

## Terms

(Stolen from the Incremental Flattening paper<sup>1</sup> :))

$$\begin{aligned}
 bop &::= + \mid - \mid * \mid / \mid \mathbf{i} \mid \dots \\
 op &::= \mathbf{transpose} \mid \mathbf{rearrange} \, (d, \dots, d) \mid \mathbf{replicate} \\
 soac &::= \mathbf{map} \mid \mathbf{reduce} \mid \mathbf{scan} \mid \mathbf{redomap} \mid \mathbf{scanomap} \\
 e &::= x \mid d \mid b \mid (e, \dots, e) \mid e[e] \mid e \, bop \, e \mid op \, e \, \dots \, e \mid 0 \\
 &\quad \mid \mathbf{loop} \, x_1 \, \dots \, x_n = e \, \mathbf{for} \, y < e \, \mathbf{do} \, e \\
 &\quad \mid \mathbf{loop} \, x_1 \, \dots \, x_n = e \, \mathbf{for} \, y = e \, \mathbf{to} \, 0 \, \mathbf{do} \, e \\
 &\quad \mid \mathbf{let} \, x_1 \, \dots \, x_n = e \, \mathbf{in} \, e \mid \mathbf{if} \, e \, \mathbf{then} \, e \, \mathbf{else} \, e \\
 &\quad \mid soac \, f \, e \, \dots \, e \\
 f &::= \lambda x_1 \, \dots \, x_n \rightarrow e \mid soac \, f \, e \, \dots \, e \mid e \, bop \mid bop \, e
 \end{aligned}$$

The **0** expression is an array of zeros of arbitrary (and polymorphic!) shape.

## Reverse-mode Rules

We define *tape maps* ( $\parallel \Omega$ ) and *adjoint contexts* ( $\Lambda \vdash$ ) as

$$\begin{aligned}
 \Omega &::= \varepsilon \mid \Omega, (x \mapsto x_s) \\
 \Lambda &::= \varepsilon \mid \Lambda, (x \mapsto \hat{x})
 \end{aligned}$$

The union of two maps prefers the right map in the instance of key conflicts:

$$(\Lambda_1 \cup \Lambda_2)[x] = \begin{cases} \Lambda_2[x] & \text{if } (x \mapsto \hat{x}) \in \Lambda_2 \\ \Lambda_1[x] & \text{otherwise} \end{cases}$$

Mappings of lists of variables is sugar for a list of mappings:

$$x_1 x_2 \dots x_n \mapsto \hat{x}_1 \hat{x}_2 \dots \hat{x}_n = \epsilon, (x_1 \mapsto \hat{x}_1), (x_2 \mapsto \hat{x}_2), \dots, (x_n \mapsto \hat{x}_n)$$

*dom* returns all keys of a map, i.e.,

$$dom(\epsilon, (x_1 \mapsto \hat{x}_1), (x_2 \mapsto \hat{x}_2)) = \{x_1, x_2\}$$

*im* returns all elements:

$$im(\epsilon, (x_1 \mapsto \hat{x}_1), (x_2 \mapsto \hat{x}_2)) = \{\hat{x}_1, \hat{x}_2\}$$

We're sloppy and overload the notation somewhat, so expressions like

$$\mathbf{let} \, dom(\epsilon, (x_1 \mapsto \hat{x}_1), (x_2 \mapsto \hat{x}_2)) = e_1 \, \mathbf{in} \, e_2$$

are to be understood as

$$\mathbf{let} \, x_1 \, x_2 = e_1 \, \mathbf{in} \, e_2$$

or

$$\mathbf{let} \, (x_1, x_2) = e_1 \, \mathbf{in} \, e_2$$

depending on the context. The difference of two maps is defined as

$$\Lambda_2 \setminus \Lambda_1 = \cup \{x \mapsto \hat{x} \mid \Lambda_2[x] \neq \Lambda_1[x], \Lambda_2[x] = \hat{x}\}$$

Reading a variable that isn't in a map always returns 0:

$$\varepsilon[x] = 0$$

## Forward pass ( $\Rightarrow_F$ )

<sup>1</sup><https://futhark-lang.org/publications/ppopp19.pdf>

$$\frac{x_{s_0} \text{ fresh} \quad e = \text{loop } \bar{x} = e_0 \text{ for } y < e_n \text{ do let } res = e_{body} \text{ in } res \quad x_{s_0} = \text{replicate } e_n \text{ 0} \quad e'_{body} = \text{let } x_s[y] = \bar{x} \text{ in let } res = e_{body} \text{ in } (res, x_s)}{e \Rightarrow_F \text{loop } (\bar{x}, x_s) = (e_0, x_{s_0}) \text{ for } y < e_n \text{ do } e'_{body} \parallel (\bar{x} \mapsto x_s)} \text{FWDFORLOOP}$$

