

Annotated
Version

Machine Learning Course - CS-433

Expectation-Maximization Algorithm

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changes by Martin Jaggi 2019, changes by Rüdiger Urbanke 2018, changes by Martin Jaggi
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EPFL

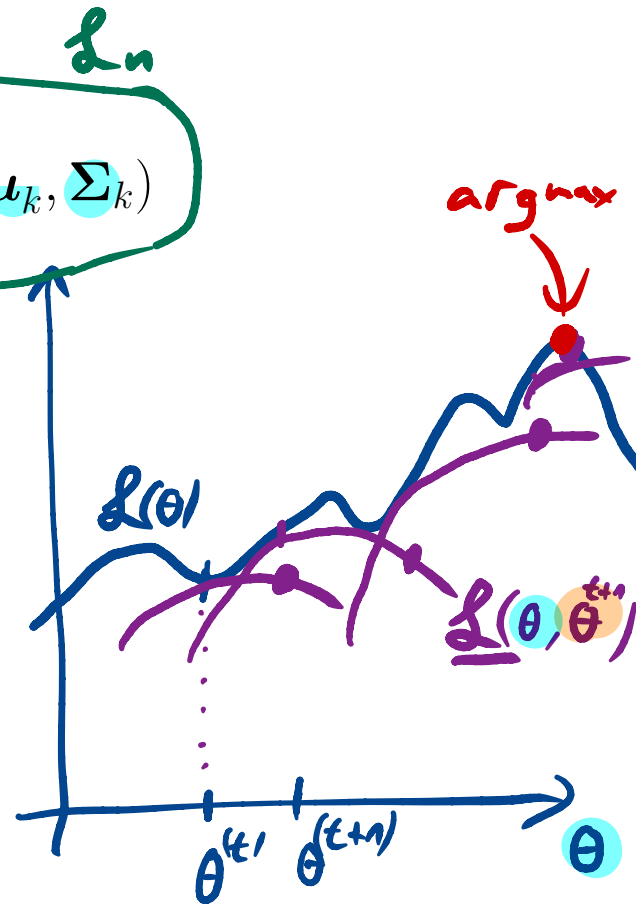
$$\boldsymbol{\theta} = \left(\underbrace{\{\pi_k\}_{k=1}^K}_{\mathbb{R}}, \underbrace{\{\mu_k\}_{k=1}^K}_{\mathbb{R}^D}, \underbrace{\{\Sigma_k\}_{k=1}^K}_{\mathbb{R}^{D \times D}} \right)$$

Motivation

Computing maximum likelihood for Gaussian mixture model is difficult due to the log outside the sum.

$$\max_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}) := \sum_{n=1}^N \log \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)$$

Expectation-Maximization (EM) algorithm provides an elegant and general method to optimize such optimization problems. It uses an iterative two-step procedure where individual steps usually involve problems that are easy to optimize.



EM algorithm: Summary

Start with $\boldsymbol{\theta}^{(1)}$ and iterate:

1. Expectation step: Compute a lower bound to the cost such that it is tight at the previous $\boldsymbol{\theta}^{(t)}$:

- $\mathcal{L}(\boldsymbol{\theta}) \geq \underline{\mathcal{L}}(\boldsymbol{\theta}, \boldsymbol{\theta}^{(t)})$ and
- $\mathcal{L}(\boldsymbol{\theta}^{(t)}) = \underline{\mathcal{L}}(\boldsymbol{\theta}^{(t)}, \boldsymbol{\theta}^{(t)})$.

$\forall \boldsymbol{\theta}$

lower bound
equality at $\boldsymbol{\theta} = \boldsymbol{\theta}^{(t)}$

2. Maximization step: Update $\boldsymbol{\theta}$:

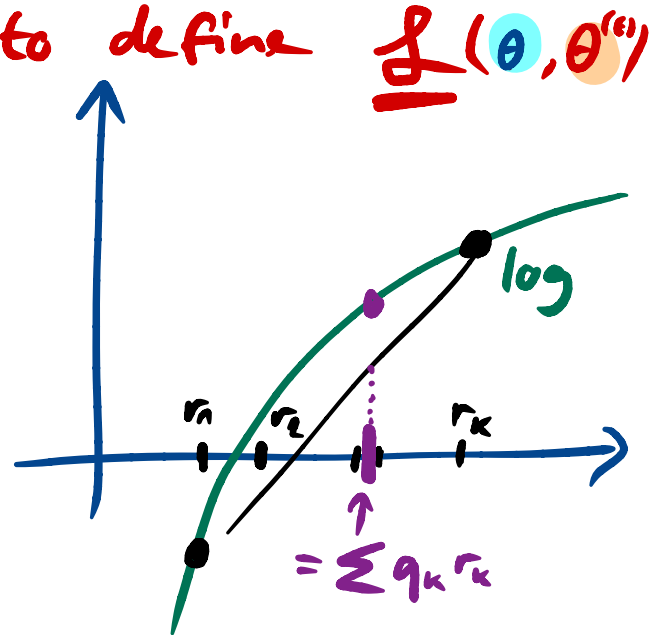
$$\boldsymbol{\theta}^{(t+1)} = \arg \max_{\boldsymbol{\theta}} \underline{\mathcal{L}}(\boldsymbol{\theta}, \boldsymbol{\theta}^{(t)}).$$

