Carnegie Mellon University

# Database Systems

Distributed Databases

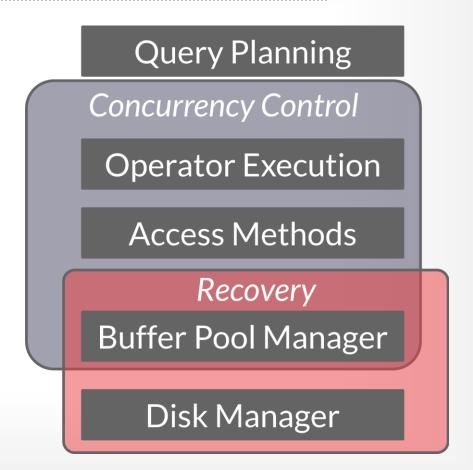


15-445/645 FALL 2024 >> PROF. A

#### COURSE STATUS

Databases are hard.

Distributed databases are harder.



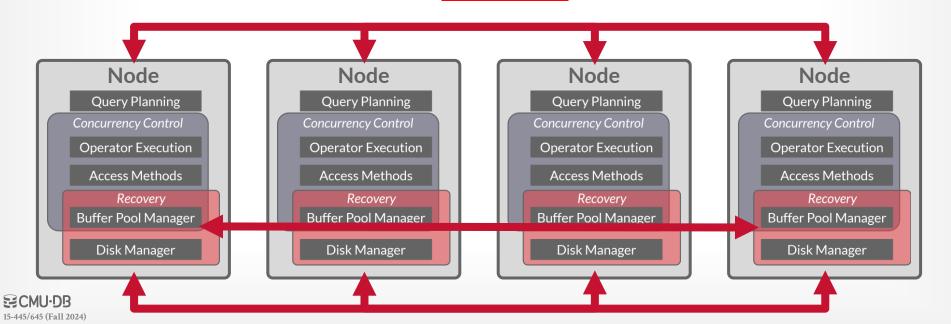


# COURSE STATUS

Databases are hard.

Distributed databases are harder.

#### coordinator



# PARALLEL VS. DISTRIBUTED

#### **Parallel DBMSs:**

- → Nodes are physically close to each other.
- → Nodes connected with high-speed LAN.
- → Communication cost is assumed to be small.

#### **Distributed DBMSs:**

- → Nodes can be far from each other.
- → Nodes connected using public network.
- → Communication cost and problems cannot be ignored.



#### DISTRIBUTED DBMSs

Use the building blocks that we covered in singlenode DBMSs to now support transaction processing and query execution in distributed environments.

- → Optimization & Planning 需要考虑节点之间的数据迁移成本
- $\rightarrow$  Concurrency Control
- → Logging & Recovery



#### TODAY'S AGENDA

System Architectures

Design Issues

Partitioning Schemes

Distributed Concurrency Control

DB Flash Talk: DataStax



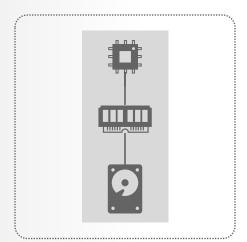
#### SYSTEM ARCHITECTURE

A distributed DBMS's system architecture specifies what shared resources are directly accessible to CPUs.

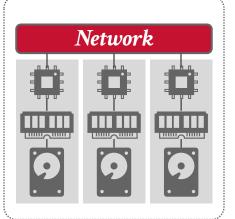
This affects how CPUs coordinate with each other and where they retrieve/store objects in the database.



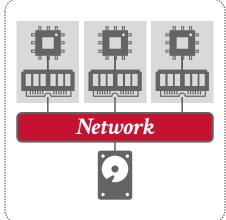
#### SYSTEM ARCHITECTURE



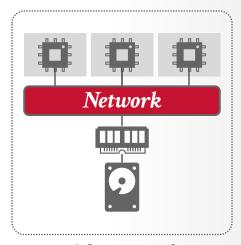
Shared Everything



Shared Nothing



Shared Disk



Shared Memory

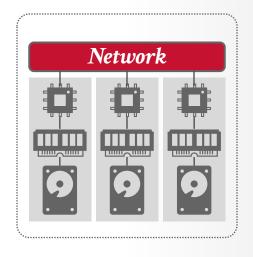


#### SHARED NOTHING

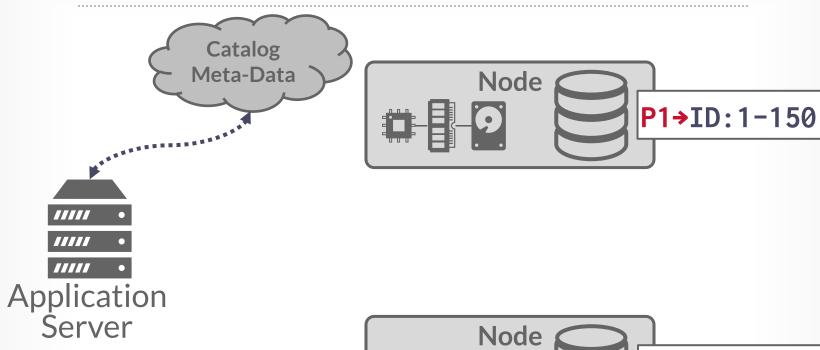
Each DBMS node has its own CPU, memory, and local disk.

Nodes only communicate with each other via network.

- → Better performance & efficiency.
- $\rightarrow$  Harder to scale capacity.
- → Harder to ensure consistency.

