

High-precision linear minimization is no slower than projection

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Abstract

This note demonstrates that, for all compact convex sets, high-precision linear minimization can be performed via a single evaluation of the projection and a scalar-vector multiplication. In consequence, if ε -approximate linear minimization takes at least $L(\varepsilon)$ vector-arithmetic operations and projection requires P operations, then $\mathcal{O}(P) \geq \mathcal{O}(L(\varepsilon))$ is guaranteed. This concept is expounded with examples, an explicit error bound, and an exact linear minimization result for polyhedral sets.

Keywords: linear minimization, projection, Frank-Wolfe, complexity

MSC Classification: 90C30 , 03D15 , 47N10 , 52A07

1 Introduction

Notation 1. \mathcal{H} is a real Hilbert space with inner product $\langle \cdot | \cdot \rangle$ and induced norm $\|\cdot\|$. The set $C \subset \mathcal{H}$ is nonempty, convex, and compact. The normal cone and indicator function of C are denoted N_C and ι_C respectively (see, e.g., [2]). The projection operator onto C is denoted $\text{Proj}_C: \mathcal{H} \rightarrow \mathcal{H}: x \mapsto \text{Argmin}_{c \in C} \|c - x\|$. The set of linear minimization oracle points is $\text{LMO}_C: \mathcal{H} \rightarrow 2^{\mathcal{H}}: x \mapsto \text{Argmin}_{c \in C} \langle c | x \rangle$. For $\varepsilon \geq 0$, an ε -approximate LMO of x is a point $v \in C$ such that $0 \leq \langle v | x \rangle - \min_{c \in C} \langle c | x \rangle \leq \varepsilon$.

Assumption 1. Suppose that projection and ε -approximate linear minimization can be performed over C using finitely many vector-arithmetic operations. Let P and $L(\varepsilon)$ respectively denote the smallest amount of operations required. ¹

¹ P and $L(\varepsilon)$ exist as limit points of monotonic sequences in \mathbb{N} bounded below.

In constrained first-order optimization, a guiding motivator for the development of Frank-Wolfe algorithms is the fact that their hallmark subroutine, the *linear minimization oracle* (i.e., a selection of the operator LMO_C), is faster than projection oracles on some sets arising in applications, particularly in high-dimensional settings [3, 4, 6]. While several works have demonstrated that for specific sets, $P > L(0)$, this principle does not appear to have been definitively established for all compact convex sets. In fact, regardless of approximateness ($\varepsilon > 0$) or exactness ($\varepsilon = 0$), it appears there are no results pertaining to all compact convex sets that allow one to compare the computational complexity of linear minimization to that of projection.

The main contribution of this article is showing that, for any $\varepsilon > 0$, a high-precision ε -approximate LMO can be obtained via the use of one projection and a scalar-vector multiplication, yielding the complexity bound $\mathcal{O}(P) \geq \mathcal{O}(L(\varepsilon))$.² The error bound in Theorem 2 explicitly depends on the radius and boundedness of C . We provide examples and demonstrate that, when C is also polyhedral, projection is no faster than exact linear minimization, i.e., the stronger inequality $\mathcal{O}(P) \geq \mathcal{O}(L(0))$ holds. The central approximation considered in this article comes from a geometric concept (see Figure 1) that appears to be unpublished, but well-known (at least informally) amongst the optimization community. Nonetheless, as far as the author is aware, the present error bound and complexity results appear to be new.

2 Relating linear minimization and projection

We begin with some basic facts; see, e.g., [2] for further background. Let x and z be points in real Hilbert space \mathcal{H} . Then,

$$\begin{aligned} v \in \text{LMO}_C(z) = \underset{c \in C}{\text{Argmin}} \langle c \mid z \rangle &\Leftrightarrow 0 \in \partial(\langle \cdot \mid z \rangle + \iota_C)(v) = z + N_C(v) \Leftrightarrow -z \in N_C(v) \\ &\Leftrightarrow \begin{cases} v \in C \\ \sup_{c \in C} \langle -z \mid c - v \rangle \leq 0. \end{cases} \end{aligned} \quad (1)$$

Similarly, we also have the familiar identity

$$p = \text{Proj}_C x \Leftrightarrow x - p \in N_C p \Leftrightarrow \begin{cases} p \in C \\ \sup_{c \in C} \langle x - p \mid c - p \rangle \leq 0. \end{cases} \quad (2)$$