convexity of $-\log$

Concavity of log

Given non-negative weights q s.t. $\sum_k q_k = 1$, the following holds for any $r_k > 0$:

$$\log \left(\sum_{k=1}^K q_k r_k \right) \geq \sum_{k=1}^K q_k \log r_k$$



The expectation step

$$\mathcal{L}_n(\theta) = \log \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \geq \sum_{k=1}^K q_{kn} \log \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{q_{kn}} =: \underline{\mathcal{L}}_n(\theta, \theta^{(t)})$$

with equality when,

$$q_{kn} := \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}$$

This is not a coincidence.

• lower bound ✓

• coincides with \mathcal{L} at $\theta = \theta^{(t)}$

$$\begin{aligned} \underline{\mathcal{L}}_n(\theta^{(t)}, \theta^{(t)}) &= \sum_{k=1}^K \underbrace{\frac{\pi_k \mathcal{N}(\cdot)}{\sum_{k'} \pi_{k'} \mathcal{N}(\cdot)}}_{q_{kn}} \log \underbrace{\frac{\pi_k \mathcal{N}(\cdot)}{\sum_{k'} \pi_{k'} \mathcal{N}(\cdot)}}_{q_{kn}} \\ &= \log \sum_{k=1}^K \pi_k \mathcal{N}(\cdot) \\ &= \mathcal{L}_n(\theta^{(t)}) \end{aligned}$$

The maximization step

Maximize the lower bound w.r.t. θ .

$$\max_{\theta} \sum_{n=1}^N \sum_{k=1}^K q_{kn}^{(t)} \left[\log \pi_k + \log \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \right] - \log q_{kn}^{(t)}$$

Differentiating w.r.t. μ_k, Σ_k^{-1} , we can get the updates for μ_k and Σ_k .

$$\mu_k^{(t+1)} := \frac{\sum_n q_{kn}^{(t)} \mathbf{x}_n}{\sum_n q_{kn}^{(t)}}$$

$$\Sigma_k^{(t+1)} := \frac{\sum_n q_{kn}^{(t)} (\mathbf{x}_n - \mu_k^{(t+1)}) (\mathbf{x}_n - \mu_k^{(t+1)})^\top}{\sum_n q_{kn}^{(t)}}$$

For π_k , we use the fact that they sum to 1. Therefore, we add a Lagrangian term, differentiate w.r.t. π_k and set to 0, to get the following update:

$$\pi_k^{(t+1)} := \frac{1}{N} \sum_{n=1}^N q_{kn}^{(t)}$$

want $\sum_k \pi_k = 1$

$$\underline{\mathcal{L}}_n + \beta \left(\sum_{k=1}^K \pi_k - 1 \right)$$

modified unconstrained objective.

$$\nabla_{\pi_k} \underline{\mathcal{L}}_n(\theta, \theta^{(t)}) \stackrel{!}{=} 0$$

$$\underline{\mathcal{L}}_n(\theta, \theta^{(t)}) = \log \left(\frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)}{q_{kn}} \right)$$

$\exp(-(\mathbf{x}_n - \mu_k)^\top \Sigma_k^{-1} (\mathbf{x}_n - \mu_k))$ independent of θ

$$\nabla_{\mu_k} \underline{\mathcal{L}}(\theta, \theta^{(t)}) \stackrel{!}{=} 0$$

$$\nabla_{\Sigma_k^{-1}} \underline{\mathcal{L}}(\theta, \theta^{(t)}) \stackrel{!}{=} 0$$

$$\mathbf{v} = \mathbf{x}_n - \mu_k$$

Summary of EM for GMM

Initialize $\mu^{(1)}, \Sigma^{(1)}, \pi^{(1)}$ and iterate between the E and M step, until $\mathcal{L}(\theta)$ stabilizes.

