

# PRML学习笔记——第四章

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## Linear Models for Classification

Datasets如果能被linear decision surface确切separate,就被称为*linear separable*.

### 4.1. Discriminant Functions

#### 4.1.1 Two classes

最简单的linear discriminator function可以是:

$$y(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0$$

原点到decision surface的距离为:

$$\frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\|} = -\frac{w_0}{\|\mathbf{w}\|}$$

空间中任一点到surface的距离为:

$$\frac{y(\mathbf{x})}{\|\mathbf{w}\|}$$

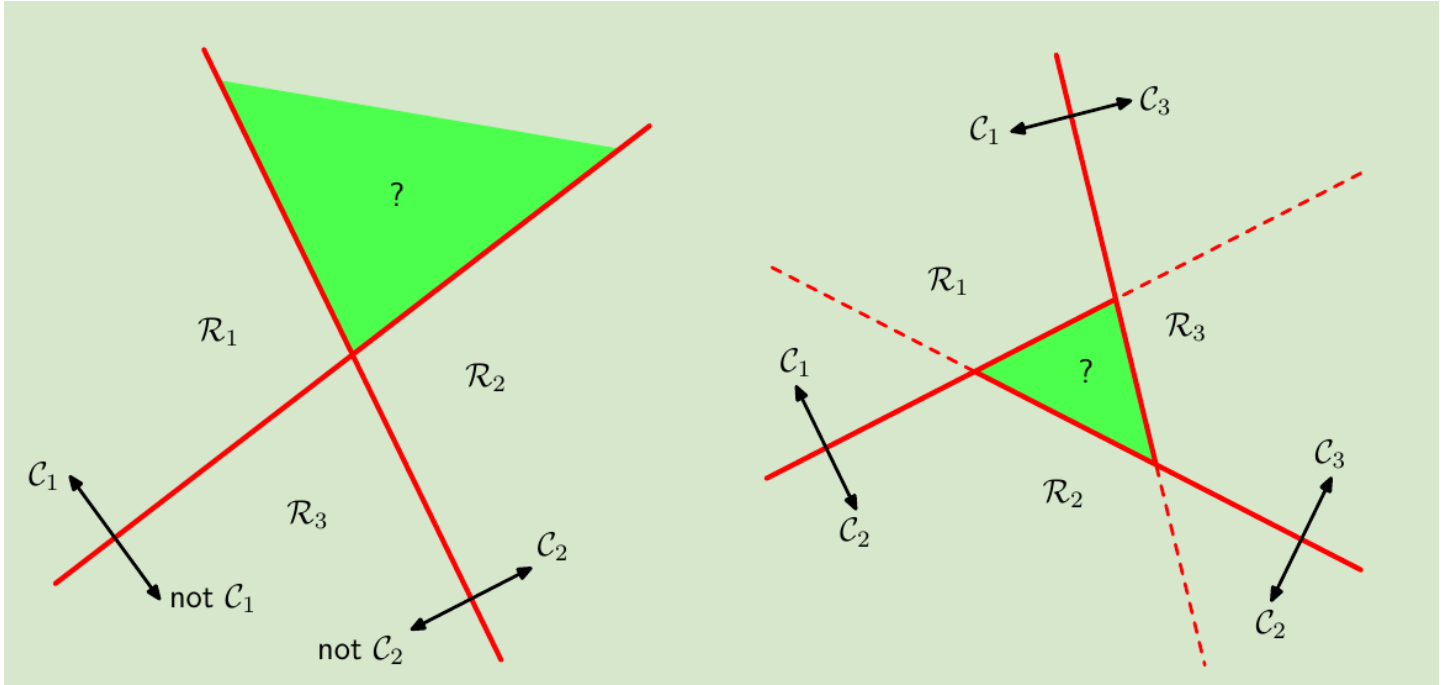
### 4.1.2 Multiple classes

对于一个 $K$ 分类问题,我们定义 $K$ 个linear function:

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$$

当 $y_k(x) > y_j(x)$  for all  $j \neq k$ ,就assign class  $k$ .并且 $\mathcal{C}_k$ 和 $\mathcal{C}_j$ 的decision boundary是

$$(\mathbf{w}_k - \mathbf{w}_j)^T \mathbf{x} + (w_{k0} - w_{j0}) = 0$$



左图简单使用 $K - 1$ 个二分类器(one-versus-the-rest)会产生ambiguous region,右图使用 $K(K - 1)/2$ 个二分类器(one-versus-one)仍然会出现ambiguous region.