Proposition 1. *Let $C \subset \mathcal{H}$ be a nonempty compact convex set. Then, for every $x \in \mathcal{H}$,*

$$\text{Proj}_C(x) \in \text{LMO}_C(\text{Proj}_C x - x). \quad (3)$$

Proof. By setting $z = \text{Proj}_C x - x$ in (1), we see from (2) that $\text{Proj}_C(x)$ is a solution of the characterization in (1). \square

Remark 1. *Since linear minimization is not unique in general, evaluating $\text{LMO}_C(\text{Proj}_C x - x)$ may not yield $\text{Proj}_C(x)$ for every numerical implementation of*

²For the sake of presentation, we suppress the dependence of P and L on $\dim(\mathcal{H})$ and C .

LMO_C [1]. However, for a particular selection of the operator LMO_C , (3) is guaranteed to hold with equality instead of inclusion.

For $\lambda > 0$ sufficiently large, one can approximate an element of $\text{LMO}_C(x)$ with

$$\text{Proj}_C(-\lambda x). \quad (4)$$

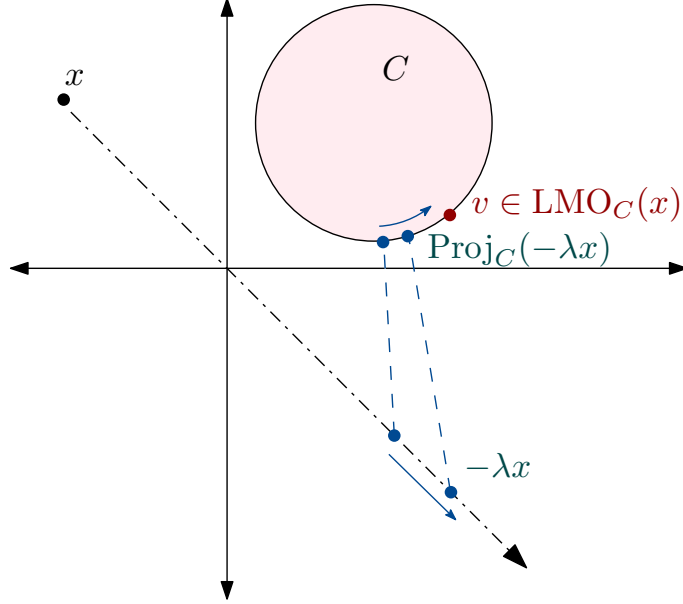


Fig. 1 As λ gets larger, $\text{Proj}_C(-\lambda x)$ approaches $\text{LMO}_C(x)$ for a shifted ℓ_2 ball.

Selecting the parameter λ can be guided as follows.

Theorem 2. Let $x \in \mathcal{H}$ and let C be a nonempty, compact, and convex subset of \mathcal{H} with diameter $\delta_C := \sup_{(c_1, c_2) \in C^2} \|c_1 - c_2\| \geq 0$ and bound $\mu_C := \sup_{c \in C} \|c\| \geq 0$. Then, for every $\lambda > 0$ and every $v \in \text{LMO}_C(x)$,

$$0 \leq \langle \text{Proj}_C(-\lambda x) \mid x \rangle - \langle v \mid x \rangle \leq \frac{\|\text{Proj}_C(-\lambda x)\|}{\lambda} \left(\|v\| - \|\text{Proj}_C(-\lambda x)\| \right). \quad (5)$$

In consequence, we have $\|\text{Proj}_C(-\lambda x)\| \leq \|v\|$ and for every $\varepsilon > 0$,

$$\lambda \geq \frac{\min\{\delta_C \mu_C, \mu_C^2\}}{\varepsilon} \Rightarrow 0 \leq \langle \text{Proj}_C(-\lambda x) \mid x \rangle - \min_{c \in C} \langle c \mid x \rangle \leq \varepsilon. \quad (6)$$