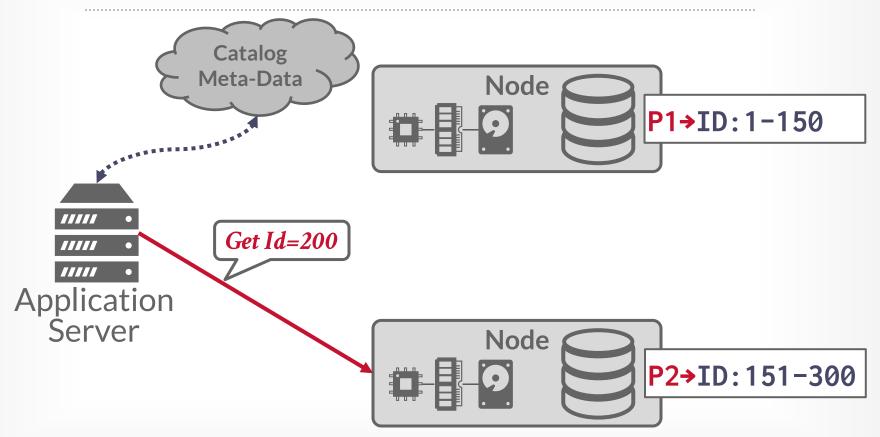




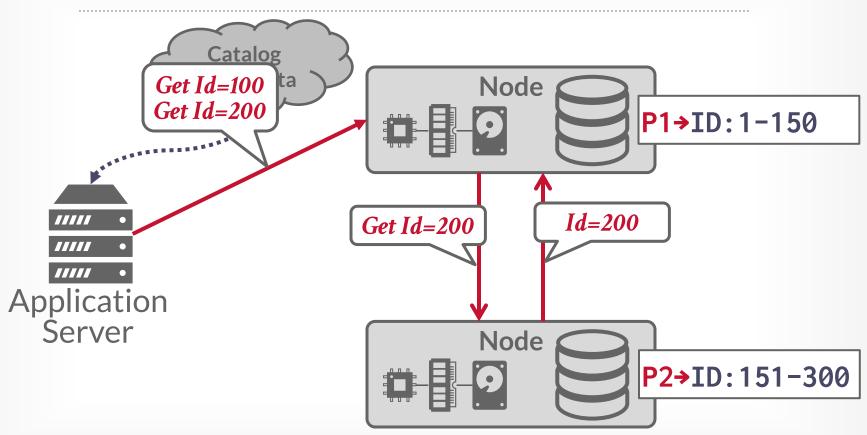










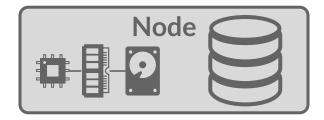






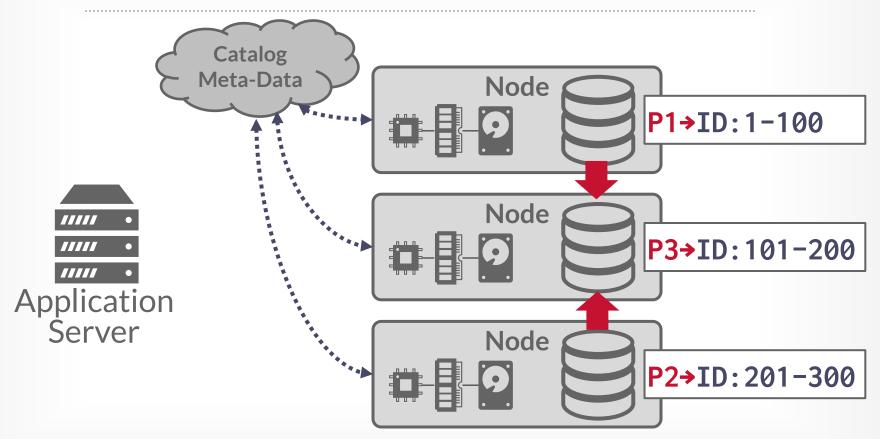










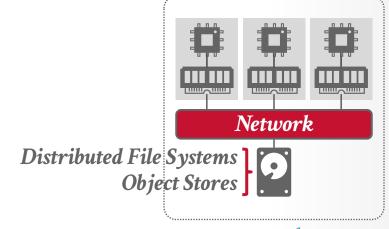




#### SHARED DISK

Nodes access a single logical disk via an interconnect, but each have their own private memories.

- → Scale execution layer independently from the storage layer.
- → Nodes can still use direct attached storage as a slower/larger cache.
- → This architecture facilitates **data lakes** and **serverless** systems.

















