

# CycleGAN

July 7, 2019

## 0.1 1. Import Libs

```
In [ ]: import torch
        from torch.autograd import Variable
        from torchvision import transforms
        from model import Generator, Discriminator
        import argparse
        import os, itertools
        import numpy as np
        from PIL import Image
        import torch.utils.data as data
        import random
        import matplotlib.pyplot as plt
        import imageio

In [ ]: def to_np(x):
        return x.data.cpu().numpy()

def plot_train_result(real_image, gen_image, recon_image, epoch, save_dir='results/', f
    fig, axes = plt.subplots(2, 3, figsize=fig_size)

    imgs = [to_np(real_image[0]), to_np(gen_image[0]), to_np(recon_image[0]),
            to_np(real_image[1]), to_np(gen_image[1]), to_np(recon_image[1])]
    for ax, img in zip(axes.flatten(), imgs):
        ax.axis('off')
        ax.set_adjustable('box-forced')
        # Scale to 0-255
        img = img.squeeze()
        img = ((img - img.min()) * 255) / (img.max() - img.min()).transpose(1, 2, 0)
        ax.imshow(img, cmap=None, aspect='equal')
    plt.subplots_adjust(wspace=0, hspace=0)

    title = 'Epoch {0}'.format(epoch + 1)
    fig.text(0.5, 0.04, title, ha='center')

    save_fn = save_dir + 'Result_epoch_{:d}'.format(epoch+1) + '.png'
```

```

plt.savefig(save_fn)
plt.show()

def plot_test_result(real_image, gen_image, recon_image, index, save_dir='results/'):
    fig_size = (real_image.size(2) * 3 / 100, real_image.size(3) / 100)
    fig, axes = plt.subplots(1, 3, figsize=fig_size)

    imgs = [to_np(real_image), to_np(gen_image), to_np(recon_image)]
    for ax, img in zip(axes.flatten(), imgs):
        ax.axis('off')
        ax.set_adjustable('box-forced')
        # Scale to 0-255
        img = img.squeeze()
        img = (((img - img.min()) * 255) / (img.max() - img.min())).transpose(1, 2, 0)
        ax.imshow(img, cmap=None, aspect='equal')
    plt.subplots_adjust(wspace=0, hspace=0)

    if not os.path.exists(save_dir):
        os.mkdir(save_dir)
    save_fn = save_dir + 'Test_result_{:d}'.format(index + 1) + '.png'
    fig.subplots_adjust(bottom=0)
    fig.subplots_adjust(top=1)
    fig.subplots_adjust(right=1)
    fig.subplots_adjust(left=0)
    plt.savefig(save_fn)
    plt.show()

class ImagePool():
    def __init__(self, pool_size):
        self.pool_size = pool_size
        if self.pool_size > 0:
            self.num_imgs = 0
            self.images = []

    def query(self, images):
        if self.pool_size == 0:
            return images
        return_images = []
        for image in images.data:
            image = torch.unsqueeze(image, 0)

```

```

        if self.num_imgs < self.pool_size:
            self.num_imgs = self.num_imgs + 1
            self.images.append(image)
            return_images.append(image)
        else:
            p = random.uniform(0, 1)
            if p > 0.5:
                random_id = random.randint(0, self.pool_size-1)
                tmp = self.images[random_id].clone()
                self.images[random_id] = image
                return_images.append(tmp)
            else:
                return_images.append(image)
    return_images = Variable(torch.cat(return_images, 0))
    return return_images

```

```

In [ ]: class DatasetFromFolder(data.Dataset):
    def __init__(self, image_dir, subfolder='train', transform=None, resize_scale=None,
        super(DatasetFromFolder, self).__init__()
        self.input_path = os.path.join(image_dir, subfolder)
        self.image_filenames = [x for x in sorted(os.listdir(self.input_path))]
        self.transform = transform

        self.resize_scale = resize_scale
        self.crop_size = crop_size
        self.fliplr = fliplr

    def __getitem__(self, index):
        # Load Image
        img_fn = os.path.join(self.input_path, self.image_filenames[index])
        img = Image.open(img_fn).convert('RGB')

        # preprocessing
        if self.resize_scale:
            img = img.resize((self.resize_scale, self.resize_scale), Image.BILINEAR)

        if self.crop_size:
            x = random.randint(0, self.resize_scale - self.crop_size + 1)
            y = random.randint(0, self.resize_scale - self.crop_size + 1)
            img = img.crop((x, y, x + self.crop_size, y + self.crop_size))
        if self.fliplr:
            if random.random() < 0.5:
                img = img.transpose(Image.FLIP_LEFT_RIGHT)

        if self.transform is not None:
            img = self.transform(img)

        return img