Proof. Let $v \in \text{LMO}_C(x)$. By Proposition 1, and the definition of the LMO,

$$\text{Proj}_C(-\lambda x) \in \underset{c \in C}{\text{Argmin}} \langle c \mid \text{Proj}_C(-\lambda x) + \lambda x \rangle, \quad (7)$$

so, for all $c \in C$, $\langle \text{Proj}_C(-\lambda x) \mid \text{Proj}_C(-\lambda x) + \lambda x \rangle \leq \langle c \mid \text{Proj}_C(-\lambda x) + \lambda x \rangle$. In particular,

$$\langle \text{Proj}_C(-\lambda x) \mid \text{Proj}_C(-\lambda x) + \lambda x \rangle \leq \langle v \mid \text{Proj}_C(-\lambda x) + \lambda x \rangle. \quad (8)$$

Dividing by λ and rearranging, then proceeding with standard norm inequalities yields

$$\langle \text{Proj}_C(-\lambda x) \mid x \rangle - \langle v \mid x \rangle \leq \lambda^{-1} (\langle v \mid \text{Proj}_C(-\lambda x) \rangle - \|\text{Proj}_C(-\lambda x)\|^2) \quad (9)$$

$$\leq \lambda^{-1} (\|v\| \|\text{Proj}_C(-\lambda x)\| - \|\text{Proj}_C(-\lambda x)\|^2) \quad (10)$$

$$= \lambda^{-1} \|\text{Proj}_C(-\lambda x)\| (\|v\| - \|\text{Proj}_C(-\lambda x)\|) \quad (11)$$

$$\leq \lambda^{-1} \|\text{Proj}_C(-\lambda x)\| \|v - \text{Proj}_C(-\lambda x)\|. \quad (12)$$

Since v is optimal, we can also lower bound (9) by 0; hence (5) follows from (11). An immediate consequence of (5) is that $\|\text{Proj}_C(-\lambda x)\| \leq \|v\|$. Proceeding with the bounds in (12), we have

$$0 \leq \langle \text{Proj}_C(-\lambda x) \mid x \rangle - \langle v \mid x \rangle \leq \lambda^{-1} \delta_C \mu_C. \quad (13)$$

On the other hand, dropping the negative term in (11) implies $0 \leq \langle \text{Proj}_C(-\lambda x) \mid x \rangle - \langle v \mid x \rangle \leq \lambda^{-1} \mu_C^2$. Hence, in either case of $\lambda \geq \varepsilon^{-1} \min\{\delta_C \mu_C, \mu_C^2\}$, (6) holds. In particular, $\text{Proj}_C(-\lambda x)$ is an ε -approximate LMO. \square

Corollary 1 (Projection is no faster than approximate LMO). *Let $\varepsilon > 0$ and suppose that Assumption 1 holds. Then $P + 1 \geq L(\varepsilon)$. In consequence, if $P \geq 1$, we also have $\mathcal{O}(P) \geq \mathcal{O}(L(\varepsilon))$.*

Proof. From Theorem 2, $L(\varepsilon)$ is bounded above by the cost of evaluating $\text{Proj}_C(-\lambda x)$, which is $P + 1$. \square

Remark 2. *The type of bound provided by Theorem 2 is consistent with many algorithms that allow for inexact linear minimization, e.g., [4, 5, 9, 10].*

In general, Theorem 2 requires $\lambda \rightarrow \infty$ to drive the error bound to zero (as demonstrated, e.g., for a shifted ℓ_2 ball). However, for some sets (e.g., the ℓ_∞ ball), exact minimization is achieved for finite λ , i.e., $\text{Proj}_C(-\lambda x) \in \text{LMO}_C(x)$.³ As will be seen in Proposition 3, exact linear minimization for finite λ can be achieved more generally.

Proposition 3 (Projection is no faster than exact LMO on polyhedral sets). *Let $x \in \mathbb{R}^n =: \mathcal{H}$ and suppose that $C \subset \mathcal{H}$ is compact, convex, and polyhedral. Then there exists a finite value $\lambda^* \geq 0$ such that $\text{Proj}_C(-\lambda^* x) \in \text{LMO}_C(x)$. Further, if Assumption 1 holds, then $P + 1 \geq L(0)$; if $P \geq 1$, then $\mathcal{O}(P) \geq \mathcal{O}(L(0))$.*

Proof. Without loss of generality $C = \{x \in \mathcal{H} \mid Ax \preceq b\}$ where $A \in \mathbb{R}^{n \times m}$ and $b \in \mathbb{R}^m$. Let $\nu = \min_{c \in C} \langle c \mid x \rangle$ and consider the problem of computing $\text{Proj}_{\text{LMO}_C(x)}(\mathbf{0})$,

