



Writing EPICS Channel Access Clients in Python

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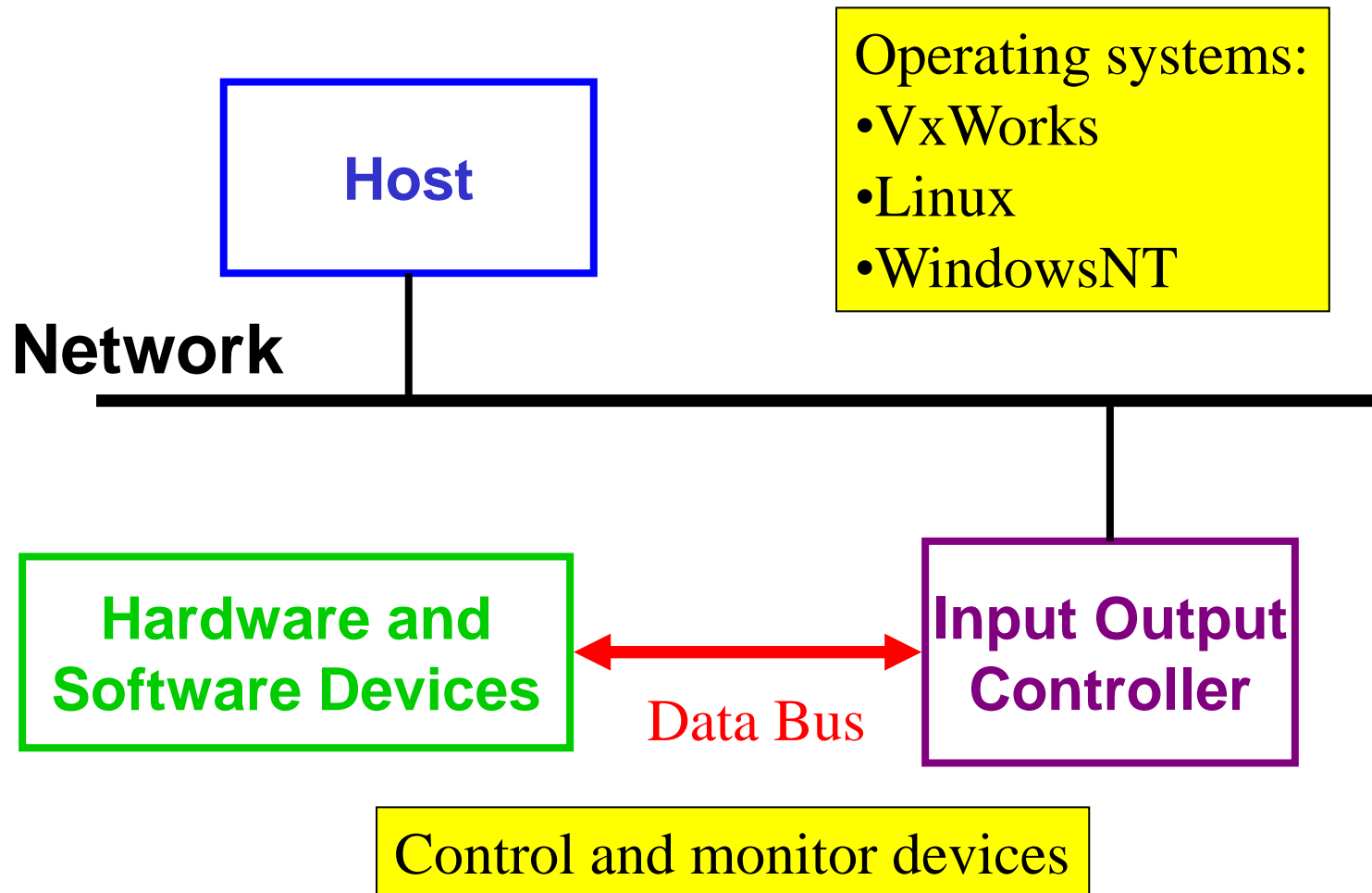


