

The background of the JUNO calibration system

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Abstract

Jiangmen Underground Neutrino Observatory (JUNO) is reactor neutrino detector with 20 kton liquid scintillator as a target. The main goal of JUNO is to determine the neutrino mass hierarchy (MH) via precisely measurement of anti-neutrino oscillation spectrum. The measurement requires high energy resolution (3% at 1 MeV) and small uncertainty (less than 1%), which give a huge challenge to calibration system. The devices of calibration system close to the central detector will increase the background, which worsen the energy resolution and thereby lower the MH sensitivity. In addition, the background will also deteriorate other neutrino spectrum like supernova neutrino, solar neutrino and so on. In this study, we will discuss the contribution background from calibration system.

Keywords: JUNO, Calibration, background, radioactivity.

1. The JUNO Introduction

Jiangmen Underground Neutrino Observatory (JUNO) is a multi-purpose neutrino experiment. The main goal of JUNO is to determine the neutrino mass hierarchy (MH) via precisely measuring reactor anti-neutrino oscillation spectrum.

The JUNO experiment is in Jiangmen city, Guangdong province, China, 53 km from Yangjiang and Taishan nuclear power plants (NPP). The target of JUNO is 20 kton liquid scintillator with 12 cm thickness spherical acrylic shell as container. The central detector is a 35.4 m diameter ball within a water pool. The water pool a 40 m high and 40 m diameter cylinder filled with ultra-pure

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11 water as a buffer to stop the external radioactivity. There are about 18000
12 20-inch and 25000 3-inch photomultipliers (PMTs) closed the central detector
13 with about 75% coverage.

14 The reactor anti-neutrino could be detected via so-called inverse beta decay
15 (IBD) reaction, $\bar{\nu}_e + p \rightarrow e^+ + n$. The positron will deposit energy first as a
16 prompt signal, while the neutron will be captured by the nuclear (proton or
17 carbon) within about 200 us as a delay signal. With the pair of prompt signal
18 positron and delay signal neutron, the efficiency of IBD events selection could
19 be significantly improved. However, the background of physics-like events will
20 smear the prompt and delay signal, which will reduce the efficiency and quality.
21 Two physics-like events from background with interval time of about 200 us will
22 be falsely identified as IBD events. And the extra introduced background events
23 will distort the reactor neutrino spectrum, and thereby worse the neutrino MH
24 sensitivity.

25 The background is mainly from cosmogenic and nature radioactive isotopes.
26 In the LS, the interaction of energetic cosmic muons with C-12 will produce
27 radioactive isotopes like Li-9, He-8, B-12 and so on. The radioactive isotope is
28 not stable and will decay to emission alpha, beta and gamma particles. Espe-
29 cially for Li-9 and He-8, they can emission both a beta and a neutrino, just like
30 a IBD signal, which will significantly influence the efficiency of IBD selection.
31 The other background source, nature radioactive isotopes is from kinds of ma-
32 terial used in the experiment. The isotopes mainly include U-238, Th-232, and
33 K-40, which have long-lived time at billion years level. The radioactive material
34 includes LS, acrylic, stainless steel, PMT and material from calibration system.
35 In principle, the closer to detector, the more significant of background contribu-
36 tion to experiment. Since the part of calibration device is close and even in the
37 central detector, so the background of calibration system contribution should
38 be significantly treated.

39 In this paper, we will study the influence of calibration system on the JUNO
40 experiment background, which consists of the following ingredients: Measure-
41 ment of radioactive material of calibration system. Background contribution
42 via MC simulation. The influence on MH sensitivity.

43 2. The JUNO calibration system

44 The JUNO calibration system is designed to mainly correct the energy re-
45 sponse of non-linearity and detector non-uniformity, which requires the multi-

46 ple sources to reach multiple locations. To meet the calibration requirement,
 47 there is no choice to totally avoid contact with the central detector even some
 48 components permanently in it. The calibration systems includes 4 deployment
 49 sub-systems as shown in Fig. 1 and 2 positioning sub-systems.