### 4.1.3 Least squares for classification

对于每一个类,都有一个linear model:

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$$

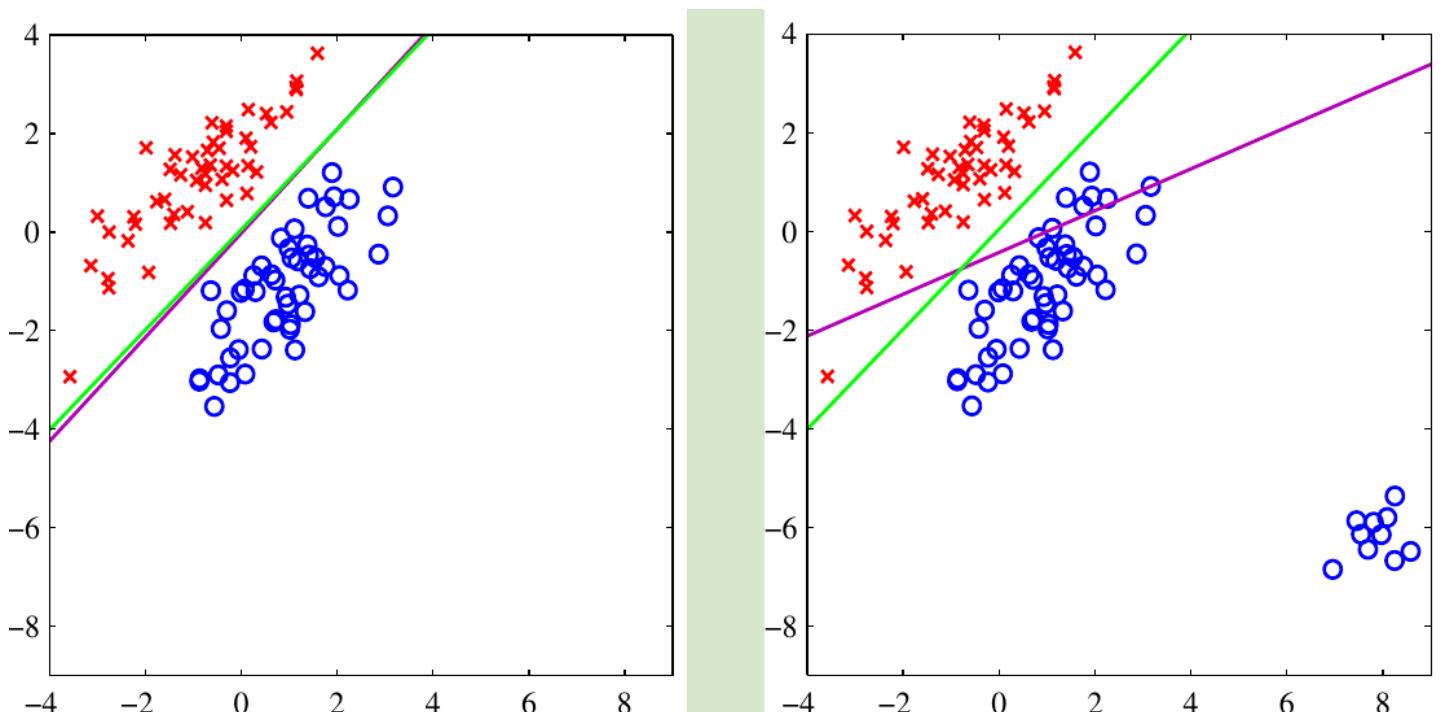
group 起来就可以写成:  $\mathbf{y}(\mathbf{x}) = \widetilde{\mathbf{W}}^T \widetilde{\mathbf{x}}$

