CloudTV Nano SDK (C++ Southbound API) 4.4

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Introduction



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1.1 Summary

The CloudTV™ Nano SDK can set up and control CloudTV sessions, providing the same capabilities across many different device types. The CloudTV Nano SDK supports cable set-top boxes as well as IP set-top boxes.

The CloudTV™ Nano SDK can be provided as a compiled software library, offering client APIs that a controlling Application (Guide/Middleware) can use to set up a CloudTV session. A device abstraction layer implements all device specific functionality. Porting to a specific device is done by implementing the device abstraction or Device Porting Layer for that device.

The Nano Client family of SDK's support the BCP and RFB-TV protocols. BCP is intended for cable systems with limited return paths (ALOHA). The RFB-TV protocol is intended for faster return paths. There are more features in the RFB-TV protocol, so the APIs are different between the two protocols. Therefore the APIs are split into two separate SDK versions. This SDK — the CloudTV Nano SDK — is written in C++ and only supports the RFB-TV protocol.

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2 Introduction

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Content of the package

2.1 Introduction

The CloudTV Nano SDK porting layer, so-called Southbound API, is an abstraction layer that allows Nano library to be platform independent and portable.

The code is divided in two main groups:

- OS specific code: this layer abstracts the Operating System of the platform. ActiveVideo provides with two
 reference implementations, one based in POSIX compliant Operating Systems and the other based in Windows.
 These reference implementations should help the integrator to CloudTV Nano SDK to create a new, if necessary.
- · Generic code: this layer has to be customized for each integration because it platform dependent.

2.2 Directory structure

The porting layer directory has the following structure

2.3 Where to start

If the integrator requires to create a new porting layer, he should initially look at the available source code.

If he needs to customize the generic layer to provide with a different abstraction layer to the Middleware or the platform, the starting point should be *porting_layer/src/generic* where most of the code should be reusable.

On the other hand, if need is driven by an unsupported Operating System, then a new directory should be created in <code>porting_layer/src/<new OS></code>. For example, if the OS where CloudTV Nano SDK has to execute is VxWorks, the new source code should be placed in: <code>porting_layer/src/vxworks</code>

The Makefile in *porting_layer* can be reused to build a new porting layer. The relevant variables to be modified are *SRC_DIR* and *SOURCE_FILES*.

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3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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Data Structure Index

Socket
Generic socket interface
SslSocket
SSL socket interface
TcpSocket
TCP socket interface
Thread
Generic thread interface
TimeStamp
Generic time and time stamp interface
UdpSocket
UDP socket interface
X11KeyMap
Class for the key mapping between the platform keycodes and X11 keycodes

Data Structure Documentation

5.1 Atomic < T > Struct Template Reference

Generic interface for 'atomic' variables.

Public Member Functions

Atomic (const T &value)

Construct an atomic value.

• T operator= (const T &value)

Assign new value atomically.

• operator T () const

Get the value atomically.

T operator++ ()

Increment the value atomically.

5.1.1 Detailed Description

template<typename T>struct ctvc::Atomic< T>

This template class helps in creating variables that need to be thread safe.

Note

Only operators that are actually used in the SDK are implemented.

5.2 ClientContext Class Reference

ClientContext stores all client-specific context information such as device manufacturer or device model.

Public Member Functions

void set_manufacturer (const char *manufacturer)

Set the device manufacturer, e.g. "Arris".

• const char * get_manufacturer () const

Returns the device manufacturer that was previously set.

void set_device_type (const char *devicetype)

Set the device type/model, e.g. "VIP1113".

const char * get_device_type () const

Returns the device type/model that was previously set.

void set_unique_id (const char *unique_id)

Set the unique device identifier, e.g. the MAC hardware address or serial number.

const char * get_unique_id () const

Returns the unique device identifier that was previously set.

void set_ca_path (const char *path)

Set the path to the CA certificate file, in PEM format.

const char * get_ca_path () const

Returns the path to the CA certificate file that was previously set.

void set_ca_client_path (const char *path)

Set the path to the TLS certificate file, in PEM format.

• const char * get_ca_client_path () const

Returns the path to the TLS certificate file.

void set_private_key_path (const char *path)

Set the path to the TLS private key file, in PEM format.

const char * get_private_key_path () const

Returns the path to the TLS private key file.

void register_log_output (ILogOutput &log_output)

Registers a private logging output with the porting layer.

void unregister_log_output (ILogOutput &log_output)

Unregisters a private logging output with the porting layer.

void set log format (const char *log format)

Sets the log formatting string. All successive log messages will be printed using this format.

 void log_message (LogMessageType message_type, const char *file, int line, const char *function, const char *message) const

Forwards a log message to all registered ILogOutput interfaces.

void log_message (LogMessageType message_type, const char *message) const

Forwards a log message to all registered ILogOutput interfaces.

void set base store path (const char *path)

Set base store path for get/set/delete_secure_data and cookie files.

DataStore & get_data_store ()

Get access to the DataStore object of this client.

X11KeyMap & get_keymap ()

Get key map for translating native keys to X11 key codes.

Static Public Member Functions

• static ClientContext & instance ()

Get the one-and-only instance as per the singleton pattern.

5.2.1 Detailed Description

This class follows the singleton pattern, thus it is not necessary to be explicitly passed to the Session object. However, its values shall be filled in before setting up a new session with the CloudTV platform.

5.2.2 Member Function Documentation

5.2.2.1 const char* get_ca_client_path () const

Returns

String with the path to the TLS certificate file. This is an empty string if it was not previously set.

