

ANN(9)

T-3

Ans ① (a) $pf = \frac{\text{average power}}{\text{apparent power}} = \frac{P}{S} = \frac{P}{(V_{rms} \cdot I_{rms})} = \cos \phi$

$$P = V_{rms} I_{rms} \cos \phi = 20 \times 220 \times 0.75$$

$$P = 3.3 \text{ kW} \quad \text{Ans}$$

(b) Also by connecting a capacitor in parallel with load, so that $pf = 1$

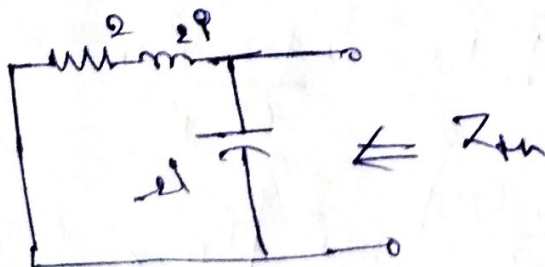
$$C = \frac{P (\tan \phi_{old} - \tan \phi_{new})}{\omega V_{rms}^2}$$

$$\phi_{new} = 0^\circ, \phi_{old} = \cos^{-1}(0.75)$$

$$C = \frac{3300 [(0.8819) - 0]}{2\pi \times 60 \times 220^2} = 1.59 \times 10^{-4} \text{ F}$$

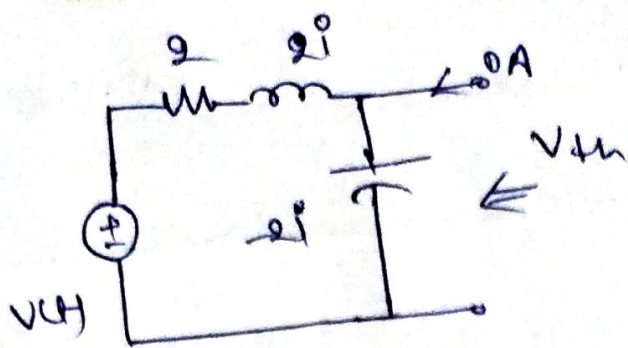
$$C = 0.159 \text{ mF} \quad \text{Ans}$$

Ans ② For MPT across Z_L , let find Thevenin equivalent
N/w across Z_L



$$Z_{th} = (2 + 2j) \parallel (-2j)$$
$$= 2 - 2j$$

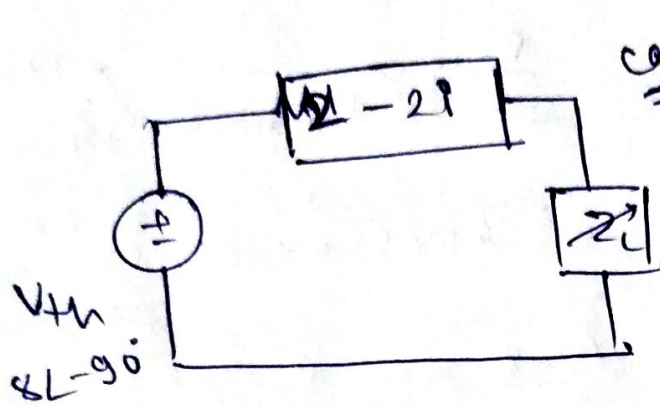
(P-1)



$$V_{th} = \frac{8 \angle 0^\circ \times (-2j)}{(2 + 2j - 2j)}$$

$$= +8 \angle 0^\circ \angle -90^\circ$$

$$= 8 \angle -90^\circ$$



case (I) for MPT
 $Z_L = Z_s^*$

and

$$P_{max} = \frac{(V_{th}^2)_{rms}}{4R_s}$$

$$= \frac{8^2 \angle -180^\circ}{4 \times 2 \times (\sqrt{2})^2}$$

$$= (8 \angle -180^\circ) / 2$$

$$P_{max} = 4W$$

case (II) For Resistive load
 $R_L = \sqrt{R_s^2 + X_L^2} = 2\sqrt{2} = \sqrt{8} \Omega$

$$I_{max} = \frac{V_{th}}{2 - 2j + \sqrt{8}} = \frac{8 \angle -180^\circ}{5.226 \angle 22.5^\circ}$$

