



Latent-Variable Models: Gaussian-Mixture & Other Cases

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Outline

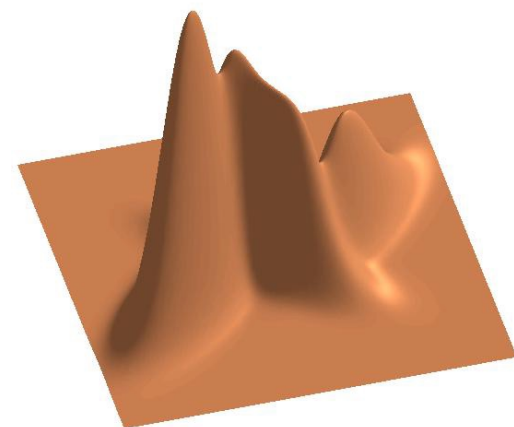
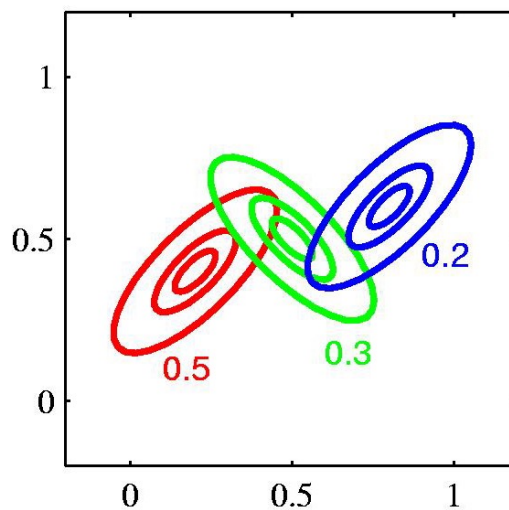
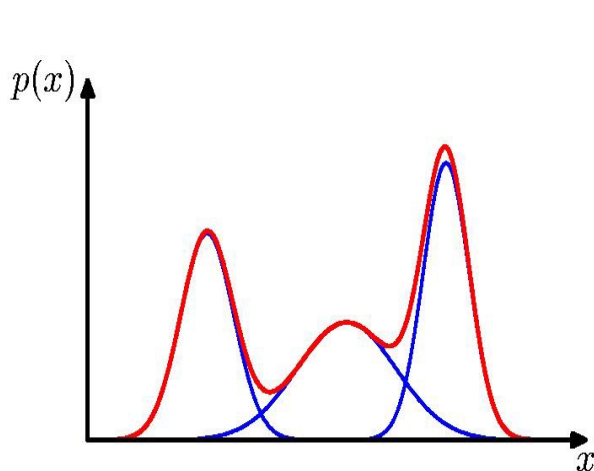
- Gaussian Mixture Distribution
- Learning the Distribution Parameters
- Other Examples of LVMs

