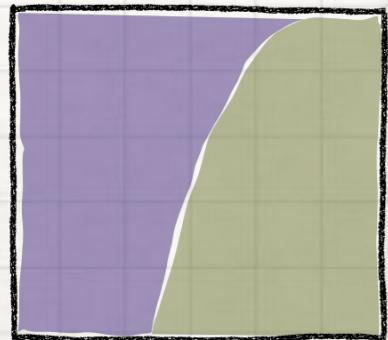


# BIAS VARIANCE BOOTSTRAPPING AND BOOSTING

# REVIEW

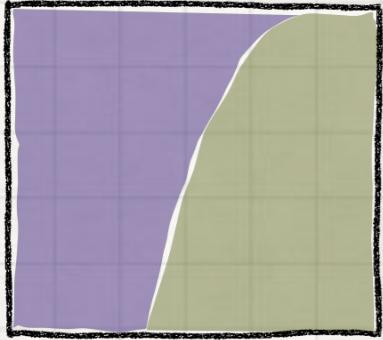
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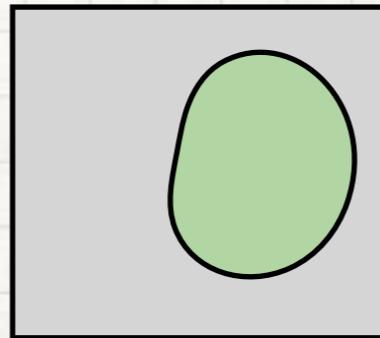


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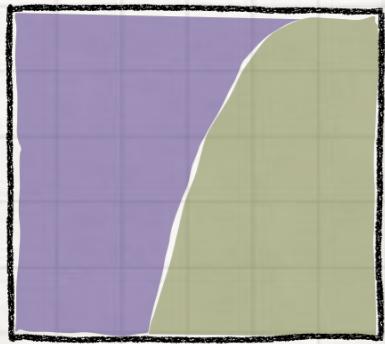


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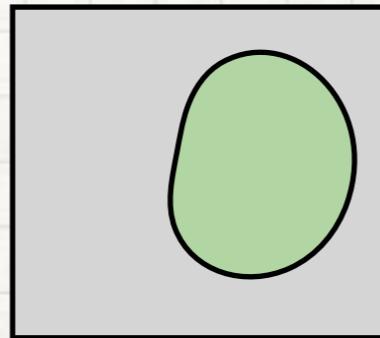


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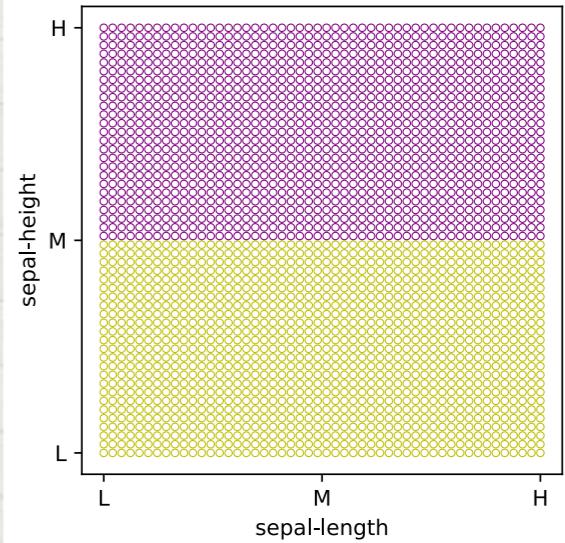
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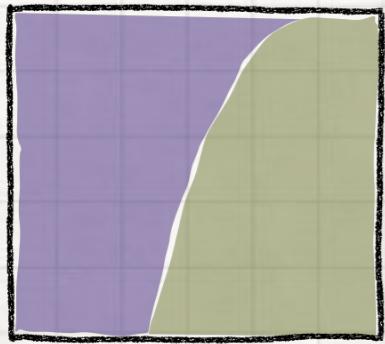


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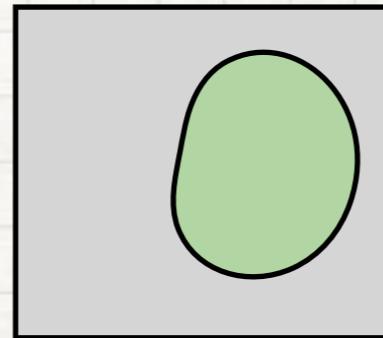


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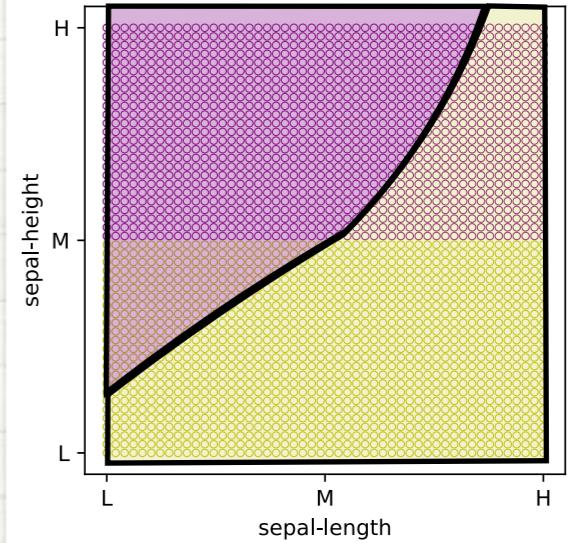
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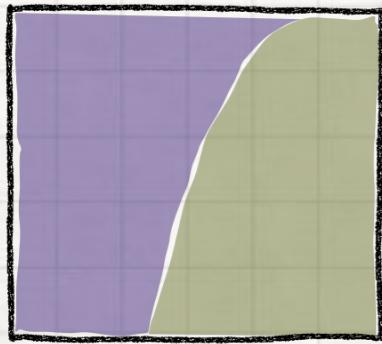


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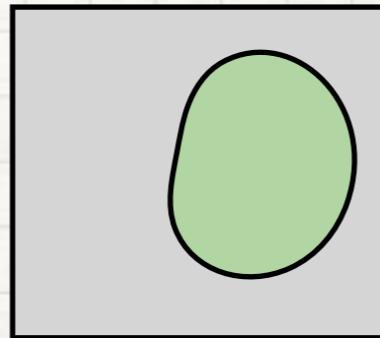


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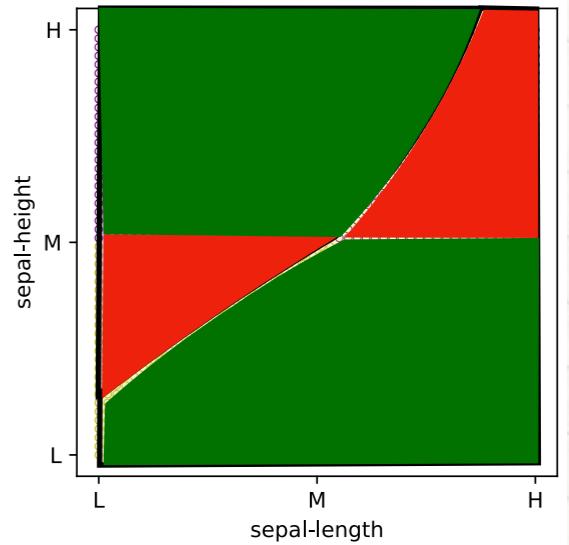
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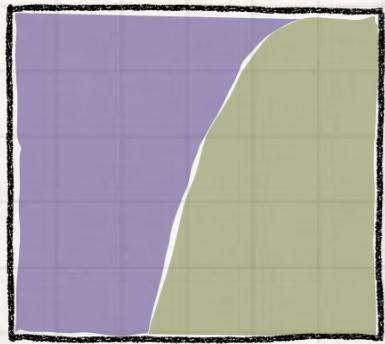


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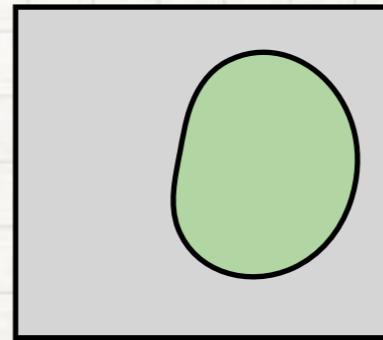


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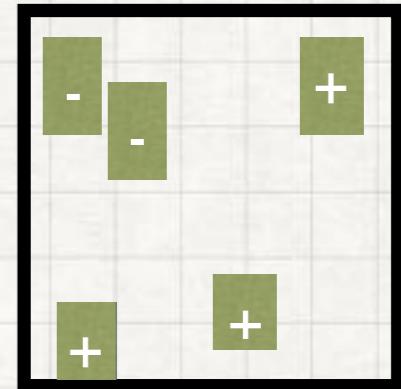
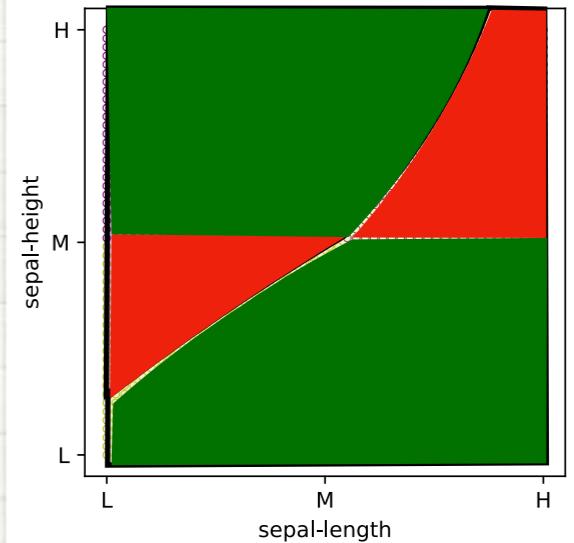
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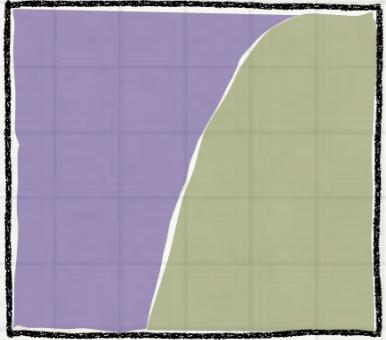
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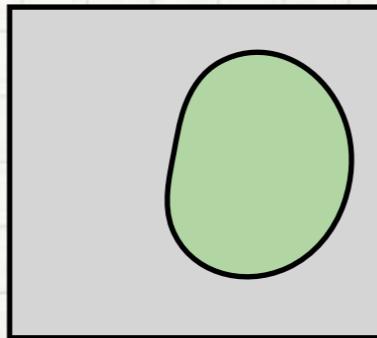
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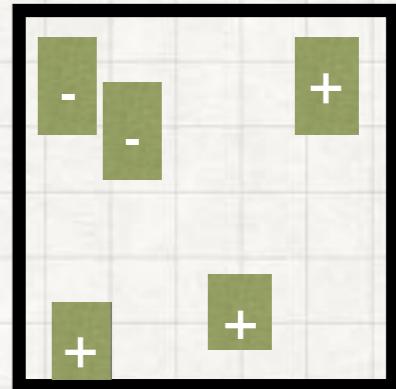
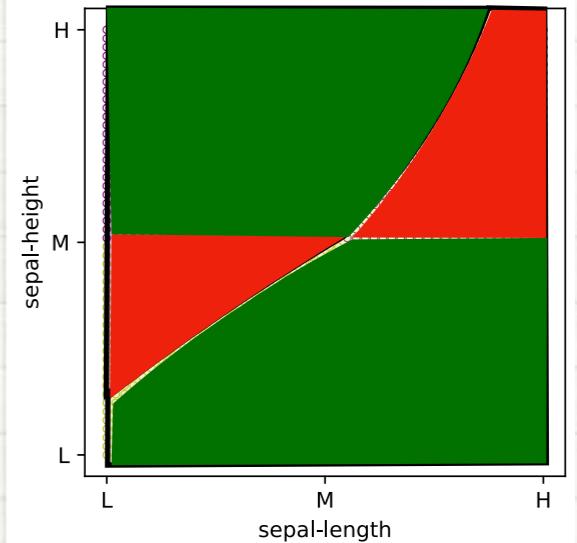


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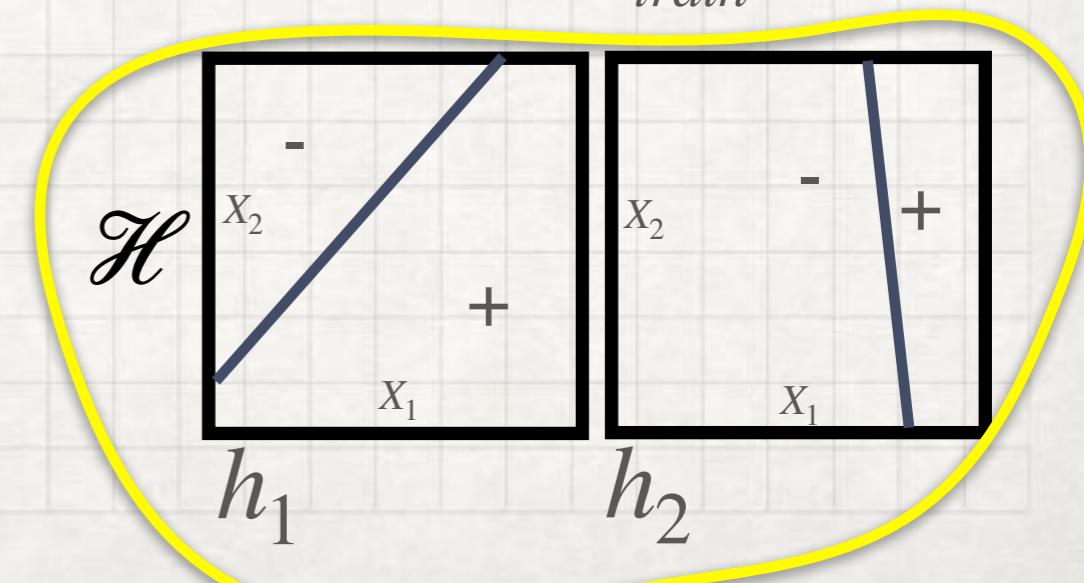
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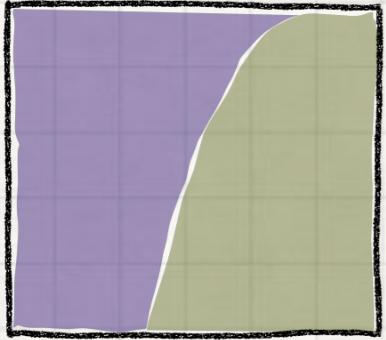


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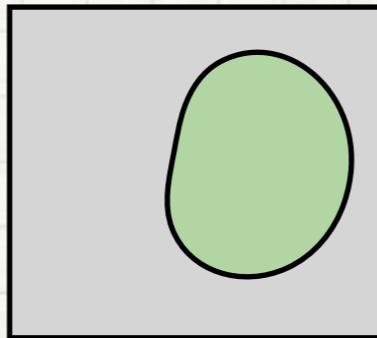
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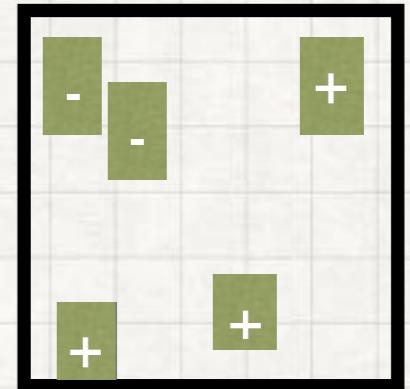
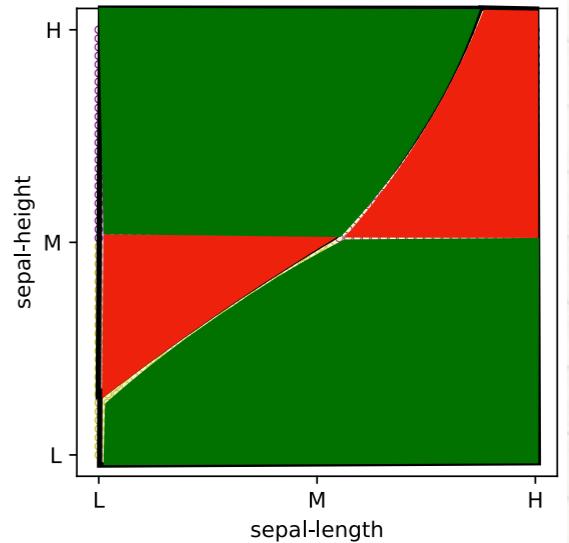


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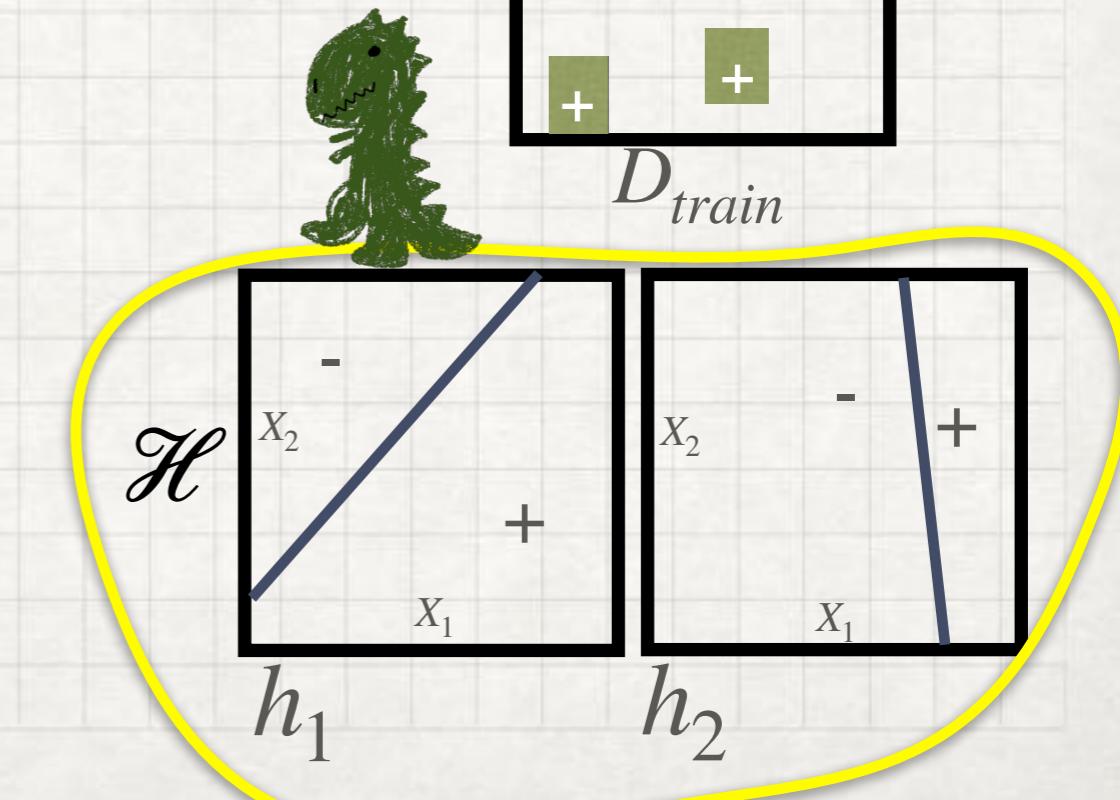
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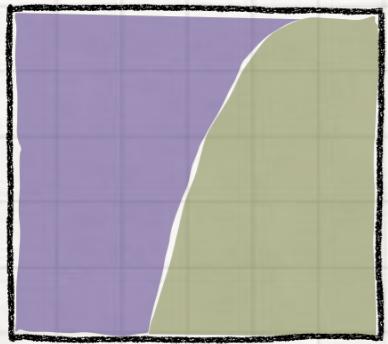


$D_{train}$



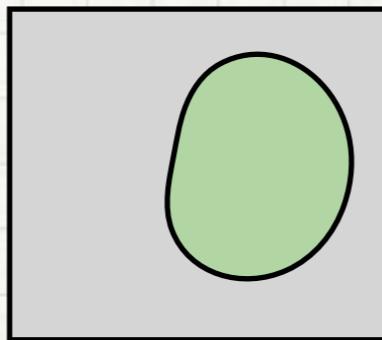
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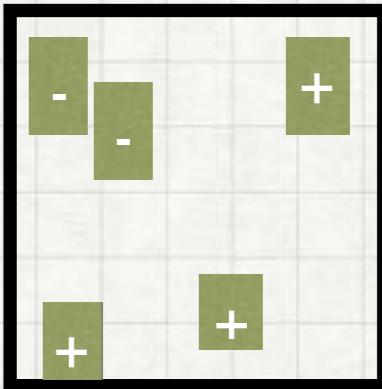
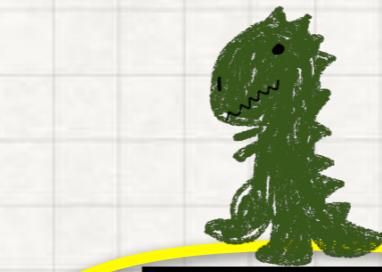
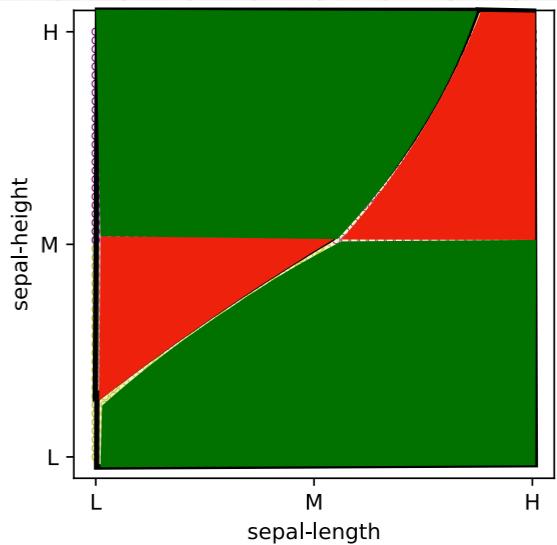


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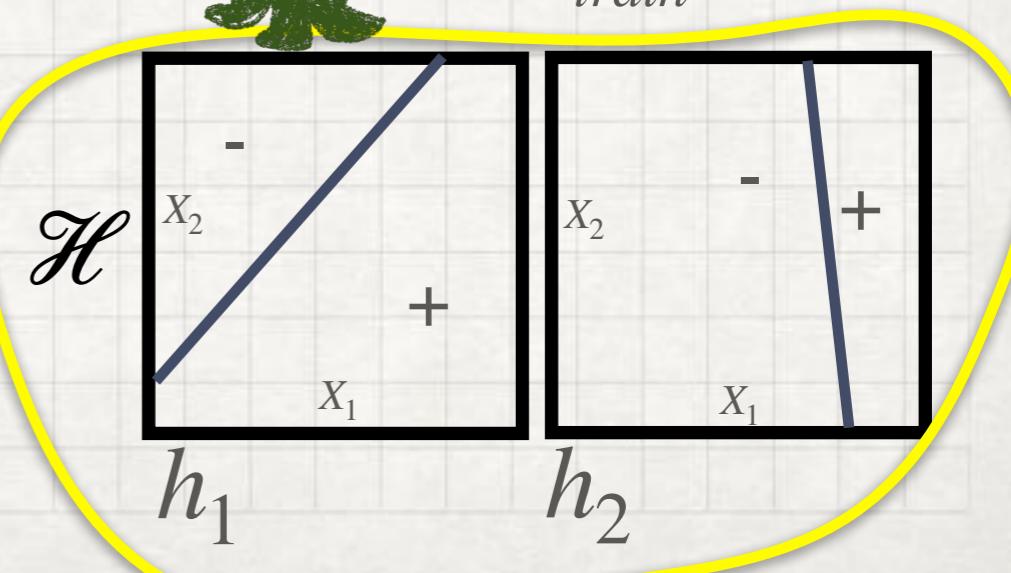
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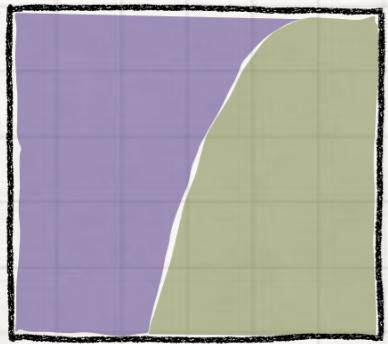


$D_{train}$



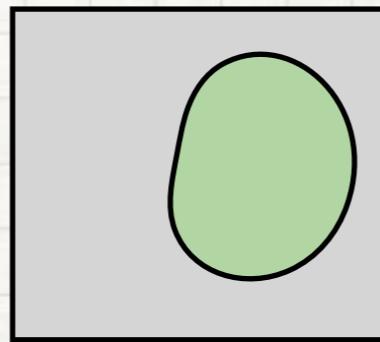
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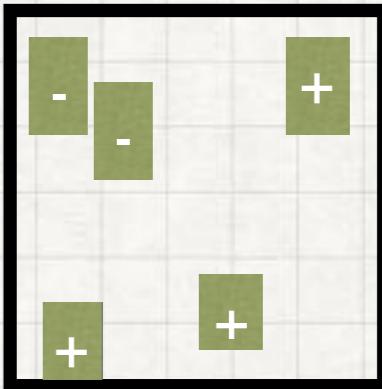
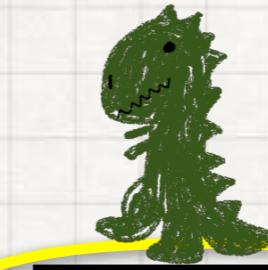
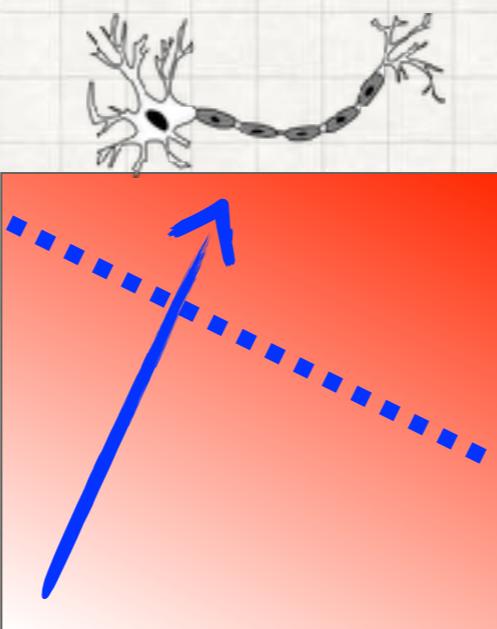
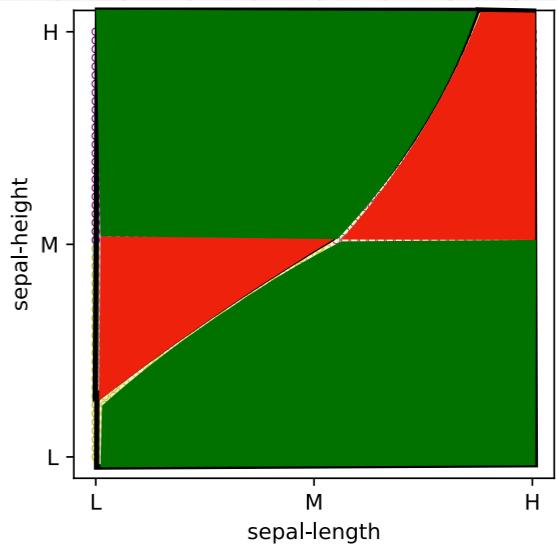


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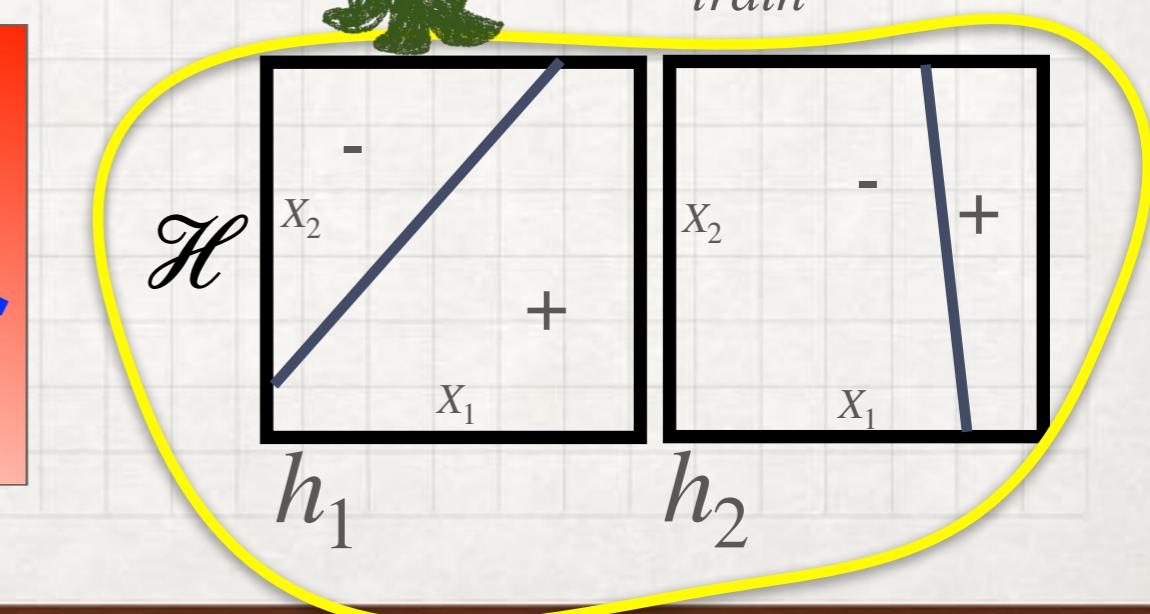
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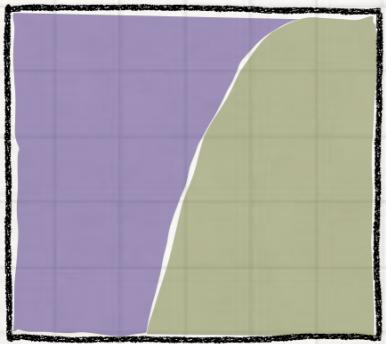


$D_{train}$

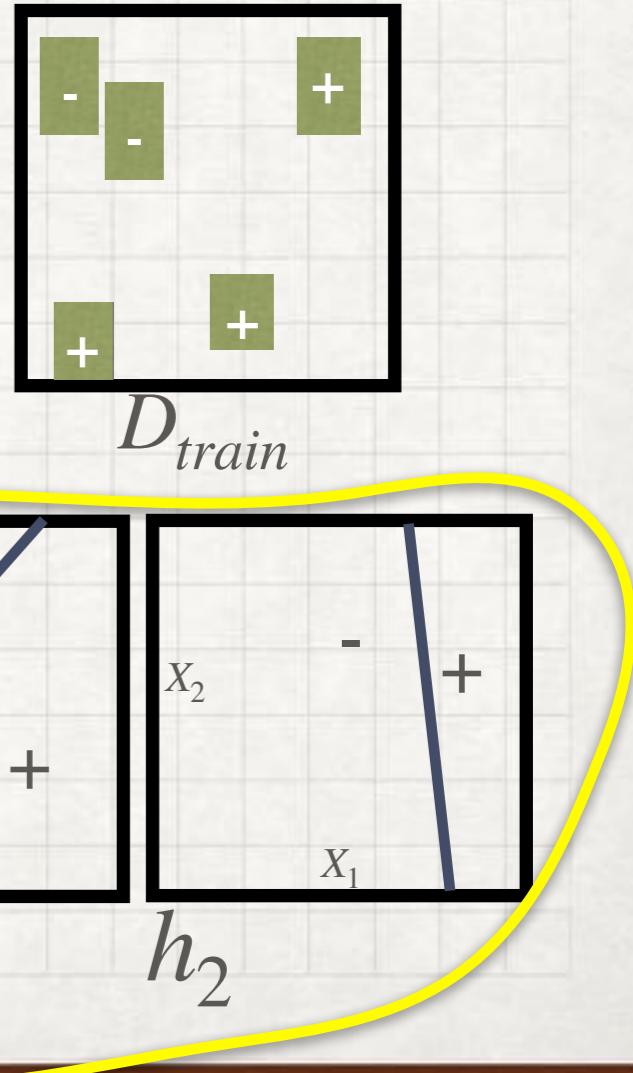
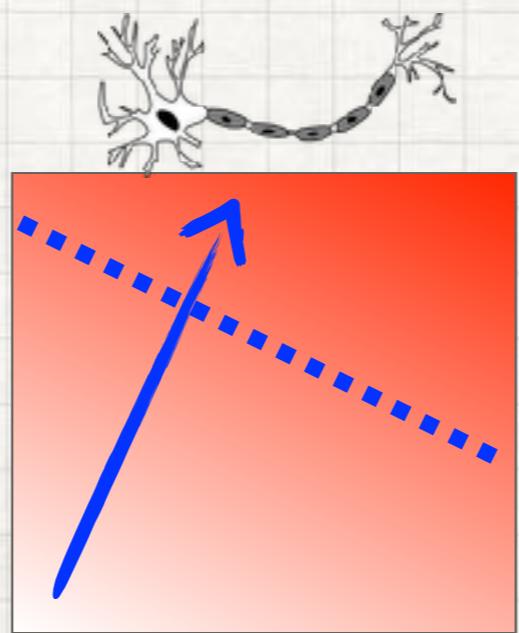
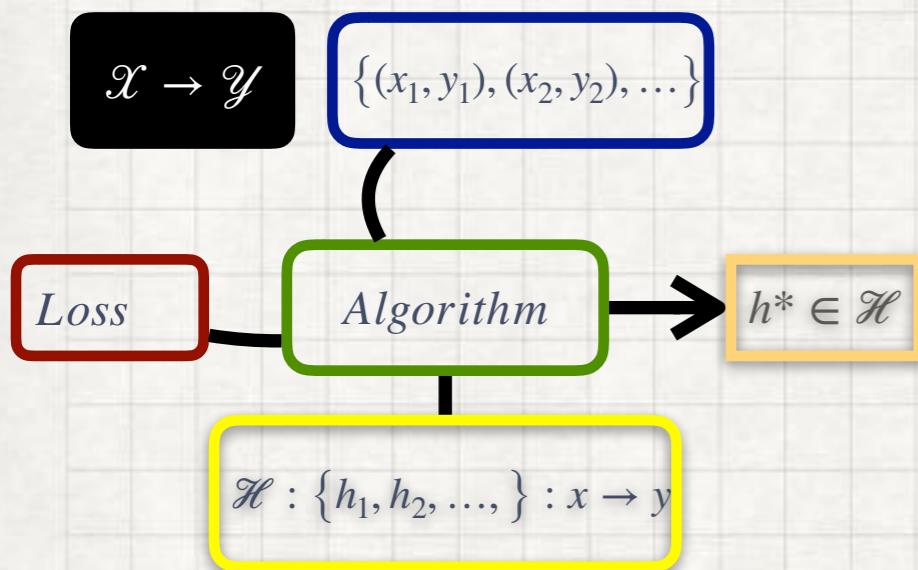
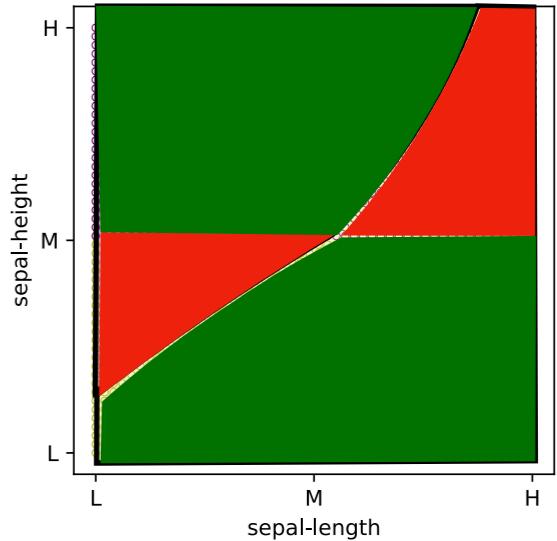
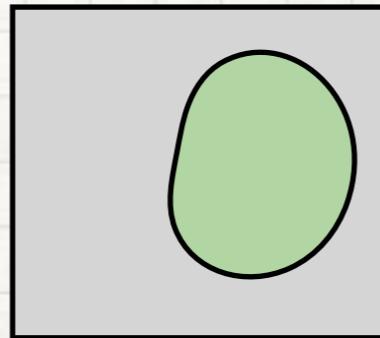