**ROCKSET** 





















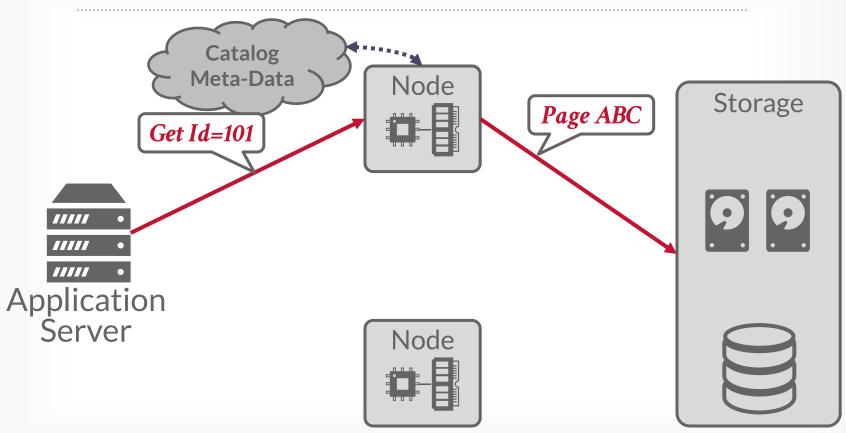




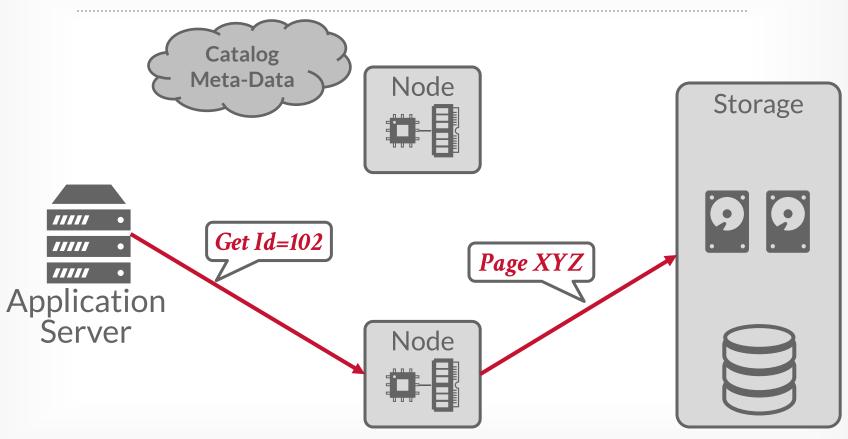






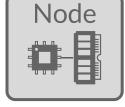




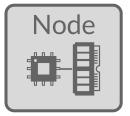


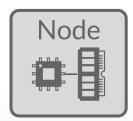


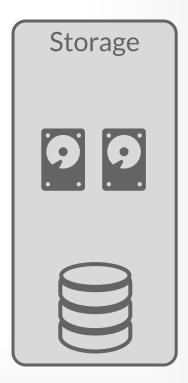




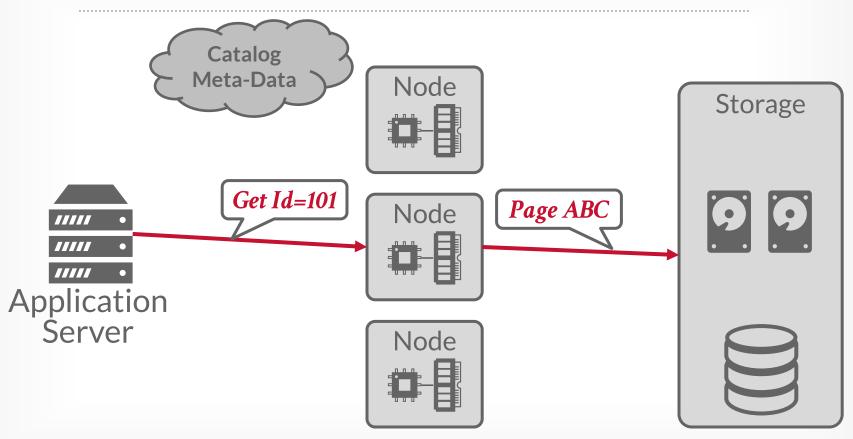




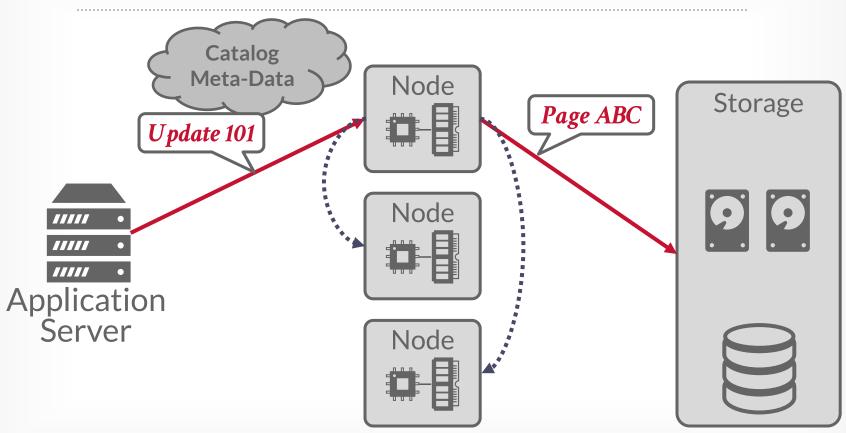




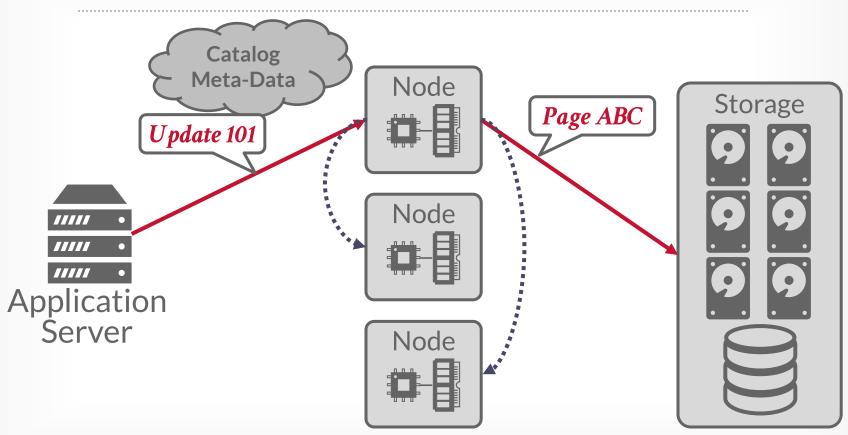












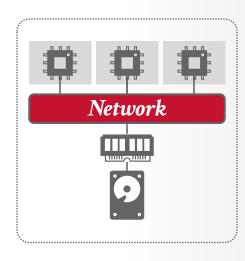


# SHARED MEMORY

Nodes access a common memory address space via a fast interconnect.

- → Each node has a global view of all the inmemory data structures.
- → Can still use local memory / disk for intermediate results.

This looks a lot like sharedeverything. Nobody does this.





#### DESIGN ISSUES

How does the application find data?

Where does the application send queries?

How to execute queries on distributed data?

- $\rightarrow$  Push query to data.
- $\rightarrow$  Pull data to query.

How do we divide the database across resources?

How does the DBMS ensure correctness? **Next Class** 



#### DATA TRANSPARENCY

Applications should not be required to know where data is physically located in a distributed DBMS.

→ Any query that run on a single-node DBMS should produce the same result on a distributed DBMS.

In practice, developers need to be aware of the communication costs of queries to avoid excessively "expensive" data movement.



#### DATABASE PARTITIONING

Split database across multiple resources:

- $\rightarrow$  Disks, nodes, processors.
- → Called "sharding" in NoSQL systems.

The DBMS executes query fragments on each partition and then combines the results to produce a single answer.



# NAÏVE TABLE PARTITIONING

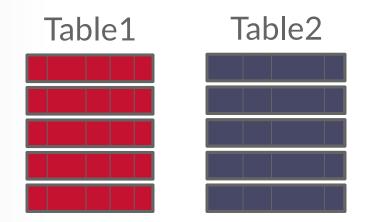
Assign an entire table to a single node.

Assumes that each node has enough storage space for an entire table.

Ideal if queries never join data across tables stored on different nodes and access patterns are uniform.

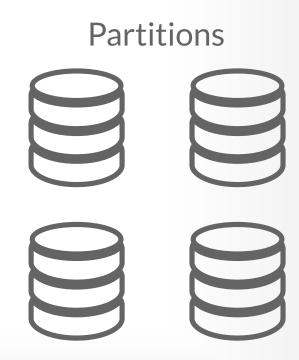


# NAÏVE TABLE PARTITIONING

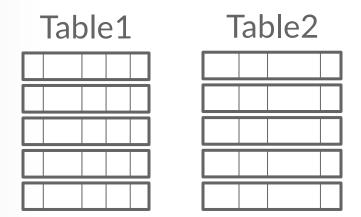


Ideal Query:

**SELECT** \* **FROM** table1



# NAÏVE TABLE PARTITIONING



Ideal Query:

**SELECT** \* **FROM** table1











#### VERTICAL PARTITIONING

Split a table's attributes into separate partitions.

Must store tuple information to reconstruct the original record.

```
CREATE TABLE foo (
  attr1 INT,
  attr2 INT,
  attr3 INT,
  attr4 TEXT
);
```

Tuple#1	attr1	attr2	attr3	attr4
Tuple#2	attr1	attr2	attr3	attr4
Tuple#3	attr1	attr2	attr3	attr4
Tuple#4	attr1	attr2	attr3	attr4



#### VERTICAL PARTITIONING

Split a table's attributes into separate partitions.

Must store tuple information to reconstruct the original record.

```
CREATE TABLE foo (
  attr1 INT,
  attr2 INT,
  attr3 INT,
  attr4 TEXT
);
```

#### Partition #1

Tuple#1	attr1	attr2	attr3
Tuple#2	attr1	attr2	attr3
Tuple#3	attr1	attr2	attr3
Tuple#4	attr1	attr2	attr3

#### Partition #2

Tuple#1	attr4
Tuple#2	attr4
Tuple#3	attr4
Tuple#4	attr4



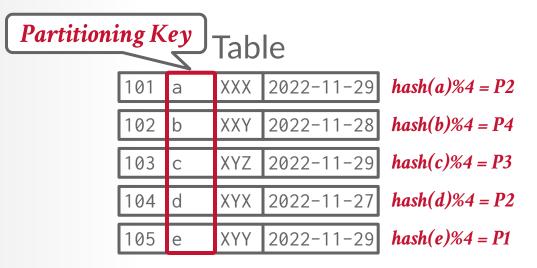
Split a table's tuples into disjoint subsets based on some partitioning key and scheme.

→ Choose column(s) that divides the database equally in terms of size, load, or usage.

