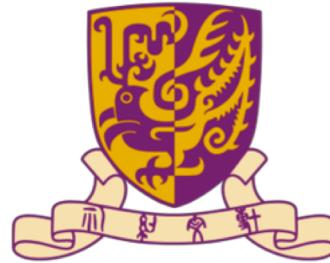


Recent Progress in Object Detection

Kai Chen (陈恺)
Multimedia Laboratory
The Chinese University of Hong Kong

About me

- 2015 - now



PhD@MMLAB, CUHK
Supervised by Dahua Lin

- 2011 - 2015



BS@Tsinghua

Research interest: object detection, video analysis

Task definition

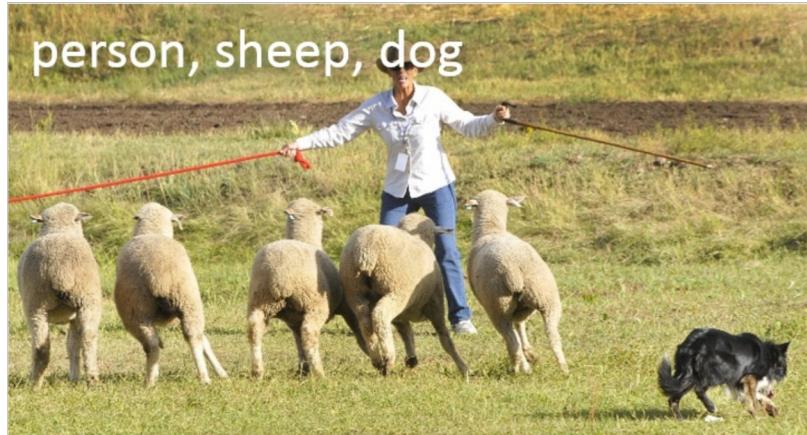
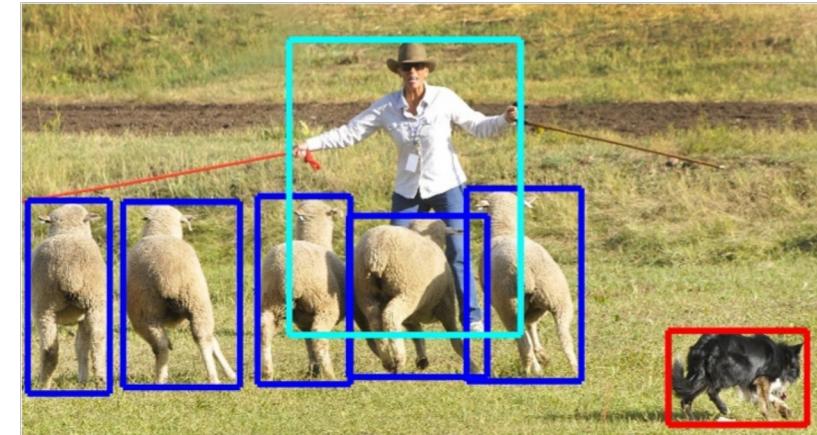


