

## Lecture 12

Thursday, 10 February 2022 1:43 PM

Steepest descent for

$$f(\underline{x}) = \frac{1}{2} \underline{x}^T Q \underline{x} - \underline{b}^T \underline{x}$$

$$\begin{bmatrix} Q = Q^T \\ Q > 0 \end{bmatrix}$$

$$\begin{aligned} \nabla f(\underline{x}) &= Q \underline{x} - \underline{b} \\ F &= Q \end{aligned}$$

$$\underline{x}^{(k+1)} = \underline{x}^{(k)} - \alpha_k \nabla f(\underline{x}^{(k)}) \text{ where}$$

$$\alpha_k = \arg \min_{\alpha \geq 0} f(\underline{x}^{(k)} - \alpha \nabla f(\underline{x}^{(k)}))$$

Q<sub>n</sub>: Can we find  $\alpha_k$  explicitly?

$$\text{Recall } \phi_k(\alpha) = f(\underline{x}^{(k)} - \alpha \underline{g}^{(k)})$$

func to  $\phi_k(\alpha)$  yields

$$0 = \phi'_k(\alpha) = \nabla f(\underline{x}^{(k)} - \alpha \underline{g}^{(k)}) \cdot (-\underline{g}^{(k)})$$

$$0 = -(\underline{g}^{(k)})^T (Q(\underline{x}^{(k)} - \alpha_k \underline{g}^{(k)}) - \underline{b})$$

$$\Rightarrow -(\underline{g}^{(k)})^T Q \underline{x}^{(k)} + \underbrace{\alpha_k (\underline{g}^{(k)})^T Q \underline{g}^{(k)}}_{\alpha_k} + \underbrace{(\underline{g}^{(k)})^T \underline{b}}_{= 0} = 0$$

$$\alpha_k (\underline{g}^{(k)})^T Q \underline{g}^{(k)} = (\underline{g}^{(k)})^T [Q \underline{x}^{(k)} - \underline{b}]$$

$$\alpha_k = \frac{(\underline{g}^{(k)})^T \underline{b}}{(\underline{g}^{(k)})^T Q \underline{g}^{(k)}} \quad \text{--- ①}$$

$$\underline{x}^{(k+1)} = \underline{x}^{(k)} - \frac{(\underline{g}^{(k)})^T \underline{b}}{(\underline{g}^{(k)})^T Q \underline{g}^{(k)}} \underline{g}^{(k)}$$

$Q$  is SPD.

$$\text{Ex: } \min f(x_1, x_2) = x_1^2 + x_2^2$$

$$\nabla P = \begin{pmatrix} 2x_1 \\ 2x_2 \end{pmatrix}$$

$$Q = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} = 2 I$$

$$\begin{aligned} \underline{g}^{(0)} &= \nabla f(\underline{x}^{(0)}) \\ &= Q \underline{x}^{(0)} \end{aligned}$$

$$\nabla f = \begin{pmatrix} 2x_1 \\ 2x_2 \end{pmatrix}$$

$$Q = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} = 2 I$$

$$\begin{aligned} g &= \nabla f^{(0)} \\ &= Q \underline{x}^{(0)} \\ &= 2 \underline{x}^{(0)} \end{aligned}$$

$$\underline{x}^{(1)} = \underline{x}^{(0)} - \frac{(g^{(0)})^T g^{(0)}}{(g^{(0)})^T Q g^{(0)}} g^{(0)}$$

$$= \underline{x}^{(0)} - \frac{(g^{(0)})^T g^{(0)}}{2 g^{(0)}^T g^{(0)}} \times 2 \underline{x}^{(0)}$$

$$Q g^{(0)} = 2 g^{(0)}$$

$$\boxed{\underline{x}^{(1)} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}}$$

$$\text{Ex: } f(x_1, x_2) = \frac{x_1^2}{5} + x_2^2$$

Zig-zag path

Chapter 8 → Gradient methods → (Deviation in the convergence analysis).