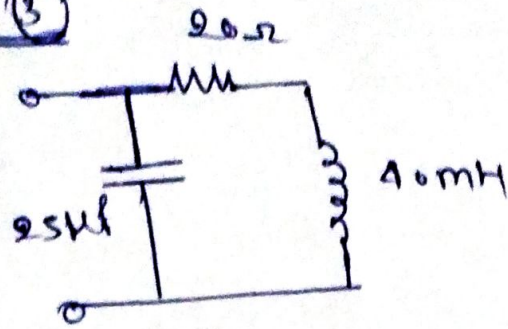
$$= 1.53 \angle -22.5^\circ$$

$$P_{max} = 1.53$$

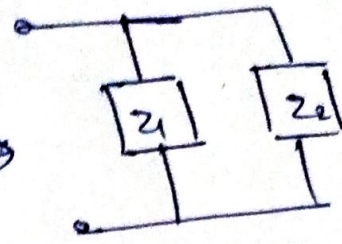
$$P_{max} = |I|^2 R_L = \frac{(1.53)^2 \times \sqrt{8}}{(\sqrt{2})^2} = \frac{6.62W}{2}$$

$$P_{max} = \frac{6.62W}{2} = 3.31 \text{ watt}$$

AN(3)



$\Rightarrow \Rightarrow$
 Z_{eq}



$$Z_1 = -jX_C = -106.157 \Omega$$

$$Z_2 = 20 + jX_L = 20 + j15.072 \Omega$$

Then $Z_{eq} = Z_1 \parallel Z_2$

$$Z_{eq} = 25.92 + j11.875$$

(a)

$$\phi = \tan^{-1} \left(\frac{Z_{eq|Im}}{Z_{eq|Re}} \right) = \tan^{-1} \left(\frac{11.875}{25.92} \right)$$

$$\phi = 24.61 \Rightarrow \boxed{\cos \phi = 0.909}$$

(b)

$\therefore L Z_{eq} = +ve$ and overall behavior of Z_{eq} is inductive hence it is lagging pf.

(c)

value of 'x' to get pf = 1

$$Z_{eq} = \frac{(20 + j15.072)(-jX_C)}{20 + j15.072 + (-jX_C)}$$

$$= \frac{(20 + j15.072)(-jX_C)(20 - j(15.072 - X_C))}{(20)^2 + (15.072 - X_C)^2}$$