Gaussian Mixture Distributions

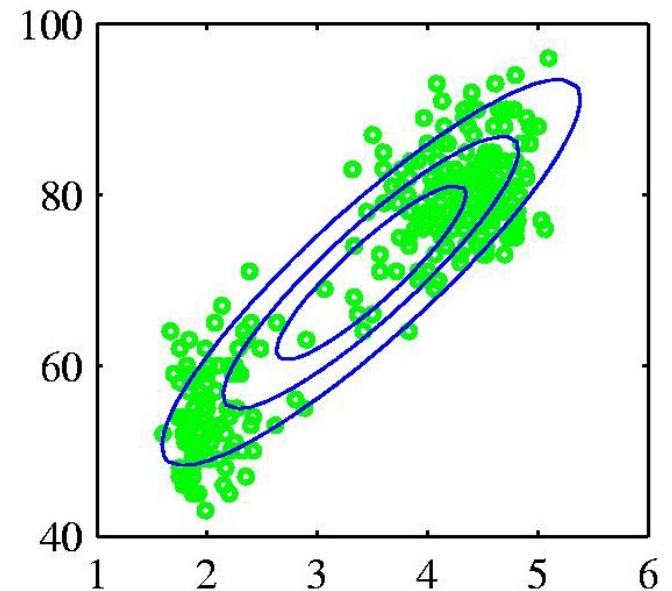
- The distribution expression

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

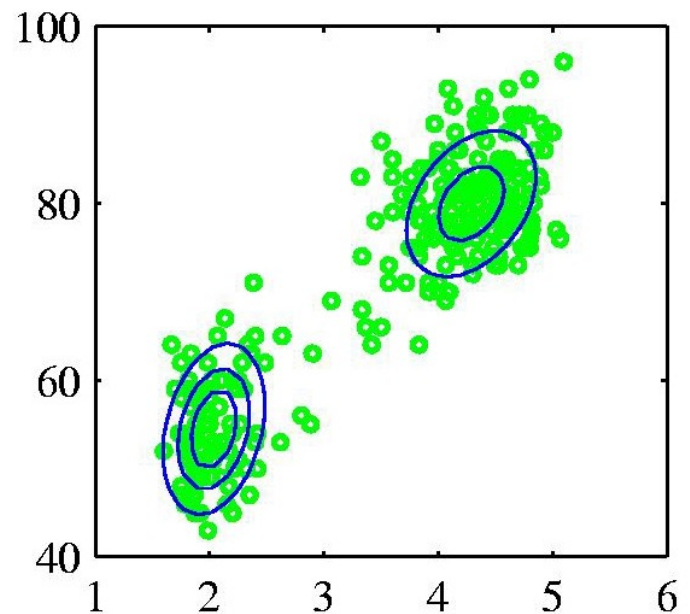
- K is the number of Gaussian distributions
- π_k is the weight of the k -th distribution with $\sum_{k=1}^K \pi_k = 1$
- $\boldsymbol{\mu}_k$ and $\boldsymbol{\Sigma}_k$ are the mean vector and covariance matrix of the k -th Gaussian distribution



- It is very difficult to model the green points by a Gaussian distribution



- But if we model it with the mixture of two Gaussian distributions, it looks much better



Representing Gaussian Mixture Distribution as LVM

- For a latent-variable model $p(\mathbf{x}, \mathbf{z})$, if we set its conditional distribution $p(\mathbf{x}|\mathbf{z})$ and prior distribution $p(\mathbf{z})$ as

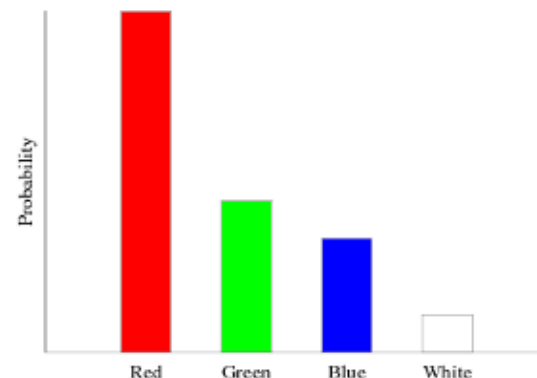
$$p(\mathbf{x}|\mathbf{z} = \mathbf{1}_k) = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

$$p(\mathbf{z} = \mathbf{1}_k) = \pi_k$$

- \mathbf{z} can only be a **one-hot vector**, with $\mathbf{1}_k$ denoting the k -th element to be 1
- $p(\mathbf{z} = \mathbf{1}_k) = \pi_k$, which is actually a categorical distribution, that is,

$$p(\mathbf{z}) = \text{Cat}(\mathbf{z}; \boldsymbol{\pi})$$

with $\text{Cat}(\mathbf{z} = \mathbf{1}_k; \boldsymbol{\pi}) = \pi_k$ and
 $\boldsymbol{\pi} = [\pi_1, \pi_2, \dots, \pi_K]$



- With $p(\mathbf{x}|\mathbf{z} = \mathbf{1}_k) = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$ and $p(\mathbf{z} = \mathbf{1}_k) = \pi_k$, we can easily see that

$$\begin{aligned} p(\mathbf{x}, \mathbf{z} = \mathbf{1}_k) &= p(\mathbf{x}|\mathbf{z} = \mathbf{1}_k)p(\mathbf{z} = \mathbf{1}_k) \\ &= \pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \end{aligned}$$

- Therefore, the joint distribution $p(\mathbf{x}, \mathbf{z})$ can be written in a more compact form as

