Terms

(Stolen from the Incremental Flattening paper¹:))

bop ::= + | - | * | / | ; | · · · · op ::= transpose | rearrange
$$(d, \dots, d)$$
 | replicate soac ::= map | reduce | scan | redomap | scanomap e ::= $x \mid d \mid b \mid (e, \dots, e) \mid e[e] \mid e \ bop \ e \mid op \ e \cdots e \mid 0$ | loop $x_1 \cdots x_n = e \ for \ y < e \ do \ e$ | loop $x_1 \cdots x_n = e \ for \ y = e \ to \ 0 \ do \ e$ | let $x_1 \cdots x_n = e \ in \ e \mid if \ e \ then \ e \ else \ e$ | soac $f \ e \cdots e$ | soac $f \ e \cdots e \mid e \ bop \mid bop \ e$

The **0** expression is an array of zeros of arbitrary (and polymorphic!) shape.

Reverse-mode Rules

We define *tape maps* ($\parallel \Omega$) and *adjoint contexts* ($\Lambda \vdash$) as

$$\Omega ::= \varepsilon \mid \Omega, (x \mapsto x_s)
\Lambda ::= \varepsilon \mid \Lambda, (x \mapsto \hat{x})$$

The union of two maps prefers the right map in the instance of key conflicts:

$$(\Lambda_1 \cup \Lambda_2)[x] = \begin{cases} \Lambda_2[x] & \text{if } (x \mapsto \hat{x}) \in \Lambda_2 \\ \Lambda_1[x] & \text{otherwise} \end{cases}$$

Mappings of lists of variables is sugar for a list of mappings:

$$x_1x_2\cdots x_n\mapsto \hat{x}_1\hat{x}_2\cdots \hat{x}_n=\epsilon, (x_1\mapsto \hat{x}_1), (x_2\mapsto \hat{x}_2), \ldots, (x_n\mapsto \hat{x}_n)$$

dom returns all keys of a map, i.e.,

$$dom(\epsilon, (x_1 \mapsto \hat{x}_1), (x_2 \mapsto \hat{x}_2)) = \{x_1, x_2\}$$

im returns all elements:

$$im(\epsilon, (x_1 \mapsto \hat{x}_1), (x_2 \mapsto \hat{x}_2)) = {\hat{x}_1, \hat{x}_2}$$

We're sloppy and overload the notation somewhat, so expressions like

let
$$dom(\epsilon, (x_1 \mapsto \hat{x}_1), (x_2 \mapsto \hat{x}_2)) = e_1$$
 in e_2

are to be understood as

let
$$x_1 \ x_2 = e_1 \text{ in } e_2$$

or

let
$$(x_1, x_2) = e_1$$
 in e_2

depending on the context. The difference of two maps is defined as

$$\Lambda_2 \setminus \Lambda_1 = \cup \{x \mapsto \hat{x} \mid \Lambda_2[x] \neq \Lambda_1[x], \Lambda_2[x] = \hat{x}\}$$

Reading a variable that isn't in a map always returns 0:

$$\varepsilon[x] = 0$$

Forward pass (\Rightarrow_F)

$$\frac{e = \mathbf{loop} \, \overline{x} = e_0 \, \mathbf{for} \, y < e_n \, \mathbf{do} \, e_{body} \qquad x_{s_0} \, \mathbf{fresh} \qquad x_{s_0} = \mathbf{replicate} \, e_n \, \mathbf{0}}{e \Rightarrow_F \, \mathbf{loop} \, (\overline{x}, x_s) = (e_0, x_{s_0}) \, \mathbf{for} \, y < e_n \, \mathbf{do} \, (e_{body}, x_s[y] = \overline{x}) \parallel (\overline{x} \mapsto x_s)} \, \mathbf{FWDLOOP}$$

https://futhark-lang.org/publications/ppopp19.pdf

Reverse pass (\Rightarrow_R)

