

Newton's Method

Recall: $\min_{\underline{x} \in \mathbb{R}^n} f(\underline{x}) := \|\mathbf{A}\underline{x} - \mathbf{b}\|^2$
 No constraints

$$\left[\begin{array}{l} \mathbf{A}_{m \times n}, \underline{x}_{n \times 1} \rightarrow \mathbf{b}_{m \times 1} \\ \text{rank } \mathbf{A} = n \\ m \geq n \end{array} \right]$$

FONC $\nabla f(\underline{x}^*) = 0$
Normal equations $(\mathbf{A}^T \mathbf{A}) \underline{x}^* = \mathbf{A}^T \mathbf{b}$.

Given measurement points, we tried fit a 'straight line' that best fits the given data.

Ex-2 Given 'm' measurements of a process at 'm' points in time, fit a 'sinusoidal' curve to fit the measurement data.

$$y = A \sin(\omega t + \phi)$$

A, ω, ϕ
 are unknown parameters

$$\underline{x} = \begin{bmatrix} A \\ \omega \\ \phi \end{bmatrix}$$

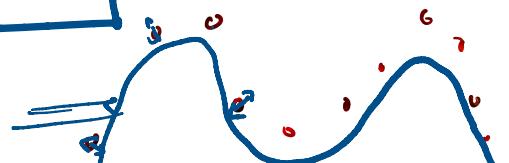
Given

i	1	2	...	m
t_i	t_1	t_2	...	t_m
y_i	y_1	y_2	...	y_m

Find $\underline{x} = \begin{bmatrix} A \\ \omega \\ \phi \end{bmatrix}$ such that the
 objective function

$$f(\underline{x}) = \|\underline{g}_1(\underline{x})\|^2$$

$$= \underline{g}_1(\underline{x})^T \underline{g}_1(\underline{x})$$



$$\left| \begin{array}{l} \underline{g}_1(\underline{x}) = y_i - A \sin(\omega t_i + \phi) \\ \underline{g}_1(\underline{x}) = \begin{bmatrix} g_{11}(\underline{x}) \\ g_{12}(\underline{x}) \\ \vdots \\ g_{1m}(\underline{x}) \end{bmatrix} \end{array} \right.$$

is a minimum.

Problem

$$\min \underline{g}_1(\underline{x})^T \underline{g}_1(\underline{x})$$

Non-linear least-square

Problem

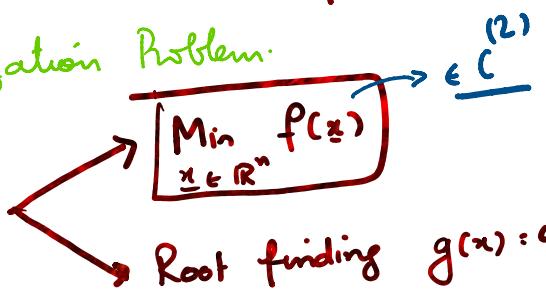
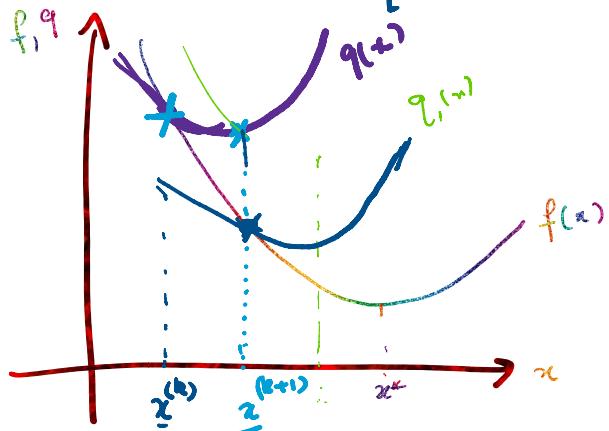
$$\min_{\underline{x} \in \mathbb{R}^n} \underline{g}(\underline{x})^T \underline{g}(\underline{x})$$

(Non-linear least-square problem)

Unconstrained optimization Problem.

Newton's Method

[Newton
Newton - Raphson
Newton - Simpson]



Idea: 1) Given a starting point, construct a quadratic approximation to the objective function that matches the value of the function, the first derivative and the second derivative at the point.

2] Minimize the approximate quadratic function instead of the objective function.

3] Use the minimizer of the approximate quadratic function as the starting point of the next step and repeat the process (iteratively).

ID

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

$$q(x)$$

$$q(x^{(k)}) = f(x^{(k)})$$

$$q'(x^{(k)}) = f'(x^{(k)})$$

$$q''(x^{(k)}) = f''(x^{(k)}).$$

$$q(x) = q(x^{(k)}) + (x - x^{(k)}) q'(x^{(k)}) + \frac{(x - x^{(k)})^2}{2!} q''(x^{(k)})$$

$$q(x) = f(x^{(k)}) + (x - x^{(k)}) f'(x^{(k)}) + \frac{(x - x^{(k)})^2}{2!} f''(x^{(k)})$$