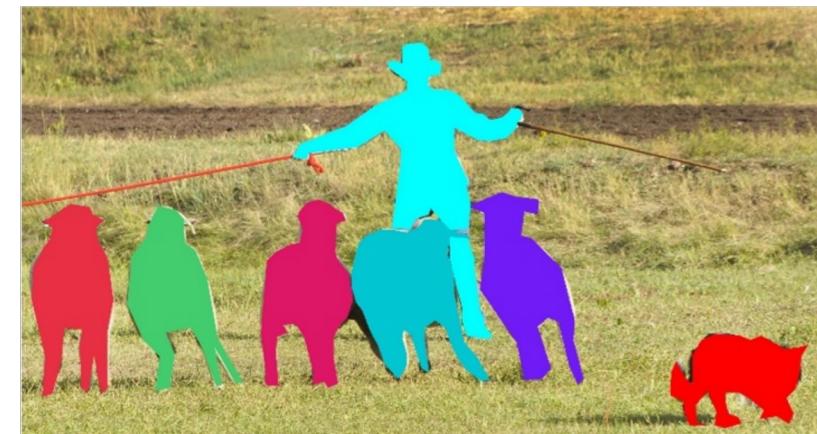
Image classification



Object detection

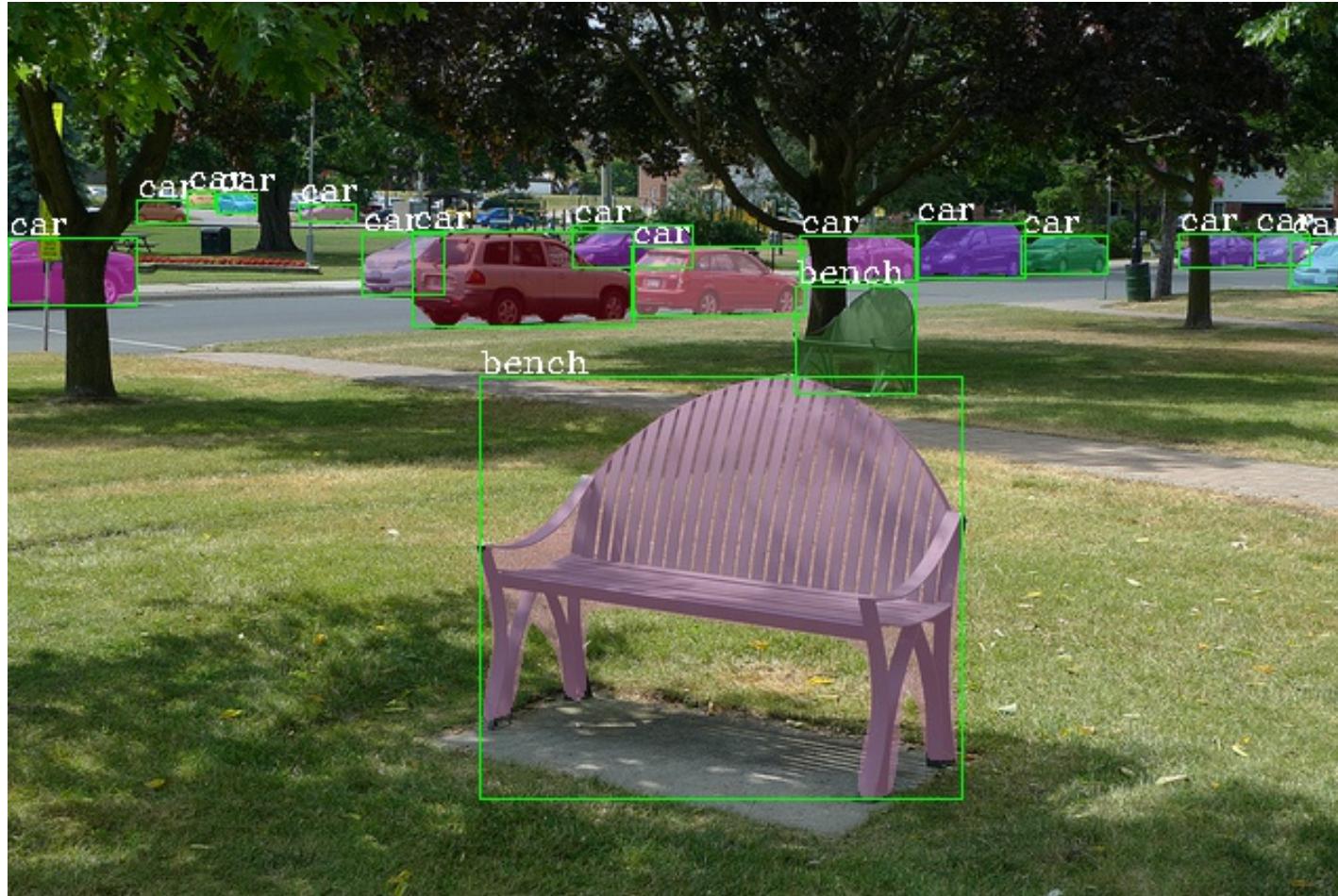


Semantic segmentation

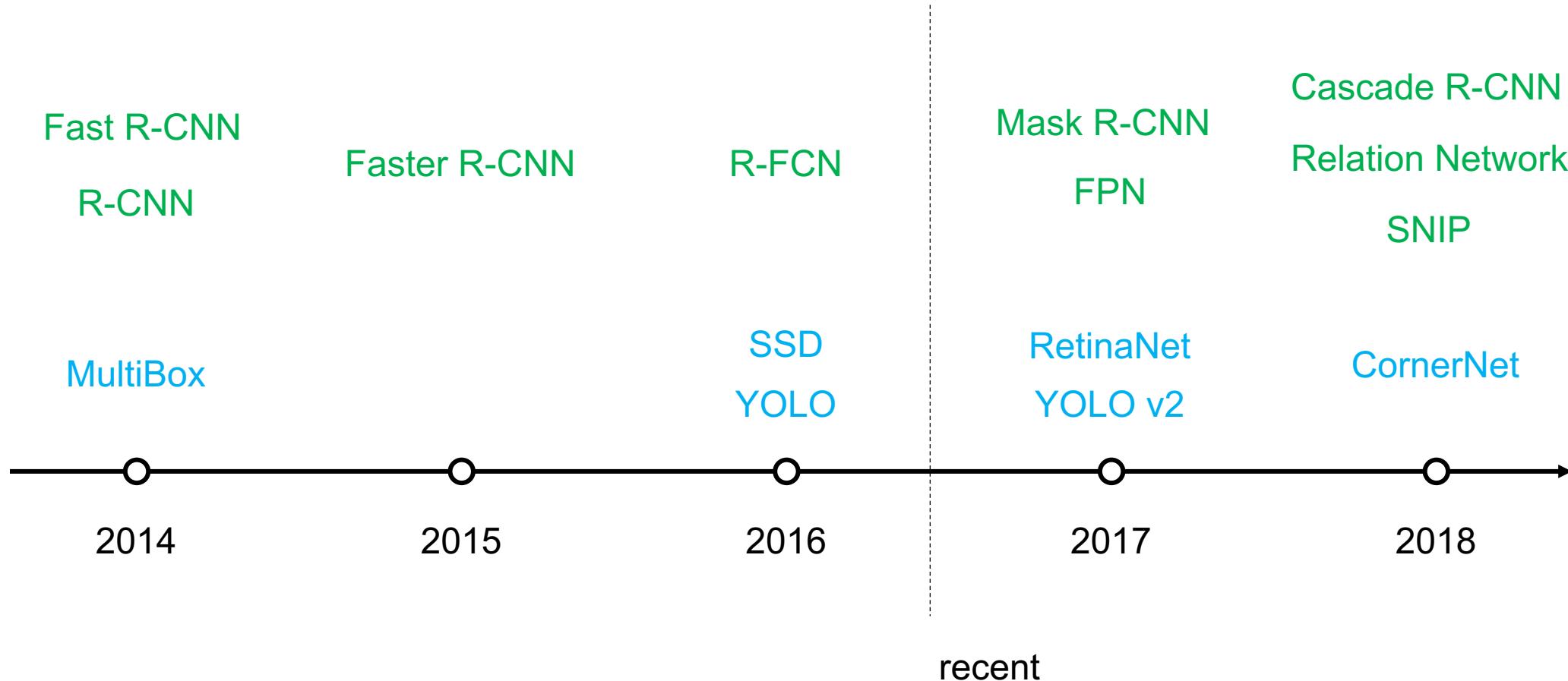


Instance segmentation

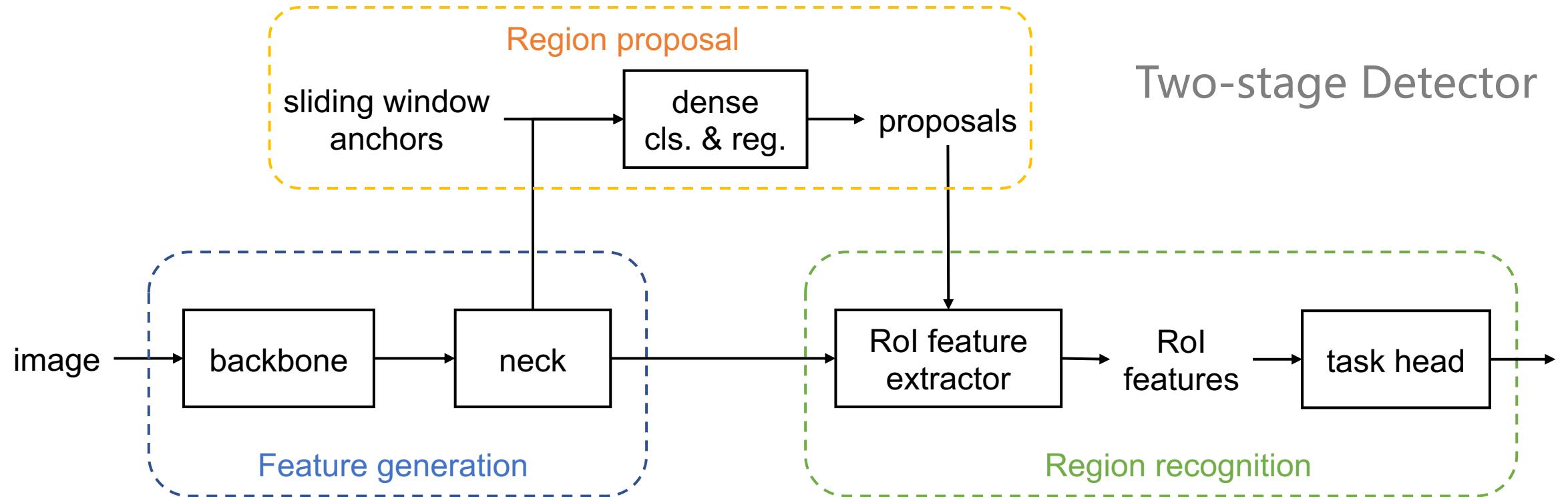
Task definition



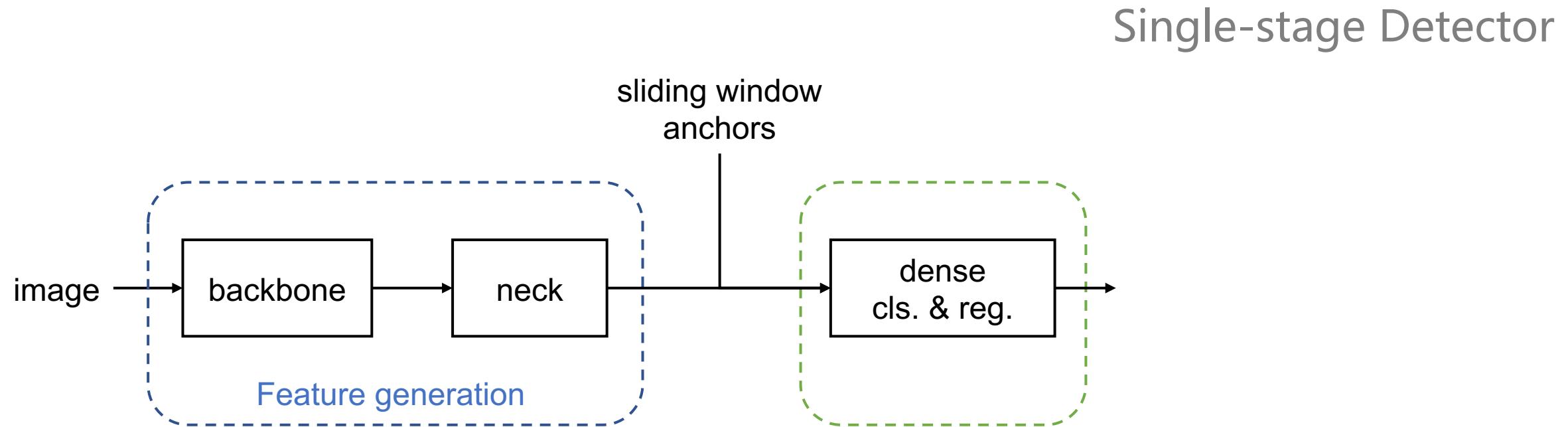
Progress



General pipeline



General pipeline

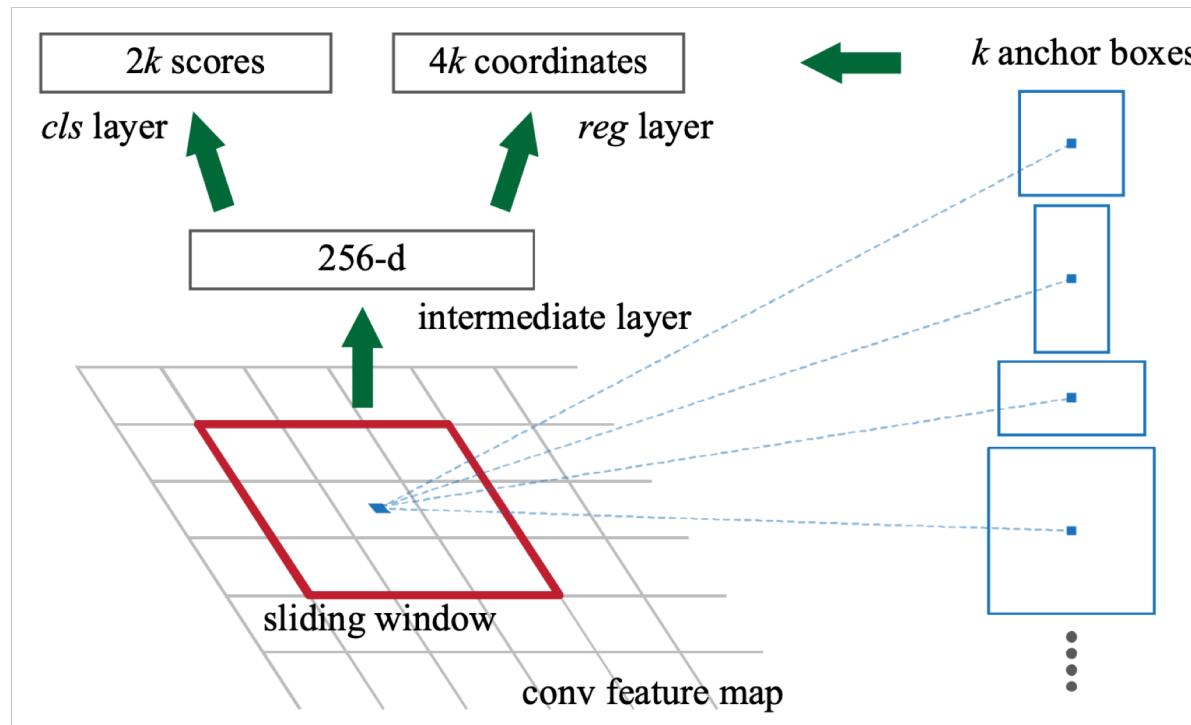


Faster R-CNN

- Region Proposal Network (RPN)
- Training pipeline

Faster R-CNN

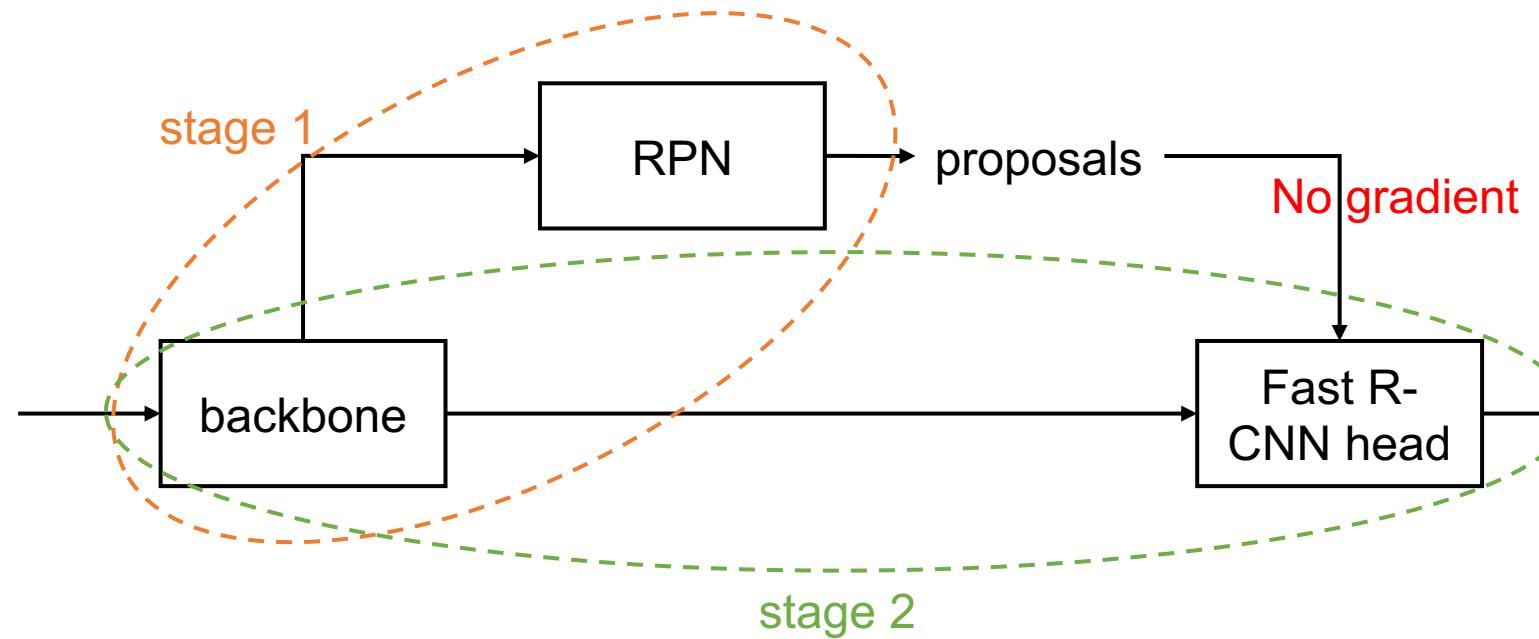
- RPN



Faster R-CNN

Training pipeline

- Alternating training: stage1 – stage2 – stage1 (finetune) – stage2 (finetune)

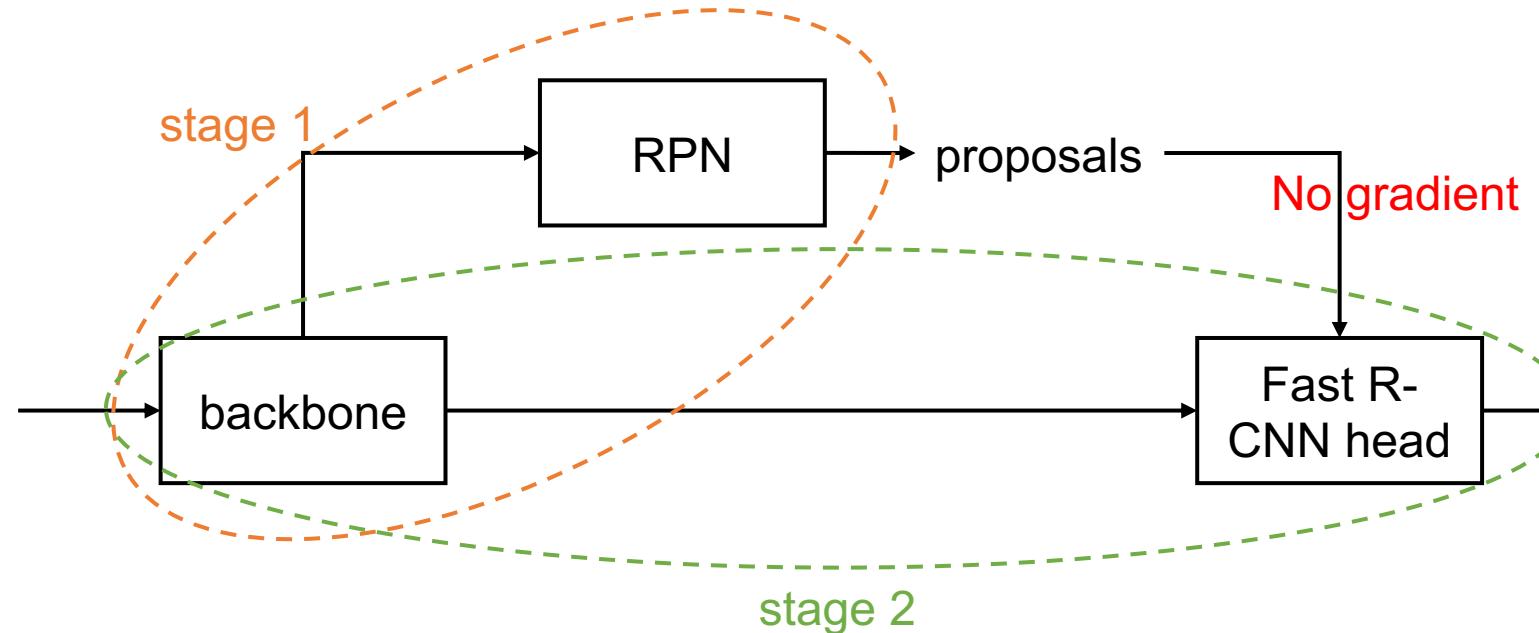


Faster R-CNN

Training pipeline

- Joint training: multi-task

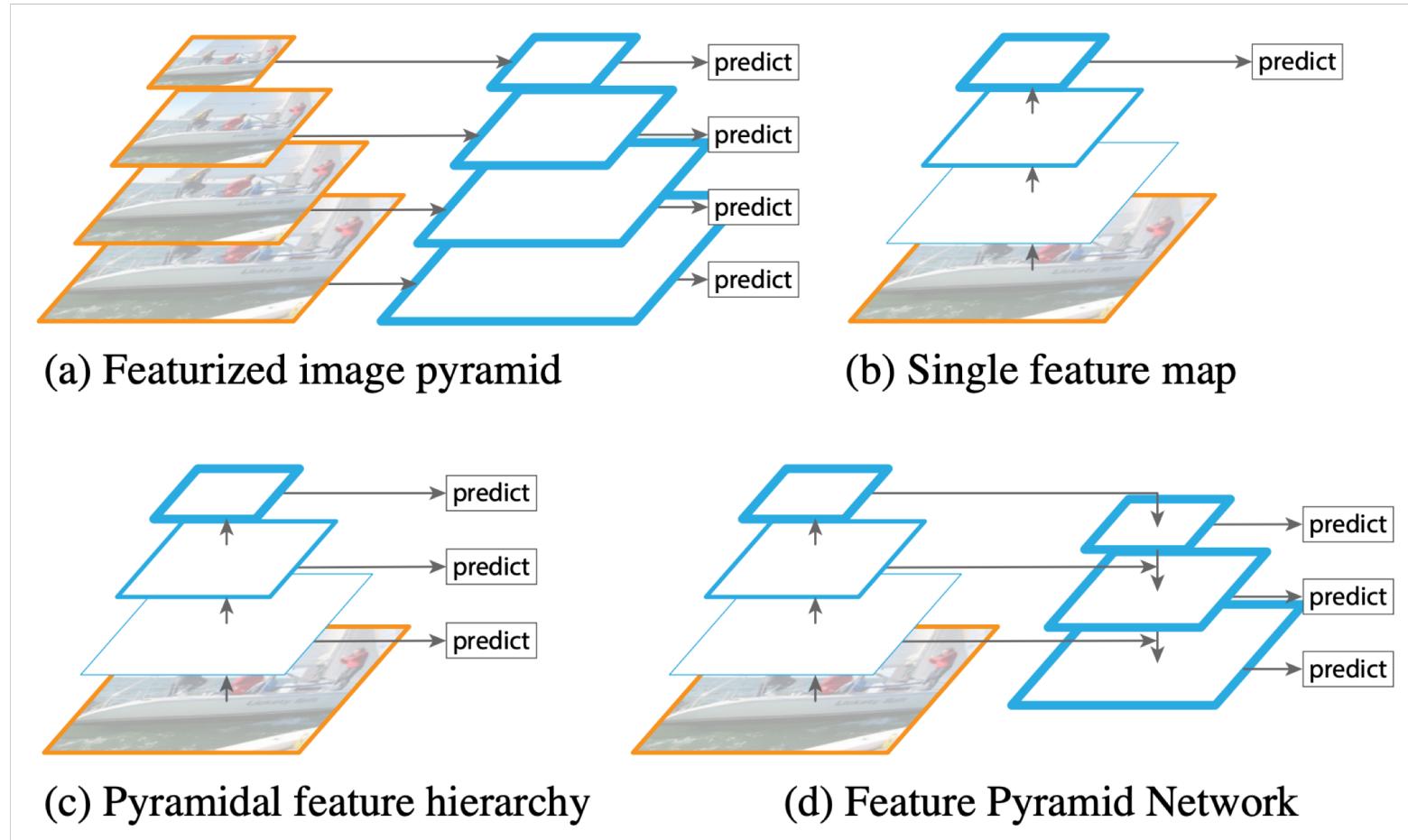
preferred



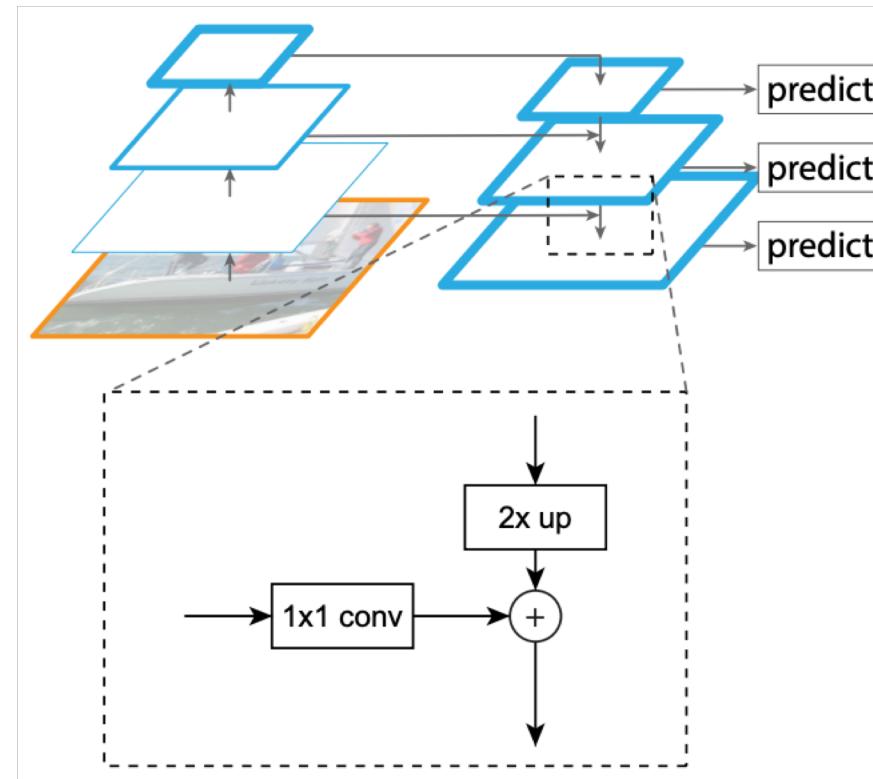
Feature Pyramid Network (FPN)