```

```

def __len__(self):
    return len(self.image_filenames)

```

## 0.2 2. Setting Hyperparameters

```
In [ ]: parser = argparse.ArgumentParser()
```

```
#Data Set Parameter
```

```

parser.add_argument('--dataset', required=False, default='horse2zebra', help='input data')
parser.add_argument('--batch_size', type=int, default=1, help='train batch size')
parser.add_argument('--input_size', type=int, default=256, help='input size')
parser.add_argument('--resize_scale', type=int, default=286, help='resize scale (0 is false)')
parser.add_argument('--crop_size', type=int, default=256, help='crop size (0 is false)')
parser.add_argument('--fliplr', type=bool, default=True, help='random fliplr True or False')

```

```
#Model Parameters
```

```

parser.add_argument('--ngf', type=int, default=32) # number of generator filters
parser.add_argument('--ndf', type=int, default=64) # number of discriminator filters
parser.add_argument('--num_resnet', type=int, default=6, help='number of resnet blocks')

```

```
#Learning Parameters
```

```

parser.add_argument('--num_epochs', type=int, default=20, help='number of train epochs')
parser.add_argument('--decay_epoch', type=int, default=10, help='start decaying learning rate')
parser.add_argument('--lrG', type=float, default=0.0001, help='learning rate for generator')
parser.add_argument('--lrD', type=float, default=0.0001, help='learning rate for discriminator')
parser.add_argument('--beta1', type=float, default=0.5, help='beta1 for Adam optimizer')
parser.add_argument('--beta2', type=float, default=0.999, help='beta2 for Adam optimizer')
parser.add_argument('--lambdaA', type=float, default=10, help='lambdaA for cycle loss')
parser.add_argument('--lambdaB', type=float, default=10, help='lambdaB for cycle loss')
params = parser.parse_args([])
print(params)

```

```
# Directories for loading data and saving results
```

```

data_dir = 'datasets/' + params.dataset + '/'
save_dir = params.dataset + '_results/'
model_dir = params.dataset + '_model/'

```

```

if not os.path.exists(save_dir):
    os.mkdir(save_dir)
if not os.path.exists(model_dir):
    os.mkdir(model_dir)

```

## 0.3 3. Load Dataset

### 0.3.1 3.2 Preprocessing

```
In [ ]: transform = transforms.Compose([
        transforms.Scale((params.input_size,params.input_size)),
        transforms.ToTensor(),
        transforms.Normalize(mean=(0.5, 0.5, 0.5), std=(0.5, 0.5, 0.5))
    ])
```

### 0.3.2 3.2 Load Train Data

```
In [ ]: train_data_A = DatasetFromFolder(data_dir, subfolder='trainA', transform=transform,
                                         resize_scale=params.resize_scale, crop_size=params.crop_size)

train_data_loader_A = torch.utils.data.DataLoader(dataset=train_data_A, batch_size=params.batch_size)

train_data_B = DatasetFromFolder(data_dir, subfolder='trainB', transform=transform,
                                  resize_scale=params.resize_scale, crop_size=params.crop_size)

train_data_loader_B = torch.utils.data.DataLoader(dataset=train_data_B, batch_size=params.batch_size)
```

### 0.3.3 3.3 Load Test Data

```
In [ ]: test_data_A = DatasetFromFolder(data_dir, subfolder='testA', transform=transform)

test_data_loader_A = torch.utils.data.DataLoader(dataset=test_data_A, batch_size=params.batch_size)

test_data_B = DatasetFromFolder(data_dir, subfolder='testB', transform=transform)

test_data_loader_B = torch.utils.data.DataLoader(dataset=test_data_B, batch_size=params.batch_size)

# Get specific test images
test_real_A_data = train_data_A.__getitem__(11).unsqueeze(0) # Convert to 4d tensor (Batch, Channel, Height, Width)
test_real_B_data = train_data_B.__getitem__(91).unsqueeze(0)
print(test_real_A_data)
```

## 0.4 4. Build Model & Optimizers & Criteria

### 0.4.1 4.1 Build Model

```
In [ ]: G_A = Generator(3, params.ngf, 3, params.num_resnet) # input_dim, num_filter, output_dim
        G_B = Generator(3, params.ngf, 3, params.num_resnet)

        D_A = Discriminator(3, params.ndf, 1) # input_dim, num_filter, output_dim
        D_B = Discriminator(3, params.ndf, 1)

        G_A.normal_weight_init(mean=0.0, std=0.02)
```

```

G_B.normal_weight_init(mean=0.0, std=0.02)
D_A.normal_weight_init(mean=0.0, std=0.02)
D_B.normal_weight_init(mean=0.0, std=0.02)

print(G_A.cuda())
print(G_B.cuda())
print(D_A.cuda())
print(D_B.cuda())

