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Examination	University	Institute	Year	CPI / %
Graduation	IIT Bombay	IIT Bombay	2024	8.19
Intermediate	CBSE	P.S.B.B.S.S School KK Nagar	2020	98.20%
Matriculation	CBSE	P.S.B.B.S.S School KK Nagar	2018	98.80%

Pursuing Honours in Computer Science and a Minor in ML and Data Science from CMInDS SCHOLASTIC ACHIEVEMENTS

• Secured All India Rank 308 in Joint Entrance Examination Advanced among 1.5 Lakh candidates	['20]
• Present in the top 0.5% in Joint Entrance Examination Mains among 0.85 million candidates	['20]

- Two time Recipient of the Kishore Vaigyanik Protsahan Yojana KVPY Fellowship (Both SA & SX Stream) ['20]
- Scored 412/450 Marks in BITSAT (Birla Institute of Technology and Science Admission Test)
- Scored among the top 1% and was qualified for the Indian National Chemistry Olympiad(INChO) ['20]
- Awarded National Talent Search Examination NTSE Scholarship by the Government of India

KEY TECHNICAL PROJECTS

International Aerial Robotics Competition

[Oct'21- Present]

'20]

['18]

UMIC, IIT Bombay | Association for Unmanned Vehicle Systems International Foundation (AUVSI)

- Developing a system of Autonomous Quadcopters for the Longest Running Aerial Robotics Competition
- Working as a **Sr. Machine Learning Engineer** in Team AeRoVe, an **interdisciplinary** team of **25+** students
- $\bullet \ \, \text{Employed a pipeline for a custom-dataset of more than } \, \mathbf{3K+} \, \text{images collected by the drone to speed-up annotation} \,$
- Achieved accuracy(mAP) of 95.6% on YOLOv4 & 85.6% on YOLOv4-tiny models for custom object detection
- Surveyed literature on object detection and tracking, including R-CNN, Fast R-CNNs, YOLOv3, YOLOv4, SORT and DeepSORT to enhance localisation accuracy and ensure smooth autonomous flight of the drone
- Ideated direction vector estimation on 3D Point Cloud data using RANSAC Segmentation & Clustering with PCL
- Reduced inference time by 300% by optimizing detection models by building serialized TRTengines in C++ using the Nvidia TensorRT library while deploying custom-YOLOv4 models on Nvidia Jetson Xavier NX

Deep Reinforcement Learning for Stock Trading

[Apr'21 - Jul'21]

Seasons of Code-'21 | Web and Coding Club (WnCC)

- Trained an intelligent agent to actually trade in the markets, by using various reinforcement learning methods
- Investigated the concepts involved in **Tabular Methods** like Markov Decision Processes, Monte Carlo Methods, Dynamic Programming, Temporal-Difference learning for solving **Reinforcement Learning problems**
- Scrutinized research papers and implemented **PPO** (Proximal Policy Gradient), an Actor-Critic RL algorithm
- Explored classic control problems such as Cartpole & Acrobat-v1 environments in the OpenAI-Gym library
- Examined and backtested quant trading strategies like mean-reversion, pair-trading on Quantconnect platform
- Learnt and tried Technical and Fundamental analysis techniques and methodologies from Zerodha Varsity

ArcFace: Deep Face Recognition Model

[Aug'21 - Nov'21]

 $GNR638\ Course\ Project\ |\ Guide:\ Prof. Biplab\ Banarjee$

- Surveyed literature on face recognition including DeepFace, FaceNet, SphereFace, CosFace and the State-of-the-Art Arcface paper to learn discriminative feature vectors and implement few-shot face recognition
- Implemented Arcface Layer from scratch and used transfer learning with ResNet50 architecture as backbone feature extractor in TensorFlow to get highly discriminative features and acheived a verification acc. of 93.2%
- Trained the Arcface model on the LFW (Labeled Faces in the Wild) dataset of 350+ people with 1.4K+ images
- Designed experiment and analysed results to compare Adam & SGD and determine the best optimizer for training
- Estimated the distance threshold and evaluated various distance metrics for optimal model performance
- Deployed the model using python based **Flask** micro web framework with a frontend UI designed with HTML and CSS to upload images and view results. Ajax and **JavaScript** was used for frontend-backend communication

DRDO'S UAV-Guided UGV Navigation Challenge

[Mar'22 - Apr'22]

Team AeRoVe | Inter-IIT Tech Meet 10.0

- Won 3rd place in DRDO's navigation challenge among 12 IITs at the InterIIT Tech Meet representing IITB
- Developed a combination of an Unmanned Ground Vehicle (UGV) and a guiding Unmanned Aerial Vehicle (UAV) autonomously capable of mapping and navigating snow covered mountainous terrain solely using **drone feedback**
- Experimented with various keypoint detection algorithms on images to find the pose and heading of the UGV
- Combined CV techniques such as Canny Edge Detection, Sobel Filters, Blurring, Adaptive Thresholding and Countour Detection with ML algorithms to get 99%+ precision in the location and direction of UGV
- Implemented a DNN for **Terrain Semantic Segmentation** to derive waypoints for control and navigation