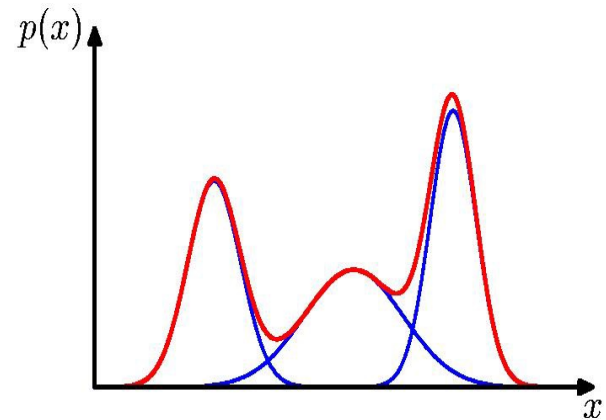
$$p(\mathbf{x}, \mathbf{z}) = \prod_{k=1}^K [\pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)]^{z_k}$$

where $\mathbf{z} = [z_1, z_2, \dots, z_K]$ is a one-hot vector, that is, there is only one non-zero element (equal to 1) in \mathbf{z}

- Due to $p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z})$, we can easily see that

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k),$$

which is exactly the Gaussian mixture distribution



Gaussian mixture distributions can be equivalently represented by the latent-variable model

$$p(\mathbf{x}, \mathbf{z}) = \prod_{k=1}^K [\pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)]^{z_k}$$

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Training by Maximizing the Marginal

- Given a set of training data $\{\mathbf{x}^{(n)}\}_{n=1}^N$, the goal is to learn the distribution parameters

$$\{\pi_k, \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K \triangleq \boldsymbol{\theta}$$

- The data points $\mathbf{x}^{(n)}$ are assumed *i.i.d*, thus we can write the joint distribution as

$$p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}) = \prod_{n=1}^N \underbrace{\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}^{(n)}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}_{p(\mathbf{x}^n)}$$

Not using the model
with latent variable

- For probabilistic models, the training objective is *to maximize the log-likelihood function*, that is,

$$\log p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}) = \sum_{n=1}^N \log \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}^{(n)}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

Maximizing $\log p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)})$

- Substituting the expression of $\mathcal{N}(\mathbf{x}^{(n)}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$ into it gives

$$\begin{aligned} \log p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}) \\ = \sum_{n=1}^N \log \left(\sum_{k=1}^K \pi_k \frac{1}{(2\pi)^{D/2} |\boldsymbol{\Sigma}_k|^{1/2}} \exp \left\{ -\frac{1}{2} (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T \boldsymbol{\Sigma}_k^{-1} (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k) \right\} \right) \end{aligned}$$

- To optimize it, we require the *derivatives* of $\log p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)})$ w.r.t. the model parameters $\{\pi_k, \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K$

How to Use the Learned Model?

- After learning the parameters $\{\pi_k, \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K$, that is, the distribution

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

is known, we can *use it to complete a lot of tasks*

- **Example:** Given a testing data point \mathbf{x} , can we use it to determine the probability that an \mathbf{x} belongs to the k -th cluster?

$$p(\mathbf{x} \in k\text{-th cluster}) = \frac{\pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{i=1}^K \pi_i \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i)}$$

- Can we explain the probability in a more principled way?

$$p(\mathbf{z} = \mathbf{1}_k | \mathbf{x}) = ?$$

$$\begin{aligned} p(\mathbf{z} = \mathbf{1}_k | \mathbf{x}) &= \frac{p(\mathbf{x}, \mathbf{z} = \mathbf{1}_k)}{p(\mathbf{x})} \\ &= \frac{p(\mathbf{x}, \mathbf{z} = \mathbf{1}_k)}{\sum_{i=1}^K p(\mathbf{x}, \mathbf{1}_i)} \\ &= \frac{\pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{i=1}^K \pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i)} \end{aligned}$$