优化目标是sum-of-square error:

$$E_D(\widetilde{\mathbf{W}}) = \frac{1}{2} \text{Tr} \left\{ (\widetilde{\mathbf{X}} \widetilde{\mathbf{W}} - \mathbf{T})^T (\widetilde{\mathbf{X}} \widetilde{\mathbf{W}} - \mathbf{T}) \right\}$$

可以解出:

$$\widetilde{\mathbf{W}} = \left( \widetilde{\mathbf{X}}^T \widetilde{\mathbf{X}} \right)^{-1} \widetilde{\mathbf{X}}^T \mathbf{T} = \widetilde{\mathbf{X}}^\dagger \mathbf{T}$$



这样的模型很大的问题就是no robustness,如图上的紫色线受右下角蓝色data point影响.

#### 4.1.4 Fisher's linear discriminant

一种以dimensionality reduction为视角的linear discriminator model:

$$y = \mathbf{w}^T \mathbf{x}$$

$y$ 是个scalar,只要设定个threshold就能用来classify.

基本思想是让两个class的mean在投影到一维空间后尽可能靠的远(between-class),并且两类投影后各自的covariance尽可能小(within-class).于是maximize:

$$J(\mathbf{w}) = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$

其中:  $\mathbf{S}_B = (\mathbf{m}_2 - \mathbf{m}_1)(\mathbf{m}_2 - \mathbf{m}_1)^T$ ,

$\mathbf{S}_W = \sum_{n \in \mathcal{C}_1} (\mathbf{x}_n - \mathbf{m}_1)(\mathbf{x}_n - \mathbf{m}_1)^T + \sum_{n \in \mathcal{C}_2} (\mathbf{x}_n - \mathbf{m}_2)(\mathbf{x}_n - \mathbf{m}_2)^T$ ..对 $\mathbf{w}$ 求微分:

$$(\mathbf{w}^T \mathbf{S}_B \mathbf{w}) \mathbf{S}_W \mathbf{w} = (\mathbf{w}^T \mathbf{S}_W \mathbf{w}) \mathbf{S}_B \mathbf{w}$$

又括号内是scalar,  $\mathbf{S}_W$ 与 $(\mathbf{m}_2 - \mathbf{m}_1)$ 同向,所以:

$$\mathbf{w} \propto \mathbf{S}_W^{-1} (\mathbf{m}_2 - \mathbf{m}_1)$$

#### 4.1.5 Relation to least squares

在least-squares的方法中,将 $\mathcal{C}_1$ 的target设为 $N/N_1$ ,  $\mathcal{C}_2$ 的target设为 $-N/N_2$ ,得到的解与Fisher solution一样.

#### 4.1.6 Fisher's discriminant for multiple classes

考虑有 $K > 2$ 个类,可以将input space投影到 $K - 1$ 维的空间.

$$\mathbf{y} = \mathbf{W}^T \mathbf{x}$$

类似二分类的想法,使用between-class covariance最大,within-class covariance最小的目标:

$$J(\mathbf{W}) = \text{Tr} \left\{ (\mathbf{W}^T \mathbf{S}_W \mathbf{W})^{-1} (\mathbf{W}^T \mathbf{S}_B \mathbf{W}) \right\}$$

其中

$$\begin{aligned} \mathbf{S}_W &= \sum_{k=1}^K \sum_{n \in \mathcal{C}_k} (\mathbf{y}_n - \boldsymbol{\mu}_k)(\mathbf{y}_n - \boldsymbol{\mu}_k)^T \\ \mathbf{S}_B &= \sum_{k=1}^K N_k (\boldsymbol{\mu}_k - \boldsymbol{\mu})(\boldsymbol{\mu}_k - \boldsymbol{\mu})^T \end{aligned}$$

