CENG 2034 - Operating Systems Week 12: Deadlocks

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Outline

- 1 System Model
- 2 Deadlock Characterizatio
- B Deadlock Handlin
- 4 Deadlock Prevention
- 5 Deadlock Avoidance
- 6 Deadlock Detection

• System consists of resources

System Model

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- Resource types $R_1, R_2, ..., R_m$ CPU cycles, memory space, I/O devices

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 - request
 - use
 - release

• Data:

• Data:

000

• A semaphore S₁ initialized to 1

- Data:

 - A semaphore S₁ initialized to 1
 A semaphore S₂ initialized to 1

Data:

System Model

- A semaphore S₁ initialized to 1
- A semaphore S_2 initialized to 1
- Two threads T_1 and T_2

```
T_1:

wait(s_1)

wait(s_2)

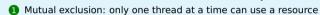
T_2:

wait(s_2)

wait(s_1)
```

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- Mutual exclusion: only one thread at a time can use a resource
- A Hold and wait: a thread holding at least one resource is waiting to acquire additional resources held by others

- 1 Mutual exclusion: only one thread at a time can use a resource
- 2 Hold and wait: a thread holding at least one resource is waiting to acquire additional resources held by others
- No preemption: a resource can be released only voluntarily by the holding thread after the task completion

System Model

Deadlock can arise if four conditions hold simultaneously

- Mutual exclusion: only one thread at a time can use a resource
- 2 Hold and wait: a thread holding at least one resource is waiting to acquire additional resources held by others
- So preemption: a resource can be released only voluntarily by the holding thread after the task completion
- 4 Circular wait: there exists a set $\{T_0, T_1, \dots, T_n\}$ of waiting threads such that

 \mathcal{T}_0 is waiting for a resource that is held by \mathcal{T}_1

 T_1 is waiting for a resource that is held by T_2

. . .

 T_{n-1} is waiting for a resource that is held by T_n , and T_n is waiting for a resource that is held by T_0

Resource-Allocation Graph

A set of vertices V and a set of edges E

Resource-Allocation Graph

A set of vertices V and a set of edges E

V is partitioned into two types:

 $T = \{T_1, T_2, \dots, T_n\}$ the set consisting of all the threads in the system

 $R = \{R_1, R_2, \dots, R_m\}$ the set consisting of all resource types in the system

Resource-Allocation Graph

A set of vertices V and a set of edges E

- V is partitioned into two types:
 - $T = \{T_1, T_2, \dots, T_n\}$ the set consisting of all the threads in the system $R = \{R_1, R_2, \dots, R_m\}$ the set consisting of all resource types in the system
- Edges:

System Model

request edge directed edge $T_i \rightarrow R_j$ assignment edge directed edge $R_j \rightarrow T_i$

One instance of R₁

One instance of R₁

System Model

Two instances of R₂

- One instance of R₁
- Two instances of R₂
- One instance of R₃

- One instance of R₁
- Two instances of R₂
- One instance of R₃
- Three instance of R₄

• One instance of R₁

System Model

- Two instances of R₂
- One instance of R₃
- Three instance of R₄
- T_1 holds one instance of R_2 and is waiting for an instance of R_1

Deadlock Detection

• One instance of R_1

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- One instance of R₃
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- T_1 holds one instance of R_2 and is waiting for an instance of R_1
- T_2 holds one instance of R_1 , one instance of R_2 , and is waiting for an instance of R_3

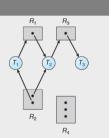
• One instance of R_1

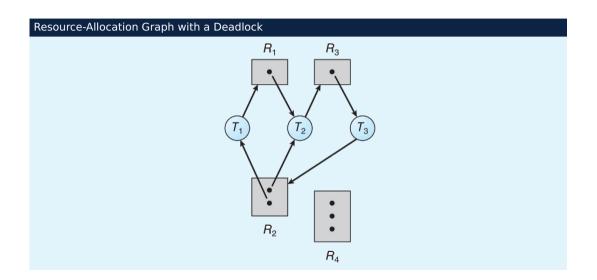
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- T_3 is holds one instance of R_3