# REVIEW

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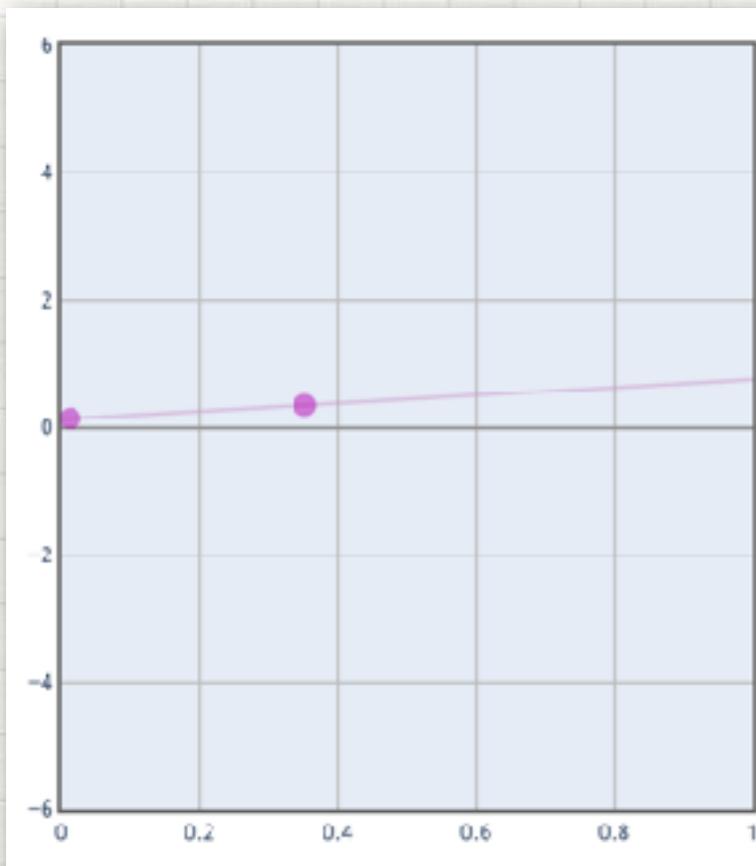


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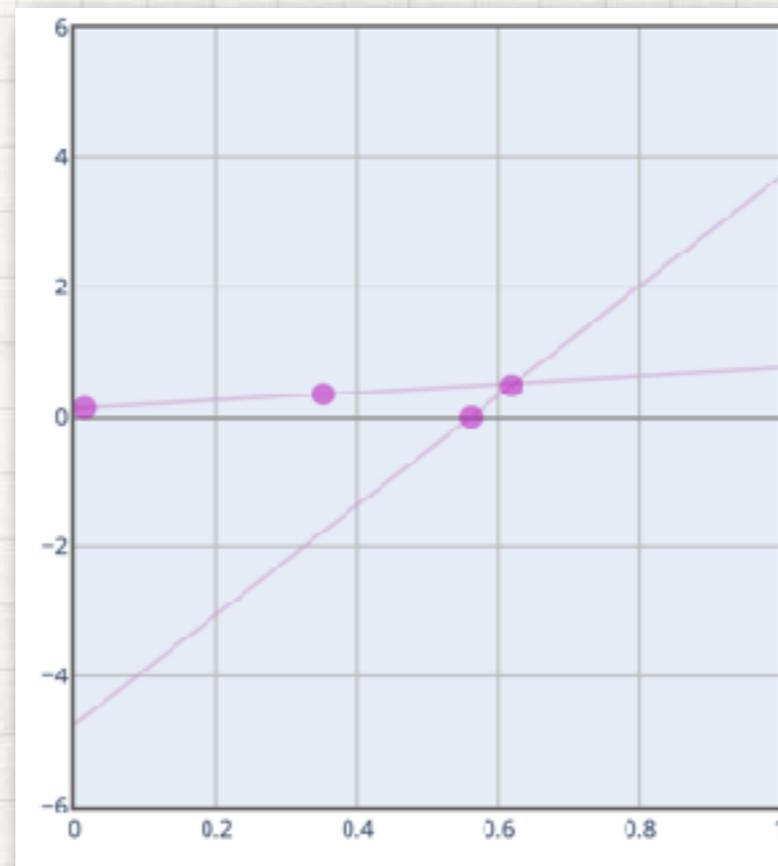
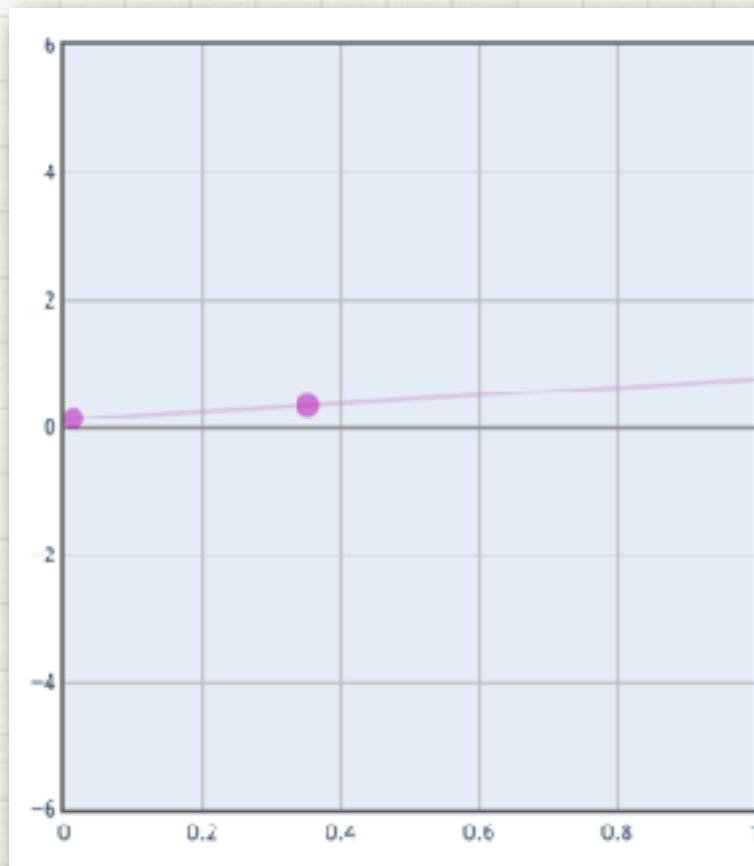


# UNCERTAINTY IN LEARNING

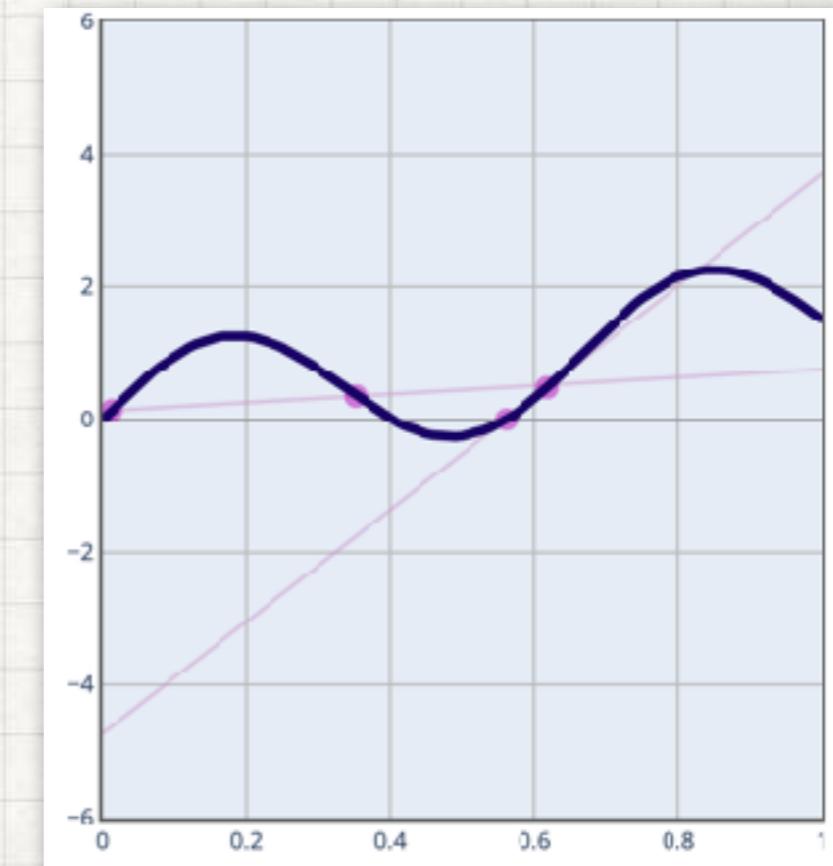
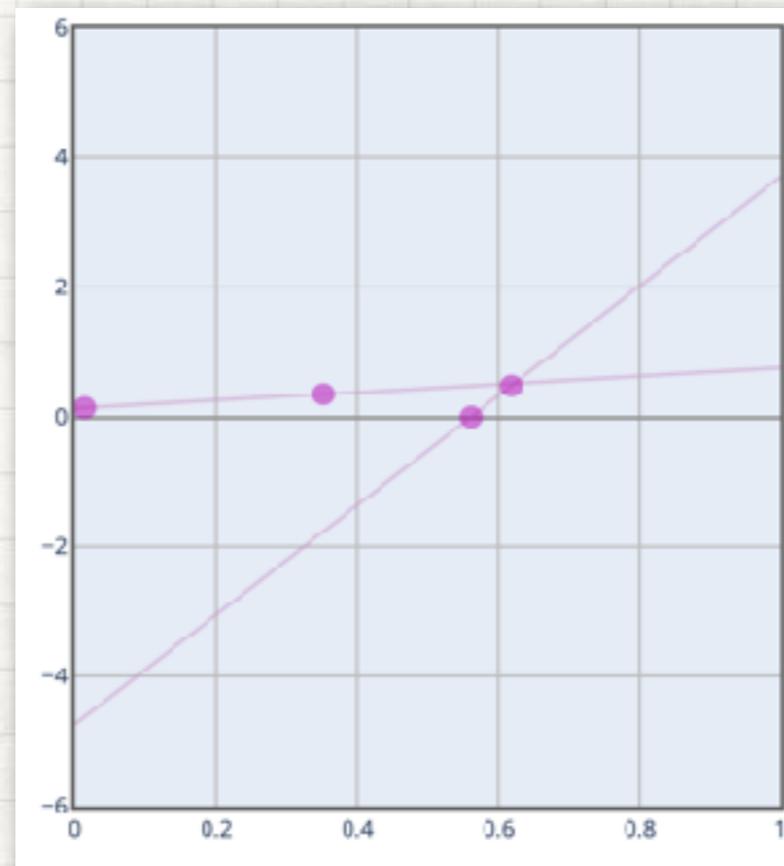
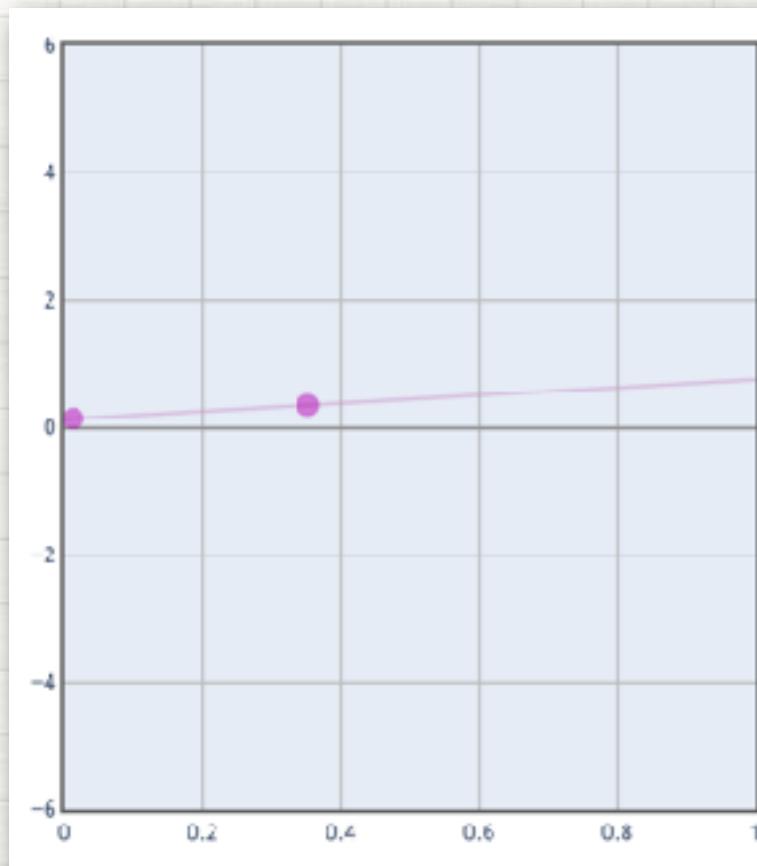
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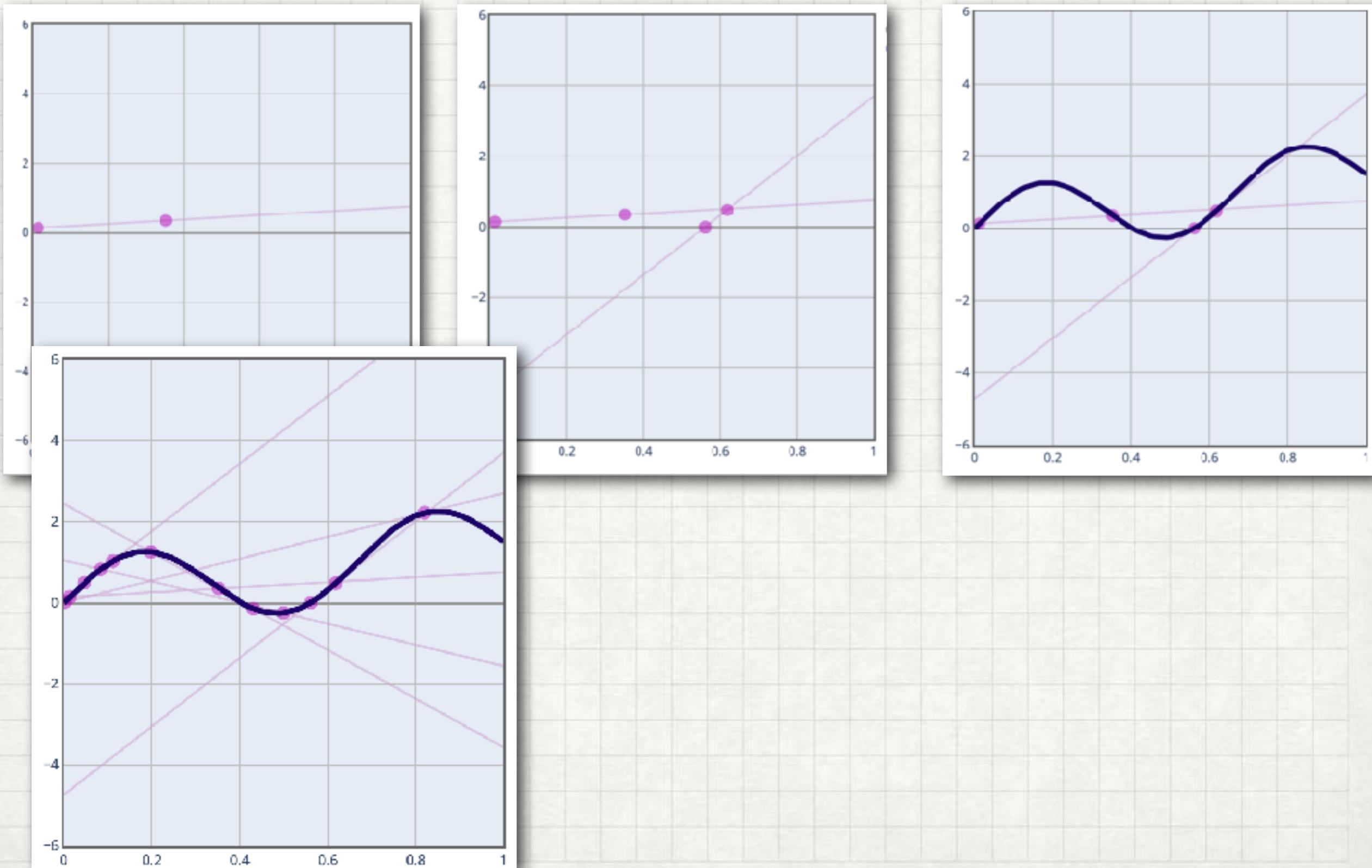
# UNCERTAINTY IN LEARNING



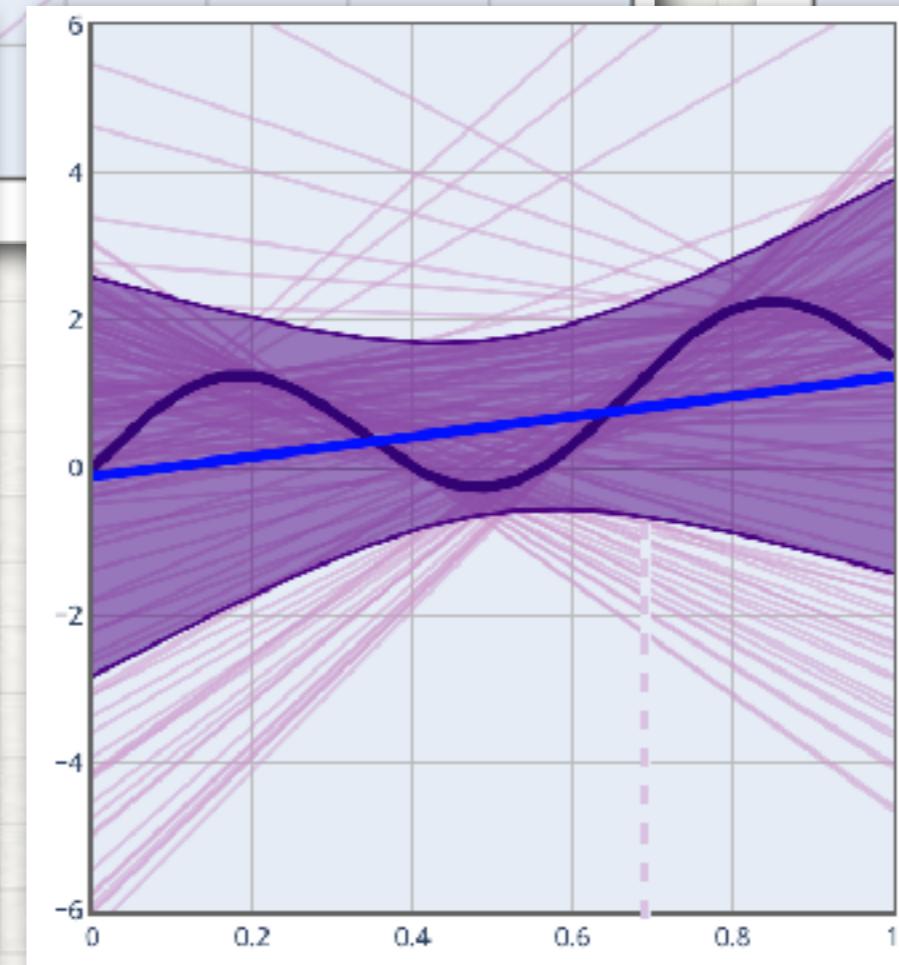
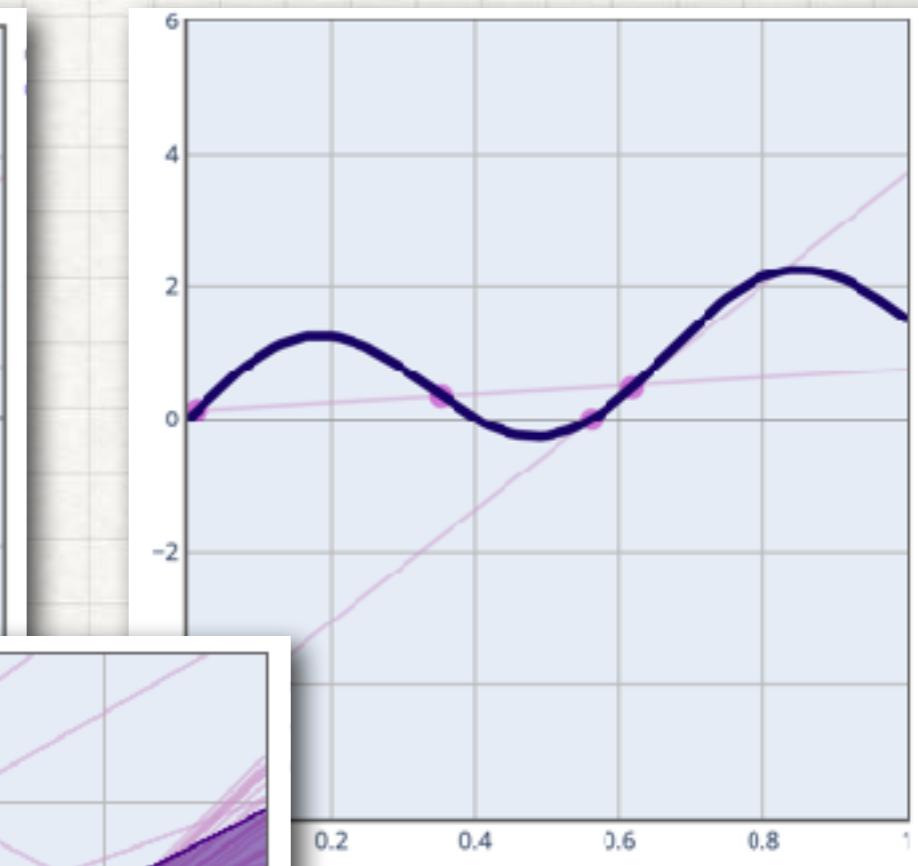
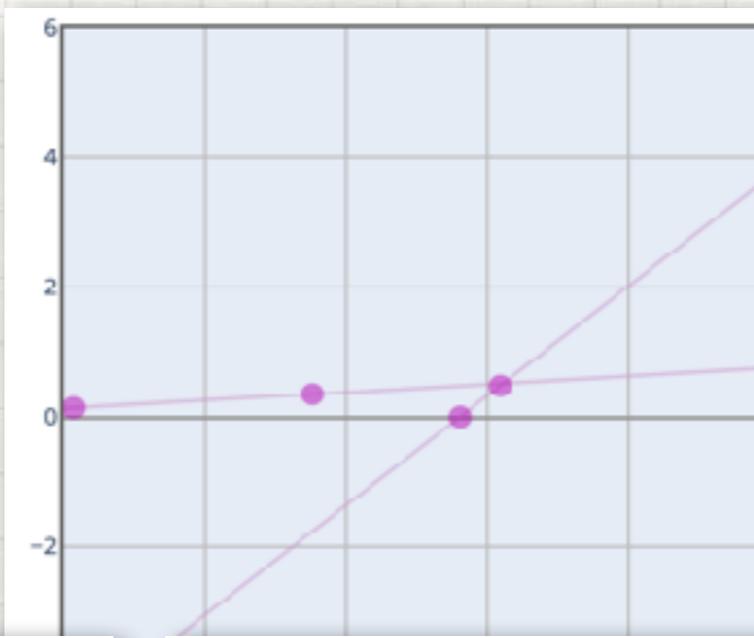
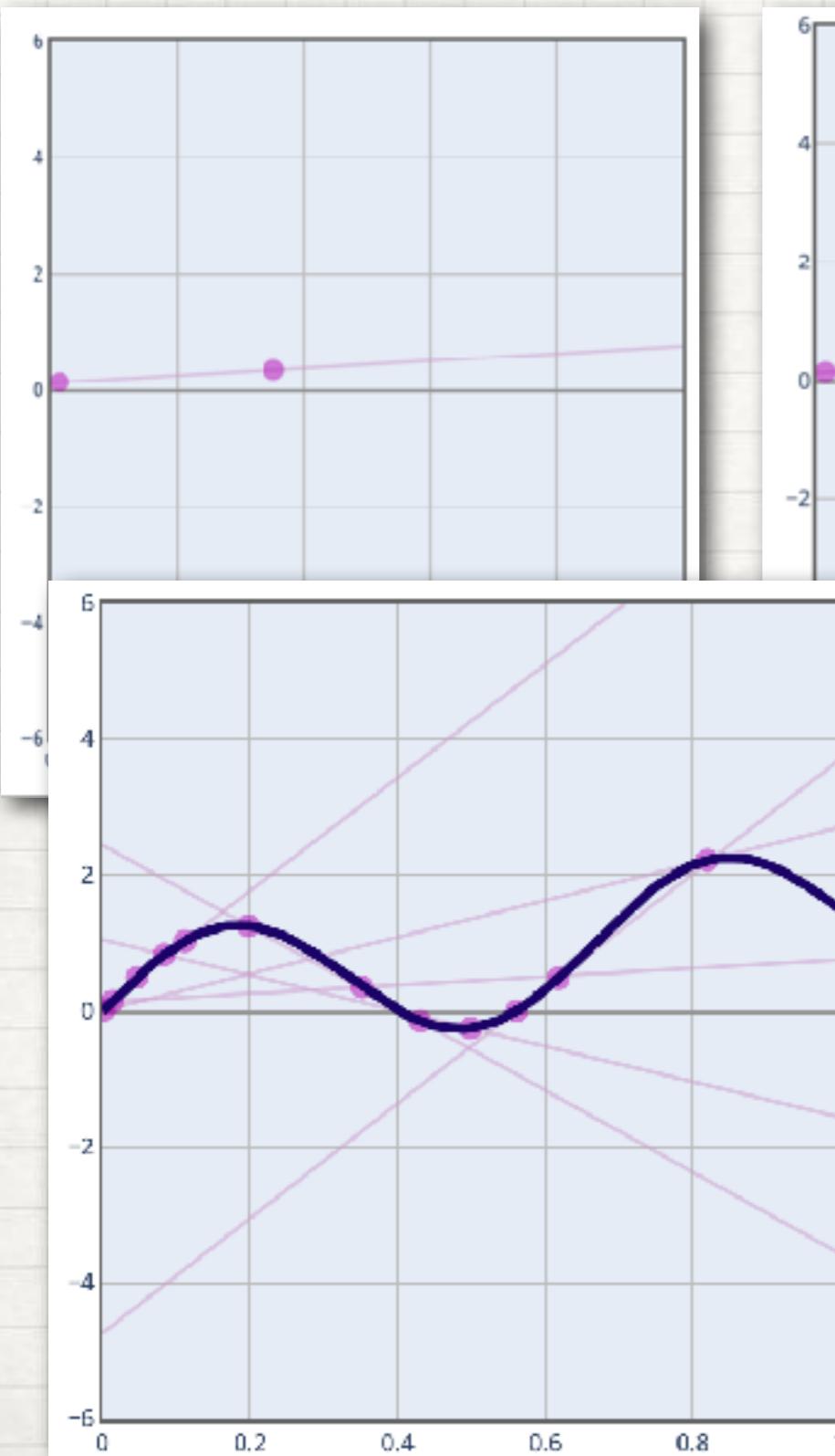
# UNCERTAINTY IN LEARNING



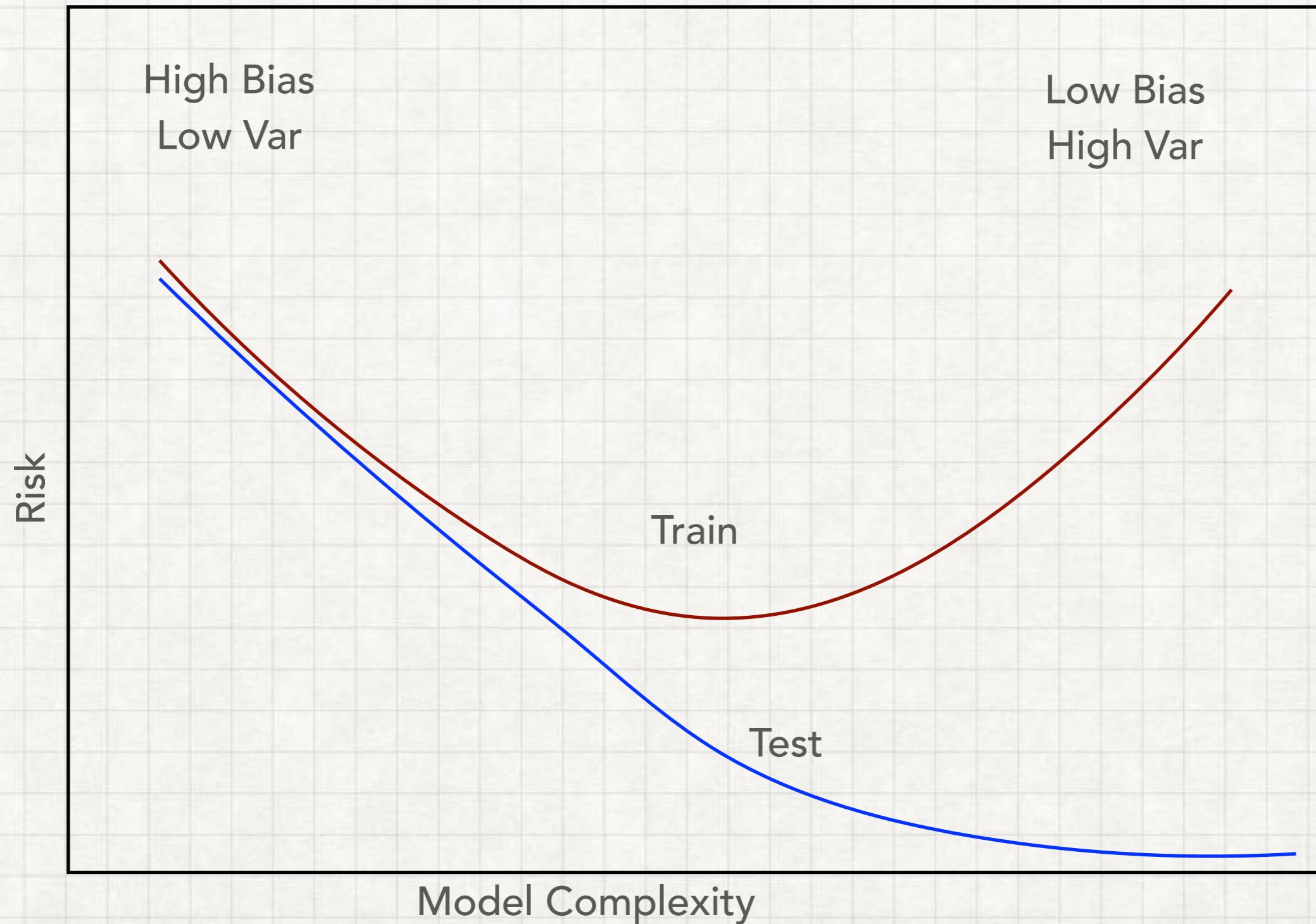
# UNCERTAINTY IN LEARNING



# UNCERTAINTY IN LEARNING



# BIAS VS VARIANCE

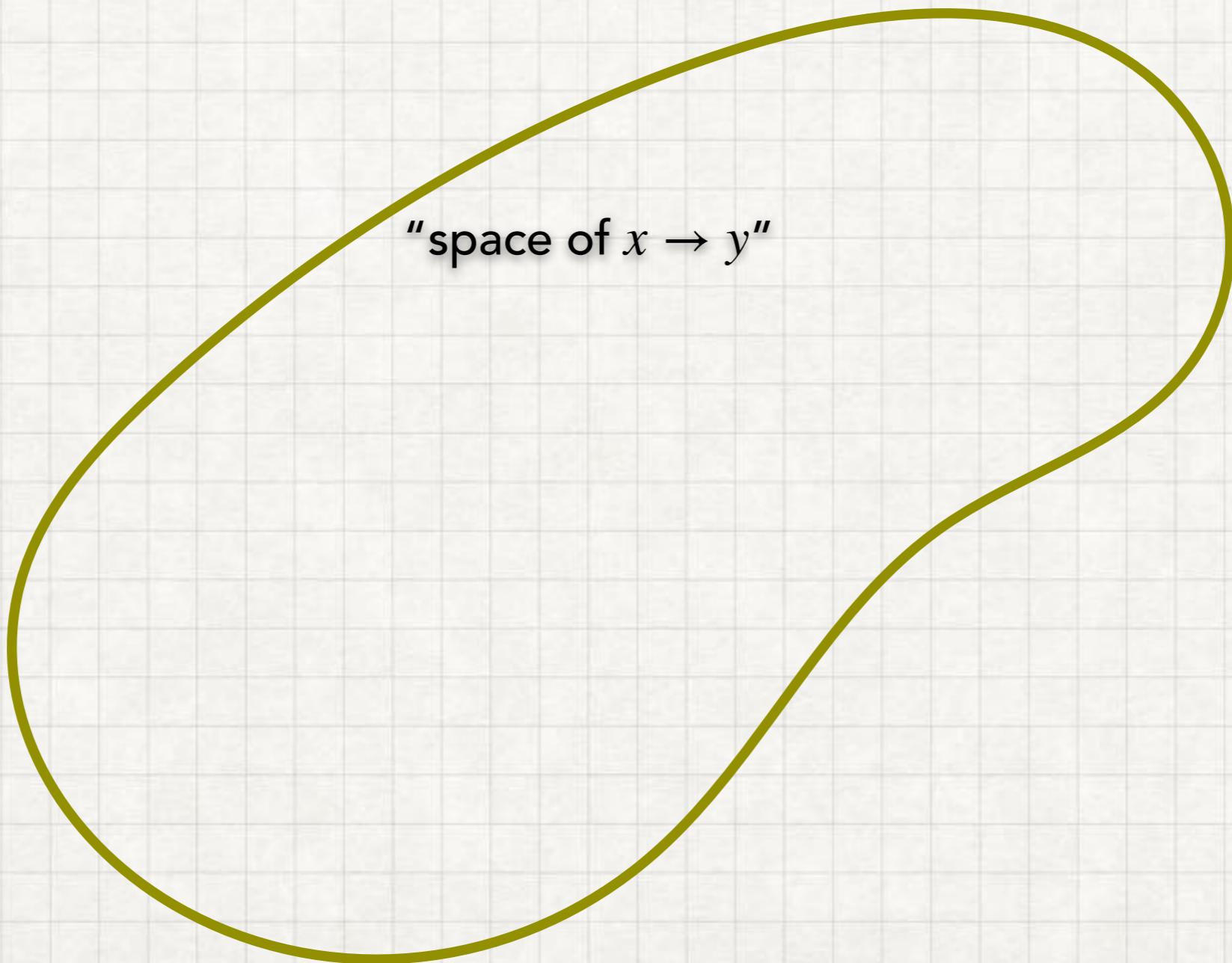


# MOD1: INTUITIVE INTERPRETATION OF *H* FAMILY AND RISK

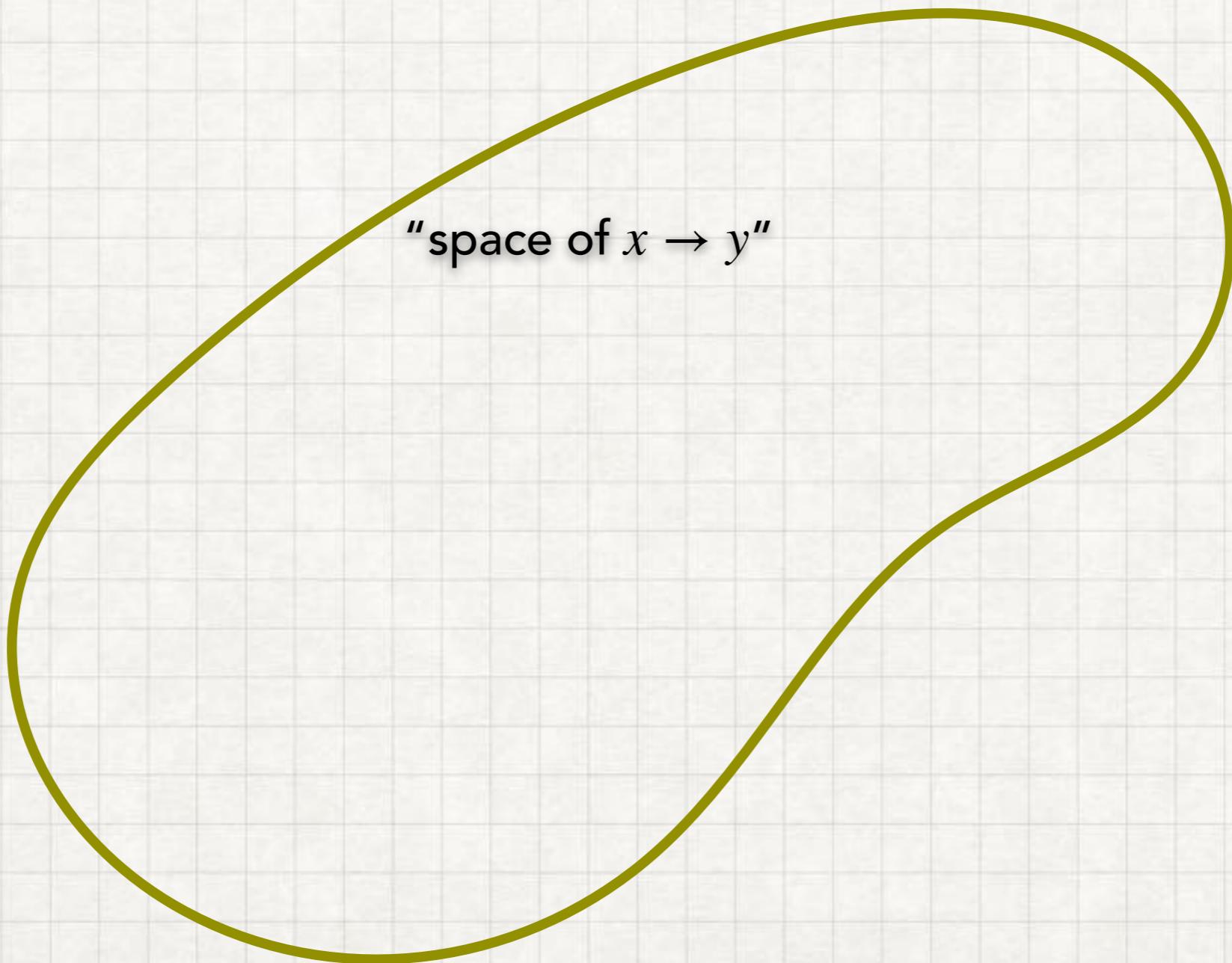
# ERROR/RISK IN FUNCTIONAL SPACE

"space of  $x \rightarrow y$ "