5.2.2.2 const char* get_ca_path () const

Returns

String indicating the path to the CA certificate file. This is an emtpy string if it was not previously set.

5.2.2.3 DataStore& get_data_store() [inline]

Returns

Reference to the DataStore object that ClientContext holds.

5.2.2.4 const char* get_device_type () const

Returns

String with device type/model. This is an empty string if it was not previously set.

5.2.2.5 X11KeyMap& get_keymap()

Returns

The key translation map.

5.2.2.6 const char* get_manufacturer () const

Returns

String with the device manufacturer. This is an empty string if it was not previously set.

5.2.2.7 const char* get_private_key_path () const

Returns

String with the path to the TLS private key file. This is an empty string if it was not previously set.

5.2.2.8 const char* get_unique_id () const

Returns

String with the unique device identifier. This is an empty string if it was not previously set.

5.2.2.9 static ClientContext& instance() [static]

Returns

Reference to the ClientContext singleton.

5.2.2.10 void log_message (LogMessageType message_type, const char * file, int line, const char * function, const char * message) const

Parameters

_			
	in	message_type	Log level

See Also

Log.h

Parameters

in	file	Name of the source file issuing the log.
in	line	Line number of the source code issuing the log.
in	function	Function that issues the log.
in	message	String containing the log message If no logging output is set, the porting layer will
		output all logging to stderr.

5.2.2.11 void log_message (LogMessageType message_type, const char * message) const [inline]

Parameters

in	message_type	Log level

See Also

Log.h

Parameters

in	message	String containing the log message If no logging output is set, the porting layer will
		output all logging to stderr.

5.2.2.12 void register_log_output (ILogOutput & log_output)

Parameters

in	log_output	Reference to an ILogOutput interface Re-registering an object that was already
		registered has no effect.

5.2.2.13 void set_base_store_path (const char * path) [inline]

Parameters

_			
	in	path	The path

5.2.2.14 void set_ca_client_path (const char * path)

Parameters

in	path	Name of the file containing the certificate
----	------	---

5.2.2.15 void set_ca_path (const char * path)

Parameters

in	path	Name of the file containing the certificate
----	------	---

5.2.2.16 void set_device_type (const char * devicetype)

Note

This is a mandatory parameter that must be set by the client.

Parameters

in	devicetype	String indicating the device type/model.

5.2.2.17 void set_log_format (const char * log_format)

Parameters

in	log_format	The format string to specify. If 0, the default format is selected. The format string uses a simplified printf-style format: All characters will be copied as-is, except when prepended with a "character or when explicitly excluded The "character escape sequences are the following: "%%": Print a single "character. "%T": Print the time of the log message (in hh:mm:ss.ms format). "%t": Print the type (debug, info, warning, error) of the log message. "%F": Print the function name from which the log was called. "%f": Print the file name from which the log was called. "%f": Print the log was called. "%n": Print the name of the thread from which the log was called. "%m": Print the log message contents. "%[": Text to include if a log message is output (and excluded if an empty log message is output). "%]": End of text section to include if a log
		message is output.

Note

The default log format is "<%T> Type:<%t> at %f:%l, %F%[, Message:<%m>%]\r\n"

5.2.2.18 void set_manufacturer (const char * manufacturer)

Note

This is a mandatory parameter that must be set by the client.

Parameters

in	manufacturer	String indicating the device manufacturer.
----	--------------	--

5.2.2.19 void set_private_key_path (const char * path)

Parameters

in	path	Name of the file containing the key
----	------	-------------------------------------

5.2.2.20 void set_unique_id (const char * unique_id)

Note

This is a mandatory parameter that must be set by the client.

Parameters

in	unique_id	String indicating the unique device identifier.
----	-----------	---

5.2.2.21 void unregister_log_output (ILogOutput & log_output)

Parameters

in	log_output	Reference to an ILogOutput interface Re-unregistering an object that was already
		unregistered has no effect.

5.3 Condition Class Reference

Generic condition variable interface.

Data Structures

struct ICondition

Interface for the implementation of Condition.

Public Member Functions

• void lock ()

Lock operation to protect a critical region.

• void unlock ()

Unlock operation to indicate the end of a critical region.

• bool trylock ()

Try to lock the mutex.

• void notify ()

Notify a thread that is waiting (to be notified).

void wait_without_lock ()

Wait until notified.

bool wait_without_lock (uint32_t timeout_in_ms)

Wait until notified while using a timeout.

5.3.1 Member Function Documentation

```
5.3.1.1 void lock() [inline], [virtual]
```

This method will wait until the mutex can be acquired. The mutex is recursive, thus if the same thread locks twice the same mutex, it won't block the execution.

Implements IMutex.

```
5.3.1.2 void notify( ) [inline]
See Also
     wait()

5.3.1.3 bool trylock( ) [inline], [virtual]
```

This method never blocks. If the mutex cannot be acquired, it will return false.

Return values

true	If the mutex has been acquired.
false	If the mutex could not be acquired.

Implements IMutex.

```
5.3.1.4 void wait_without_lock( ) [inline]
```

The corresponding mutex will be atomically released when the wait starts. As soon as the calling thread gets notified, the mutex ownership will be gained (again atomically).

