.$$

II.

$$\begin{array}{ll} \max & \underline{c}^T \underline{x} \\ \text{s.t.} & \begin{array}{l} A\underline{x} \leq \underline{b} \\ \underline{x} \geq 0 \end{array} \end{array} \quad \left(\begin{array}{c} m \\ n \end{array} \right)$$

$$\begin{array}{ll} \min & -\underline{c}^T \underline{x} \\ \text{s.t.} & \begin{array}{l} g_1(\underline{x}) = A\underline{x} - \underline{b} \leq 0 \\ g_2(\underline{x}) = -\underline{x} \leq 0 \end{array} \end{array} \quad \left(\begin{array}{c} w^* \\ v^* \end{array} \right)$$

$$\underline{\mu}^* = \begin{bmatrix} w^* \\ v^* \end{bmatrix}.$$

$$\begin{cases} w^*, v^* \geq 0. \\ A\underline{x}^* \leq \underline{b}, \underline{x}^* \geq 0 \quad [\text{Primal feasibility}] \\ \underline{w}^{*T} A - \underline{v}^{*T} = \underline{c}^T \quad [\text{Stationarity}] \\ \underline{w}^{*T} (A\underline{x}^* - \underline{b}) = 0; \quad \underline{v}^{*T} \underline{x}^* = 0. \end{cases}$$

$$\text{Example:} \quad \max f(x_1, x_2) = 7x_1 + 6x_2$$

Dual variables

$$\begin{array}{ll} \text{s.t.} & \begin{cases} 3x_1 + x_2 \leq 120 \\ x_1 + 2x_2 \leq 160 \\ x_1 \leq 35 \\ x_1 \geq 0, \end{cases} \end{array}$$

$\rightarrow w_1$

$\rightarrow w_2$

$\rightarrow w_3$

$\rightarrow v_1$

$$\begin{array}{l}
 L \quad \begin{array}{l} x_1 = 0 \\ x_1 > 0, \\ x_2 > 0 \end{array} \quad \begin{array}{l} \rightarrow w_3 \\ \rightarrow v_1 \\ \rightarrow v_2 \end{array} \\
 A = \begin{bmatrix} 3 & 1 \\ 1 & 2 \\ 1 & 0 \end{bmatrix} \quad \underline{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \underline{b} = \begin{bmatrix} 120 \\ 160 \\ 35 \end{bmatrix} \\
 \underline{c} = \begin{bmatrix} 7 \\ 6 \end{bmatrix}
 \end{array}$$

Primal feasibility

$$\begin{bmatrix} 3 & 1 \\ 1 & 2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1^* \\ x_2^* \end{bmatrix} \leq \begin{bmatrix} 120 \\ 160 \\ 35 \end{bmatrix} \\
 \begin{bmatrix} x_1^* \\ x_2^* \end{bmatrix} \geq \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Dual feasibility

$$[w_1 \ w_2 \ w_3] \geq [0 \ 0 \ 0]$$

$$[v_1 \ v_2] \geq 0.$$

Stationarity

$$[w_1 \ w_2 \ w_3] \begin{bmatrix} 3 & 1 \\ 1 & 2 \\ 1 & 0 \end{bmatrix} - [v_1 \ v_2] = [-7 \ 6].$$

Complementary Slack

$$[w_1 \ w_2 \ w_3] \left(\begin{bmatrix} 3 & 1 \\ 1 & 2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} 120 \\ 160 \\ 35 \end{bmatrix} \right) = 0$$

$$[v_1 \ v_2] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$$

A Q M A √ F