

WEEK 1 REVIEW

$$\hat{\rho} = \frac{1}{2} (\mathbb{I} + \vec{n} \cdot \vec{\sigma})$$

why do we have '1' here?

$\text{Tr}(\hat{\rho}) = 1 \rightarrow$ to represent a physical state

$$\text{Tr}(\hat{\rho}) = \frac{1}{2} \left(\underbrace{\text{Tr}(\mathbb{I})}_{2} + \text{Tr}(\vec{n} \cdot \vec{\sigma}) \right) = 1$$

$\text{Tr}(\sigma_x) = \text{Tr}(\sigma_y) = \text{Tr}(\sigma_z) = 0$

To ensure positive semi-definite. (non-zero) eigenvalues

$$i\hbar \frac{\partial \hat{\rho}}{\partial t} = [\hat{H}, \hat{\rho}] \quad \text{von Neumann Equation}$$

$$i\hbar \frac{\partial \hat{A}}{\partial t} = [\hat{A}, \hat{H}] \quad \text{Heisenberg Equation}$$

Von Neumann

. Operators are time-independent

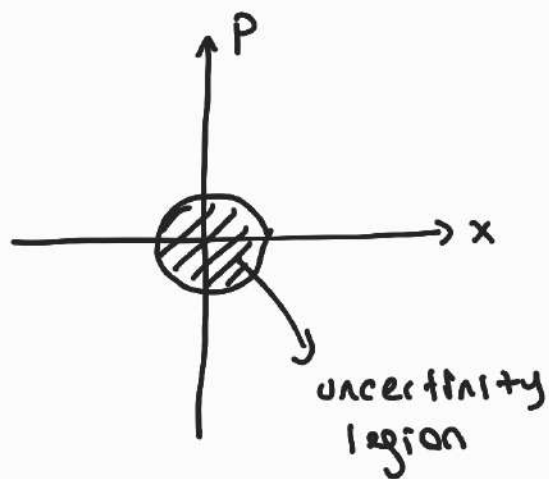
. State vectors are time-dependent

Heisenberg

. Operators are time-dependent

. State vectors are time-independent

Phase-Space Representation



Wigner Function

- quasi-probability distribution
- Fourier transform of the density matrix

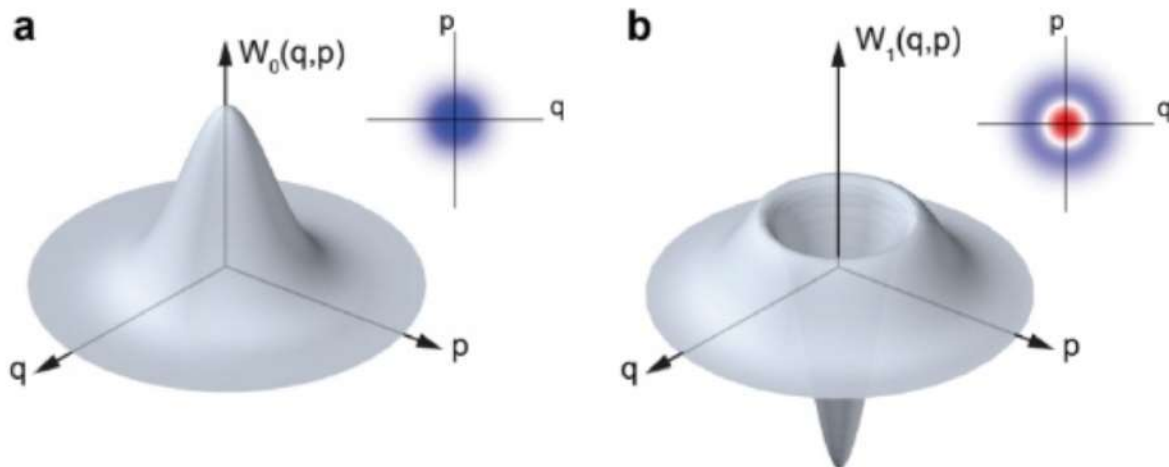


Figure 2.2: Wigner distribution for photon-number states: **a**, The vacuum state $|0\rangle$ has a Gaussian distribution centered at the origin of the phase space. **b**, The single photon state $|1\rangle$ exhibits negative probabilities around the origin.