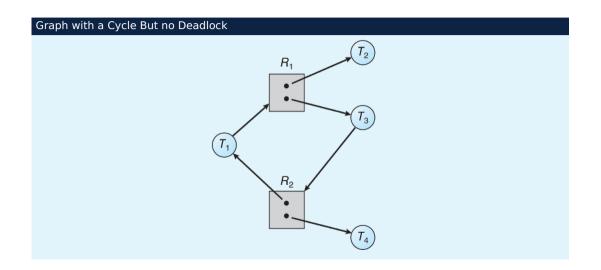
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Basic Facts

• If graph contains no cycles \Rightarrow no deadlock

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- If graph contains no cycles ⇒ no deadlock
- If graph contains a cycle ⇒
 - if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock

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- 1 System Mode
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Methods for Handling Deadlocks

• Ensure that the system will never enter a deadlock state:

Methods for Handling Deadlocks

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 - Deadlock prevention

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System Model

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System Model

Methods for Handling Deadlocks

- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance
- Allow the system to enter a deadlock state and then recover
- Ignore the problem and pretend that deadlocks never occur in the system

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System Model

Invalidate one of the four necessary conditions for deadlock:

 Mutual Exclusion – not required for sharable resources (e.g., read-only files); must hold for non-sharable resources

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 - Require threads to request and be allocated all its resources before it begins execution or allow thread to request resources only when the thread has none allocated to it

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- Hold and Wait must guarantee that whenever a thread requests a resource, it does not hold any other resources
 - Require threads to request and be allocated all its resources before it begins execution or allow thread
 to request resources only when the thread has none allocated to it
 - Low resource utilization; starvation possible

No Preemption:

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System Model

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- Circular Wait:
 - Impose a total ordering of all resource types, and require that each thread requests resources in an increasing order of enumeration

Circular Wait

• Invalidating the circular wait condition is most common

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- Resources must be acquired in order

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System Model

Requires that the system has some additional a priori information available

- Simplest and most useful model requires that each thread declare the maximum number of resources of each type that it may need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes

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 - When T_i is finished, T_i can obtain needed resources, execute, return allocated resources, and terminate
 - When T_i terminates, T_{i+1} can obtain its needed resources, and so on ...

Basic Facts

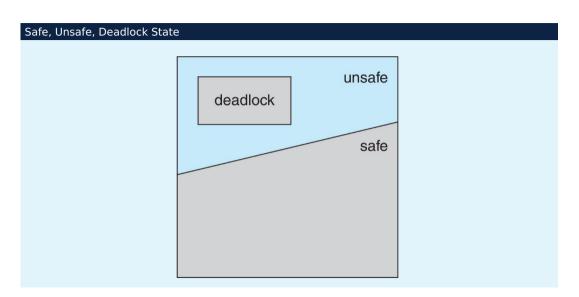
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- If a system is in unsafe state ⇒ possibility of deadlock
- Avoidance ⇒ ensure that a system will never enter an unsafe state



Avoidance Algorithms

• Single instance of a resource type – Use a resource-allocation graph

Avoidance Algorithms

- Single instance of a resource type Use a resource-allocation graph
- Multiple instances of a resource type Use the Banker's Algorithm