$$e_{loop} = \mathbf{let} \ \overline{rs} = \mathbf{loop} \ \overline{x} = e_0 \ \mathbf{for} \ y < e_n \ \mathbf{do} \ e_{body} \ \mathbf{in} \ \overline{rs} \\ e_{loop} \Rightarrow_F e'_{loop} \parallel \Omega \\ \overline{fv} = FV(e_{body}) \setminus \overline{x} \quad \overline{x}, \ \overline{fv}, \ \overline{fv}, \ \overline{fv}', \ \overline{fv}', \ \overline{fs}', \ \overline{fs}' \ \mathbf{frsh} \ \overline{reset} = \mathbf{map} \ (\Lambda_-0) \ \overline{x} \\ \Lambda'_1 = \Lambda_1, \ \overline{x} \mapsto \overline{x}, \ \overline{fv} \mapsto \overline{fv}, \ \overline{rs} \mapsto \overline{rs} \quad \hat{e}_{body} = \mathbf{let} \ \overline{z} = e'_{body} \ \mathbf{in} \ \overline{z} \quad (\Lambda'_1 \vdash e_{body}) \Rightarrow_R (\Lambda_2 \vdash \hat{e}_{body}) \\ \Lambda_{2,\Delta fv} = \{v \mapsto \hat{v} \mid v \in \overline{fv}, (v \mapsto \hat{v}) \in \Lambda_2 \setminus \Lambda'_1\} \quad \Lambda_{2,rs} = \{r \mapsto \hat{r} \mid r \in \overline{rs}, (r \mapsto \hat{r}) \in \Lambda_2\} \\ \ell''_{body} = \mathbf{let} \ \overline{rs} = \Omega[y] \ \mathbf{in} \ (\mathbf{let} \ \overline{z'} = e'_{body} \ \mathbf{in} \ \overline{(reset}, \mathbf{m}(\Lambda_{2,rs}), \mathbf{im}(\Lambda_{2,\Delta fv}))) \\ \widehat{\mathbf{mit}} = (\overline{reset}, \Lambda_1[\overline{lres}], \Lambda_1[dom(\Lambda_{2,\Delta fv})]) \\ \widehat{\mathbf{mit}} = (\overline{reset}, \Lambda_1[\overline{lres}], \Lambda_1[dom(\Lambda_{2,\Delta fv})]) \\ \Lambda_1 \vdash e_{loop} \Rightarrow_R \left(\Lambda_3 \vdash \mathbf{let} \ \overline{fv}, \overline{fv'}\right) = \hat{e}_{loop} \ \mathbf{in} \ (\mathbf{let} \ \overline{fv''} = (\mathbf{map} \ (+) \ \overline{fv'} \ \overline{rs'}) \ \mathbf{in} \ \overline{fv''}) \\ \Lambda_1 \vdash e_{loop} \Rightarrow_R \left(\Lambda_3 \vdash \mathbf{let} \ \overline{fv}_t = \hat{e}_t \ \mathbf{in} \ \overline{fv} \right) = \hat{e}_{loop} \ \mathbf{in} \ (\mathbf{let} \ \overline{fv''} = (\mathbf{map} \ (+) \ \overline{fv'} \ \overline{rs'}) \ \mathbf{in} \ \overline{fv''}) \right) \\ \Lambda \vdash e_t \Rightarrow_R \Lambda_t \vdash \mathbf{let} \ \overline{fv}_t = \hat{e}_t \ \mathbf{in} \ \overline{fv} \right) = \hat{e}_{loop} \ \mathbf{in} \ (\mathbf{let} \ \overline{fv''} = (\mathbf{map} \ (+) \ \overline{fv'} \ \overline{rs'}) \ \mathbf{in} \ \overline{fv''}) \right) \\ \Lambda \vdash e_t \Rightarrow_R \Lambda_t \vdash \mathbf{let} \ \overline{fv}_t = \hat{e}_t \ \mathbf{in} \ \overline{fv} \right) \\ \Lambda \vdash e_t \Rightarrow_R \Lambda_t \vdash \mathbf{let} \ \overline{fv}_t = \hat{e}_t \ \mathbf{in} \ \overline{fv} \right) = \hat{e}_t \ \mathbf{in} \ \mathbf{sort} (fv_t + \mathbf{im} (\Lambda_{\Delta_f} - \Lambda_{\Delta_f})) \\ \hat{e}'_f = \mathbf{let} \ \overline{fv}_f = \hat{e}_f \ \mathbf{in} \ \mathbf{sort} (fv_t + \mathbf{im} (\Lambda_{\Delta_f} - \Lambda_{\Delta_f})) \\ \Lambda \vdash \mathbf{let} \ \overline{res} = \hat{e}_f \ \mathbf{in} \ \mathbf{sort} (fv_t + \mathbf{im} (\Lambda_{\Delta_f} - \Lambda_{\Delta_f})) \\ \hat{e}'_f = \mathbf{let} \ \overline{fv}_f = \hat{e}_f \ \mathbf{in} \ \mathbf{sort} (fv_t + \mathbf{im} (\Lambda_{\Delta_f} - \Lambda_{\Delta_f})) \\ \hat{e}'_f = \mathbf{let} \ \overline{res} = \hat{e}_f \ \mathbf{in} \ \mathbf{sort} (fv_f + \mathbf{im} (\Lambda_{\Delta_f} - \Lambda_{\Delta_f})) \\ \hat{e}'_f = \mathbf{let} \ \overline{res} = \hat{e}_f \ \mathbf{in} \ \overline{res} \ \overline{x}_s = e' \ \mathbf{in} \$$