# ERROR/RISK IN FUNCTIONAL SPACE



# FUNCTIONAL SPACE?



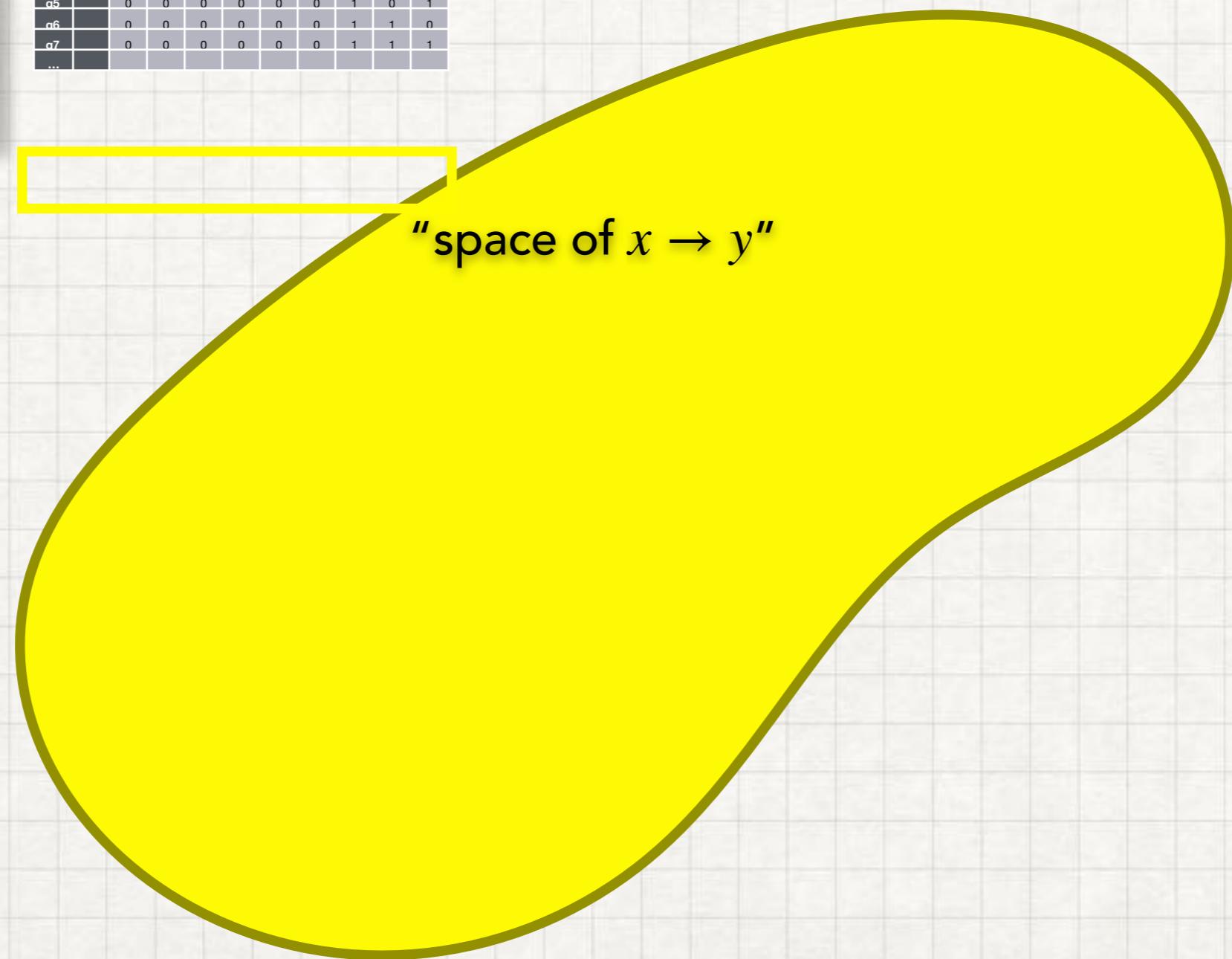
# FUNCTIONAL SPACE?

- $2^{2500} =$

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Y\X	X1	L	L	L	M	M	M	H	H	H
X2	L	M	H	L	M	H	L	M	H	
a0	0	0	0	0	0	0	0	0	0	0
a1	0	0	0	0	0	0	0	0	0	1
a2	0	0	0	0	0	0	0	1	0	0
a3	0	0	0	0	0	0	0	1	1	0
a4	0	0	0	0	0	0	1	0	0	0
a5	0	0	0	0	0	0	1	0	1	0
a6	0	0	0	0	0	0	1	1	0	0
a7	0	0	0	0	0	0	1	1	1	0
...										

"space of  $x \rightarrow y$ "

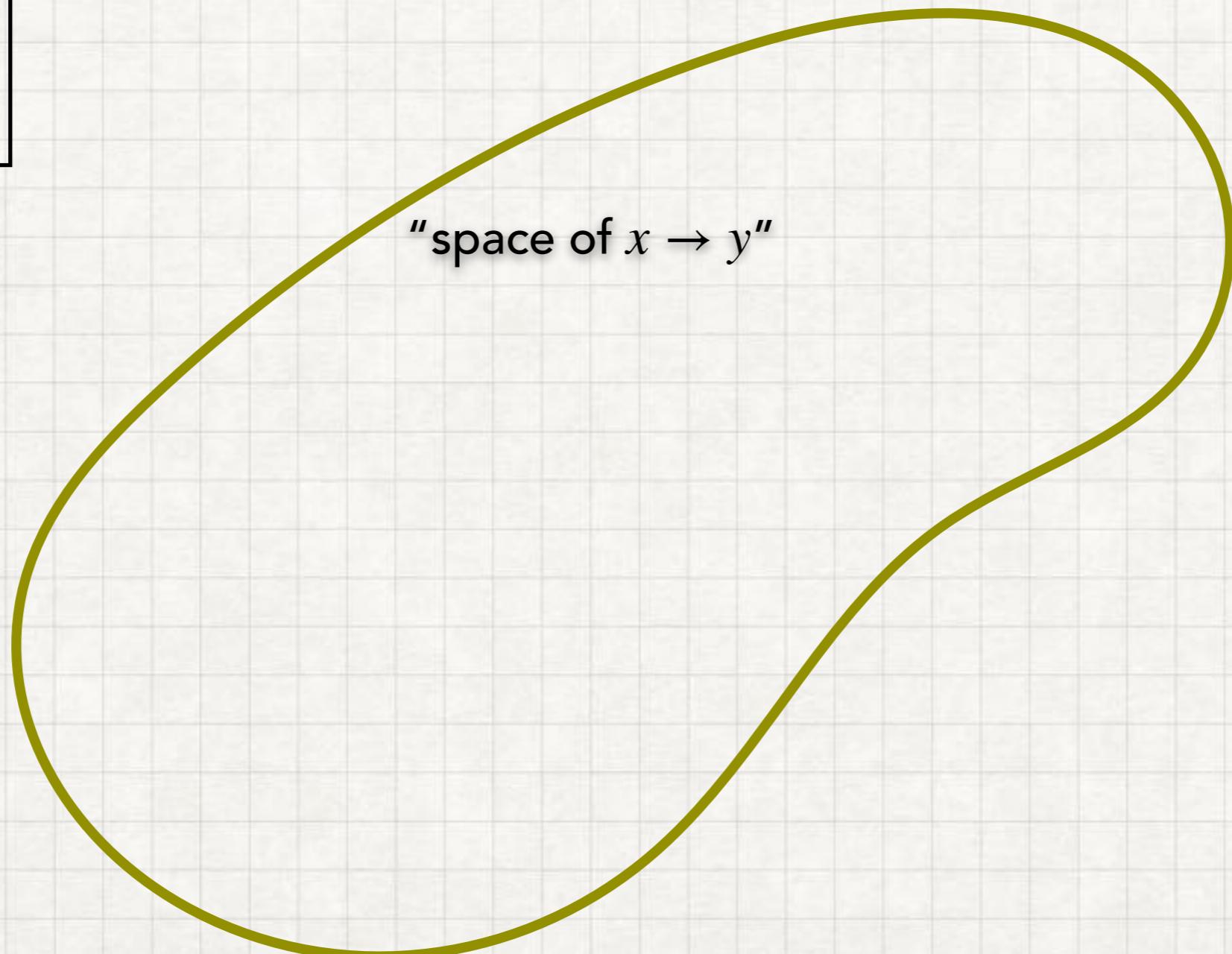


# FUNCTIONAL SPACE ...

$x, y$

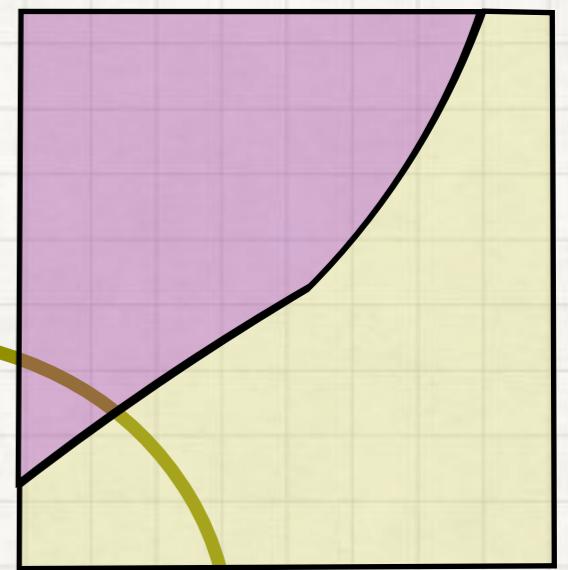
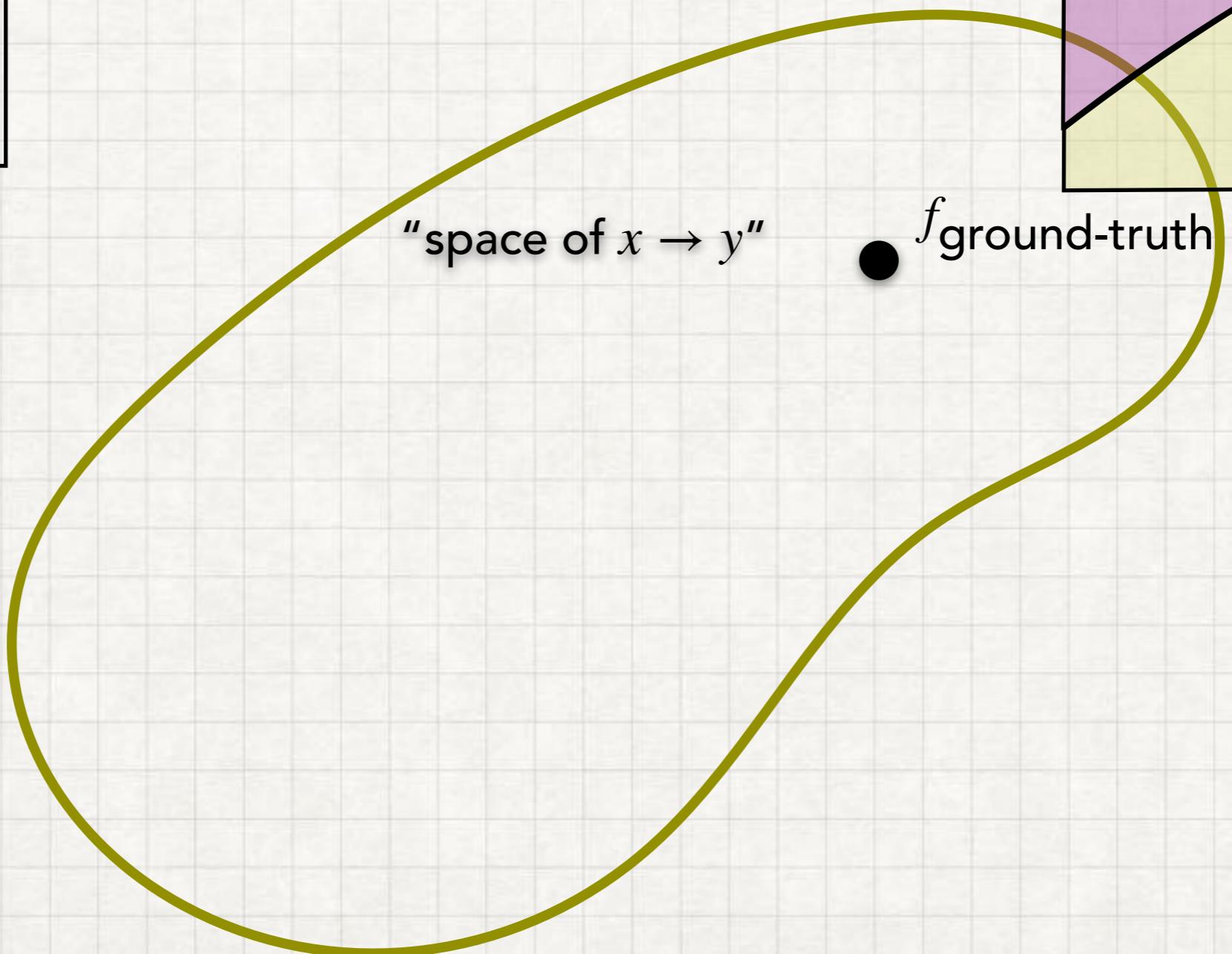
setosa /  
versicolor ?

"space of  $x \rightarrow y$ "

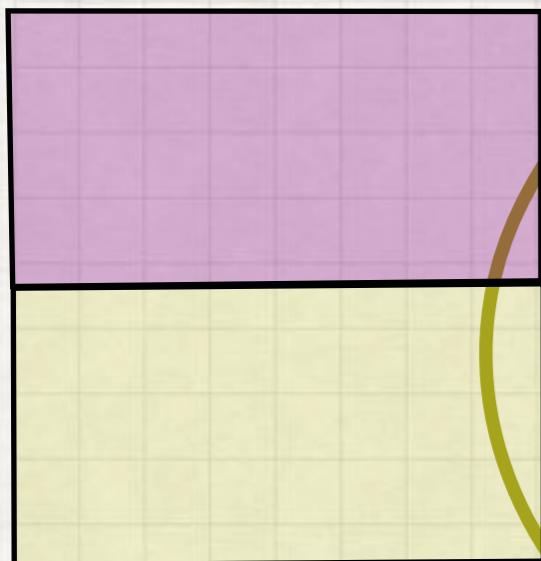
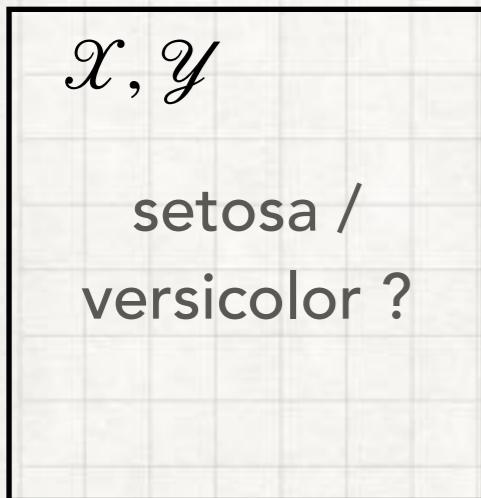


# FUNCTIONAL SPACE ...

$x, y$   
setosa /  
versicolor ?



# FUNCTIONAL SPACE ...

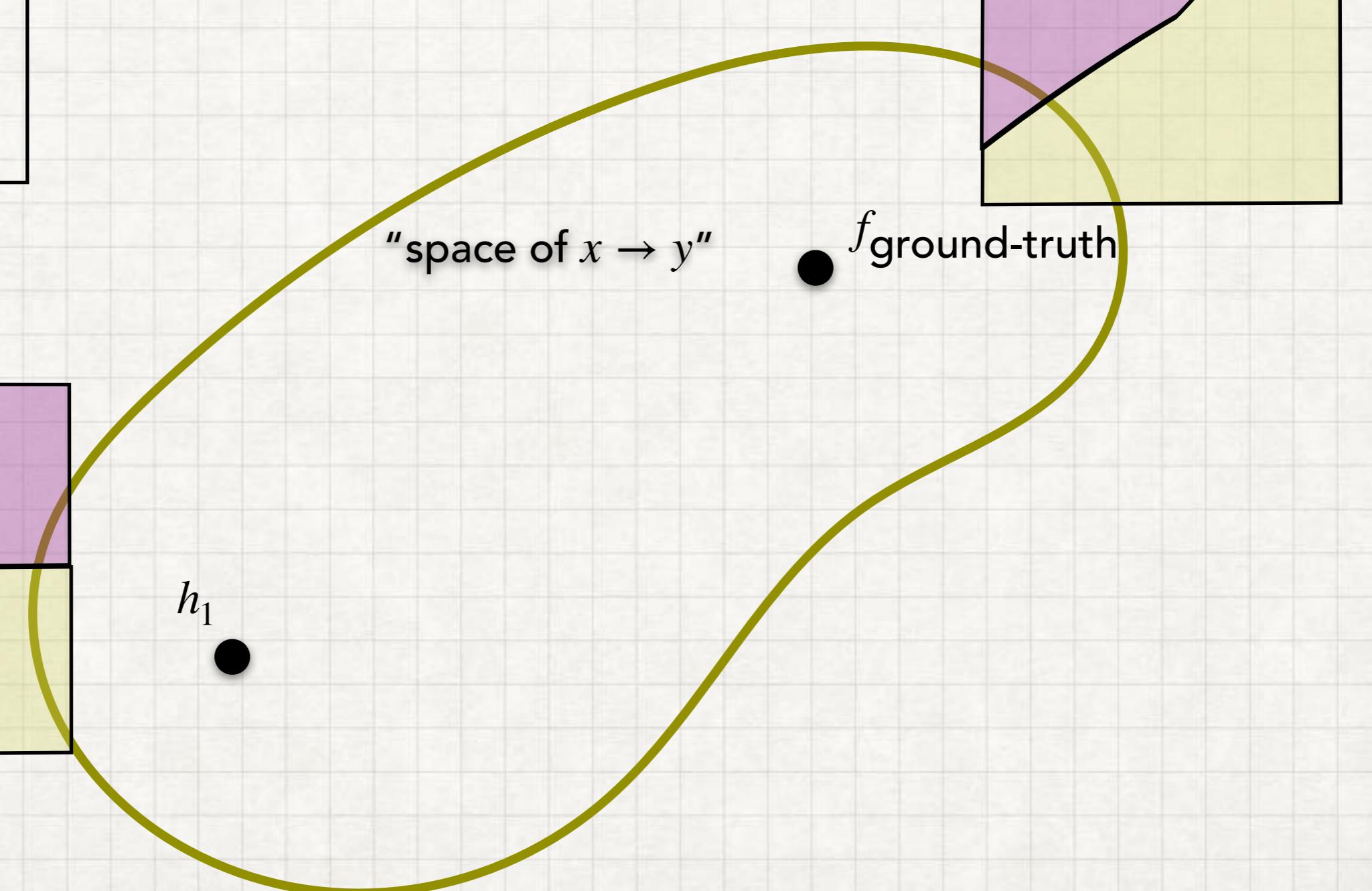
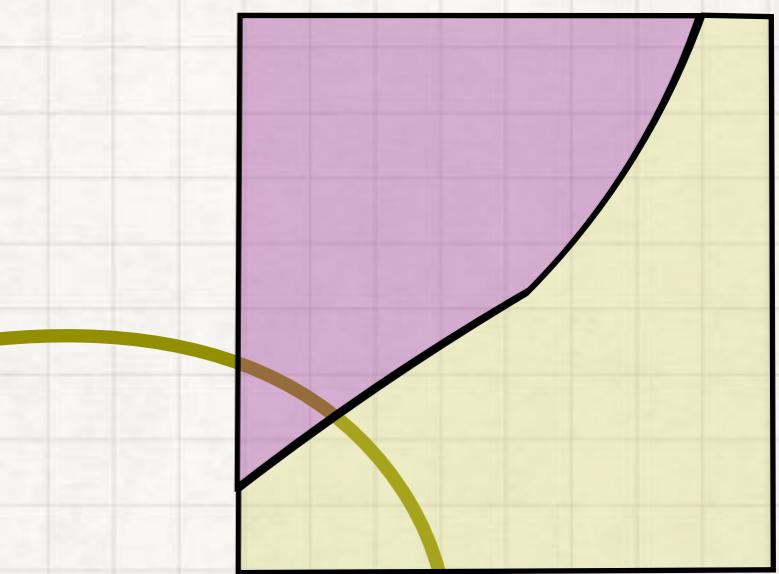


$h_1$

"space of  $x \rightarrow y$ "

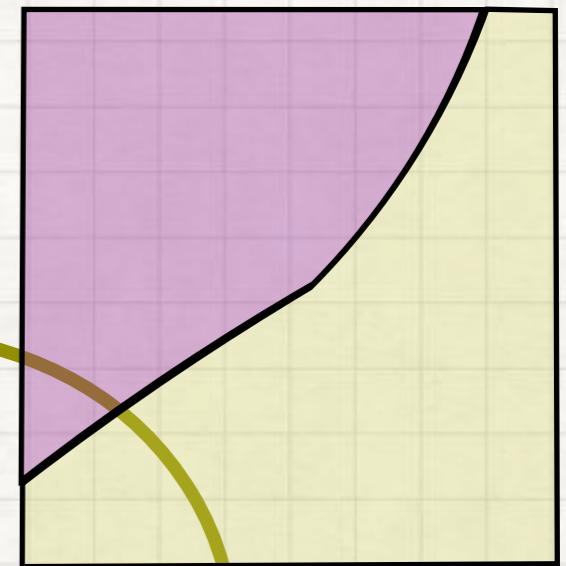
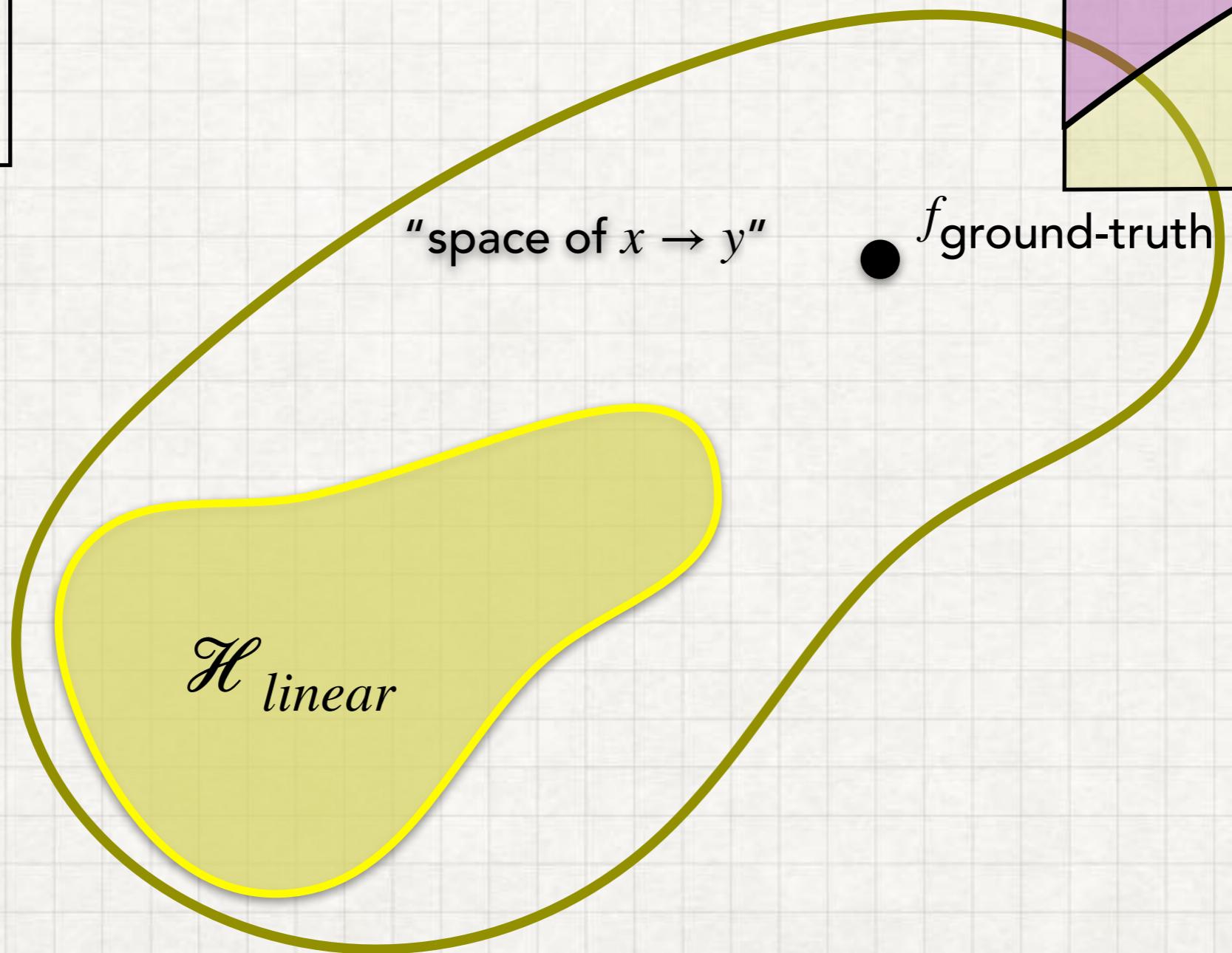


$f_{\text{ground-truth}}$



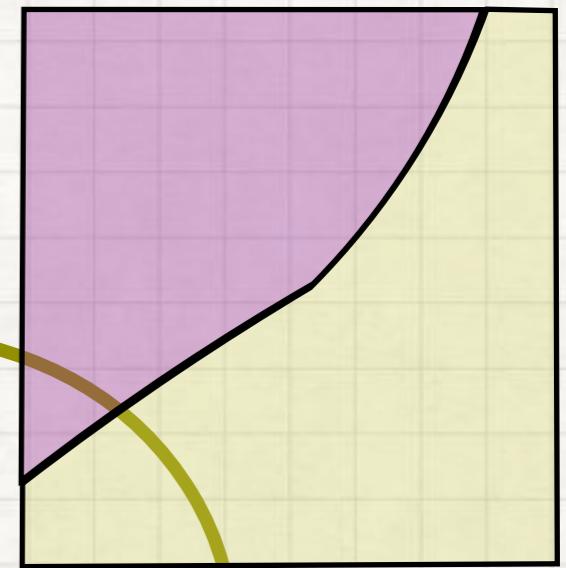
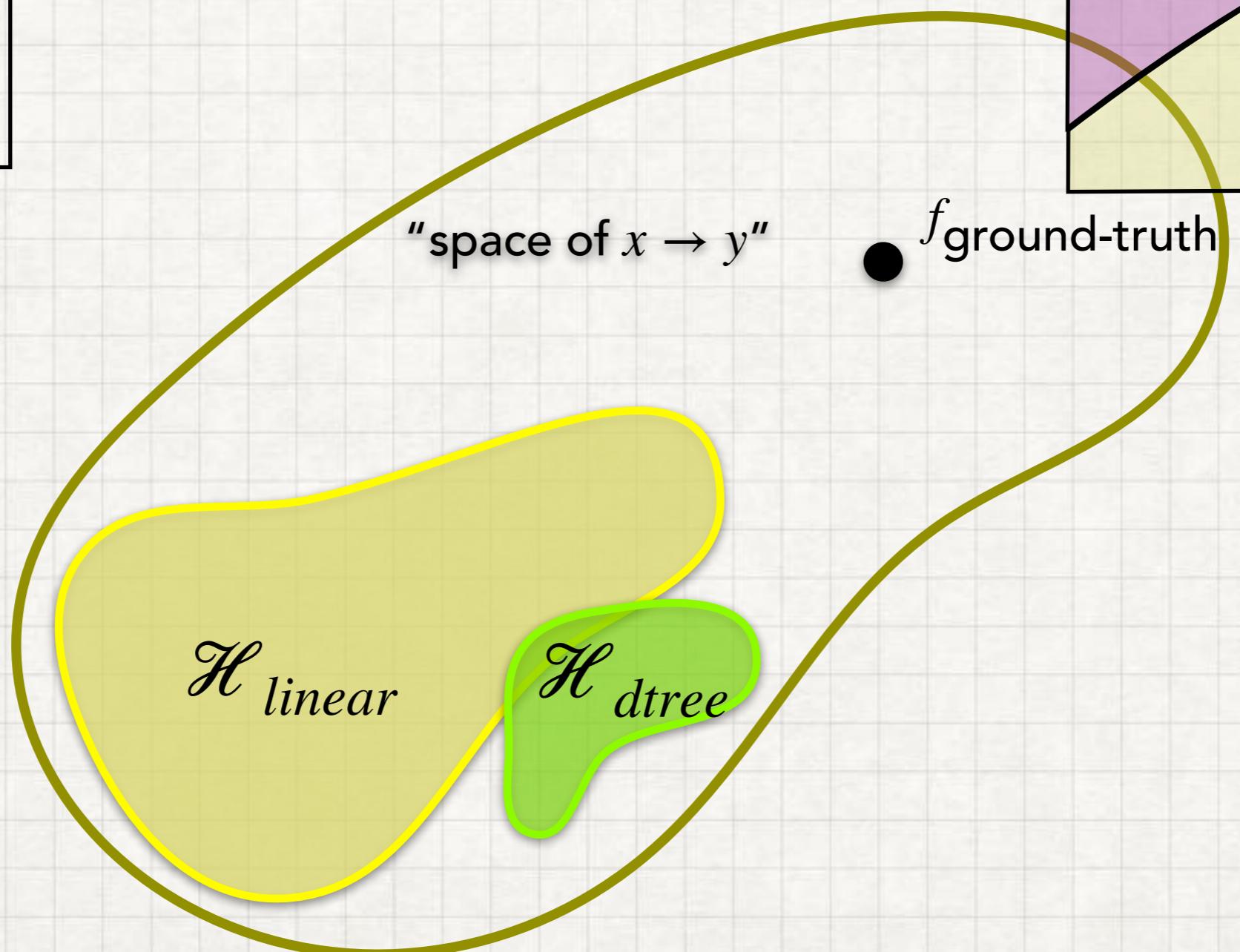
# FUNCTIONAL SPACE.

$x, y$   
setosa /  
versicolor ?



# FUNCTIONAL SPACE.

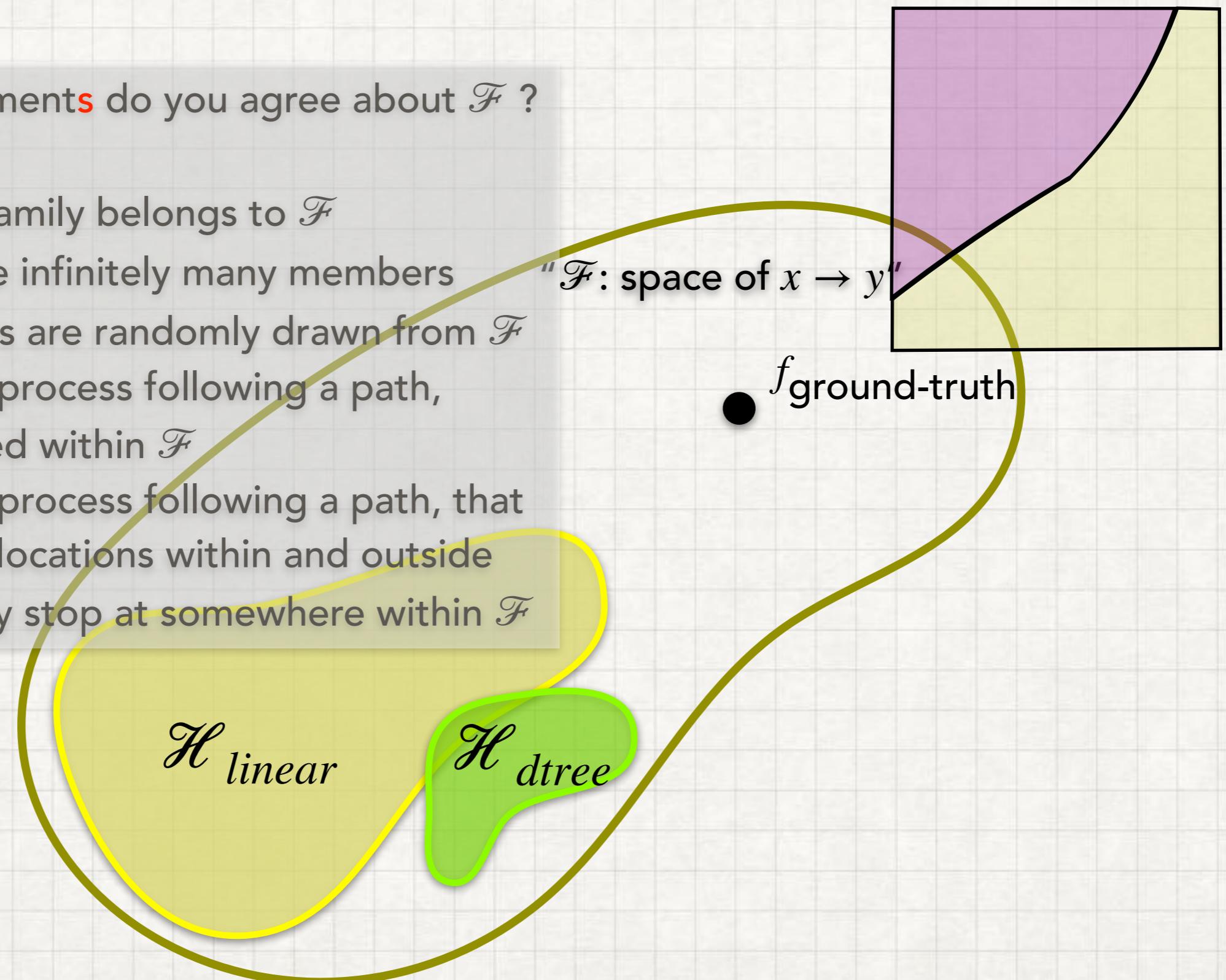
$x, y$   
setosa /  
versicolor ?