Driven Harmonic Oscillator

$$m \frac{d^2 x}{dt^2} + kx = F(t) = F_0 \cos(\omega t)$$

$$\text{Example} \rightarrow H = -\frac{1}{2} \hbar \omega \sigma_z - A \cos(\omega_d t) \sigma_x$$

Rotating Frame:

Ex. dynamics of spin $\pm 1/2$ in magnetic field

$$\vec{B} = (B_1 \cos \omega t, B_1 \sin \omega t, B_0)$$

$$H(t) = -\frac{\gamma \hbar}{2} \underbrace{\vec{B}(t) \cdot \vec{\sigma}}_{B_x(t)\sigma_x + B_y(t)\sigma_y + B_z(t)\sigma_z}$$

$$H(t) = -\underbrace{\frac{\gamma \hbar}{2} B_0}_{\hbar \omega_0} \sigma_z - \underbrace{\frac{\gamma \hbar}{2} B_1}_{\hbar \omega_1} \{ \sigma_x \cos \omega t + \sigma_y \sin \omega t \}$$

Find $H_{\text{rot}} = \tilde{H}$ which does not depend on time.

$$H(t) = -\frac{\hbar \omega_0}{2} \sigma_z - \frac{\hbar \omega_1}{2} \left\{ \sigma_+ e^{-i\omega t} + \sigma_- e^{+i\omega t} \right\}$$

Change of Frame:

$$|\psi\rangle_{\text{Rotating frame}} = e^{-i\frac{\omega t}{2} \sigma_z} |\psi\rangle_{\text{lab frame}}$$

Rotation around angle ωt around z-axis

$$K = -\frac{\hbar\omega}{2} \sigma_z$$

$$|\psi_t\rangle_{\text{rot}} = e^{itK/\hbar} |\psi_t\rangle_{\text{lab}}$$

$$\tilde{U}_t |\tilde{\psi}_0\rangle_{\text{rot}} = e^{itK/\hbar} U_t |\psi_0\rangle_{\text{lab}}$$

$$\tilde{U}_t = U_t e^{itK/\hbar}$$

Schrodinger Equation: $i\hbar \frac{d}{dt} \tilde{U}_t = \tilde{H} \tilde{U}_t$

does not depend on time

$$\tilde{U}_t = \exp\left(-\frac{it}{\hbar} \tilde{H}\right)$$

$$i\hbar \frac{d}{dt} \tilde{U}_t = -K e^{itK/\hbar} U_t + e^{itK/\hbar} \left(\frac{dU_t}{dt} i\hbar \right)$$

\tilde{U}_t $H(t)U_t$

$$i\hbar \frac{d}{dt} \tilde{U}_t = -K e^{itK/\hbar} U_t + e^{itK/\hbar} H(t) U_t$$

$$i\hbar \frac{d}{dt} \tilde{U}_t = \left(-K + e^{itK/\hbar} H(t) e^{-itK/\hbar} \right) \tilde{U}_t$$

$\tilde{H}(t)$

$$\tilde{H}(t) = +\frac{\hbar\omega}{2} \sigma_z + e^{itK/\hbar} \left[-\frac{\hbar\omega_0}{2} \sigma_z - \frac{\hbar\omega_1}{2} \left\{ \sigma_x \cos(\omega t) + \sigma_y \sin(\omega t) \right\} \right] e^{-itK/\hbar}$$

commutes

$$\tilde{H} = -\frac{\hbar(\omega_0 - \omega)}{2} \sigma_z - \frac{\hbar\omega_1}{2} \sigma_x$$