#### 4.1.7 The perceptron algorithm

perceptron 是个仅用于二分类的算法,discriminator function是

$$y(\mathbf{x}) = f(\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}))$$

这里的 $f(\cdot)$ 是一个step function:

$$f(a) = \begin{cases} +1, & a \geq 0 \\ -1, & a < 0 \end{cases}$$

$\phi(\mathbf{x})$ 是basis function.通过minimize一个error function优化 $\mathbf{w}$ :

$$E_P(\mathbf{w}) = - \sum_{n \in \mathcal{M}} \mathbf{w}^T \phi_n t_n$$

使用stochastic gradient descent去优化这个function:

$$\mathbf{w}^{(\tau+1)} = \mathbf{w}^{(\tau)} - \eta \nabla E_P(\mathbf{w}) = \mathbf{w}^{(\tau)} + \eta \phi_n t_n$$

## 4.2. Probabilistic Generative Models

现在我们来考虑二分类的posterior:

$$\begin{aligned} p(\mathcal{C}_1 | \mathbf{x}) &= \frac{p(\mathbf{x} | \mathcal{C}_1) p(\mathcal{C}_1)}{p(\mathbf{x} | \mathcal{C}_1) p(\mathcal{C}_1) + p(\mathbf{x} | \mathcal{C}_2) p(\mathcal{C}_2)} \\ &= \frac{1}{1 + \exp(-a)} = \sigma(a) \end{aligned}$$

其中 $a = \ln \frac{p(\mathbf{x} | \mathcal{C}_1) p(\mathcal{C}_1)}{p(\mathbf{x} | \mathcal{C}_2) p(\mathcal{C}_2)}$ ,  $\sigma(a)$ 被称为*logistic sigmoid*.

但多分类的时候:

$$\begin{aligned} p(\mathcal{C}_k | \mathbf{x}) &= \frac{p(\mathbf{x} | \mathcal{C}_k) p(\mathcal{C}_k)}{\sum_j p(\mathbf{x} | \mathcal{C}_j) p(\mathcal{C}_j)} \\ &= \frac{\exp(a_k)}{\sum_j \exp(a_j)} \end{aligned}$$

其中 $a_k = \ln p(\mathbf{x} | \mathcal{C}_k) p(\mathcal{C}_k)$ . 式中的normalized exponential也被称为*softmax function*.

### 4.2.1 Continuous inputs

假设input variable服从同covariance的Gaussian:

$$p(\mathbf{x} | \mathcal{C}_k) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma|^{1/2}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) \right\}.$$

posterior是:

$$p(\mathcal{C}_1 | \mathbf{x}) = \sigma(\mathbf{w}^T \mathbf{x} + w_0)$$

其中

$$\begin{aligned}\mathbf{w} &= \Sigma^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_2) \\ w_0 &= -\frac{1}{2}\boldsymbol{\mu}_1^T \Sigma^{-1} \boldsymbol{\mu}_1 + \frac{1}{2}\boldsymbol{\mu}_2^T \Sigma^{-1} \boldsymbol{\mu}_2 + \ln \frac{p(\mathcal{C}_1)}{p(\mathcal{C}_2)}\end{aligned}$$

观察到quadratic消失了,也就意味着decision boundary是linear的.若不假设不同class covariance一致,那么得到的decision boundary是曲面.