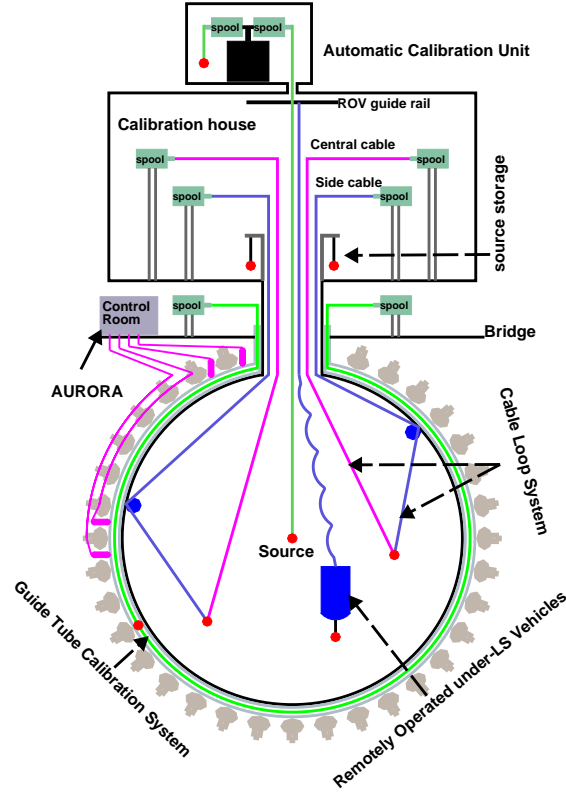


Figure 1: The overview of JUNO Calibration systems

50 2.1. Automatic Calibration Unit (ACU)

51 The ACU is located at the top of the calibration house, which keep away
 52 from the central detector (CD). So normally, the contribution of ACU can be
 53 ignored. Only in the calibration turn, the calibration source of ACU attached
 54 on cable will enter the CD. The routine calibration sources include laser source

55 and radioactive source. The rate of laser source and radioactive source are
56 respectively 50 Hz and 100 Hz. The only fact we should concern is whether the
57 background rate of cable is enough high to affect the calibration data.

58 *2.2. Cable Loop System*

59 The strategy of CLS is to deploy the calibration source in a vertical section
60 via adjusting the length of two cables, called center cable and side cable respec-
61 tively. And the side cable will go through a anchor, a piece of 3.2 kg PTFE
62 attached on inner surface of acrylic shell. Based on the design of CLS, part of
63 side cables will be permanently in the central detector (CD) during the physics
64 data taking. The length of cable in the CD is ?? m, and the total mass is ??
65 kg. The core of the cable is stainless steel (SS), while the shell is PTFE.

66 *2.3. Guide Tube Calibration System (GTCS)*

67 The GTCS is a tube looped outside of the acrylic sphere along a latitude
68 line, within which a radioactive source with cables attached to both ends gets
69 driven around with good positioning precision. The design of this system is
70 discussed in details in Ref. [?]. MeV-scale gammas can easily penetrate the
71 12 cm acrylic and deposit energy in the LS region, although the full absorption
72 peak is mixed with a somewhat significant leakage tail (correctable by fitting).
73 Based on the simulation studies in Ref. [?], this configuration is sufficient to
74 calibrate the CD non-uniformity at the boundary.

75 *2.4. Remotely Operated under-LS Vehicles (ROV)*

76 ROV

77 *2.5. USS*

78 USS is a significant component of JUNO calibration system. The system is
79 permanently in JUNO central detector for calibration source position determi-
80 nation. To avoid the problem of multiple paths that will worse the precision
81 of position measurement, the USS receiver will be installed in the inner of
82 CD, meaning that it will permanently contact with LS. Since the components
83 of USS are in the LS of JUNO, it will introduce non-negligible background to
84 the detector.

