

Some Notes on Polylogarithm

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1 Two ways of defining (Multiple) Polylogarithm

1. MPL's can be defined by iterated integrals (Goncharov G -function)

$$G(\sigma_1, \sigma_2, \dots, \sigma_n; z) = \int_0^z \frac{dt}{t - \sigma_1} G(\sigma_2, \dots, \sigma_n; t) \quad (1.1)$$

with

$$G(z) := 1, \quad G(\vec{0}_n; z) := \frac{1}{n!} \log^n z. \quad (1.2)$$

In Panzer's notation(arXiv: 1403.3385), this function is denoted by $L_{\sigma_1, \dots, \sigma_n}$ or $L_{\omega_{\sigma_1}, \dots, \omega_{\sigma_n}}$

Furthermore, we introduce the iterated integrals with general endpoints

$$I(a_0; a_1, \dots, a_n; a_{n+1}) = \int_{a_0 < t_1 < \dots < t_n < a_{n+1}} \frac{dt_1 \dots dt_n}{(t_1 - a_1) \dots (t_n - a_n)} \quad (1.3)$$

2. MPL's can be defined by nested sums

$$\text{Li}_{m_1, \dots, m_k}(z_1, \dots, z_k) := \sum_{0 < n_1 < n_2 < \dots < n_k} \frac{z_1^{n_1} z_2^{n_2} \dots z_k^{n_k}}{n_1^{m_1} n_2^{m_2} \dots n_k^{m_k}} \quad \text{for } |z_i| < 1 \quad (1.4)$$

This can be viewed as a generation of classical polylogarithm:

$$\text{Li}_1(z) = \sum_{n=1}^{\infty} \frac{z^n}{n} = -\log(1 - z) = \int_0^z \frac{dt}{1 - t} \quad (1.5)$$

$$\text{Li}_k(z) = \sum_{n=1}^{\infty} \frac{z^n}{n^k} = \int_0^z \frac{dt}{t} \text{Li}_{k-1}(t) \quad (1.6)$$

This two kinds of MPL's are related by

$$G(\vec{0}_{m_1-1}, \sigma_1, \dots, \vec{0}_{m_k-1}, \sigma_k; z) = (-1)^k \text{Li}_{m_k, \dots, m_1} \left(\frac{\sigma_{k-1}}{\sigma_k}, \dots, \frac{\sigma_1}{\sigma_2}, \frac{z}{\sigma_1} \right) \quad (1.7)$$

Several special examples of G -functions

$$G(\vec{\sigma}_n; z) = \frac{1}{n!} \log^n \left(1 - \frac{z}{\sigma} \right) \quad G(\vec{0}_{n-1}, \sigma; z) = -\text{Li}_n \left(\frac{z}{\sigma} \right). \quad (1.8)$$

In this note, we will focus on G -functions and denote $G(\sigma_1, \sigma_2, \dots, \sigma_n; z)$ by $G(\vec{\sigma}; z)$

2 Shuffle algebras, derivatives, integrals of MPL's

According to the definition of G -function (1.1), the differentiation is trivial

$$\partial_z G(\sigma_1, \dots, \sigma_n; z) = \frac{1}{z - \sigma_1} G(\sigma_2, \dots, \sigma_n; z). \quad (2.1)$$

The integral of $R(z)G(\vec{\sigma}; z)$ with a rational function $R(z)$ is also easy due to

$$\int dz \frac{G(\vec{\sigma}; z)}{(z - \rho)^{n+1}} = -\frac{G(\vec{\sigma}; z)}{n(z - \rho)^n} + \int dz \frac{\partial_z G(\vec{\sigma}; z)}{n(z - \rho)^n}, \quad (2.2)$$

$$\int dz z^n G(\vec{\sigma}; z) = \frac{z^{n+1} G(\vec{\sigma}; z)}{n+1} - \int dz \frac{z^n \partial_z G(\vec{\sigma}; z)}{n+1} \quad (2.3)$$

Now let us consider a product of two G -functions

$$G(\vec{\sigma}; z)G(\vec{\rho}; z) = \int_{0 < t_n < t_{n-1} < \dots < t_1 < z} \frac{dt_1 \dots dt_n}{(t_1 - \sigma_1) \dots (t_n - \sigma_n)} \int_{0 < t'_m < t'_{m-1} < \dots < t'_1 < z} \frac{dt'_1 \dots dt'_m}{(t'_1 - \rho_1) \dots (t'_m - \rho_m)}.$$

This integral can be expressed as a sum of iterated integral by decomposed the integration region into simplexes. Obviously, The only request on t and t' in each simplex is that they should preserve their origin orders, respectively. Then all simplexes correspond to all possible relative orders between t and t' . Thus, we end up with

$$G(\vec{\sigma}; z)G(\vec{\rho}; z) = \sum_{\vec{\omega} \in \vec{\sigma} \sqcup \vec{\rho}} G(\vec{\omega}; z) \quad (2.4)$$

Example:

$$\begin{aligned} G(a_1, a_2; z)G(b_1, b_2; z) &= G(a_1, a_2, b_1, b_2; z) + G(a_1, b_1, a_2, b_2; z) + G(b_1, a_1, a_2, b_2; z) \\ &+ G(a_1, b_1, b_2, a_2; z) + G(b_1, a_1, b_2, a_2; z) + G(b_1, b_2, a_1, a_2; z) \end{aligned}$$

3 Symbol of MPL

There are two approaches to define the symbol for a MPL (iterated integral). One is coproduct, the other is differential.

1. Coproduct

There is a Hopf algebra on the space of iterated integrals(arXiv:math/0208144), that is, we can define coproduct for an iterated integral

$$\begin{aligned} &(\Delta(I(a_0; a_1, \dots, a_n; a_{n+1}))) \\ &= \sum_{0=i_0 < i_1 < \dots < i_k < i_{k+1}=n+1} I(a_0; a_{i_1}, \dots, a_{i_k}; a_{n+1}) \otimes \left(\prod_{p=0}^k I(a_{i_p}; a_{i_{p+1}}, \dots, a_{i_{p+1}-1}; a_{i_{p+1}}) \right) \end{aligned}$$

The symbol (map) can be defined as the maximal iteration of the coproduct (modulo $i\pi$)

$$S(F) = \Delta_{1,\dots,1}(F) \bmod i\pi \quad (3.1)$$

(For a clear review of Hopf algebra, see arXiv:1203.0454)

2. Differential

The total differential of a MPL's $F^{(n)}(\sigma_1, \dots, \sigma_m)$ can be written as

$$dF^{(n)} = \sum_i F_i^{(n-1)} d \log R_i \quad (3.2)$$

where R_i are rational functions of $\sigma_1, \dots, \sigma_m$, then the symbol of $F^{(n)}$ can be computed recursively by

$$S(F^{(n)}) = \sum_i S(F_i^{(n-1)}) \otimes R_i. \quad (3.3)$$

Indeed, the differential of a iterated integral is

$$dI(a_0; a_1, \dots, a_n; a_{n+1}) = \sum_{i=1}^n I(a_0; a_1, \dots, \hat{a}_i, \dots, a_n; a_{n+1}) d \log \frac{a_{i+1} - a_i}{a_i - a_{i-1}}. \quad (3.4)$$

Example:

$$S\left(\prod_{i=1}^n \log a_i\right) = \sum_{\sigma \in S_n} a_{\sigma(1)} \otimes \dots \otimes a_{\sigma(n)}, \quad S\left(\text{Li}_n(z)\right) = -((1-z) \otimes \underbrace{z \otimes \dots \otimes z}_{n-1}) \quad (3.5)$$

It is easy to see that

$$A \otimes a \otimes B + A \otimes b \otimes B = A \otimes ab \otimes B \quad (3.6)$$

$$A \otimes \rho_n \otimes B = 0 \quad (3.7)$$

$$S(FG) = S(F) \sqcup S(G) \quad (3.8)$$

where ρ_n is an n -th root of unity.

The introduction of symbol trivialize the functional relation of MPL, for example

$$\text{Li}_2(1-z) = \zeta_2 - \text{Li}_2(z) - \log(z) \log(1-z). \quad (3.9)$$

To integrate a symbol

$$S = \sum_{I=(i_1, \dots, i_n)} c_I a_{i_1} \otimes \dots \otimes a_{i_n} \quad (3.10)$$

to a function, the symbol must satisfy the integrability condition

$$\sum c_I a_{i_1} \otimes \dots \otimes a_{i_{p-1}} \otimes a_{i_{p+2}} \otimes \dots \otimes a_{i_n} d \log a_{i_p} \wedge d \log a_{i_{p+1}} = 0 \quad (3.11)$$

for every consecutive pair of indices.

4 Symbol Integration

(This part is the same as the argument in arXiv:1806.06072)

Consider the following integral where the integrand converges both at zero and infinity (more generally one can consider an integral with finite integration endpoints),

$$I(y, x_i) = \int_0^\infty d \log(x+y) F^{(n)}(x, x_i) \equiv \int_0^\infty \frac{dx}{x+y} F^{(n)}(x, x_i). \quad (4.1)$$

The first step in the symbol integration involves taking the total differential of the integral $I(y, x_i)$,

$$\begin{aligned} dI(y, x_i) &= [dy \partial_y + dx_i \partial_{x_i}] I(y, x_i) \\ &= -dy \int_0^\infty \frac{dx}{(x+y)^2} F^{(n)}(x, x_i) + dx_i \int_0^\infty \frac{dx}{(x+y)} \partial_{x_i} F^{(n)}(x, x_i). \end{aligned} \quad (4.2)$$