for unity pf $\arg \rho_{22} = 0$

$$\frac{[400x_c + 15.072x_c(15.072 - x_c)]}{(20)^2 + (15.072 - x_c)^2} = 0$$

$$400 + 15.072(15.072 - x_c) = 0$$

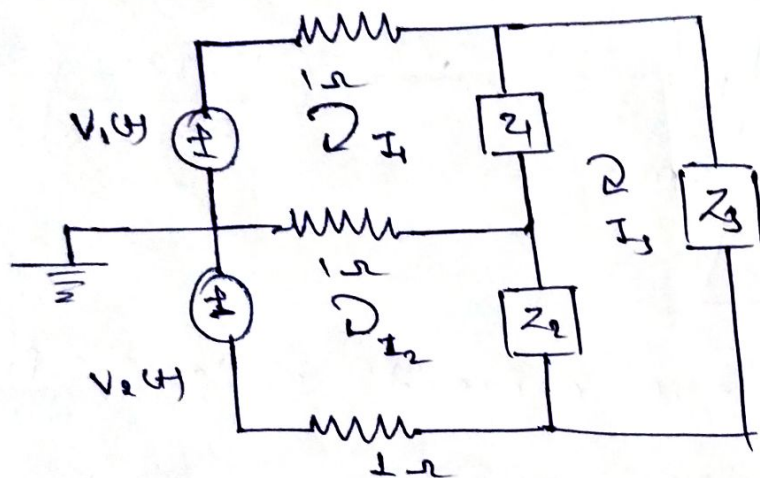
$$x_c = 41.61$$

$$\frac{1}{\omega c} = 41.61$$

$$\Rightarrow C = \frac{1}{2\pi \times 60 \times 41.61} = 63.73 \mu f$$

$$\boxed{C = 63.73 \mu f} \quad \underline{\underline{\text{Ans}}}$$

Ans 4 given ckt



$$V_1(t) = 120\sqrt{2} \sin \omega t$$

$$= 120\sqrt{2} \angle 0^\circ$$

$$V_2(t) = 120\sqrt{2} \cos \omega t$$

$$= 120\sqrt{2} \sin(90^\circ + \omega t)$$

$$= 120\sqrt{2} \angle 90^\circ$$

apply KVL to Loop ①, ② and ③

$$-V_1 + I_1 + Z_1(I_1 - I_3) + (I_1 - I_2) = 0$$

$$\Rightarrow I_1(4 + 5i) - I_2 - (2 + 5i)I_3 = 120\sqrt{2} \quad \text{--- ①}$$

$$-V_2 + (I_2 - I_1) + Z_2(I_2 - I_3) + I_2 = 0$$

$$-I_1 + (5 + 4i)I_2 - (3 + 4i)I_3 = 120\sqrt{2}i \quad \text{--- ②}$$

$$Z_3 I_3 + Z_2 (I_2 - I_1) + Z_1 (I_2 - I_1) = 0$$

$$\Rightarrow -(2+5j)I_1 - (3+4j)I_2 + (10-6j)I_3 = 0 \quad \text{--- (3)}$$

By solving (1), (2), (3)

$$I_1 = 24.51 - j37.17 = 44.52 \angle -56.6^\circ$$

$$I_2 = 13.92 + j30.34 = 33.38 \angle 65.36^\circ$$

$$I_3 = 2.82 + j21.18 = 21.37 \angle 82.42^\circ$$

Hence, power supplied by V_1 :

$$\begin{aligned} P_{avg} &= \frac{1}{2} \cdot V_1 I_1 \cos(\theta_v - \theta_i) \\ &= \frac{1}{2} \times 120\sqrt{2} \times 44.52 (0 - (-56.6^\circ)) \end{aligned}$$

$$\boxed{P_{avg} = 2.079 \text{ kW}}$$

△ Power supply by V_2 :

$$\begin{aligned} P_{avg} &= \frac{1}{2} \times V_2 \times I_2 \cos(\theta_v - \theta_i) \\ &= \frac{1}{2} \times 120\sqrt{2} \times 33.38 (90^\circ - 65.36^\circ) \\ &= 2.57 \text{ kW} \quad \underline{\underline{\text{Ans}}} \end{aligned}$$

Ans (5)

(a)

Time

Phasor domain

$v(t)$

\rightarrow

V

$i(t)$

\rightarrow

V/gw

$10 \cos t$

\rightarrow

$10 \angle 0^\circ$

Hence equation will become \Rightarrow

$$V + \frac{V}{gw} = 10 \angle 0^\circ \Rightarrow V(1 - j) = 10 \angle 0^\circ$$

