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Operating Systems and Concurrency

Lecture 9:
Concurrency

University of Nottingham,
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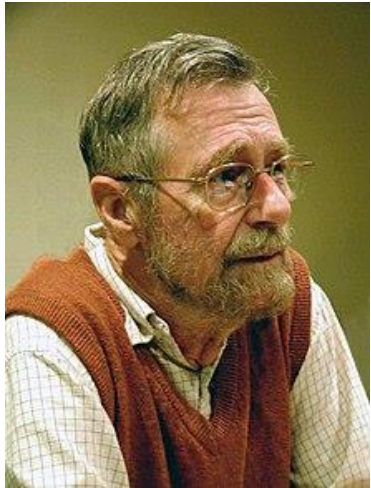
- Software approaches: Peterson's solution
- Hardware approaches:
 - Disabling interrupts
 - test_and_set()
 - compare_and_swap()
- OS Approach: Mutex



- OS approach
 - Semaphores
 - Implementation approaches
 - Examples
 - Difficulties and challenges
 - Producer/consumer problem

OS approaches

Semaphores



- Proposed by **Edsger Dijkstra**, is a technique to manage a concurrent process by using a simple **integer value**, which is known as a **semaphore**.
- A Semaphore **S** is an integer variable that, **apart from initialization**, is accessed only through **two** standard **atomic operations**: **wait()** and **signal()**
 - **wait()** → **p** [from the Dutch word **proberen**, which means “to test”]
 - Is called when a resource is **acquired**, the counter is decremented.
 - This operation is used when a process wants to access a shared resource.
 - **Signal()** → **v** [from the Dutch word **verhogen**, which means “to increment”]
 - Is called when a resource is **released**, **the counter is incremented**.
 - This operation is used when a process **has finished using a resource and releases it**, allowing other waiting processes to access it.


```
typedef struct {  
    int value;  
    struct process * list;  
} semaphore;
```

Figure: Conceptual definition of a semaphore

```
wait(semaphore * S) {  
    S->value--;  
    if(S->value < 0) {  
        add process to S->list  
        block(); // system call  
    }  
}
```

```
signal(semaphore * S) {  
    S->value++;  
    if(S->value <= 0) {  
        remove a process P from S->list;  
        wakeup(P); // system call  
    }  
}
```

Figure: Conceptual implementation of a acquire() and post()

- **wait() (P or acquire):**
 - S->value--: **Decrements** the semaphore value.
 - If the value is still ≥ 0 , the process can **proceed because resources are available**.
 - S->value < 0: If the semaphore value goes below 0, it means **no more resources are available, so the process must wait**.
 - The process is then **added to a waiting list**, and **it is blocked (suspended) until resources become available**.



OS approaches (cont.)

Semaphores: Process Blocking in wait()

- Decrement the **counter** ($S \rightarrow \text{value}--$).
- Check if the counter is negative ($S \rightarrow \text{value} < 0$):
 - **If yes**, the process cannot proceed, so:
 - The process is added to the **blocked queue** (often called the **semaphore's waiting list**).
 - The process's state is changed from **running** to **blocked**, indicating it cannot execute further.
 - A system call like **block()** is invoked to **suspend the process**, transferring control to the OS scheduler.
- The operating system is responsible for **managing blocked processes**. When a process is blocked, it's removed from the CPU, and the scheduler selects **another process to run**.
- This ensures **no busy waiting occurs** (i.e., the CPU isn't wasting cycles by constantly checking the semaphore).

Semaphores

OS approaches (cont.)

```
typedef struct {  
    int value;  
    struct process * list;  
} semaphore;
```

Figure: Conceptual definition of a semaphore

```
wait(semaphore * S) {  
    S->value--;  
    if(S->value < 0) {  
        add process to S->list  
        block(); // system call  
    }  
}
```

```
signal(semaphore * S) {  
    S->value++;  
    if(S->value <= 0) {  
        remove a process P from S->list;  
        wakeup(P); // system call  
    }  
}
```

Figure: Conceptual implementation of a acquire() and post()

- **signal() (V or release):**
 - S->value++: Increments the semaphore value. This indicates that a resource **has been released or made available**.
 - S->value <= 0: If there are processes waiting (S->value is ≤ 0), one process is removed from the waiting list, and **it is woken up to continue execution**.



OS approaches (cont.)

Semaphores: Semaphore Types

- **Binary Semaphore (Mutex):** This type of semaphore has a value of **either 0 or 1**. It is typically used for **ensuring mutual exclusion in critical sections** where only one process can access a resource at a time.
- **Counting Semaphore:** This type of semaphore can have any **non-negative integer value**. It is used to **control access to a resource that has multiple instances** (e.g., a pool of connections).
 - It is generally used in situations where there are **multiple identical resources**, such as **a pool of database connections**, a set of shared memory buffers, or a thread pool.
 - The semaphore's value is initialized to the number of available resources.
 - E.g., if there are 5 instances of a shared resource, the semaphore is initialized with a value of 5.