See Also

notify()

5.3.1.5 bool wait_without_lock (uint32_t timeout_in_ms) [inline]

If locked, the corresponding mutex will be atomically released when the wait starts. As soon as the calling thread gets notified, the mutex ownership will be gained (again atomically). If not notified, the method will wait for at most timeout_in_ms milliseconds for notify() to be called by another thread. If notify() is called before the timeout expires, wait_without_lock() returns true. If notify() was not called within timeout_in_ms milliseconds, wait_without_lock() returns false. In both cases the Mutex will be locked again, before returning from this call unless it was not locked upon enty.

Parameters

in	timeout_in_ms	The maximum time to wait for another thread to call <i>notify()</i> before returning false.
----	---------------	---

Return values

true	if successful.
false	if a timeout occurred.

See Also

notify()

5.4 DataStore Class Reference

Class for (secure) storage of the data.

Public Member Functions

void set_base_store_path (const char *path)

Set base store path for get/set/delete_data.

• ResultCode set data (const char *id, const uint8 t *data, uint32 t length)

This is called to save persistent data.

ResultCode set_data (const char *id, const std::vector< uint8_t > &data)

This is called to save persistent data from an std::vector.

ResultCode set_data (const char *id, const std::string &data)

This is called to save persistent data from an std::string.

ResultCode get_data (const char *id, uint8_t *data, uint32_t size, uint32_t *length)

This is called to get stored persistent data.

ResultCode get data (const char *id, std::vector< uint8 t > &data)

This is called to get stored persistent data into an std::vector.

ResultCode get_data (const char *id, std::string &data)

This is called to get stored persistent data into an std::string.

ResultCode delete_data (const char *id)

This is called to delete persistent data.

Static Public Attributes

static const ResultCode INVALID PARAMETER

The parameter is not valid.

static const ResultCode COULD NOT OPEN ITEM

The requested item cannot be opened.

static const ResultCode READ_ERROR

Error during reading of the item.

• static const ResultCode WRITE ERROR

Error during writing of the item.

• static const ResultCode COULD_NOT_REMOVE_ITEM

The item could not be deleted.

5.4.1 Detailed Description

Nano SDK uses this class to store data in the platform.

5.4.2 Member Function Documentation

5.4.2.1 ResultCode delete_data (const char * id)

Parameters

Returns

ResultCode

5.4.2.2 ResultCode get_data (const char * id, uint8_t * data, uint32_t size, uint32_t * length)

Parameters

in	id	The id of the data.
out	data	Buffer for the data to be retrieved; if null, only the length will be returned.
in	size	The size of data buffer (if data != null).
out	length	The length of data that is or will be retrieved, may return 0 if the data is empty.

Returns

ResultCode

5.4.2.3 ResultCode get_data (const char * id, std::vector< uint8_t > & data)

Parameters

in	id	The id of the data.
out	data	The data that is retrieved, may be empty.

Returns

ResultCode

5.4.2.4 ResultCode get_data (const char * id, std::string & data)

Parameters

in	id	The id of the data.
out	data	The data that is retrieved, may be empty.

Returns

ResultCode

5.4.2.5 void set_base_store_path (const char * path)

Parameters

ĺ	in	path	The path.

5.4.2.6 ResultCode set_data (const char * id, const uint8_t * data, uint32_t length)

Parameters

in	id	The id of the data.
in	data	The data to be saved.
in	length	The length of the data, may be 0.

Returns

ResultCode

Note

The DataStore may implement mechanisms to prevent writing the same data multiple times.

5.4.2.7 ResultCode set_data (const char * id, const std::vector < uint8_t > & data) [inline]

Parameters

in	id	The id of the data.
in	data	The data to be saved, may be empty.

Returns

ResultCode

Note

The DataStore may implement mechanisms to prevent writing the same data multiple times.

5.4.2.8 ResultCode set_data (const char * id, const std::string & data) [inline]

Parameters

in	id	The id of the data.
in	data	The data to be saved, may be an empty string.

Returns

ResultCode

Note

The DataStore may implement mechanisms to prevent writing the same data multiple times.

5.4.3 Field Documentation

5.4.3.1 const ResultCode COULD_NOT_OPEN_ITEM [static]

See Also

ResultCode

5.4.3.2 const ResultCode COULD_NOT_REMOVE_ITEM [static]

See Also

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5.4.3.3 const ResultCode INVALID_PARAMETER [static]

See Also

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5.4.3.4 const ResultCode READ_ERROR [static]

See Also

ResultCode

5.4.3.5 const ResultCode WRITE_ERROR [static]

See Also

ResultCode

5.5 Condition::ICondition Struct Reference

Interface for the implementation of Condition.

Public Member Functions

- virtual void **notify** ()=0
- virtual void wait_without_lock ()=0
- virtual bool wait_without_lock (uint32_t)=0

5.5.1 Detailed Description

Condition uses an object that implements this interface to expose its functionality. There is a one-to-one mapping between ICondition methods and Condition's, i.e. they have the same syntax and semantics

See Also

Condition

5.6 ILogOutput Struct Reference

Log output forwarding interface.

Public Member Functions

• virtual void log_message (LogMessageType message_type, const char *message)=0

Receives a formatted log message string with a severance as indicated by message_type.

5.6.1 Member Function Documentation

5.6.1.1 virtual void log_message (LogMessageType message_type, const char * message) [pure virtual]

Parameters

in	message type	Log level
111	moodage_type	209 10401

See Also

Log.h

Parameters

in	message	String containing the log message

5.7 IMutex Struct Reference

Abstract interface for the implementation of Mutex.

Public Member Functions

- virtual void lock ()=0
- virtual void unlock ()=0
- virtual bool trylock ()=0

5.7.1 Detailed Description

See Also

Mutex and Condition

5.8 Thread::IRunnable Struct Reference

Interface of the object that Thread will execute in parallel.