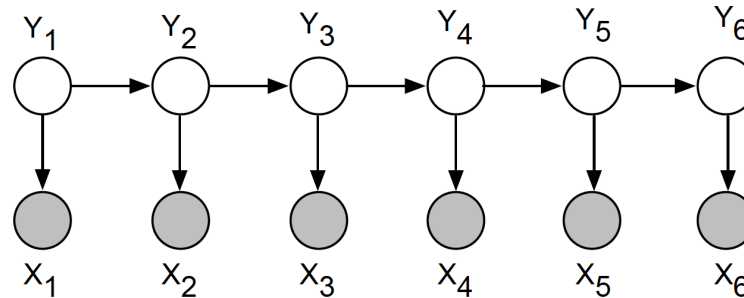
Thus, in the latent-variable model, the **posteriori** $p(\mathbf{z} | \mathbf{x})$ indicates the probability that a data instance belongs to different clusters

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Applications: Hidden Markov Model

- Hidden Markov Model (HMM)



- It is widely used in speech recognition, part-of-speech tagging, localization *etc.*
- Joint distribution

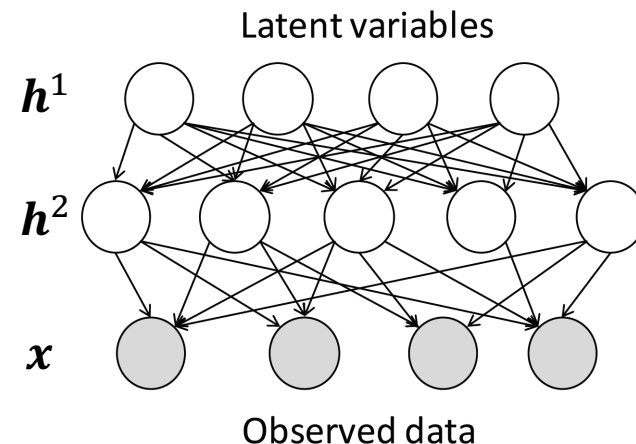
$$p(\mathbf{y}, \mathbf{x}) = p(y_1)p(x_1|y_1) \prod_{t=2}^T p(y_t|y_{t-1})p(x_t|y_t)$$

where $p(y_t|y_{t-1})$ is the transition probability; $p(x_t|y_t)$ is the emission probability

Applications: Image Modeling

- Sigmoid belief networks (SBN)

- $h_i^1 \sim \text{Bernoulli}(0.5)$
- $h_j^2 \sim \text{Bernoulli}(\sigma([W_1 h^1 + b_1]_j))$
- $x_k \sim \text{Bernoulli}(\sigma([W_2 h^2 + b_2]_k))$



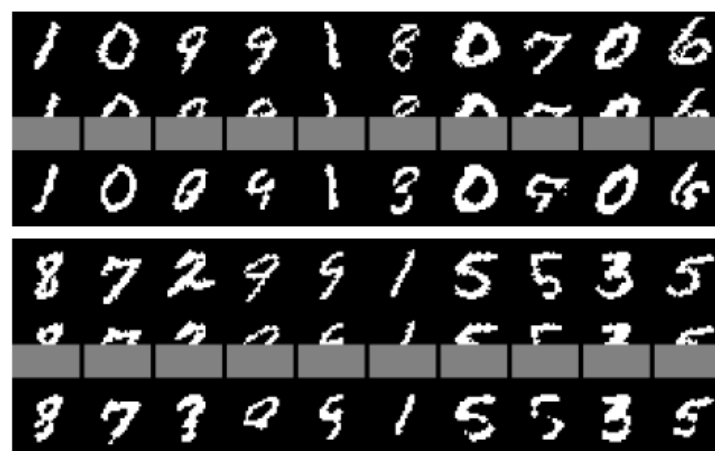
Joint pdf: $p(x, h^2, h^1) = p(x|h^2)p(h^2|h^1)p(h^1)$



Original



Generating



In-painting

Applications: Text Modeling

- Topic Model: Latent Dirichlet Allocation (LDA)

- $\theta \sim \text{Dir}(\alpha)$: the distribution of different topics

- $\varphi_k \sim \text{Dir}(\beta)$: the distribution of words for topic

- $z_n \sim \text{Multinomial}(\theta)$: the topic of n -th word

- $w_n \sim \text{Multinomial}(\varphi_{z_n})$: the n -th word