wrong in the LN

$$k = -\frac{\hbar\omega}{2}\sigma_z \quad e^{itk/\hbar} = e^{it(-\frac{\hbar\omega}{2})\cdot\frac{1}{\hbar}\sigma_z} = e^{-i\frac{\omega}{2}\sigma_z}$$

$$\rightarrow e^{-i\frac{\omega}{2}\sigma_z} \sigma_x e^{i\frac{\omega}{2}\sigma_z} \quad \cos(\omega t)$$

$$\begin{pmatrix} e^{-i\frac{\omega t}{2}} & 0 \\ 0 & e^{i\frac{\omega t}{2}} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} e^{i\frac{\omega t}{2}} & 0 \\ 0 & e^{-i\frac{\omega t}{2}} \end{pmatrix}$$

$$\begin{pmatrix} 0 & e^{-i\omega t/2} \\ e^{i\omega t/2} & 0 \end{pmatrix} \begin{pmatrix} e^{i\omega t/2} & 0 \\ 0 & e^{-i\omega t/2} \end{pmatrix} = \begin{pmatrix} 0 & e^{-i\omega t} \\ e^{i\omega t} & 0 \end{pmatrix} \quad \cos(\omega t)$$

$$\rightarrow e^{-i\frac{\omega}{2}\sigma_z} \sigma_y e^{i\frac{\omega}{2}\sigma_z} \quad \sin(\omega t)$$

$$\begin{pmatrix} e^{-i\omega t/2} & 0 \\ 0 & e^{i\omega t/2} \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} e^{i\omega t/2} & 0 \\ 0 & e^{-i\omega t/2} \end{pmatrix}$$

$$\begin{pmatrix} 0 & -ie^{-i\omega t/2} \\ ie^{i\omega t/2} & 0 \end{pmatrix} \begin{pmatrix} e^{i\omega t/2} & 0 \\ 0 & e^{-i\omega t/2} \end{pmatrix} = \begin{pmatrix} 0 & -ie^{-i\omega t} \\ ie^{i\omega t} & 0 \end{pmatrix} \quad \sin(\omega t)$$

$$\begin{pmatrix} 0 & e^{-i\omega t} \\ e^{i\omega t} & 0 \end{pmatrix} \frac{(e^{i\omega t} + e^{-i\omega t})}{2} + \begin{pmatrix} 0 & -ie^{-i\omega t} \\ ie^{i\omega t} & 0 \end{pmatrix} \frac{(e^{i\omega t} - e^{-i\omega t})}{2i}$$

$$\downarrow \quad \downarrow$$

$$\begin{pmatrix} 0 & \frac{1+e^{-2i\omega t}}{2} \\ \frac{1+e^{2i\omega t}}{2} & 0 \end{pmatrix} + \begin{pmatrix} 0 & -\frac{1-e^{-2i\omega t}}{2} \\ \frac{e^{2i\omega t}-1}{2} & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & e^{-2i\omega t} \\ e^{2i\omega t} & 0 \end{pmatrix} = \begin{pmatrix} 0 & \cos(2\omega t) - i\sin(2\omega t) \\ \cos(2\omega t) + i\sin(2\omega t) & 0 \end{pmatrix}$$

$$= \cos(2\omega t) \sigma_x + \sin(2\omega t) \sigma_y$$

$$H_{\text{rot}} = U H U^\dagger + i\hbar \dot{U} U^\dagger \quad \checkmark$$

$$U = e^{-i\frac{\omega}{2}\sigma_z} \quad \dot{U} = \frac{dU}{dt} = -i\frac{\omega}{2} e^{-i\frac{\omega}{2}\sigma_z}$$

$$H(t) = -\underbrace{\frac{\gamma\hbar}{2} B_0}_{\hbar\omega_0} \sigma_z - \underbrace{\frac{\gamma\hbar}{2} B_1}_{\hbar\omega_1} \{ \sigma_x \cos\omega t + \sigma_y \sin\omega t \}$$