Resource-Allocation Graph Scheme

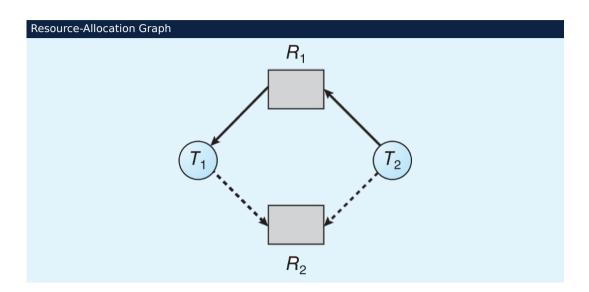
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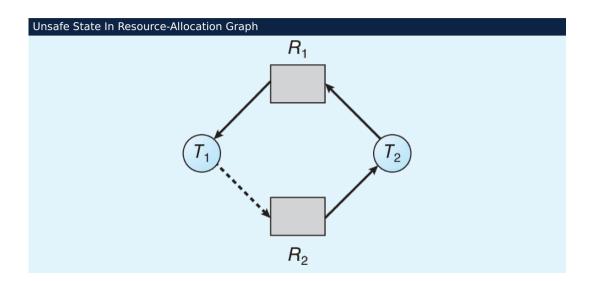
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- Resources must be claimed a priori in the system





Resource-Allocation Graph Algorithm

• Suppose that thread T_i requests a resource R_i

Resource-Allocation Graph Algorithm

- Suppose that thread T_i requests a resource R_j
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph

System Model

Multiple instances of resources

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- Each thread must a priori claim maximum use
- When a thread requests a resource, it may have to wait
- When a thread gets all its resources it must return them in a finite amount of time

Data Structures for the Banker's Algorithm

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Let n = number of threads, and m = number of resources types.

• Available: Vector of length m. If available [j] = k, there are k instances of resource type R_j available

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- Allocation: $n \times m$ matrix. If Allocation[i, j] = k then T_i is currently allocated k instances of R_j
- Need: $n \times m$ matrix. If Need[i,j] = k, then T_i may need k more instances of R_j to complete its task Need[i,j] = Max[i,j] Allocation[i,j]

System Model

1 Let Work and Finish be vectors of length m and n, respectively. Initialize:

Work = Available

Finish[i] = false for i = 0, 1, ..., n-1

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Finish[i] = false

Need; ≤ Work

If no such i exists, go to step 4

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Work = Work + Allocation;

Finish[i] = true

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 \bigcirc Work = Work + Allocation,

Finish[i] = true

go to step 2

4 If Finish[i] == true for all i, then the system is in a safe state

Resource-Request Algorithm for Thread T_i

 $\mathsf{Request}_i = \mathsf{request} \ \mathsf{vector} \ \mathsf{for} \ \mathsf{thread} \ T_i. \ \mathsf{If} \ \mathsf{Request}_i[j] = k \ \mathsf{then} \ \mathsf{thread} \ T_i \ \mathsf{wants} \ k \ \mathsf{instances} \ \mathsf{of} \ \mathsf{resource} \ \mathsf{type} \ R_j$

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Resource-Request Algorithm for Thread T_i

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• If safe \Rightarrow the resources are allocated to T_i

Resource-Request Algorithm for Thread T_i

 $\mathsf{Request}_i = \mathsf{request} \ \mathsf{vector} \ \mathsf{for} \ \mathsf{thread} \ T_i. \ \mathsf{If} \ \mathsf{Request}_i[j] = k \ \mathsf{then} \ \mathsf{thread} \ T_i \ \mathsf{wants} \ k \ \mathsf{instances} \ \mathsf{of} \ \mathsf{resource} \ \mathsf{type} \ R_j$

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```
Available = Available - Request;;

Allocation; = Allocation; + Request;;