1. E-step: Compute assignments $q_{kn}^{(t)}$:

$$q_{kn}^{(t)} := \frac{\pi_k^{(t)} \mathcal{N}(\mathbf{x}_n | \mu_k^{(t)}, \Sigma_k^{(t)})}{\sum_{k=1}^K \pi_k^{(t)} \mathcal{N}(\mathbf{x}_n | \mu_k^{(t)}, \Sigma_k^{(t)})} \approx \frac{\exp(-\frac{\|\mathbf{x}_n - \mu_k\|^2}{\sigma^2})}{\sum_{k=1}^K \exp(-\frac{\|\mathbf{x}_n - \mu_k\|^2}{\sigma^2})}$$

2. Compute the marginal likelihood (cost).

$$\mathcal{L}(\theta^{(t)}) = \sum_{n=1}^N \log \sum_{k=1}^K \pi_k^{(t)} \mathcal{N}(\mathbf{x}_n | \mu_k^{(t)}, \Sigma_k^{(t)})$$

3. M-step: Update $\mu_k^{(t+1)}, \Sigma_k^{(t+1)}, \pi_k^{(t+1)}$.

$$\mu_k^{(t+1)} := \frac{\sum_n q_{kn}^{(t)} \mathbf{x}_n}{\sum_n q_{kn}^{(t)}}$$

$$\Sigma_k^{(t+1)} := \frac{\sum_n q_{kn}^{(t)} (\mathbf{x}_n - \mu_k^{(t+1)}) (\mathbf{x}_n - \mu_k^{(t+1)})^\top}{\sum_n q_{kn}^{(t)}}$$

$$\pi_k^{(t+1)} := \frac{1}{N} \sum_n q_{kn}^{(t)}$$

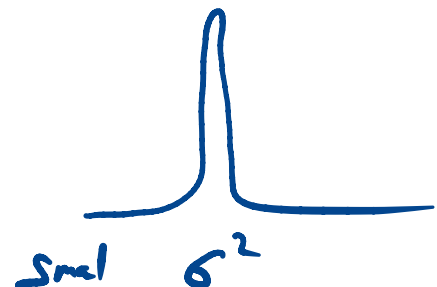
$\sigma^2 \rightarrow 0 = \begin{cases} 1 & \text{cluster } k \\ 0 & \text{other} \end{cases}$
k-means assignment

$q_{kn} \approx z_{kn}$

mean

members of cluster k

If we let the covariance be diagonal i.e. $\Sigma_k := \sigma^2 \mathbf{I}$, then EM algorithm is same as K-means as $\sigma^2 \rightarrow 0$.