```

## 0.4.2 4.2 Optimizers

```

In [ ]: G_optimizer = torch.optim.Adam(itertools.chain(G_A.parameters(), G_B.parameters()), lr=
        D_A_optimizer = torch.optim.Adam(D_A.parameters(), lr=params.lrD, betas=(params.beta1,
        D_B_optimizer = torch.optim.Adam(D_B.parameters(), lr=params.lrD, betas=(params.beta1,

```

## 0.4.3 4.3 Loss Functions

```

In [ ]: MSE_Loss = torch.nn.MSELoss().cuda()
        L1_Loss = torch.nn.L1Loss().cuda()

```

```

## Training GAN

```

```

D_A_avg_losses = []
D_B_avg_losses = []
G_A_avg_losses = []
G_B_avg_losses = []

```

```

# Generated image pool

```

```

num_pool = 50
fake_A_pool = ImagePool(num_pool)
fake_B_pool = ImagePool(num_pool)

```

## 0.5 5. Training Models

```

In [ ]: step = 0
        for epoch in range(params.num_epochs):
            D_A_losses = []
            D_B_losses = []
            G_A_losses = []
            G_B_losses = []
            cycle_A_losses = []
            cycle_B_losses = []
            if (epoch + 1) > params.decay_epoch:
                D_A_optimizer.param_groups[0]['lr'] -= params.lrD / (params.num_epochs - params.
                D_B_optimizer.param_groups[0]['lr'] -= params.lrD / (params.num_epochs - params.
                G_optimizer.param_groups[0]['lr'] -= params.lrG / (params.num_epochs - params.

            for i, (real_A, real_B) in enumerate(zip(train_data_loader_A, train_data_loader_B))

```

```

# input image data
real_A = Variable(real_A.cuda())
real_B = Variable(real_B.cuda())

# ----- train generator G -----
# A --> B
fake_B = G_A(real_A)
D_B_fake_decision = D_B(fake_B)
G_A_loss = MSE_Loss(D_B_fake_decision, Variable(torch.ones(D_B_fake_decision.size(0))))

# forward cycle loss
recon_A = G_B(fake_B)
cycle_A_loss = L1_Loss(recon_A, real_A) * params.lambdaA

# B --> A
fake_A = G_B(real_B)
D_A_fake_decision = D_A(fake_A)
G_B_loss = MSE_Loss(D_A_fake_decision, Variable(torch.ones(D_A_fake_decision.size(0))))

# backward cycle loss
recon_B = G_A(fake_A)
cycle_B_loss = L1_Loss(recon_B, real_B) * params.lambdaB

# Back propagation
G_loss = G_A_loss + G_B_loss + cycle_A_loss + cycle_B_loss
G_optimizer.zero_grad()
G_loss.backward()
G_optimizer.step()

# ----- train discriminator D_A -----
D_A_real_decision = D_A(real_A)
D_A_real_loss = MSE_Loss(D_A_real_decision, Variable(torch.ones(D_A_real_decision.size(0))))

fake_A = fake_A_pool.query(fake_A)

D_A_fake_decision = D_A(fake_A)
D_A_fake_loss = MSE_Loss(D_A_fake_decision, Variable(torch.zeros(D_A_fake_decision.size(0))))

# Back propagation
D_A_loss = (D_A_real_loss + D_A_fake_loss) * 0.5
D_A_optimizer.zero_grad()
D_A_loss.backward()
D_A_optimizer.step()

# ----- train discriminator D_B -----
D_B_real_decision = D_B(real_B)