#### Partitioning Schemes:

- → Hashing
- $\rightarrow$  Ranges
- → Predicates





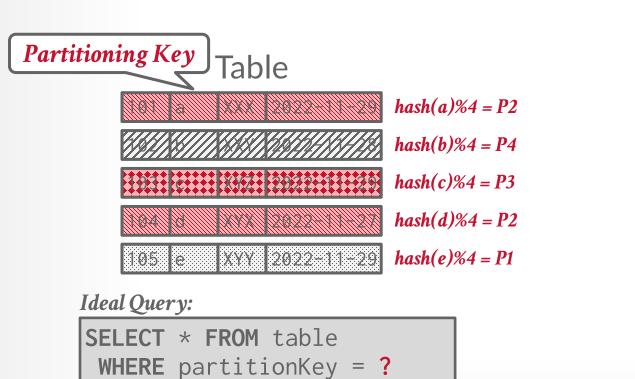
#### Ideal Query:

SELECT \* FROM table
WHERE partitionKey = ?



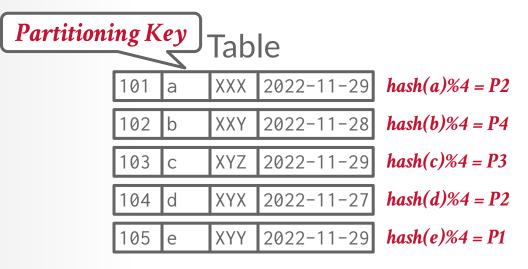






# **Partitions**





#### Ideal Query:

```
SELECT * FROM table
WHERE partitionKey = ?
```

#### **Partitions**



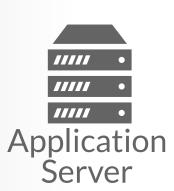


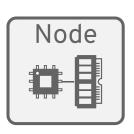


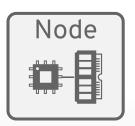


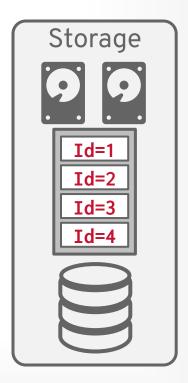


# SHARED-DISK PARTITIONING



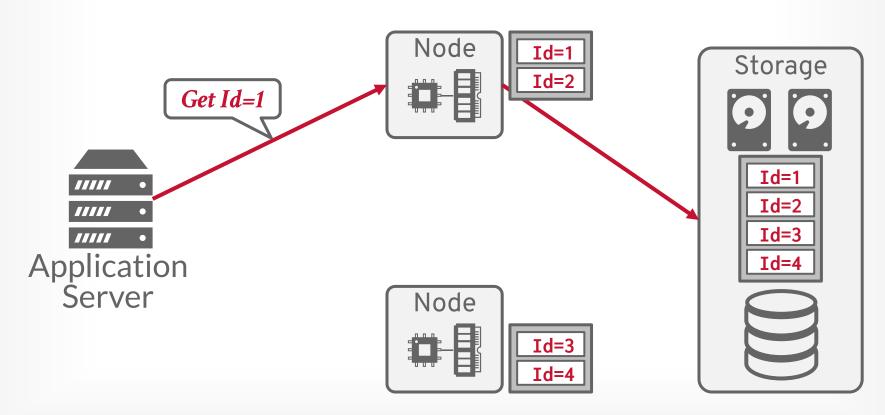






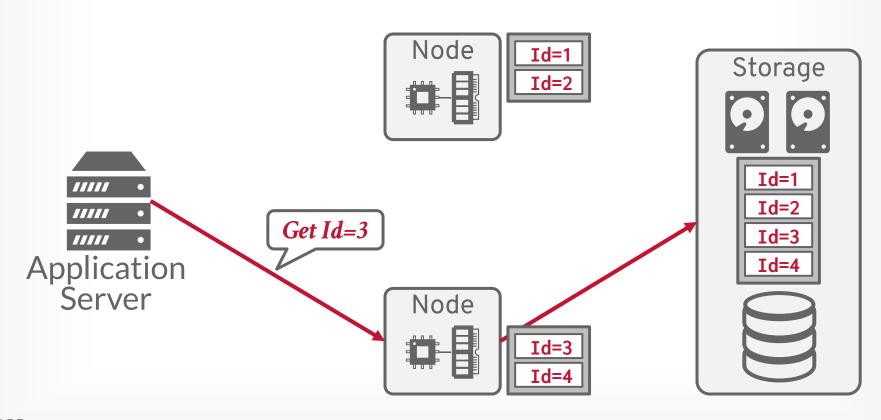


# SHARED-DISK PARTITIONING



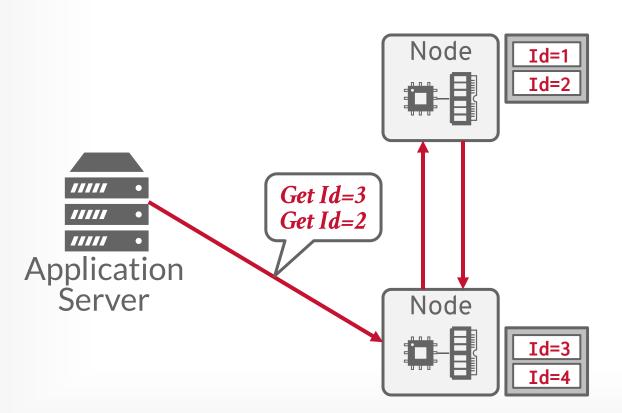


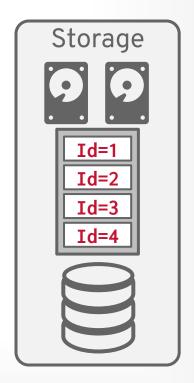
# SHARED-DISK PARTITIONING





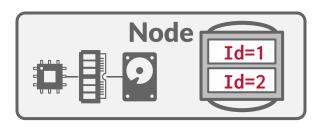
### SHARED-DISK PARTITIONING

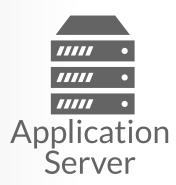


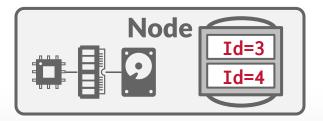