# FUNCTIONAL SPACE.

Q: Which statements **s** do you agree about  $\mathcal{F}$  ?

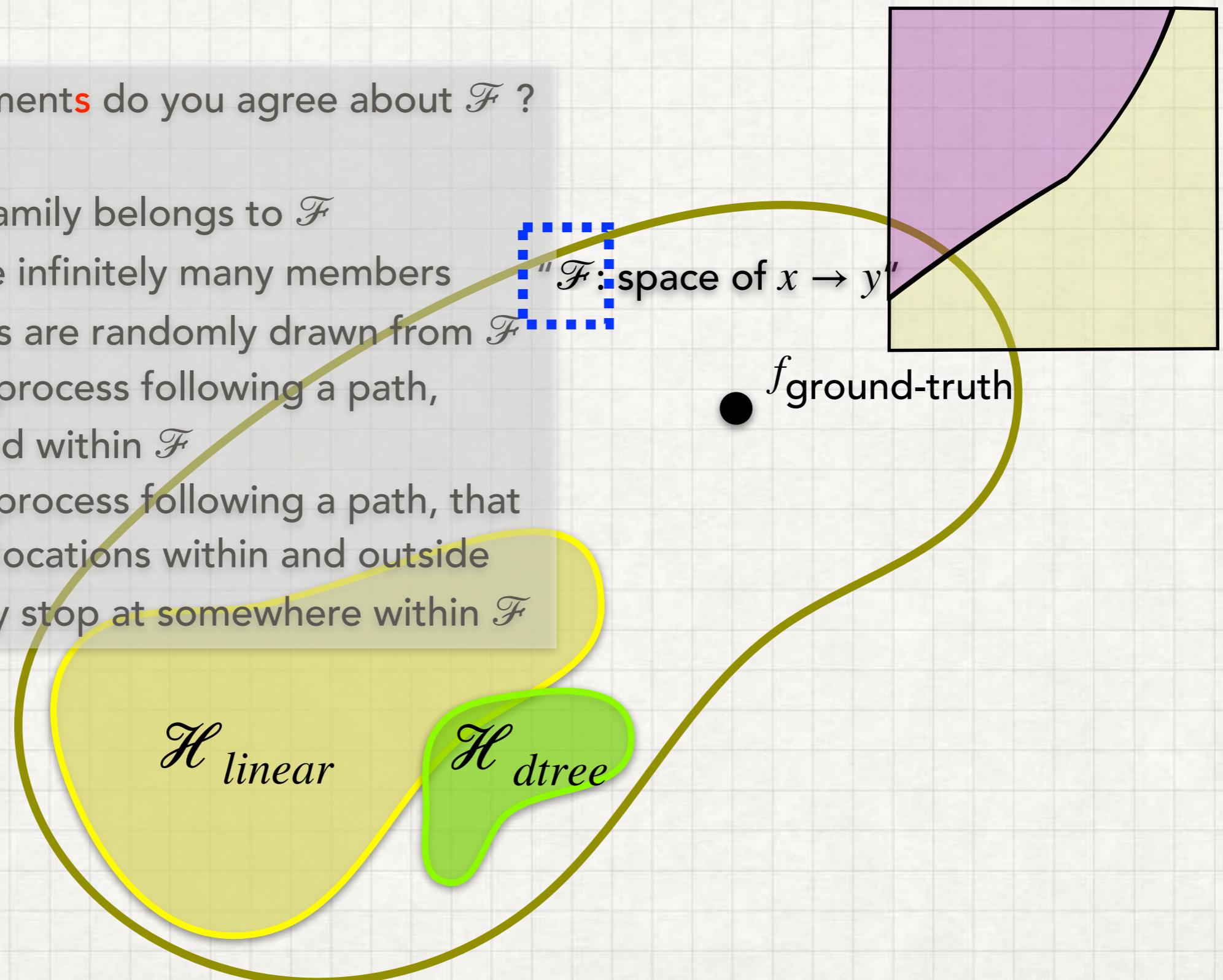
- A. Any model family belongs to  $\mathcal{F}$
- B.  $\mathcal{F}$  must have infinitely many members
- C. Data samples are randomly drawn from  $\mathcal{F}$
- D. Training is a process following a path, strictly limited within  $\mathcal{F}$
- E. Training is a process following a path, that may lead to locations within and outside  $\mathcal{F}$ , but finally stop at somewhere within  $\mathcal{F}$



# FUNCTIONAL SPACE.

Q: Which statements **F** do you agree about  $\mathcal{F}$  ?

- A. Any model family belongs to  $\mathcal{F}$
- B.  $\mathcal{F}$  must have infinitely many members
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# FUNCTIONAL SPACE.

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- A Any model family belongs to  $\mathcal{F}$
- B.  $\mathcal{F}$  must have infinitely many members
- C. Data samples are randomly drawn from  $\mathcal{F}$
- D. Training is a process following a path,  
strictly limited within  $\mathcal{F}$
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may lead to locations within and outside  
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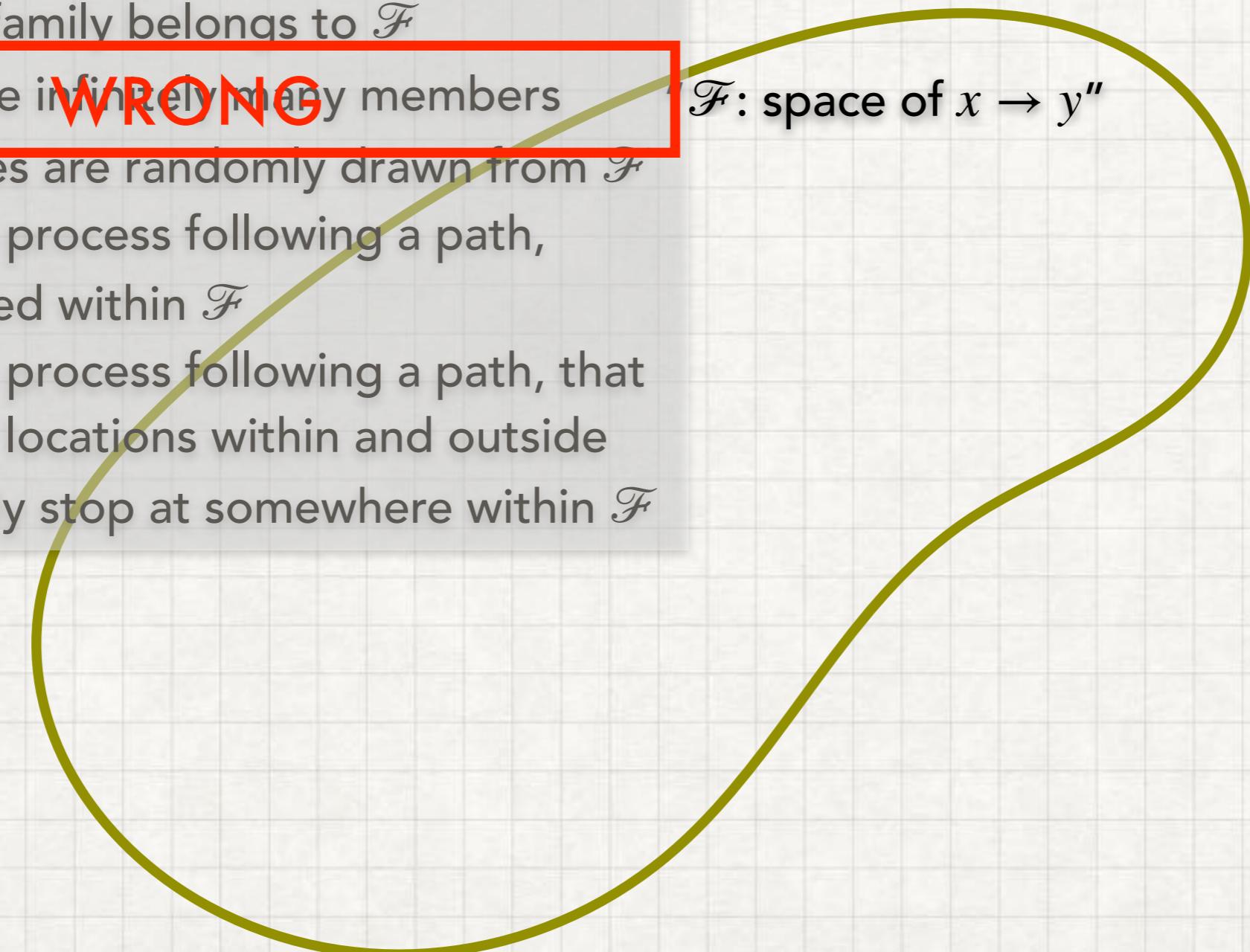
" $\mathcal{F}$ : space of  $x \rightarrow y$ "

# FUNCTIONAL SPACE.

Q: Which statements do you agree about  $\mathcal{F}$  ?

- A. Any model family belongs to  $\mathcal{F}$
- B.  $\mathcal{F}$  must have infinitely many members **WRONG**
- C. Data samples are randomly drawn from  $\mathcal{F}$
- D. Training is a process following a path, strictly limited within  $\mathcal{F}$
- E. Training is a process following a path, that may lead to locations within and outside  $\mathcal{F}$ , but finally stop at somewhere within  $\mathcal{F}$

$\mathcal{F}$ : space of  $x \rightarrow y''$



# FUNCTIONAL SPACE.

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strictly limited within  $\mathcal{F}$
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may lead to locations within and outside  
 $\mathcal{F}$ , but finally stop at somewhere within  $\mathcal{F}$

$\mathcal{F}$ : space of  $x \rightarrow y''$

- $2^{2500} =$

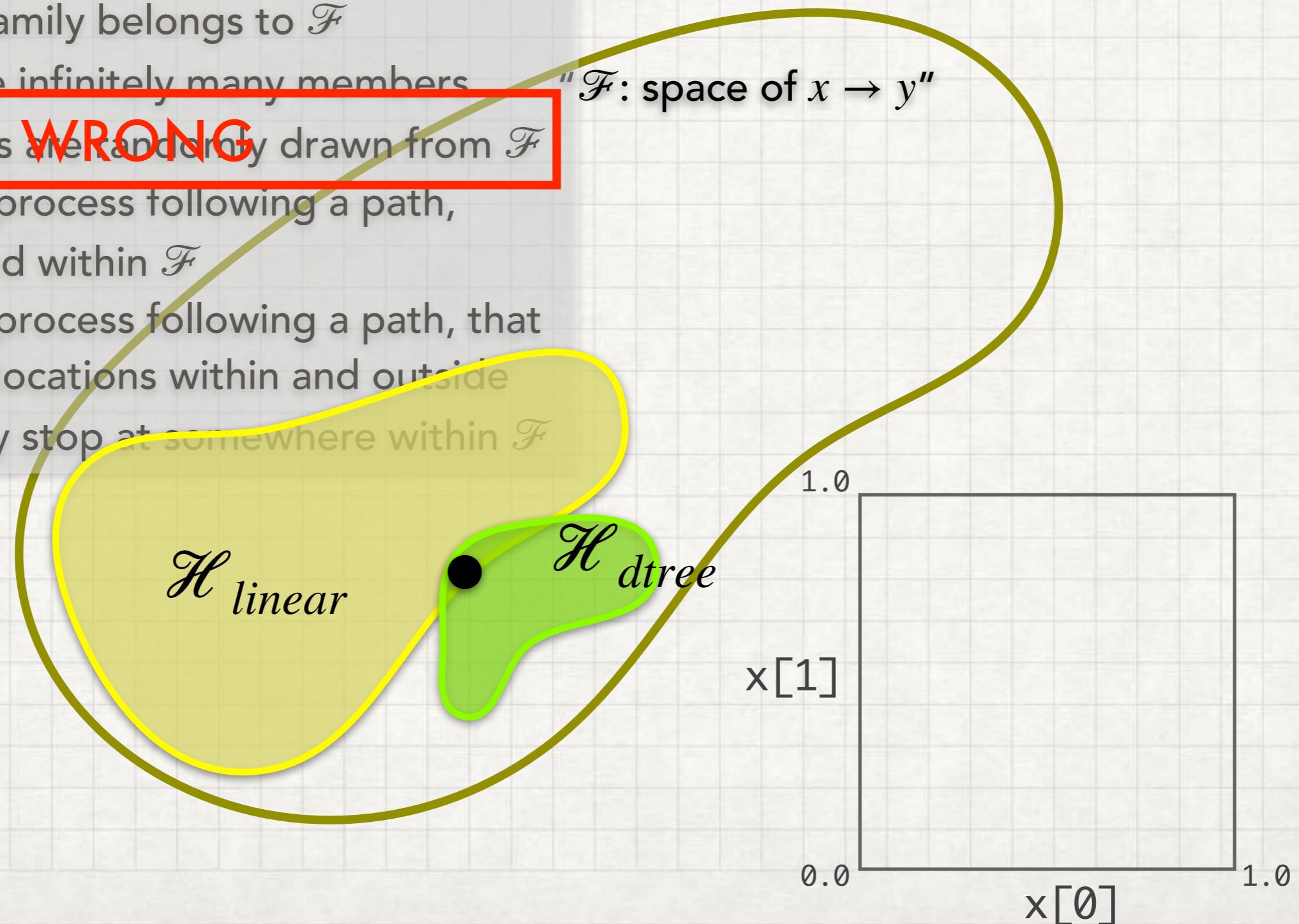
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220932619489509376

	X1	L	L	L	M	M	M	H	H	H
Y X	X2	L	M	H	L	M	H	L	M	H
a0		0	0	0	0	0	0	0	0	0
a1		0	0	0	0	0	0	0	0	1
a2		0	0	0	0	0	0	0	1	0
a3		0	0	0	0	0	0	0	1	1
a4		0	0	0	0	0	0	1	0	0
a5		0	0	0	0	0	0	1	0	1
a6		0	0	0	0	0	0	1	1	0
a7		0	0	0	0	0	0	1	1	1

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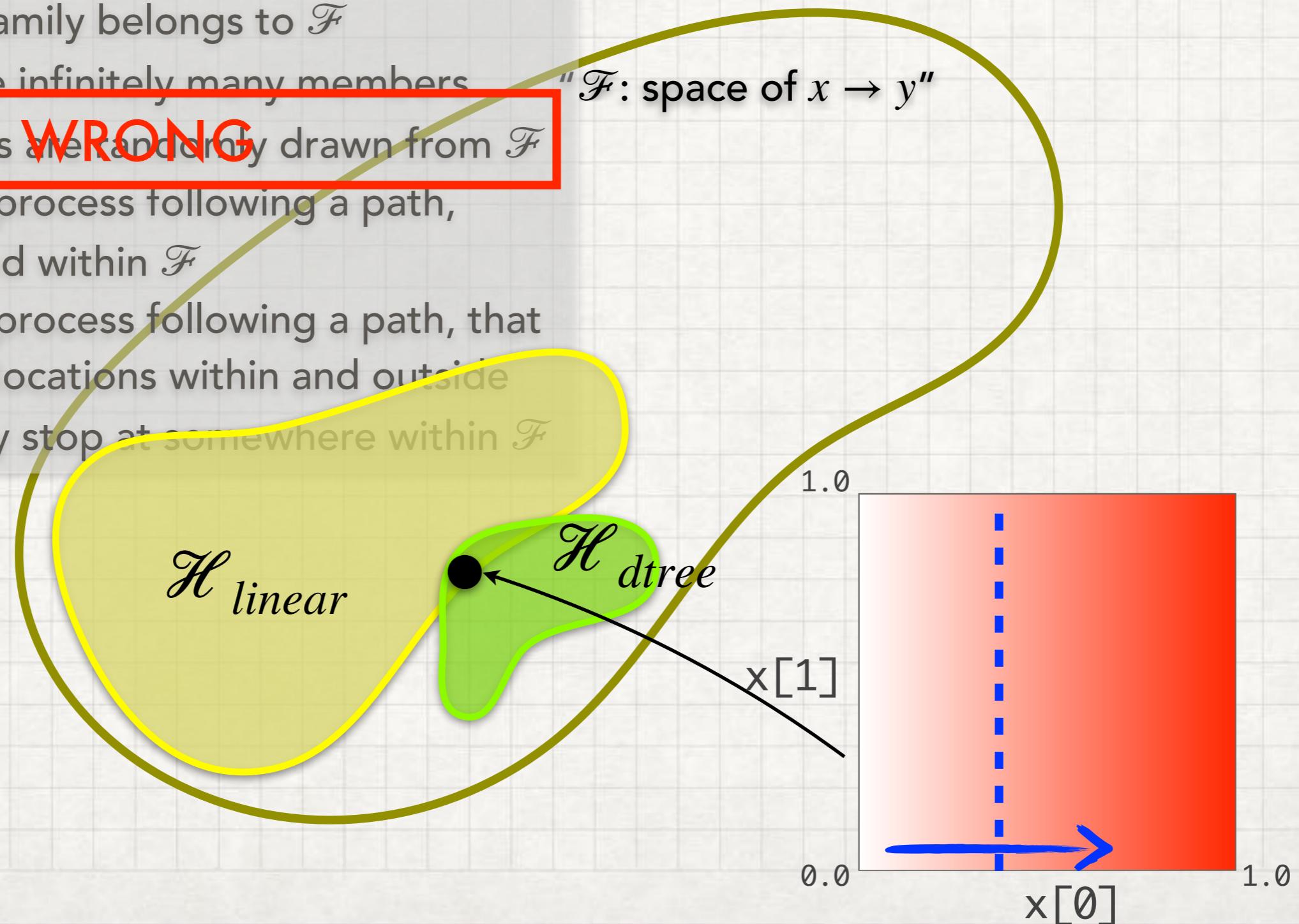
- A. Any model family belongs to  $\mathcal{F}$
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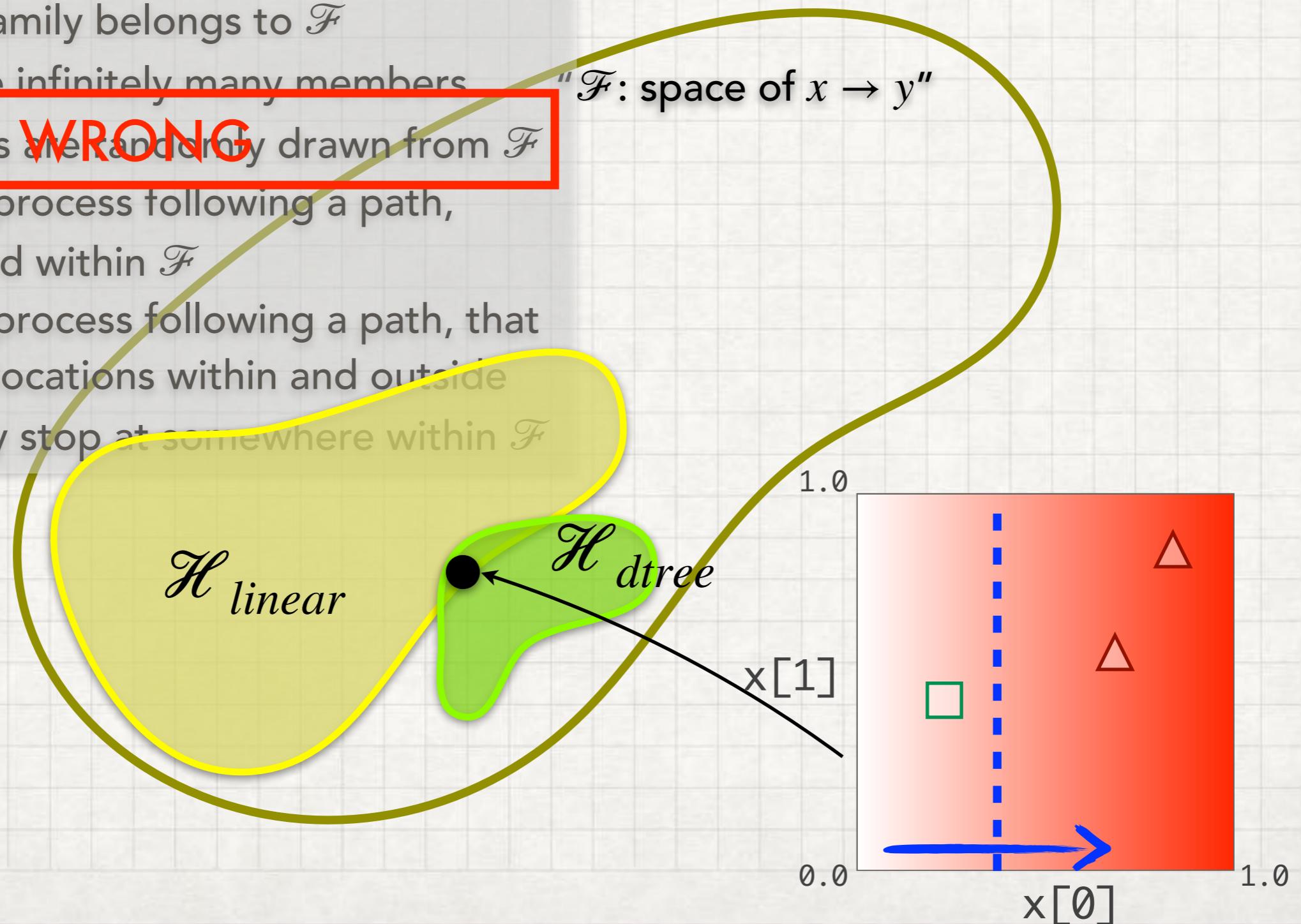
- A. Any model family belongs to  $\mathcal{F}$
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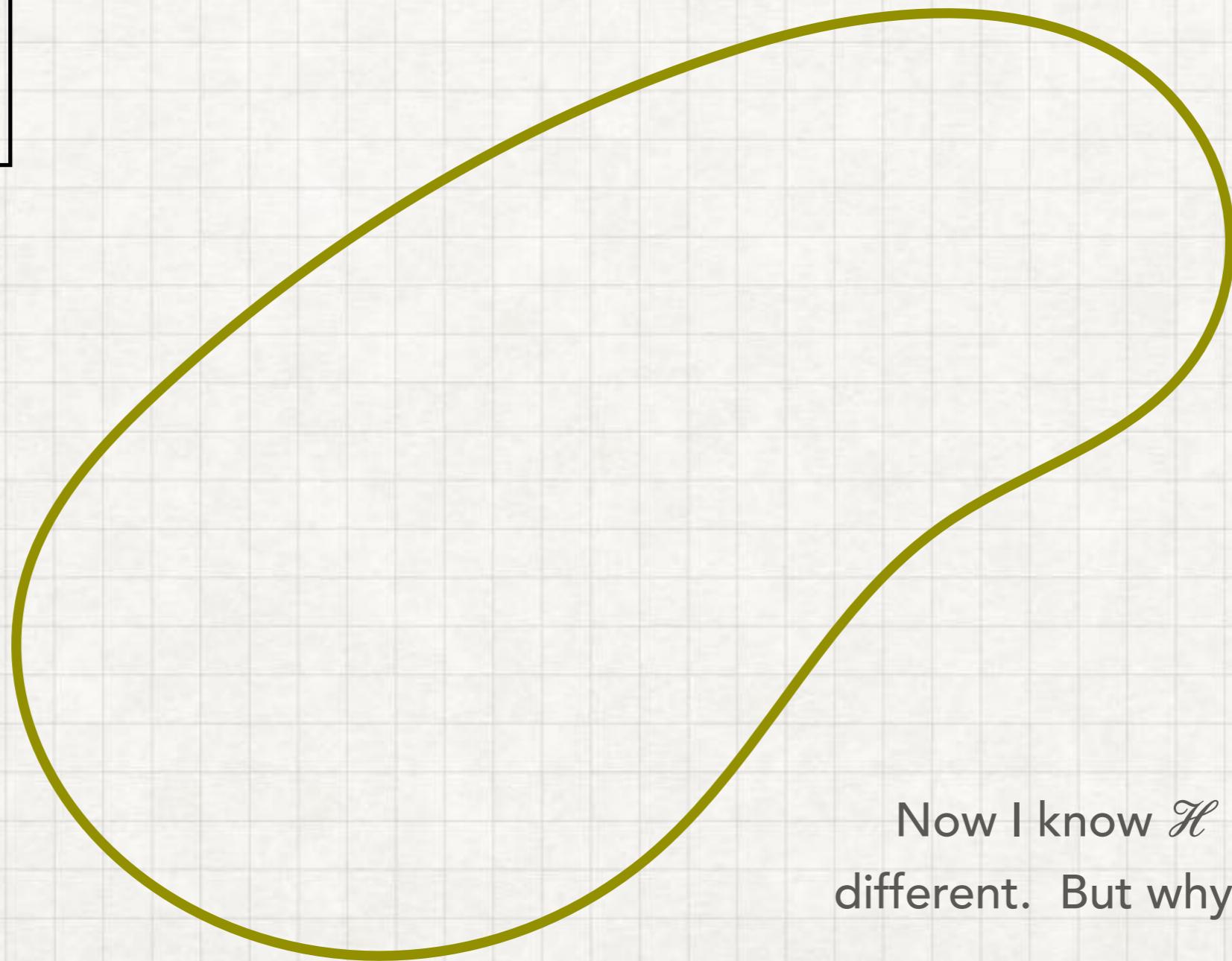
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**WRONG**  
 $\mathcal{F}$ , but finally stop at somewhere within  $\mathcal{F}$

" $\mathcal{F}$ : space of  $x \rightarrow y$ "

# WHY FUNCTIONAL SPACE?

$x, y$

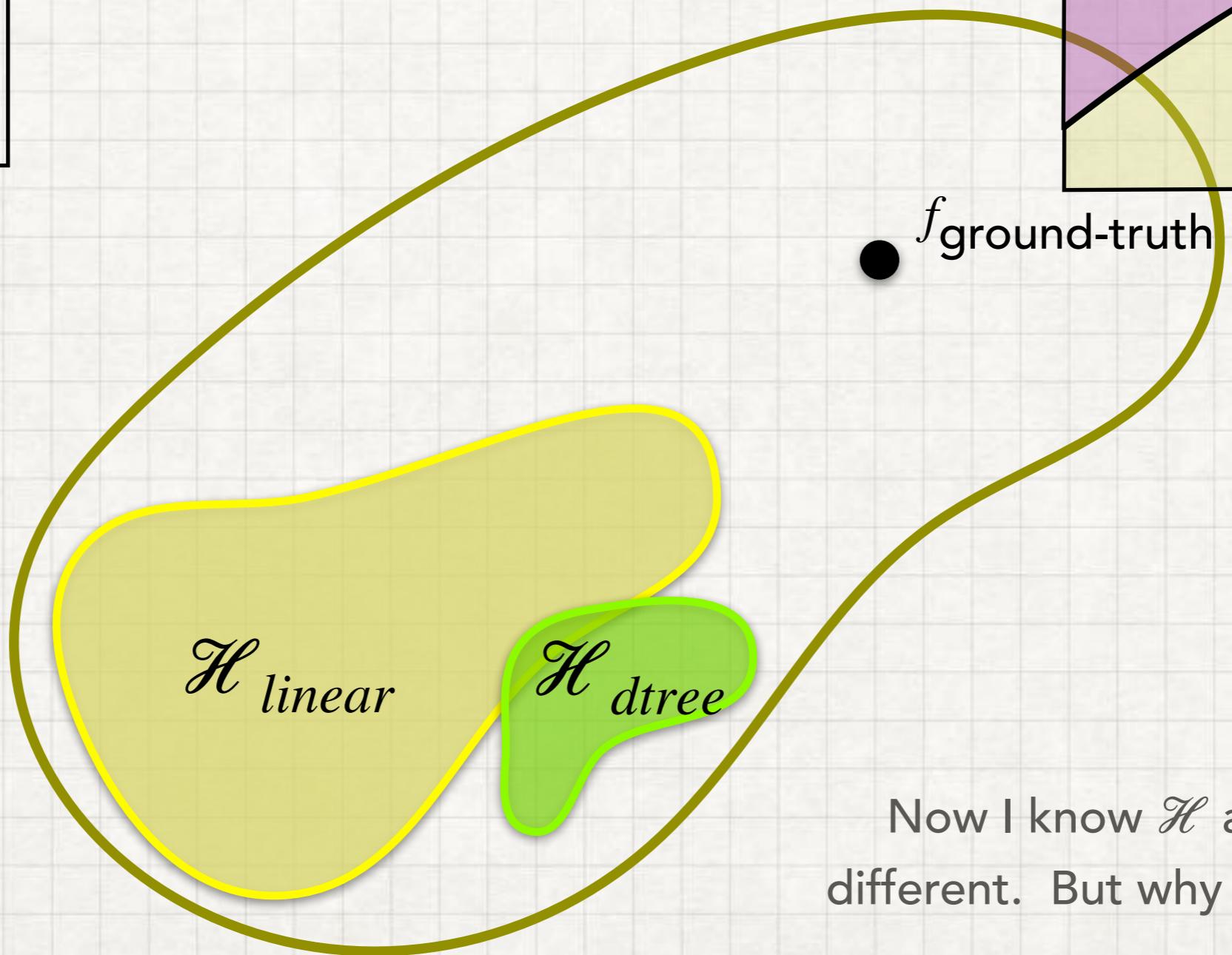
setosa /  
versicolor ?



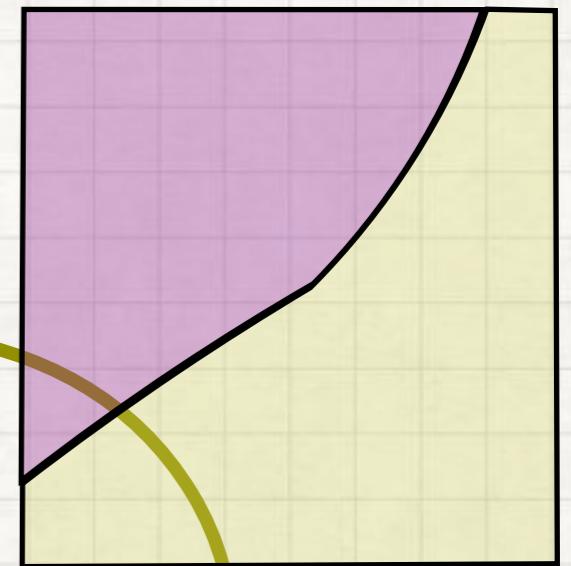
Now I know  $\mathcal{H}$  and  $\mathcal{F}$  are  
different. But why we need  $\mathcal{F}$ ?

# WHY FUNCTIONAL SPACE?

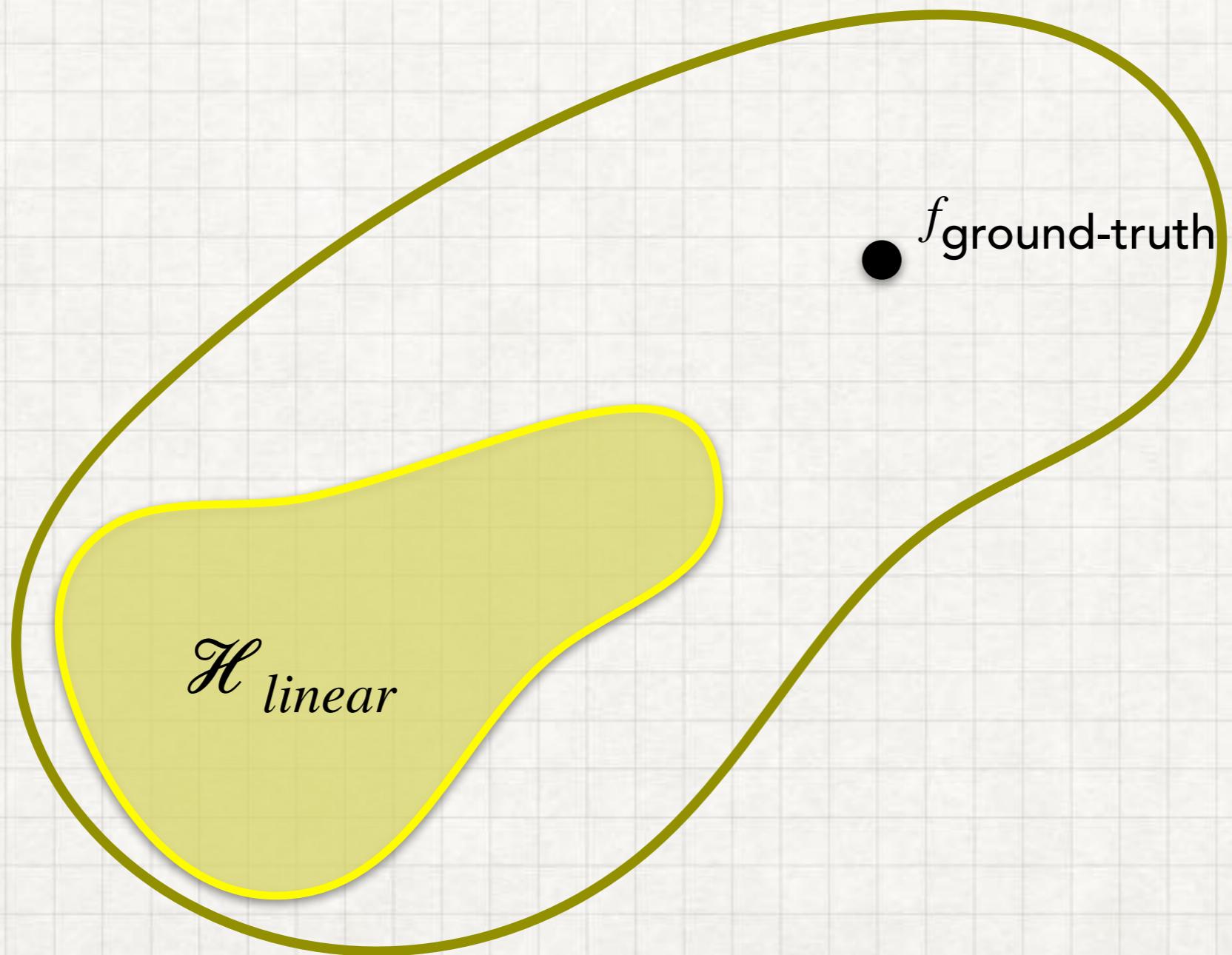
$x, y$   
setosa /  
versicolor ?