Need; = Need; - Request;:
```

- If safe ⇒ the resources are allocated to T_i
- If unsafe $\Rightarrow T_i$ must wait, and the old resource-allocation state is restored

Example (Banker's Algorithm)

• 5 threads T_0 through T_4 ;

Example (Banker's Algorithm)

System Model

- 5 threads T_0 through T_4 ;
- 3 resource types: A (10 instances) B (5 instances) C (7 instances)

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System Model

- 3 resource types: A (10 instances) B (5 instances) C (7 instances)
- Current state snapshot:

	Allocation	Max	Available
	ABC	ABC	ABC
T_0	010	753	3 3 2
T_1	200	3 2 2	
T_2	302	902	
T_3	211	222	
T_4	002	4 3 3	

Example (Banker's Algorithm (cont'd))

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- Current-state snapshot:

System Model

Need
ABC
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122
600
011
431

Example (Banker's Algorithm (cont'd))

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- 3 resource types: A (10 instances) B (5 instances) C (7 instances)
- Current-state snapshot:

System Model

	Need
	ABC
T_0	7 4 3
T_1	122
T_2	600
T_3	011
T_4	4 3 1

• The system is in a safe state since the sequence

$$< T_1, T_3, T_4, T_2, T_0 >$$

satisfies safety criteria

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Deadlock Detection

Allow system to enter deadlock state

Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm

Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme

Single Instance of Each Resource Type

Maintain wait-for graph

System Model

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 - Nodes are threads

Single Instance of Each Resource Type

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Single Instance of Each Resource Type

- Maintain wait-for graph
 - Nodes are threads
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- Periodically invoke an algorithm that searches for a cycle in the graph

Single Instance of Each Resource Type

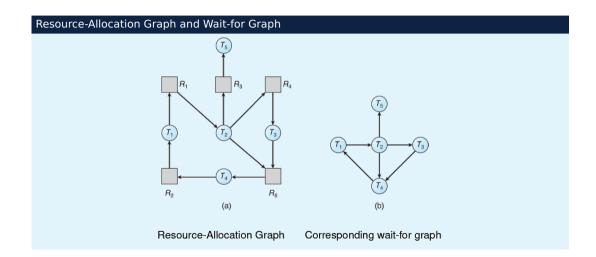
- Maintain wait-for graph
 - Nodes are threads
 - $T_i \rightarrow T_j$ if T_i is waiting for T_j
- Periodically invoke an algorithm that searches for a cycle in the graph
- If there is a cycle, there exists a deadlock

Single Instance of Each Resource Type

Maintain wait-for graph

System Model

- Nodes are threads
- $T_i \rightarrow T_j$ if T_i is waiting for T_j
- Periodically invoke an algorithm that searches for a cycle in the graph
- If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of n^2 operations, where n is the number of vertices in the graph



Several Instances of a Resource Type

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- Allocation: An $n \times m$ matrix defines the number of resources of each type currently allocated to each thread
- Request: An $n \times m$ matrix indicates the current request of each thread. If Request[i][j] = k, then thread T_i is requesting k more instances of resource type R_j

System Model

 $oldsymbol{0}$ Let Work and Finish be vectors of length m and n, respectively Initialize:

Work = Available

Finish[i] = false if Allocation $\neq 0$ for i = 1, 2, ... n

Finish[i] = true otherwise

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① If Finish[i] == false, for some i s.t. $1 \le i \le n$, then the system is in deadlock state. Moreover, if Finish[i] == false, then T_i is deadlocked

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- Current-state snapshot:

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	ABC	ABC	ABC
T_0	010	000	000
T_1	200	202	
T_2	303	000	
T_3	211	100	
T_4	002	002	

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Sequence

System Model

$$< T_0, T_2, T_3, T_4, T_1 >$$

will result in Finish[i] = true for all i

Example (Detection Algorithm (cont'd))

• T₂ requests an additional instance of type C

	Request
	ABC
T_0	000
T_1	202
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State of system?

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 - Can reclaim resources held by thread T_0 , but insufficient resources to fulfill other threads; requests

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- State of system?
 - Can reclaim resources held by thread T₀, but insufficient resources to fulfill other threads; requests
 - Deadlock exists, consisting of threads T_1 , T_2 , T_3 , and T_4

Detection Algorithm Usage

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System Model

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- When, and how often, to invoke depends on:
 - How often a deadlock is likely to occur?
 - How many threads will be affected by deadlock when it happens?
- If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked threads "caused" the deadlock.

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 - 6 Is the thread interactive or batch?

Recovery from Deadlock: Resource Preemption

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- Selecting a victim minimize cost
- Rollback return to some safe state, restart the thread for that state
- Starvation same thread may always be picked as victim, include number of rollback in cost factor

Thanks! & Questions?