

Lab 08

Q1 (Hashing): Hash Functions [6 marks]

Draw the tables (three separate tables for a, b, and c) that result after inserting the following values in the given order: 17, 25, 11, 46, 14 to a table of size N.

Handle collisions using **linear probing** (Check lecture15 Slide 12)

```
set.add(11);      //abs(11) % 10 == 1
set.add(49);      //abs(49) % 10 == 9
set.add(24);      //abs(24) % 10 == 4
set.add(37);      //abs(37) % 10 == 7
set.add(54);      //abs(54) % 10 == 4 collides with 24!
```

index	0	1	2	3	4	5	6	7	8	9
value	0	11	0	0	24	54	0	37	0	49
size	5									

probe #1 add(54): i full!

probe #2 i+1 has space!

Q1 (Hashing): Hash Functions [6 marks]

Draw the tables (three separate tables for a, b, and c) that result after inserting the following values in the given order: 17, 25, 11, 46, 14 to a table of size N.

Handle collisions using **quadratic probing** (Check lecture15 Slide 13)

```
set.add(11);  
set.add(49);  
set.add(24);  
set.add(37);  
set.add(54); // collides with 24; must probe
```

index	0	1	2	3	4	5	6	7	8	9
value	0	11	0	0	24	54	0	37	0	49
size	5									

probe #1 add(54): I full!

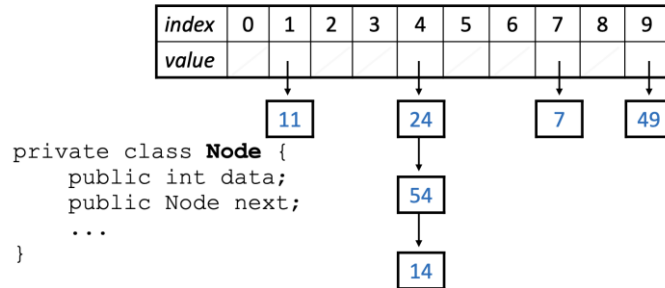
probe #2 $i + 1^2$ has space!

Q1 (Hashing): Hash Functions [6 marks]

Draw the tables (three separate tables for a, b, and c) that result after inserting the following values in the given order: 17, 25, 11, 46, 14 to a table of size N.

Handle collisions using **Separate Chaining** (Check lecture 15 Slide 28)

- **separate chaining**: Solving collisions by storing a list at each index.
 - add/contains/remove must traverse lists, but the lists are short
 - impossible to "run out" of indexes, unlike with probing



Q2 (Hashing): Collision Handling

`linearProbing()`

If the hash function indicates that a value should be stored at an already full (non-zero) index of the array

- this function increments the index until an available spot is found
- then inserts the new element at that index.

Check lecture15 – slides 16-29

Q2 (Hashing): Collision Handling

`quadraticProbing()`

This method is similar to linear probing, except instead of incrementing the index by one until an available spot is found, this method increments by a quadratically increasing amount.

- If the initial index returned by the hash function is i , the next index tried is $i+1^2$, then $i+2^2$, and so on until an available spot is found.

Check lecture15 – slides 16-29

Q2 (Hashing): Collision Handling

`doubleHashing()`

This final method is slightly more complicated. A secondary hash function is calculated in the case of a collision.

This function often is in the form of $d(k) = q - k \% q$ for a given key k , when q is a prime number.

Check lecture15 – slides 16-29

Q3 (Sorting): Comparing performance [4 marks]

- The code in this file is **complete**, but you should examine it anyway.
- An Excel spreadsheet is provided for you: **Results.xlsx**
- Your task is to run the file at least three times and collect the runtime data
 - The average of the trials for each method at each array size should be automatically calculated
- Examine the graph you've created and see if you can guess the Big-O complexities (either $O(n^2)$ and $O(n \log(n))$) of each of these sorting algorithms.
 - Note your hypothesis in the Excel spreadsheet.
 - For full marks, make a text comment in the Excel spreadsheet below your hypothesis, explaining your thinking

Q4 (Minimum Spanning Tree): [6 marks (BONUS)]

`printList()` : This method prints the graph's adjacency list.

`getMST()` : This method creates and returns a new `MSTGraph` which represents the minimum spanning tree of the original graph