$$1. \ bo = \frac{1}{\sqrt{n}} \left[ \frac{1}{1} \right]$$

$$= \frac{V_1}{\|V_1\|_2}$$

$$29. \|E\|_{F}^{2} = \underbrace{E}_{i=1}^{min(mxn)} 6i^{2}$$
 rank  $1 = 6i^{2}$ 

$$= 61^{2} + 62^{2} + 63^{2} - 61^{2}$$

$$= 62^{2} + 63^{2}$$

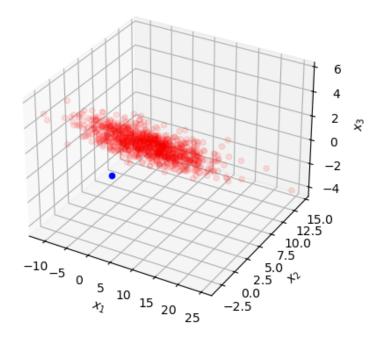
$$2j$$
.  $||E||_F^2 = \frac{\min(m \times n)}{6i} \frac{2}{\min(m \times n)}$ 

$$= 6_1^2 + 6_2^2 + 6_3^2 - \left(6_1^2 + 6_2^2\right)$$

# Assign6Starter

March 22, 2024

```
[130]: # Enable interactive rotation of graph
       %matplotlib widget
       import numpy as np
       from scipy.io import loadmat
       import matplotlib.pyplot as plt
       from mpl_toolkits.mplot3d import Axes3D
       # Load data for activity
       X = np.loadtxt('sdata.csv',delimiter=',')
[131]: fig = plt.figure()
       ax = fig.add_subplot(111, projection='3d')
       ax.scatter(X[:,0], X[:,1], X[:,2], c='r', marker='o', alpha=0.1)
       ax.scatter(0,0,0,c='b', marker='o')
       ax.set_xlabel('$x_1$')
       ax.set_ylabel('$x_2$')
       ax.set_zlabel('$x_3$')
       plt.show()
```



#### 1 Question 2a:

No, because the subspace need to cross the origin (0, 0, 0)

# 2 Question 2b:

We need to substract the data with mean so the subspace will cross the origin.

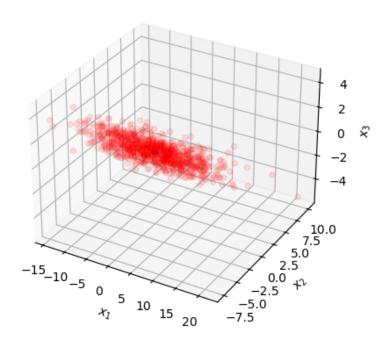
```
[132]: # Subtract mean
X_m = X - np.mean(X, 0)

[133]: # display zero mean scatter plot
fig = plt.figure()

ax = fig.add_subplot(111, projection='3d')
ax.scatter(X_m[:,0], X_m[:,1], X_m[:,2], c='r', marker='o', alpha=0.1)

ax.scatter(0,0,0,c='b', marker='o')
ax.set_xlabel('$x_1$')
ax.set_ylabel('$x_2$')
```

```
ax.set_zlabel('$x_3$')
plt.show()
```



### 3 Question 2c:

Yes, the mean-removed data appear to lie in a low-dimensional subspace. Because it cross the origin.

```
[134]: # Use SVD to find first principal component

U,s,VT = np.linalg.svd(X_m,full_matrices=False)

# complete the next line of code to assign the first principal component to a a = VT[0,:]

[135]: # display zero mean scatter plot and first principal component

fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
```

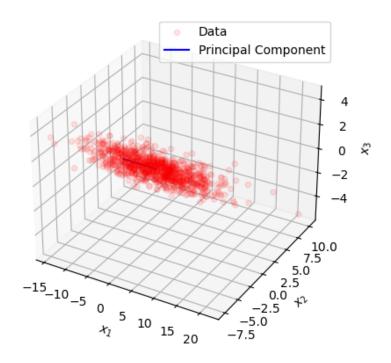
```
#scale length of line by root mean square of data for display
ss = s[0]/np.sqrt(np.shape(X_m)[0])

ax.scatter(X_m[:,0], X_m[:,1], X_m[:,2], c='r', marker='o', label='Data',
alpha=0.1)

ax.plot([0,ss*a[0]],[0,ss*a[1]],[0,ss*a[2]], c='b',label='Principal Component')

ax.set_xlabel('$x_1$')
ax.set_ylabel('$x_2$')
ax.set_zlabel('$x_3$')

ax.legend()
plt.show()
```



### 4 Question 2d:

A one-dimensional subspace doesn't display good visualization because there are many overlapping data.

#### 5 Question 2e:

#### 6 Question 2f:

What is b? b is mean

# 7 Question 2g: Notes

# 8 Question 2h:

(1000, 3)

