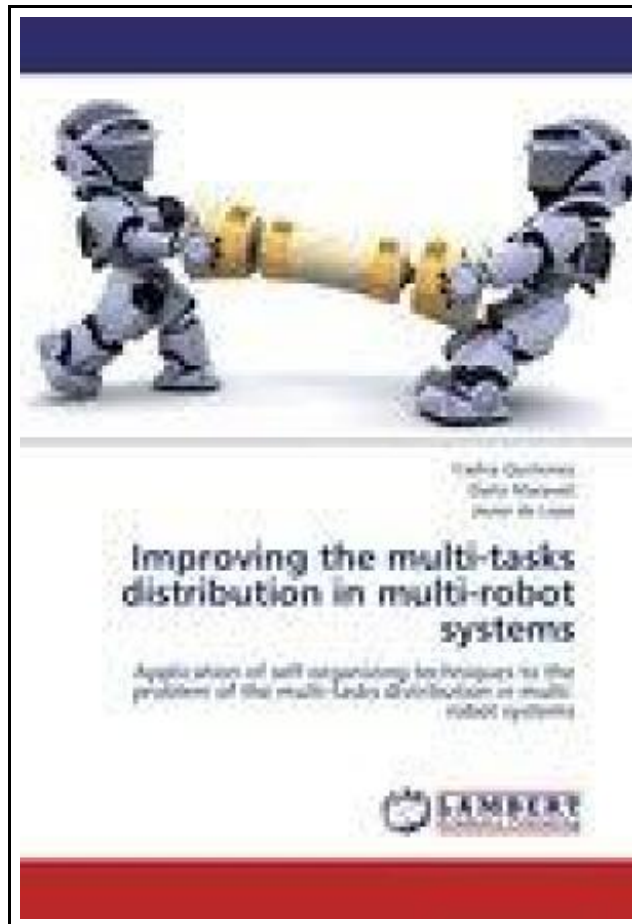


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(Ms. Hannah Lowe)

IMPROVING THE MULTI-TASKS DISTRIBUTION IN MULTI-ROBOT SYSTEMS



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