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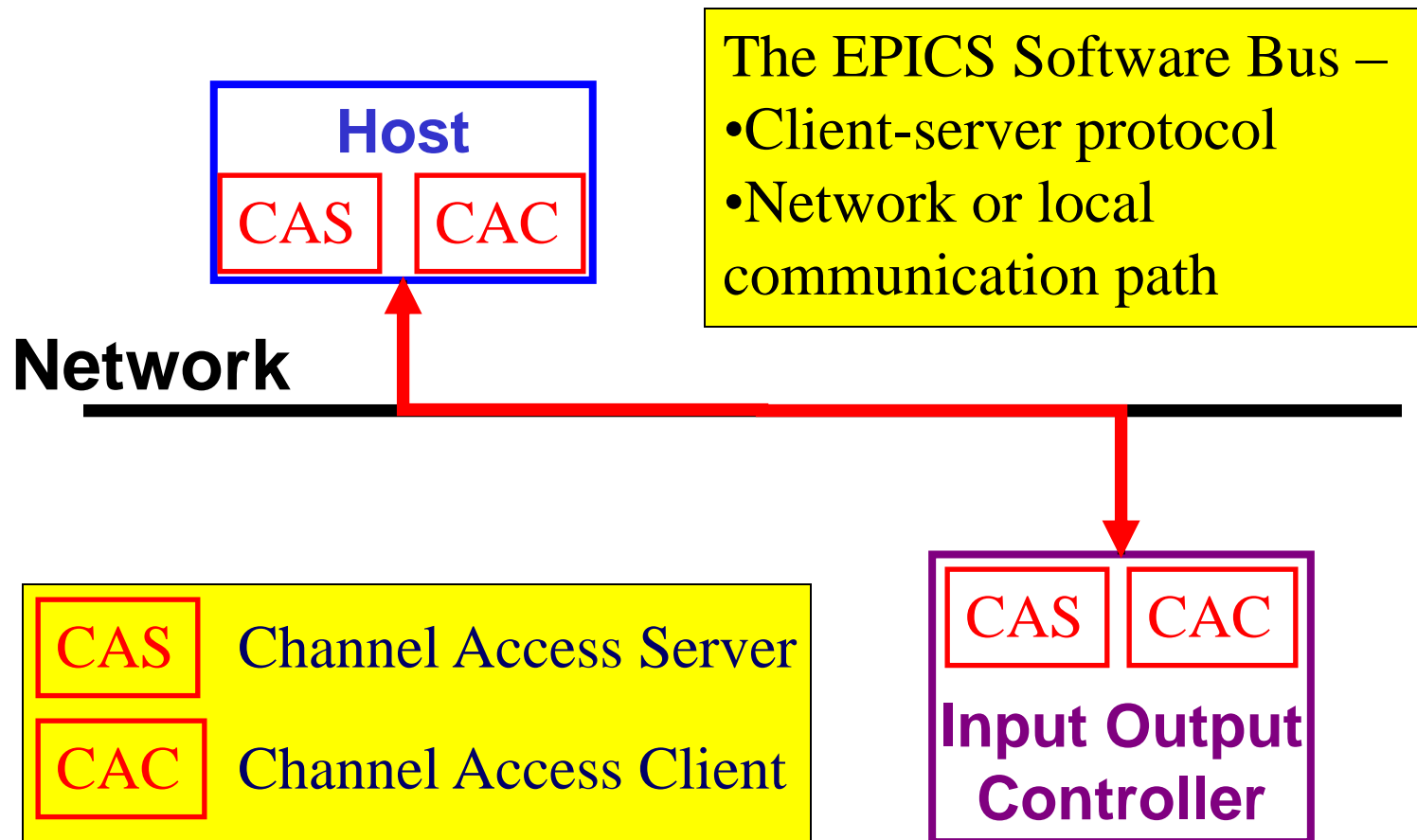


EPICS Architecture





Channel Access





CA Communication



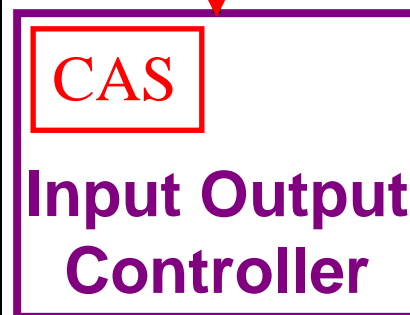
Network

CA Client –

- Connects with a record by name
- Access individual fields in a record
- Read/write, post events on value change, ...

CA Server –

- A record connects data with a name
- Fields in each record specify how to manipulate the data
- Fields for conversions, alarm limits, ...