Public Member Functions

• virtual bool run ()=0

This function will run in its own thread.

5.8.1 Member Function Documentation

```
5.8.1.1 virtual bool run ( ) [pure virtual]
```

Return values

false	It will be run again (looped)
true	It will stop and the thread will exit

5.9 Semaphore:: ISemaphore Struct Reference

Interface for the implementation of Semaphore.

Public Member Functions

- virtual void post ()=0
- virtual void wait ()=0
- virtual bool wait (uint32_t timeout_in_ms)=0
- virtual bool **trywait** ()=0

5.9.1 Detailed Description

Semaphore uses an object that implements this interface to expose its functionality. There is a one-to-one mapping between ISemaphore methods and Semaphore's, i.e. they have the same syntax and semantics

See Also

Semaphore

5.10 Socket::ISocket Struct Reference

Interface for the implementation of socket functionality.

Public Member Functions

- virtual void open ()=0
- virtual void close ()=0
- virtual ResultCode connect (const char *host, int port)=0
- virtual ResultCode bind (const char *host, int port)=0
- virtual ResultCode send (const uint8 t *data, uint32 t length)=0
- virtual ResultCode receive (uint8 t *data, uint32 t size, uint32 t &length)=0
- virtual ResultCode set receive buffer size (uint32 t size)=0
- virtual ResultCode set reuse address (bool on)=0
- virtual ResultCode set non blocking (bool on)=0

5.10.1 Detailed Description

Socket uses an object that implements this interface to expose socket functionality. There is a one-to-one mapping between ISocket methods and Socket's, i.e. they have the same syntax and semantics

See Also

Socket

5.11 Thread::IThread Struct Reference

Interface for the implementation of Thread.

Public Member Functions

- virtual ResultCode start (IRunnable &runnable, Priority priority)=0
- virtual void **stop** ()=0
- virtual ResultCode wait_until_stopped ()=0
- virtual bool is_running ()=0
- virtual bool must_stop ()=0
- virtual ResultCode stop and wait until stopped ()=0
- virtual const std::string & get_name () const =0

5.11.1 Detailed Description

Thread uses an object that implements this interface to expose the threading functions. There is a one-to-one mapping between IThread methods and Thread's, i.e. they have the same syntax and semantics

See Also

Thread N.B. the only exception is the static method Tread::self() because by definition static methods cannot be part of an interface. Furthermore, the implementation is hidden by default.

5.12 Keyboard Class Reference

Generic platform-independent keyboard interface Mainly meant for use with example applications, not intended for use with real clients.

Static Public Member Functions

static int get key ()

Get a key from the console keyboard.

Static Public Attributes

• static const int TIMEOUT_IN_MS = 10

Time to block when no key is pressed.

static const int ESC_SEQ = 0x1000

Special key codes Common ASCII key codes like 'A' are not defined here.

static const int BACKSPACE KEY = '\b'

Backspace key, same as '\b'.

• static const int ENTER KEY = '\r'

Enter key, same as '\r'.

• static const int ESC KEY = 0x1B

ESC-key (if not followed by a '[' character).

static const int DEL KEY = 0x7F

DEL key.

static const int UP_KEY = 0x100

Cursor up key.

static const int DOWN KEY = 0x101

Cursor down key.

static const int LEFT_KEY = 0x102

Cursor left key.

static const int RIGHT_KEY = 0x103

Cursor right key.

5.12.1 Member Function Documentation

```
5.12.1.1 static int get_key( ) [static]
```

Returns

Key value (typically ASCII), EOF if end-of-file is reached or 0 if no key was pressed.

Note

get_key() typically blocks for at most *TIMEOUT_IN_MS* milliseconds waiting for a key to be pressed. Escape sequences are returned as specific values. An ESC-'['-<key> sequence is returned as value ESC_SEQ + x, where x is the ASCII key value after the escape sequence. For example, the 'UP' arrow key typically encodes as ESC-'['-'A', which will then be returned as the value ESC_SEQ + 'A'. Other escape sequences are not translated and typically ignore the first ESC key. And ESC-ESC sequence returns as a single ESC_KEY character, 0x1B.

5.12.2 Field Documentation

```
5.12.2.1 const int ESC_SEQ = 0x1000 [static]
```

ESC-key followed by a '[' character. The key value returned will be this value plus an escape-specific key value. For instance, the escape sequence ESC-'['-'E' will return the key value 0x1045, which equals ESC_SEQ + 'E'. (This holds for unrecognized escape sequences; Recognized sequences like ESC-'['-'A' will be returned as UP KEY, for instance.)

5.13 X11KeyMap::KeyMap Struct Reference

A single key map entry for use in add mapping()

Data Fields

· int from key

Platform key code to be mapped from.

X11KeyCode to_key

X11 key code to be generated.

5.14 Mutex Class Reference

Generic mutex interface.

Public Member Functions

• void lock ()

Lock operation to protect a critical region.

• void unlock ()

Unlock operation to indicate the end of a critical region.

• bool trylock ()

Try to lock the mutex.

5.14.1 Detailed Description

Mutex uses an object that implements this interface to expose its functionality. There is a one-to-one mapping between IMutex methods and Mutex's, i.e. they have the same syntax and semantics

See Also

Mutex

5.14.2 Member Function Documentation

```
5.14.2.1 void lock() [inline], [virtual]
```

This method will wait until the mutex can be acquired. The mutex is recursive, thus if the same thread locks twice the same mutex, it won't block the execution.