### SHARED-NOTHING PARTITIONING

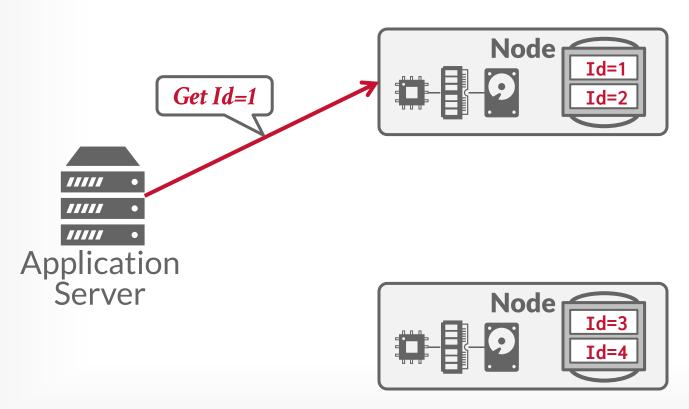






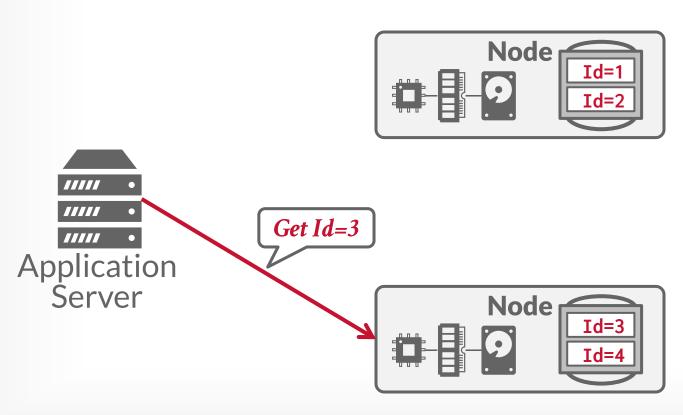


### SHARED-NOTHING PARTITIONING



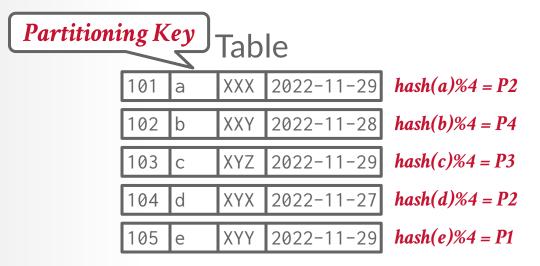


### SHARED-NOTHING PARTITIONING





#### HORIZONTAL PARTITIONING



#### Ideal Query:

SELECT \* FROM table
WHERE partitionKey = ?









#### HORIZONTAL PARTITIONING

# Partitioning Key Table

	101	а	XXX	2022-11-29	hash(a)%4 = P2
--	-----	---	-----	------------	----------------

2022-11-28 hash(b)%4 = P4102 XXY

2022-11-29 hash(c)%4 = P3

hash(d)%4 = P22022-11-27

2022-11-29 hash(e)%4 = P1le

#### Ideal Query:

**SELECT** \* **FROM** table WHERE partitionKey = ?





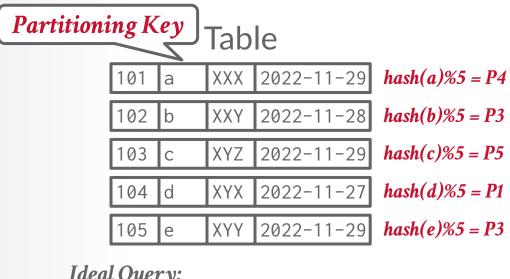






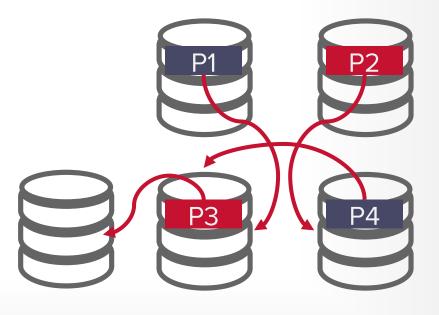


#### HORIZONTAL PARTITIONING

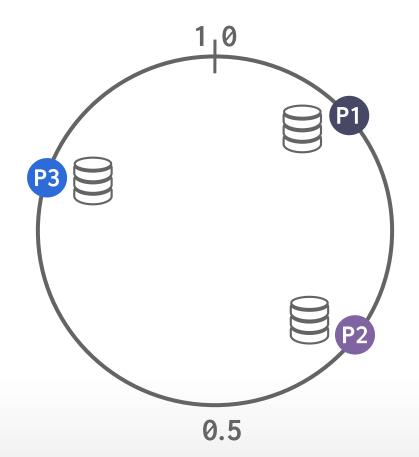


#### Ideal Query:

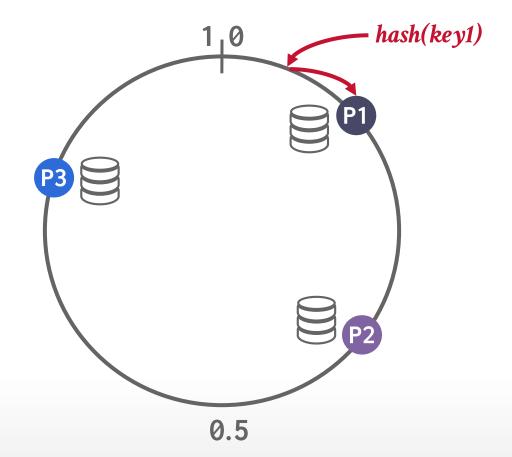
\* FROM table WHERE partitionKey = ?