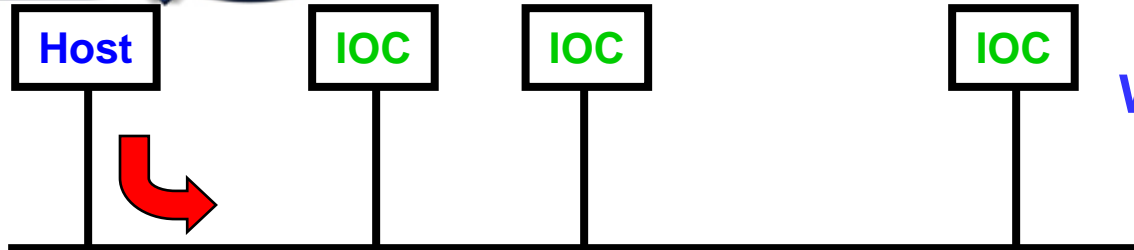


CA Services

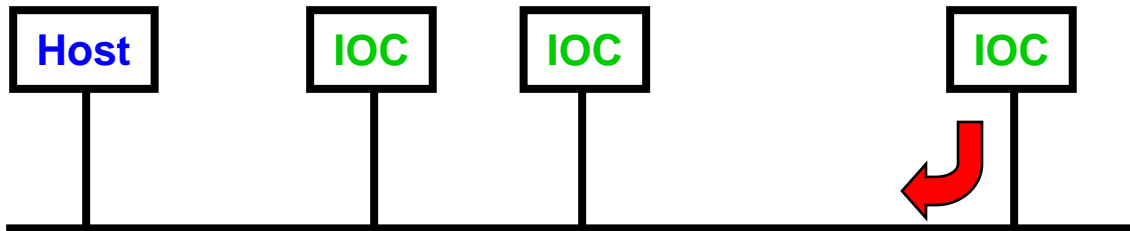
- Dynamic channel creation
- Automatic channel reconnect
- Read
- Write
- Monitoring
 - ♦ Generates callbacks
 - ♦ Events
 - ♦ Access control
 - ♦ Connection
- Data type conversions
- Composite data structures



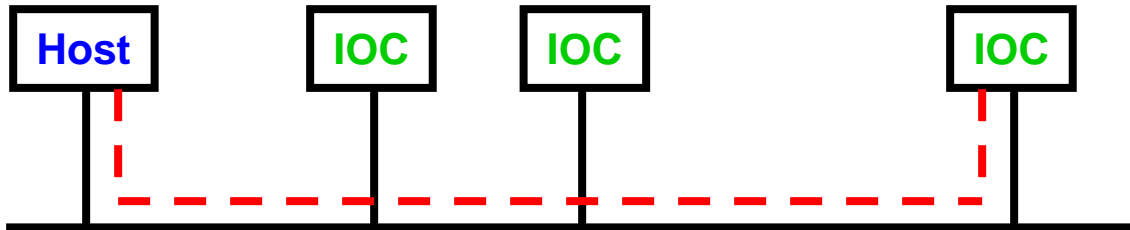
Channel Creation



Who has channel 'XXXX'?
(udp broadcast)



I have channel 'XXXX'.



Negotiate connection.
(point-to-point tcp)



CA Buffering

- “All requests which require interaction with a CA server are accumulated (buffered) and not forwarded to the IOC until one of *ca_flush_io()*, *ca_pend_io()*, *ca_pend_event()*, *ca_sg_pend()* are called allowing several operation to be efficiently sent over the network in one message.”
- Read/write transactions can not be in the same message as the connection request



CA Request Status

- “If the server for a channel is located in a different node than the client then the operations that communicate with the server return status indicating the validity of the request.”
- “In other words, success returned from the client library routine indicates that it checked your request, it appeared to be valid, and it forwarded it to the server.”
- Check the status when the transactions have completed



CA Transaction Status

- “Any process variable values written into your program’s variables by *ca_get()* should not be referenced by your program until ECA_NORMAL has been received from *ca_pend_io()*.”
- Upon receipt of a callback the transaction is complete and the transaction status is available from within the callback.



CA Operation

- “For proper operation CA must periodically be allowed to take care of background activity. This requires that your application must either wait in one of *ca_pend_event()*, *ca_pend_io()*, or *ca_sg_block()*, or it must call *ca_pend_event()* at least every 15 seconds.”



EPICS CA Summary

- EPICS software bus
- Client-server architecture
- Library functionality
 - ♦ Create and maintain connections
 - ♦ Synchronous transactions
 - ♦ Asynchronous transactions
 - ♦ Transaction status reporting
 - ♦ Buffering for efficiency

Details follow in the discussion of CaChannel.