($\omega = 1 \text{ rad/sec}$)

$$\Rightarrow V(1-j) = 10\angle 0^\circ \Rightarrow V\sqrt{2}\angle -45^\circ = 10\angle 0^\circ$$

$$\Rightarrow V = \frac{10}{\sqrt{2}}\angle 45^\circ = 7.07\angle 45^\circ \text{ V}$$

$$V_{CH} = 7.07 \cos(\omega t + 45^\circ)$$

$$\boxed{V_{CH} = 7.07 \cos(\omega t + 45^\circ)} \quad \underline{\text{Ans}}$$

(b) $\frac{d}{dt}v_{CH} \rightarrow j\omega V, v_{CH} \rightarrow V, \int v_{CH} \rightarrow \frac{V}{j\omega}$

$$\text{Then } j\omega V + 5V + 4j \times \frac{V}{j\omega} = 20\angle 10^\circ$$

$$\omega = 4 \text{ rad/sec}$$

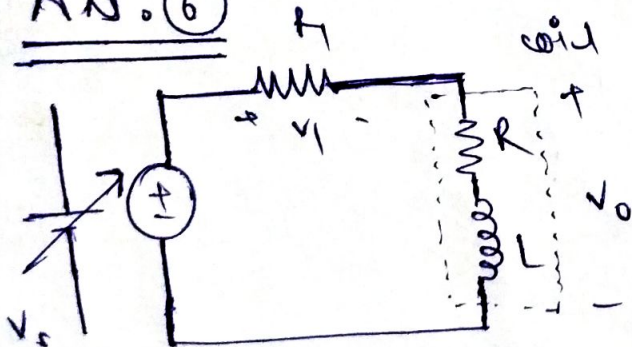
$$4j \times V + 5V + (-jV) = 20\angle 10^\circ$$

$$\Rightarrow (3j + 5)V = 20\angle 10^\circ$$

$$\Rightarrow V = \frac{20\angle 10^\circ}{5.43\angle 30.96^\circ} = 3.43\angle -20.96^\circ \text{ V}$$

$$\boxed{v_{CH} = 3.43 \sin(\omega t - 20.96^\circ)} \text{ V}$$

Ans. (6)



$$|V_s| = 145 \text{ V}$$

$$|V_1| = 50 \text{ V}$$

$$|V_0| = 110 \text{ V}$$

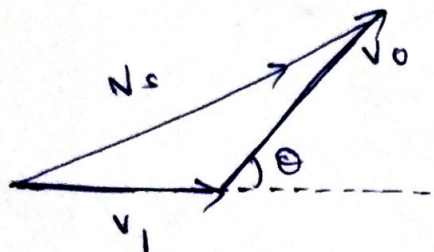
$$f_{\text{req.}} = 60 \text{ Hz}$$

$$R + j\omega L = \frac{|V_0|}{|I_0|} \angle \theta_v - \theta_i \quad \text{--- (1)}$$

For finding θ_v and θ_i ,

Since load is partly inductive, current I_o lags the voltage V_o .

Since V_1 is across a ~~resistor~~ resistor, hence I_o and V_o have same phase.

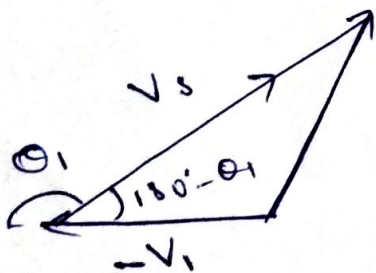


$$|V_o|^2 = |V_1|^2 + |V_o|^2 + 2|V_1||V_o|\cos\theta$$

put all the values

$$\angle \cos\theta = \frac{(145)^2 - (50)^2 - (110)^2}{2 \times 50 \times 110}$$

$$\theta = 54.26^\circ = \theta_v - \theta_i$$



$$|V_o|^2 = |V_1|^2 + |V_s|^2 + 2|V_1||V_s|\cos\theta_1$$

put all the values

and

$$\theta_1 = 141.99^\circ$$

then angle b/w V_s and V_1

$$180^\circ - \theta_1 = 38.01^\circ$$

$$\therefore |I_o| = \frac{|V_1|}{R_1} = \left(\frac{50}{R_1}\right)$$

$$R + j\omega L = \frac{|V_o|}{|I_o|} \angle \theta = \frac{110 \times R_1}{50} \angle 54.26^\circ$$

$$\begin{aligned} R + j\omega L &= 2.2 R_1 (0.584 + j0.812) \\ &= 1.285 R_1 + j1.785 R_1 \end{aligned}$$