The first term we write as a derivative with respect to x and integrate by parts, we find

$$dy \int_0^\infty dx \left[\partial_x \frac{1}{(x+y)} \right] F^{(n)}(x, x_i) = dy \frac{F^{(n)}(x, x_i)}{x+y} \Big|_{x=0}^{x=\infty} - dy \int_0^\infty \frac{dx}{(x+y)} \partial_x F^{(n)}(x, x_i). \quad (4.3)$$

Since the $F^{(n)}(x, x_i)$ are MPL's,

$$\begin{aligned} \partial_x F^{(n)}(x, x_i) &= \sum_j F_j^{(n-1)}(x, x_i) \frac{\partial \log(x + \beta_j)}{\partial x} \\ \partial_{x_i} F^{(n)}(x, x_i) &= \sum_j F_j^{(n-1)}(x, x_i) \frac{\partial \log(x + \beta_j)}{\partial \beta_j} \left(\frac{\partial \beta_j}{\partial x_i} \right) + \sum_{j'} H_{j'}^{(n-1)}(x, x_i) \frac{\partial \log f_{j'}}{\partial x_i} \end{aligned} \quad (4.4)$$

where $f_{j'}$ are functions of x_i 's only.

Taking the boundary term at $x = \infty$ to vanish, the differential of the integral becomes,

$$\begin{aligned} dI(y, x_i) &= -d \log y F^{(n)}(0, x_i) - \sum_j dy \int_0^\infty \frac{dx}{(x+y)(x+\beta_j)} F_j^{(n-1)} \\ &\quad + \sum_j dx_i \underbrace{\left(\frac{\partial \beta_j}{\partial x_i} \right)}_{=d\beta_j} \int_0^\infty \frac{dx}{(x+y)(x+\beta_j)} F_j^{(n-1)} \\ &\quad + \sum_{j'} dx_i \underbrace{\frac{\partial \log f_{j'}}{\partial x_i}}_{=d \log f_{j'}} \int_0^\infty \frac{dx}{(x+y)} H_{j'}^{(n-1)} \end{aligned} \quad (4.5)$$

We use partial fraction for the first two terms,

$$\frac{1}{(x+y)(x+\beta_j)} = \frac{1}{(y-\beta_j)} \left[\frac{1}{(x+\beta_j)} - \frac{1}{(x+y)} \right]. \quad (4.6)$$

Putting everything together, we find,

$$\begin{aligned} dI = & -d \log y F^{(n)}(0, x_i) + \sum_{j'} d \log f_{j'} \int_0^\infty \frac{dx}{(x+y)} H_{j'}^{(n-1)} \\ & - \sum_j \left[\frac{dy}{(y-\beta_j)} - \frac{d\beta_j}{(y-\beta_j)} \right] \int_0^\infty \left[\frac{dx}{(x+\beta_j)} - \frac{dx}{(x+y)} \right] F_j^{(n-1)}. \end{aligned} \quad (4.7)$$

Combining the respective terms in the brackets back into $d \log$ -forms, we recover the expressions

$$\begin{aligned} dI(y, x_i) = & -d \log y F^{(n)}(0, x_i) + \sum_{j'} d \log f_{j'} \int_0^\infty d \log(x+y) H_{j'}^{(n-1)}(x, x_i) \\ & + \sum_j d \log(y-\beta_j) \int_0^\infty d \log \left(\frac{x+y}{x+\beta_j} \right) F_j^{(n-1)}(x, x_i) \end{aligned} \quad (4.8)$$

5 MPL Integration

(This part follows from arXiv: 0804.1660 and arXiv:1403.3385, for more details, see arXiv:1407.0074)

In the calculation of Feynman integrals or the α' -expansions of string integrals or other cases, we will usually encounter integrals involving MPL's, but the integral is of form

$$\int dz R(z) G(\vec{\sigma}(z); z'(z)) \quad (5.1)$$

rather simply $\int dR(z) G(\vec{\sigma}; z)$ we have discussed in sec.2. To perform the integration in (5.1), we need to express $G(\vec{\sigma}(z); z'(z))$ as

$$G(\vec{\sigma}(z); z'(z)) = \sum_{\vec{\tau}} c_{\vec{\tau}} G(\vec{\tau}; z) \quad (5.2)$$

In the practical cases, the integral of form (5.1) usually appear in the intermediary steps of calculation of

$$f_n = \int_0^\infty dz_n f_{n-1}(z_n) = \int_0^\infty dz_1 \cdots \int_0^\infty dz_n f_0 \quad (5.3)$$

with certain polylogarithms $f_0(\vec{z})$. Suppose $f_{k-1}(z_k)$ has a primitive $F(z_k)$, then

$$\int_0^\infty f_{k-1}(z_k) dz_k = \lim_{z_k \rightarrow \infty} F(z_k) - \lim_{z_k \rightarrow 0} F(z_k) \quad (5.4)$$