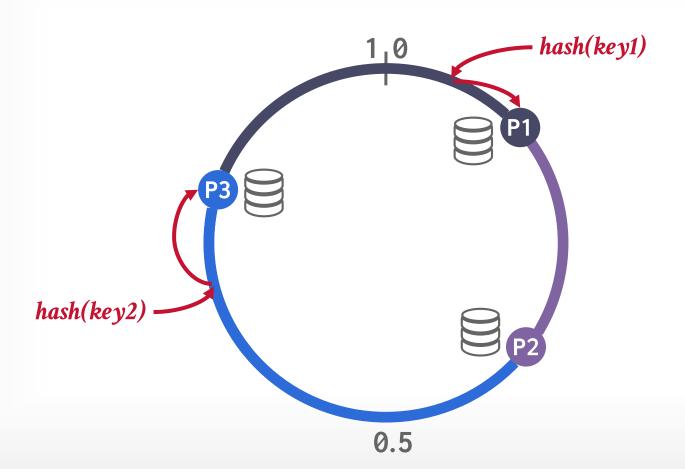




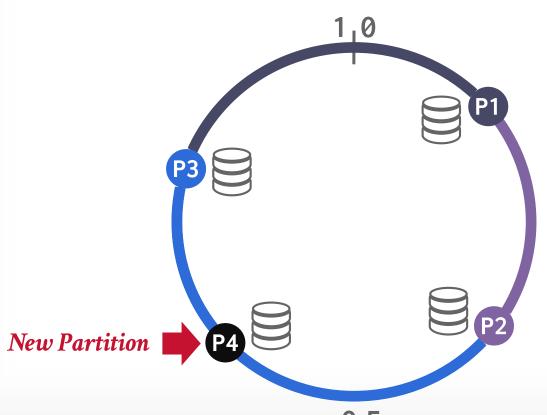




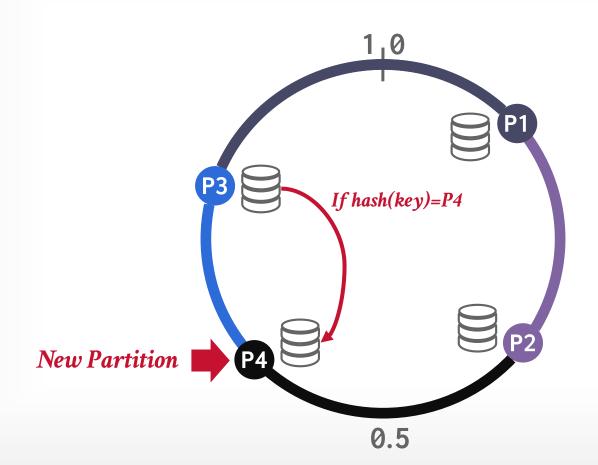




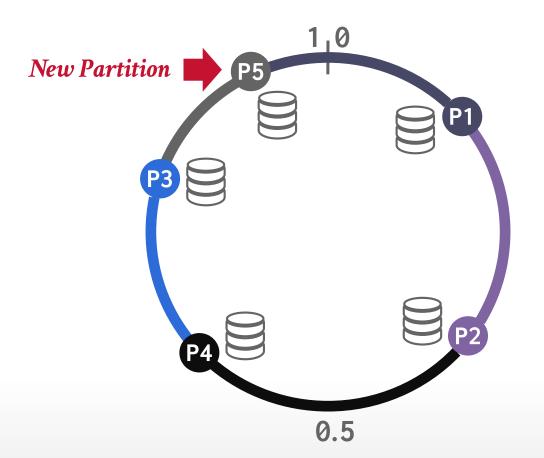




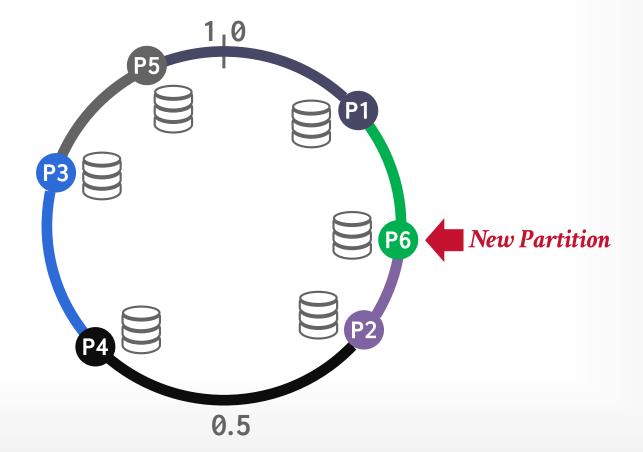




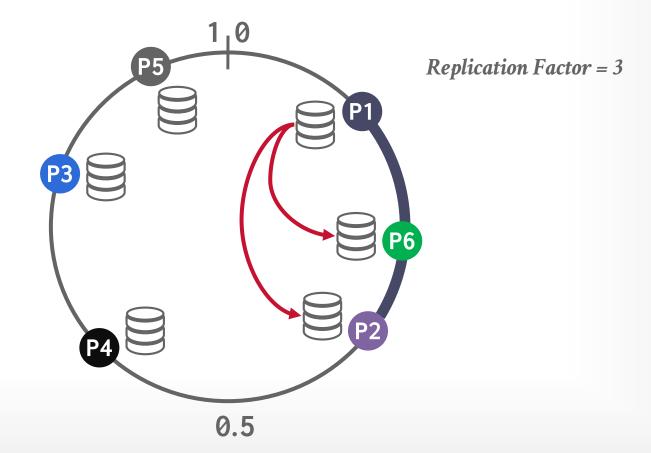


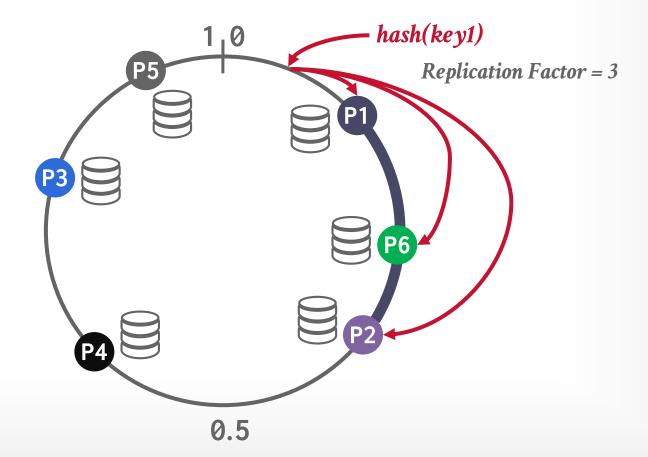
















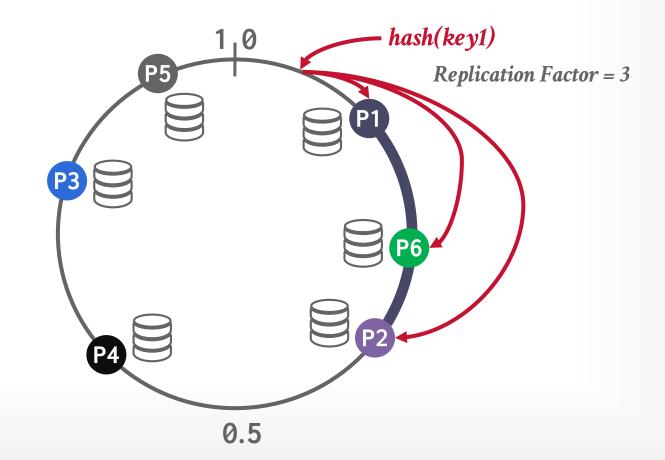














### SINGLE-NODE VS. DISTRIBUTED

A <u>single-node</u> txn only accesses data that is contained on one partition.

→ The DBMS may not need check the behavior concurrent txns running on other nodes.

A <u>distributed</u> txn accesses data at one or more partitions.

 $\rightarrow$  Requires expensive coordination.



#### TRANSACTION COORDINATION

If our DBMS supports multi-operation and distributed txns, we need a way to coordinate their execution in the system.

Two different approaches:

- → **Centralized**: Global "traffic cop".
- → **Decentralized**: Nodes organize themselves.

Most distributed DBMSs use a hybrid approach where they periodically elect some node to be a temporary coordinator.