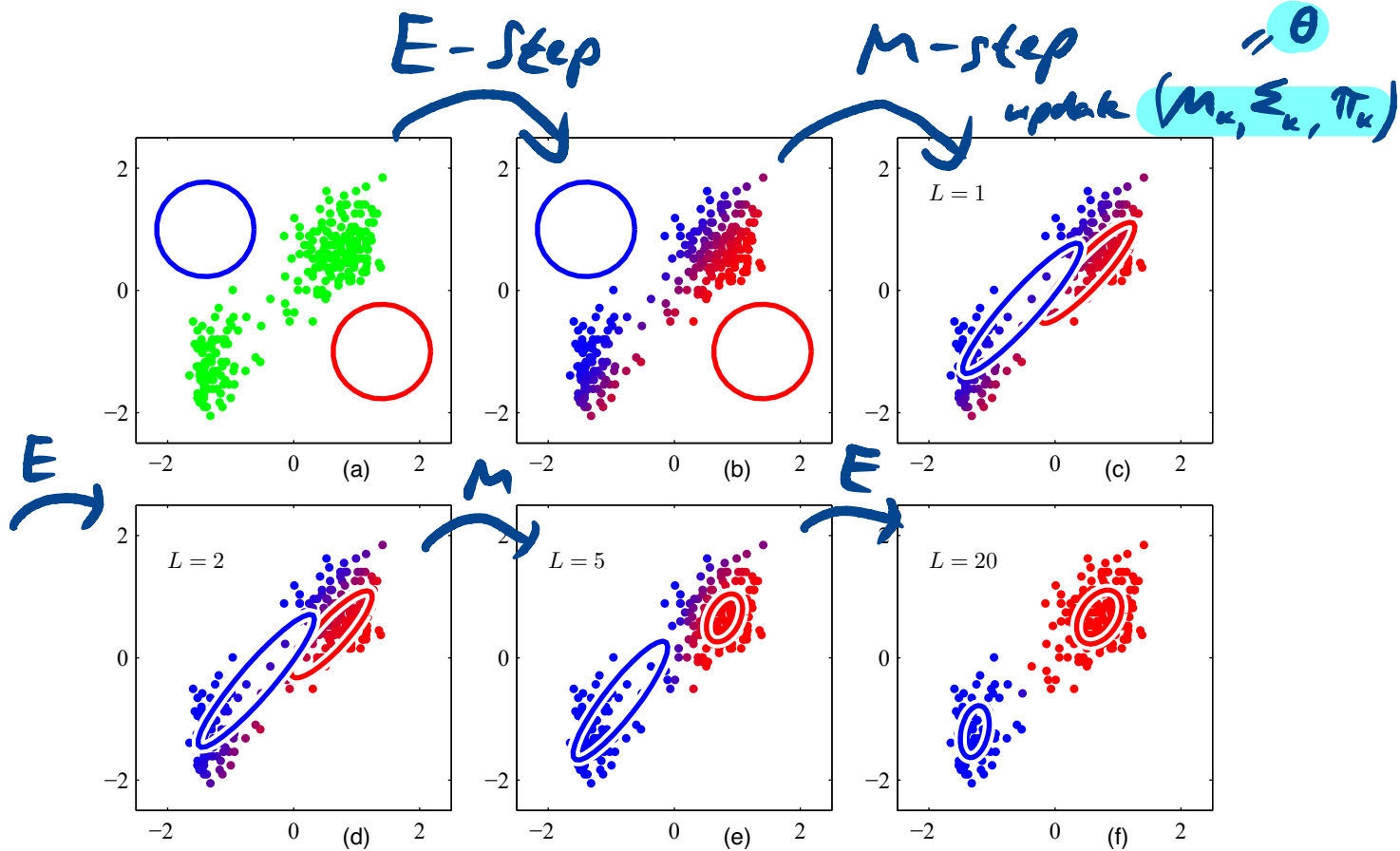


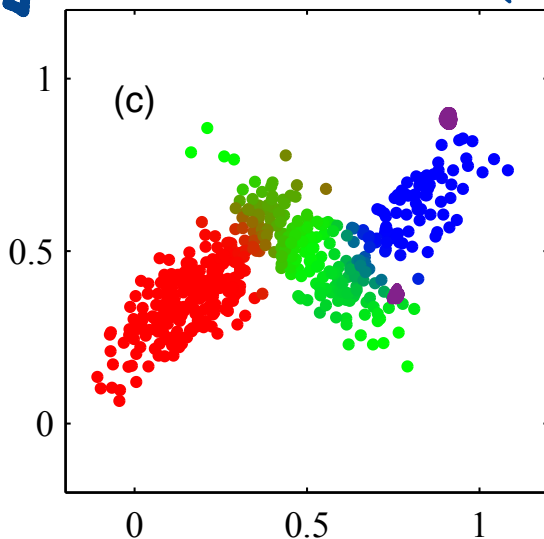
Figure 1: EM algorithm for GMM

Posterior distribution

We now show that $q_{kn}^{(t)}$ is the posterior distribution of the latent variable, i.e. $q_{kn}^{(t)} = p(z_n = k | \mathbf{x}_n, \theta^{(t)})$

$$p(\mathbf{x}_n, z_n | \theta) = \underbrace{p(\mathbf{x}_n | z_n, \theta)}_{\text{likelihood}} \underbrace{p(z_n | \theta)}_{\text{prior}} = \underbrace{p(z_n | \mathbf{x}_n, \theta)}_{\text{posterior}} \underbrace{p(\mathbf{x}_n | \theta)}_{\text{marginal likelihood}}$$

Bayes



$$p(z_n = k | \mathbf{x}_n, \theta) = \frac{\text{prior} \cdot \text{likelihood}}{\text{ML}}$$

$$= \frac{p(z_n = k | \theta) p(\mathbf{x}_n | z_n = k, \theta)}{\sum_{k=1}^K p(z_n = k) p(\mathbf{x}_n | z_n = k, \theta)}$$

$$= \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \pi_k}{\sum_k \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k) \pi_k} =: q_{kn}$$

EM in general

Given a general joint distribution $p(\mathbf{x}_n, z_n | \boldsymbol{\theta})$, the marginal likelihood can be lower bounded similarly:

The EM algorithm can be compactly written as follows:

$$\boldsymbol{\theta}^{(t+1)} := \arg \max_{\boldsymbol{\theta}} \sum_{n=1}^N \mathbb{E}_{p(z_n | \mathbf{x}_n, \boldsymbol{\theta}^{(t)})} [\log p(\mathbf{x}_n, z_n | \boldsymbol{\theta})]$$

Another interpretation is that part of the data is missing, i.e. (\mathbf{x}_n, z_n) is the “complete” data and z_n is missing. The EM algorithm averages over the “unobserved” part of the data.