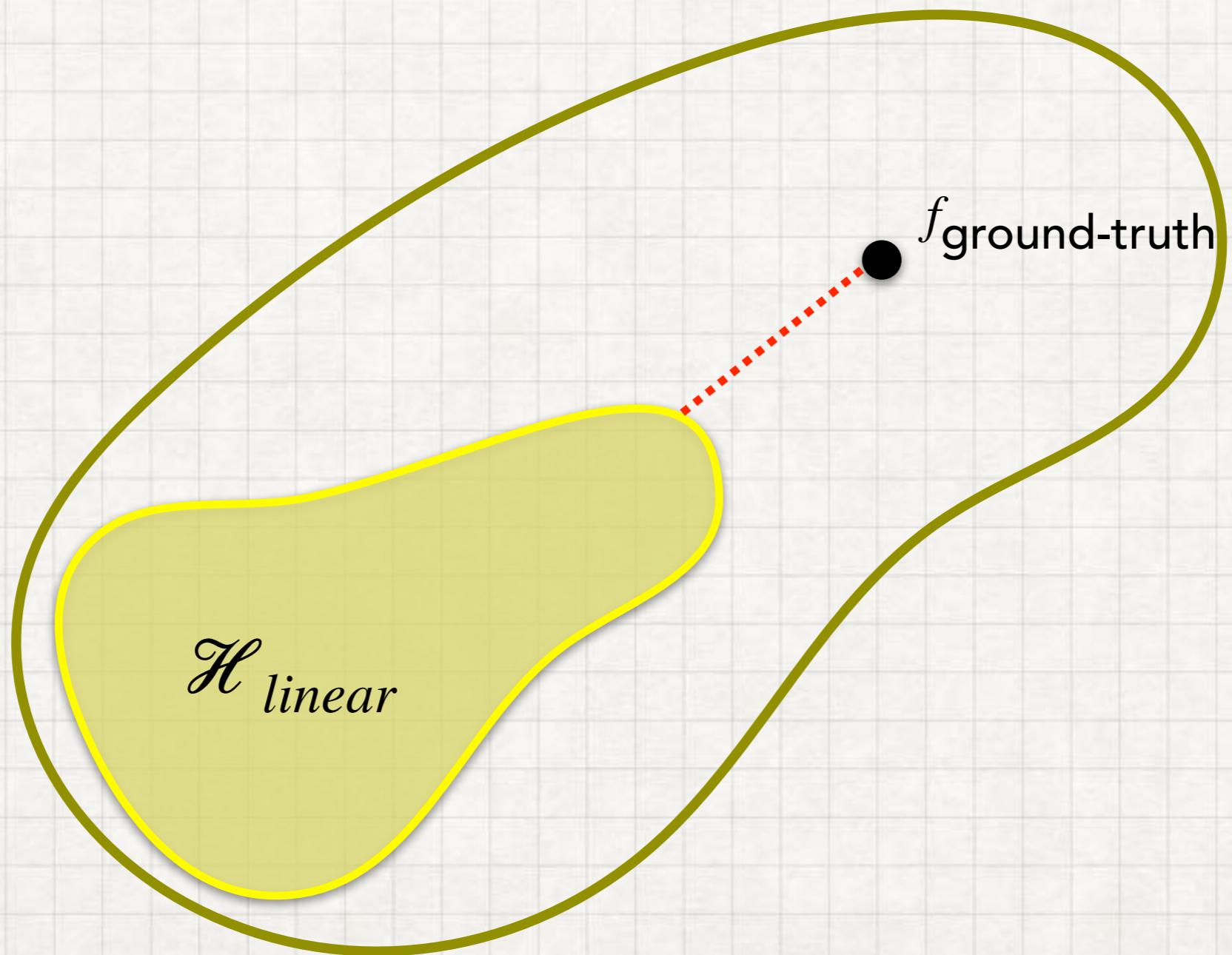
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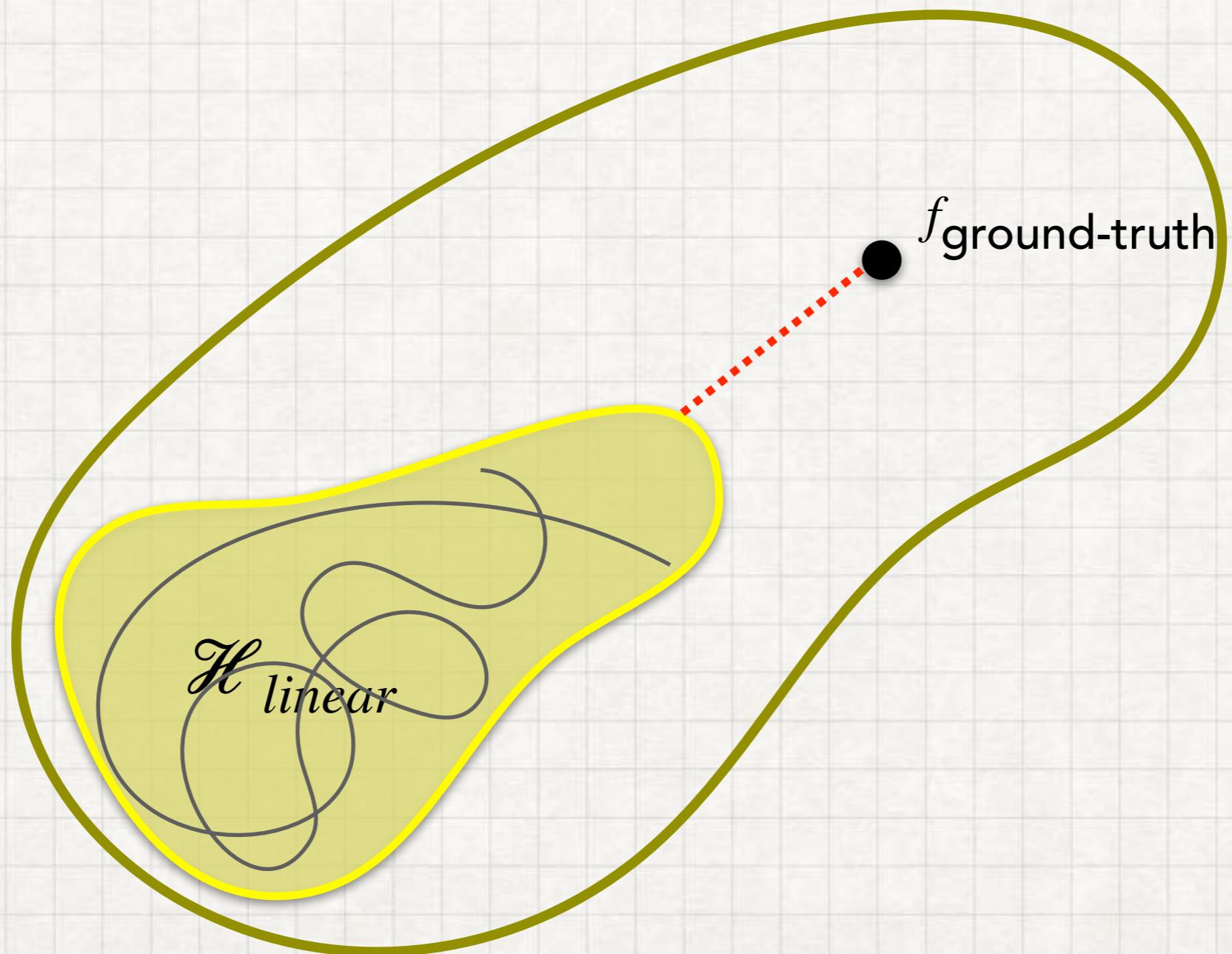
# WHY FUNCTIONAL SPACE – GIVEN $\mathcal{H}$ ?



# WHY FUNCTIONAL SPACE – GIVEN $\mathcal{H}$ ?



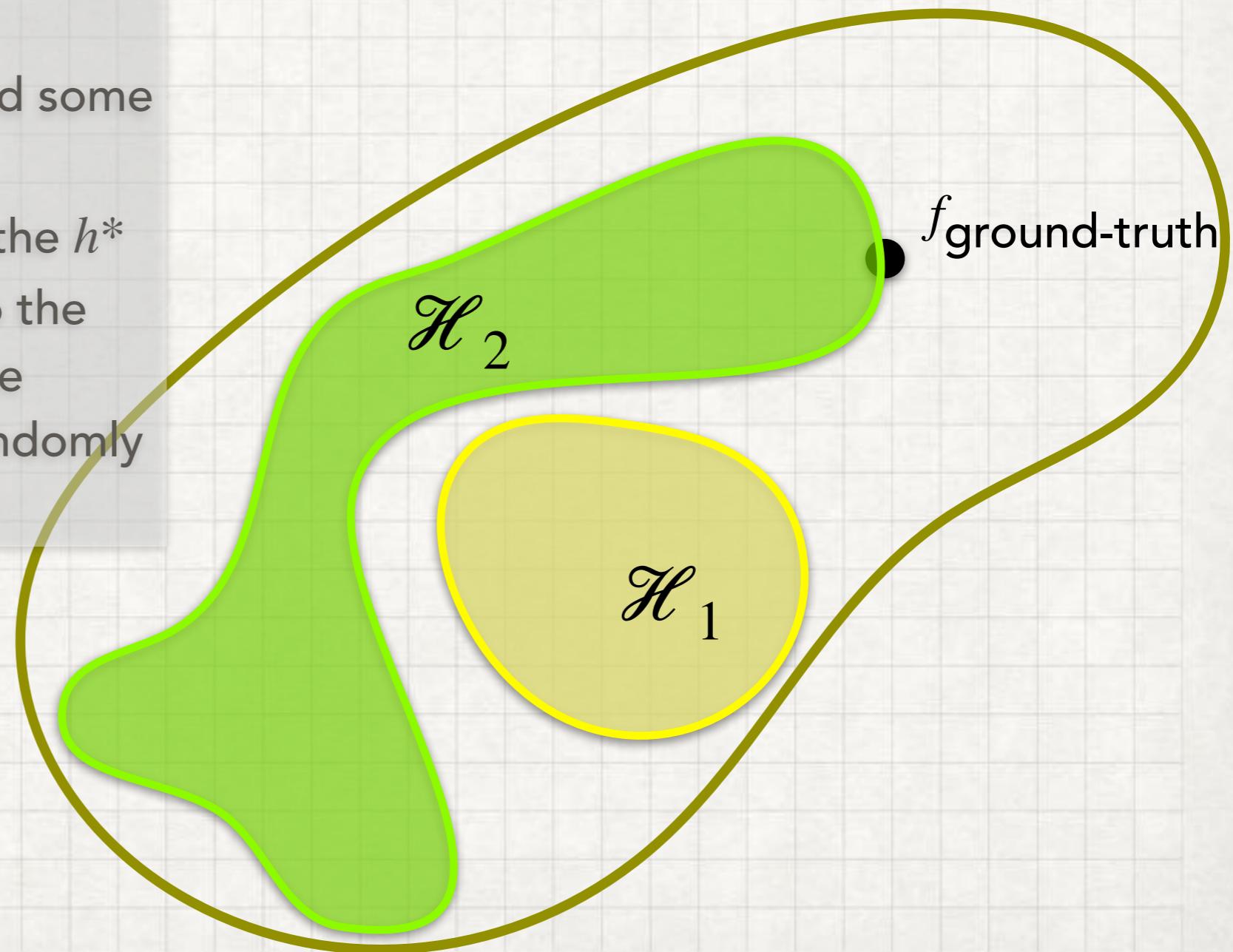
# WHY FUNCTIONAL SPACE – GIVEN $\mathcal{H}$ ?



# WHICH ONE IS BETTER?

**Q:** Which hypothesis family will result in less error?

- A.  $\mathcal{H}_2$ , it (almost) includes the ground-truth, so one can find some good predictor  $h^*$  from  $\mathcal{H}_2$
- B. Not sure, because whether the  $h^*$  selected from  $\mathcal{H}_2$  is close to the ground-truth depends on the training dataset, which is randomly generated.

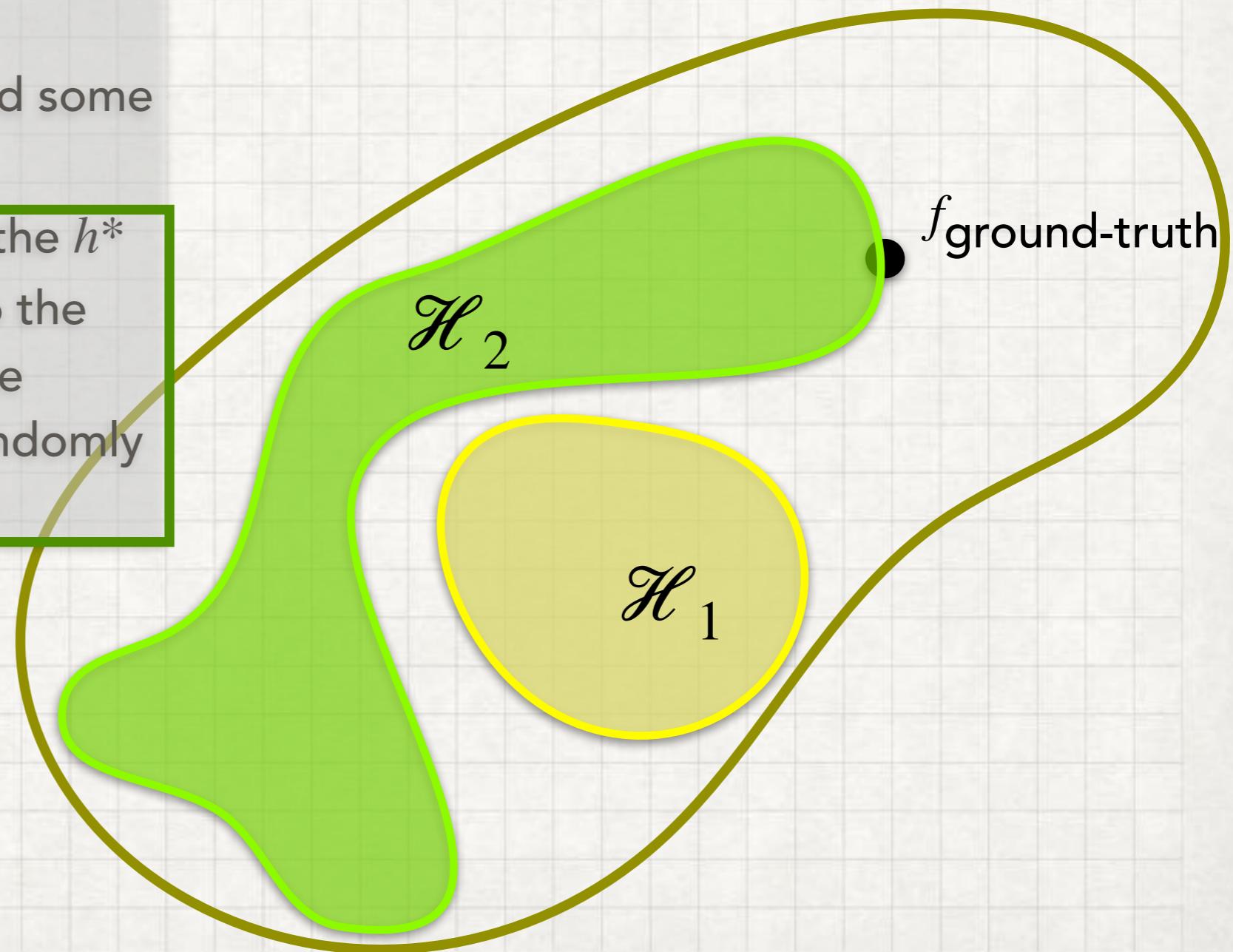


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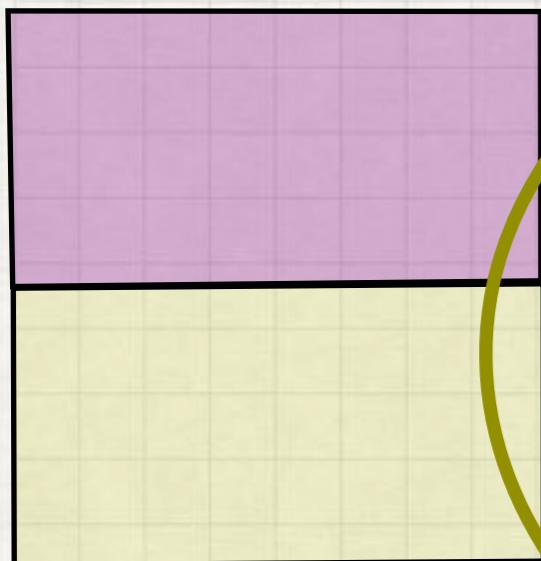


# ERROR/RISK IN FUNCTIONAL SPACE

$x, y$

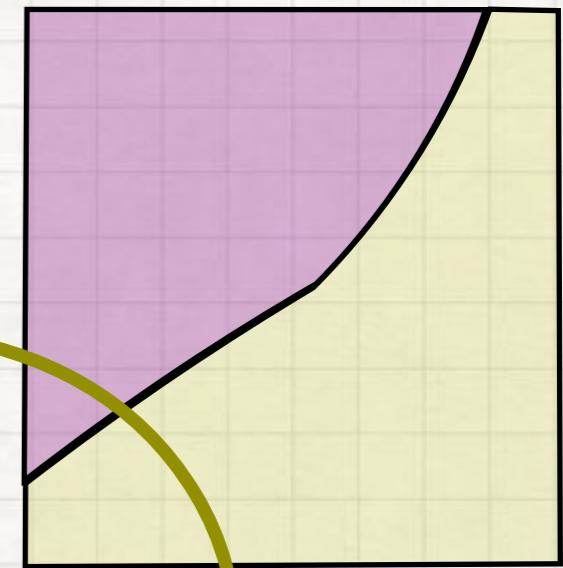
setosa /  
versicolor ?

Risk: Distance in Functional Space  
Error Area in Data Space



$h_1$

$f_{\text{ground-truth}}$

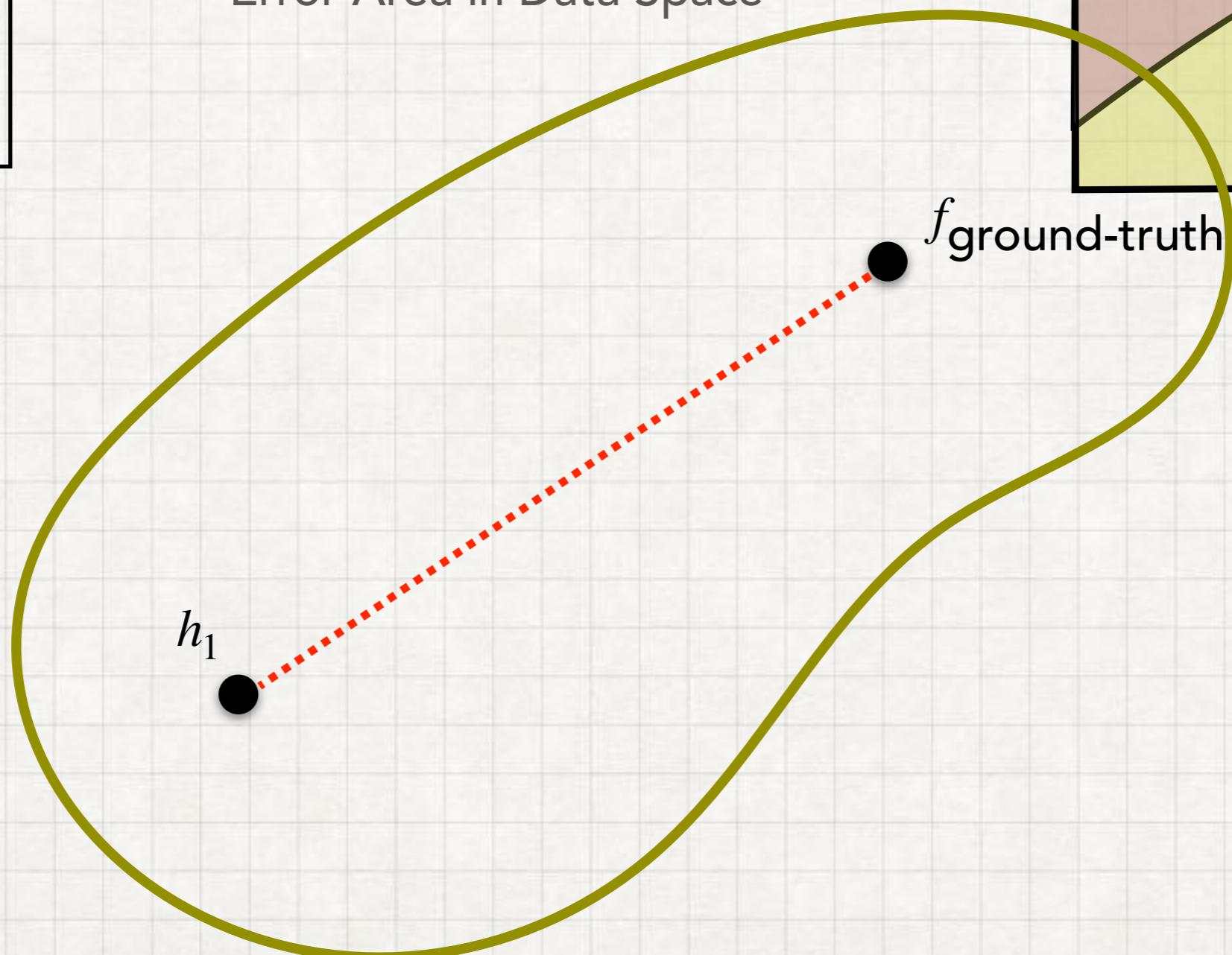
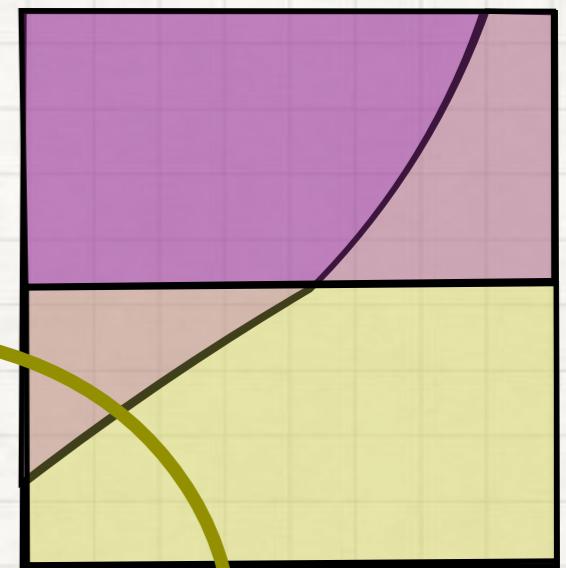


# ERROR/RISK IN FUNCTIONAL SPACE

$x, y$

setosa /  
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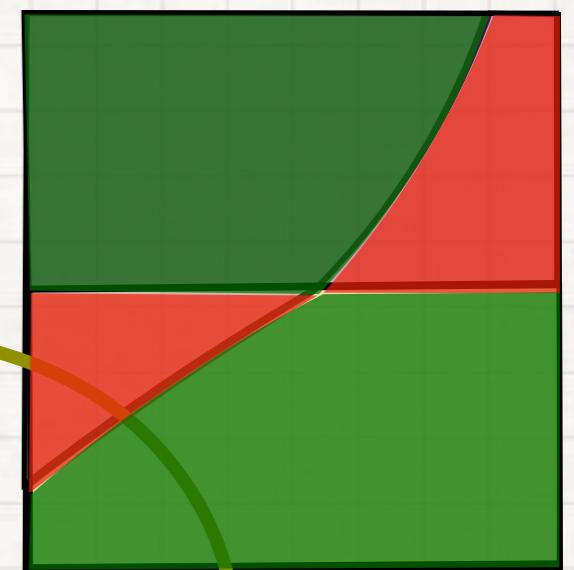
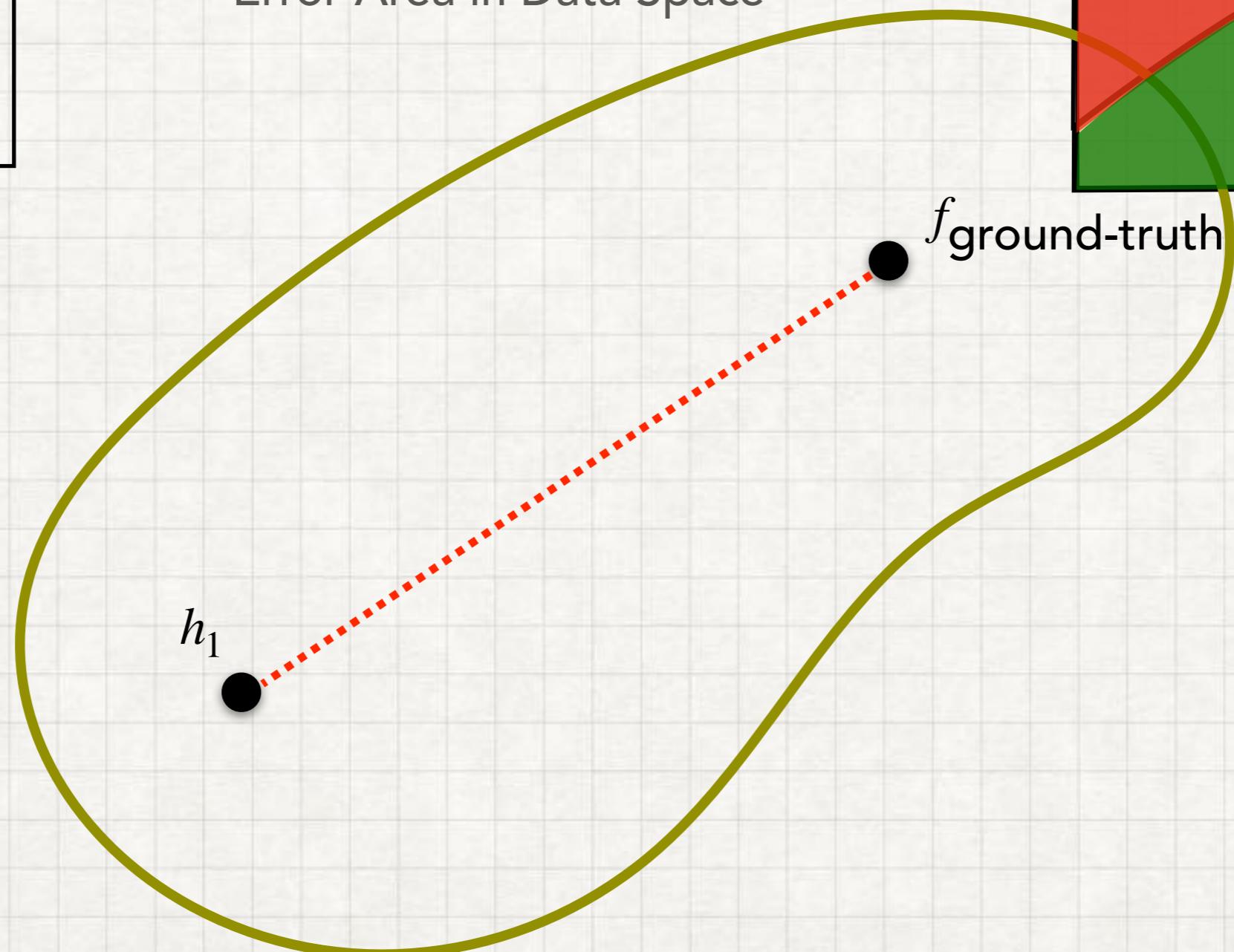
Risk: Distance in Functional Space  
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# ERROR/RISK IN FUNCTIONAL SPACE

$x, y$   
setosa /  
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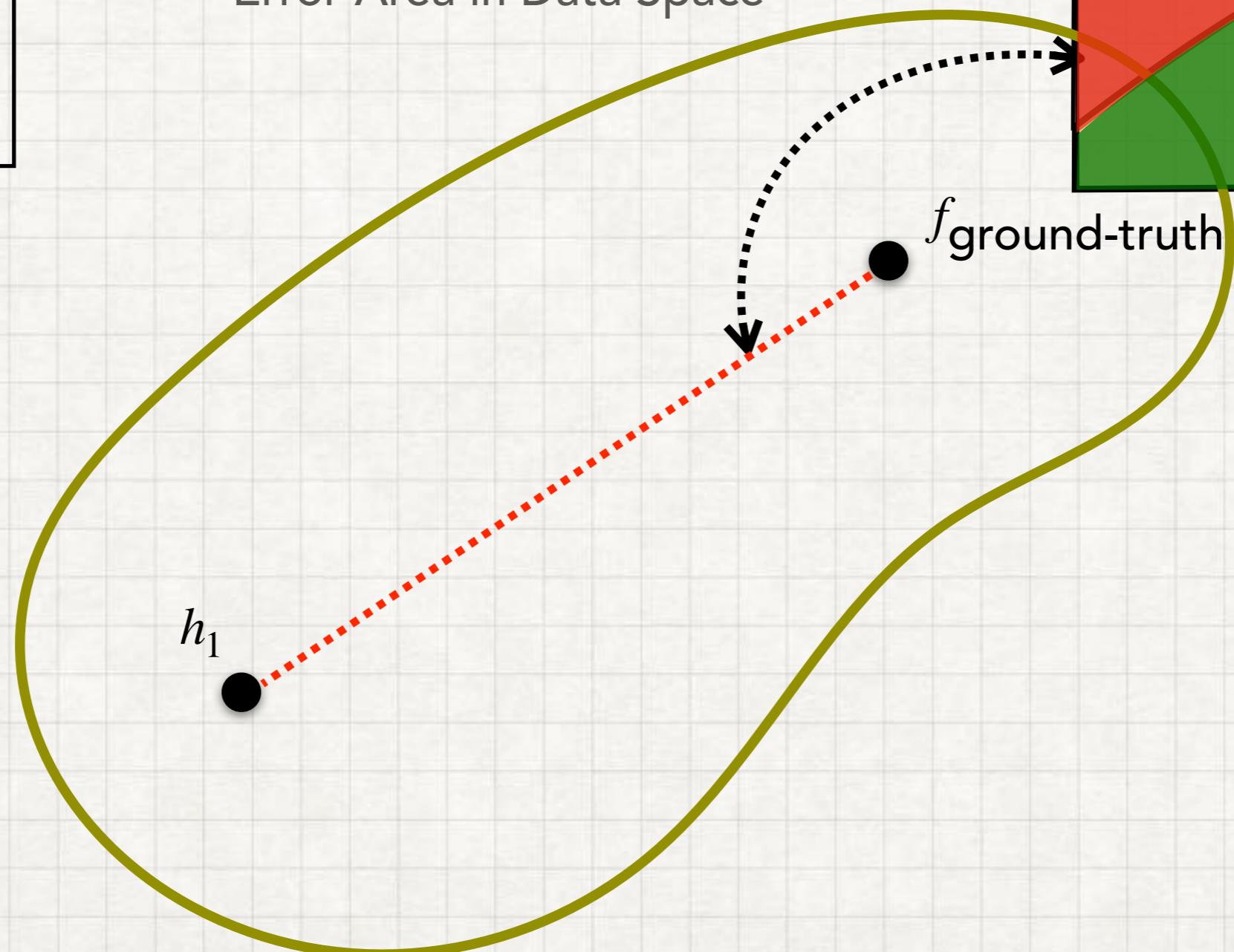
Risk: Distance in Functional Space  
Error Area in Data Space



# ERROR/RISK IN FUNCTIONAL SPACE

$x, y$   
setosa /  
versicolor ?

Risk: Distance in Functional Space  
Error Area in Data Space

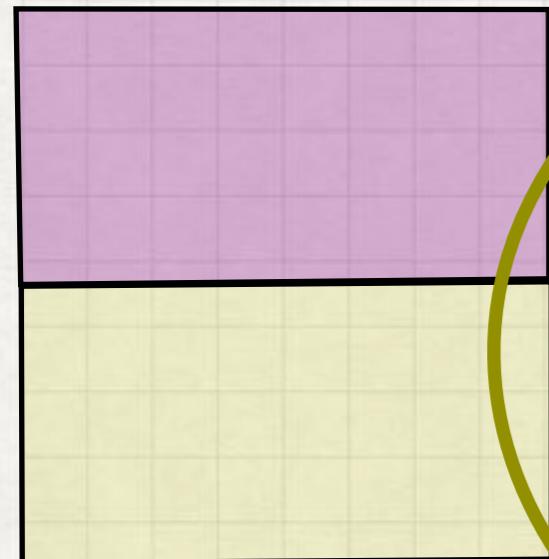


# ERROR/RISKS OF TWO HYPOTHESES

$x, y$

setosa /  
versicolor ?

