

## Lecture 11

Monday, 7 February 2022 2:00 PM

### Recall:

Directional derivative of  $f$  in the direction of  $\underline{u}$  at  $\underline{x}^{(0)}$  is

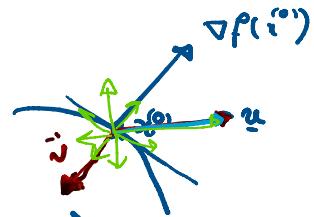
$$\nabla_{\underline{u}} f(\underline{x}^{(0)}) = Df(\underline{x}^{(0)}) \underline{u}$$

$$= \nabla f(\underline{x}^{(0)})^T \underline{u} = \langle \nabla f(\underline{x}^{(0)}), \underline{u} \rangle.$$

### Recall:

$$\underline{x}^{(k+1)} = \underline{x}^{(k)} -$$

$$F(\underline{x}^{(k)})^{-1} \nabla f(\underline{x}^{(k)})$$



Result: At a given point  $\underline{x}^{(0)}$ ,  $\underline{u} = -\nabla f(\underline{x}^{(0)})$  points in the direction of most rapid decrease for  $f(\underline{x})$  and the rate of decrease of  $f(\underline{x})$  at  $\underline{x}^{(0)}$  in this direction is  $-\|\nabla f(\underline{x}^{(0)})\|$ . [Direction of steepest descent.]

### Compute the direction of steepest descent

$$-\|\nabla f(\underline{x}^{(0)})\| = -\|\nabla f(\underline{x}^{(0)})\| \|\underline{u}\| \quad (\because \|\underline{u}\| = 1)$$

$$\leq \langle \nabla f(\underline{x}^{(0)}), \underline{u} \rangle$$

$$= \nabla_{\underline{u}} f(\underline{x}^{(0)})$$

$$\nabla_{\underline{u}} f(\underline{x}^{(0)}) \geq -\|\nabla f(\underline{x}^{(0)})\|$$

$$\begin{aligned} & \text{Cauchy-Schwarz} \\ & |\langle a, b \rangle| \leq \|a\| \|b\| \\ & -\|a\| \|b\| \leq \langle a, b \rangle \\ & \leq \|a\| \|b\| \end{aligned}$$

Minimum value is when we have an equality;

$$\text{that is when } \underline{u} = \frac{-\nabla f(\underline{x}^{(0)})}{\|\nabla f(\underline{x}^{(0)})\|}.$$

[What we were looking for? Which direction  $\underline{u}$  makes  $\nabla_{\underline{u}} f(\underline{x}^{(0)})$  as small as possible?  $\hookrightarrow$  steepest descent direction].

## Method of Steepest descent

Let  $f(\underline{x})$  be a function with continuous partial derivatives on  $\mathbb{R}^n$  and let  $\underline{x}^{(0)} \in \mathbb{R}^n$ . Steepest descent  $\{\underline{x}^{(k)}\}$  with initial point  $\underline{x}^{(0)}$  for minimizing  $f(\underline{x})$  is given by

$$\underline{x}^{(k+1)} = \underline{x}^{(k)} - \alpha_k \nabla f(\underline{x}^{(k)}), \quad \alpha_k > 0$$

with  $\alpha_k$  is the value of  $\alpha > 0$  that minimizes the

$$\text{function } \phi_k(\alpha) = f(\underline{x}^{(k)} - \underline{\alpha} \nabla f(\underline{x}^{(k)})), \quad \underline{\alpha} > 0$$

Example: Find the first 3 terms of steepest descent

$$\text{of } f(x, y) = 4x^2 - 4xy + 2y^2; \quad \underline{x}^{(0)} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}.$$

$$\begin{array}{l} \text{Sln} \\ \nabla f(x, y) = \begin{pmatrix} 8x - 4y \\ -4x + 4y \end{pmatrix} \quad (\nabla f) \begin{pmatrix} 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 8 \times 2 - 4 \times 3 \\ -4 \times 2 + 4 \times 3 \end{pmatrix} \\ = \begin{pmatrix} 4 \\ 4 \end{pmatrix} \end{array}$$

$$\begin{aligned} \underline{x}^{(1)} &= \underline{x}^{(0)} - \alpha \nabla f(\underline{x}^{(0)}) \\ &= \begin{pmatrix} 2 \\ 3 \end{pmatrix} - \alpha \begin{pmatrix} 4 \\ 4 \end{pmatrix} = \begin{pmatrix} \overbrace{2-4\alpha}^{\sim} \\ \overbrace{3-4\alpha}^{\sim} \end{pmatrix}. \end{aligned}$$

$$\phi_0(\alpha) = f(2-4\alpha, 3-4\alpha)$$

$$0 = \phi'_0(\alpha) = \underbrace{-\nabla f(2-4\alpha, 3-4\alpha)}_{\cdot} \cdot \begin{pmatrix} 4 \\ 4 \end{pmatrix}$$