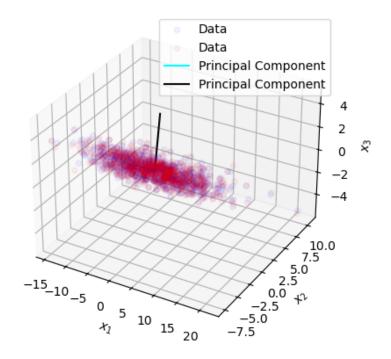
```
[138]: array([[11.18430814, 5.3315948, -0.88826538],
              [ 3.41454955, 1.65138299, -0.47852885],
              [2.09449227, 1.0523074, -0.63838285],
              [0.53520662, 0.22159313, 0.25147638],
              [ 1.59260018, 0.6570293 , 0.76899203],
              [-4.80486921, -2.31211678, 0.57110436]])
[139]: # Use SVD to find first principal component
       print(X_m.shape)
       U,s,VT = np.linalg.svd(X,full_matrices=False)
       # complete the next line of code to assign the first principal component to a
       a = VT[0,:]
       b = VT[1,:]
      (1000, 3)
[140]: # display zero mean scatter plot and first principal component
       fig = plt.figure()
       ax = fig.add_subplot(111, projection='3d')
       #scale length of line by root mean square of data for display
       ss = s[0]/np.sqrt(np.shape(X)[0])
       ax.scatter(X[:,0], X[:,1], X[:,2], c='b', marker='o', label='Data', alpha=0.05)
       ax.scatter(X_m[:,0], X_m[:,1], X_m[:,2], c='r', marker='o', label='Data',_
       →alpha=0.05)
       ax.plot([0,ss*a[0]],[0,ss*a[1]],[0,ss*a[2]], c='cyan',label='Principal_u

    Gomponent¹)

       ax.plot([0,ss*b[0]],[0,ss*b[1]],[0,ss*b[2]], c='black',label='Principal__

Gomponent')

       ax.set_xlabel('$x_1$')
       ax.set_ylabel('$x_2$')
       ax.set_zlabel('$x_3$')
       ax.legend()
       plt.show()
```



### 9 Question 2i:

The rank 2 approx (blue) is a good approximation. It lies in a plane. The plane capture the dominant components of the data.

### 10 Question 2k:

Find and compare the numerical values for  $||\mathbf{E}||2$  F using both the rank-1 and rank-2 approximation. sigma 2 square

# 11 Question 3a:

```
[141]: import numpy as np
import scipy.io as sio
data = sio.loadmat('face_emotion_data.mat')
X, y = data['X'], data['y']

total_error = []
```

```
for i in range(8):
    for j in range(8):
        if i == j: continue
        test_idx_1 = np.arange(i*16, (i+1)*16)
        test_idx_2 = np.arange(j*16, (j+1)*16)
        train_idx = np.setdiff1d(np.arange(128), test_idx_1)
        train_idx = np.setdiff1d(train_idx, test_idx_2)
        X_train, y_train = X[train_idx, :], y[train_idx, :]
        X_test_1, y_test_1 = X[test_idx_1, :], y[test_idx_1, :]
        X_{\text{test}_2}, y_{\text{test}_2} = X[\text{test}_i dx_2, :], y[\text{test}_i dx_2, :]
        param = None
        lowest = 9223372036854775807
        for r in range(1,10):
            U, s, VT = np.linalg.svd(X_train, full_matrices=False)
            S = np.diag(1/s[:r])
            approx = VT[:r, :].T @ S @ U[:,:r].T @ y_train
            y_pred = np.sign(X_test_2 @ approx)
            error = []
            for idx, item in enumerate(y_pred):
                if item == y_test_2[idx]:
                     error.append(0)
                else:
                     error.append(1)
            error_percentage = sum(error) / len(error)
            # print(error_percentage)
            if error_percentage < lowest:</pre>
                lowest = error_percentage
                param = r
        U, s, VT = np.linalg.svd(X_train, full_matrices=False)
        S = np.diag(1/ s[:param])
        w = VT[:param, :].T @ S @ U[:,:param].T @ y_train
        y_pred_1 = np.sign(X_test_1 @ w)
        error = []
        for idx, item in enumerate(y_pred_1):
            if item == y_test_1[idx]:
                error.append(0)
            else:
                error.append(1)
        error_percentage = sum(error) / len(error)
        # print(error_percentage)
        total_error.append(error_percentage)
```

```
print("Error SVD: ", sum(total_error)/ 56)
```

Error SVD: 0.11160714285714286

```
[142]: import numpy as np
       import scipy.io as sio
       data = sio.loadmat('face_emotion_data.mat')
       X, y = data['X'], data['y']
       total_error = []
       for i in range(8):
           for j in range(8):
               param = None
               lowest = 9223372036854775807
               lambda_list = [0, 0.5, 1, 2, 4, 8, 16]
               if i == j: continue
               test_idx_1 = np.arange(i*16, (i+1)*16)
               test_idx_2 = np.arange(j*16, (j+1)*16)
               train_idx = np.setdiff1d(np.arange(128), test_idx_1)
               train_idx = np.setdiff1d(train_idx, test_idx_2)
               X_train, y_train = X[train_idx, :], y[train_idx, :]
               X_test_1, y_test_1 = X[test_idx_1, :], y[test_idx_1, :]
               X_test_2, y_test_2 = X[test_idx_2, :], y[test_idx_2, :]
               for x in lambda list:
                   U, s, VT = np.linalg.svd(X_train, full_matrices=False)
                   S = s / (s**2 +x)
                   S = np.diag(S)
                   w = VT.T @ S @ U.T @y_train
                   y_pred = np.sign(X_test_2 @ w)
                   error = []
                   for idx, item in enumerate(y_pred):
                       if item == y_test_2[idx]:
                           error.append(0)
                       else:
                           error.append(1)
                   error_percentage = sum(error) / len(error)
                   if error_percentage < lowest:</pre>
```

```
lowest = error_percentage
                param = x
       U, s, VT = np.linalg.svd(X_train, full_matrices=False)
       S = s / (s**2 + param)
       S = np.diag(S)
        # print(S)
       new_w = VT.T @ S @ U.T @y_train
       y_pred_1 = np.sign(X_test_1 @ new_w)
       error = []
       for idx, item in enumerate(y_pred_1):
            if item == y_test_1[idx]:
                error.append(0)
            else:
                error.append(1)
        error_percentage = sum(error) / len(error)
       total_error.append(error_percentage)
print("Error SVD - Ridge: ", sum(total_error)/ 56)
```

Error SVD - Ridge: 0.04799107142857143

[]: