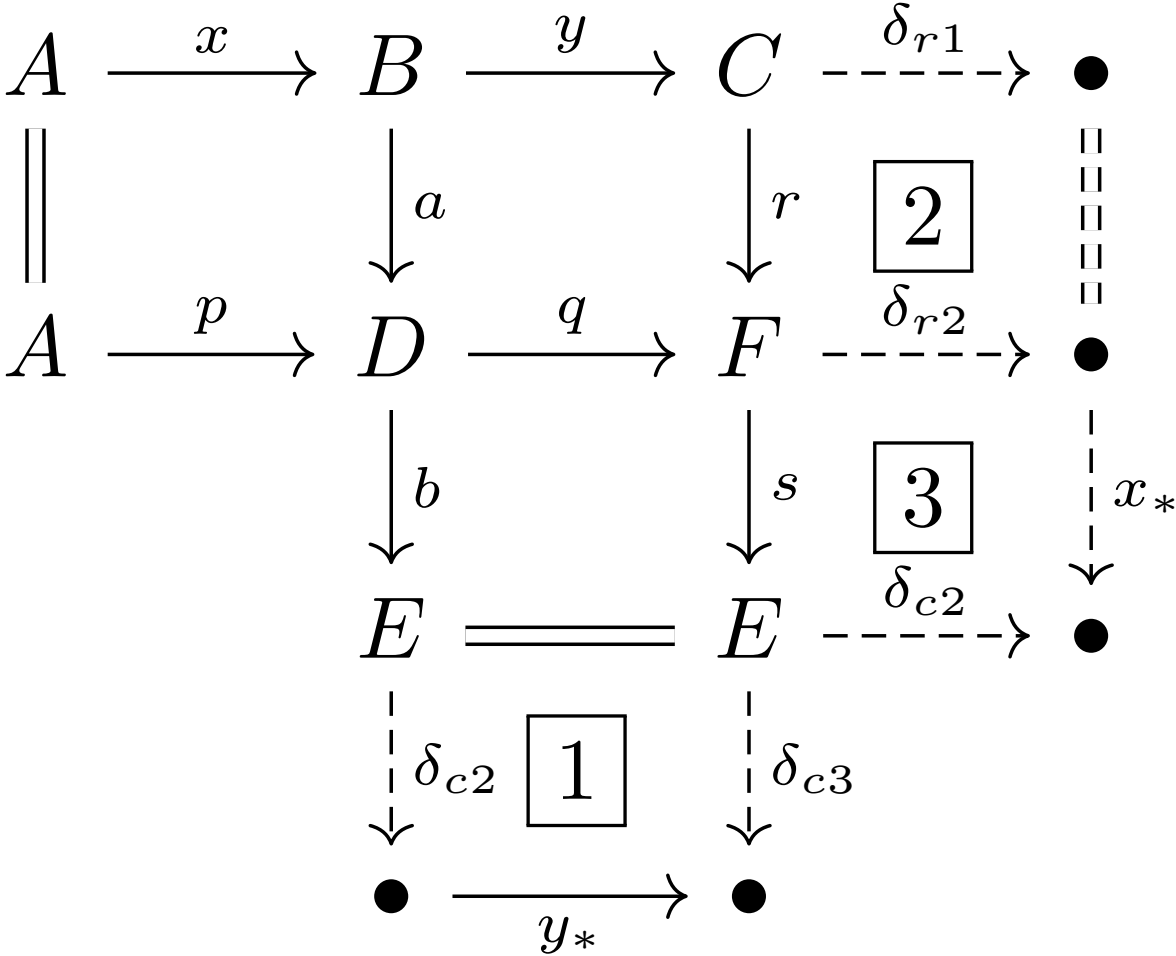
A
x
B
y
C
δr1
a
r
2
p
D
q
F
δr2
b
s
3
x∗
E
E
δc2
1
δc3
y∗