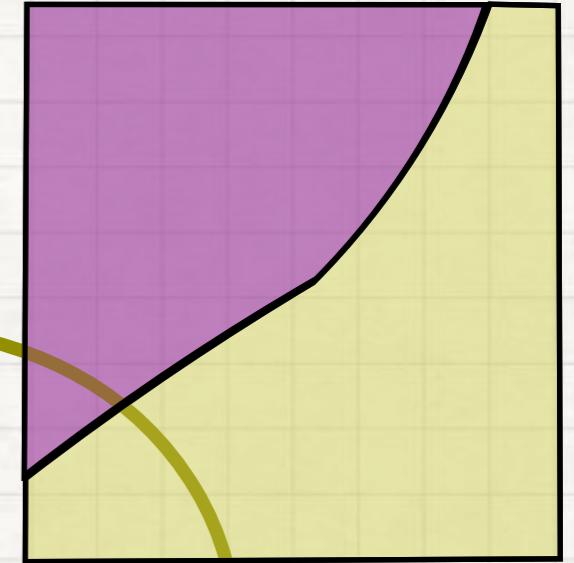
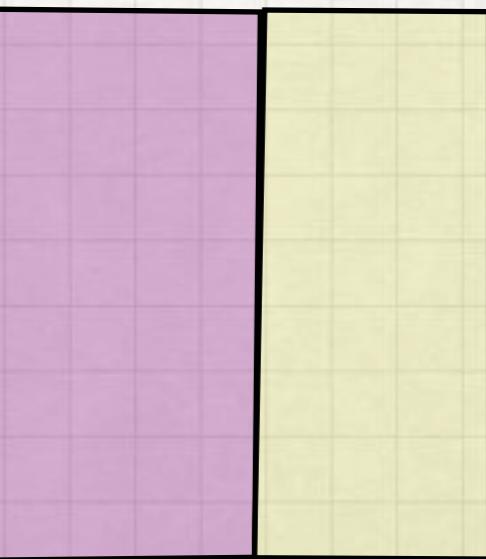
Risk: Distance in Functional Space  
Error Area in Data Space



"space of  $x \rightarrow y$ "



$f_{\text{ground-truth}}$

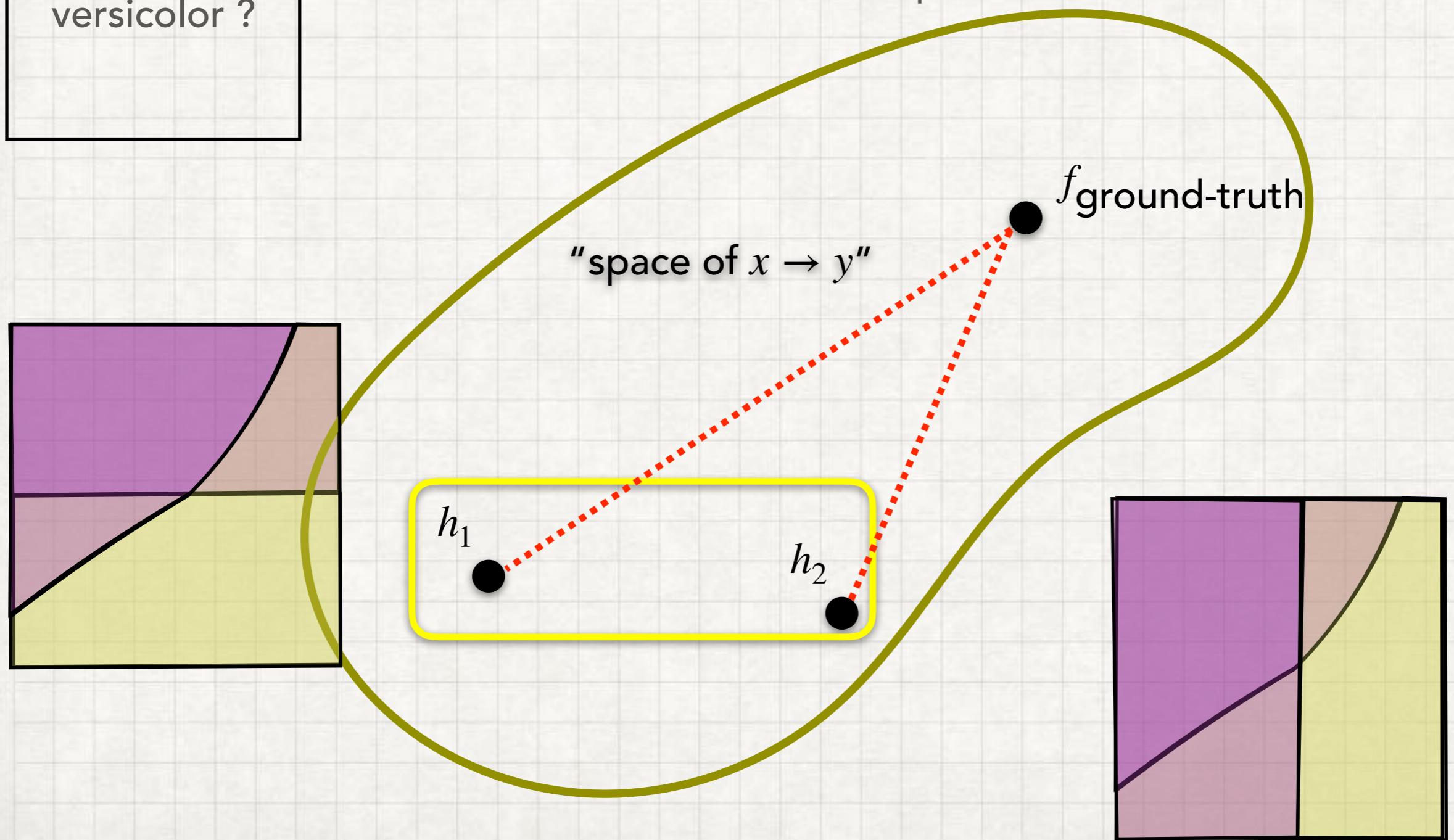


# ERROR/RISKS OF TWO HYPOTHESES

$x, y$

setosa /  
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Risk: Distance in Functional Space  
Error Area in Data Space

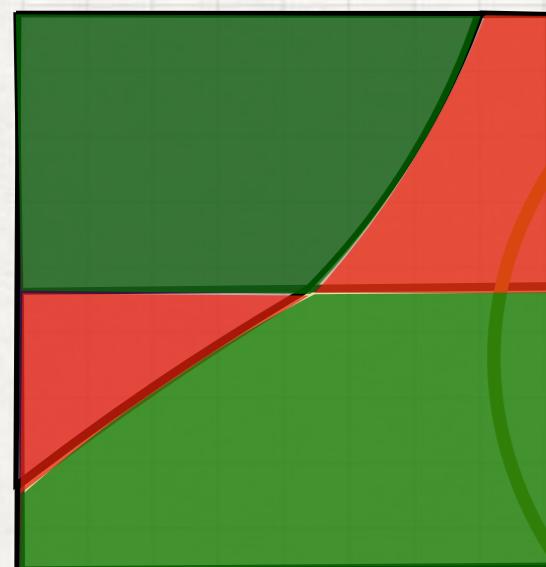


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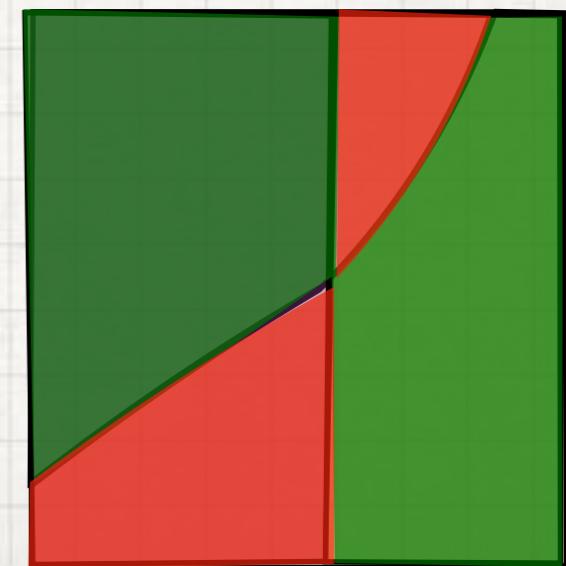


"space of  $x \rightarrow y$ "

$f_{\text{ground-truth}}$

$h_1$

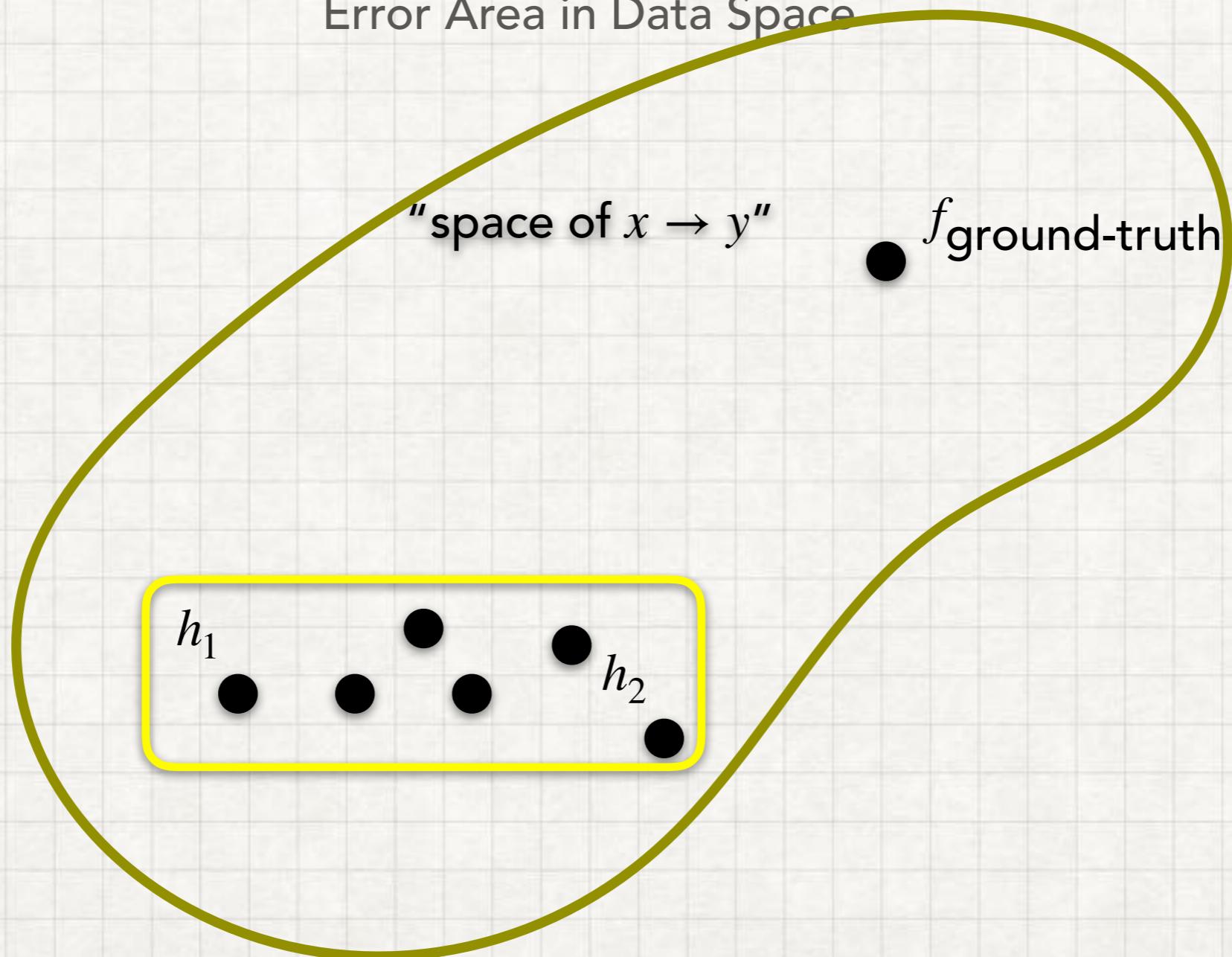
$h_2$



# ERROR/RISKS OF MANY HYPOTHESES

Risk: Distance in Functional Space

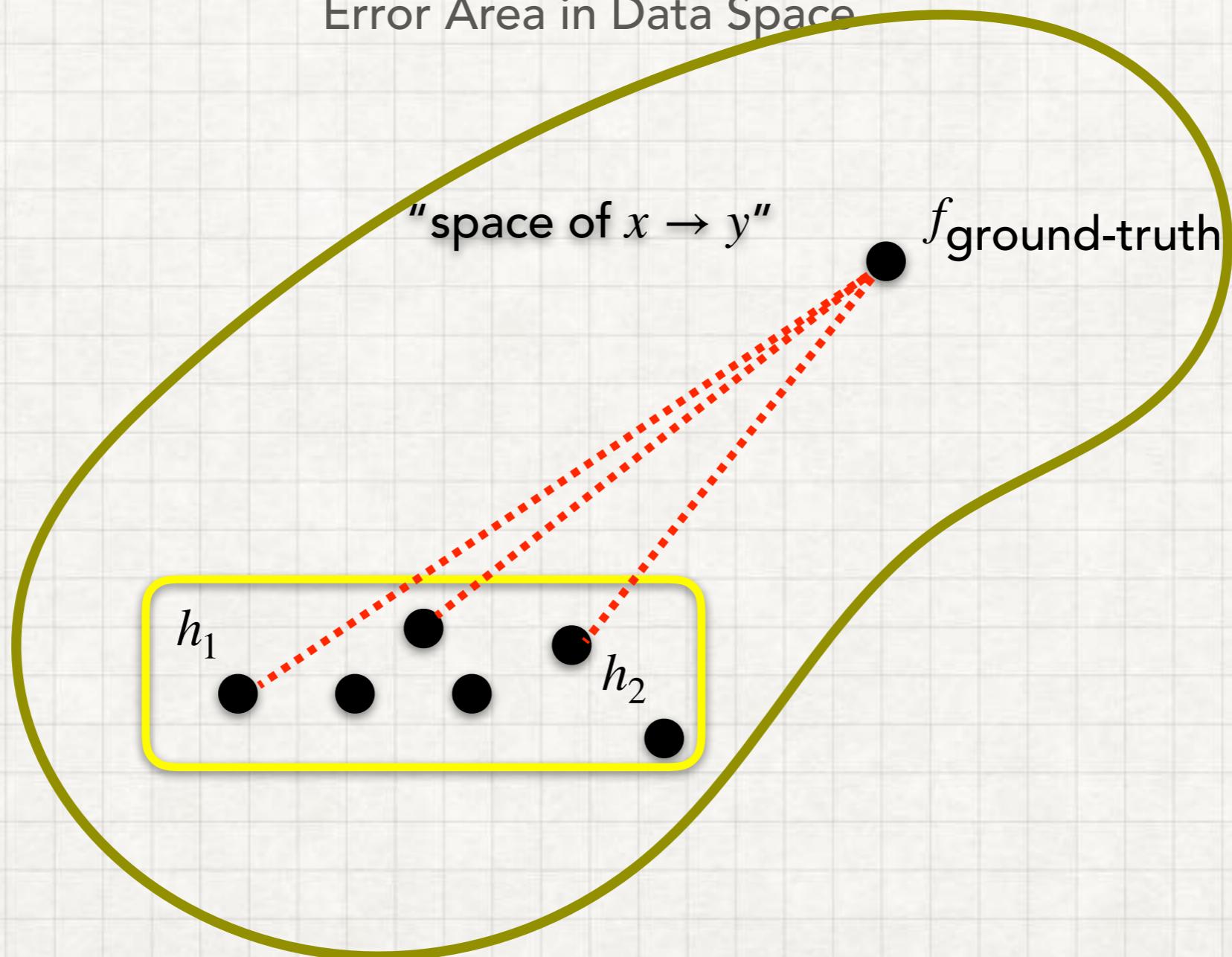
Error Area in Data Space



# ERROR/RISKS OF MANY HYPOTHESES

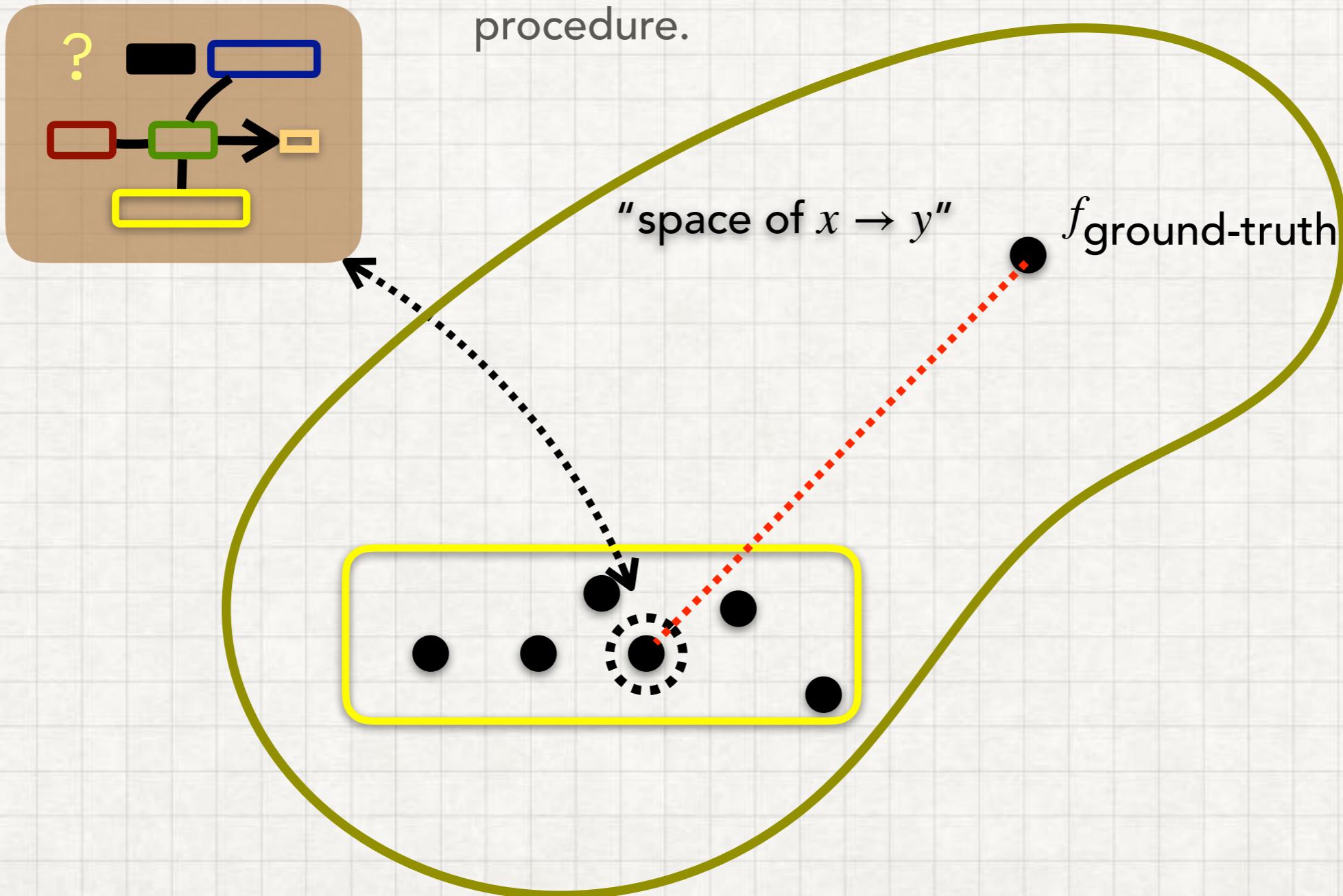
Risk: Distance in Functional Space

Error Area in Data Space



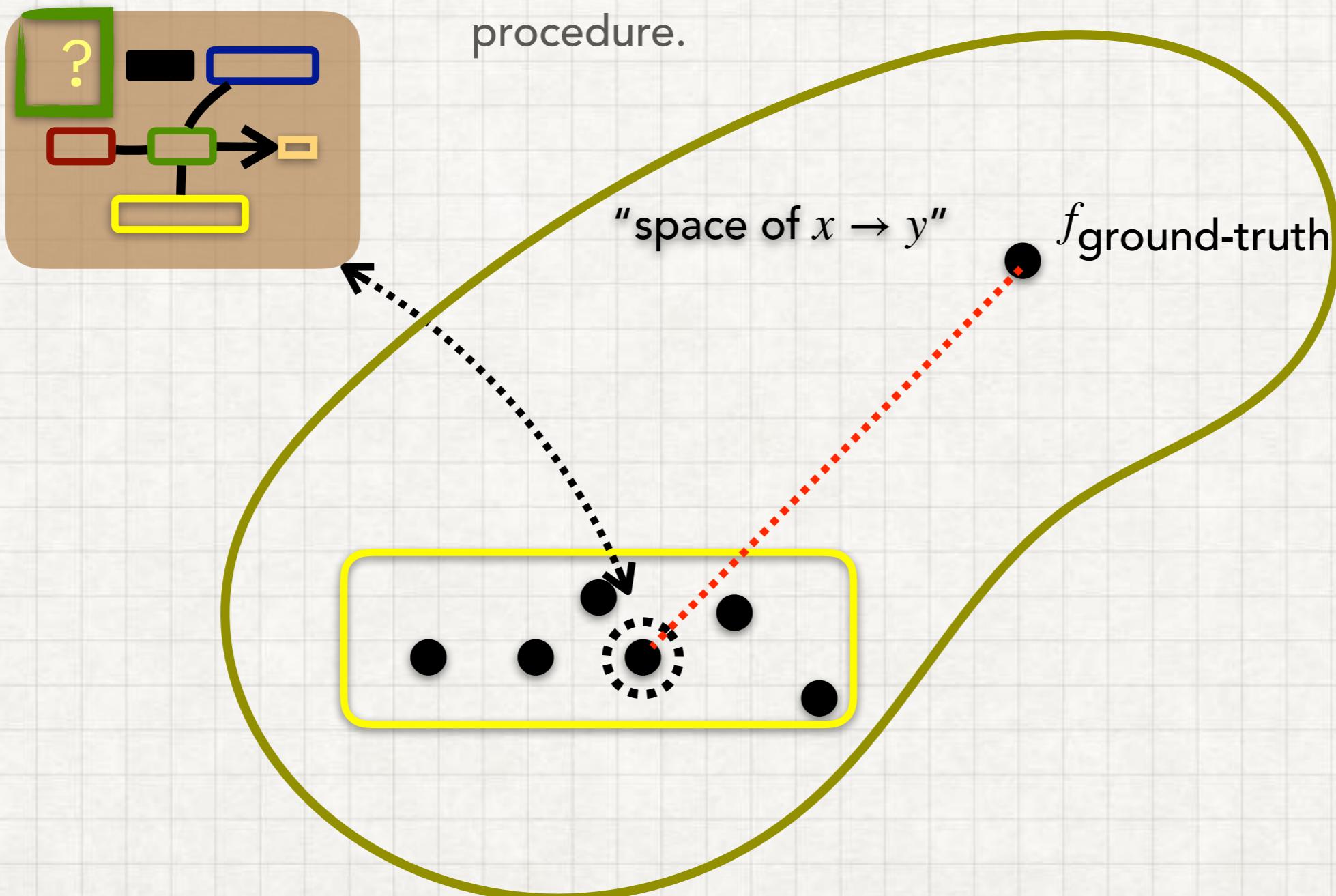
# ERROR/RISKS OF SELECTED HYPOTHESES FROM MANY

The learning problem is concerned with the hypothesis selected by the learning procedure.

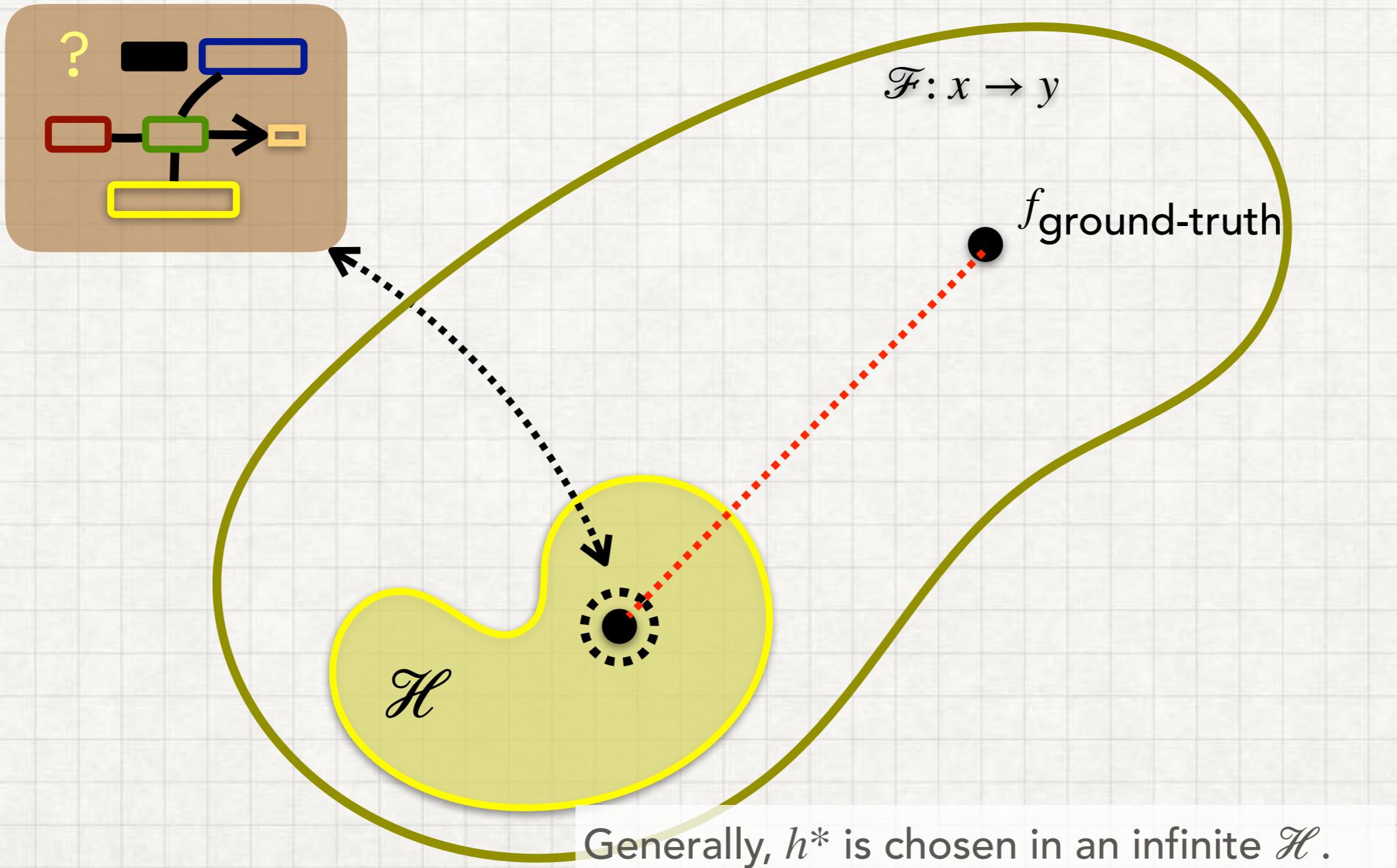


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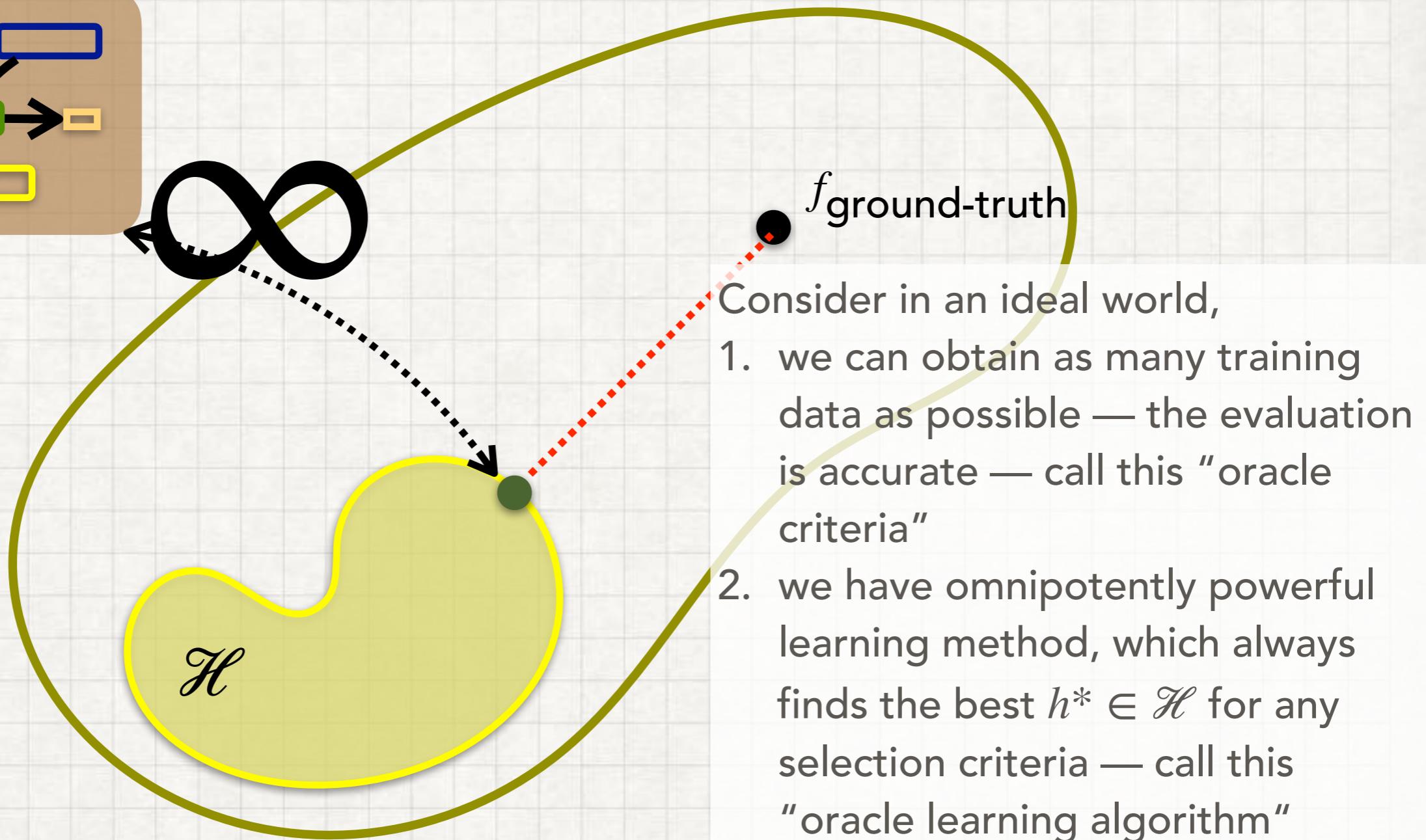
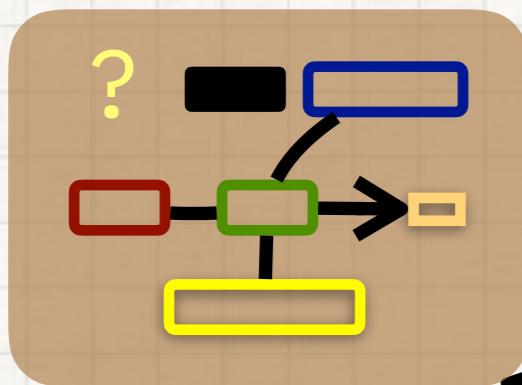


# ERROR/RISKS OF SELECTED HYPOTHESIS FROM $\mathcal{H}$



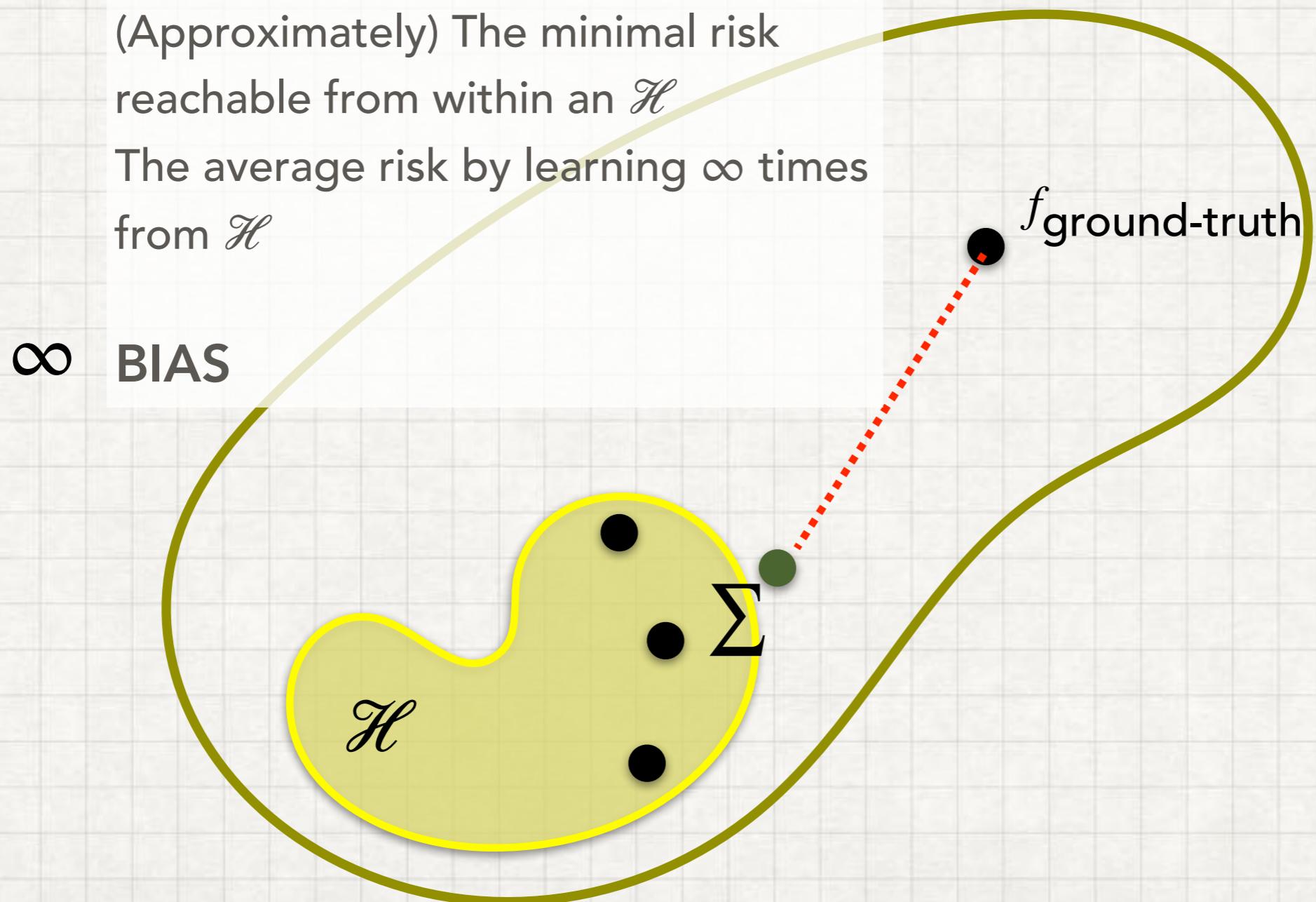
**MOD2: DISCRIMINATE TWO TYPES  
OF RISKS WHEN FACING RANDOM  
DATA BIAS AND VARIANCE**

# OPTIMUM WITHIN $\mathcal{H}$



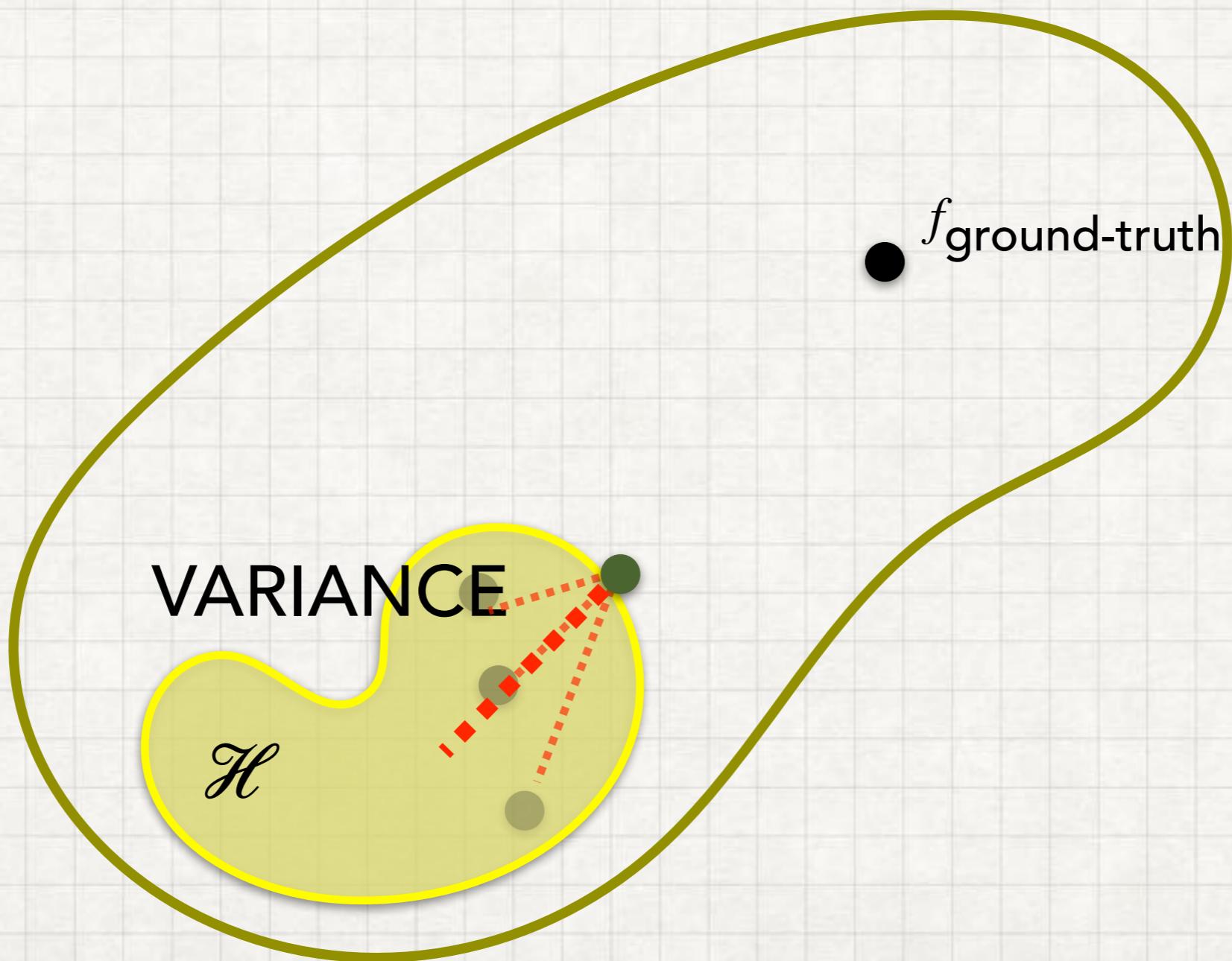
Putting together, we then consider the minimal risk of an  $\mathcal{H}$ .