85 The radioactivity isotopes will emit MeV energy level particles (alpha, beta,
86 gamma), which is in the energy range of physics events. These particles will
87 enter to the detector and be detected, resulting signal disturbing the real physics

88 signal, which is called background. So controlling the background of USS is a
89 work for JUNO calibration. The USS includes cables, which is close the Acrylic
90 inner sphere, with total length xx m, and 8 ultrasonic receivers, which is attached
91 on acrylic shell. The USS cables consist of Teflon and stainless steel (SS), with
92 diameter 1 mm. The line density is 0.01 kg/m. The ultrasonic receivers consist
93 of two parts, NI and PCB with mass 0.106 kg.

94 2.6. CCD

95 2.7. AURORA

96 3. Radioactive background

97 3.1. Potential background

- 98 1. isotopes: U,Th,K,Cs,Co, Radon, Kr.
- 99 2. decay: gamma, beta, alpha,
- 100 3. bulk, surface, emanation

101

102 3.2. Requirements and budget

103 The main background is from LS, The overall budget should be kept less
104 than 0.2 Hz.

105

Calibration component location	Items
Inside CD (permanently)	USS receivers
Inside CD (permanently)	USS cable
Inside CD (permanently)	CLS cable
Inside CD (permanently)	Anchor and mounting structure
106 Inside CD (permanently)	Surface cleanliness
Radon emanation of the calibration house	ACU/CLS spool/ROV/Calibration house
Outside CD (permanently)	GT
Outside CD (permanently)	CCD
Outside CD (permanently)	AURORA

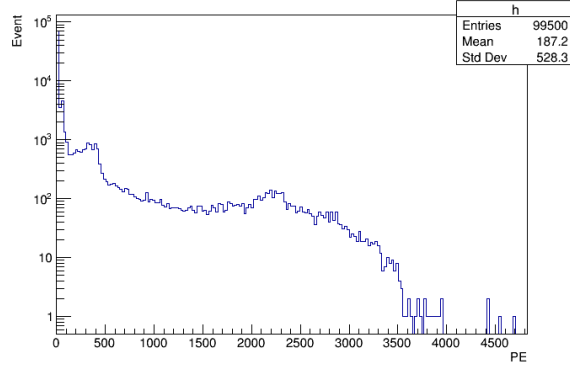


Figure 2: Simulation for U238 in USS receiver

4. Simulation method, cut

4.1. Simulation method

SNIPER is an official tool to simulate JUNO experiment. The main detector geometry is developed by JUNO software members, but not including USS related geometry. So first, we need draw the geometry of USS, and put it into the whole detector in correct position. And then assume the radioactive sources (U238, Th232, K40) are uniformly distributed in the material. The simulation will run for every component independently. After the simulation, the total PE spectrum will be obtain as shown in Fig. 2.

4.2. Energy and Fiducial volume cut

With the MC simulation, we can calculate the efficiency of radioactivity particles detected. However, the truth is that not all events can affect the real physics signal.

Considering that the energy of prompt IBD signal is above 1 MeV. So one energy cut of 700 keV could basically remove the low energy events that won't affect the IBD spectrum.

Duo to the sharply increased background, poor calibration and bad vertex reconstruction at the boundary of detector, the quality of physics events at the boundary will decrease. To ensure the quality of physics events, 0.5 m cut will be carried out during calculation, which means that we only calculate the events with radius less than 17.2m (the radius of detector is 17.7m).

128 4.3. Survival probability

129 With given number of simulation events, after above cut, a ratio of residual
130 events and the initial events can be calculated. The ratio is called survival
131 probability, which is radioactive isotopes, positions and geometry dependent.
132 The survival probability is one of the key points to reflect the importance to
133 the detector background. And with known survival probability and material
134 radioactivity, the background contribution to the detector could be calculated.

135 Table? shows the summary of survival probability of calibration system
136 survival probability.

137 Analysis the results for each sub-systems

138 5. Radioactivity measurement

139 To control the background from JUNO calibration system, first we need to
140 select pure material with low radioactivity. We used the high pure germanium
141 detector located in Jinpin underground experiment to test the radioactivity of
142 the material as shown in Fig 1. The table 1 shows the testing result, which is
143 best material we obtain so far. The Th232 and U238 radioactivity is measured
144 from two daughter nuclear, to be conservative, we use the maximum of the
145 two value as the final material radioactivity. The result seems good with low
146 radioactivity. But to preciously calculate the background contribution, we need
147 MC simulation to scale the value.