$$0 = -4 \begin{pmatrix} 8(2-4\alpha) - 4(3-4\alpha) \\ -4(2-4\alpha) + 4(3-4\alpha) \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\rightarrow (2-4\alpha) - (3-4\alpha) \quad / / /$$

$$= -16 \begin{pmatrix} 2(2-4\alpha) - (3-4\alpha) \\ -2+4\alpha + 3-4\alpha \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$0 = -16 \left[ \cancel{4} - \cancel{8}\alpha - \cancel{3} + \cancel{4}\alpha - \cancel{2} + \cancel{4}\alpha + \cancel{3} - \cancel{4}\alpha \right]$$

$$0 = -16 [2 - 4\alpha] \Rightarrow \boxed{\alpha_0 = \frac{1}{2}} \quad \varphi''\left(\frac{1}{2}\right) \rightarrow$$

$$\underline{x}^{(1)} = \underline{x}^{(0)} - \frac{1}{2} \nabla f(\underline{x}^{(0)})$$

$$= \begin{pmatrix} 2 - 4 \cdot \frac{1}{2} \\ 3 - 4 \cdot \frac{1}{2} \end{pmatrix} \div \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

$$\underline{x}^{(2)} = \underline{x}^{(1)} - \alpha \nabla f(\underline{x}^{(1)})$$

Check:

$$\varphi_1(\alpha) = f \begin{pmatrix} 4\alpha \\ 1-4\alpha \end{pmatrix}$$

$$\varphi_1'(\alpha) : 0 \Rightarrow \boxed{\alpha_1 = \frac{1}{10}} \quad \text{Check Hw.} \quad \underline{x}^{(2)} = \begin{pmatrix} 2/5 \\ 3/5 \end{pmatrix}$$

$$\underline{x}^{(3)} = \begin{pmatrix} 0 \\ 1/5 \end{pmatrix}.$$

$$\begin{aligned} f(x, y) &= 4x^2 - 4xy + 2y^2 \\ &= 2 [x^2 + x^2 - 2xy + y^2] \\ &= 2 [x^2 + (\underbrace{x-y})^2] \geq 0 \end{aligned}$$

min is 0 at  $(0, 0)$ .

...  $\underline{x}^{(0)} \underline{x}^{(1)} \underline{x}^{(2)} \underline{x}^{(3)}$

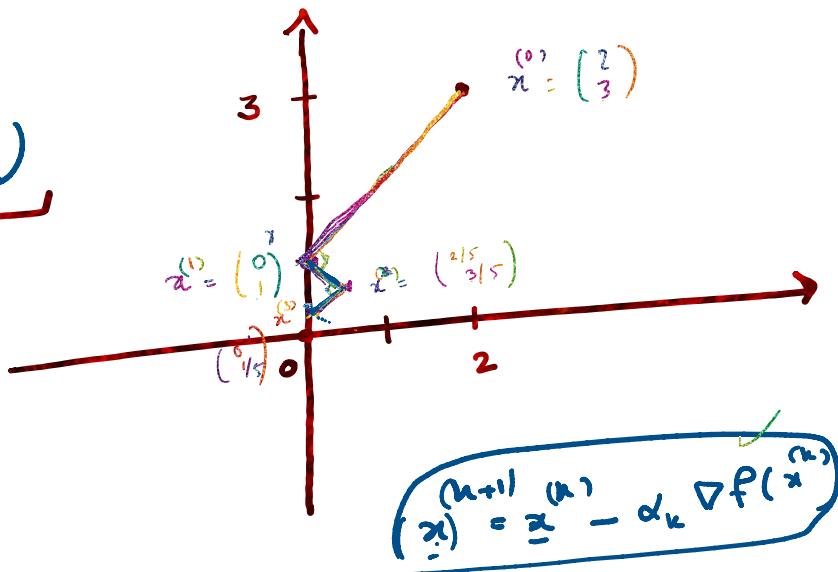
↑

$\underline{x}^{(0)} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

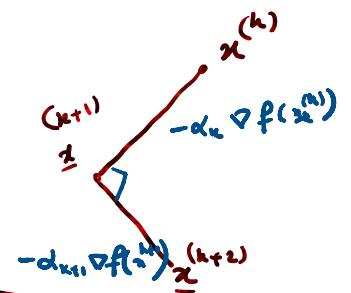
Plot  $\underline{x}^{(0)}, \underline{x}^{(1)}, \underline{x}^{(2)}, \underline{x}^{(3)}$   
 $(\underline{x}^{(k+1)} - \underline{x}^{(k)}) \perp (\underline{x}^{(k+2)} - \underline{x}^{(k+1)})$

Observe that the directions  
are orthogonal!