Implements IMutex.

```
5.14.2.2 booltrylock( ) [inline], [virtual]
```

This method never blocks. If the mutex cannot be acquired, it will return false.

Return values

true	If the mutex has been acquired.
false	If the mutex could not be acquired.

Implements IMutex.

5.15 ResultCode Class Reference

Generic class to return the result of the methods.

Public Member Functions

· ResultCode ()

Default constructor for non-initialized code.

• int get_code () const

Return the unique code number of the result.

• const char * get_description () const

Return a textual description of the result.

• bool operator== (const ResultCode &rhs) const

Comparison operator.

bool operator!= (const ResultCode &rhs) const

Comparison operator.

ResultCode & operator= (const ResultCode &rhs)

Assignment operator.

• bool is_ok () const

Return true if the object is ResultCode::SUCCESS.

• bool is_error () const

Return true if the object is not ResultCode::SUCCESS.

ResultCode & operator = (const ResultCode &rhs)

Combine this result code with the right hand side code. If this code is_ok(), the right hand side is taken. If this code is_error(), the code is not changed.

Static Public Attributes

• static const ResultCode SUCCESS

Operation succeeded.

5.15.1 Detailed Description

The design of this class has the following features:

- Minimum overhead when the objects are copied (e.g. when returning an object)
- · The object can be compared
- · Type check during compiling time
- · Access to a textual description of the result (

```
See Also
```

```
get_description())
```

• Each defined ResultCode has an unique code number (

See Also

```
get_code())
```

5.15.2 Member Function Documentation

```
5.15.2.1 int get_code ( ) const [inline]
```

Returns

Unique code number of the result

5.15.2.2 const char* get_description () const

Returns

Pointer to the array that contains the textual description of the result

```
5.15.2.3 boolis_error() const [inline]
```

Returns

True is the object is not ResultCode::SUCCESS. False otherwise.

```
5.15.2.4 boolis_ok( )const [inline]
```

Returns

True is the object is ResultCode::SUCCESS. False otherwise.

5.15.2.5 bool operator!= (const ResultCode & rhs) const [inline]

Parameters

in	rhs	Operand on the right hand side of "!=" sign
----	-----	---

Returns

True, if both ResultCode objects are different. False otherwise.

5.15.2.6 ResultCode& operator=(const ResultCode & rhs) [inline]

Parameters

in	rhs	Operand on the right hand side of "=" sign
----	-----	--

Returns

Reference to this

5.15.2.7 bool operator== (const ResultCode & rhs) const [inline]

Parameters

in	rhs	Operand on the right hand side of "==" sign
----	-----	---

Returns

True, if both ResultCode objects are the same. False otherwise.

5.15.2.8 ResultCode& operator = (const ResultCode & rhs) [inline]

Parameters

in	rhs	Operand on the right hand side of " =" sign
----	-----	---

Returns

Reference to this

5.16 Semaphore Class Reference

Generic platform-independent semaphore interface.

Data Structures

• struct ISemaphore

Interface for the implementation of Semaphore.

Public Member Functions

• Semaphore ()

Semaphores are counting semaphore objects used for synchronization between threads. They are constructed with a count of 0.

• void post ()

Post to the semaphore; the semaphore's count is incremented by 1. If any thread is blocked on wait(), one of them is released now.

· void wait ()

Wait for the semaphore to have a count greater than 0. If so, the semaphore's count is decremented and the call returns. If not, the method will wait indefinitely until some other thread calls post().

bool wait (uint32_t timeout_in_ms)

Wait for the semaphore to have a count greater than 0 using a timeout. If the count is greater than 0 when the call is made, the semaphore's count is decremented and the call returns immediately with the return value true. If not, the method will wait for at most timeout_in_ms milliseconds for post() to be called by another thread. If post() is called before the timeout expires, wait() returns true. If post() was not called within timeout_in_ms milliseconds, wait() returns false.

· bool trywait ()

Check whether the semaphore has a count greater than 0. If so, the semaphore's count is decremented and the call returns immediately with the return value true. If not, the method returns immediately with the return value false.

5.16.1 Member Function Documentation

5.16.1.1 booltrywait() [inline]

Return values

true	if successful; the semaphore count will be decremented by one.
false	if unsuccessful; the semaphore count will not have changed and still be 0.

5.16.1.2 bool wait (uint32_t timeout_in_ms) [inline]

Parameters

in	timeout_in_ms	The maximum time to wait for another thread to call <i>post()</i> before returning false.
----	---------------	---

Return values

true	if successful; the semaphore count will be decremented by one.
false	if a timeout occurred; the semaphore count will not have changed and still be 0.

5.17 Socket Class Reference

Generic socket interface.

Data Structures

struct ISocket

Interface for the implementation of socket functionality.

Public Member Functions

Socket (ISocket &impl)

Constructor of Socket.

• void open ()

Open the socket.

• void close ()

Close the socket.

ResultCode connect (const char *host, int port)

Establish a connection with a host in the specified port.

ResultCode bind (const char *host, int port)

Bind a port to a local address and in a specific port.

ResultCode send (const uint8_t *data, uint32_t length)

Send data to the host.

ResultCode receive (uint8_t *data, uint32_t size, uint32_t &length)

Receive data from the socket.

• ResultCode set_receive_buffer_size (uint32_t size)

Set the size of the socket buffer of the platform.

· ResultCode set reuse address (bool on)

The local address can be re-used for binding operations.

