# Bayesian Neural Networks

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#### Talk Outline

- 1. Why should we care?
- 2. Brief review and derivation of background info
  - a. Vanilla Neural Network review
  - b. Bayes' Rule
- 3. Bayesian Neural Networks overview
- 4. Variational Inference
  - a. KL Divergence and some key results
  - b. ELBO objective
- 5. Pseudocode
- 6. Code demo + results
- 7. Future plans

## Primary References

Blundell, C., Cornebise, J., Kavukcuoglu, K., & Wierstra, D.. (2015). Weight uncertainty in neural networks. *Proceedings of the 32nd International Conference on International Conference on Machine Learning - Volume 37 (ICML'15)*. JMLR.org, 1613–1622.

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## Why are we interested?

- Rhys
  - Interested in novel quantitative models with applications to finance
- Liyi
  - Been working on both Bayesian statistics and neural networks. Interested in seeing examples how they come together.
- Arian
  - Interested in Artificial Intelligence and what the future will hold with such powerful technology!

## Why a Bayesian approach?

- Easier to estimate uncertainty than in standard DL
  - Standard DL weights are point estimates
  - Bayesian NN automatically encapsulates uncertainty in estimation
  - Models 'know when they don't know'
- A natural marginalization effect, or ensemble learning
- More robust to overfitting
  - o 'Occam' factor
- Less data hungry than standard DL techniques
- Comparable predictive performance to standard without significant increase in computational complexity
  - However, training is sensitive to factors such as initialization

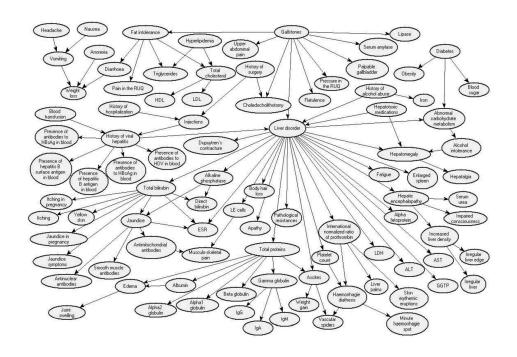
#### Potential Applications

#### • Good where:

- Even one mistake is costly
- Data collection is impractical
- o Data is noisy
- One class is oversampled

#### • Fields of Interest:

- Medical Diagnosis
- Financial asset forecasting
- Fraud detection
- Computer vision



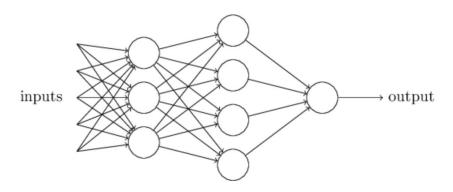
Onisko, Druzdel & Wasyluk (1999) - A Bayesian Network Model for Diagnosis of Liver Disorders

#### Current State of BNN

- Still not very prevalent in industry
- Improvements in variational inference
  - Decreases in computational complexity
- Significant research interest
  - DL community is interested in more robust, randomness-injected models
  - E.g. NeurIPS workshop: Bayesian Deep Learning
- Increasing community support
  - Open source software packages
  - Implemented in TensorFlow-Probability

#### Neural Networks Overview

- Simple mathematical model somewhat inspired by 'brain'
  - A series of neurons that output based off of its inputs, weights, and bias
  - An activation function to add non-linearity (ReLU, sigmoid, etc.)
- Each neuron has:
  - $\circ$  A set of inputs  $(x_1, x_2, \dots x_n)$
  - A set of weights for each input
     (w<sub>1</sub>, w<sub>2</sub>, ... w<sub>n</sub>)
  - o A bias (b)



Source: http://neuralnetworksanddeeplearning.com/chap1.html

## Training Neural Networks

- 1. Initialize a random set of weights and biases
- 2. Generate a prediction
- 3. Define a loss function to measure prediction error
  - a. Depends on the class of problem
- 4. Calculate gradient and step in the opposite direction (gradient descent)
  - a. The size of this step is called the learning rate
- 5. Repeat until we find a minimum for the loss function