OS approaches (cont.)

Semaphores: counting semaphore wait() Operation (Requesting a Resource)

- Initialization: its value represents the number of available resources.
 - E.g, $S = 5$ means that 5 resources are available.
- Decrement the **counter** ($S \rightarrow \text{value}--$).
- Check if the counter is negative ($S \rightarrow \text{value} < 0$):
 - **If yes**, the process cannot proceed, so:
 - The process is added to the **blocked queue** (often called the **semaphore's waiting list**).
 - The process's state is changed from **running** to **blocked**, indicating it cannot execute further.
 - A system call like **block()** is invoked to **suspend the process**, transferring control to the OS scheduler.



OS approaches (cont.)

Semaphores: counting semaphore signal() Operation (Releasing a Resource)

- signal() Operation (Releasing a Resource):
 - $S \rightarrow \text{value}++$: Increments the semaphore value. This indicates that a resource has been released or made available.
 - $S \rightarrow \text{value} \leq 0$: If there are processes waiting ($S \rightarrow \text{value}$ is ≤ 0), one process is removed from the waiting list, and it is woken up to continue execution.
- If the value was non-negative, the resource count is simply incremented without waking up any processes.



OS approaches (cont.)

Semaphores: Behavior of Counting Semaphores

- **Positive Semaphore Value ($S > 0$):** This indicates the number of resources that are still available for use. A process can proceed immediately when calling `wait()`.
- **Zero Semaphore Value ($S == 0$):** All resources are currently in use. Any process that attempts to `wait()` on the semaphore at this point will block, as no resources are available.
- **Negative Semaphore Value ($S < 0$):** A negative semaphore value represents the number of processes that are **blocked**, waiting for resources.
 - E.g., if $S == -3$, it means there are 3 processes waiting for resources to become available.



- **Resource Management:** Counting semaphores are ideal for managing access to pools of resources where there are multiple instances, such as:
 - **Database connections** in a connection pool.
 - **Shared memory buffers** in a buffer pool.
 - **Thread pools**, where multiple worker threads can be available to handle concurrent tasks.
- Counting semaphores are often used to **limit the level of concurrency in tasks**. For instance, they can limit the number of concurrent readers or writers in a system.
- Using a counting semaphore to manage a pool of resources allows the operating system to **automatically handle synchronization** by **blocking** processes when resources are unavailable and **waking** them when resources become available, **ensuring processes can access resources as soon as they are free**.
- **But, does not enforce mutual exclusion.**



Semaphores Implementation...

Thread 1

```
...  
wait(&s) 1 => 0  
...  
...  
...  
post(&s)  
...  
...  
...  
...  
...  
...
```

Thread 2

```
...  
...  
...  
wait(&s)  
...  
(wakeup)  
...  
...  
post(&s)  
...  
...  
...
```

Thread 3

```
...  
...  
...  
...  
wait(&s)  
...  
...  
...  
(wakeup)  
...  
post(&s)  
...  
...
```

Figure: Semaphore example

Semaphores Implementation...

Thread 1

```
...  
wait(&s)  
...  
...  
...  
post(&s)  
...  
...  
...  
...  
...  
...
```

Thread 2

```
...  
...  
...  
wait(&s) 0 => -1  
...  
(wakeup)  
...  
...  
post(&s)  
...  
...  
...
```

Thread 3

```
...  
...  
...  
...  
wait(&s)  
...  
...  
...  
(wakeup)  
...  
post(&s)  
...  
...
```

Figure: Semaphore example

Semaphores Implementation...

Thread 1

```
...  
wait(&s)  
...  
...  
...  
post(&s)  
...  
...  
...  
...  
...  
...
```

Thread 2

```
...  
...  
...  
wait(&s)  
...  
(wakeup)  
...  
...  
post(&s)  
...  
...  
...
```

Thread 3

```
...  
...  
...  
...  
wait(&s) -1 => -2  
...  
...  
...  
(wakeup)  
...  
post(&s)  
...
```

Figure: Semaphore example

Semaphores Implementation

Thread 1	Thread 2	Thread 3
...
wait(&s)
...
...	wait(&s)	...
...	...	wait(&s)
post(&s) -2 => -1	(wakeup)	...
...
...
...	post(&s)	(wakeup)
...
...	...	post(&s)
...

Figure: Semaphore example

Semaphores Implementation

Thread 1	Thread 2	Thread 3
...
wait(&s)
...
...	wait(&s)	...
...	...	wait(&s)
post(&s)	(wakeup)	...
...
...
...	post(&s) -1 => 0	(wakeup)
...
...	...	post(&s)
...