ISocket & get_impl ()

Static Public Member Functions

static ResultCode get local address (std::string &local address)

Get the address that is bound to the network adapter (usually DHCP assigned).

Static Public Attributes

static const ResultCode SOCKET NOT OPEN

The socket is not open.

static const ResultCode READ_ERROR

Error reading from the socket.

• static const ResultCode WRITE ERROR

Error writing to the socket.

• static const ResultCode BIND_ERROR

Error when binding the socket to a port.

static const ResultCode HOST NOT FOUND

Host not found error.

static const ResultCode CONNECTION REFUSED

The connection could not be established because it was refused by the server.

static const ResultCode CONNECT_FAILED

The connection could not be established.

static const ResultCode CONNECT_TIMEOUT

Timeout while trying to establish a connection.

static const ResultCode LISTEN_FAILED

The port could not be listened.

static const ResultCode SOCKET OPTION ACCESS FAILED

Error in the given options.

static const ResultCode THREAD_SHUTDOWN

A blocking call was interrupted because the calling thread is shut down.

Protected Attributes

ISocket & m_impl

5.17.1 Detailed Description

The implementation is done as part of the porting layer. All implementation is forwarded to the private Impl class. Coding this inline should speed-up code and reduce code size.

This class should not be used directly, but one of the derived classes instead

See Also

UdpSocket, TcpSocket, SslSocket

5.17.2 Constructor & Destructor Documentation

5.17.2.1 Socket (ISocket & impl) [inline]

Parameters

in	impl	Object that implements ISocket interface to implement the required functionality
----	------	--

5.17.3 Member Function Documentation

5.17.3.1 ResultCode bind (const char * host, int port) [inline]

After successfully binding the port, data can be received using the method receive()

Parameters

in	host	Local address in either dotted notation or FQDN
in	port	Local port

Return values

ResultCode::SUCCESS	If socket has been successfully bound.
SOCKET_NOT_OPEN	When the socket has not been previously opened
HOST_NOT_FOUND	When the hostname cannot be resolved or be reached
BIND_ERROR	When the given host/port could not be bound

5.17.3.2 ResultCode connect (const char * host, int port) [inline]

Parameters

in	host	Destination address in either dotted notation or FQDN
in	port	Destination port

ResultCode::SUCCESS	When the connection has been established
SOCKET_NOT_OPEN	When the socket has not been previously opened
HOST_NOT_FOUND	When the hostname cannot be resolved or be reached

CONNECTION REFUSED	When the server has refused the connection request

5.17.3.3 static ResultCode get_local_address (std::string & local_address) [static]

Parameters

out	local_address	The local address in dotted IP notatation (e.g. 172.178.16.128).

Return values

ResultCode::SUCCESS	If the operation succeeded.
SOCKET_NOT_OPEN	When the temporary socket failed to open.
SOCKET_OPTION_ACCES-	If the operation failed.
S_FAILED	

5.17.3.4 ResultCode receive (uint8_t * data, uint32_t size, uint32_t & length) [inline]

This method only can be used after a successful binding.

Parameters

in	data	Buffer where the received data will be stored
in	size	Size of the buffer "data"
out	length	Number of bytes received

Return values

ResultCode::SUCCESS	If the operation succeeded. This does not imply that actual data was received. If
	length == 0, this indicates that the connection was closed by the peer.
SOCKET_NOT_OPEN	When the socket has not been previously opened.
READ_ERROR	When there was an error with the reading, e.g. the socket was not opened.
THREAD_SHUTDOWN	When the call was interrupted because the calling thread is shut down.

5.17.3.5 ResultCode send (const uint8_t * data, uint32_t length) [inline]

This method only can be used after a successful connection has been established

See Also

connect().

Parameters

in	data	Array of bytes to be sent
in	length	Number of bytes to be sent

ResultCode::SUCCESS	If the entire buffer has been successfully sent
SOCKET_NOT_OPEN	When the socket has not been previously opened
WRITE_ERROR	When there was an error with the writing, e.g. the socket was not opened or the
	connection is closed.

5.17.3.6 ResultCode set_receive_buffer_size (uint32_t size) [inline]

Parameters

in	size	Size of the socket buffer

Returns

ResultCode::SUCCESS If the new size has been successfully set.

Return values

SOCKET_NOT_OPEN	When the socket has not been previously opened.
SOCKET_OPTION_ACCES-	If the operation failed.
S_FAILED	

5.17.3.7 ResultCode set_reuse_address (bool on) [inline]

Parameters

in	on	Whether the local address can be reused.
----	----	--

Return values

ResultCode::SUCCESS	If the operation succeeded.
SOCKET_NOT_OPEN	When the socket has not been previously opened.
SOCKET_OPTION_ACCES-	If the operation failed.
S_FAILED	

5.18 SslSocket Class Reference

SSL socket interface.

Additional Inherited Members

5.19 TcpSocket Class Reference

TCP socket interface.

Public Member Functions

• virtual ResultCode listen (uint32_t backlog)

Listen into an specific port for incoming connection request.

virtual TcpSocket * accept ()

Accept a new connection.

virtual ResultCode set_no_delay (bool on)

If set, the data will be sent as soon as possible.

Protected Member Functions

• TcpSocket (ISocket &)

Additional Inherited Members

5.19.1 Member Function Documentation

```
5.19.1.1 virtual TcpSocket* accept() [virtual]
```

This method can only be used after listen() succeeded.

Returns

A pointer to an TcpSocket object to send or receive data or 0 if accept() failed or was interrupted because the calling thread is shut down.

