

Theoretical and Practical Insights into Graph-Based Indexing

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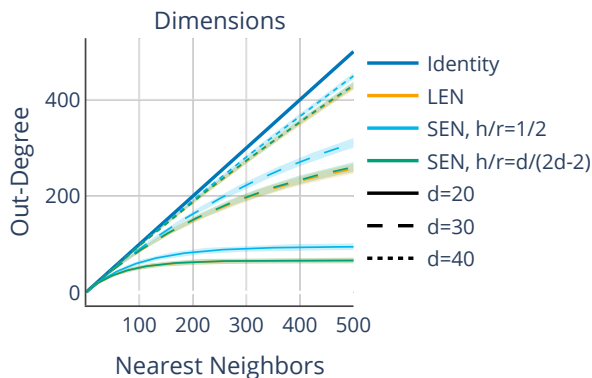
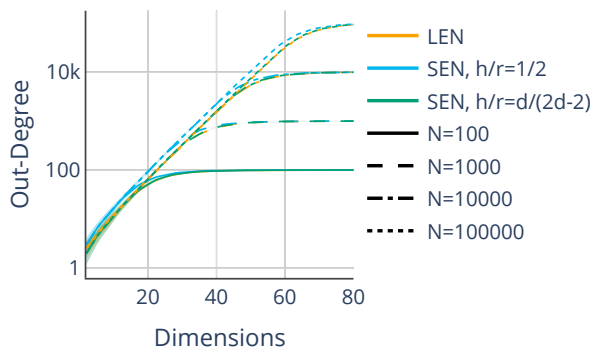
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Motivation

- Graph-based indexing (HNSW, DEG, etc.) works well, but why?
- Literature claims quality based on graph classes (RNG/LEN, SSG/SEN, etc.)
- In dense, high-dim. data, we argue that recall rather follows probabilistics
- The long-term goal is better understanding and autoparametric approaches
- For experiments, new competitive Rust libraries

Graph Classes

- Out-degree of RNG and SSG grows with $\Gamma(d)$
- Practical sparse graphs cannot approximate that
- For small enough k , $k\text{NNG} \subseteq \text{RNG}, \text{SSG}$
- Recall must follow from other properties

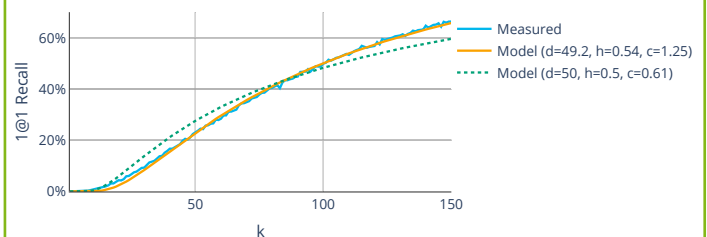


Analysis of Capped Beam Search on $k\text{NNG}$

- We cap the back tracking queue of beam search to size Q
- Probability of a single vertex having a neighbor towards q from geometry
- Probability of the queue having such a neighbor from probability amplification
- Probability of finding the 1-nn from repeated trials with expected path length L

$$p_{beam}(\text{success}) = \left(1 - \left(1 - k/E_{sector}^{(N)}\right)^Q\right)^L$$

N is the dataset size, $E_{sector}^{(N)}$ the expected number of sector exclusion neighbors in N points



This simple model fits real recall okay, but better understanding of L needed.

Implications

- Approximating RNG/SSG in high-dim. is futile
- $k\text{NNG}$ recall can likely (for synthetic data) be modeled
- Automatic suggestion for parameter choice given desired recall likely possible
- Multiple immediate results, e.g.:
 - Capped beam search theoretically useful and practically faster
 - Random edges can improve recall
 - Hierarchies in high-dim. much less useful