电机实验二

无刷直流电机特性试验

正转及反转代码

pwm1.CmtnPointer表示当前绕组电流的方向(0~5)

hall1.HallGpioAccepted == 5 当前转子所处位置经由霍尔传感器反馈为第五扇区

```
1
    #if MOTOR_DIR == 0 //正转
    // Comment the following if-else-if statements in case of
 3
    // non-inverted Hall logics for commutation states.
                    if (hall1.HallGpioAccepted == 2)
 5
                         pwm1.CmtnPointer = 0;
 6
 7
                     else if (hall1.HallGpioAccepted == 6)
 8
                         pwm1.CmtnPointer = 1;
 9
10
                     else if (hall1.HallGpioAccepted == 4)
11
                         pwm1.CmtnPointer = 2;
12
13
                     else if (hall1.HallGpioAccepted == 5)
14
                         pwm1.CmtnPointer = 3;
15
                    else if (hall1.HallGpioAccepted == 1)
16
17
                         pwm1.CmtnPointer = 4;
18
                     else if (hall1.HallGpioAccepted == 3)
19
20
                         pwm1.CmtnPointer = 5;
    #elif MOTOR_DIR == 1 // (反转)
21
22
    // Comment the following if-else-if statements in case of
23
    // inverted Hall logics for commutation states.
24
                     if (hall1.HallGpioAccepted == 1)
25
                         pwm1.CmtnPointer = 3;
26
27
                     else if (hall1.HallGpioAccepted == 5)
28
                         pwm1.CmtnPointer = 2;
29
30
                     else if (hall1.HallGpioAccepted == 4)
31
                         pwm1.CmtnPointer = 1;
32
33
                     else if (hall1.HallGpioAccepted == 6)
34
                         pwm1.CmtnPointer = 0;
35
                     else if (hall1.HallGpioAccepted == 2)
36
                         pwm1.CmtnPointer = 5;
37
38
                     else if (hall1.HallGpioAccepted == 3)
39
40
                         pwm1.CmtnPointer = 4;
41
    #endif
42
```

正转扇区顺序	2	6	4	5	1	3
绕组电流方向	A^-B	A^-C	B^-C	B^-A	C^-A	C^-B
绕组电流方向对应的编码	0	1	2	3	4	5
反转扇区顺序	1	5	4	6	2	3
绕组电流方向	B^-A	B^-C	A^-C	A^-B	C^-B	C^-A
绕组电流方向对应的编码	3	2	1	0	5	4

```
1
    实验二
 2
 3
   #define PARK_MACRO(v)
 4
 5
        v.Ds = _IQmpy(v.Alpha,v.Cosine) + _IQmpy(v.Beta,v.Sine);
 6
       v.Qs = _IQmpy(v.Beta,v.Cosine) - _IQmpy(v.Alpha,v.Sine);
 7
8
    #endif // __PARK_H__
9
10
11
12
13
    #define CLARKE_MACRO(v)
14
15
   v.Alpha = v.As;
16
   v.Beta = _IQmpy((v.As +_IQmpy2(v.Bs)),_IQ(0.57735026918963));
17
18
   // 1/sqrt(3) = 0.57735026918963
19
20 #endif // __CLARKE_H__
```