5.19.1.2 virtual ResultCode listen (uint32_t backlog) [virtual]

Parameters

in	backlog	Maximum queue length. When the backlog is exhausted, new connection will be
		rejected.

Return values

ResultCode::SUCCESS	If the operation succeeded.
SOCKET_NOT_OPEN	When the socket has not been previously opened.
LISTEN_FAILED	If the operation failed.

5.19.1.3 virtual ResultCode set_no_delay(bool on) [virtual]

When the amount of data is small, the platform will try to wait for more data before sending it. If this flag is set, the data is sent as soon as possible.

Parameters

in	on	True to send the data as soon as possible.

ResultCode::SUCCESS	If the operation succeeded.
SOCKET_NOT_OPEN	When the socket has not been previously opened.
SOCKET_OPTION_ACCES-	If the operation failed.
S_FAILED	

5.20 Thread Class Reference

Generic thread interface.

Data Structures

• struct IRunnable

Interface of the object that Thread will execute in parallel.

struct IThread

Interface for the implementation of Thread.

Public Types

enum Priority {
 PRIO_LOW, PRIO_NORMAL,
 PRIO_HIGH, PRIO_HIGHEST }

Priority levels at which a thread can run.

Public Member Functions

• Thread (const std::string &thread_name)

Constructor.

ResultCode start (IRunnable &runnable, Priority priority)

Execute the function in a separate thread.

• void stop ()

Stop the current running thread (if any)

ResultCode wait_until_stopped ()

Wait for the thread until it stops.

• bool is_running ()

Check if Thread is currently executing an IRunnable object.

• bool must_stop ()

Check if Thread must stop.

ResultCode stop_and_wait_until_stopped ()

Stop the thread and wait until it finishes.

• const std::string & get_name () const

Get a reference to the thread name.

5.20 Thread Class Reference 35

Static Public Member Functions

• static void sleep (uint32_t time_in_milliseconds)

Sleep for the given number of milliseconds.

static Thread * self ()

Get a pointer to the current thread.

Static Public Attributes

static const ResultCode THREAD_ALREADY_STARTED

The thread was already started.

static const ResultCode CANNOT CREATE THREAD

The thread could not be created.

• static const ResultCode CANNOT_SET_THREAD_PRIORITY

The thread priority could not be set.

• static const ResultCode FAILED_WAITING_FOR_THREAD_TO_FINISH

The thread could not be joined.

5.20.1 Detailed Description

The implementation is done as part of the porting layer. All implementation is forwarded to the private Impl class. Coding this inline should speed-up code and reduce code size.

5.20.2 Member Enumeration Documentation

5.20.2.1 enum Priority

Enumerator

PRIO_LOW Priority below normal. Such a thread should only run if no other threads can run at that moment.

PRIO_NORMAL Normal priority, at which threads run that would otherwise not have their priority set. Typically the same prority as that of the main() thread.

PRIO_HIGH Priority above normal. Such a thread should run if possible (i.e. if not blocked), unless a higher priority thread can run.

PRIO_HIGHEST Highest priority. Such a thread should run at all times if it can (i.e. if not blocked).

5.20.3 Constructor & Destructor Documentation

5.20.3.1 Thread (const std::string & thread_name)

Parameters

in	thread_name	Name of the current thread.
----	-------------	-----------------------------

5.20.4 Member Function Documentation

5.20.4.1 const std::string& get_name() const [inline]

Returns

Reference to the thread name.

5.20.4.2 boolis_running() [inline]

Return values

True	if the thread is running.
False	if the thread is not running.

5.20.4.3 bool must_stop() [inline]

Return values

True	if the thread is running and has been signaled to stop.
False	if the thread is not running or not signaled to stop.

5.20.4.4 static Thread* **self()** [static]

Returns

Pointer to current thread or NULL if if not on an explicit thread, e.g. the main thread.

5.20.4.5 static void sleep (uint32_t time_in_milliseconds) [static]

Parameters

in	time_in	Number of milliseconds to sleep.
	milliseconds	

5.20.4.6 ResultCode start (IRunnable & runnable, Priority priority) [inline]

Parameters

in	runnable	Object with run() function to be executed in a separated thread.
in	priority	Priority at which the thread is expected to run.

ResultCode::SUCCESS	When the thread has started successfully.

CANNOT_CREATE_THREA-	If the thread couldn't be started, e.g. lack of resources.
D	
THREAD_ALREADY_STAR-	If there is already an IRunnable being executed.
TED	
CANNOT_SET_THREAD_P-	If the requested thread priority cannot be set.
RIORITY	

```
5.20.4.7 ResultCode stop_and_wait_until_stopped( ) [inline]
See Also
     stop() and wait_until_stopped()

Returns

See Also
     wait_until_stopped()
```

5.20.4.8 ResultCode wait_until_stopped() [inline]

stop() shall be called previously

Return values

ĺ	ResultCode::SUCCESS	If the thread has successfully finished
Ì	FAILED_WAITING_FOR_T-	When an error condition ocurred, e.g. no thread was started.
	HREAD_TO_FINISH	

5.21 TimeStamp Class Reference

Generic time and time stamp interface.

Public Member Functions

• TimeStamp ()

Construct a new TimeStamp object.

TimeStamp (const TimeStamp &rhs)

Construct a new TimeStamp object with initial value.

TimeStamp & operator= (const TimeStamp &rhs)

Assigns a new value to the TimeStamp, replacing its current contents.