#### 4.2.2 Maximum likelihood solution

仍然假设data关于类别服从共covariance的Gaussian.二分类为例,  $t_n = 1$  是  $\mathcal{C}_1$ ,  $t_n = 0$  是  $\mathcal{C}_2$ , 设prior是  $p(\mathcal{C}_1) = \pi, p(\mathcal{C}_2) = 1 - \pi$ , 则posterior:

$$p(\mathbf{x}_n, \mathcal{C}_1) = p(\mathcal{C}_1) p(\mathbf{x}_n | \mathcal{C}_1) = \pi \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_1, \Sigma).$$

$$p(\mathbf{x}_n, \mathcal{C}_2) = p(\mathcal{C}_2) p(\mathbf{x}_n | \mathcal{C}_2) = (1 - \pi) \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_2, \Sigma)$$

可以计算likelihood:

$$p(\mathbf{t} | \pi, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \Sigma) = \prod_{n=1}^N [\pi \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_1, \Sigma)]^{t_n} [(1 - \pi) \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_2, \Sigma)]^{1-t_n}$$

MLE的结果:

$$\begin{aligned}\boldsymbol{\mu}_1 &= \frac{1}{N_1} \sum_{n=1}^N t_n \mathbf{x}_n \\ \boldsymbol{\mu}_2 &= \frac{1}{N_2} \sum_{n=1}^N (1 - t_n) \mathbf{x}_n\end{aligned}$$

$$\begin{aligned}& -\frac{1}{2} \sum_{n=1}^N t_n \ln |\Sigma| - \frac{1}{2} \sum_{n=1}^N t_n (\mathbf{x}_n - \boldsymbol{\mu}_1)^T \Sigma^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_1) \\ & -\frac{1}{2} \sum_{n=1}^N (1 - t_n) \ln |\Sigma| - \frac{1}{2} \sum_{n=1}^N (1 - t_n) (\mathbf{x}_n - \boldsymbol{\mu}_2)^T \Sigma^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_2) \\ & = -\frac{N}{2} \ln |\Sigma| - \frac{N}{2} \text{Tr}\{\Sigma^{-1} \mathbf{S}\}\end{aligned}$$

其中

$$\begin{aligned}\mathbf{S} &= \frac{N_1}{N} \mathbf{S}_1 + \frac{N_2}{N} \mathbf{S}_2 \\ \mathbf{S}_1 &= \frac{1}{N_1} \sum_{n \in \mathcal{C}_1} (\mathbf{x}_n - \boldsymbol{\mu}_1) (\mathbf{x}_n - \boldsymbol{\mu}_1)^T \\ \mathbf{S}_2 &= \frac{1}{N_2} \sum_{n \in \mathcal{C}_2} (\mathbf{x}_n - \boldsymbol{\mu}_2) (\mathbf{x}_n - \boldsymbol{\mu}_2)^T.\end{aligned}$$

最终  $\boldsymbol{\Sigma} = \mathbf{S}$ . 也就是两类的weighted average of covariance.

### 4.2.3 Discrete features

当input是discrete时,考虑变量是binary,做*naive bayes*假设:所有变量都是independent,所以class-conditional distribution:

$$p(\mathbf{x} \mid \mathcal{C}_k) = \prod_{i=1}^D \mu_{ki}^{x_i} (1 - \mu_{ki})^{1-x_i}$$

## 4.3. Probabilistic Discriminative Models

### 4.3.1 Fixed basis functions

目前的model都是关于parameter是linear的,但由于basis function(可以是nonlinear)的存在,尽管decision boundary在feature space中是linear,关于input space可以是nonlinear.

### 4.3.2 Logistic regression

考虑二分类的情况,sigmoid有个微分性质:

$$\frac{d\sigma}{da} = \sigma(1 - \sigma)$$

设  $t_n \in \{0, 1\}$ , likelihood function可写成:

$$p(\mathbf{t} \mid \mathbf{w}) = \prod_{n=1}^N y_n^{t_n} \{1 - y_n\}^{1-t_n}$$

通过取negative logarithm of the likelihood(NLL/cross entropy error):

$$E(\mathbf{w}) = -\ln p(\mathbf{t} | \mathbf{w}) = -\sum_{n=1}^N \{t_n \ln y_n + (1 - t_n) \ln(1 - y_n)\}$$

求gradient:

$$\nabla E(\mathbf{w}) = \sum_{n=1}^N (y_n - t_n) \phi_n$$

如此可以用gradient descent来解.

note: 由于logistic regression实际是MLE,所以不可避免会引入over-fit,通过加入regularization或者求MAP最大可以解决.