# DEFINITION OF BIAS



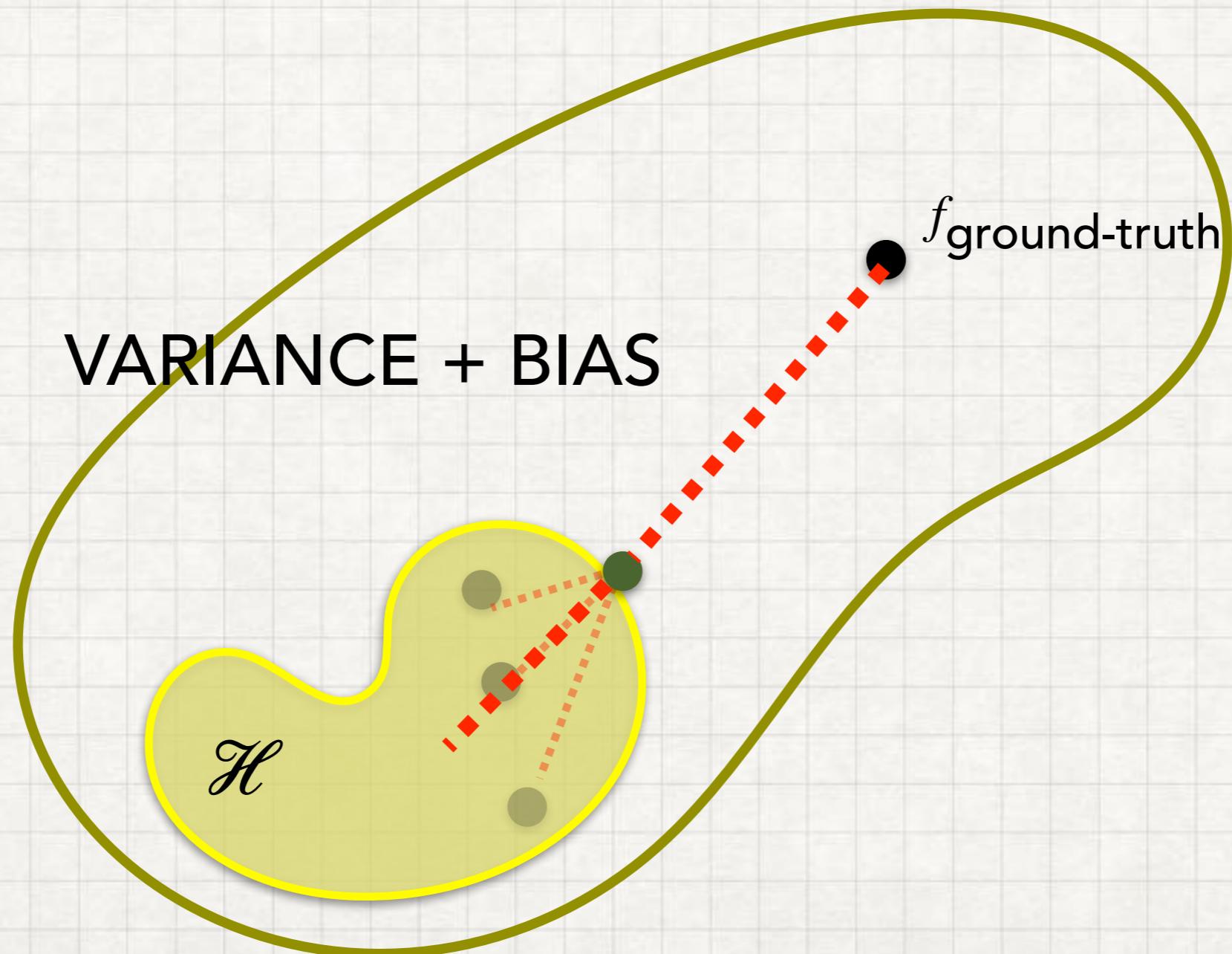
# RISK OF TRAINING WITH ONE, RANDOM

$D_{train}$



# TOTAL RISK OF A TRAINING

- The expected risk of the hypothesis selected by the learning framework consists of the following two parts.



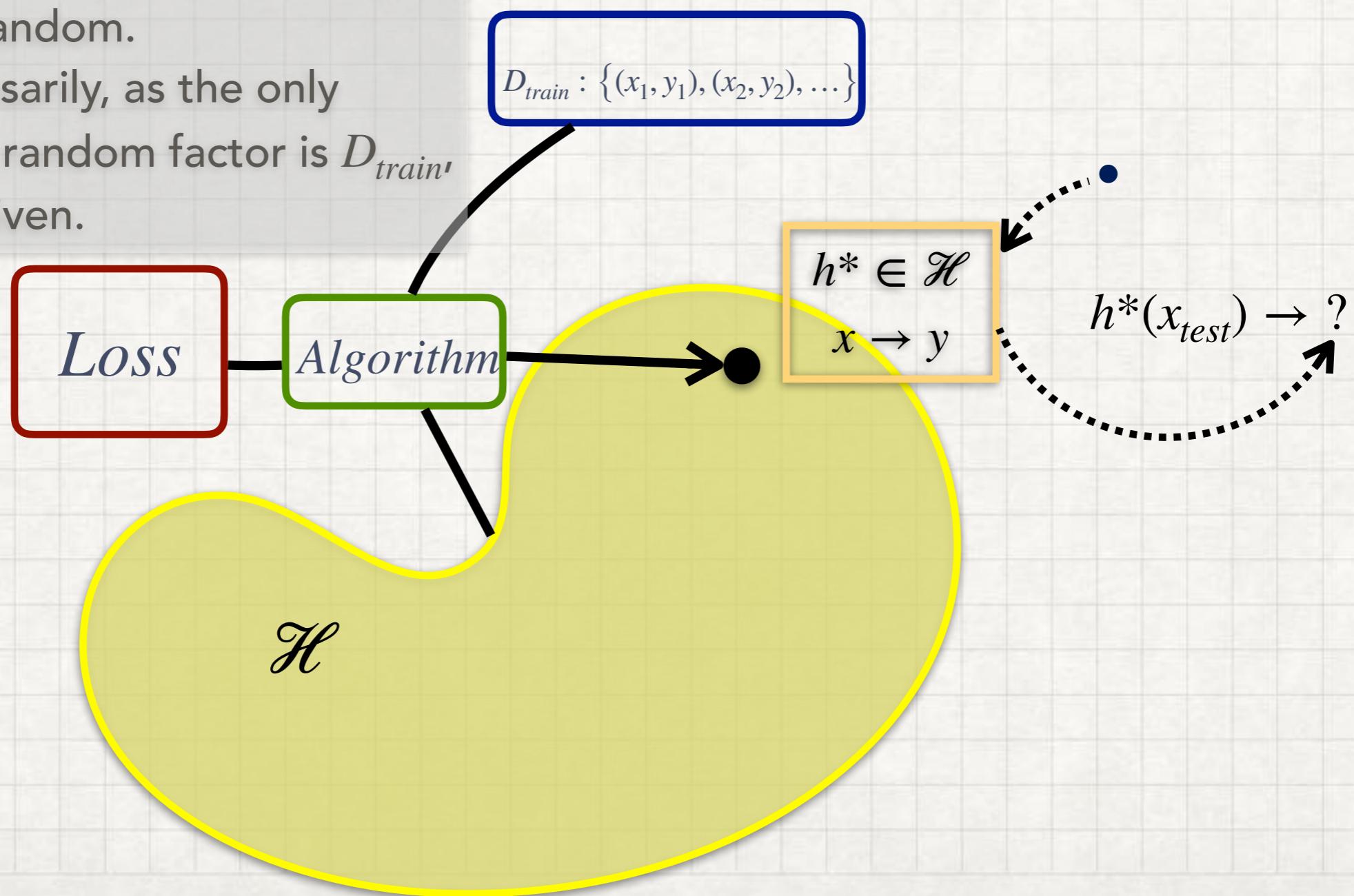
# SUMMARISE: RANDOMISATION OF THE PREDICTION

- "Microscope of risk", consider the generalisation error at one  $x_{test}$ .

**Q:** Given a  $D_{train}$ , the selected  $h^*$  ...

$$\mathcal{X} \rightarrow \mathcal{Y}$$

- A. must be random.
- B. Not necessarily, as the only inevitable random factor is  $D_{train}$ , which is given.

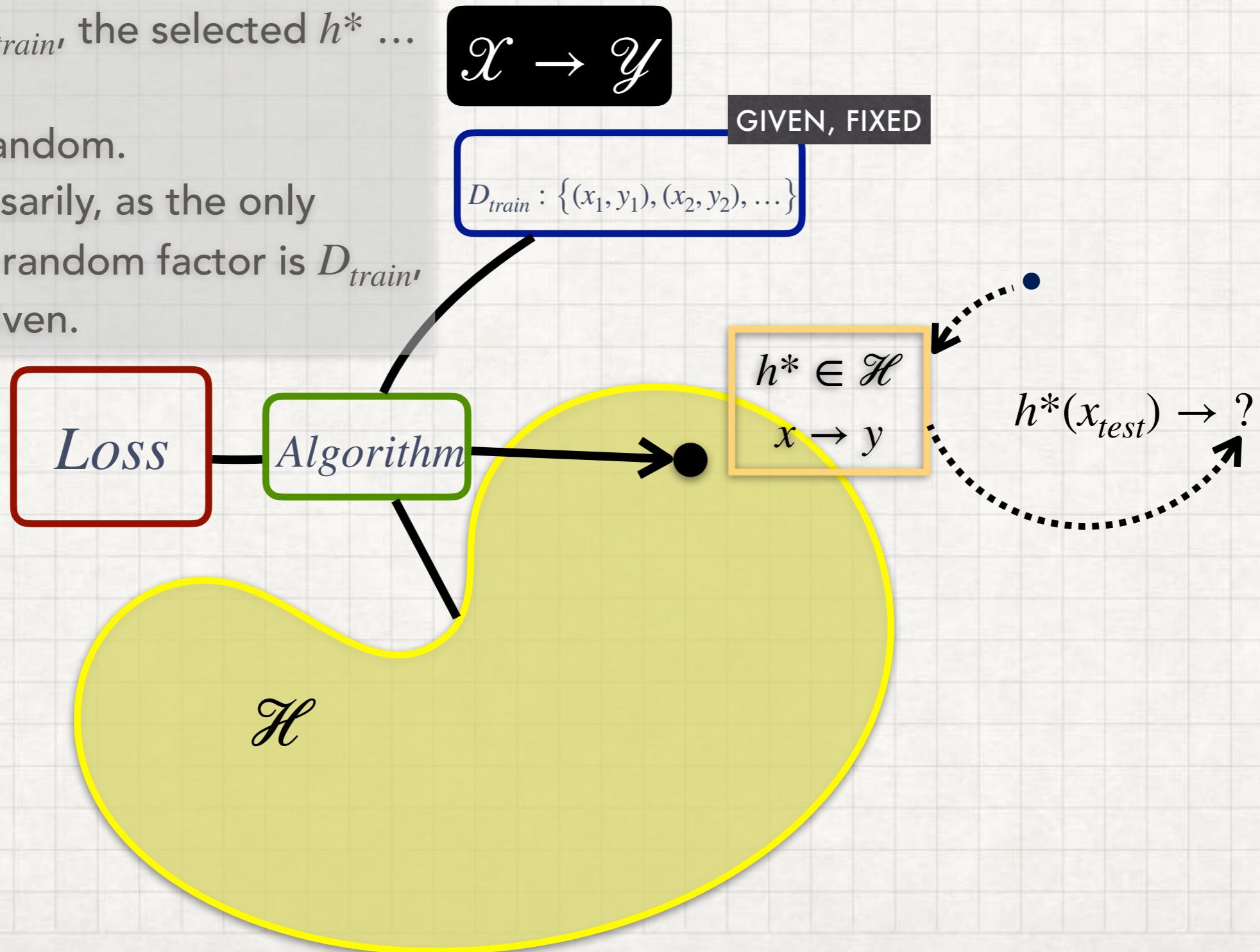


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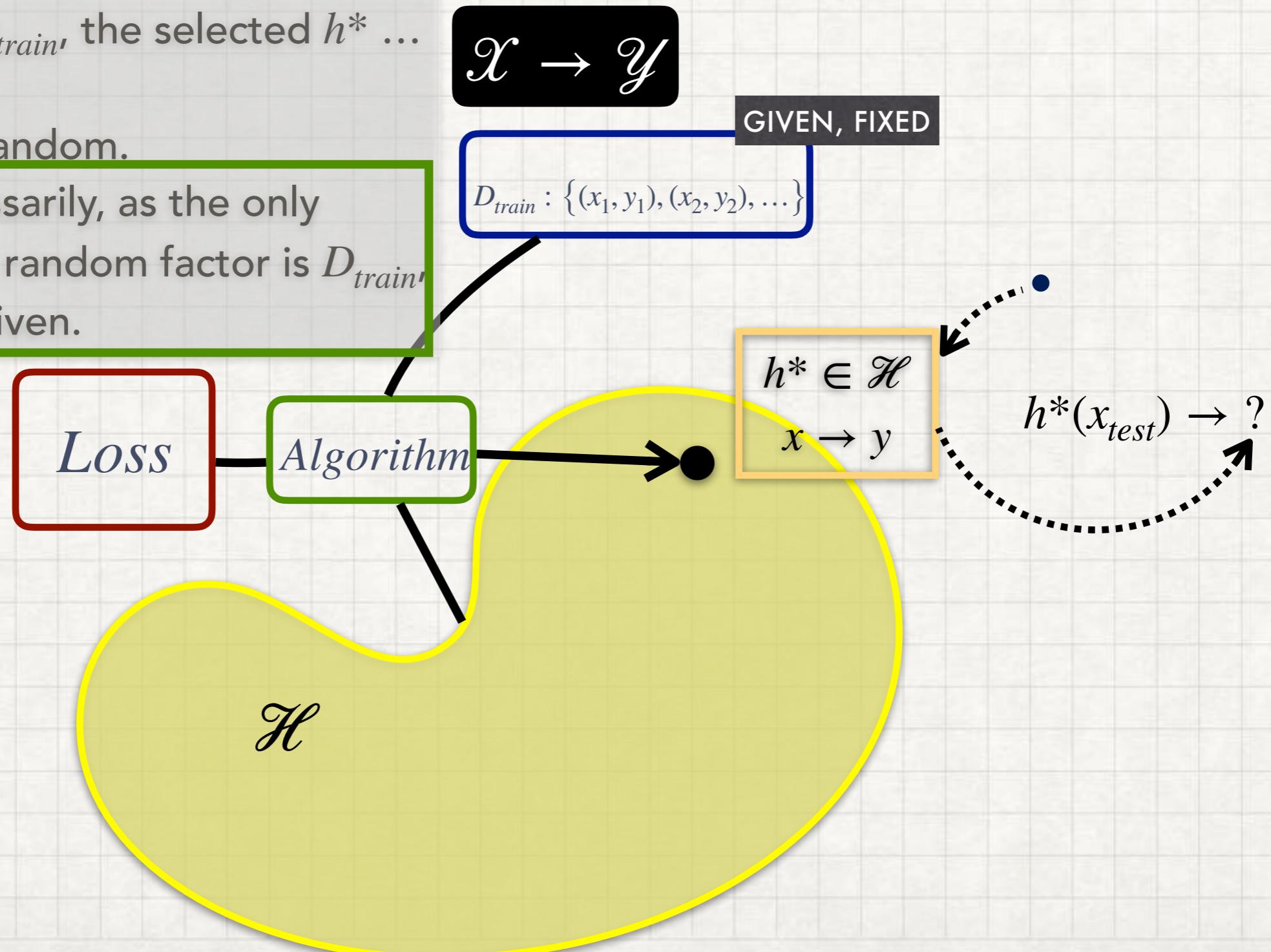
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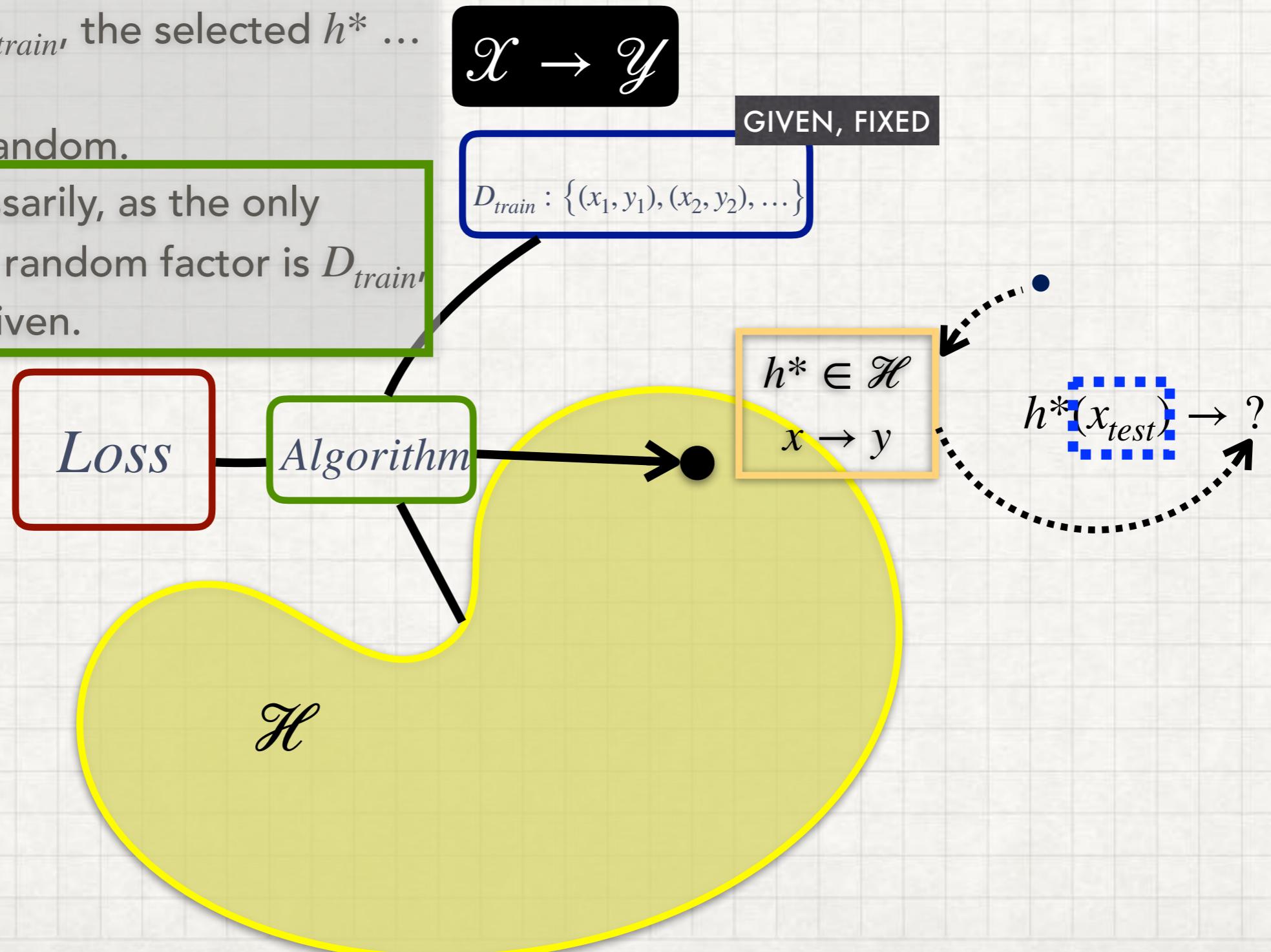
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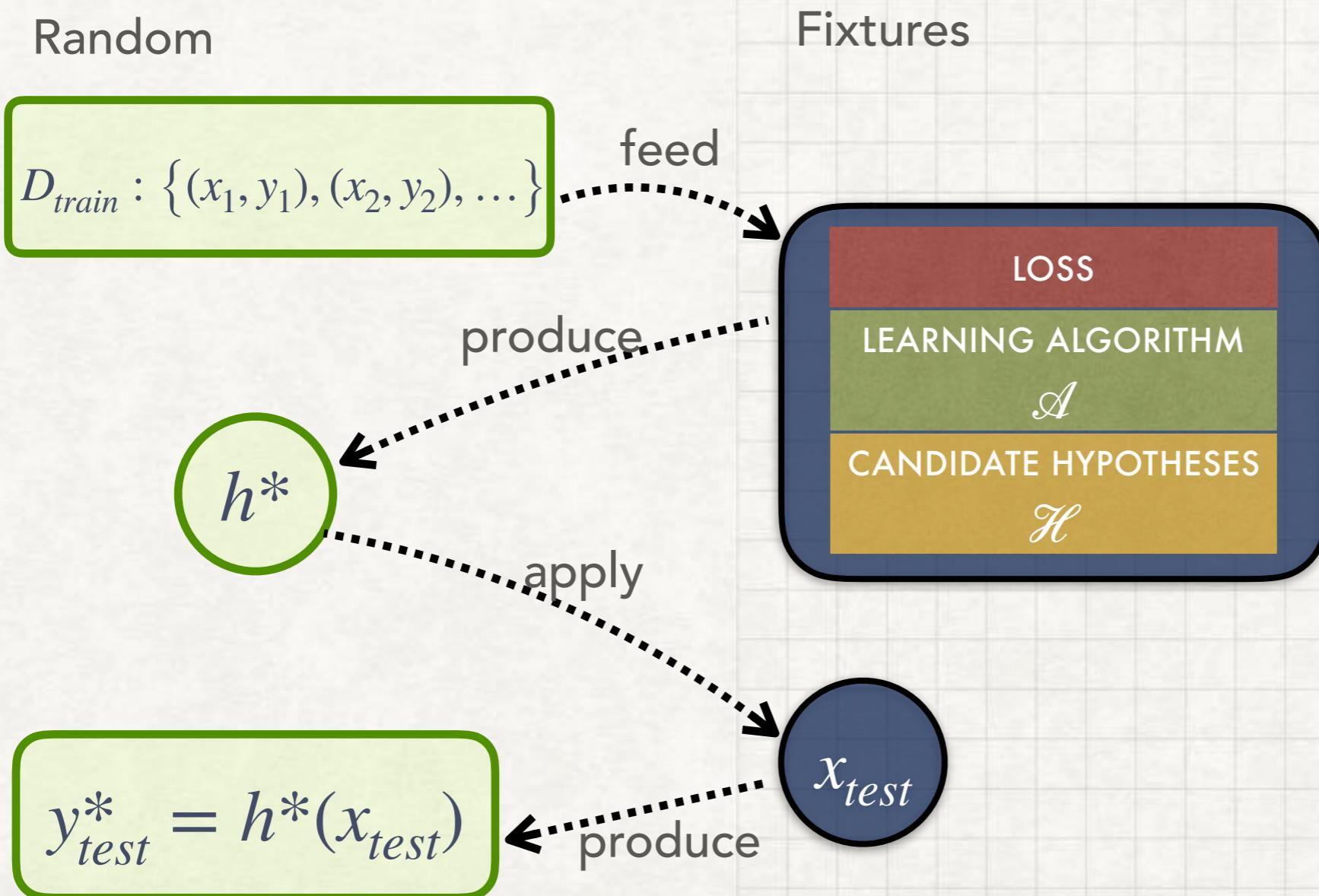
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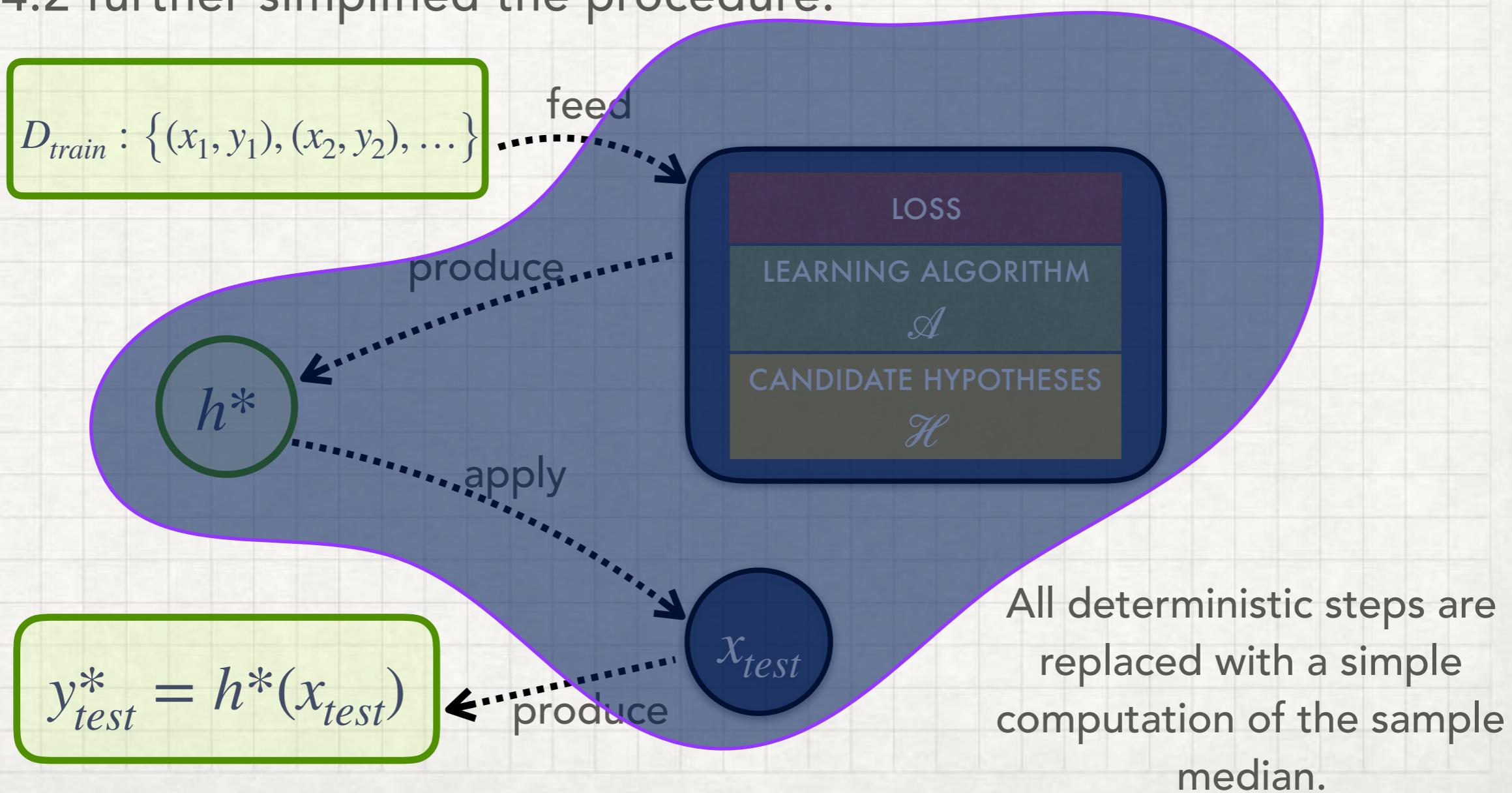
# RANDOMISATION ANALYSIS

- The only factor that is inevitably random is the data sample  $D_{train}$ , so the final result of the following flow is random.



# NOTEBOOK STUDY

- 4.2 and 4.3, Skip the “bootstrapping” parts (the notebook contains Python implementation, which must respect the structure of the contents, rather than the progress of ideas.)
  - 4.2 further simplified the procedure:

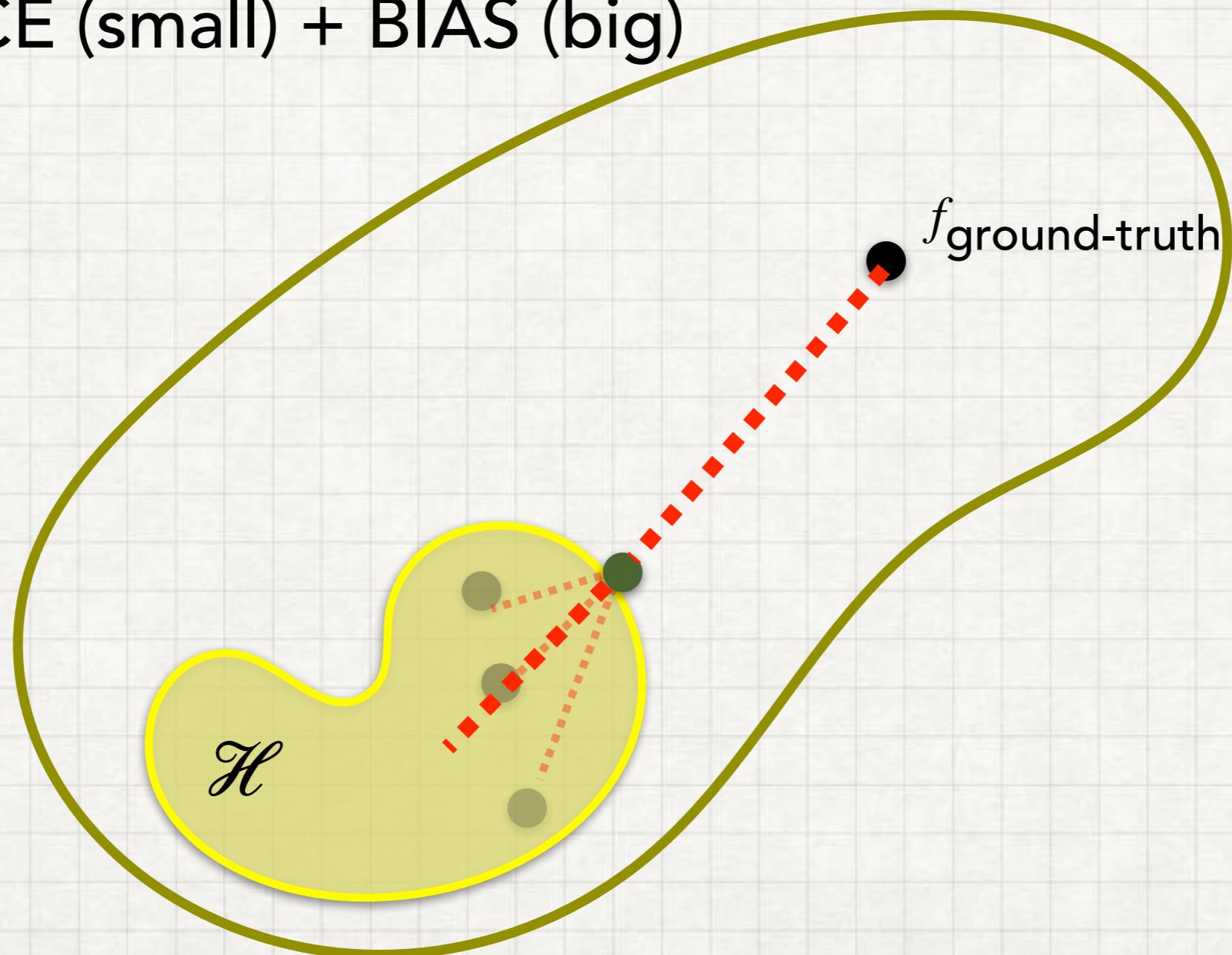


# NOTEBOOK STUDY

- 4.2 and 4.3, Skip the “bootstrapping” parts (the notebook contains Python implementation, which must respect the structure of the contents, rather than the progress of ideas.)
  - 4.2 simplify -> median computation.
  - 4.3 Experiment with the first Exercise in “Bias and Variance Explained”.

# TOTAL RISK OF A TRAINING SMALL $\mathcal{H}$

VARIANCE (small) + BIAS (big)



# TOTAL RISK OF A TRAINING

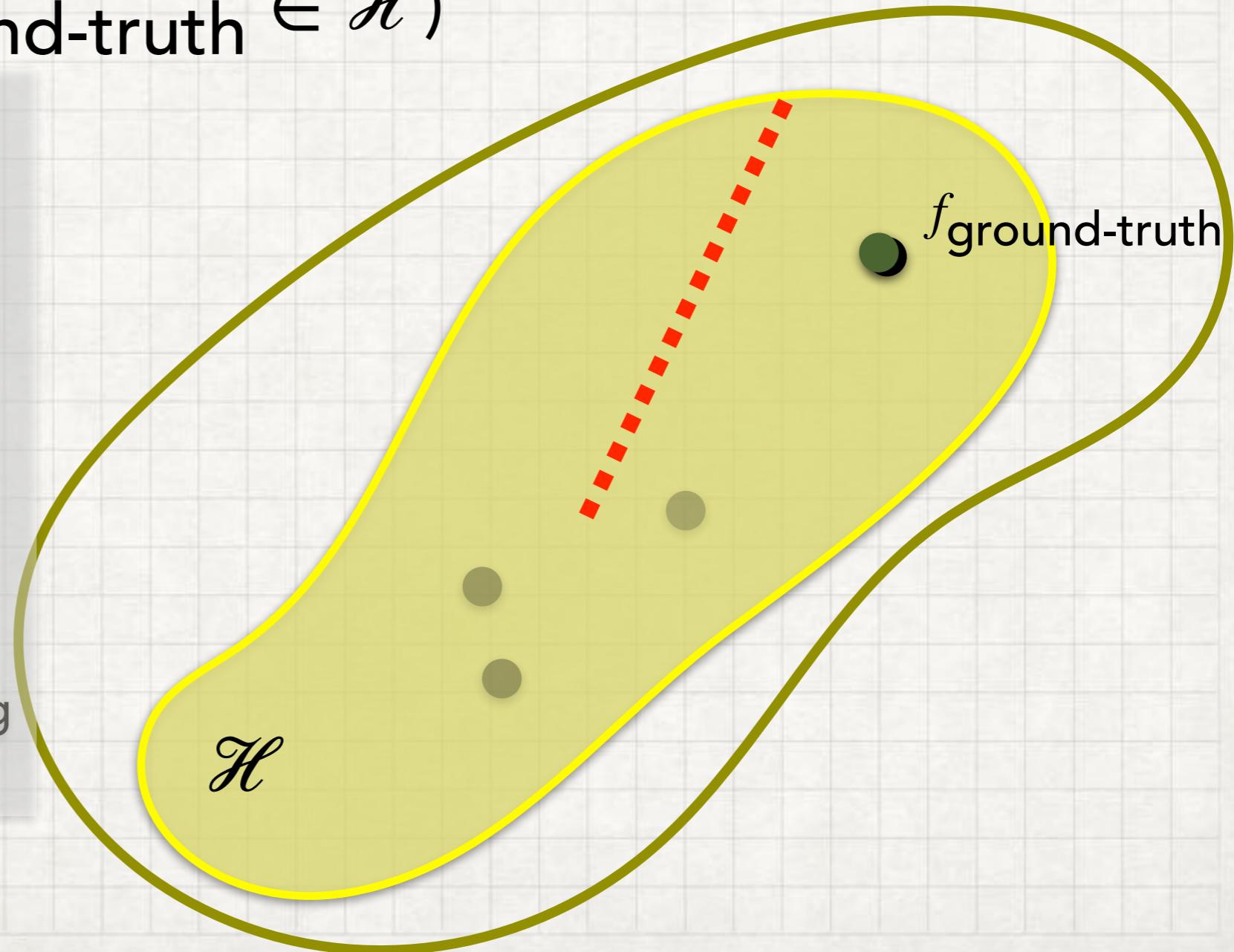
BIG  $\mathcal{H}$

VARIANCE (big) + BIAS (small/zero —

when  $f_{\text{ground-truth}} \in \mathcal{H}$ )

**Q:** Given  $\mathcal{H}$ , can we reduce the variance?

- A. No, variance is an intrinsic property of  $\mathcal{H}$ .
- B. Yes, by using less training samples, so the training result will not change as much.
- C. Yes, by using more training samples.