#### Backpropagation: Basic Outline

- Efficiently calculates gradient of loss function
- Want to calculate  $\partial C/\partial w_{jk}^l$  and  $\partial C/\partial b_j^l$ 
  - $\circ$   $w_{ik}^l$ : weight for the connection in the kth neuron in the (l -1)th layer to the jth neuron in the lth layer
  - o b<sup>1</sup>;: bias of the jth neuron in the lth layer
- Instead calculate  $\partial C/\partial z_i^l$  and relate it to above quantities
  - $\circ$   $z_{j}^{l}$ : weighted input to the jth neuron in the lth layer
  - This measures the 'error' of a given neuron
  - $\circ$  When  $\partial C/\partial z_i^l$  is small, neuron is close to optimal

## Backpropagation: Terminology

- $\boldsymbol{z}_{\ i}^{l}$  : weighted input to the jth neuron in the lth layer
- $\sigma$ : activation function
- a<sup>l</sup><sub>i</sub>: activation input to the jth neuron in the lth layer Just  $\sigma(z_i^l)$
- $\begin{array}{ll} \bullet & \delta^l_{\ j} \hbox{: the error } (\partial C/\partial z^l_{\ j}) \\ \bullet & w^l_{\ jk} \hbox{: weight for the connection in the kth neuron in the (l-1)th layer to the jth} \end{array}$ neuron in the lth layer

$$\delta_j^L = \frac{\partial C}{\partial a_j^L} \sigma'(z_j^L)$$

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$$\delta_j^l = \sum_k w_{kj}^{l+1} \delta_k^{l+1} \sigma'(z_j^l).$$

$$\frac{\partial C}{\partial w_{jk}^l} = a_k^{l-1} \frac{\partial C}{\partial z_j^l} \quad \Longleftrightarrow \quad \frac{\partial C}{\partial w} = a_{\rm in} \delta_{\rm out},$$

$$\frac{\partial C}{\partial w} = a_{\rm in} \delta_{\rm out},$$

$$\frac{\partial C}{\partial b_j^l} = \delta_j^l.$$

### Backpropagation: Pseudocode

- 1. Set the initial input values
- 2. Feed the input values forward through all layers
- 3. Compute the error in the last layer (formula 1)
- 4. Calculate the error of previous layers from the last iteratively (formula 2) a. This is the 'backpropagation'
- 5. Obtain the gradient from formulas 3-4

#### Loss Function

- Regression problems: MSE
- Classification problems: cross entropy loss
  - Given number of classes C, number of training examples N
  - Assume true labels y as one-hot C-vector: [0,...,0,1,0,...,0]
  - Apply softmax function to last layer of neural network so that prediction y\_hat is a C-1 simplex
  - Loss function:

$$-\sum_{i=1}^N\sum_{c=1}^C y_{i,c}\log(\hat{y_{i,c}})$$

#### Bayesian View

- Prior. Initial 'belief' about parameters:  $p(\theta)$
- Likelihood. Data probability given parameters:  $p(D|\theta)$
- Marginal. How is the data distributed: p(D)
- Posterior. Parameter distribution with knowledge of data:  $p(\theta|D)$
- Average over all possible parameters to get a distribution for new inputs

$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) \ p(\theta)}{p(\mathcal{D})}$$

$$p(y^*|x^*, \mathcal{D}) = \int p(y^*|x^*, \theta) \ p(\theta|\mathcal{D}) d\theta.$$

#### NN as Maximum Likelihood

- Can view a neural network as a likelihood model:
  - $\circ$  P(y|x, w)
  - $\circ$  Given some input x, we assign probabilities to each possible output  $y \in Y$  using weights w
  - $\circ$  Y =  $\mathbb{R}$  for regression problems
  - $\circ$  Y = set of classes for classification
- Standard NN provides point estimates for weights using MLE

$$egin{aligned} \mathbf{w}^{ ext{MLE}} &= rg \max_{\mathbf{w}} \log P(\mathcal{D}|\mathbf{w}) \ &= rg \max_{\mathbf{w}} \sum_{i} \log P(\mathbf{y}_{i}|\mathbf{x}_{i},\mathbf{w}). \end{aligned}$$