### 4.3.3 Iterative reweighted least squares

logistic regression的cross entropy error无法得到closed-form solution是因为一阶导中包含了非线性 (sigmoid)的求和.利用Newton-Raphson iterative optimization scheme,我们可以更高效求解:

$$\mathbf{w}^{(\text{new})} = \mathbf{w}^{(\text{old})} - \mathbf{H}^{-1} \nabla E(\mathbf{w})$$

首先求出cross entropy的一阶导和hessian matrix:

$$\begin{aligned} \nabla E(\mathbf{w}) &= \sum_{n=1}^N (y_n - t_n) \phi_n = \mathbf{\Phi}^T (\mathbf{y} - \mathbf{t}) \\ \mathbf{H} = \nabla \nabla E(\mathbf{w}) &= \sum_{n=1}^N y_n (1 - y_n) \phi_n \phi_n^T = \mathbf{\Phi}^T \mathbf{R} \mathbf{\Phi} \end{aligned}$$

其中的 $\mathbf{R}$ 是 $n \times n$ 的diagonal matrix,对角元素为:

$$R_{nn} = y_n (1 - y_n)$$

由于 $1 > y_n > 0$ ,所以 $\mathbf{H}$ 是正定的,也就说明logistic regression有global minimum solution. IRLS:

$$\begin{aligned} \mathbf{w}^{(\text{new})} &= \mathbf{w}^{(\text{old})} - (\mathbf{\Phi}^T \mathbf{R} \mathbf{\Phi})^{-1} \mathbf{\Phi}^T (\mathbf{y} - \mathbf{t}) \\ &= (\mathbf{\Phi}^T \mathbf{R} \mathbf{\Phi})^{-1} \left\{ \mathbf{\Phi}^T \mathbf{R} \mathbf{\Phi} \mathbf{w}^{(\text{old})} - \mathbf{\Phi}^T (\mathbf{y} - \mathbf{t}) \right\} \\ &= (\mathbf{\Phi}^T \mathbf{R} \mathbf{\Phi})^{-1} \mathbf{\Phi}^T \mathbf{R} \mathbf{z} \end{aligned}$$



### 4.3.4 Multiclass logistic regression

多分类的posterior为:

$$p(\mathcal{C}_k | \phi) = y_k(\phi) = \frac{\exp(a_k)}{\sum_j \exp(a_j)}$$

其中  $a_k = \mathbf{w}_k^T \phi$ .

softmax的derivation也有性质:

$$\frac{\partial y_k}{\partial a_j} = y_k (I_{kj} - y_j)$$

使用likelihood:

$$p(\mathbf{T} | \mathbf{w}_1, \dots, \mathbf{w}_K) = \prod_{n=1}^N \prod_{k=1}^K p(\mathcal{C}_k | \phi_n)^{t_{nk}} = \prod_{n=1}^N \prod_{k=1}^K y_{nk}^{t_{nk}}$$

NLL为:

$$E(\mathbf{w}_1, \dots, \mathbf{w}_K) = -\ln p(\mathbf{T} | \mathbf{w}_1, \dots, \mathbf{w}_K) = -\sum_{n=1}^N \sum_{k=1}^K t_{nk} \ln y_{nk}$$

类似于二分类的logistic regression,多分类有类似的优化形式:

$$\begin{aligned} \nabla_{\mathbf{w}_j} E(\mathbf{w}_1, \dots, \mathbf{w}_K) &= \sum_{n=1}^N (y_{nj} - t_{nj}) \phi_n \\ \nabla_{\mathbf{w}_k} \nabla_{\mathbf{w}_j} E(\mathbf{w}_1, \dots, \mathbf{w}_K) &= -\sum_{n=1}^N y_{nk} (I_{kj} - y_{nj}) \phi_n \phi_n^T \end{aligned}$$