Figure: Semaphore example

Semaphores Implementation

Thread 1

```
...  
wait(&s)  
...  
...  
...  
post(&s)  
...  
...  
...  
...  
...  
...
```

Thread 2

```
...  
...  
...  
wait(&s)  
...  
(wakeup)  
...  
...  
post(&s)  
...  
...  
...
```

Thread 3

```
...  
...  
...  
...  
wait(&s)  
...  
...  
...  
(wakeup)  
...  
post(&s) 0 => 1  
...
```

Figure: Semaphore example



OS Solution

Semaphores: requirements

- **Mutual Exclusion:** Semaphores (especially binary semaphores or mutexes) **effectively ensure mutual exclusion**.
- **Progress:** Semaphores generally **ensure progress**, but the **system's queueing strategy** plays a role in ensuring fairness.
- **Bounded Waiting:** Semaphores **do not inherently ensure bounded waiting**. Additional fairness mechanisms are needed to prevent starvation.

- Semaphores within the same process can be declared as global variables of the type `sem_t`
 - `sem_init()` initialises the value of the semaphore
 - `sem_wait()` decrements the value of the semaphore
 - `sem_post()` increments the values of the semaphore
- An explanation of any of these functions can be found in the man pages (<https://linux.die.net/man>), e.g. by typing `man sem_init` on the Linux command line

Semaphores in Linux

Example

```
// includes here, e.g. semaphore.h
sem_t s;
int sum=0;
void * calc(void * number_of_increments)
{ int i;
  for(i=0; i<*((int*) number_of_increments);i++)
  { sem_wait(&s);
    sum++;
    sem_post(&s);
  }
}
void main()
{ int iterations = 50000000;
  pthread_t tid1,tid2;
  sem_init(&s,0,1);

  pthread_create(&tid1, NULL, calc, (void *) &iterations);
  pthread_create(&tid2, NULL, calc, (void *) &iterations);
  pthread_join(tid1,NULL);
  pthread_join(tid2,NULL);
  printf("The value of sum is: %d\n", sum);
}
```

Output:

The value of sum is: 100000000



OS Solution

Semaphores: Advantage

- Simple and efficient for basic synchronization tasks.
- No busy waiting (processes can be blocked until they are allowed to proceed).
- Can be used for both mutual exclusion and complex synchronization.

Caveats Potential Difficulties (Disadvantage)

- **Indefinite blocking or starvation**, a situation in which processes wait indefinitely **within the semaphore**.
 - May occur if we remove processes from the list associated with a semaphore in **LIFO (last-in, first-out) order**.
- **Deadlock**: A situation where two or more processes are **waiting indefinitely** for an event that can be caused only by one of the waiting processes.

- E.g. Consider P0 and P1, each accessing two semaphores, S and Q, set the value 1;
- Suppose that **P0 executes wait(S) and then P1 executes wait(Q)**.
- When P0 executes wait(Q), it must wait until P1 executes signal(Q).
- Similarly, when P1 executes wait(S), it must wait until P0 executes signal(S).
- Since these signal() operations cannot be executed, **P0 and P1 are deadlocked**.

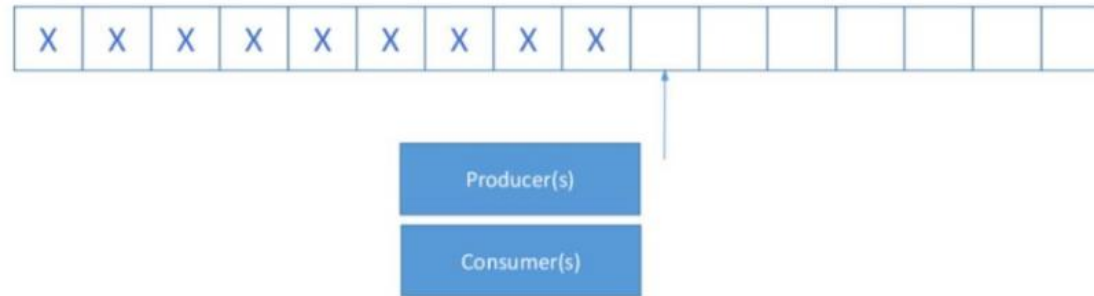
P0	P1
Wait(S);	...
...	Wait(Q);
Wait(Q);	...
...	Wait(S);
.	.
.	.
.	.
Signal(S);	...
...	Signal(Q);
Signal(Q);	...
....	Signal(S);