$$= \begin{pmatrix} -\frac{\hbar\omega_0}{2} & 0 \\ 0 & +\frac{\hbar\omega_0}{2} \end{pmatrix} + \begin{pmatrix} 0 & -\frac{\hbar\omega_1}{2} \cos\omega t \\ -\frac{\hbar\omega_1}{2} \cos\omega t & 0 \end{pmatrix}$$

$$+ \begin{pmatrix} 0 & -\frac{\hbar\omega_1}{2} \sin(\omega t)(-i) \\ -\frac{\hbar\omega_1}{2} \sin(\omega t)(i) & 0 \end{pmatrix} = \begin{pmatrix} -\frac{\hbar\omega_0}{2} & -\frac{\hbar\omega_1}{2} e^{-i\omega t} \\ -\frac{\hbar\omega_1}{2} e^{i\omega t} & +\frac{\hbar\omega_0}{2} \end{pmatrix}$$

$$H_{rot} = U H U^\dagger + i \hbar \dot{U} U^\dagger$$

$$e^{-i \frac{\hbar \omega}{2} \sigma_z} = \cos\left(\frac{\omega t}{2}\right) I - i \sin\left(\frac{\omega t}{2}\right) \sigma_z = \begin{pmatrix} \overbrace{\cos\left(\frac{\omega t}{2}\right) - i \sin\left(\frac{\omega t}{2}\right)}^{e^{-i \frac{\omega t}{2}}} & 0 \\ 0 & \underbrace{\cos\left(\frac{\omega t}{2}\right) + i \sin\left(\frac{\omega t}{2}\right)}_{e^{i \frac{\omega t}{2}}} \end{pmatrix}$$

$$U H U^\dagger = \begin{pmatrix} e^{-i \omega t/2} & 0 \\ 0 & e^{i \omega t/2} \end{pmatrix} \begin{pmatrix} -\frac{\hbar \omega_0}{2} & -\frac{\hbar \omega_1}{2} e^{-i \omega t} \\ -\frac{\hbar \omega_1}{2} e^{i \omega t} & \frac{\hbar \omega_0}{2} \end{pmatrix} \begin{pmatrix} e^{i \omega t/2} & 0 \\ 0 & e^{-i \omega t/2} \end{pmatrix} e^{i \omega t/2}$$

$$= \begin{pmatrix} -\frac{\hbar \omega_0}{2} e^{-i \omega t/2} & -\frac{\hbar \omega_1}{2} e^{-\frac{3}{2} i \omega t} \\ -\frac{\hbar \omega_1}{2} e^{\frac{3}{2} i \omega t} & \frac{\hbar \omega_0}{2} e^{i \omega t/2} \end{pmatrix} \begin{pmatrix} e^{i \omega t/2} & 0 \\ 0 & e^{-i \omega t/2} \end{pmatrix}$$

$$= \begin{pmatrix} -\frac{\hbar \omega_0}{2} & -\frac{\hbar \omega_1}{2} e^{-2i \omega t} \\ -\frac{\hbar \omega_1}{2} e^{2i \omega t} & \frac{\hbar \omega_0}{2} \end{pmatrix}$$

$$i \hbar \dot{U} U^\dagger = i \hbar \cdot \left(-i \frac{\omega}{2}\right) \underbrace{e^{-i \frac{\omega}{2} \sigma_z} I e^{i \frac{\omega}{2} \sigma_z}}_I = \frac{\hbar \omega}{2} I$$

$$H_{rot} = U H U^\dagger + i \hbar \dot{U} U^\dagger = \begin{pmatrix} -\frac{\hbar \omega_0}{2} + \frac{\hbar \omega}{2} & -\frac{\hbar \omega_1}{2} e^{-2i \omega t} \\ -\frac{\hbar \omega_1}{2} e^{2i \omega t} & \frac{\hbar \omega_0}{2} + \frac{\hbar \omega}{2} \end{pmatrix}$$

$$H_{rot} = \frac{\hbar (\omega - \omega_0)}{2} \sigma_z - \frac{\hbar \omega_1}{2} \left[\sigma_x \cos(2\omega t) + \sigma_y \sin(2\omega t) \right]$$