- Top-down pathway
- Multi-level prediction

Feature Pyramid Network (FPN)



Feature Pyramid Network (FPN)

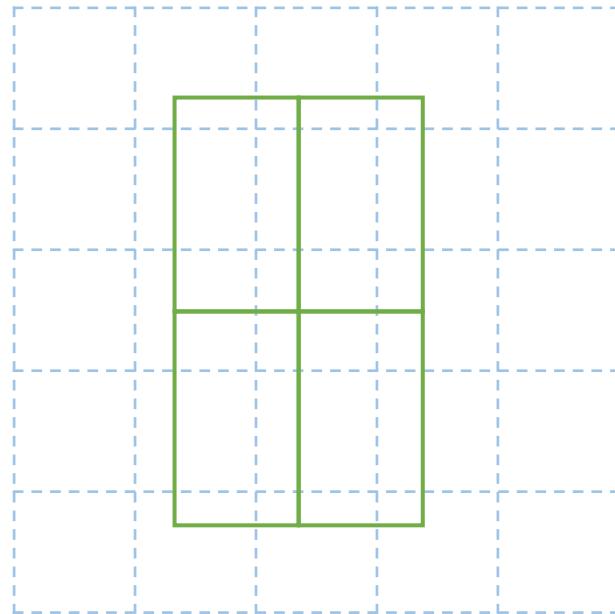


Mask R-CNN

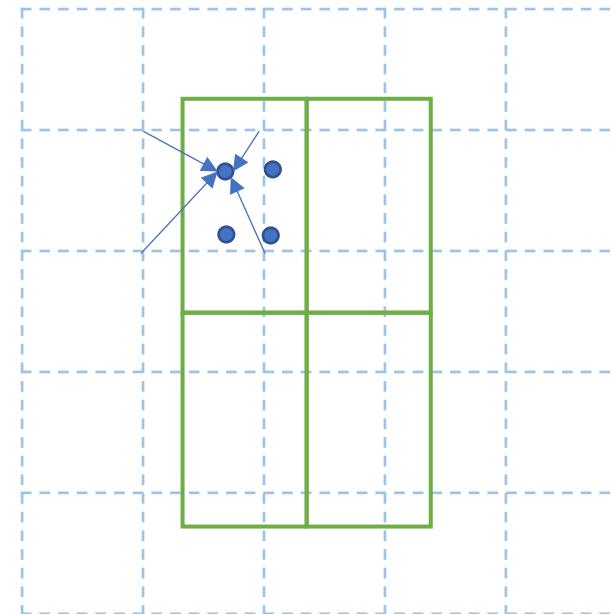
- ROIAlign
- Mask branch

Mask R-CNN

RoI Pooling

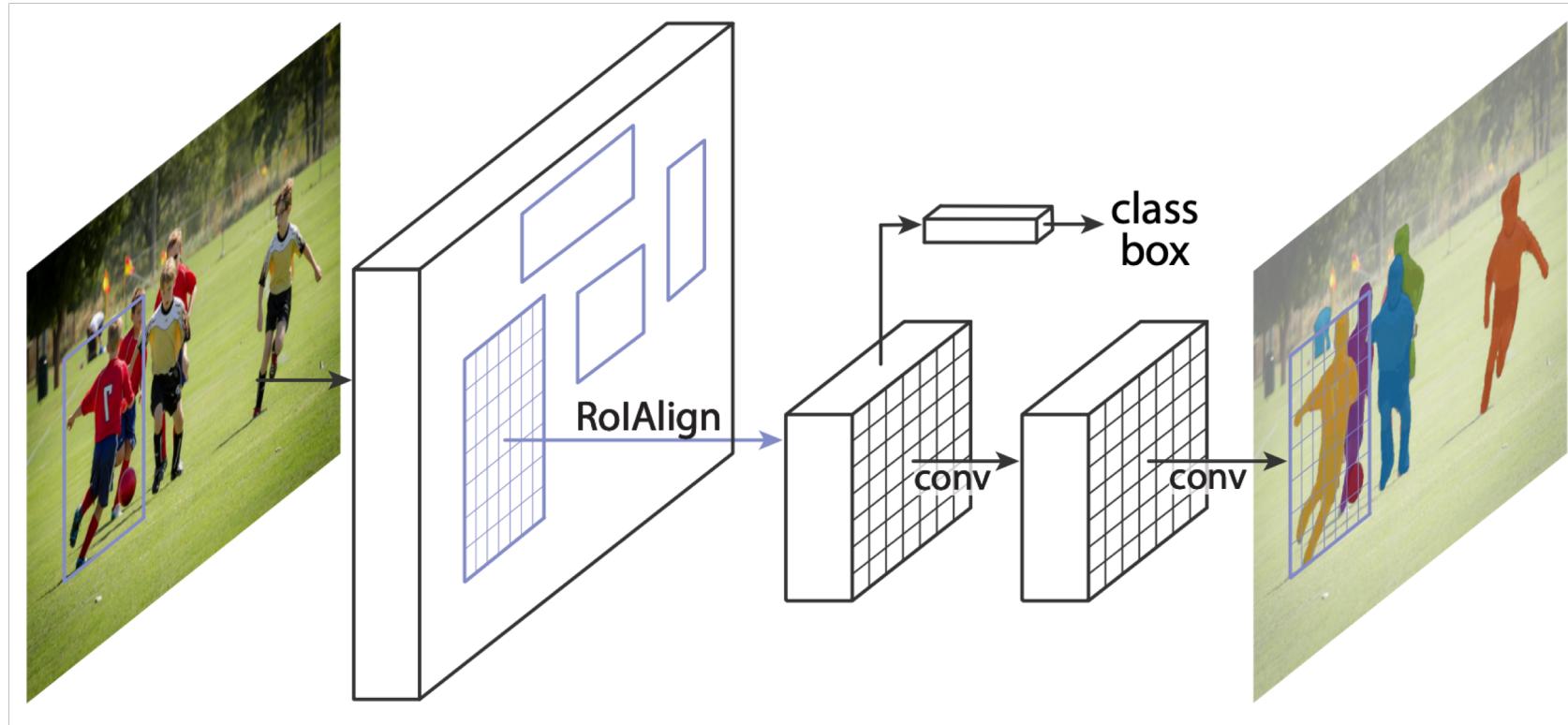


RoI Align



Mask R-CNN

Mask branch

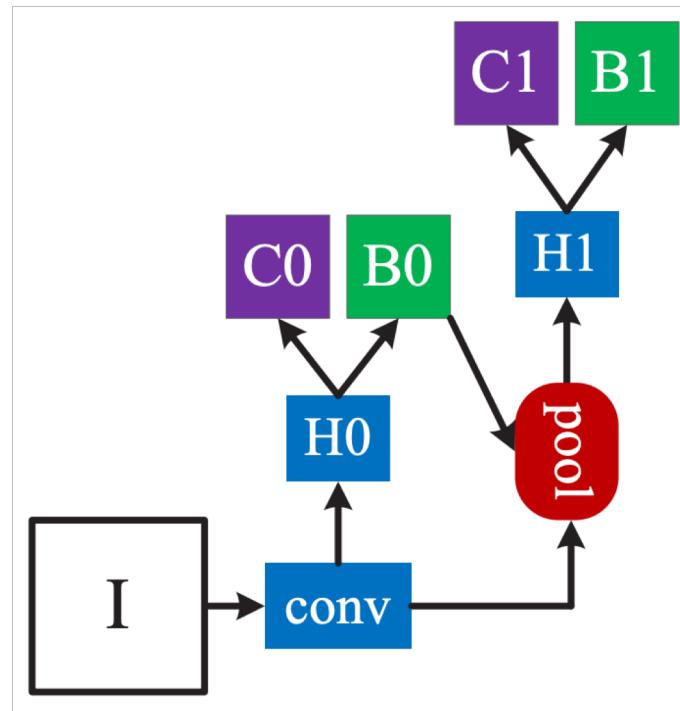


Cascade R-CNN

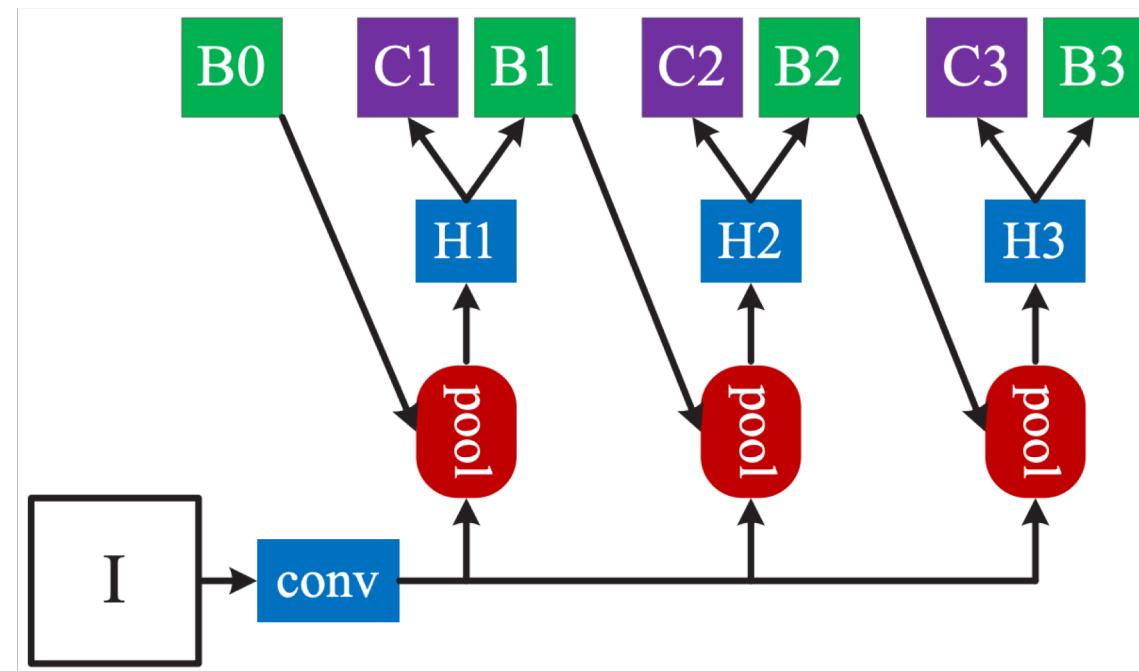
- Cascade architecture
- Training distribution