Convergence of the steepest descent method

[Quadratic forms  
a SPD].

$$\underline{x}^{(k+1)} = \underline{x}^{(k)} - \alpha_k \underline{g}^{(k)}$$

$$\underline{g}^{(k)} = \nabla f(\underline{x}^{(k)})$$

$$\alpha = \dots \text{ in } ①$$

Relation between  $f(\underline{x}^{(k+1)})$  and  $f(\underline{x}^{(k)})$  [skip superscript, subscript]

$$f(\underline{x} + \alpha \underline{d}) = \frac{1}{2} (\underline{x} + \alpha \underline{d})^T Q (\underline{x} + \alpha \underline{d}) - \underline{b}^T (\underline{x} + \alpha \underline{d})$$

$$= f(\underline{x}) + \underbrace{\alpha \underline{x}^T Q \underline{d}}_{\text{from } ①} + \frac{\alpha^2}{2} \underline{d}^T Q \underline{d} - \underbrace{\alpha \underline{b}^T \underline{d}}$$

$$= f(\underline{x}) + \alpha \underline{d}^T [Q \underline{x} - \underline{b}] + \frac{\alpha^2}{2} \underline{d}^T Q \underline{d}$$

$$= f(\underline{x}) - \alpha \underline{d}^T \underline{d} + \frac{\alpha^2}{2} \underline{d}^T \alpha \underline{d}$$

$$= f(\underline{x}) - \frac{(\underline{d}^T \underline{d})^2}{2} + \frac{1}{2} \frac{(\underline{d}^T \underline{d})^2}{(\underline{d}^T Q \underline{d})^2} (\underline{d}^T Q \underline{d})$$

$$\left. \begin{aligned} \alpha &\text{ from } ① \\ \alpha &= \frac{\underline{d}^T \underline{d}}{\underline{d}^T Q \underline{d}} \end{aligned} \right\}$$

$$f(\underline{x}) - \frac{(\underline{d}^T \underline{d})^2}{\underline{d}^T Q \underline{d}} + \frac{1}{2} \frac{(\underline{d}^T \underline{d})^2}{(\underline{d}^T Q \underline{d})^2} (\underline{d}^T Q \underline{d})$$

$$f(\underline{x} + \alpha \underline{d}) = f(\underline{x}) - \frac{1}{2} \frac{(\underline{d}^T \underline{d})^2}{\underline{d}^T Q \underline{d}}$$

[We are writing  $f(\underline{x}^{k+1})$  in terms of  $f(\underline{x}^k)$ ]

Compare  $f(\underline{x}^{k+1})$  and  $f(\underline{x}^k)$

$$\frac{f(\underline{x}^{k+1}) - f(\underline{x}^k)}{f(\underline{x}^k) - f(\underline{x}^*)} \leq \delta \quad (\Rightarrow f(\underline{x}^{k+1}) - f(\underline{x}^*) \leq \delta (f(\underline{x}^k) - f(\underline{x}^*)).$$

We want ' $\delta$ ' to be smaller rather than larger.

$$\underline{x}^* = Q^{-1} \underline{b}$$

$\delta$  depends on the smallest and largest eigenvalue of the Hessian

$$\frac{f(\underline{x}^{k+1}) - f(\underline{x}^*)}{f(\underline{x}^k) - f(\underline{x}^*)} = \frac{f(\underline{x}^k) - \frac{1}{2} \frac{(\underline{d}^T \underline{d})^2}{\underline{d}^T Q \underline{d}} - f(\underline{x}^*)}{f(\underline{x}^k) - f(\underline{x}^*)}$$

$$= 1 - \frac{\frac{1}{2} \frac{(\underline{d}^T \underline{d})^2}{\underline{d}^T Q \underline{d}}}{f(\underline{x}^k) - f(\underline{x}^*)}.$$

$f(\underline{x}) = \frac{1}{2} \underline{x}^T Q \underline{x} - \underline{b}^T \underline{x}$

Exercise  $\rightarrow f(\underline{x}^k) - f(\underline{x}^*)$

HW  $= \frac{1}{2} \underline{d}^T Q \underline{d}$

$$f(\underline{x}^k) - f(\underline{x}^*)$$

$$= 1 - \frac{(\underline{d}^T \underline{d})^2}{(\underline{d}^T Q \underline{d})(\underline{d}^T Q^{-1} \underline{d})}$$

small

$$= \frac{1 - \frac{1}{\rho_k}}{1 - \frac{1}{\rho_k}}$$

$$= 1 - \frac{1}{\rho_k}$$

$$\beta := \frac{(\underline{d}^\top Q \underline{d})(\underline{d}^\top Q' \underline{d})}{(\underline{d}^\top \underline{d})^2}$$

$\lambda_{\min}, \lambda_{\max} \rightarrow Q$

Kantorovich inequality  $\rightarrow$

$$\beta \leq \frac{(\lambda_{\min} + \lambda_{\max})^2}{4 \lambda_{\min} \lambda_{\max}}$$