ASR Role Playing Seminar

CS753 Course Project | Guide: Prof.Preethi Jyothi

- Presented a seminar talk on a paper on Audio-Visual Video Parsing discussing the task, method and experiments
- Implemented End-to-End Neural Speaker Diarization which partitions audio input according to speaker identity
- Reviewed a paper titled Learning Audio-Visual Dereverberation and analysed the pros & cons of the model
- Prepared a poster for the BERT-ASR paper highlighting the main ideas of the paper visually with minimal text
- Compiled a scientific report on the paper titled Mask-CTC explaining the architecture & training method used
- Used Kaldi ASR and Coqui deep-learning toolkits to train and make ASR and STT systems in regional languages

ASME Student Design Challenge 2021

[Jan '21 - Apr'21]

[Jan'22-Apr'22]

UMIC, IIT Bombay | American Society of Mechanical Engineers (ASME)

- International Student Design Challenge focusing on efficient energy capture, storage and use in robotics
- Secured 4th position WORLDWIDE in the World Finals stage of the competition amongst 30+ teams
- Worked in the Mechanical subsystem to build a bot to carry a 5 kg payload powered by a single AAA battery
- Designed the robot and made a 3D CAD model in Fusion360 and analyzed the mechanical feasibility of the design
- Engineered circuit to charge super-capacitor and battery using a solar panel and wind turbine under 60 seconds

OTHER PROJECTS

Float-Moodle [Nov'21-Dec'21]

CS251 Course Project | Guide:Prof.Amitabha Sanyal

- Collaborated with a team of 4 students and created a website to aid students and professors with course logistics
- Developed using **Django framework** and PostGreSQL DB and provided several features to upload assignments, lectures, perform auto-grading of submissions, conduct tests and calculate various statistics for students in a class
- Created a **Command Line Interface** using Python, **Bash** and Django REST Framework to build the APIs required to communicate with the website for uploading assignments and fetching other relevant course information

Car Price Prediction Model

[Jun'21]

Self Project

- Trained a Random Forest Regressor with test set RMSE of 1.31 to predict resale value of cars using sk-learn
- $\bullet \ \, \text{Deployed model using $\bf Flask \& Jsonify libraries and created front-end interface using $\bf HTML$ to get input data}$

Hactoberfest 2021 [Oct'21]

 $Self\ Project$

- Hacktoberfest is a monthlong celebration of **open source** software by DigitalOcean, Intel and Deepwrite
- Contributed 5 PRs which were inspected and merged to 4 different repositories maintained by WNCC IIT Bombay

LEADERSHIP ROLES

Manager, Team AeRoVe | Innovation Cell IITB

[May'22 - Present]

 $UMIC\ aims\ to\ facilitate\ technical\ start-ups\ and\ foster\ an\ atmosphere\ of\ innovation\ \mathscr{E}\ entrepreneurship$

- Managing a team of 22, responsible for gaining sponsorships and establishing a strong social media presence
- Moderating and channeling information between the Core team members and the Non-Core team members
- Managing a budget of ₹1.5+ million and responsible for procuring required equipment for the technical team
- Conducted a 3-phase recruitment drive for the biz-team and shortlisted 5 candidates out of 70+ total applicants
- Mentoring and training 2 freshman students in the Machine Learning & Computer Vision subsystem of AeRoVe

Coordinator, Team AeRoVe | UMIC IIT Bombay

[Jan'21 - May'22]

 $Team\ of\ 25+\ students\ working\ on\ autonomous\ ground\ \mathcal{E}\ aerial\ vehicles\ competing\ internationally$

- Member of the team in charge of planning, organizing and publicizing events under the Innovation Cell
- ullet Spearheaded 2 technical recruitment drives to induct members from a pool of 200+ UG applicants for core team
- Mentored a team of 5 freshmen recruits in the S.T.A.R Program to ideate and solve complex-robotics projects

TECHNICAL SKILLS

Programming Languages Python, C, C++, Java, Bash, URDF, Xacro

ML & Data Science
TensorFlow, PyTorch, TensorRT, OpenCV, Numpy, Pandas, Scipy, scikit-learn
Git, LATEX, Arduino, ROS, Gazebo, Kaldi ASR, Coqui STT, Fusion360

Web Development HTML, CSS, Bootstrap, Javascript, Django, Flask

KEY COURSES UNDERTAKEN

Computer Science Data Structures and Algorithms, Software Systems Lab, Discrete Structures, Computer Net-

works, Design and Analysis of Algorithms, Operating Systems*, Compilers**

ML/DL & Statistics ML for Remote Sensing II, Automatic Speech Recognition, Foundations of Intelligent & Learning Agents*, Artificial Intelligence*, Data Analysis and Interpretation, Machine Learning

Specialization^{\$}, Deep Learning Specialization^{\$}, Fundamentals of Reinforcement Learning^{\$}

* To be completed by Dec '22

** To be completed by Apr '23

\$ Online Courses

EXTRA-CURRICULAR ACTIVITIES

- Mentored two teams of young scientific minds in the TrailBlazHER Innovation Challenge 2021
- Trained for 9 years in Alan-Thilak Shito Ryu Karate and Silambattam and received a Black-belt
- Placed 2nd in galaxy Science Quiz twice and won the Mind Storm Quiz at IIT Mardras' Forays Mathfest
- Completed a 10 level Robotics course and graduated with distinction in Programming from Kidobotikz
 Attended a 6 week long summer program on Game Theory in Duke Univ's TIP at Shiv Nadar University Noida