• bool is_valid () const

Check if the stored time value is valid.

• bool is_absolute () const

Check if the stored time value is absolute.

· bool is_relative () const

Check if the stored time value is relative.

bool is_comparable (const TimeStamp &rhs) const

Check if the stored time value can be compared to the other.

· void invalidate ()

Make the time stamp invalid.

· int64 t get as microseconds () const

Get the time value in microseconds.

int64 t get as milliseconds () const

Get the time value in milliseconds.

• int64 t get as seconds () const

Get the time value in seconds.

• TimeStamp & add microseconds (int64 t delta in us)

Add microseconds to a TimeStamp.

• TimeStamp & add_milliseconds (int64_t delta_in_ms)

Add milliseconds to a TimeStamp.

TimeStamp & add_seconds (int32_t delta_in_s)

Add seconds to a TimeStamp.

bool operator== (const TimeStamp &rhs) const

Comparison operators. Assumes is_comparable() to be true.

- bool operator>= (const TimeStamp &rhs) const
- bool **operator**<= (const TimeStamp &rhs) const
- bool operator!= (const TimeStamp &rhs) const
- bool operator< (const TimeStamp &rhs) const
- bool operator> (const TimeStamp &rhs) const
- TimeStamp & operator+= (const TimeStamp &rhs)

Arithmetic operators.

- TimeStamp & operator-= (const TimeStamp &rhs)
- TimeStamp operator+ (const TimeStamp &rhs) const
- TimeStamp operator- (const TimeStamp &rhs) const

Static Public Member Functions

static TimeStamp now ()

Sample the current time.

static TimeStamp zero ()

Return a relative time of 0.

5.21.1 Detailed Description

The implementation is done as part of the porting layer. The inline coding is done to reduce code size, increase speed and reduce memory usage.

5.21.2 Constructor & Destructor Documentation

5.21.2.1 TimeStamp (const TimeStamp & rhs) [inline]

Parameters

in	rhs	Initial value.
----	-----	----------------

5.21.3 Member Function Documentation

5.21.3.1 TimeStamp& add_microseconds (int64_t delta_in_us) [inline]

Note

Assumes the time stamp is valid

Parameters

in	delta in us	Time in microseconds.

Returns

TimeStamp reference to this.

Note

This alters the current object value.

5.21.3.2 TimeStamp& add_milliseconds (int64_t delta_in_ms) [inline]

Note

Assumes the time stamp is valid

Parameters

in	delta_in_ms	Time in milliseconds.
----	-------------	-----------------------

Returns

TimeStamp reference to this.

Note

This alters the current object value.

5.21.3.3 TimeStamp& add_seconds (int32_t delta_in_s) [inline]

Note

Assumes the time stamp is valid.

Parameters

in	delta_in_s	Time in seconds.	
----	------------	------------------	--

Returns

TimeStamp reference to this.

Note

This alters the current object value.

```
5.21.3.4 int64_t get_as_microseconds() const [inline]
```

Returns

Time stamp value in microseconds. May return absolute or relative time, depending on is_absolute()

Note

Assumes the time stamp is valid

```
5.21.3.5 int64_t get_as_milliseconds() const [inline]
```

Returns

Time stamp value in milliseconds. May return absolute or relative time, depending on is_absolute()

Note

Assumes the time stamp is valid

```
5.21.3.6 int64_t get_as_seconds() const [inline]
```

Returns

Time stamp value in seconds. May return absolute or relative time, depending on is_absolute()

Note

Assumes the time stamp is valid

```
5.21.3.7 boolis_absolute( ) const [inline]
```

Return values

true	if absolute, false otherwise.

5.21.3.8 bool is_comparable (const TimeStamp & rhs) const [inline]

Parameters

in	rhs	Reference to object being compared.
		, reserve to eleject de migranien

Return values

true	if so, false otherwise. If true, both time stamps are valid and of the same type.

5.21.3.9 boolis_relative() const [inline]

Return values

true	if relative, false otherwise.
------	-------------------------------

5.21.3.10 boolis_valid() const [inline]

Return values

true	if valid, false otherwise.

5.21.3.11 TimeStamp& operator=(const TimeStamp & rhs) [inline]

Parameters

in	rhs	New value.

Returns

Reference to this object.

5.22 UdpSocket Class Reference

UDP socket interface.

Additional Inherited Members

5.23 X11KeyMap Class Reference

Class for the key mapping between the platform keycodes and X11 keycodes.

Data Structures

struct KeyMap

A single key map entry for use in add_mapping()

Public Member Functions

void add mapping (int from key, X11KeyCode to key)

Add a new mapping of a native key code to an X11 key code.

void add_mapping (const KeyMap map[], unsigned int n_entries)

Add a new set of translations from native key code to X11 key code.

• X11KeyCode translate (int native_key) const

Translate a native key code to an X11 key code.

5.23.1 Member Function Documentation

5.23.1.1 void add_mapping (int from_key, X11KeyCode to_key)

Parameters

in	from_key	The native (remote control) key code.
in	to_key	The X11KeyCode it maps to.

5.23.1.2 void add_mapping (const KeyMap map[], unsigned int n_entries)

Parameters

in	тар	The map structure array pointer.
in	n_entries	The number of entries in the array.

5.23.1.3 X11KeyCode translate (int native_key) const

Parameters

in	native_key	The native (remote control) key code.

Returns

X11 translated code for *native_key* or the native key if no mapping exists at all, or X11_INVALID if a keymap was set, but no mapping exists for *native_key*.

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