RWA

Uncertainty and Commutation

$$\Delta x = \sqrt{\langle (x - \langle x \rangle)^2 \rangle}$$

$$\Delta p = \sqrt{\langle (p - \langle p \rangle)^2 \rangle}$$

}

Cauchy-Schwarz Inequality

$$(\Delta x)^2 (\Delta p)^2 \geq \frac{1}{4} \langle [x, p] \rangle^2$$

expectation

$$(\Delta x)^2 (\Delta p)^2 \geq \frac{1}{4} \underbrace{(i\hbar)^2}_{\hbar^2}$$

$$\Rightarrow (\Delta x)(\Delta p) \geq \frac{\hbar}{2}$$

Quadrature and Phase Space

Classical Considerations

Classical electromagnetic field

$$E(t) = E_0 \cos(\omega t + \theta)$$

$$= \underbrace{E_0 \cos \theta}_{X_1} \cos(\omega t) - \underbrace{E_0 \sin \theta}_{X_2} \sin(\omega t)$$

$$= X_1 \cos(\omega t) + X_2 \sin(\omega t)$$

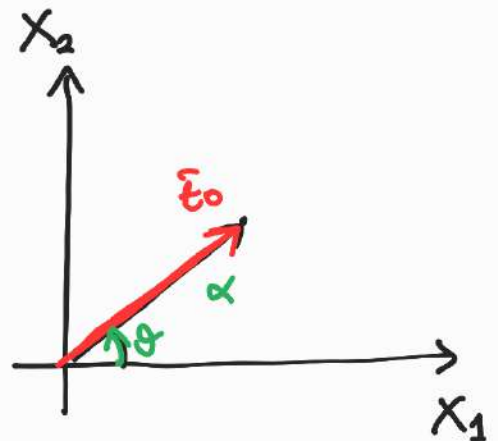
Phasor representation of field

$$\underbrace{\alpha(t)}_{\text{phasor}} = E_0 e^{-i\theta} e^{-i\omega t} = \underbrace{\alpha}_{\substack{\downarrow \\ \text{amplitude} \\ \text{of phasor}}} e^{-i\omega t}$$

$$\alpha = X_1 + iX_2$$

$$X_1 = \text{Re}(\alpha) = \frac{1}{2}(\alpha + \alpha^*)$$

$$X_2 = \text{Im}(\alpha) = \frac{1}{2i}(\alpha - \alpha^*)$$



Quantum

Quadrature Operators

$$\hat{X}_1 = \frac{1}{2}(\hat{a} + \hat{a}^\dagger) \hat{=} \hat{x}$$

$$\hat{X}_p = \frac{1}{2}(\hat{a} e^{-ip} + \hat{a}^\dagger e^{ip})$$

Hermitian <math display="block">\hat{X}_2 = \frac{1}{2i}(\hat{a} - \hat{a}^\dagger) \hat{=} \hat{p}