Why Python?

- “Python is an *interpreted, interactive, object-oriented* programming language”
- Fermilab experience
 - ♦ Reduced development time
 - ♦ Portable (Linux, NT, OSF1)
 - ♦ Graphics (Tcl/Tk)
 - ♦ Powerful extension library
 - ♦ Easy to extend (SWIG)
 - ♦ Short learning curve
- www.python.org



Using CA from Python

- Maintain full CA functionality
 - ♦ Callbacks
 - ♦ Data types
- Map each connection to an object
- Two step process
 - ♦ caPython – make the CA library callable from Python (wrapping)
 - ♦ CaChannel – use the wrapped functions in caPython to create channel objects



Simple Interpreter Example

```
[savage@d0ol30 ~]$ setup d0online
```

```
[savage@d0ol30 ~]$ python
```

```
Python 2.1 (#3, May 16 2001, 15:15:15)
```

```
[GCC 2.95.2 19991024 (release)] on linux2
```

```
Type "copyright", "credits" or "license" for more information.
```

```
>>> from CaChannel import *
```

```
>>> ch = CaChannel('catest')
```

Make a connection via a name.

```
>>> ch.searchw()
```

Create the connection.

```
>>> ch.putw(123.456)
```

Write a value.

```
>>> ch.getw()
```

Read a value.

```
123.456
```



Simple Script Example

```
#!/bin/env python  
from CaChannel import *  
def main():  
    try:  
        catest = CaChannel('catest')  
        catest.searchw()  
        catest.putw(123.456)  
        print catest.getw()  
    except CaChannelException, status:  
        print ca.message(status)  
main()
```

Print the error string.



Graphical Interfaces

IOC Resource Monitor Display /

File View Help

CAL CFT CTL MUO MUO/RCT SMT SMT/RCT STT Test

IOC Node	CPU %	Mem %	FD %	
MCH Vertical Interconnect				
d0o1ct103	43	51	48	Reboot
Platform				
d0o1ct109	5	41	46	Reboot
d0o1ct111	13	59	46	Reboot
ICD High Voltage				
d0o1ct126	15	33	44	Reboot
d0o1ct127	14	33	42	Reboot
d0o1ct133	10	33	44	Reboot
CAL High Voltage				
d0o1ct142	15	35	48	Reboot
d0o1ct143	15	35	46	Reboot
d0o1ct144	14	34	46	Reboot
d0o1ct145	17	35	52	Reboot

Status:

Reconnect Reboot

Rack Environment Monitor Display -

File View Help

MCH1S MCH1N MCH2S MCH2N MCH3S MCH3N DAB

Rack	Smoke	Air Flow	Water Leak	Water Flow	Flow g/m	RM DSTAT
M300						Normal Reset
M301					5-6	Normal Reset
M302					5-6	Normal Reset
M303						Normal Reset
M306					2-4	Normal Reset
M307					2-4	Normal Reset
M308					5-6	Normal Reset
M310					<2	Normal Reset
M311					2-4	Normal Reset
M312					2-4	Normal Reset

Status:

Reconnect



Architecture

CaChannel

- ◆ **Python class**
- ◆ **Calls caPython functions**

Move from C functions to a Python class interface.

caPython

- ◆ **Python wrapper around the C library**
- ◆ **Collection of python functions**

EPICS channel access C library

- ◆ **Collection of C functions and macros**
- ◆ **Distributed with EPICS**



CaChannel

- Methods
- Data types
- Synchronous I/O
- Asynchronous I/O
- Monitoring
- Use with Tkinter



CaChannel Construction

- CaChannel is constructed from caPython and the SWIG pointer library
- “SWIG is an interface compiler that connects programs written in C and C++ with scripting languages such as Perl, Python, Ruby, and Tcl.”
- caPython – CA functions, macros, and helper functions wrapped using SWIG
- SWIG pointer library – manipulation of C pointers from Python



CaChannel Methods ...