### 4.3.5 Probit regression

posterior被描述为linear combination of feature后的activation输出.  $p(t = 1 | a) = f(a)$ , 这里的  $f(\cdot)$  即为activation. 通过设置阈值  $\theta$  来给出target类别:

$$\begin{cases} t_n = 1 & \text{if } a_n \geq \theta \\ t_n = 0 & \text{otherwise} \end{cases}$$

现在把  $\theta$  看成从一个从  $p(\theta)$  的distribution里抽取得到的, 那么activation function可以这样给出

$$f(a) = \int_{-\infty}^a p(\theta) d\theta$$

当 $\theta$ 取标准正态分布的时候:

$$\Phi(a) = \int_{-\infty}^a \mathcal{N}(\theta | 0, 1) d\theta$$

被称为 *probit function*. 使用了这个函数作为 activation function 时的 GLM (generalize linear model) 被称为 *probit regression*.

note: 由于 probit 带有二次项, 所以比 logistic regression 更易受 outliers 影响.

## 4.4 The Laplace Approximation

由于 sigmoid 等一些非线性 activation function 的存在, 无法进行解析积分  $p(z)$ . Laplace approximation 是使用 Gaussian 的  $q(z)$  去 approximate  $p(z)$ , 来解决这个问题. 设要被近似的概率为  $p(z) = \frac{1}{Z} f(z)$ . 其中  $Z$  用作 normalization. 我们使用概率的众数  $z_0$  点:

$$\left. \frac{df(z)}{dz} \right|_{z=z_0} = 0$$

在  $z_0$  使用 Taylor 展开:

$$\ln f(z) \simeq \ln f(z_0) - \frac{1}{2} A (z - z_0)^2$$

其中  $A = -\frac{d^2}{dz^2} \ln f(z) \Big|_{z=z_0}$ . 如此可以用 Gaussian 去近似  $p(z)$ :

$$q(z) = \left( \frac{A}{2\pi} \right)^{1/2} \exp \left\{ -\frac{A}{2} (z - z_0)^2 \right\}$$

## 4.5. Bayesian Logistic Regression

### 4.5.1 Laplace approximation

prior 用 Gaussian:

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_0, \mathbf{S}_0)$$

likelihood 用 Laplace approximate, 并利用 Bayes' theorem  $p(\mathbf{w} | \mathbf{t}) \propto p(\mathbf{w}) p(\mathbf{t} | \mathbf{w})$  求 posterior 最大:

$$\ln p(\mathbf{w} \mid \mathbf{t}) = -\frac{1}{2}(\mathbf{w} - \mathbf{m}_0)^T \mathbf{S}_0^{-1} (\mathbf{w} - \mathbf{m}_0) + \sum_{n=1}^N \{t_n \ln y_n + (1 - t_n) \ln(1 - y_n)\} + \text{const}$$

这样得到的解是MAP解:

$$q(\mathbf{w}) = \mathcal{N}(\mathbf{w} \mid \mathbf{w}_{\text{MAP}}, \mathbf{S}_N)$$

### 4.5.2 Predictive distribution

现在考虑marginalize这一步:

$$p(\mathcal{C}_1 \mid \phi, \mathbf{t}) = \int p(\mathcal{C}_1 \mid \phi, \mathbf{w}) p(\mathbf{w} \mid \mathbf{t}) d\mathbf{w} \simeq \int \sigma(\mathbf{w}^T \phi) q(\mathbf{w}) d\mathbf{w}$$

引入 $\delta$ 函数:

$$\sigma(\mathbf{w}^T \phi) = \int \delta(a - \mathbf{w}^T \phi) \sigma(a) da$$

最后predictive function:

$$p(\mathcal{C}_1 \mid \mathbf{t}) = \int \sigma(a) p(a) da = \int \sigma(a) \mathcal{N}(a \mid \mu_a, \sigma_a^2) da$$