Coordinator



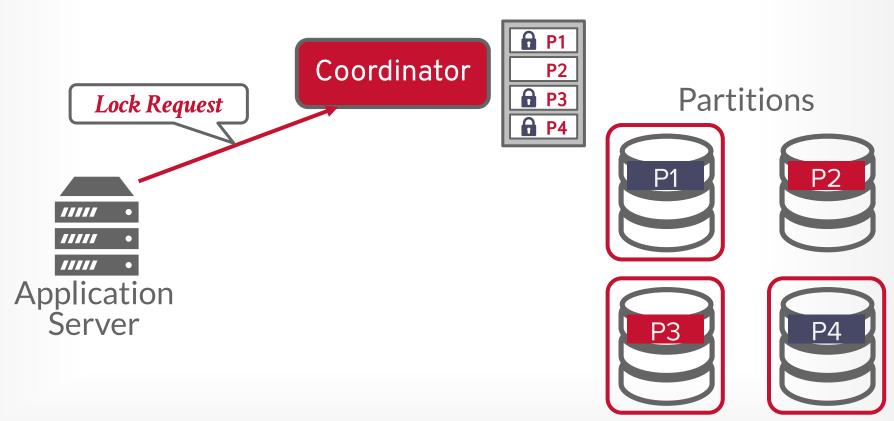




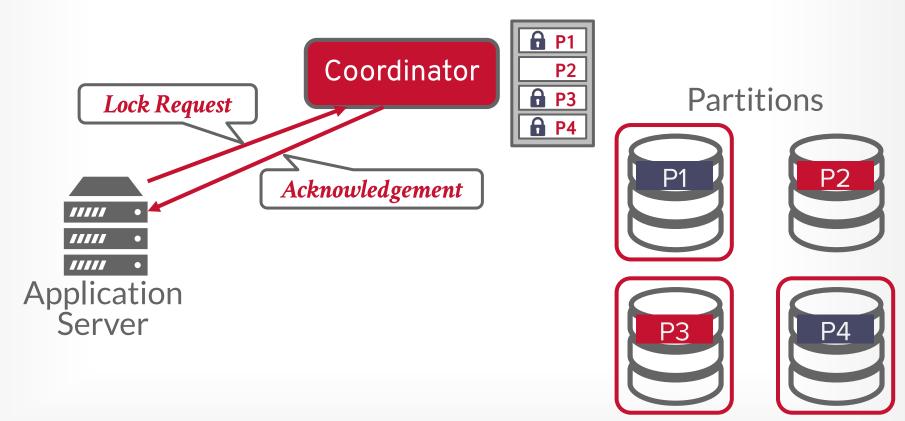




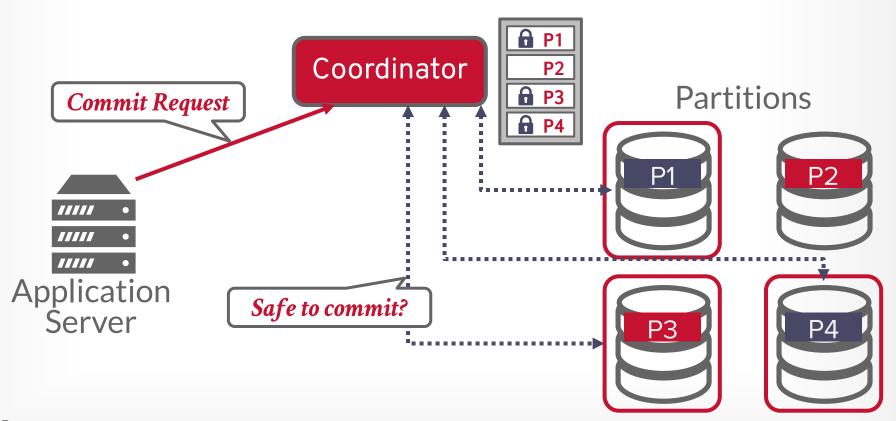




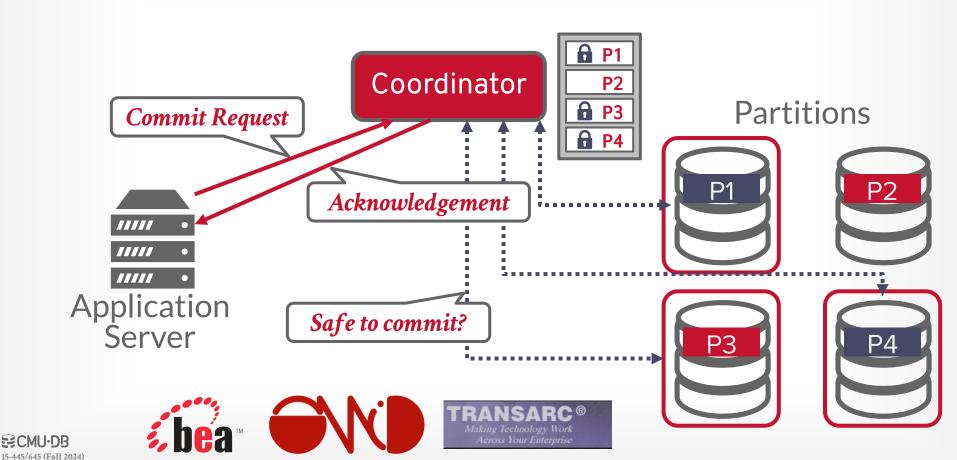


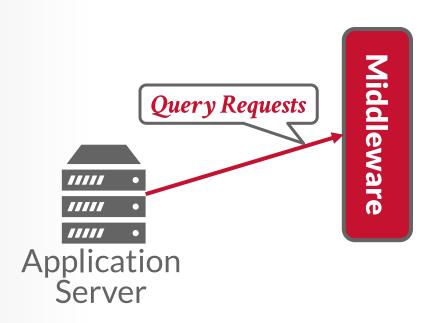












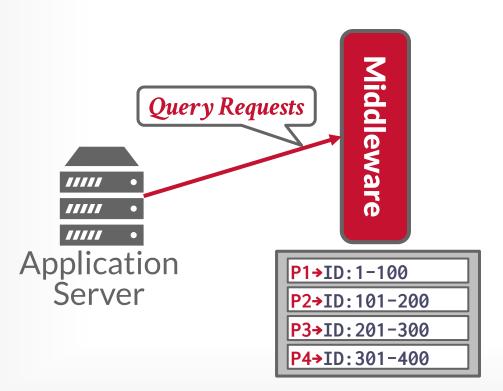












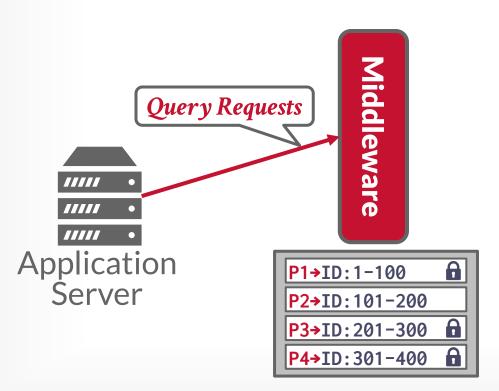












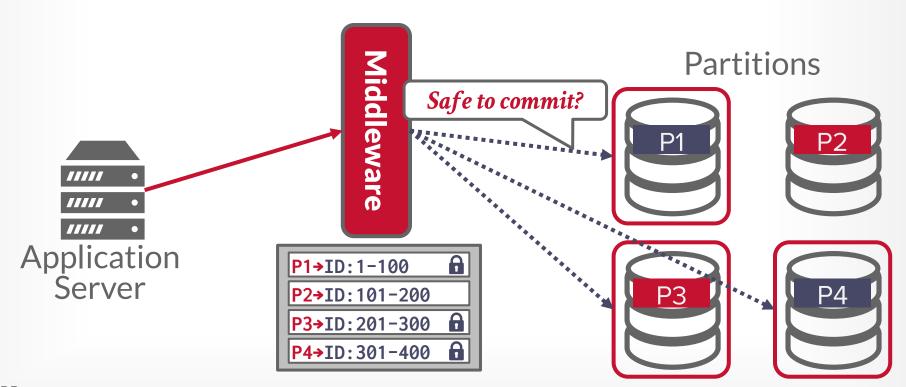




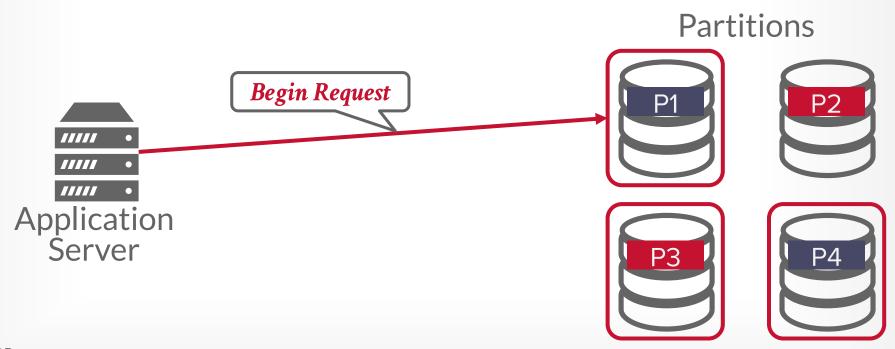




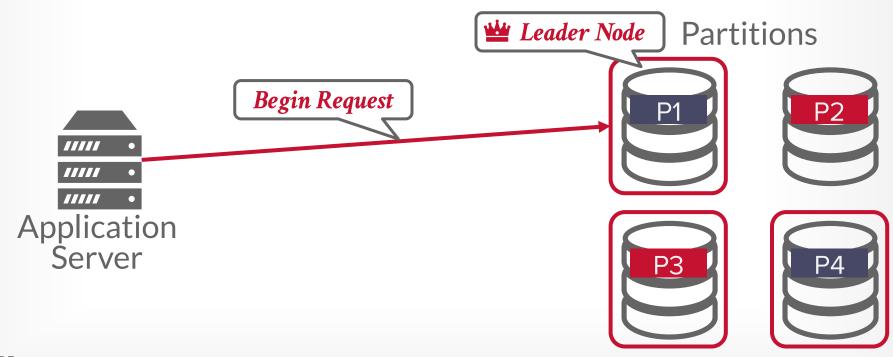




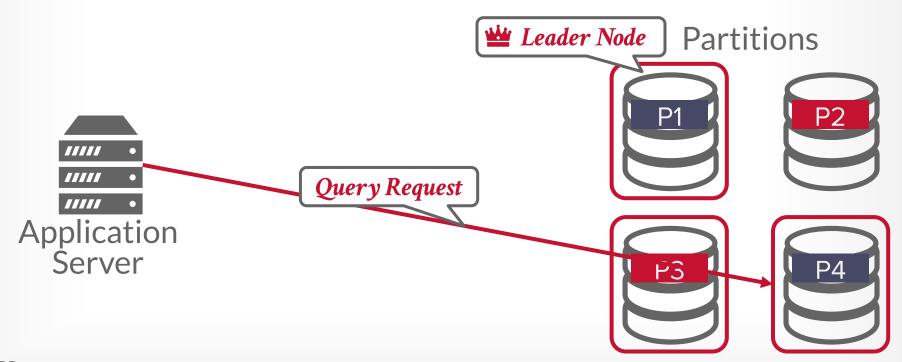




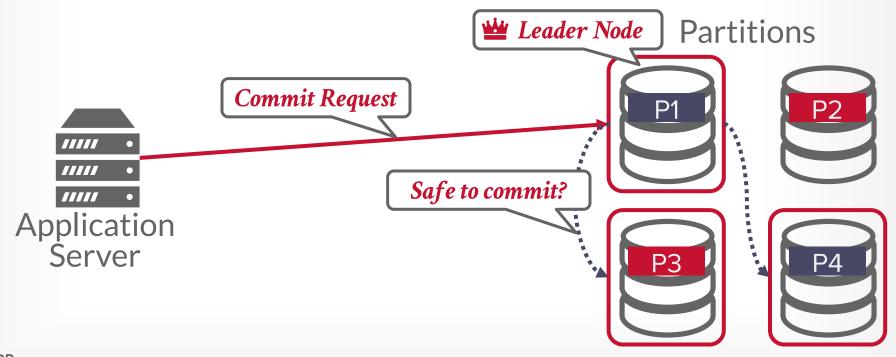














#### **OBSERVATION**

We have assumed that the nodes in our distributed systems are running the same DBMS software.

But organizations often run many different DBMSs in their applications.