$$\hat{X}_{p+\pi/2} = \frac{1}{2i}(\hat{a} e^{-ip} - \hat{a}^\dagger e^{ip})$$

$$[\hat{X}_1, \hat{X}_2] = \frac{i}{2}$$

$$\Delta X_1 \Delta X_2 \geq \frac{1}{4}$$

Vacuum State

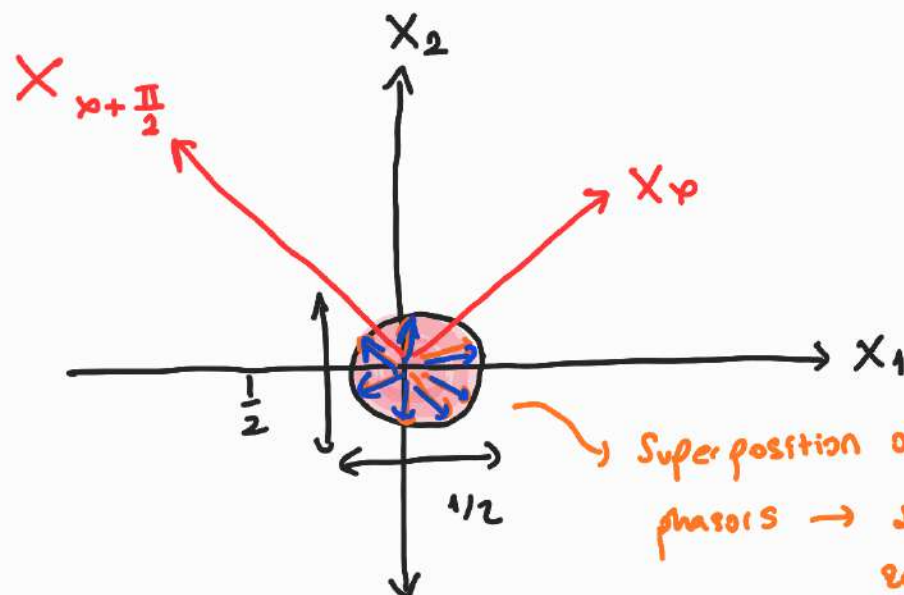
$$P^{(0)}(x_1) = |\langle x_1 | 0 \rangle|^2 = \sqrt{\frac{2}{\pi}} e^{-2x_1^2}$$

$$P^{(0)}(x_2) = |\langle x_2 | 0 \rangle|^2 = \sqrt{\frac{2}{\pi}} e^{-2x_2^2}$$

FT of Gaussian is again Gaussian

Fluctuations

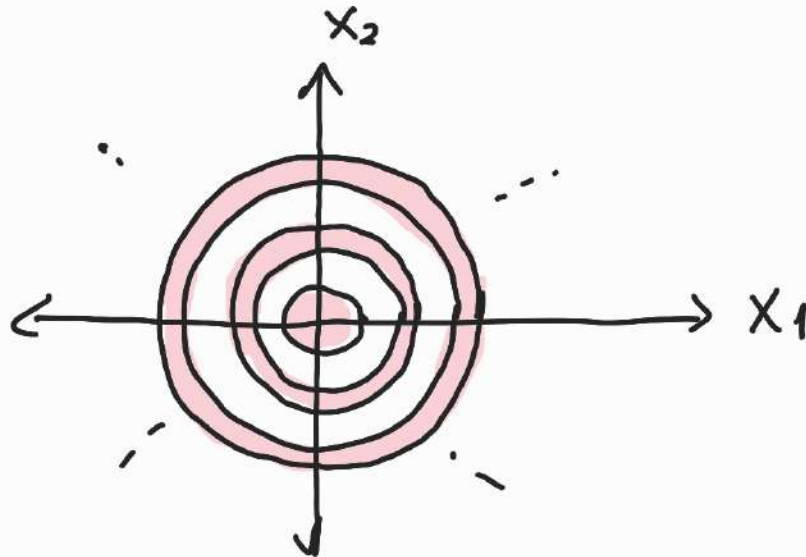
$$\Delta X_1 = \sqrt{\langle 0 | \hat{X}_1^2 | 0 \rangle - \langle 0 | \hat{X}_1 | 0 \rangle^2} = \frac{1}{2}$$



Fock State $|n\rangle$

$$p^{(0)}(x_1) = |\langle x_1 | n \rangle|^2 = \sqrt{\frac{2}{\pi}} \frac{1}{2^n n!} e^{-2x_1^2} \left(H_n(\sqrt{2}x_1) \right)^2$$

$$\Delta x_1 = \frac{1}{2} \sqrt{2n+1} \quad \text{similar to electric field fluctuations}$$



Coherent State

$$\hat{D}(\alpha) = e^{\alpha \hat{a}^\dagger - \alpha^* \hat{a}} \rightarrow \text{Displacement Operator}$$

$$\hat{D}(\alpha) |\beta\rangle \rightarrow |\beta + \alpha\rangle$$

$$|\alpha\rangle = \hat{D}(\alpha) |0\rangle$$