- Connection
 - ♦ search
 - ♦ search_and_connect
 - ♦ clear_channel
- Synchronization
 - ♦ pend_io
 - ♦ pend_event
 - ♦ poll
 - ♦ flush_io
- Write
 - ♦ array_put
 - ♦ array_put_callback
- Read
 - ♦ array_get
 - ♦ array_get_callback
 - ♦ getValue
- Monitors
 - ♦ add_masked_array_event
 - ♦ clear_event



... CaChannel Methods

- Simple and slow
 - ♦ searchw = search + pend_io
 - ♦ getw = array_get + pend_io
 - ♦ putw = array_put + pend_io
- Information
 - ♦ field_type
 - ♦ element_count
 - ♦ name
 - ♦ state
 - ♦ host_name
 - ♦ read_access
 - ♦ write_access



Synchronous I/O

```
>>>  
>>> ch.search()  
>>> ch.pend_io()  
>>>  
>>> ch.array_put(123.456)  
>>> ch.pend_io()  
>>>  
>>> ch.array_get()  
>>> ch.pend_io()  
>>> ch.getValue()  
123.456
```

- `pend_io` = flush request buffer and wait for CA requests to complete for all CaChannel objects
- Multiple requests can be issued before each `pend_io`
- All connections must be made before `get` or `put`
- On a `get` a value is not valid until `pend_io` has returned with no errors



Data Types ...

```
>>> ch.getw()  
123.456  
>>> ch.getw(ca.DBR_INT)  
123  
>>> ch.getw(ca.DBR_STRING)  
'123'  
>>> ch.field_type()  
6  
>>> ca.dbr_text(ch.field_type())  
'DBR_DOUBLE'  
>>>
```

- Each PV has a native type
- Different data types can be requested
- Requests using the native type are most efficient

Not all caPython functions are implemented as methods of CaChannel.



... Data Types ...

```
>>> scan =  
    CaChannel('catest.SCAN')  
>>> scan.searchw()  
>>> scan.getw()  
6  
>>> scan.getw(ca.DBR_STRING)  
'1 second'  
>>> scan.putw(5)  
>>> scan.getw(ca.DBR_STRING)  
'2 second'  
>>> ca.dbr_text(scan.field_type())  
'DBR_ENUM'  
>>>
```

- The SCAN field of a record identifies how often the record is processed
- There is an enumerated list of possible SCAN field values



... Data Types

```
>>> scan.putw('1 second')
Traceback (innermost last):
  File "<stdin>", line 1, in ?
  File "CaChannel.py", line 383, in putw
    count, pval = self.__setup_put(value, req_type)
  File "CaChannel.py", line 131, in __setup_put
    CaChannel.dbr_d[req_type]['convert'](value),
ValueError: invalid literal for int(): 1 second
>>> scan.putw('1 second', ca.DBR_STRING)
>>> scan.getw(ca.DBR_STRING)
'1 second'
```

Writing the enumerated identifier (5) works on the previous slide and writing a value ('1 second') fails.



Request Data Types

Request type	Python type	Comments
DBR_STRING	String	
DBR_ENUM	Integer	Enumerated
DBR_CHAR	Integer	8 bits
DBR_INT	Integer	16 bits
DBR_LONG	Integer	32 bits
DBR_FLOAT	Float	
DBR_DOUBLE	Float	
Array of DBR	List of type	



Asynchronous I/O ...

- No waiting for CA requests to complete
- A user written callback function is executed when the request has completed
- `ca_pend_event` = flush the request buffer and wait for timeout or until all CA background activity is processed
- `ca_poll` = `ca_pend_event` with a short timeout
- `ca_flush_io` = flush the request buffer



... Asynchronous I/O

- Asynchronous callbacks do not preempt the main thread
- Instead `ca_pend_io`, `ca_pend_event`, or `ca_poll` must be called at least every 15 seconds to allow background activity to process



Connection Callback

```
ch.search_and_connect('catest', connectCb)
while 1: ch.pend_event()

def connectCb(epics_args, user_args):
    print 'name =', ca.name(epics_args[0])
    print 'state =', epics_args[1]
```

- `epics_args` = 2 element tuple
 - `epics_args[0]` = channel identifier, used to get the channels name
 - `epics_args[1]` = connection state
 - `ca.OP_CONN_UP`
 - `ca.OP_CONN_DOWN`
- `user_args` = tuple containing all python objects specified after the callback in the method



Put Callback

```
ch.array_put_callback(3.3, None, None, putCb)
while 1: ch.pend_event()
```

```
def putCb(epics_args, user_args):
    print ca.name(epics_args['chid'])
    print ca.dbr_text(epics_args['type'])
    print epics_args['count']
    print ca.message(epics_args['status'])
    print user_args
```