x^* is a minimizer for $q(x) \Rightarrow \boxed{\nabla q(x^*) = 0}$

x^* is a minimizer for $q(x) \Rightarrow \nabla q(x^*) = 0$

$$\nabla q(x) = f'(x^{(k)}) + (x - x^{(k)}) f''(x^{(k)}) = 0$$

$$\Rightarrow (x^* - x^{(k)}) f''(x^{(k)}) = -f'(x^{(k)})$$

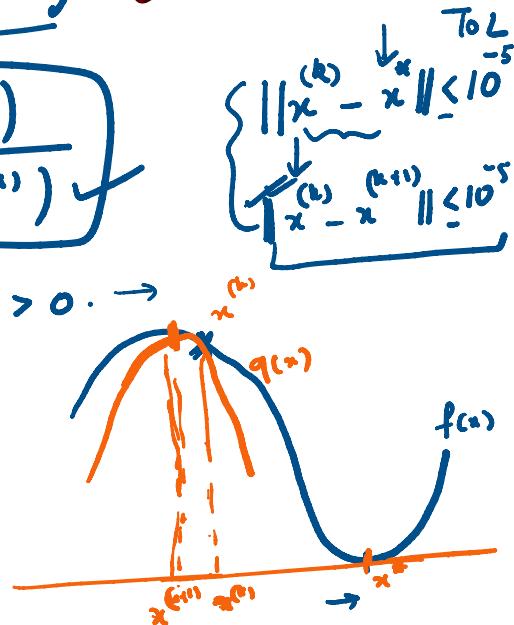
$$\Rightarrow x^* = x^{(k)} - \frac{f'(x^{(k)})}{f''(x^{(k)})} \quad (\neq 0)$$

$$x^{(k+1)} = x^{(k)} - \frac{f'(x^{(k)})}{f''(x^{(k)})}$$

$$\left\{ \begin{array}{l} \|x^{(k)} - x^*\| \leq 10^{-5} \\ \|x^{(k)} - x^{(k+1)}\| \leq 10^{-5} \end{array} \right.$$

Caveats

- Works well mostly if $f''(x) > 0$.
- Fails with bad starting points



Root-finding

$$g(x) = f'(x)$$

$$g(x^{k+1}) \approx g(x^{(k)}) + g'(x^{(k)})(x - x^{(k)})$$

$$x^{(k+1)} = x^{(k)} - \frac{g(x^{(k)})}{g'(x^{(k)})}$$

Extension

$$f : \mathbb{R}^n \rightarrow \mathbb{R}$$

$$f(\underline{x}) \approx q(\underline{x})$$

q is a quadratic approximation.

$$q(\underline{x}^{(k)}) = f(\underline{x}^{(k)})$$

$$\nabla q(\underline{x}^{(k)}) = \nabla f(\underline{x}^{(k)})$$

$$\dots \quad \dots, (k))$$

$$\begin{aligned}\nabla q(\underline{x}^{(k)}) &= \nabla f(\underline{x}^*) \\ \nabla^2 q(\underline{x}^{(k)}) &= \nabla^2 f(\underline{x}^{(k)}) = F(\underline{x}^{(k)})\end{aligned}$$

FONC $\nabla q(\underline{x}^*) = 0$

$$\begin{aligned}f(\underline{x}) &\approx f(\underline{x}^k) + \frac{(\underline{x} - \underline{x}^{(k)})^T \nabla f(\underline{x}^{(k)})}{+ \frac{1}{2} (\underline{x} - \underline{x}^{(k)})^T F(\underline{x}^{(k)}) (\underline{x} - \underline{x}^{(k)})} \\ &= q(\underline{x})\end{aligned}$$

$$\nabla q(\underline{x}) = 0 \Rightarrow \nabla f(\underline{x}^{(k)}) + F(\underline{x}^{(k)}) (\underline{x}^* - \underline{x}^{(k)}) = 0$$

$$\underline{x}^* = \underline{x}^{(k)} - (F(\underline{x}^{(k)}))^{-1} \nabla f(\underline{x}^{(k)})$$

Next iterate for minimizer of f is

$$\boxed{\underline{x}^{(k+1)} = \underline{x}^{(k)} - F(\underline{x}^{(k)})^{-1} \nabla f(\underline{x}^{(k)})}$$

$= 0$

$F > 0$

Algorithm

→ Solve

→ Update

$$F(\underline{x}^{(k)}) \underline{d}^{(k)} = -\nabla f(\underline{x}^{(k)}) \text{ for } \underline{d}^{(k)}$$

(Linear system)

$$\underline{x}^{(k+1)} = \underline{x}^{(k)} + \underline{d}^{(k)}$$

Problem: If f is quadratic, and $F = F^T > 0$,
the Newton's method converges in one step irrespective
of the initial point $\underline{x}^{(0)}$.

PF: $f(\underline{x}) = \frac{1}{2} \underline{x}^T Q \underline{x} - \underline{b}^T \underline{x}$ | $\nabla f(\underline{x}) = Q\underline{x} - \underline{b}$
 $F = Q$

Pf:

$$f(\underline{x}) = \frac{1}{2} \underline{x}^T Q \underline{x} - \underline{b}^T \underline{x}$$

$$\underline{x}^{(1)} = \underline{x}^{(0)} - F(\underline{x}^0)^{-1} \nabla f(\underline{x}^0).$$

$$= \underline{x}^{(0)} - \underline{Q}^{-1} [\underline{Q}\underline{x}^0 - \underline{b}]$$

$$\underline{x}^{(1)} = \underline{x}^{(0)} - \underline{x}^{(0)} + \underline{Q}^{-1} \underline{b} = \underline{Q}^{-1} \underline{b} = \underline{x}^*.$$

$\nabla f(\underline{x}) =$
 $F = Q$
FNC gives
 $\underline{Q}\underline{x}^* - \underline{b} = 0$
 $\underline{x}^* = \underline{Q}^{-1} \underline{b}$

- Qns:
- ① Solution of non-linear least-square problem using
Newton's method
 - ② Convergence of Newton's method