# TOTAL RISK OF A TRAINING

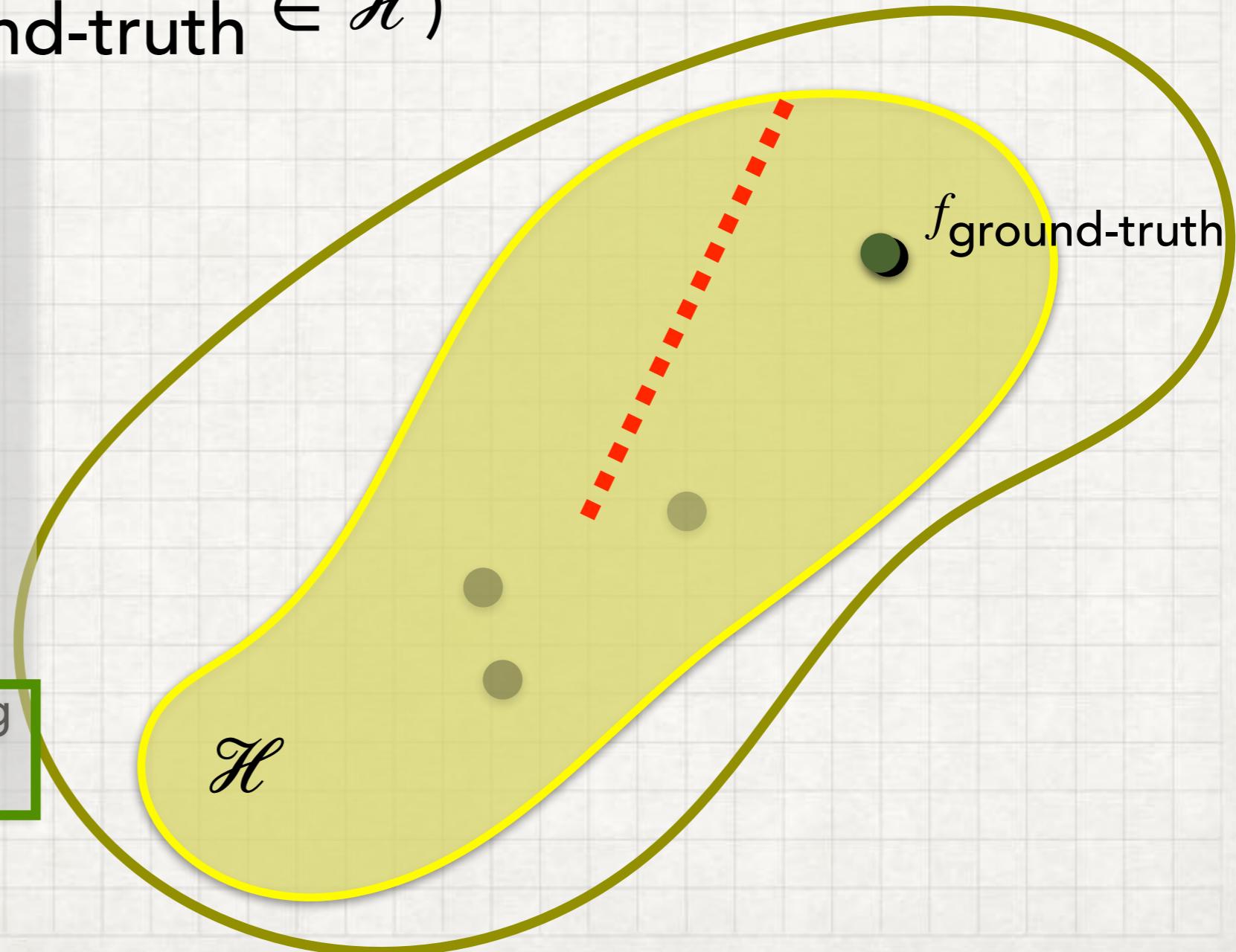
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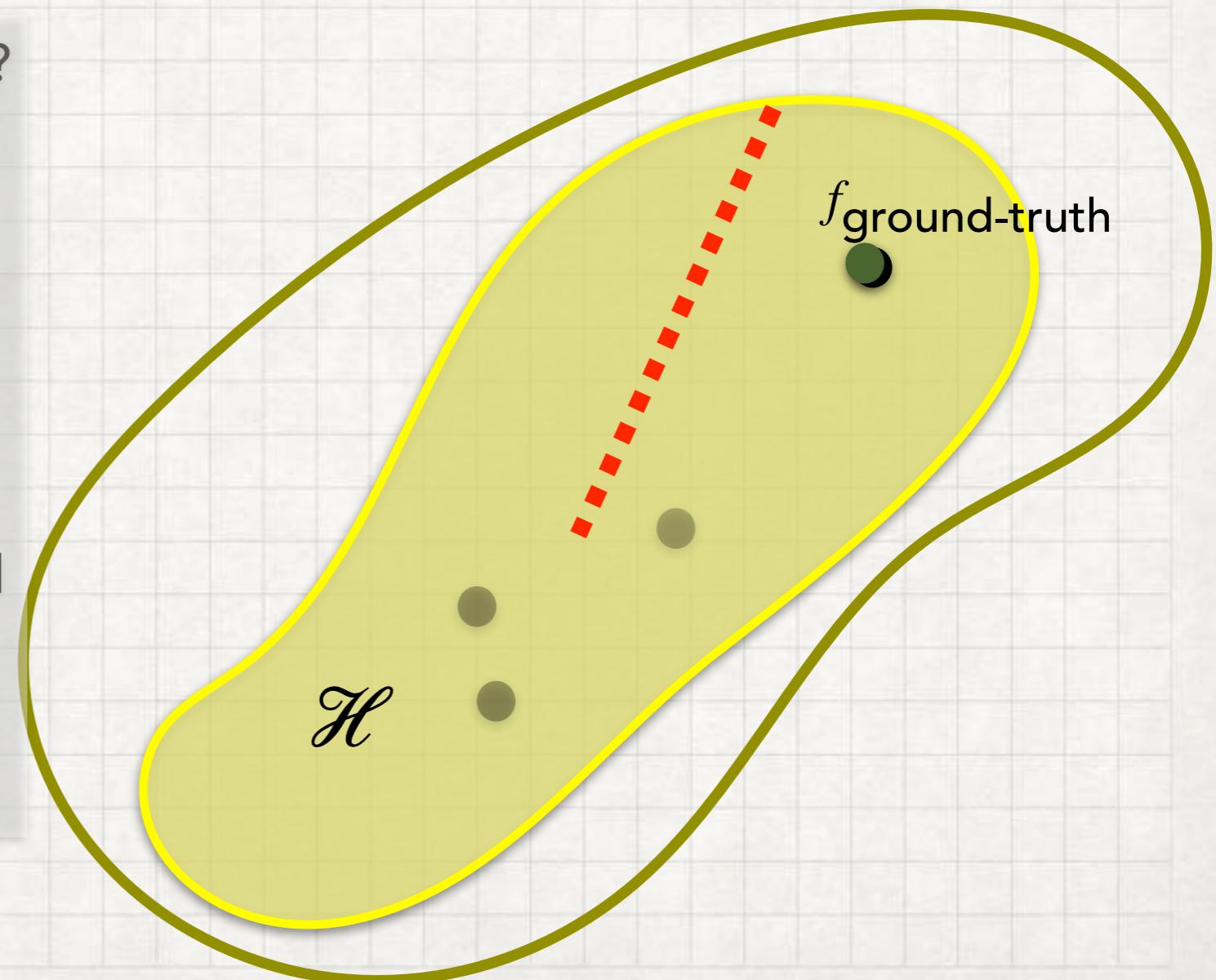


# TOTAL RISK OF A TRAINING BIG $\mathcal{H}$

VARIANCE (big) + BIAS (small/zero —  
when  $f_{\text{ground-truth}} \in \mathcal{H}$ )

**Q:** Given  $\mathcal{H}$ , can we reduce the **bias**?

- A. Very little, bias is an asymptotical property of  $\mathcal{H}$ , can not be easily changed by providing more training samples.
- B. Yes, by using less training samples, so the training result will not change as much.
- C. Yes, by using more training samples.



# TOTAL RISK OF A TRAINING

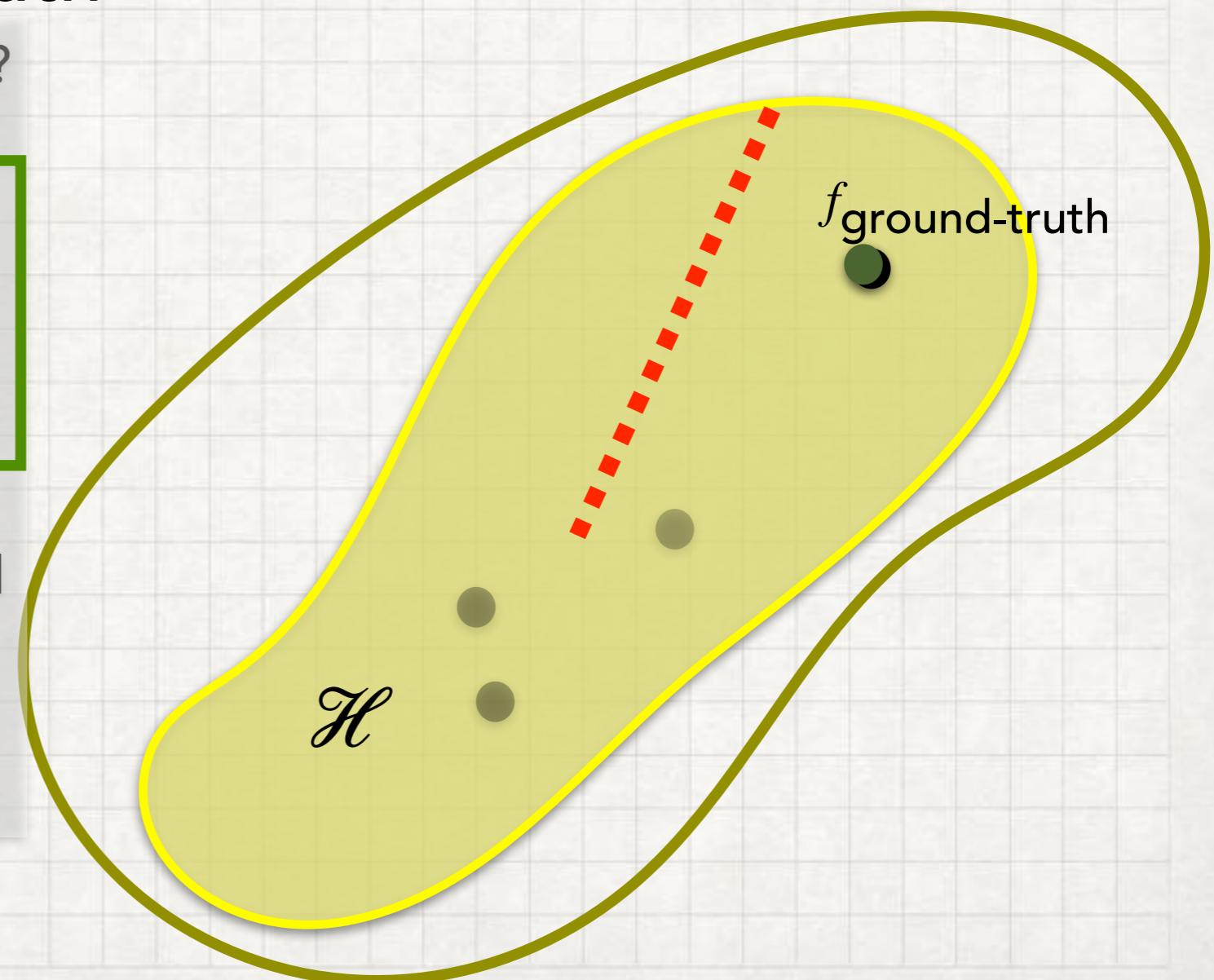
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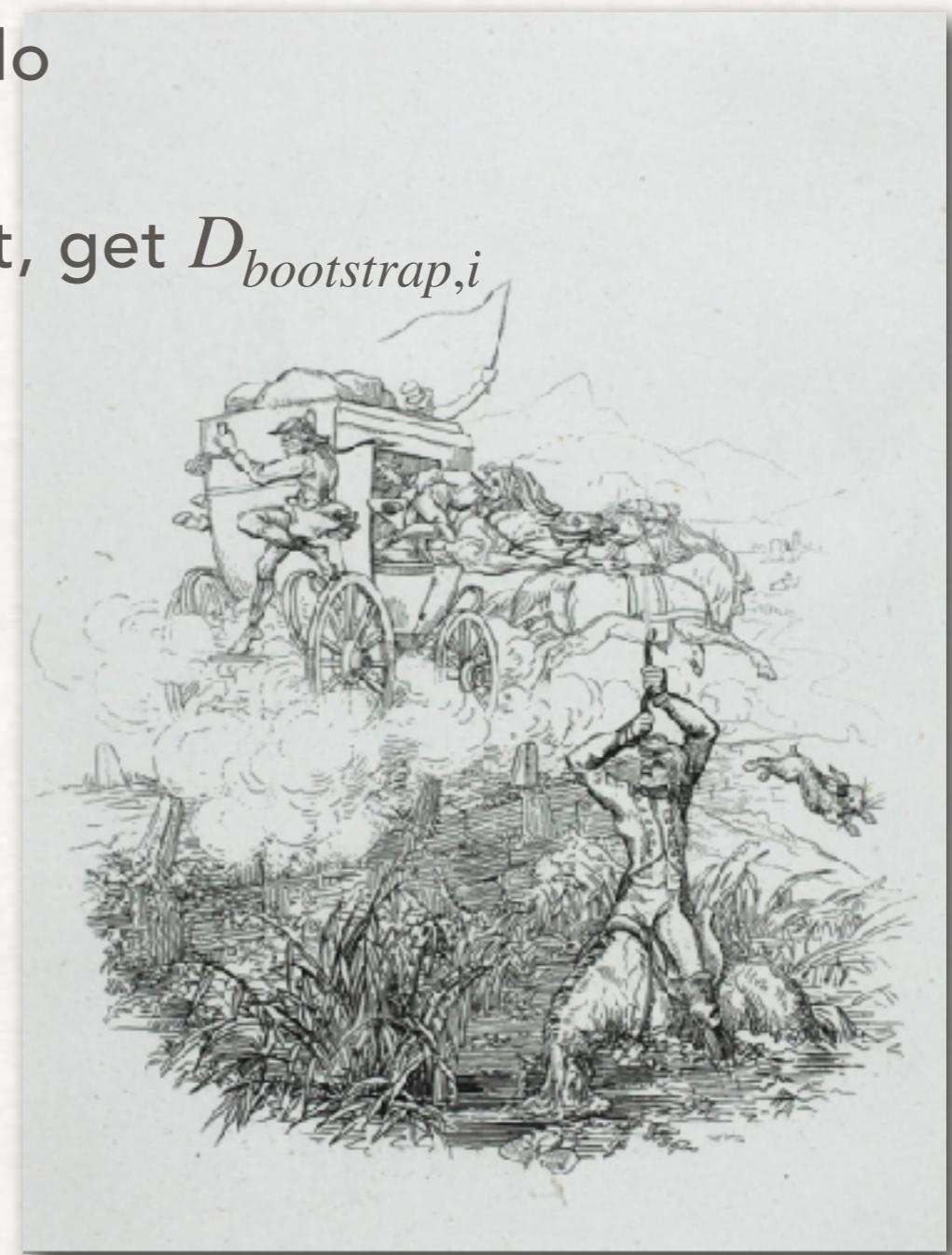
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- C. Yes, by using more training samples.



# MOD3: ASSESSING AND ADDRESSING VARIANCE USING A SINGLE $D_{train}$

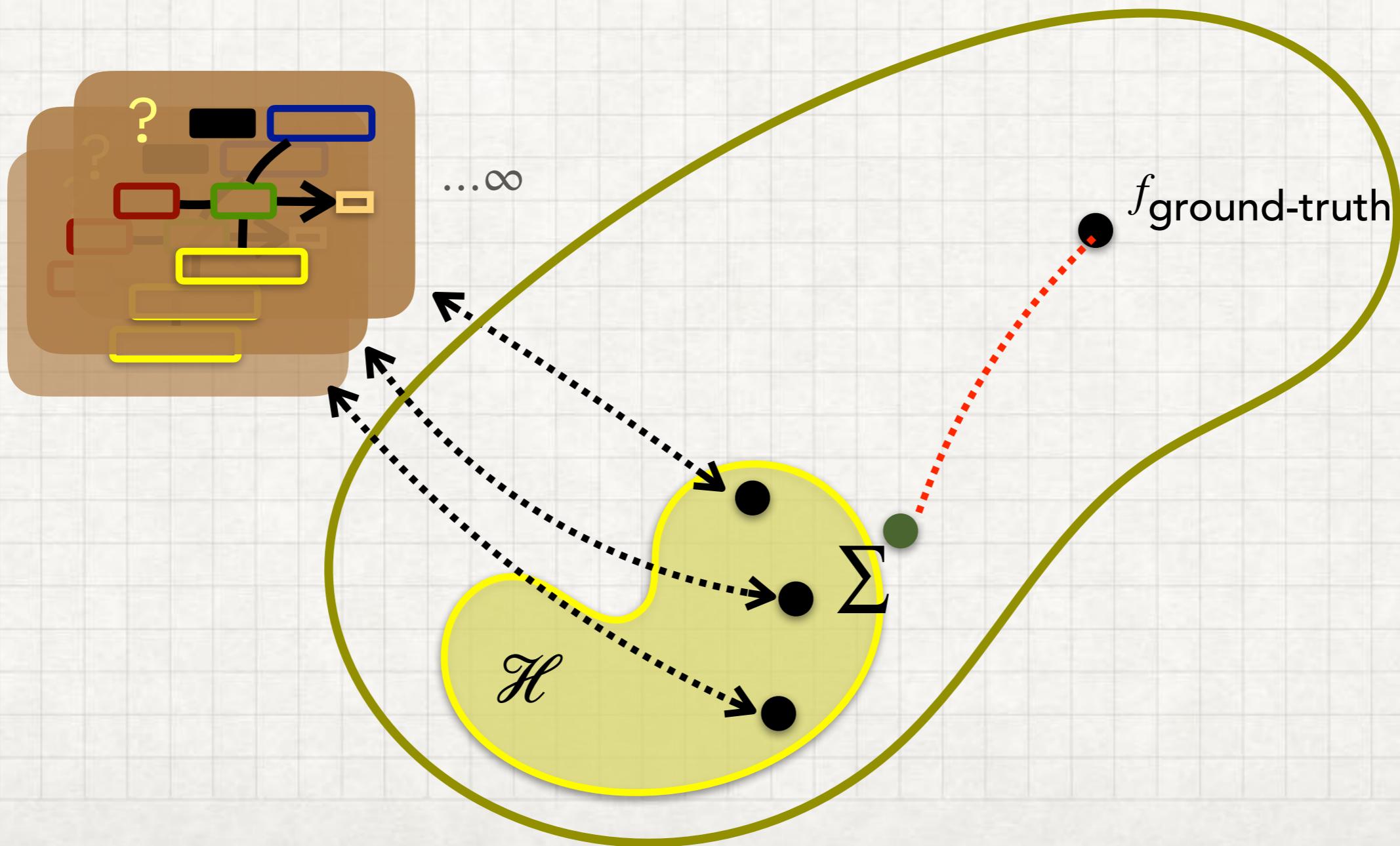
# REVIEW: BOOTSTRAP / BAGGING

- IN: Data  $D_{train}$ , Model Family and Learning Method
- Repeat \$bootstrap-number times: do
  - Re-sample  $D_{train}$  with replacement, get  $D_{bootstrap,i}$
  - Train model, get  $h_i^B$
- Prediction: Aggregate  $h_i^B(x_{test})$ 's



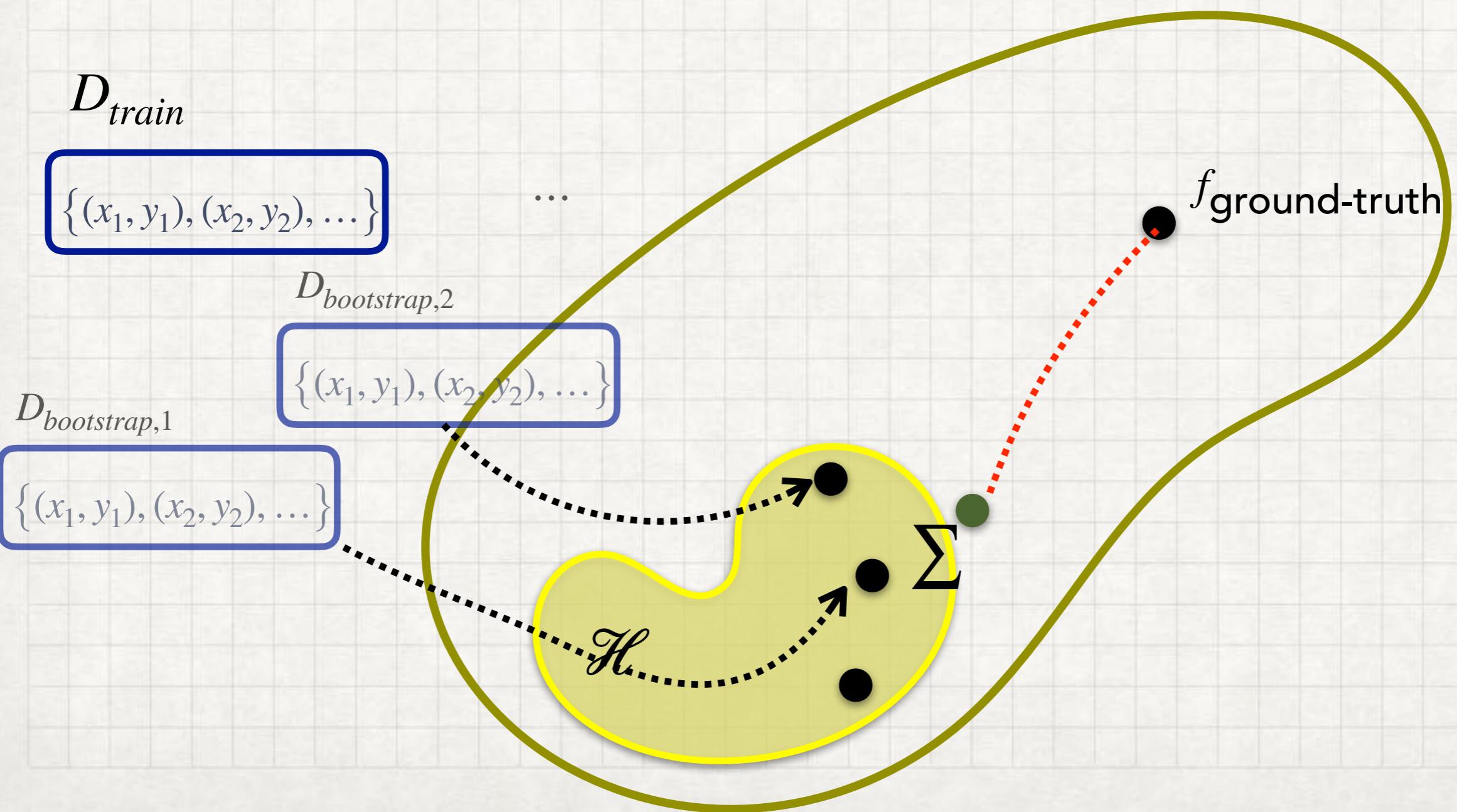
# BAGGING IS AN ATTEMPT TO ACHIEVE “INFINITE” MODEL AVERAGING

- The bootstrap samples are used to assess statistical information and reduce the variance due to the randomisation of  $D_{train}$



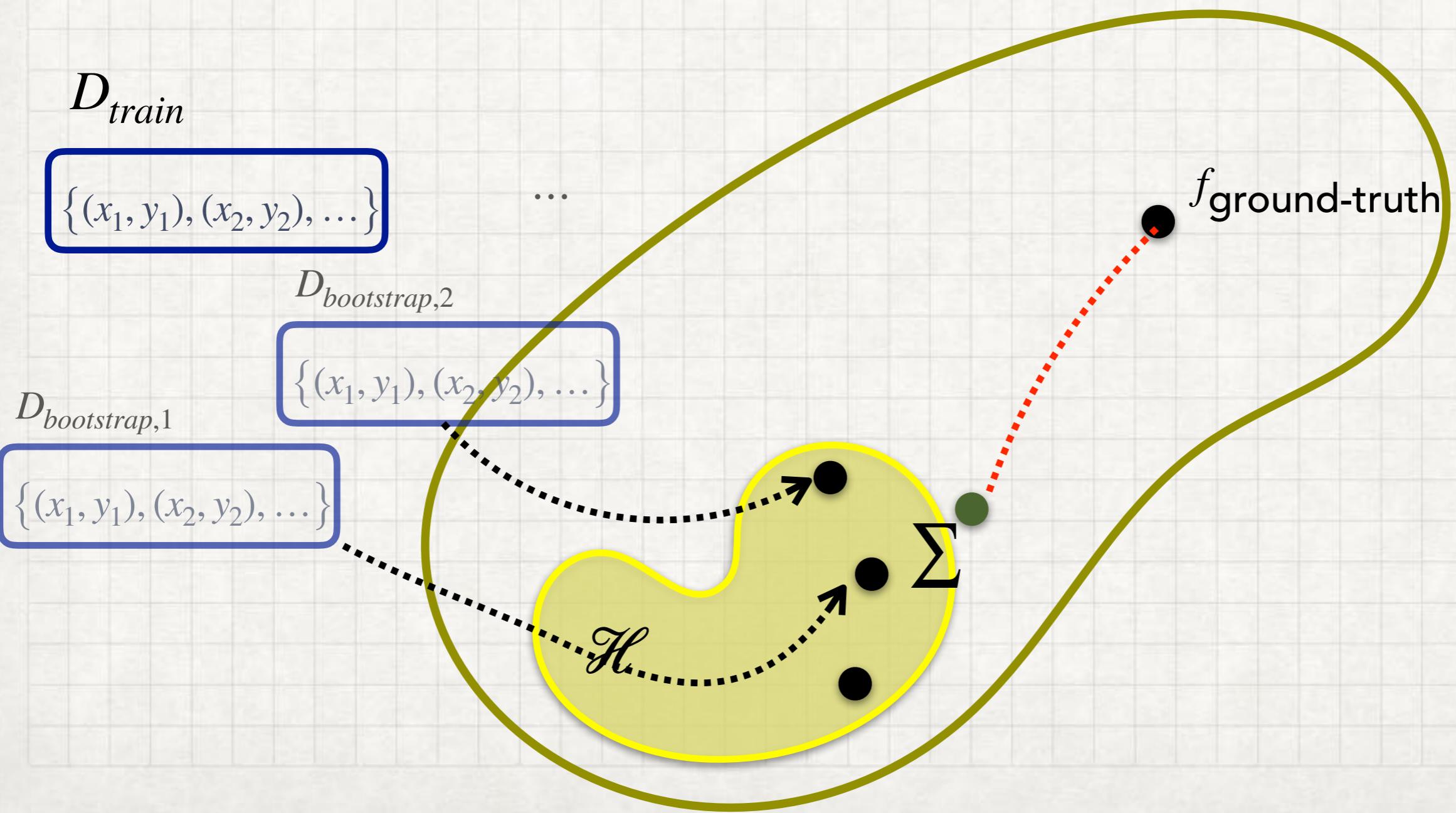
# BOOTSTRAP SAMPLES

- The bootstrap samples are used to assess statistical information and reduce the variance due to the randomisation of  $D_{train}$



# BOOTSTRAP: FREE LUNCH?

- Bootstrap cannot change the bias. But it can reduce variance given right settings at the cost of computation.



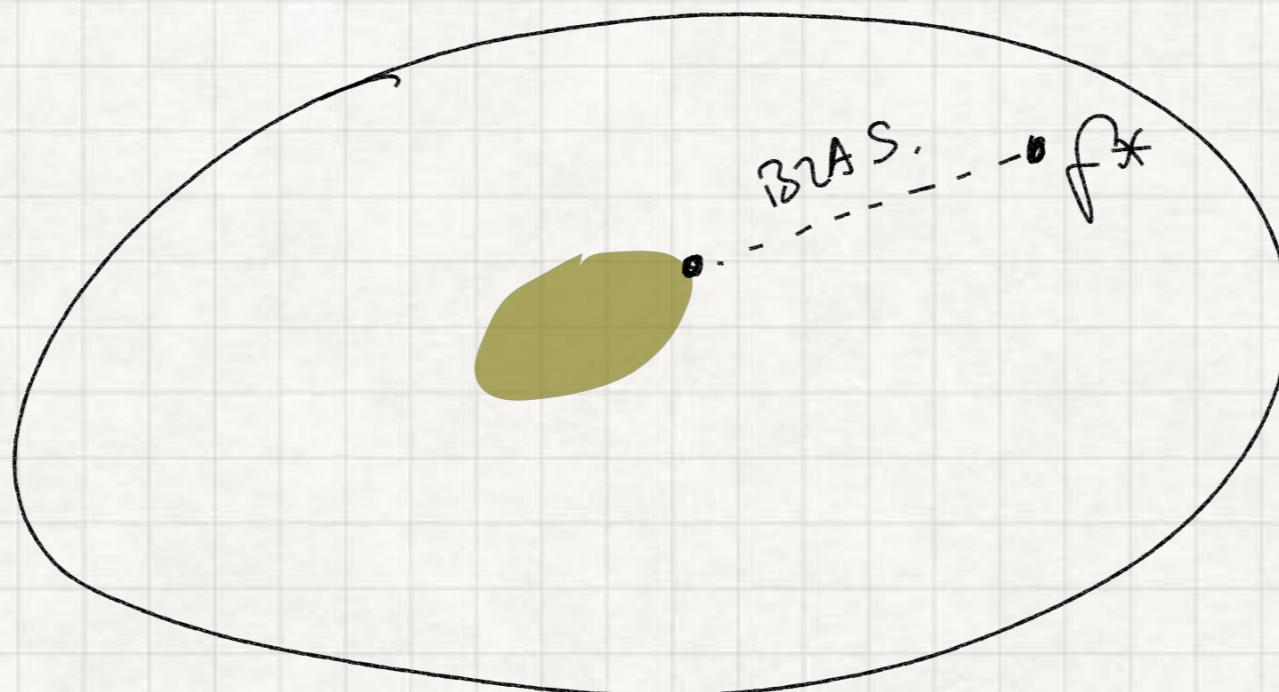
# NOTEBOOK STUDY

- 4.2 “bootstrap” parts
  - What is bootstrap samples.
  - Experiment and contemplate: For the estimation of median from samples, how bootstrap (resampling) helps reduce variance.
- 4.3 Observe Bias and Variance in sample model (if not done in the previous notebook study).
- 4.4 Bootstrap helps reduce variance in some settings.

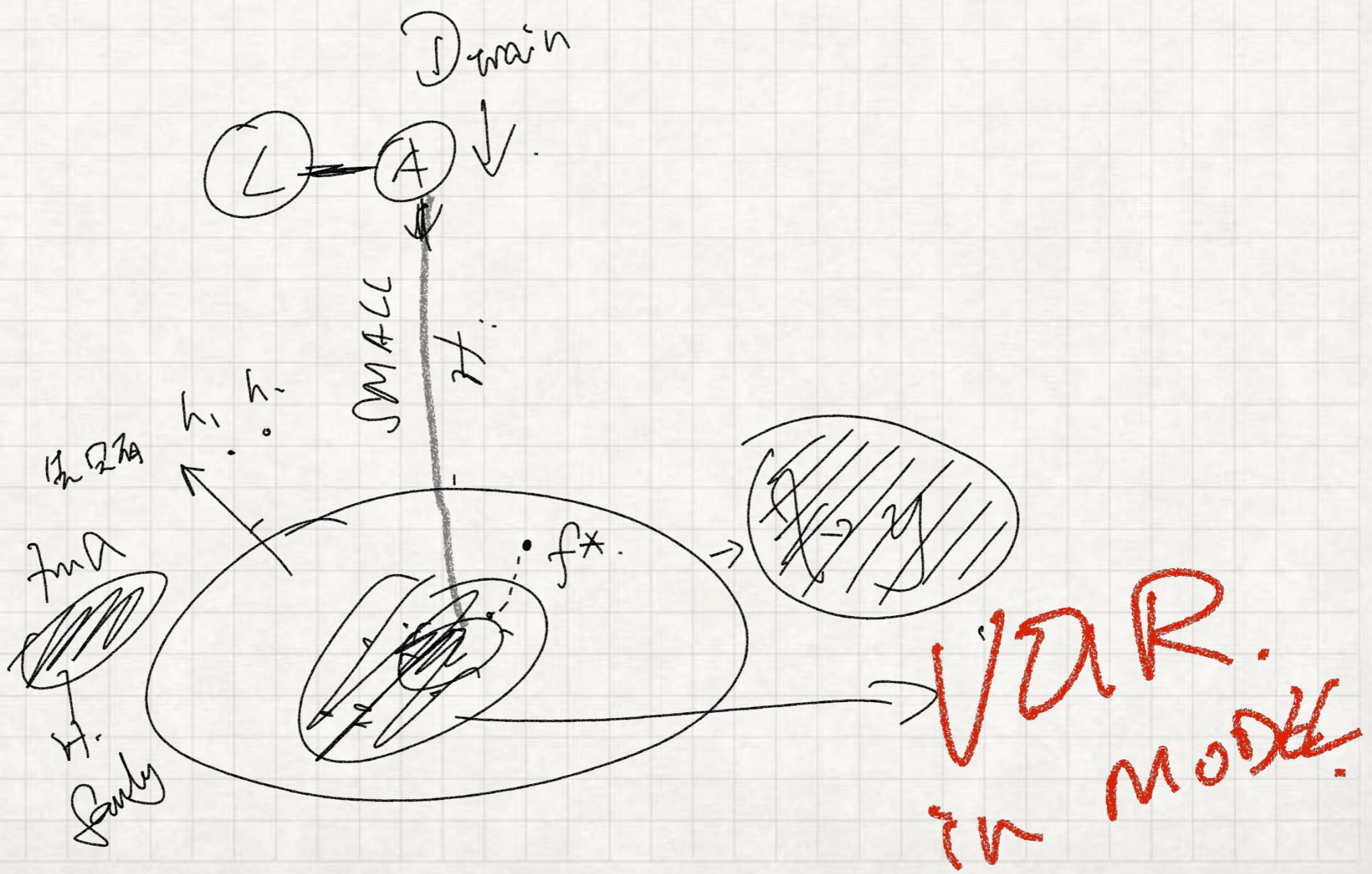
**THANKS**

# WHAT WE HAVE LEFT?

- observation noise
- Training capability — partially why neural network works.



# VARIANCE: BIG $\mathcal{H}$ , BIG VARIANCE



# NOTEBOOK TIME

- Compare bias/variance of two models