³Interactive graph demonstrations in 2-D for the shifted ℓ_2 ball: <https://www.desmos.com/calculator/ntpelncpu> and ℓ_∞ ball: <https://www.desmos.com/calculator/qk3tnqskgw>.

i.e., the minimal-norm element of $\text{LMO}_C(x)$:

$$\underset{\substack{z \in \mathcal{H} \\ Az \preceq b \\ \langle z | x \rangle \leq \nu}}{\text{minimize}} \quad \frac{1}{2} \|z\|^2. \quad (14)$$

By [8, Theorem 11.15], strong duality holds and hence the perturbation function $\mathbf{v}: \mathbb{R}^{m+1} \rightarrow [-\infty, +\infty]: y \mapsto \inf_{z \in \mathcal{H}} \{f(x) \mid Az - b \preceq (y_i)_{i=1}^m; \langle z | x \rangle - \nu \leq y_{m+1}\}$ is *stable* in the sense of [7], i.e., $\mathbf{v}(\mathbf{0})$ is finite and there exists $M > 0$ such that [7, pp. 8]

$$(\forall \xi > 0) \quad \frac{\mathbf{v}(\mathbf{0}) - \mathbf{v}(\xi, \dots, \xi)}{\xi} \leq M. \quad (15)$$

With an eye towards using [7, Theorem 3], we will use (15) to show that the partially-dualized perturbation function $v: \mathbb{R} \rightarrow [-\infty, +\infty]: \xi \mapsto \inf_{z \in \mathcal{H}; Az - b \preceq 0} \{f(x) \mid \langle x | z \rangle - \nu \leq \xi\}$ is also stable: this follows from the fact that $v(0) = \mathbf{v}(\mathbf{0})$ and, for all $\xi > 0$, $v(\xi) \leq \mathbf{v}(\xi, \dots, \xi)$, so

$$\frac{v(0) - v(\xi)}{\xi} = \frac{\mathbf{v}(\mathbf{0}) - v(\xi)}{\xi} \leq \frac{\mathbf{v}(\mathbf{0}) - \mathbf{v}(\xi, \dots, \xi)}{\xi} \leq M, \quad (16)$$

as claimed. By [7, Theorem 3], there exists $\lambda^* \geq 0$ such that

$$\text{Proj}_{\text{LMO}_C(x)}(\mathbf{0}) = \underset{\substack{z \in \mathcal{H} \\ Az \preceq b}}{\text{Argmin}} \quad \frac{1}{2} \|z\|^2 + \lambda^* (\langle x | z \rangle - \nu) \quad (17)$$

$$= \underset{\substack{z \in \mathcal{H} \\ Az \preceq b}}{\text{Argmin}} \quad \frac{1}{2} \|- \lambda^* x - z\|^2 = \text{Proj}_C(-\lambda^* x), \quad (18)$$

where (18) makes use of the fact that the minimization is not changed by addition of the constant $\lambda^* \nu + \|\lambda^* x\|^2/2$. This establishes that, for finite $\lambda^* \geq 0$, $\text{Proj}_C(-\lambda^* x) \in \text{LMO}_C(x)$. In consequence, under Assumption 1, the computation required to perform $\text{Proj}_C(-\lambda^* x)$ (namely $P + 1$) is an upper bound on $L(0)$, which completes the proof. \square

3 Conclusion

While this note demonstrates two connections between the complexities of projection and linear minimization, the general relationship between P and $L(0)$ warrants further investigation.

For some sets (e.g., a singleton), $P = L(0)$. Hence, even though $P > L(0)$ has been demonstrated on a myriad of important sets [3], strict inequality cannot hold in general. Nonetheless, it remains an open question as to whether or not there exists *any* compact convex set such that its projection operator has a faster runtime complexity than exact linear minimization.

Question 1. *Does there exist a nonempty compact convex set such that $P < L(0)$?*

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Acknowledgements

Many thanks to Mathieu Besançon, who first suggested trying a duality approach for the proof of Proposition 3, and Elias Wirth. Also, thanks the anonymous user ‘gerw’ on Math Stack Exchange.

Data availability statement

No data was used in the creation of this article. Citations are available above.

Conflict of interest statement

The author declares no conflict of interest.