$$X \xrightarrow{f} Y \xrightarrow{g} Z \xrightarrow{\eta}$$

$$\downarrow^{v_X} \qquad \downarrow \qquad \parallel$$

$$V_X \longrightarrow E \xrightarrow{\text{TFib}} Z \longrightarrow$$

$$\downarrow^{u_X} \qquad \downarrow^{-a}$$

$$U_X = U_X$$

$$\downarrow^{\delta_X} \qquad \downarrow$$