Default element count

Native data type

- `epics_args` is a dictionary with keys:
 - `chid` = channel identifier
 - `type` = request type (DBR_XXXX)
 - `count` = element count
 - `status` = transaction status code from server



Get Callback

```
ch.array_get_callback(None, None, getCb1)
while 1: ch.pend_event()
```

```
def getCb1(epics_args, user_args):
    print "pvName = ", ca.name(epics_args['chid'])
    print "type = ", ca.dbr_text(epics_args['type'])
    print "count = ", epics_args['count']
    print "status = ", ca.message(epics_args['status'])
    print "user args = ", user_args
    print "value(s) = ", epics_args['pv_value']
```

Default element count

Native data type

- value(s) = data returned by the server. Multiple data elements are returned in a tuple.



Compound Data Types

- Only supported in asynchronous mode
- Extra information with the value
 - ♦ Status – alarm values
 - ♦ Time – status + timestamp
 - ♦ Graphics – status + alarm limits + display limits
 - ♦ Control – graphics + control limits
- Routines are provided to convert DBR type to compound type



Get Status Callback

```
ch.array_get_callback(ca.dbf_type_to_DBR_STS(ch.field_type()), None, getCb2)  
while 1: ch.pend_event()
```

```
def getCb2(epics_args, user_args):  
    print "pvName = ", ca.name(epics_args['chid'])  
    print "type = ", ca.dbr_text(epics_args['type'])  
    print "count = ", epics_args['count']  
    print "status = ", ca.message(epics_args['status'])  
    print "user args = ", user_args  
    print "value(s) = ", epics_args['pv_value']  
    print ca.alarmSeverityString(epics_args['pv_severity'])  
    print ca.alarmStatusString(epics_args['pv_status'])
```



Default element count

- pv_severity = alarm severity
- pv_status = alarm status



Monitoring ...

- Asynchronous I/O originated at the server
- Client requests notification from the server when
 - ♦ the channel's value changes by more than the value dead band or alarm dead band
 - ♦ the channel's alarm state changes
- Monitor callbacks match those described under asynchronous I/O



... Monitoring ...

```
def eventCb(epics_args, user_args):
    print ca.message(epics_args['status'])
    print "new value = ", epics_args['pv_value']
    print ca.alarmSeverityString(epics_args['pv_severity'])
    print ca.alarmStatusString(epics_args['pv_status'])

try:
    chan = CaChannel()
    chan.searchw('catest')
    chan.add_masked_array_event(
        ca.dbf_type_to_DBR_STS(chan.field_type()),
        None, ca.DBE_VALUE | ca.DBE_ALARM, eventCb)
except CaChannelException, status:
    print ca.message(status)
```



... Monitoring

Monitor mask	Notification condition
ca.DBE_VALUE	when the channel's value changes by more than MDEL
ca.DBE_LOG	when the channel's value changes by more than ADEL
ca.DBE_ALARM	when the channel's alarm state changes



Functions Not Implemented

- `ca_change_connection_event`
 - ♦ use `ca_search_and_connect`
- `ca_add_exception_event`
- `ca_replace_printf_handler`
- `ca_replace_access_rights_event`
- `ca_puser` macro
 - ♦ not used
- `ca_test_event`
- Scan groups



Tkinter and CaChannel

- EPICS CA is not thread safe
- All CaChannel activity must be performed in the main thread
- Use the Tkinter after method to interrupt the mainloop at regular intervals to allow CA background activity to execute
- Execute CaChannel calls from the update function called by after



caPython

- Maintain full CA functionality
- SWIG handles the wrapping of functions not associated with callbacks without intervention
 - Label the functions with the C function name minus the ca_ prefix
 - ca_pend_io -> pend_io
- Additional C functions were added to handle callbacks
- Access to constants in the header files
- Macros are wrapped in functions

