Explaining Hubness by the Expected k-occurrences

Summary

- \triangleright A dataset is said to present **hubness** if there are points that exhibit a large *k*-occurrence.
- \triangleright Assuming that the dataset is sampled from i.i.d. random variables, the expected k-occurrence has a close form.
- ▶ We present preliminary ideas on how this expectation can be used to explain hubness.

Dataset model

Given a dataset X we define

► The *k*-neighbourhood relationship for $x, c \in X$

$$Neigh_{\mathcal{X}}^{k}(x;c) \stackrel{\text{def}}{=} \begin{cases} 1 & \text{if } x \text{ is in the } k\text{-nn} \\ 0 & \text{otherwise} \end{cases}$$

▶ The *k*-occurrence of a point $x \in X$

$$Occ_{\mathcal{X}}^{k}(x) \stackrel{\text{def}}{=} |\{c \in \mathcal{X} : Neigh_{\mathcal{X}}^{k}(x;c) = 1\}|$$

Closeness value

► The **closeness value** of a point *x* with respect to a reference point *c* is defined as

$$C(x;c) = \int_{B^c(r_{xc})} f_X(y) \, dy$$

where $B^c(r_{xc})$ denotes the ball centered on c with radius the distance between x and c.

Example

We aim to compute the expected 30-occurrences of points in a set of 1000 points sampled uniformly in the square. The empirical and theoretical computations agree.

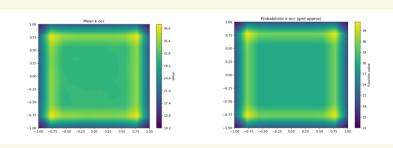


Figure: Empirical mean *k*-occurrence (left) and the theoretical computation (right). The results closely match.

Probabilistic model

Given a pdf f_X we define

► The probability of the *k*-neighbourhood relation

$$\mathcal{N}^{k:N}(x;c) \stackrel{\text{\tiny def}}{=} \mathcal{P}_{x_2...x_N} \stackrel{\text{\tiny i.i.d.}}{\sim} f_X \big(Neigh^k_{\{x,c,x_2...x_N\}}(x;c) = 1 \big)$$

► The expected value of the *k*-occurrence

$$O^{k:N}(x) \stackrel{\text{\tiny def}}{=} \mathbb{E}_{x_1...x_N} \mathop{\stackrel{\text{\tiny i.i.d.}}{\sim}} f_X [Occ^k_{\{x,x_1...x_N\}}(x)]$$

in a dataset sampled from i.i.d. random variables distributed as f_X .

Computation of $O^{k:N}(x)$

Based on the closeness value, we can compute:

► The probability of the *k*-neighbourhood relationship:

$$\mathcal{N}^{k:N}(x;c) = \sum_{i=1}^{k} {N-1 \choose i-1} \mathcal{C}(x;c)^{i-1} (1 - \mathcal{C}(x;c))^{N-i}$$

 \blacktriangleright The expectation of k-occurrence:

$$O^{k:N}(x) = N \int_{\mathbb{R}^D} \mathcal{N}^{k:N}(x;c) f_X(c) dc$$

Findings about Hubness

- ► The total number of points (*N*) and of neighbours (*k*) are necessary in order to define hubs.
- ► The closeness value relates hubness with dimensionality and change of gradients in the pdf (such as borders of the support).
- ► The centrality of a point does not necessarily relate with a higher *k*-occurrence.