Is this an accident?



$$(\underline{x}^{(k+1)} - \underline{x}^{(k)}) \cdot (\underline{x}^{(k+2)} - \underline{x}^{(k+1)}) \\ = \alpha_{k+1} \alpha_k \nabla f(\underline{x}^{(k)}) \nabla f(\underline{x}^{(k+1)}) = 0$$



$\underline{x}^{(k+1)} = \underline{x}^{(k)} - \alpha_k \nabla f(\underline{x}^{(k)})$  where  $\alpha_k$  is a minimizer of

$$\phi_k(\alpha) = f(\underline{x}^{(k)} - \alpha \nabla f(\underline{x}^{(k)})) \quad \alpha \geq 0.$$

$\alpha_k$  satisfies

$$0 = \phi'_k(\alpha_k) = \nabla f(\underline{x}^{(k+1)}). \nabla f(\underline{x}^{(k)})$$

We proved: The method of steepest descent moves in perpendicular steps. If  $\{\underline{x}^{(k)}\}$  is a steepest descent sequence for the function  $f(z)$ , then for each  $k \in \mathbb{N}$ , the vector joining  $\underline{x}^{(k)}$  to  $\underline{x}^{(k+1)}$  is orthogonal to the vector joining  $\underline{x}^{(k+1)}$  to  $\underline{x}^{(k+2)}$ .

Drawbacks: Inherently slow; same direction

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Computationally inefficient.

Direction of negative gradient is the best when we start, but later on ceases to be the best; Zigzag paths as it pursues the search in the same directions.

Theorem: If  $\{\underline{x}^{(k)}\}$  is the steepest descent sequence for  $f(\underline{z})$  and if  $\nabla f(\underline{x}^{(k)}) \neq 0$  for some  $k$ , then

+ point over  
Newton's method.

$$\text{Pf: } \underline{x}^{(k+1)} = \underline{x}^{(k)} - \alpha_k \nabla f(\underline{x}^{(k)})$$

\* -  $\alpha_k$  is the minimizer of  $\phi_k(\alpha) = f(\underline{x}^{(k)} - \alpha \nabla f(\underline{x}^{(k)}))$

$$f(\underline{x}^{(k+1)}) = \phi_k(\alpha_k) \leq \phi_k(\alpha) \quad \text{for some } \alpha \text{ or all } \alpha \quad (\alpha \geq 0). \quad \boxed{f(\underline{x}^{(k)}) = \phi_k(0)}$$

as \* holds.

Akash

$$f(\underline{x}^{(k+1)}) = f(\underline{x}^{(k)}) + \nabla f(\underline{x}^{(k)}) \cdot (\underline{x}^{(k+1)} - \underline{x}^{(k)}) + O(\|\underline{x}^{(k+1)} - \underline{x}^{(k)}\|^2).$$

$$\underline{x}^{(k+1)} - \underline{x}^{(k)} = -\alpha_k \nabla f(\underline{x}^{(k)})$$

$$f(\underline{x}^{(k+1)}) = f(\underline{x}^{(k)}) + \frac{1}{2} \alpha_k^2 \|\nabla f(\underline{x}^{(k)})\|^2 + O(\|\underline{x}^{(k+1)} - \underline{x}^{(k)}\|^2)$$

$$f(\underline{x}^{(k+1)}) - f(\underline{x}^{(k)}) = -\alpha_k \|\nabla f(\underline{x}^{(k)})\|^2 \leq 0$$

$$\phi'_k(\alpha) = -\nabla f(\underline{x}^{(k)} - \alpha \nabla f(\underline{x}^{(k)})) \cdot \nabla f(\underline{x}^{(k)})$$

$$\phi_k(\alpha) = f(\underline{x}^{(k)} - \alpha \nabla f(\underline{x}^{(k)}))$$

$$\phi_k'(\alpha) = -\nabla f(x^{(k)})^\top \nabla f(x^*)$$

$$\phi_k'(\alpha) = -\|\nabla f(x^{(k)})\|^2 < 0$$

$\phi_k$  is a decreasing fn.

$$\exists \bar{\alpha} > 0 \text{ s.t. } \phi_k(0) > \phi_k(\bar{\alpha}) \quad 0 \leq \alpha \leq \bar{\alpha}$$

$$\Rightarrow f(x^{(k+1)}) = \phi_k(\alpha_k) \leq \varphi_k(\bar{\alpha}) < \varphi_k(0) = f(x^{(k)}).$$

Descent methods.

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Remark:

$$\min_{x \in \mathbb{R}^n} f(x)$$

$f$  is  $\begin{cases} \text{Coercive} \\ \text{Convex} \end{cases}$

$$\left[ \frac{1}{2} x^T Q x - b^T x + c \right]$$

positive outcome  
of steepest descent.