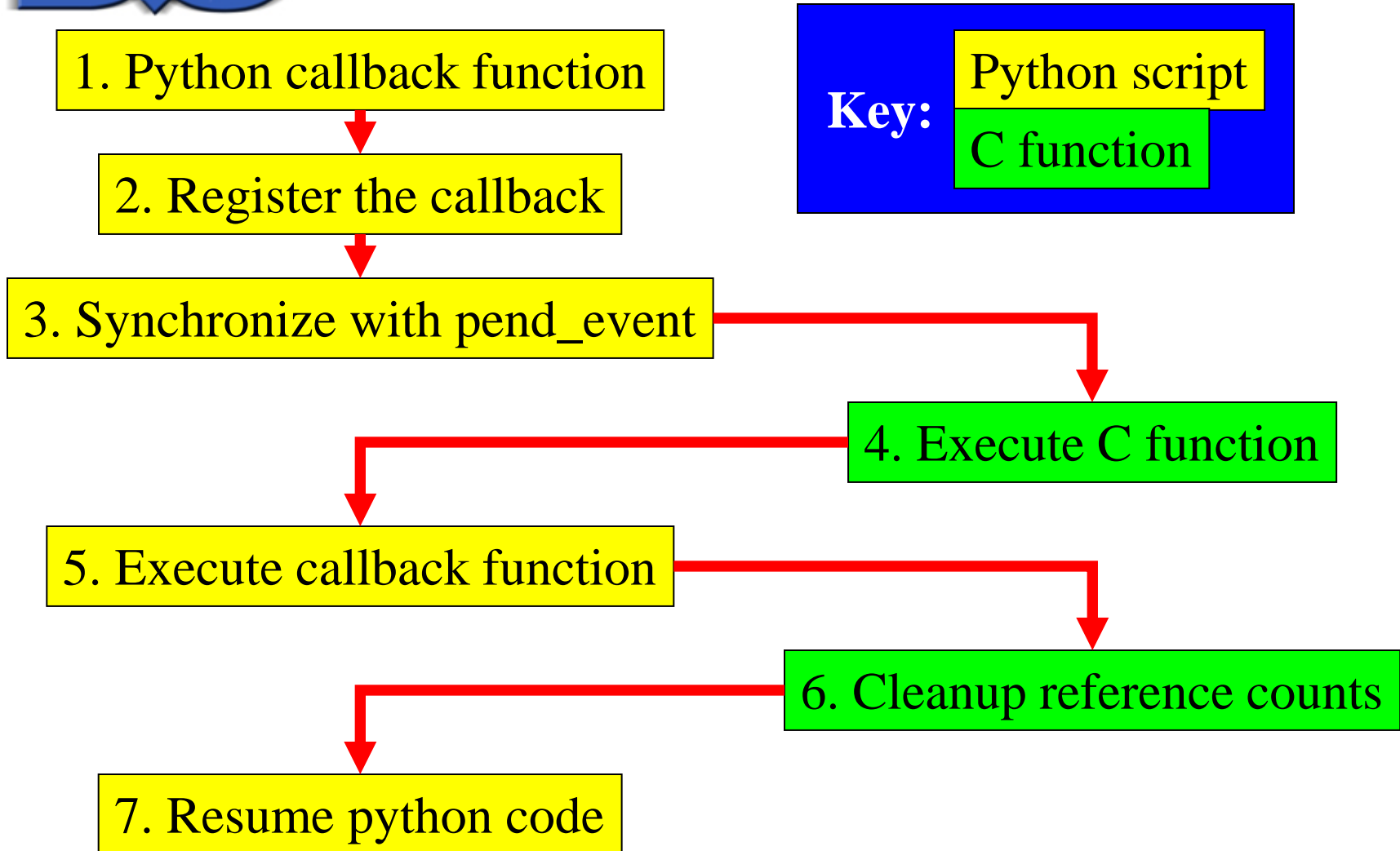


caPython Initialization

- Provide access to constants in header files
 - ♦ DBF_XXXX types – native field types
 - ♦ DBR_XXXX types – transaction request types
 - ♦ ECA_XXXX – transaction status codes
 - ♦ Connection states
 - ♦ Event masks
- When the ca module is imported into python execute *ca_task_initialize()*



caPython Callbacks





Callback Example

```
int ca_search_and_connect(  
    char *CHANNEL_NAME,  
    chid *PCHID,  
    void (*USERFUNC)(struct connection_handler_args ARGS),  
    void *PUSER);
```

- When `ca_search_and_connect()` completes it calls `USERFUNC` with one argument of type `struct connection_handler_args`
- `connectCallback` is the C function always called
- The python callback function and user data are combined and passed in through `PUSER`



Callback Functions

- Convert the channel access C data for return to the Python callback function
- Separate the python callback function and user data found in PUSER
- Call the Python function with two arguments
 - ♦ CA data
 - ♦ User data - if no user data is specified then the user data tuple is empty
- Cleanup reference counts