#### BNN Overview

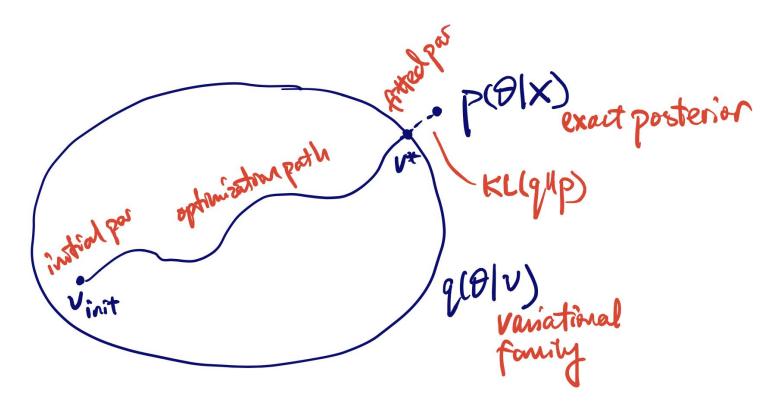
- NN as likelihood
- Prior distribution on the weights
- Find posterior for the weights given training data
- Cannot derive analytical forms for the posterior
- Instead:
  - Approximate inference with Variational Inference

#### Variational Inference

#### Turn inference problem to optimization problem

- Assume a family of distributions for the posterior
- Vary the parameters of the distribution to minimize distance between this distribution and the true posterior
  - Distance described by the KL-Divergence

#### Variational Inference



#### Kullback-Leibler (KL) divergence

- Measures how 'different' two probability distributions are
  - Bayesian: Measures the distance from approximate dist. to true posterior
- General entropy for probability distribution
  - KL is just the expected log difference
- Intuition: Amount of information lost when using Q instead of P
- Asymmetric so not a distance metric

$$h[f] = \mathbb{E}[-\ln(f(x))] = -\int_{\mathbb{X}} f(x) \ln(f(x)) \, dx. \qquad D_{KL}(P\|Q) = \mathbb{E}_{x \sim P} \left[\log rac{P(X)}{Q(X)}
ight]$$

## Properties of KL Divergence

- Non-negative
  - The best we can do is lose 0 'bits' of information
  - Can't gain
- Only zero iff P = Q
  - Lose nothing if our approximation is exact
  - Losing nothing means our approximation is exact
- Minimization amounts to finding better approximations of P

## Non-negativity of KL Divergence

Fact about ln:  $\forall x > 0, ln(x) \leq x - 1$ 

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$$\leq \int p(x)(\frac{q(x)}{p(x)} - 1)dx = \int q(x) - p(x)dx = 1 - 1 = 0$$

Jensen's Inequality:  $\phi(\mathbb{E}[X]) \leq \mathbb{E}[\phi(X)]$  for convex  $\phi$ 

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$$\log(\frac{q(x)}{p(x)}) = 0 \iff p(x) = q(x)$$

## ELBO Equation (Blei, et al. 2018)

- Directly minimizing KL is not computable
- z: parameters of our model (latent variables)
- x: observed data
- Dependent on p(x), our evidence
  - This generally has no closed form
  - Intractable to compute

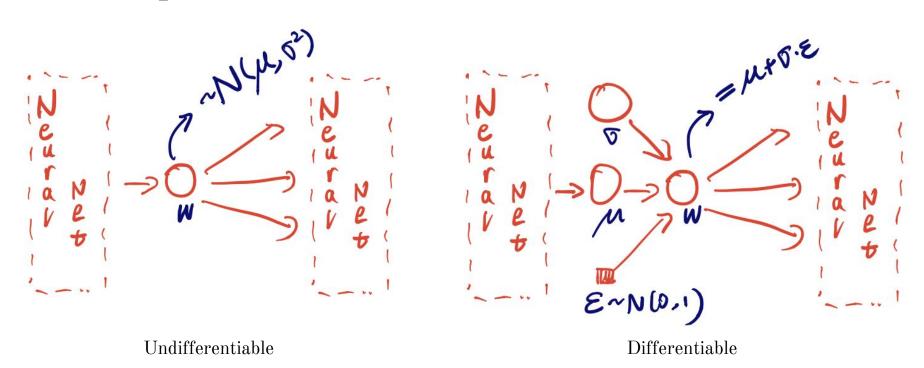
$$p(\mathbf{z} | \mathbf{x}) = \frac{p(\mathbf{z}, \mathbf{x})}{p(\mathbf{x})}.$$
  $p(\mathbf{x}) = \int p(\mathbf{z}, \mathbf{x}) d\mathbf{z}.$ 