```

```

D_B_real_loss = MSE_Loss(D_B_real_decision, Variable(torch.ones(D_B_fake_decis

fake_B = fake_B_pool.query(fake_B)

D_B_fake_decision = D_B(fake_B)
D_B_fake_loss = MSE_Loss(D_B_fake_decision, Variable(torch.zeros(D_B_fake_decis

# Back propagation
D_B_loss = (D_B_real_loss + D_B_fake_loss) * 0.5
D_B_optimizer.zero_grad()
D_B_loss.backward()
D_B_optimizer.step()

# ----- Print -----
# loss values
D_A_losses.append(D_A_loss.item())
D_B_losses.append(D_B_loss.item())
G_A_losses.append(G_A_loss.item())
G_B_losses.append(G_B_loss.item())

if i%10 == 0:
    print('Epoch [%d/%d], Step [%d/%d], D_A_loss: %.4f, D_B_loss: %.4f, G_A_lo
          % (epoch+1, params.num_epochs, i+1, len(train_data_loader_A), D_A_lo

step += 1

D_A_avg_loss = torch.mean(torch.FloatTensor(D_A_losses))
D_B_avg_loss = torch.mean(torch.FloatTensor(D_B_losses))
G_A_avg_loss = torch.mean(torch.FloatTensor(G_A_losses))
G_B_avg_loss = torch.mean(torch.FloatTensor(G_B_losses))

# avg loss values for plot
D_A_avg_losses.append(D_A_avg_loss)
D_B_avg_losses.append(D_B_avg_loss)
G_A_avg_losses.append(G_A_avg_loss)
G_B_avg_losses.append(G_B_avg_loss)

# Show result for test image
test_real_A = Variable(test_real_A_data.cuda())
test_fake_B = G_A(test_real_A)
test_recon_A = G_B(test_fake_B)

test_real_B = Variable(test_real_B_data.cuda())
test_fake_A = G_B(test_real_B)
test_recon_B = G_A(test_fake_A)

```



```

        plot_train_result([test_real_A, test_real_B], [test_fake_B, test_fake_A], [test_real_A, test_real_B],
                           epoch, save_dir=save_dir)

```

```

In [ ]: # Plot average losses
        avg_losses = []
        avg_losses.append(D_A_avg_losses)
        avg_losses.append(D_B_avg_losses)
        avg_losses.append(G_A_avg_losses)
        avg_losses.append(G_B_avg_losses)

        fig, ax = plt.subplots()
        ax.set_xlim(0, params.num_epochs)
        for i in range(len(avg_losses)):
            temp = max(np.max(avg_losses[i]), temp)
        ax.set_ylim(0, temp*1.2)
        plt.xlabel("Epochs")
        plt.ylabel("Values")
        plt.label("Loss Curve")
        plt.plot(avg_losses[0], label='D_A')
        plt.plot(avg_losses[1], label='D_B')
        plt.plot(avg_losses[2], label='G_A')
        plt.plot(avg_losses[3], label='G_B')
        plt.legend()
        save_fn = save_dir+'Loss_Values_epoch_{:d}'.format(params.num_epochs)+'.png'
        plt.savefig(save_fn)
        plt.show()

```

```

# Save trained parameters of model
torch.save(G_A.state_dict(), model_dir + 'generator_A_param.pkl')
torch.save(G_B.state_dict(), model_dir + 'generator_B_param.pkl')
torch.save(D_A.state_dict(), model_dir + 'discriminator_A_param.pkl')
torch.save(D_B.state_dict(), model_dir + 'discriminator_B_param.pkl')

```

```

In [ ]: transform = transforms.Compose([
        transforms.Scale((params.input_size, params.input_size)),
        transforms.ToTensor(),
        transforms.Normalize(mean=(0.5, 0.5, 0.5), std=(0.5, 0.5, 0.5))
    ])

```

```

In [ ]: test_data_A = DatasetFromFolder(data_dir, subfolder='testA', transform=transform)
        test_data_loader_A = torch.utils.data.DataLoader(

```

```

        dataset=test_data_A, batch_size=params.batch_size, shuffle=False)

test_data_B = DatasetFromFolder(data_dir, subfolder='testB', transform=transform)
test_data_loader_B = torch.utils.data.DataLoader(
    dataset=test_data_B, batch_size=params.batch_size, shuffle=False)

In [ ]: G_A = Generator(3, params.ngf, 3, params.num_resnet)
        G_B = Generator(3, params.ngf, 3, params.num_resnet)
        G_A.cuda()
        G_B.cuda()
        G_A.load_state_dict(torch.load(model_dir + 'generator_A_param.pkl'))
        G_B.load_state_dict(torch.load(model_dir + 'generator_B_param.pkl'))

In [ ]: for i, real_A in enumerate(test_data_loader_A):
        # input image data
        real_A = Variable(real_A.cuda())

        # A --> B --> A
        fake_B = G_A(real_A)
        recon_A = G_B(fake_B)

        # Show result for test data
        plot_test_result(real_A, fake_B, recon_A, i, save_dir=save_dir + 'AtoB/')

        print('%d images are generated.' % (i + 1))

    for i, real_B in enumerate(test_data_loader_B):

        # input image data
        real_B = Variable(real_B.cuda())

        # B -> A -> B
        fake_A = G_B(real_B)
        recon_B = G_A(fake_A)

        # Show result for test data
        plot_test_result(real_B, fake_A, recon_B, i, save_dir=save_dir + 'BtoA/')

        print('%d images are generated.' % (i + 1))

```