Cascade R-CNN

Cascade architecture



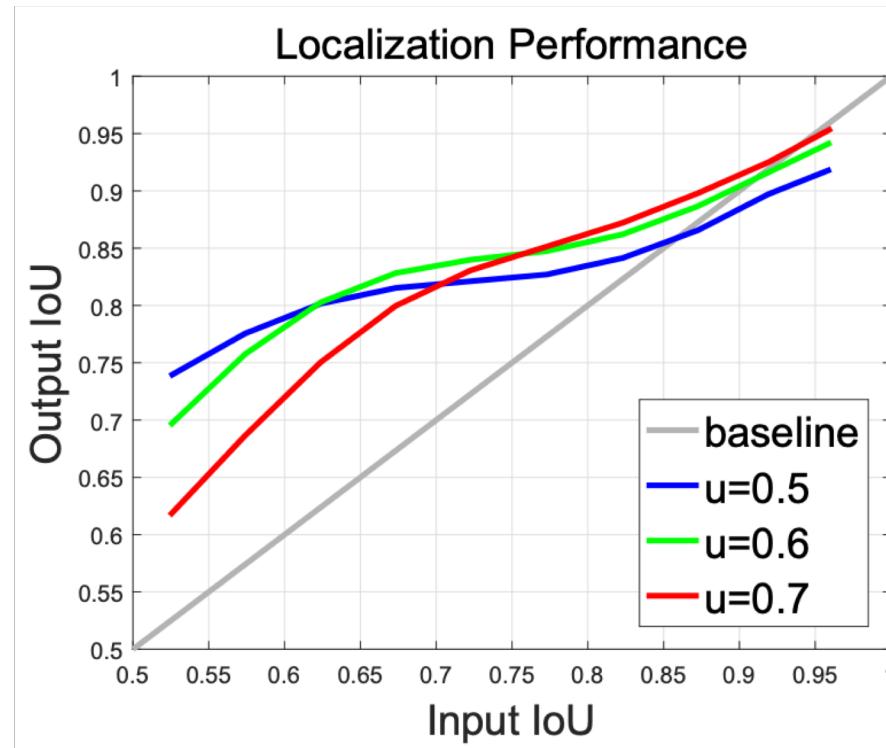
Faster R-CNN



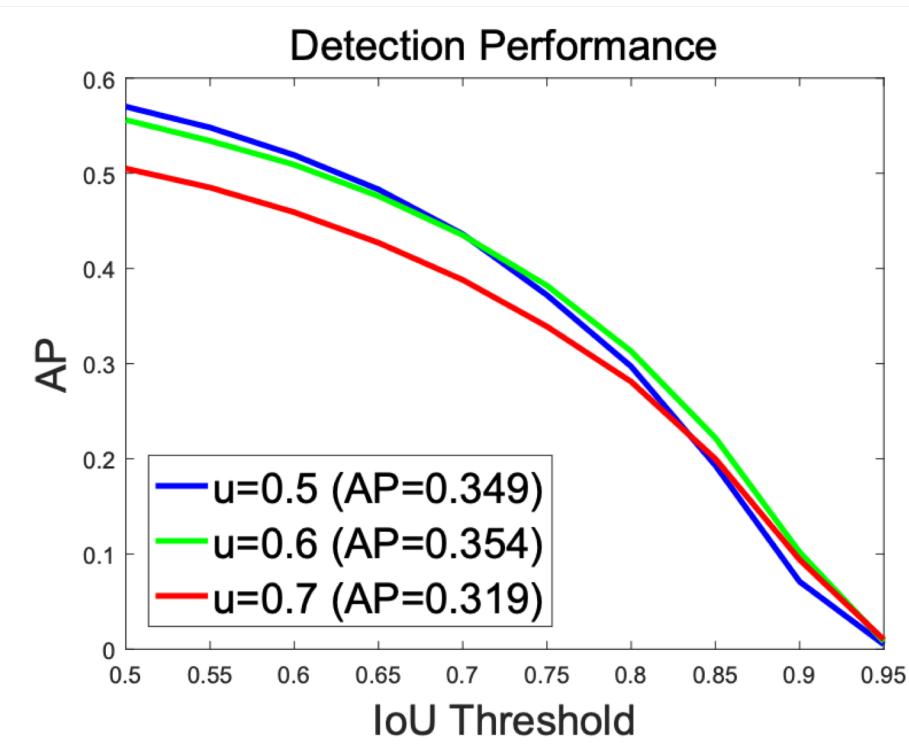
Cascade R-CNN

Cascade R-CNN

Training distribution



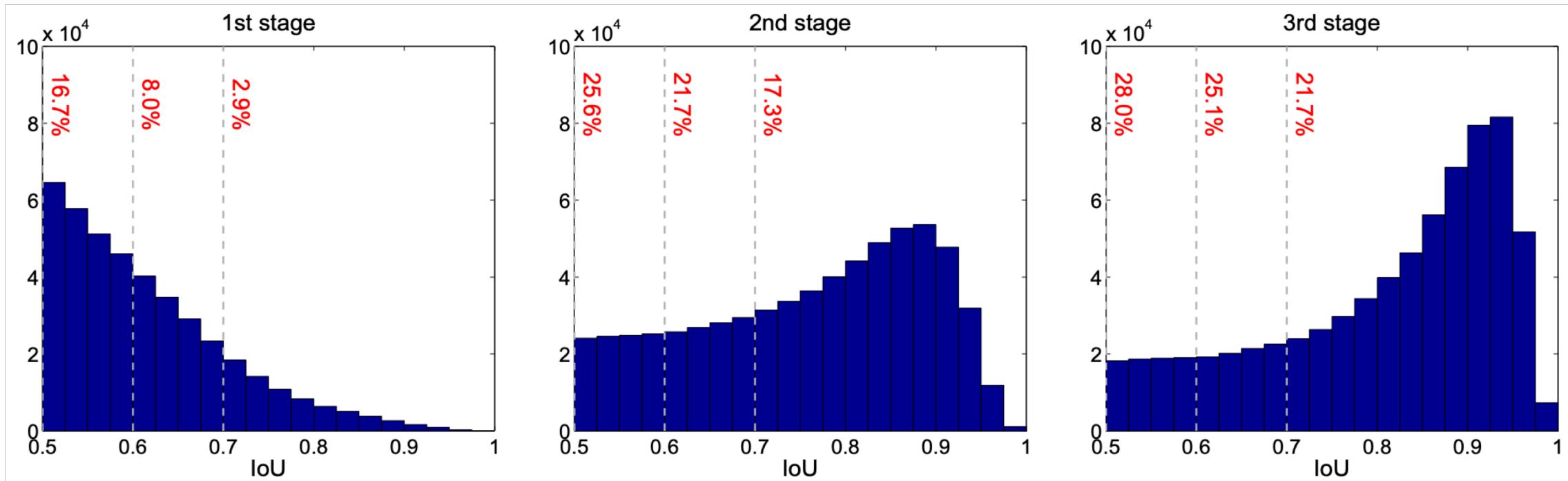
Regressor



Detector

Cascade R-CNN

Training distribution

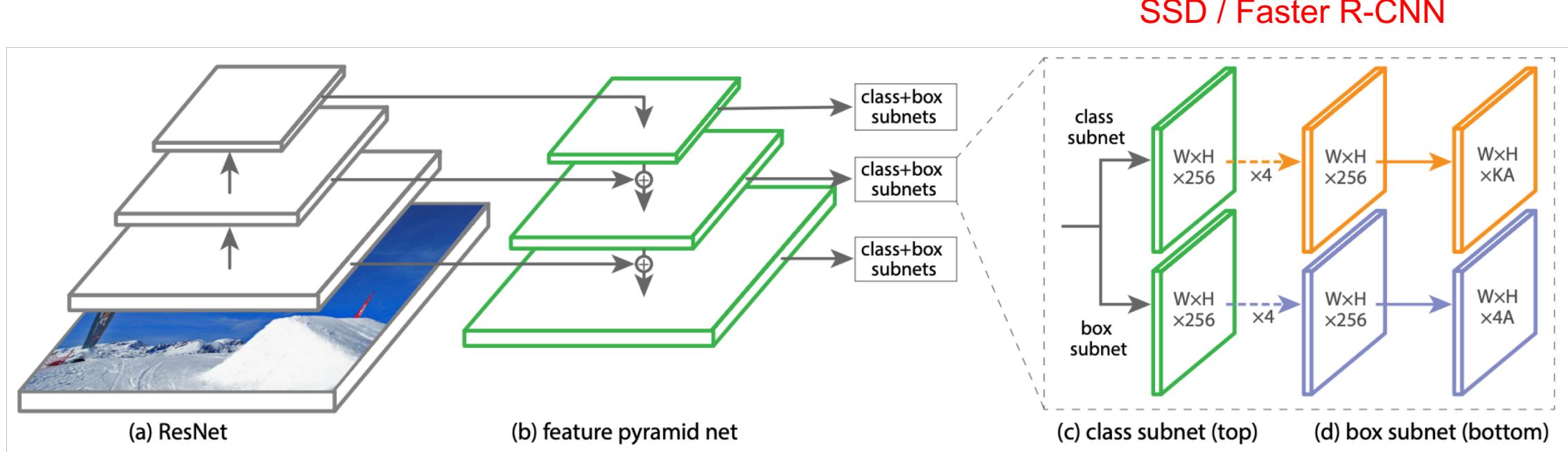


RetinaNet

- FPN
- Focal Loss

RetinaNet

FPN



RetinaNet

Focal Loss

- Problem: class imbalance
 - inefficient training
 - loss is overwhelmed by negative samples

Model	Solution
Two-stage detectors	1) proposal 2) mini-batch sampling
SSD	Hard negative mining
RetinaNet	Focal loss

RetinaNet

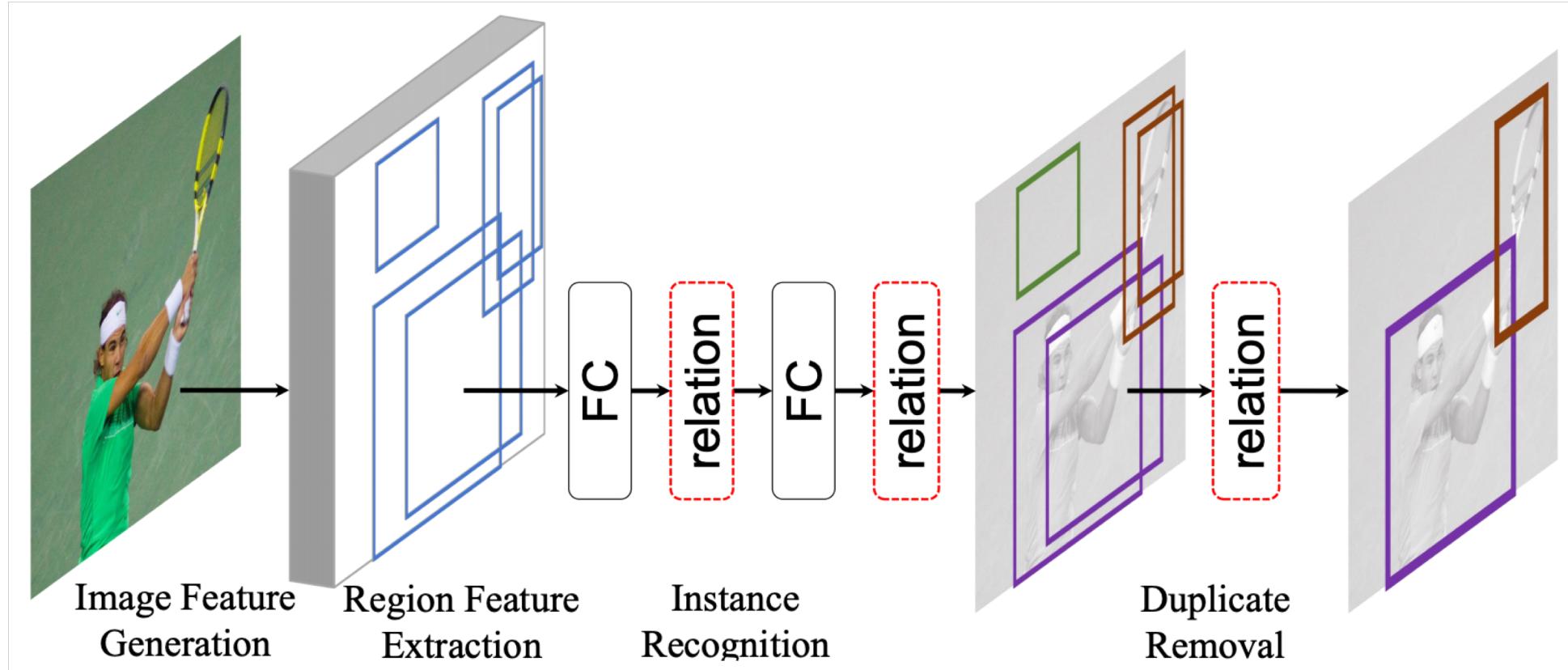
Focal Loss

- Solution: high confidence \rightarrow small loss

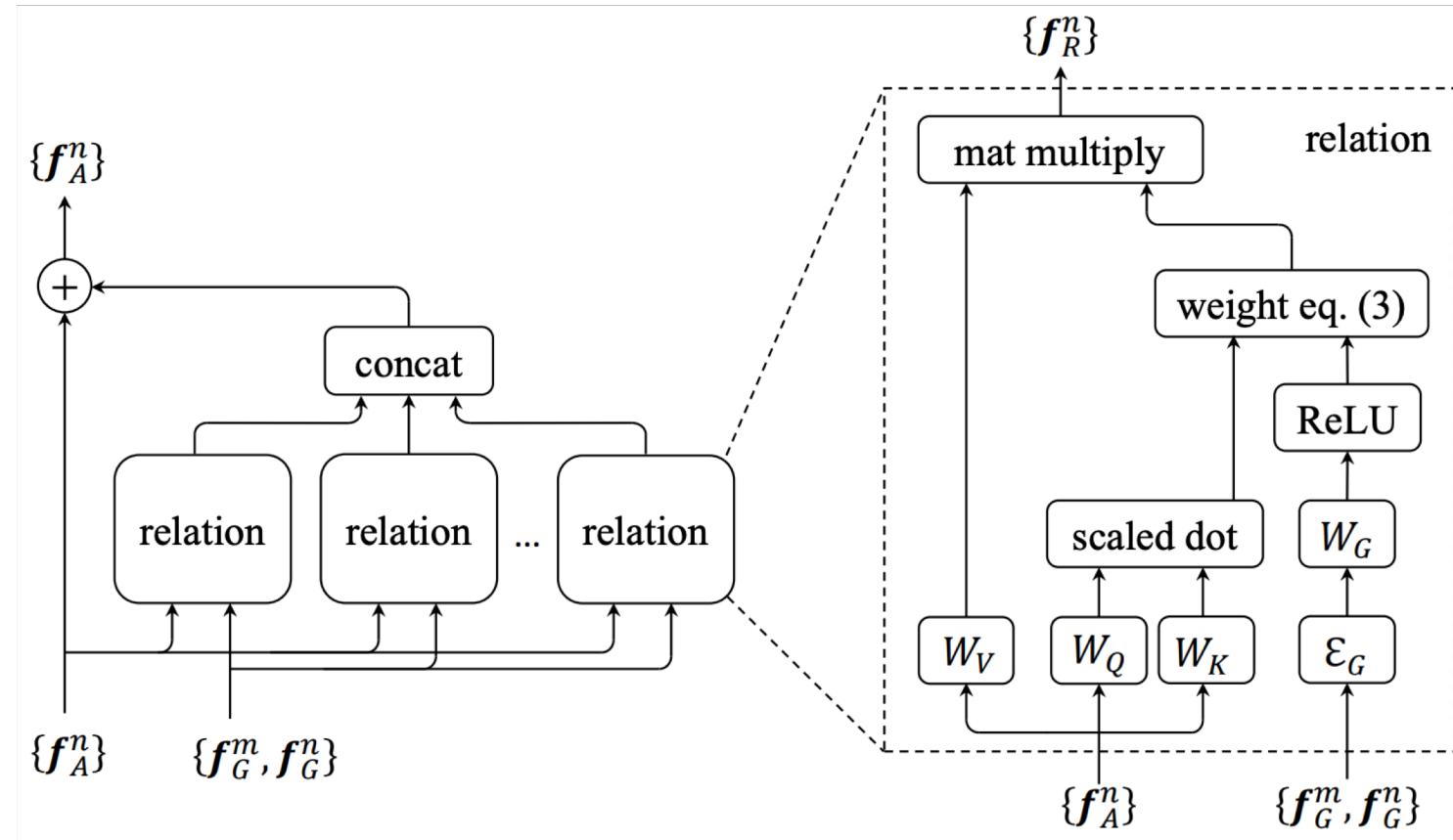
$$p_t = \begin{cases} p & \text{if } y = 1 \\ 1 - p & \text{otherwise} \end{cases}$$

$$\text{FL}(p_t) = -\alpha_t(1 - p_t)^\gamma \log(p_t).$$

Relation Network



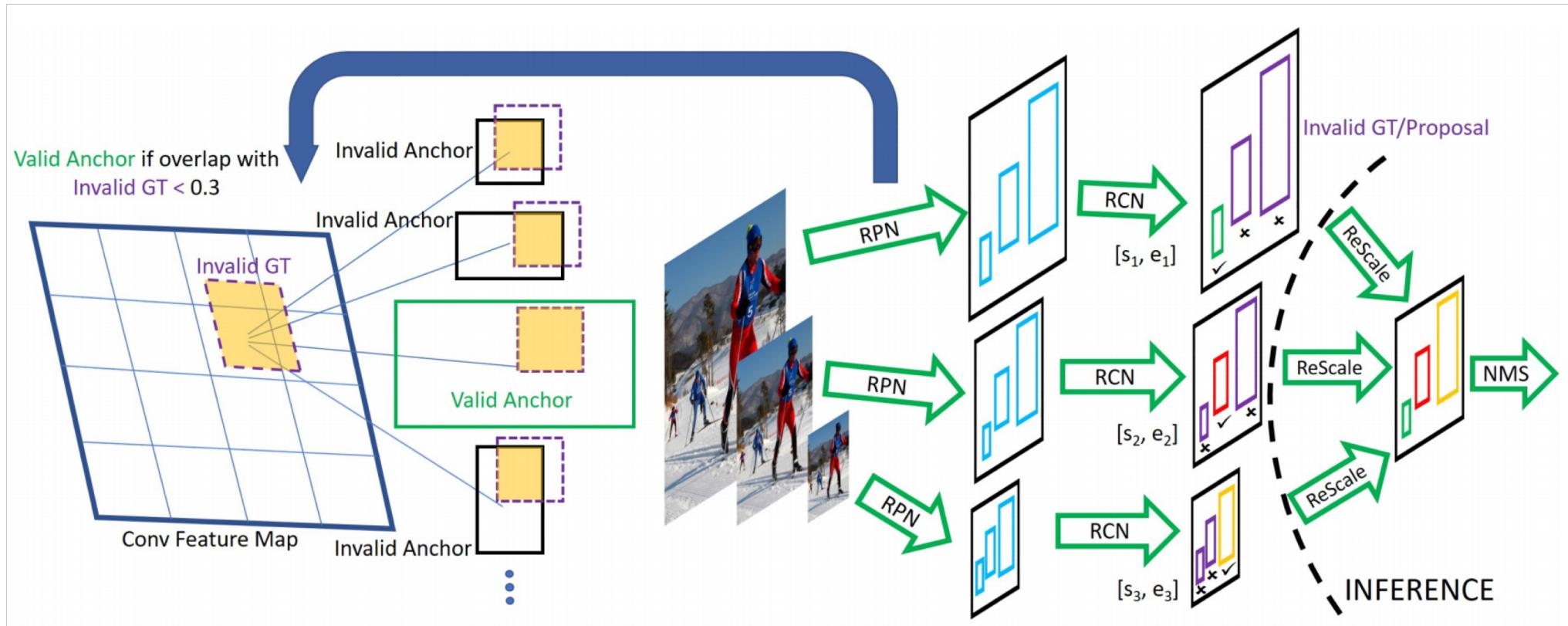
Relation Network



Scale Normalization for Image Pyramids (SNIP)