 $KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x})) = \mathbb{E}[\log q(\mathbf{z})] - \mathbb{E}[\log p(\mathbf{z},\mathbf{x})] + \log p(\mathbf{x}).$ 

$$ELBO(q) = \mathbb{E} [\log p(\mathbf{z}, \mathbf{x})] - \mathbb{E} [\log q(\mathbf{z})].$$

- Instead maximize the ELBO equation
- Equal to negative  $KL + \log p(x)$  which is constant with respect to q
- Maximizing this equation is equivalent to minimizing KL
- All quantities are effectively computable

## The 'Reparameterization Trick'



Kingma & Welling (2014) - Auto-encoding Variational Bayes Rezende, et al. (2014) - Stochastic Backpropagation and Approximate Inference in Deep Generative Models

#### Algorithm 1: Bayesian Neural Network based on Variational Inference

- 0. Initialize variational parameters  $\nu = (\mu, \rho)$ . Choose step size  $\alpha$ .
- 1. **for** i = 1 to N do

$$\epsilon_i \sim \mathcal{N}(0, I)$$

b. Compute weights

$$w_i = \mu + \log(1 + \exp \rho) * \epsilon_i$$

 $\mathbf{end}$ 

2. Compute Monte Carlo loss

$$\mathcal{L} = \sum_{i=1}^N \log(q(w_i|
u)) - \log(p(w_i)) - \log(P(\mathcal{D}|w_i))$$

3. Update variational parameters

$$\mu = \mu - \alpha \nabla_{\mu} \mathcal{L}$$
$$\rho = \rho - \alpha \nabla_{\rho} \mathcal{L}$$

## Results: Test Accuracy

Bayes-1200-1200-10	Bayes-100-100-10	FC-1200-1200-10	FC-100-100-10
98.18%	97.90%	98.15%	97.74%

Test accuracies of Bayesian and (non-Bayesian) feed forward neural networks on the MNIST dataset. x-x-10 refers to a network with two hidden layers, each of x hidden units.

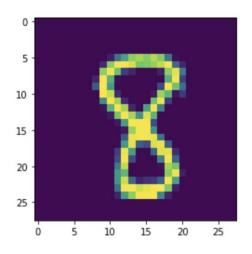
## Results: Model Pruning

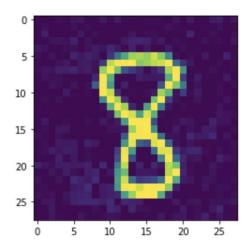
Removed 0%	Removed 50%	Removed 75%	Removed 95%	Removed 98%
98.18%	98.18%	98.17%	97.89%	96.72%
98.15%	97.53%	92.87%	47.55%	38.20%

Test accuracies with different proportions of weights set to 0.

First row: Bayesian neural net (1200-1200-10). Second row: vanilla neural net of the same structure.

## Results: Input Perturbation





Adversarially perturb input data using FC-1200-1200-10. Left: the network predicts as 8. Right: the network predicts as 3.

## Results: Input Perturbation

Bayes-100-100-10	FC-1200-1200-10-ReLU	FC-100-100-10-ReLU	FC-100-100-10-Sigmoid
96.33% (97.79%)	0.00%~(98.12%)	83.49% (97.65%)	89.91% (97.73%)
FC-10	FC-10 ( $\lambda = 1$ )	FC-10 ( $\lambda = 1e - 2$ )	FC-10 ( $\lambda = 1e - 4$ )
53.21% (93.01%)	82.57% (88.92%)	$75.23\% \ (92.71\%)$	52.29% (93.04%)

Accuracy of Bayesian and non-Bayesian neural networks on the perturbed dataset. In parenthesis is their accuracies on the original validation set.

#### Future Plans

#### Liyi Zhang

• Graduate study on Stats/CS; planning to work more on deep probabilistic modeling and approximate inference

#### Rhys Murray

• S&T right after graduation, planning to go back to a graduate program in Stats or pure math

#### Arian Pentza

• Planning to head into the web-dev industry, so if any of you guys need help making a website just hit me up

#### References

Charles Blundell, Julien Cornebise, Koray Kavukcuoglu, & Daan Wierstra. 2015. Weight uncertainty in neural networks. *Proceedings of the 32nd International Conference on International Conference on Machine Learning - Volume 37 (ICML'15)*. JMLR.org, 1613–1622.

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