The Producer/Consumer Problem Description

- How Semaphore solve **Producer/Consumer** problem?
- Producer(s) and consumer(s) **share n buffers** (e.g. an array) that are capable of holding one item each (printer queue)
 - The buffer can be of **bounded** (size n) or **unbounded** size
 - There can be **one or multiple consumers** and/or **producers**
- The **producer(s)** add(s) items and **goes to sleep** if the buffer is full
- The **consumer(s)** remove(s) items and **goes to sleep** if the buffer is **empty**

The Producer/Consumer Problem Description



```
while (true) {  
    // wait until items in buffer  
    while (counter == 0); /* do nothing */  
  
    consumed = buffer[out];  
    out = (out + 1) % BUFFER_SIZE;  
    counter--;  
    /* consume the item in next consumed */  
}
```

Consumer

```
while (true) {  
    //while buffer is full  
    while (counter == BUFFER_SIZE) ; /* do nothing */  
  
    // add item when space becomes available  
    buffer[in] = new_item;  
    in = (in + 1) % BUFFER_SIZE;  
    counter++;  
}
```

Producer



The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer

- The simplest version of the problem has one producer, **one consumer**, and a **buffer of unbounded size**.
- There are two shared variables
 - A **counter (index)** variable keeps track of the number **of items in the buffer**
- It uses **two binary semaphores**:
 - **sync synchronises** access to the **buffer (counter)**, **initialised to 1**
 - **delay_consumer** ensures that the consumer goes to sleep when there are no items available, **initialised to 0**



The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer

- Semaphores:
 - **sync**: This semaphore is used to ensure mutual exclusion when accessing the shared items variable.
 - **delay_consumer**: This semaphore is used to block the consumer when there are no items available.
- Shared Variable:
 - **Counter/items**: This represents the number of items in the buffer. The producer increments this value when producing items, and the consumer decrements it when consuming items.

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0

```

void * consumer(void * p)
{
    sem_wait(&delay_consumer); 0 => -1
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0

```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync); 1 => 0
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1

```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++; 0 => 1
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1

```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
	-1	0	1
	-1	0	1

```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer); (wakeup)
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items == 0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items == 1)
            sem_post(&delay_consumer); -1 => 0
        sem_post(&sync);
    }
}

```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```
void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}
```

```
void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync); 0 => 1
    }
}
```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync); 1=> 0
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1
Enter_CS	0	0	1

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--; 1 => 0
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1
Enter_CS	0	0	1
	0	0	0

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

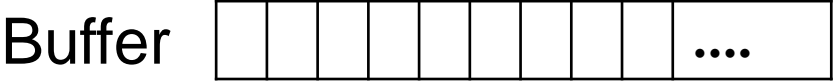
```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1
Enter_CS	0	0	1
	0	0	0
	0	0	0

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync); 0 => 1
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1
Enter_CS	0	0	1
	0	0	0
	0	0	0
Exit_CS	0	1	0

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items == 0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items == 1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1
Enter_CS	0	0	1
	0	0	0
	0	0	0
Exit_CS	0	1	0
	0	1	0

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer); 0 => -1
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1
Enter_CS	0	0	1
	0	0	0
	0	0	0
Exit_CS	0	1	0
	0	1	0
C_blocked	-1	1	0

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0

```
void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}
```

```
void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync); 1 => 0
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}
```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1

```
void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}
```

```
void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++; 0 => 1
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}
```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1

```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
	-1	0	1
	-1	0	1

```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync);
    }
}

```

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```
void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer); (wakeup)
    }
}
```

```
void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer); -1 => 0
        sem_post(&sync);
    }
}
```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Wakeup_C	0	0	1

Figure: Single producer/consumer with unbounded buffer

The Producer/Consumer Problem

One Consumer, One Producer, Unbounded Buffer (First Attempt)



```

void * consumer(void * p)
{
    sem_wait(&delay_consumer);
    while(1)
    {
        sem_wait(&sync);
        items--;
        printf("%d\n", items);
        sem_post(&sync);
        if(items==0)
            sem_wait(&delay_consumer);
    }
}

```

```

void * producer(void * p)
{
    while(1)
    {
        sem_wait(&sync);
        items++;
        printf("%d\n", items);
        if(items==1)
            sem_post(&delay_consumer);
        sem_post(&sync); 0 => 1
    }
}

```

Action	delay_cons=0	Syn=1	Item=0
C_blocked	-1	1	0
Enter_CS	-1	0	0
	-1	0	1
	-1	0	1
	-1	0	1
Weakup_C	0	0	1
Exit_CS	0	1	1

Figure: Single producer/consumer with unbounded buffer



- Modern Operating Systems (Tanenbaum): **Chapter 2(2.3.5)**
- **Operating System Concepts (Silberschatz): Chapter 6(6.6)**
- Operating Systems: Internals and Design Principles (Starlings):
Chapter 5(5.3)