- Scale specific instead of scale invariant

Scale Normalization for Image Pyramids (SNIP)



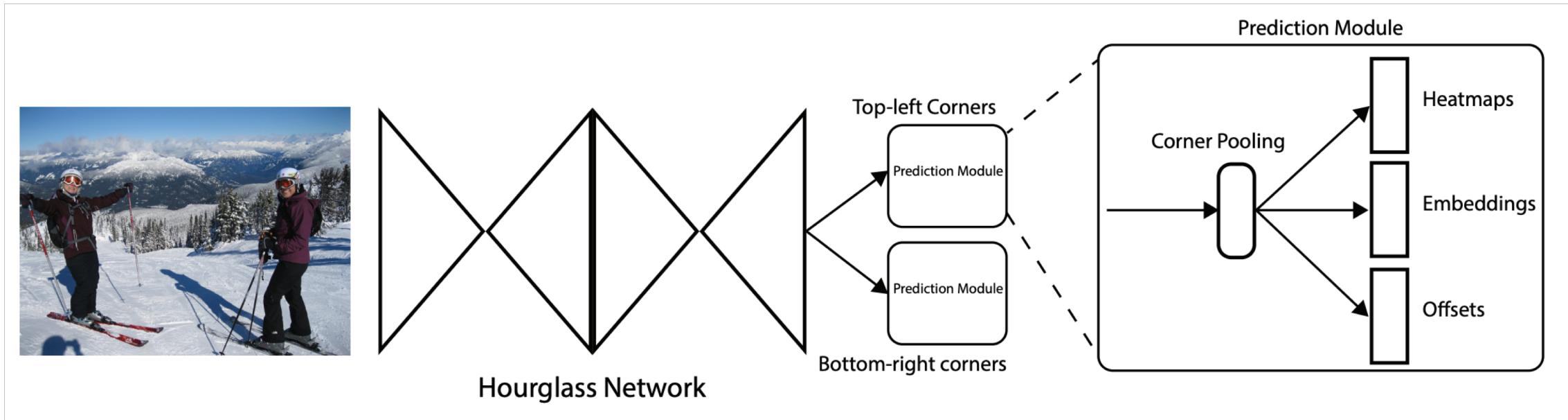
CornerNet

- Object as pair of keypoints
- Pipeline: detect corners -> group corners



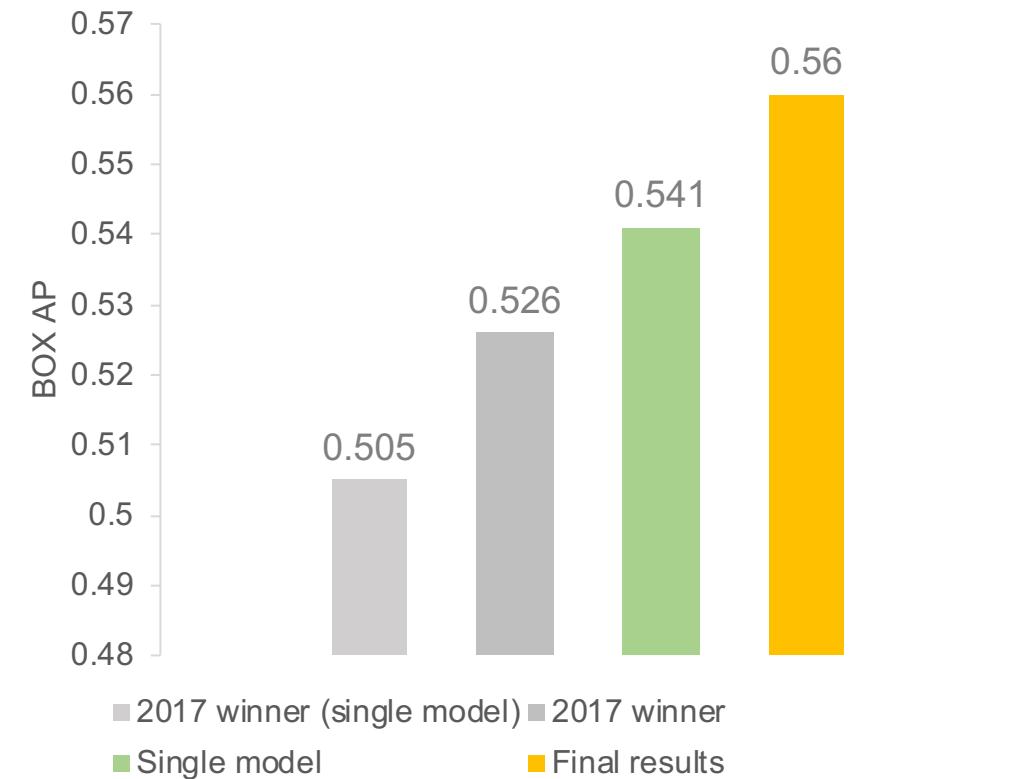
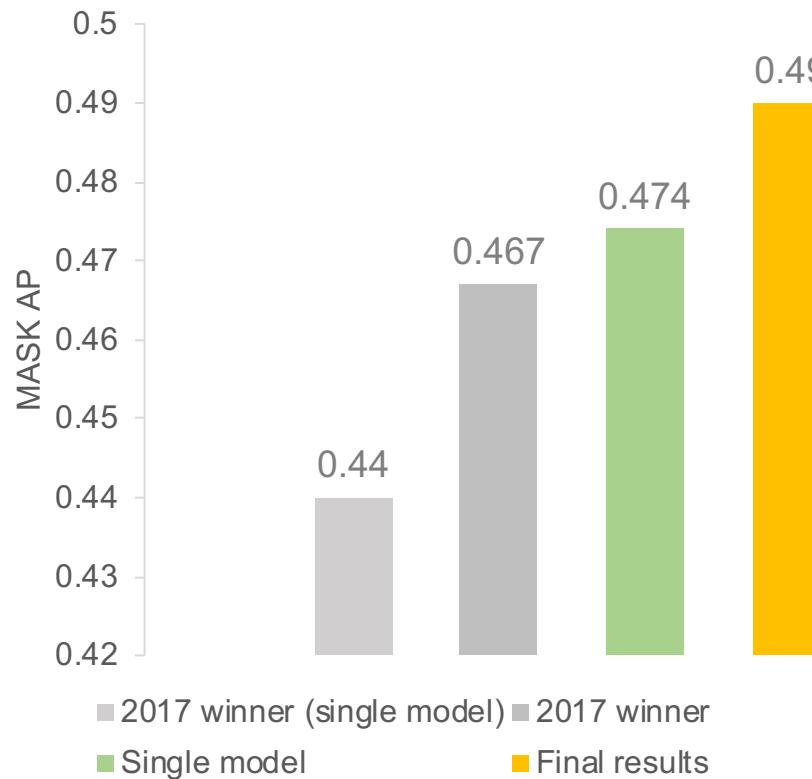
CornerNet

- Pipeline



COCO Challenge 2018

Comparison of our approach with 2017 winning entries on COCO test-dev.



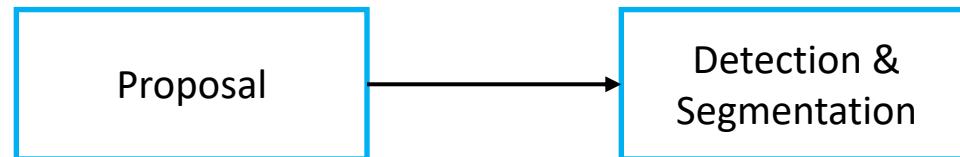
COCO Challenge 2018

1. We developed a **hybrid task cascade** framework for detection and segmentation.

Detection &
Segmentation

COCO Challenge 2018

1. We developed a **hybrid task cascade** framework for detection and segmentation.
2. We proposed a feature **guided anchoring** scheme to improve the average recall (AR) of RPN by 10 points.



COCO Challenge 2018

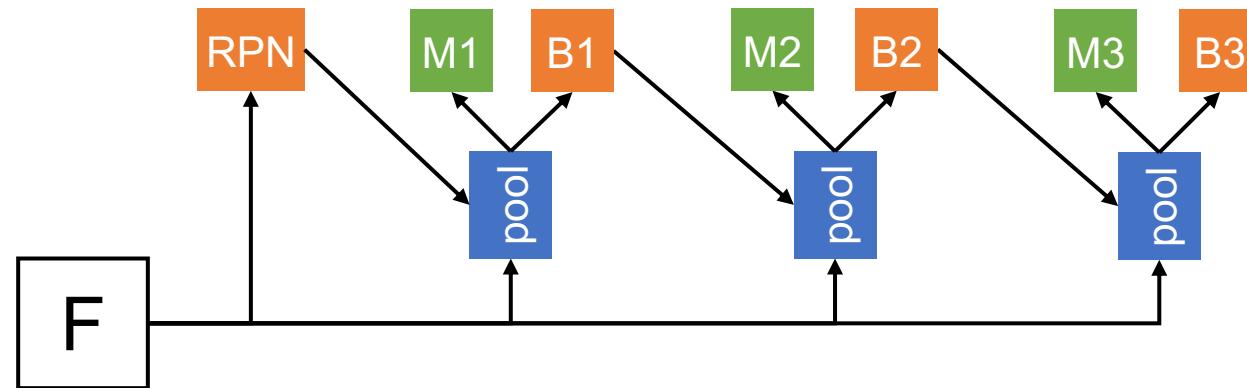
1. We developed a **hybrid task cascade** framework for detection and segmentation.
2. We proposed a feature **guided anchoring** scheme to improve the average recall (AR) of RPN by 10 points.
3. We designed a new backbone **FishNet**.



COCO Challenge 2018

Hybrid Task Cascade (HTC)

- Cascade Mask R-CNN (Cascade R-CNN + Mask R-CNN)

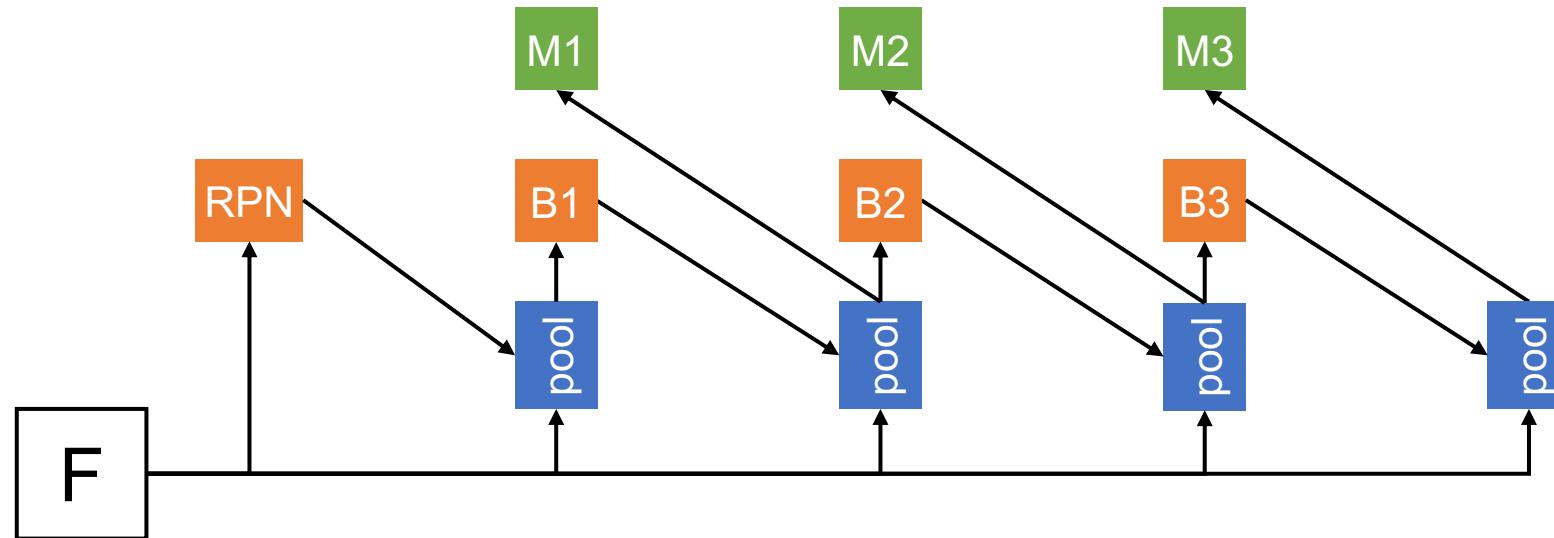


Problem: Two branches at each stage are executed in parallel, without interaction.