There are divergences in each limit, although these divergences must cancel at the end. Thus, it would be convenient define a regularized limit for MPL $G(\vec{\sigma}; z)$. The singularities of $G(\vec{\sigma}; z)$ at $z \rightarrow \tau$ are logarithmic at worst, so we have the expansion

$$G(\vec{\sigma}(z)) = \sum_{i=0}^{|\vec{\sigma}|} f_{\vec{\sigma}, \tau}^{(i)}(z) \log^i(z - \tau). \quad (5.5)$$

Then regularized limits are defined as

$$\text{Reg}_{z \rightarrow \tau} G(\vec{\sigma}; z) := f_{\vec{\sigma}, \tau}^{(0)}(\tau) \quad (5.6)$$

(For more details of regularized limits, see arXiv:1407.0074)

Then our problem becomes to express $\text{Reg}_{z_k \rightarrow \infty} G(\vec{\sigma}; z_k)$ in terms of $G(*; z_{k+1})$. We can approach this problem by taking partial differential of $G(\vec{\sigma}; z_k)$ with respect to $z_{k+1} := t$, then we find

$$\begin{aligned} \partial_t G(\vec{\sigma}; z_k) &= \sum_{i=1}^{k-1} \partial_t \log(\sigma_i(t) - \sigma_{i+1}(t)) \left(G(\sigma_1, \dots, \hat{\sigma}_{i+1}, \dots, \sigma_k; z_k) - G(\sigma_1, \dots, \hat{\sigma}_i, \dots, \sigma_k; z_k) \right) \\ &\quad + \partial_t \log(\sigma_1 - z_k) G(\sigma_2, \dots, \sigma_k; z_k) - \partial_t \log \sigma_k G(\sigma_1, \dots, \sigma_{k-1}; z_k) \end{aligned} \quad (5.7)$$

Using $\text{Reg}_{z_k \rightarrow \infty} \partial_t = \partial_t \text{Reg}_{z_k \rightarrow \infty}$ yields

$$\begin{aligned} &\partial_t \text{Reg}_{z_k \rightarrow \infty} G(\vec{\sigma}; z_k) \\ &= -\partial_t \log \sigma_k \text{Reg}_{z_k \rightarrow \infty} G(\sigma_1, \dots, \sigma_{k-1}; z_k) \\ &\quad + \sum_{i=1}^{k-1} \partial_t \log(\sigma_i(t) - \sigma_{i+1}(t)) \text{Reg}_{z_k \rightarrow \infty} \left(G(\sigma_1, \dots, \hat{\sigma}_{i+1}, \dots, \sigma_k; z_k) - G(\sigma_1, \dots, \hat{\sigma}_i, \dots, \sigma_k; z_k) \right) \end{aligned} \quad (5.8)$$

To make sure $\text{Reg}_{z_k \rightarrow \infty} G(\vec{\sigma}; z_k)$ is polylogarithms of t , We assume that $\sigma_1, \dots, \sigma_k \in \mathbb{Q}(t)$ such that any $\sigma_i - \sigma_j = c \prod_{\tau} (t - \tau)^{\lambda_{\tau}}$. We can use the same trick recursively in the right hand side, and end up with

$$\partial_t \text{Reg}_{z_k \rightarrow \infty} G(\vec{\sigma}; z_k) = \sum_{\vec{\rho} \in \Sigma_t^\times, \tau \in \Sigma_t} \frac{\lambda_{\tau, \vec{\rho}}}{t - \tau} G(\vec{\rho}; t) \cdot c_{\vec{\rho}} \quad (5.9)$$

where $\lambda_{\tau, \vec{\rho}} \in \mathbb{Z}$, $c_{\vec{\rho}}$ is some constants,

$$\Sigma_t := \left\{ \text{zeros of } \prod_{i < j} [\sigma_i(t) - \sigma_j(t)] \right\}. \quad (5.10)$$

So

$$\text{Reg}_{z_k \rightarrow \infty} G(\vec{\sigma}; z_k) = C + \sum_{\vec{\rho} \in \Sigma_t^\times, \tau \in \Sigma_t} \lambda_{\tau, \vec{\rho}} G(\vec{\rho}; t) c_{\vec{\rho}} \quad (5.11)$$

where the integration constant C is determined by

$$C = \text{Reg}_{t \rightarrow 0} \text{Reg}_{z_k \rightarrow \infty} G(\vec{\sigma}; z_k). \quad (5.12)$$

This procedure is known as “expansion on a fibration basis”.