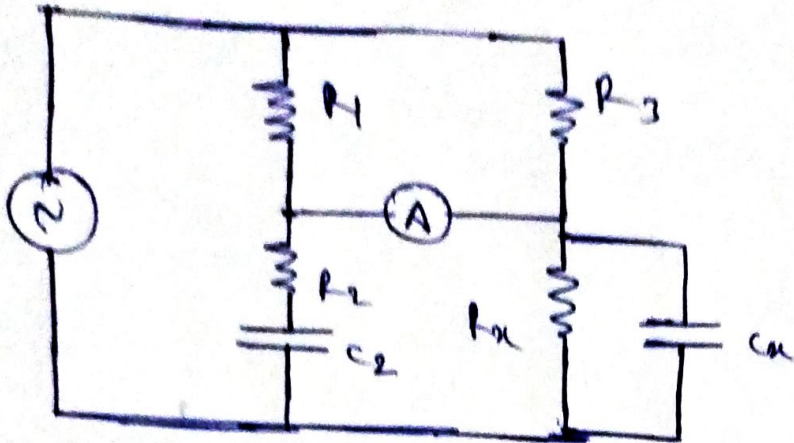
Hence

$$\boxed{R = 1.285 R_1}$$

$$\omega L = 1.785 R_1 \Rightarrow L = \frac{1.785 R_1}{2\pi \times 60}$$

$$\boxed{L = 4.735 R_1 \text{ mH}} \quad \underline{\text{Ans}}$$

Ans (7)



Given

$$R_1 = 400 \Omega$$

$$R_2 = 600 \Omega$$

$$R_3 = 1.2 \text{ k}\Omega$$

$$R_x = 0.3 \text{ k}\Omega$$

$$f_{\text{req}} = 50 \text{ Hz}$$

$$\omega = 100\pi \text{ rad/sec}$$

\therefore bridge is balanced here

$$\frac{R_1}{(R_2 - \frac{j}{\omega C_2})} = \frac{R_3}{R_x \parallel (\frac{-j}{\omega C_x})}$$

$$\Rightarrow \frac{R_1}{R_2 - \frac{j}{\omega C_2}} = \frac{R_3}{\left(\frac{R_x \times (-j/\omega C_x)}{R_x - \frac{j}{\omega C_x}} \right)}$$

\Rightarrow put all the values and arrange it

$$R_2 R_3 - \frac{j R_3}{\omega C_2} = \frac{R_1 R_x (1 - j \omega R_x C_x)}{1 + \omega^2 R_x^2 C_x^2}$$

$$R_2 R_3 = \frac{R_1 R_x}{1 + (\omega R_x C_x)^2} \quad \text{--- (1)}$$

$$\frac{R_3}{\omega C_2} = \frac{\omega R_1 R_x^2 C_x}{1 + (\omega R_x C_x)^2} \quad \text{--- (2)}$$

$$\textcircled{1} \div \textcircled{2}$$

$$\omega R_2 R_3 = \frac{1}{\omega R_x C_x} \Rightarrow$$

$$R_2 C_2 = \frac{1}{\omega^2 R_x C_x} \quad \text{--- (3)}$$

$$R_x C_x = \frac{L}{(100\pi)^2 \times 600 \times 0.3 \times 10^{-6}} = 0.056 \text{ sec.}$$

From eq ①

$$R_2 R_3 = \frac{R_1 R_x}{1 + \omega^2 (R_x C_x)^2}$$

$$\Rightarrow \boxed{R_x = 559 \text{ k}\Omega}$$

Then

$$C_x = \frac{0.56}{556} \times 10^{-3}$$

$$\boxed{C_x = 0.1 \mu\text{F}} \quad \text{Ans}$$