COCO Challenge 2018

Hybrid Task Cascade (HTC)

- Interleaved execution

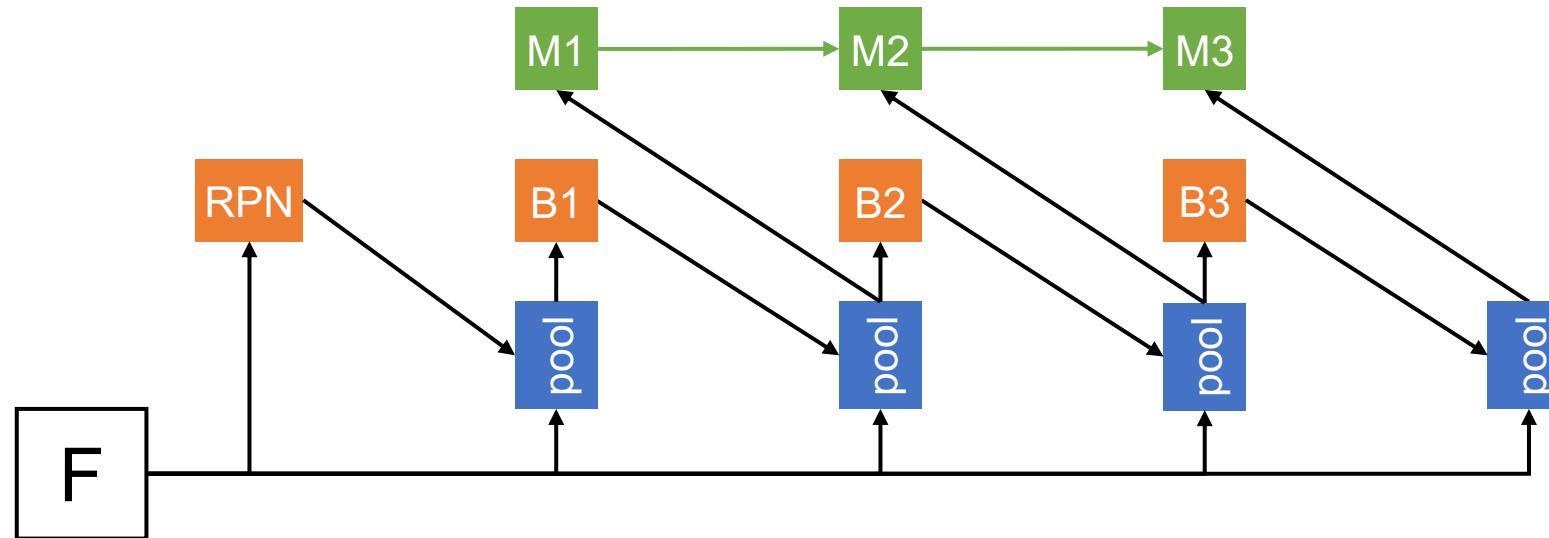


Problem: No direct information flow between mask branches at different stages.

COCO Challenge 2018

Hybrid Task Cascade (HTC)

- Mask Information Flow

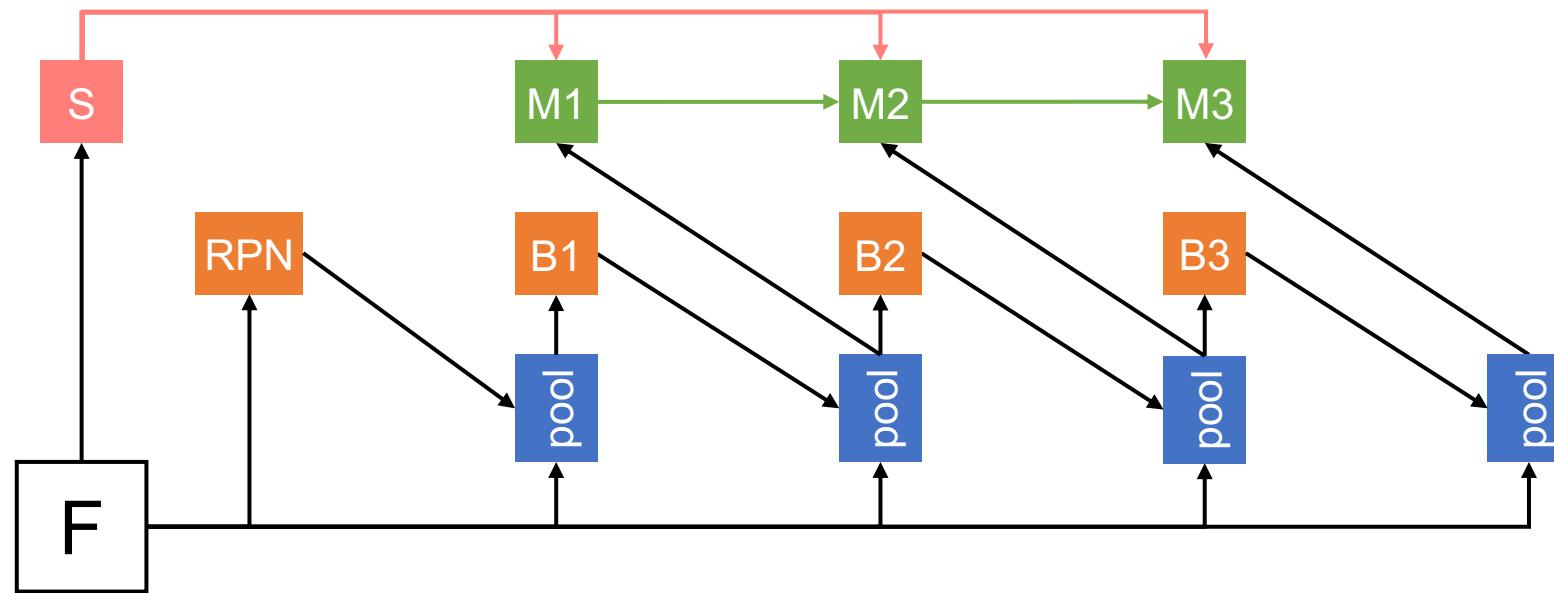


Problem: Spatial context is not much explored.

COCO Challenge 2018

Hybrid Task Cascade (HTC)

- Spatial context



COCO Challenge 2018

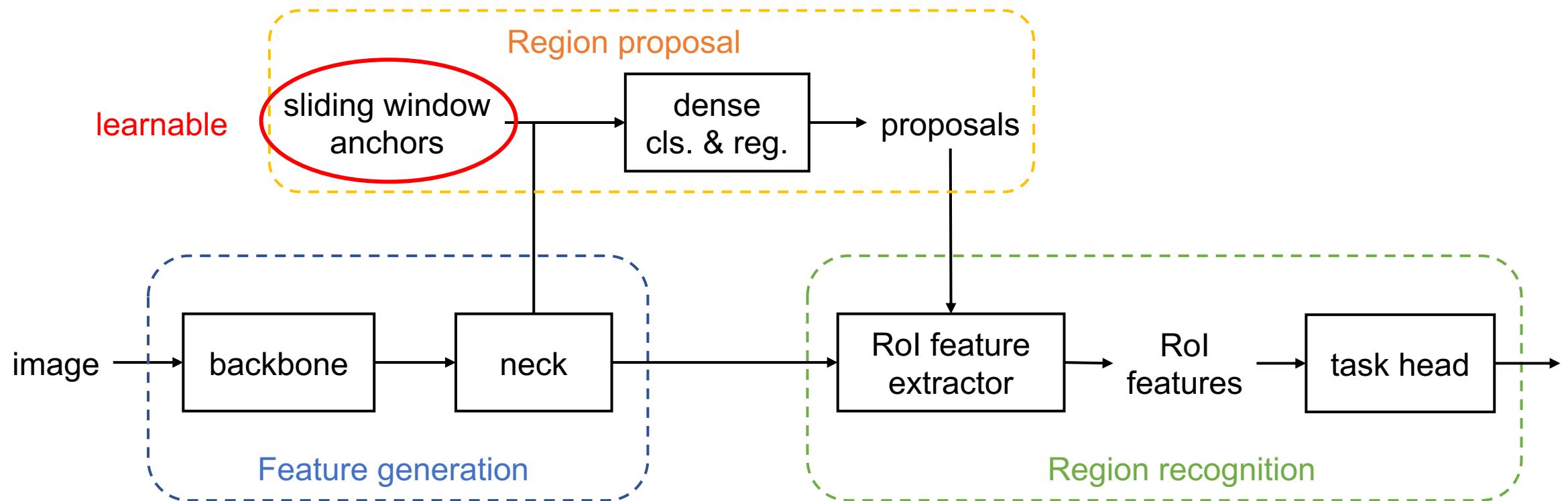
Hybrid Task Cascade (HTC)

Table 1: Comparison with state-of-the-art methods on COCO test-dev dataset.

Method	Backbone	box AP	mask AP	AP ₅₀	AP ₇₅	AP _S	AP _M	AP _L	runtime (fps)
Mask R-CNN [18]	ResNet-50-FPN	39.1	35.6	57.6	38.1	18.7	38.3	46.6	5.3
PANet[27]	ResNet-50-FPN	41.2	36.6	58.0	39.3	16.3	38.1	52.4	-
Cascade Mask R-CNN	ResNet-50-FPN	42.7	36.9	58.6	39.7	19.6	39.3	48.8	3.0
Cascade Mask R-CNN	ResNet-101-FPN	44.4	38.4	60.2	41.4	20.2	41.0	50.6	2.9
Cascade Mask R-CNN	ResNeXt-101-FPN	46.6	40.1	62.7	43.4	22.0	42.8	52.9	2.5
HTC (ours)	ResNet-50-FPN	43.6	38.4	60.0	41.5	20.4	40.7	51.2	2.5
HTC (ours)	ResNet-101-FPN	45.3	39.7	61.8	43.1	21.0	42.2	53.5	2.4
HTC (ours)	ResNeXt-101-FPN	47.1	41.2	63.9	44.7	22.8	43.9	54.6	2.1

COCO Challenge 2018

Guided anchoring



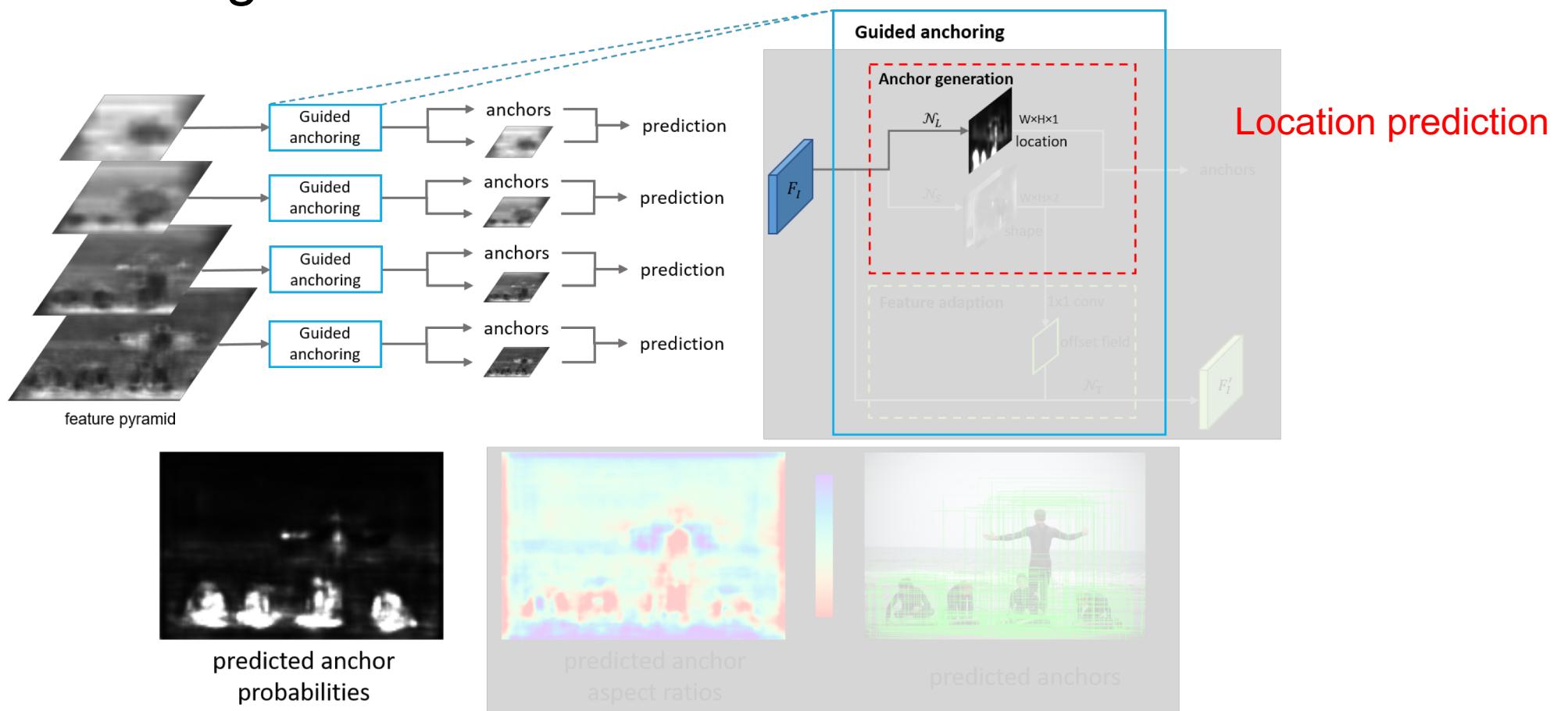
COCO Challenge 2018

Guided anchoring

- Our goal
 - Sparse
 - Arbitrary shape
- General rules for anchor design
 - Alignment
 - Consistency