## Reverse pass ( $\Rightarrow_R$ )

$$\frac{\begin{array}{l} e_{body} = \text{let } \bar{rs} = e'_{body} \text{ in } \bar{rs} \\ e_{loop} = \text{let } \bar{lres} = \text{loop } \bar{x} = e_0 \text{ for } y < e_n \text{ do } e_{body} \text{ in } \bar{lres} \quad e_{loop} \Rightarrow_F e'_{loop} \parallel \Omega \\ \bar{fv} = FV(e_{body}) \setminus \bar{x} \quad \bar{\hat{x}}, \bar{\hat{fv}}, \bar{\hat{fv}'}, \bar{\hat{fv}''}, \bar{\hat{rs}}, \bar{\hat{rs}'} \text{ fresh} \quad \bar{reset} = \text{map } (\lambda \_. \text{0}) \bar{\hat{x}} \\ \Lambda'_1 = \Lambda_1, \bar{x} \mapsto \bar{\hat{x}}, \bar{fv} \mapsto \bar{\hat{fv}}, \bar{rs} \mapsto \bar{\hat{rs}} \quad \hat{e}_{body} = \text{let } \hat{z} = \hat{e}'_{body} \text{ in } \hat{z} \quad (\Lambda'_1 \vdash e_{body}) \Rightarrow_R (\Lambda_2 \vdash \hat{e}_{body}) \\ \Lambda_{2,\Delta_{fv}} = \{v \mapsto \hat{v} \mid v \in \bar{fv}, (v \mapsto \hat{v}) \in \Lambda_2 \setminus \Lambda'_1\} \quad \Lambda_{2,rs} = \{r \mapsto \hat{r} \mid r \in \bar{rs}, (r \mapsto \hat{r}) \in \Lambda_2\} \\ \hat{e}'_{body} = \text{let } \bar{rs} = \Omega[y] \text{ in } (\text{let } \hat{z}' = \hat{e}'_{body} \text{ in } (\bar{reset}, im(\Lambda_{2,rs}), im(\Lambda_{2,\Delta_{fv}}))) \\ \widehat{init} = (\bar{reset}, \Lambda_1[\bar{lres}], \Lambda_1[dom(\Lambda_{2,\Delta_{fv}})]) \\ \hat{e}_{loop} = \text{loop } (\bar{\hat{x}}, \bar{\hat{rs}}, \bar{\hat{fv}}) = \widehat{init} \text{ for } y = e_n - 1 \text{ to } 0 \text{ do } \hat{e}'_{body} \quad \Lambda_3 = \Lambda_1 \cup \left( dom(\Lambda_{2,\Delta_{fv}}) \mapsto \bar{\hat{fv}''} \right) \end{array}}{\Lambda_1 \vdash e_{loop} \Rightarrow_R \left( \Lambda_3 \vdash \text{let } (-, \bar{\hat{rs}'}, \bar{\hat{fv}'}) = \hat{e}_{loop} \text{ in } (\text{let } \bar{\hat{fv}''} = (\text{map } (+) \bar{\hat{fv}'} \bar{\hat{rs}'}) \text{ in } \bar{\hat{fv}''}) \right)} \text{REVFORLOOP}$$

$$\frac{\begin{array}{l} \Lambda \vdash e_t \Rightarrow_R \Lambda_t \vdash \text{let } \bar{\hat{fv}}_t = \hat{e}_t \text{ in } \bar{\hat{fv}}_t \quad \Lambda \vdash e_f \Rightarrow_R \Lambda_f \vdash \text{let } \bar{\hat{fv}}_f = \hat{e}_f \text{ in } \bar{\hat{fv}}_f \\ \Lambda_{\Delta_t} = \Lambda \setminus \Lambda_t \quad \Lambda_{\Delta_f} = \Lambda \setminus \Lambda_f \quad \hat{e}'_t = \text{let } \bar{\hat{fv}}_t = \hat{e}_t \text{ in } sort(\bar{\hat{fv}}_t \uparrow\uparrow im(\Lambda_{\Delta_f} - \Lambda_{\Delta_t})) \\ \hat{e}'_f = \text{let } \bar{\hat{fv}}_f = \hat{e}_f \text{ in } sort(\bar{\hat{fv}}_f \uparrow\uparrow im(\Lambda_{\Delta_t} - \Lambda_{\Delta_f})) \quad \bar{\hat{rs}} \text{ fresh} \quad \Lambda' = \Lambda, \left( dom(\Lambda_{\Delta_t} \cup \Lambda_{\Delta_f}) \mapsto \bar{\hat{rs}} \right) \end{array}}{\Lambda \vdash \text{let } \bar{res} = \text{if } e_p \text{ then } e_t \text{ else } e_f \text{ in } \bar{res} \Rightarrow_R \Lambda' \vdash \text{let } \bar{res} = \text{if } e_p \text{ then } \hat{e}'_t \text{ else } \hat{e}'_f \text{ in } \bar{res}} \text{REVIF}$$