148 6. Radioactive background result

149 6.1. Calibration systems

150 6.1.1. ACU

151 Since there are no component of ACU permanently in central detector, so
152 the only concern about ACU background contribution is for calibration data.
153 The background is from mechanical cable for radioactive source and optical fiber
154 for laser source. The background rates of mechanical cable and optical fiber are
155 respectively ?? mHz and ?? mHz, negligible compared with the calibration
156 source.

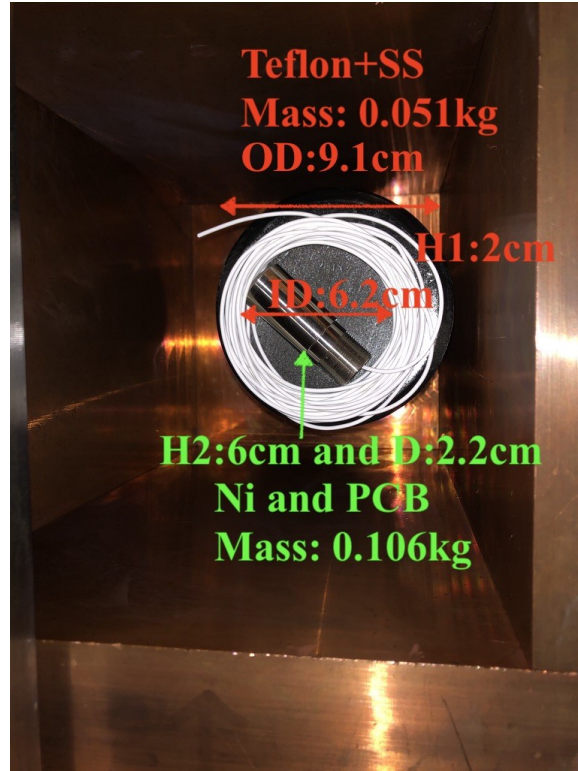


Figure 3: JUNO USS cables and receivers. They are in high pure germanium detector for radioactivity testing

6.1.2. CLS

The mechanical cable of CLS and corresponding anchor will be permanently in CD. The contribution background of CLS is shown in Table ?.

The anchor is at the boundary of CD, contact with the acrylic inner surface, so with the fiducial volume cut, most of background event will be removed resulting low rate of contribution. However, based on the CLS design, most of mechanical cable is in the fiducial volume, so even with fiducial volume cut, it is still difficult to significantly decrease the background rate.

165			
	Isotope	Rate (mHz)	Err (mHz)
	Co60	0.056	0.088
	K40	0.309	0.226
	Th232	0.520	0.214
	U238	0.419	0.143
	Total (mHz)	0.987	0.574
166			
	Isotope	Rate (mHz)	Err (mHz)
	U238	0.162	0.327
	Th232	2.470	0.573
	K40	0.712	0.424
	Total(mHz)	3.344	0.784
167	6.1.3. <i>GT</i>		
	Isotope	Rate (mHz)	Err (mHz)
	Co60	0.056	0.088
	K40	0.309	0.226
	Th232	0.520	0.214
	U238	0.419	0.143
168			
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	U238	0.162	0.327
	Th232	2.470	0.573
	K40	0.712	0.424
	Total(mHz)	3.344	0.784
170	6.1.4. <i>USS</i>		
	Isotope	Rate (mHz)	Err (mHz)
		Rate(mHz)	Err(mHz)
	Co60	0.056	0.088
	K40	0.309	0.226
	Th232	0.520	0.214
171			
	U238	0.419	0.143
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	U238	0.162	0.327
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173 *6.2. Influence to total JUNO background*

174 **7. Conclusion**

175 **8. Acknowledgement**

176 **References**