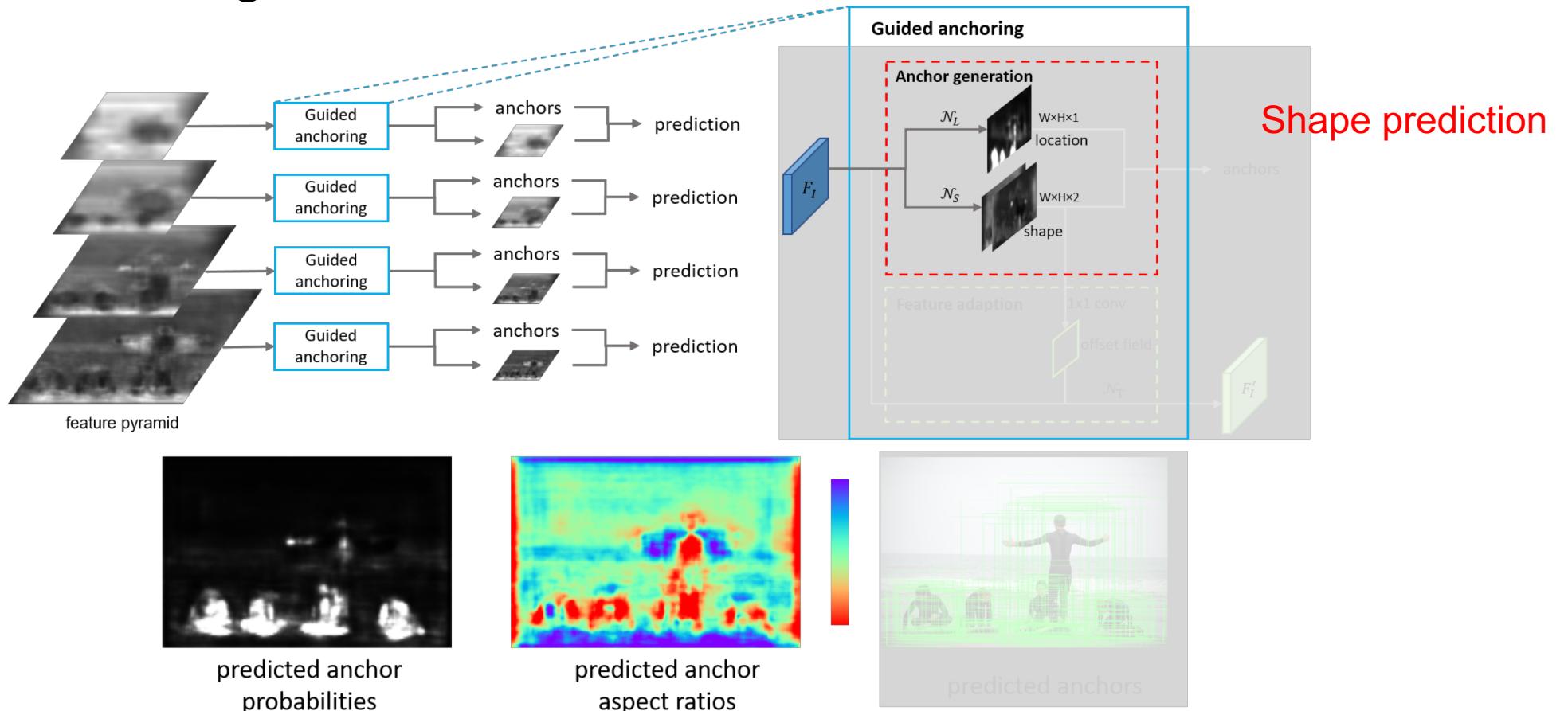
COCO Challenge 2018

Guided anchoring



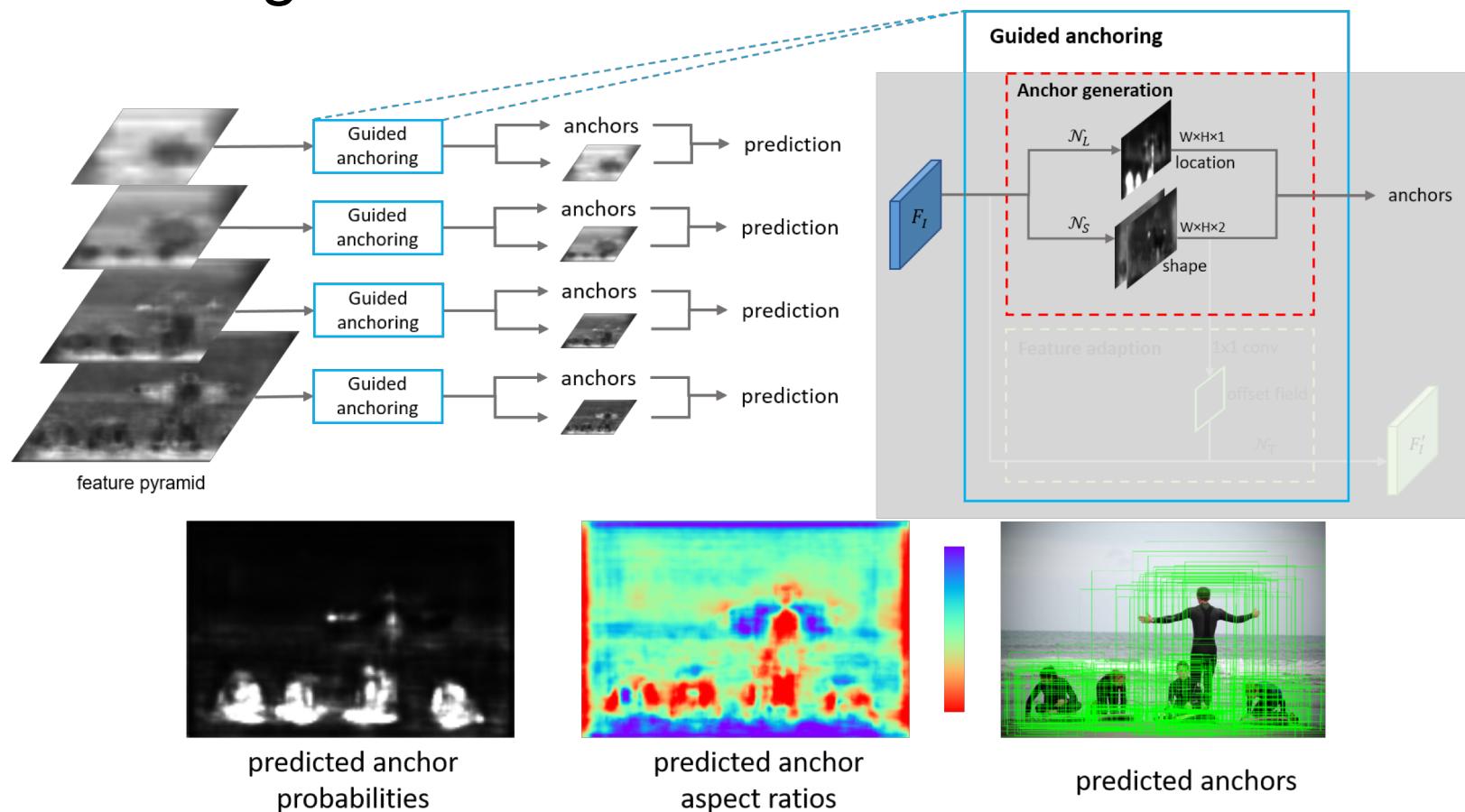
COCO Challenge 2018

Guided anchoring



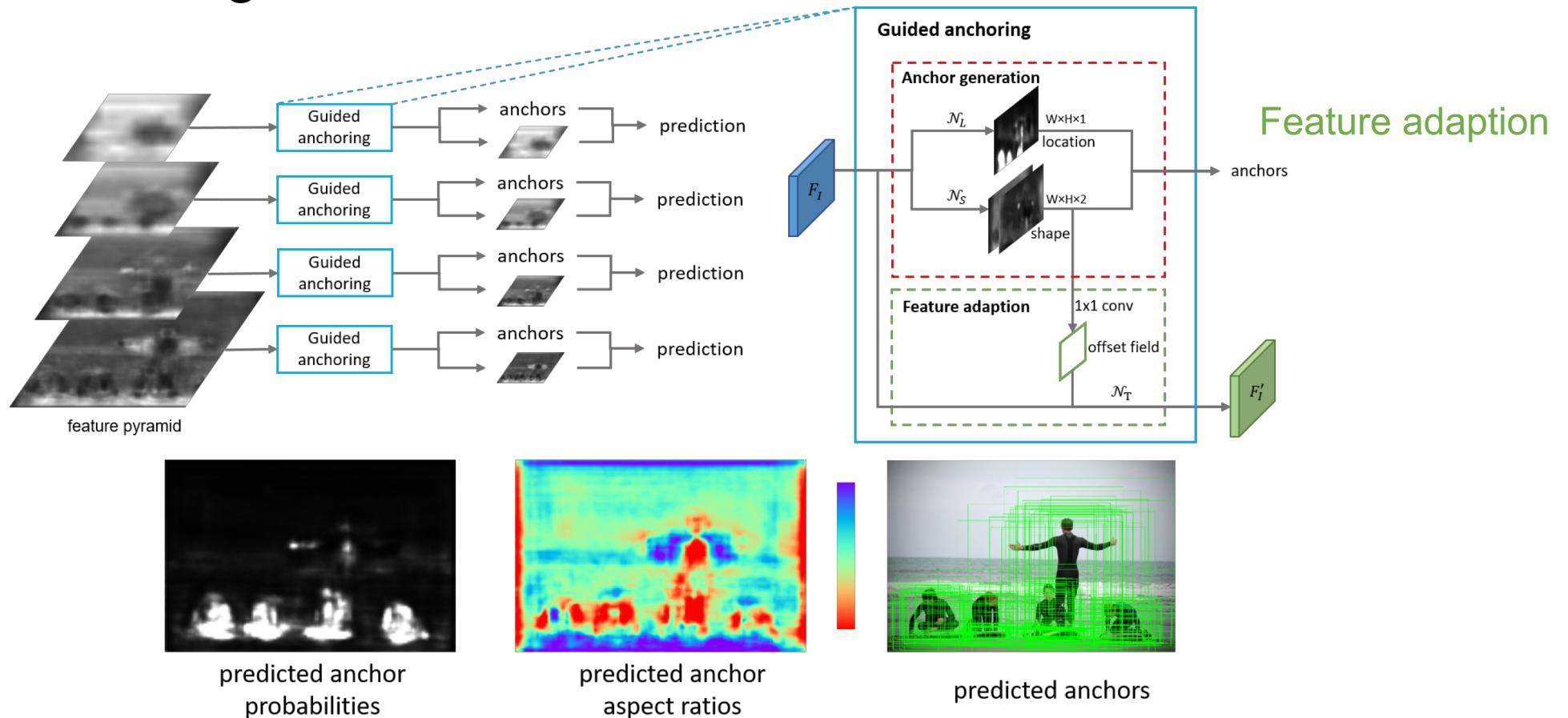
COCO Challenge 2018

Guided anchoring



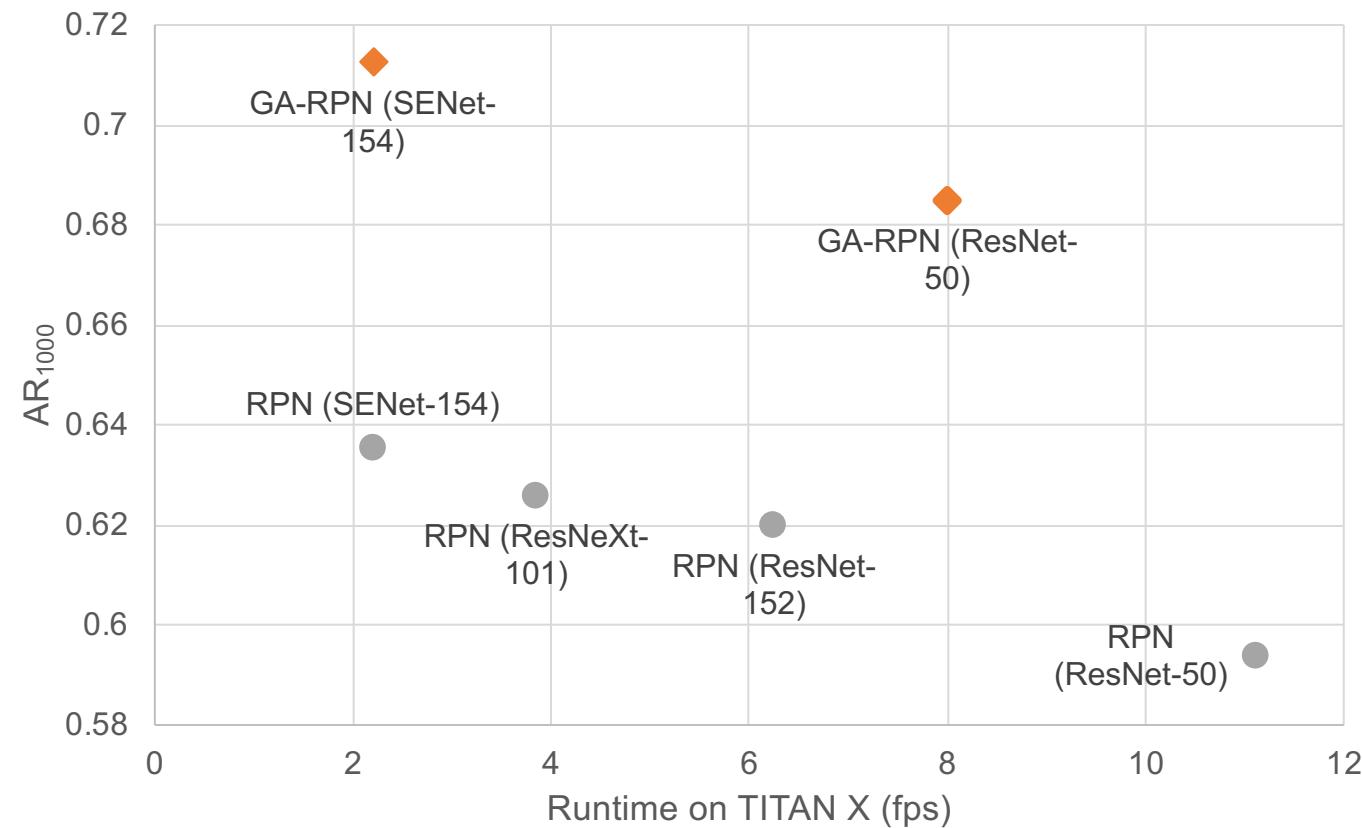
COCO Challenge 2018

Guided anchoring



COCO Challenge 2018

Guided anchoring



COCO Challenge 2018

Guided anchoring

Table 2: Detection results on MS COCO 2017 *test-dev*.