$$\frac{\begin{array}{l} f = \lambda \bar{x} \rightarrow \text{let } \bar{res} = e \text{ in } \bar{rs} \\ \text{let } \bar{res} = e \text{ in } \bar{res} \Rightarrow_F \text{let } \bar{res} \bar{x}_s = e' \text{ in } \bar{res} \bar{x}_s \parallel \Omega \quad \Lambda \vdash \text{let } \bar{res} = e \text{ in } \bar{res} \Rightarrow_R \Lambda' \vdash \text{let } \bar{z}\bar{s} = \hat{e} \text{ in } \bar{z}\bar{s} \\ \bar{\hat{b}}\bar{s} = sort(\{\hat{x} \mid x \in \bar{x}, \Lambda[x] = \hat{x}, \hat{x} \in \bar{z}\bar{s}\}) \quad \bar{\hat{f}}\bar{v} = sort(\bar{z}\bar{s} \setminus \bar{\hat{b}}\bar{s}) \end{array}}{\Lambda \vdash (\lambda \bar{x} \rightarrow \text{let } \bar{res} = e \text{ in } \bar{rs}) \Rightarrow_R \Lambda' \vdash \left( \lambda \bar{x} (\Lambda'[\bar{res}]) \rightarrow \text{let } \bar{rs} \bar{x}_s = e' \text{ in let } \bar{\hat{b}}\bar{s} \bar{\hat{f}}\bar{v} = \hat{e} \text{ in } (\bar{\hat{b}}\bar{s}, \bar{\hat{f}}\bar{v}) \right)} \text{REVLAMBDA}$$

$$\frac{\begin{array}{l} \Lambda_1 \vdash (\lambda \bar{x} \rightarrow e) \Rightarrow_R \Lambda_2 \vdash \left( \lambda \bar{x} \bar{res} \rightarrow \text{let } \bar{x} \bar{\hat{b}}\bar{s} \bar{\hat{f}}\bar{v} = \hat{e} \text{ in } (\bar{\hat{b}}\bar{s}, \bar{\hat{f}}\bar{v}) \right) \\ \Lambda_3 = \Lambda_2, \bar{x}\bar{s} \mapsto \bar{\hat{x}}\bar{s}, sort(FV(\lambda \bar{x} \rightarrow e)) \mapsto \bar{\hat{f}}\bar{v} \end{array}}{\Lambda_1 \vdash (\text{let } \bar{y}\bar{s} = \text{map } (\lambda \bar{x} \rightarrow e) \bar{x}\bar{s} \text{ in } \bar{y}\bar{s}) \Rightarrow_R \Lambda_3 \vdash \text{let } (\Delta \bar{\hat{x}}\bar{s}, \Delta \bar{\hat{f}}\bar{v}\bar{s}) = \text{map } \left( \lambda \bar{x} \bar{res} \rightarrow \text{let } \bar{x} \bar{\hat{b}}\bar{s} \bar{\hat{f}}\bar{v} = \hat{e} \text{ in } (\bar{\hat{b}}\bar{s}, \bar{\hat{f}}\bar{v}) \right) \bar{x}\bar{s} (\Lambda_1[\bar{y}\bar{s}]) \text{ in} \\ \text{let } \Delta \bar{\hat{f}}\bar{v} = \text{reduce } (\text{zipwith}(+)) \text{ 0 } \Delta \bar{\hat{f}}\bar{v}\bar{s} \text{ in} \\ \text{let } \bar{\hat{x}}\bar{s} = \text{updateArray}(\emptyset, \bar{\hat{x}}\bar{s}, \Delta \bar{\hat{x}}\bar{s}) \text{ in} \\ \text{let } \bar{\hat{f}}\bar{v}' = \text{zipwith } (+) \Lambda[sort(FV(\lambda \bar{x} \rightarrow e))] \Delta \bar{\hat{f}}\bar{v} \text{ in } (\bar{\hat{x}}\bar{s}, \bar{\hat{f}}\bar{v}')} \text{REVMAP}$$

$$\frac{\text{TODO}}{\text{TODO}} \text{REVREDUCE}$$