Method	AP	AP ₅₀	AP ₇₅	AP _S	AP _M	AP _L
Fast R-CNN	37.1	59.6	39.7	20.7	39.5	47.1
GA-Fast-RCNN	39.4	59.4	42.8	21.6	41.9	50.4
Faster R-CNN	37.1	59.1	40.1	21.3	39.8	46.5
GA-Faster-RCNN	39.8	59.2	43.5	21.8	42.6	50.7
RetinaNet	35.9	55.4	38.8	19.4	38.9	46.5
GA-RetinaNet	37.1	56.9	40.0	20.1	40.1	48.0

COCO Challenge 2018

- FishNet

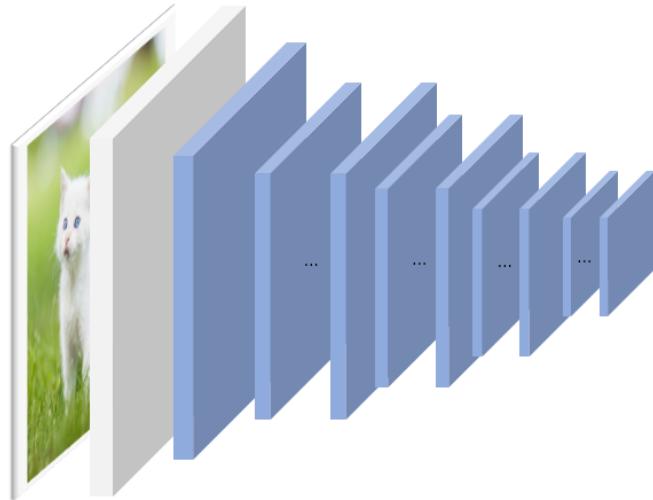
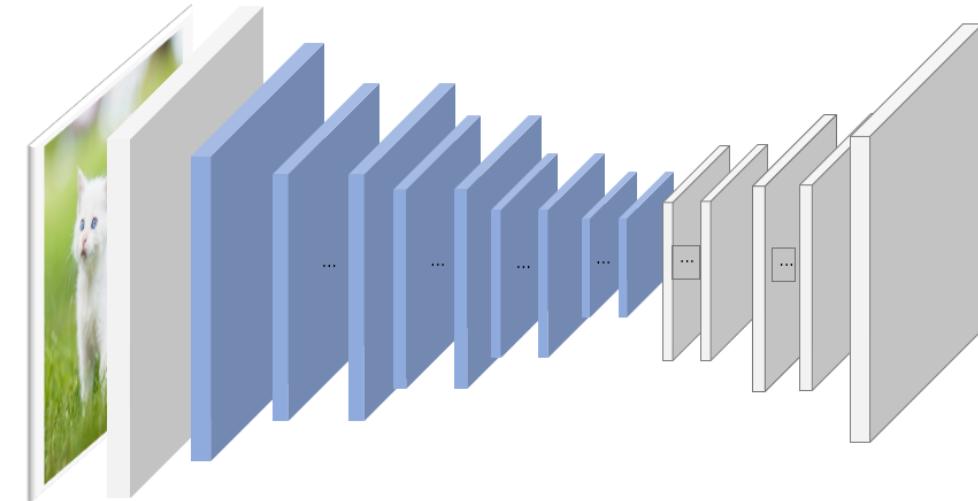


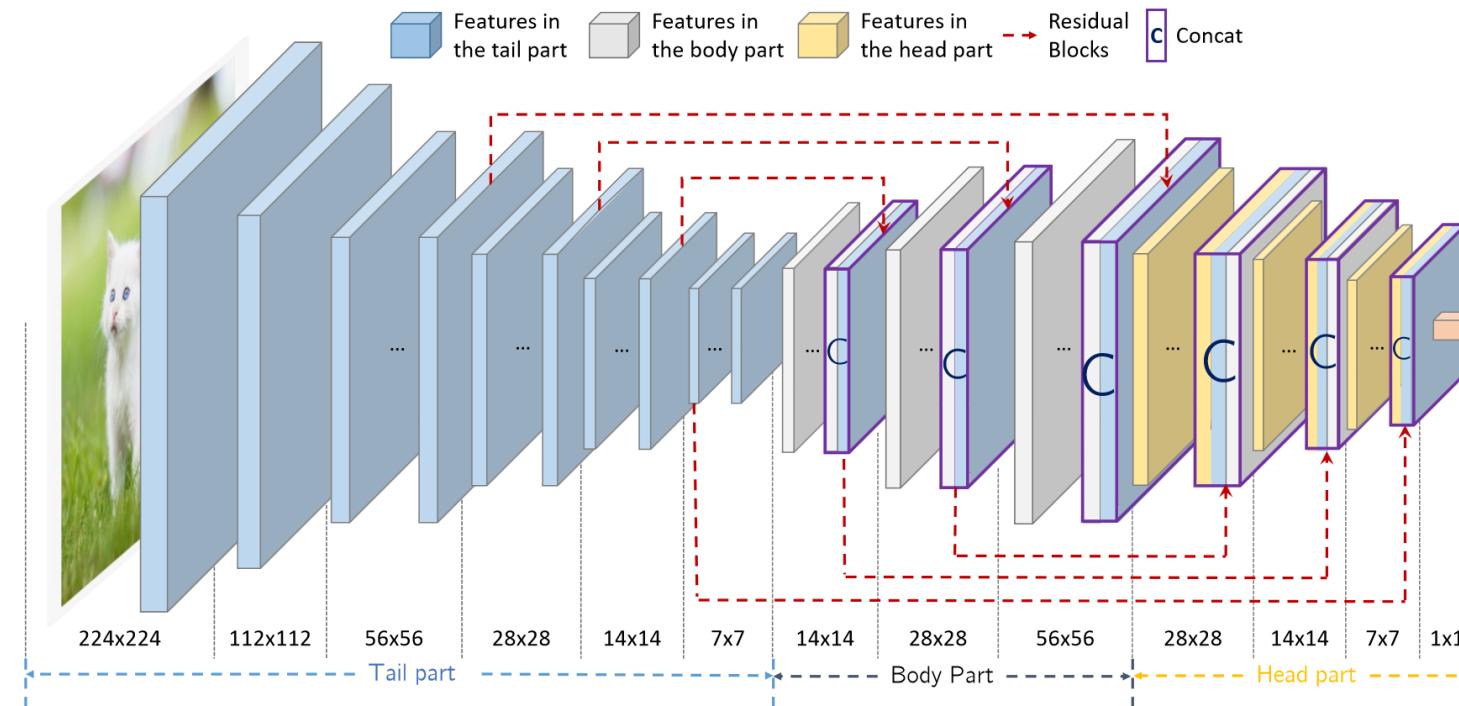
Image classification



Region and pixel level tasks
Segmentation, pose estimation, detection ...

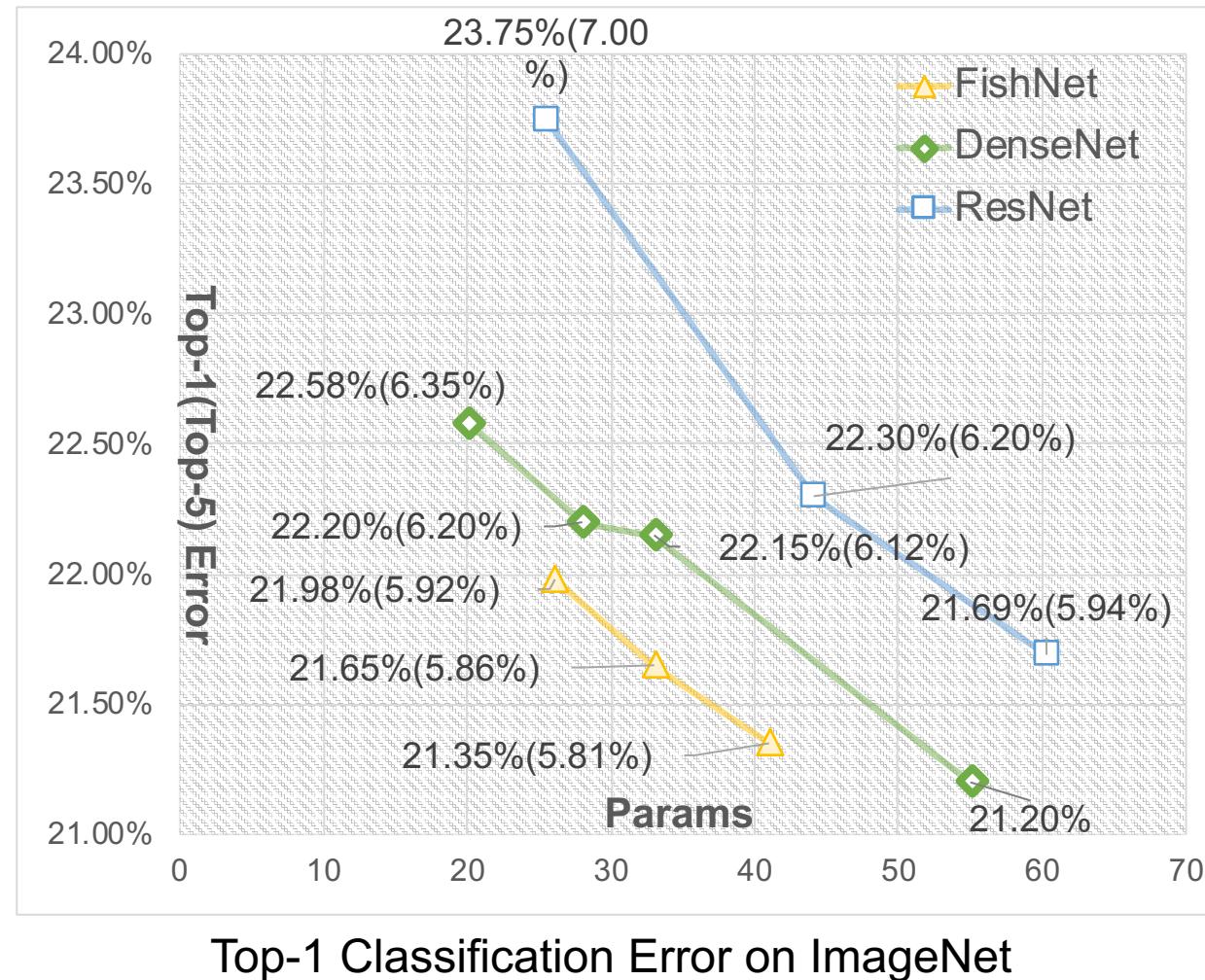
COCO Challenge 2018

- FishNet



COCO Challenge 2018

- FishNet



COCO Challenge 2018

- FishNet

MS COCO *val-2017* detection and instance segmentation results.

	Instance Segmentation	Object Detection
Backbone	$AP^s/AP_S^s/AP_M^s/AP_L^s$	$AP^d/AP_S^d/AP_M^d/AP_L^d$
ResNet-50 [3]	34.5/15.6/37.1/52.1	38.6/22.2/41.5/50.8
ResNet-50 [†]	34.7/18.5/37.4/47.7	38.7/22.3/42.0/51.2
ResNeXt-50 (32x4d) [†]	35.7/19.1/38.5/48.5	40.0/23.1/43.0/52.8
FishNet-188	37.0 /19.8/40.2/50.3	41.5 /24.1/44.9/55.0
vs. ResNet-50 [†]	+2.3/+1.3/+2.8/+2.6	+2.8/+1.8/+2.9/+3.8
vs. ResNeXt-50 [†]	+1.3/+0.7/+1.7/+1.8	+1.5/+1.0/+1.9/+2.2

COCO Challenge 2018

Implementation details

1. Training scales
 - short edge: random sampled from 400 ~ 1400
 - long edge: 1600
2. Test scales
 - (600, 900), (800, 1200), (1000, 1500), (1200, 1800), (1400, 2100)
3. Pipeline
 - Joint training
 - Finetune with GA-RPN proposals
 - Test with GA-RPN proposals
4. Resources
 - 32 Tesla V100 GPUs (16GB) for 3 days

COCO Challenge 2018

Implementation details

Backbones

- SENet-154
 - ResNeXt101 (64*4d)
 - ResNeXt101 (32*8d)
 - DPN-107
 - FishNet
- ~0.8 points higher
comparable

COCO Challenge 2018

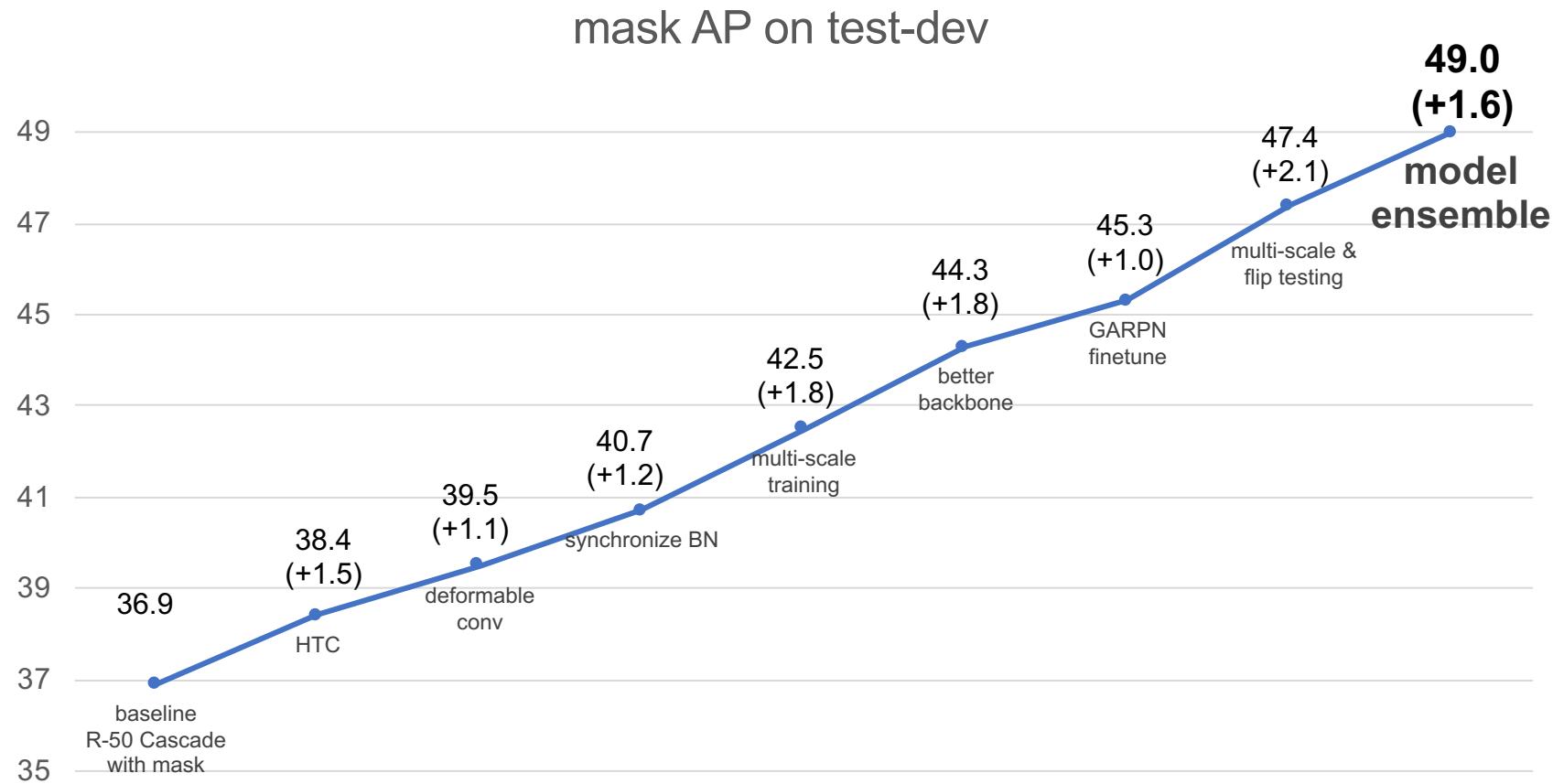
Implementation details

Other tricks

- w/ SoftNMS
- w/o OHEM
- w/o classwise balance sampling
- w/o voting for bbox or mask

COCO Challenge 2018

- With bells and whistles



Open-MMLab

- Project introduction: <https://zhuanlan.zhihu.com/p/47011261> by Dahua Lin
- Current repositories
 - mmcv
 - mmdetection

mm detection

- **Comprehensive**

- | | |
|---|---|
| <input checked="" type="checkbox"/> RPN | <input checked="" type="checkbox"/> Fast/Faster R-CNN |
| <input checked="" type="checkbox"/> Mask R-CNN | <input checked="" type="checkbox"/> FPN |
| <input checked="" type="checkbox"/> Cascade R-CNN | <input checked="" type="checkbox"/> RetinaNet |
| <input type="checkbox"/> More ··· ··· | |

- **High performance**

- Better performance
- Optimized memory consumption
- Faster speed

- **Handy to develop**

- Written with PyTorch
- Modular design



[GitHub: mm detection](#)