It would be nice if we could have a single interface for all our data.



#### FEDERATED DATABASES

Distributed architecture that connects disparate DBMSs into a single logical system.

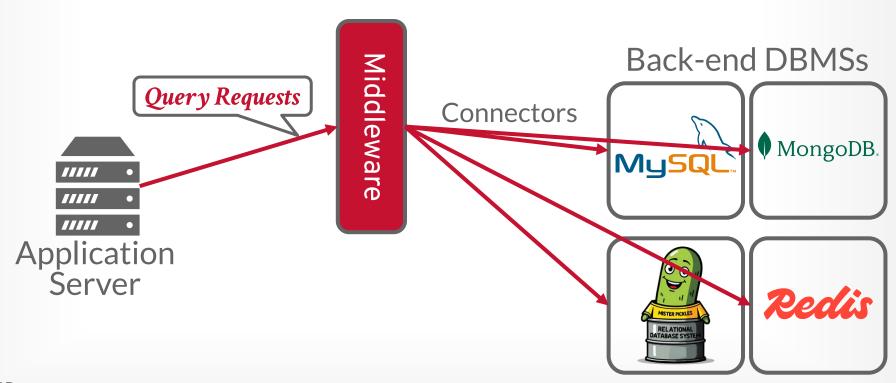
→ Expose a single query interface that can access data at any location.

This is hard and nobody does it well

- → Different data models, query languages, limitations.
- → No easy way to optimize queries
- → Lots of data copying (bad).



#### FEDERATED DATABASE EXAMPLE





### DISTRIBUTED CONCURRENCY CONTROL

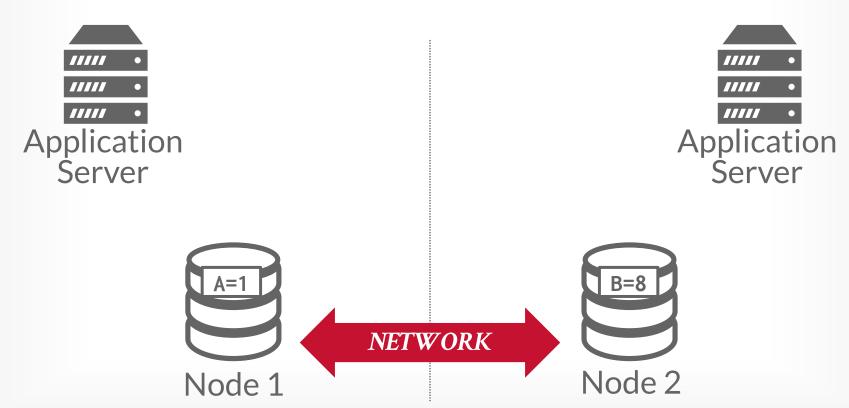
Need to allow multiple txns to execute simultaneously across multiple nodes.

→ Many of the same protocols from single-node DBMSs can be adapted.

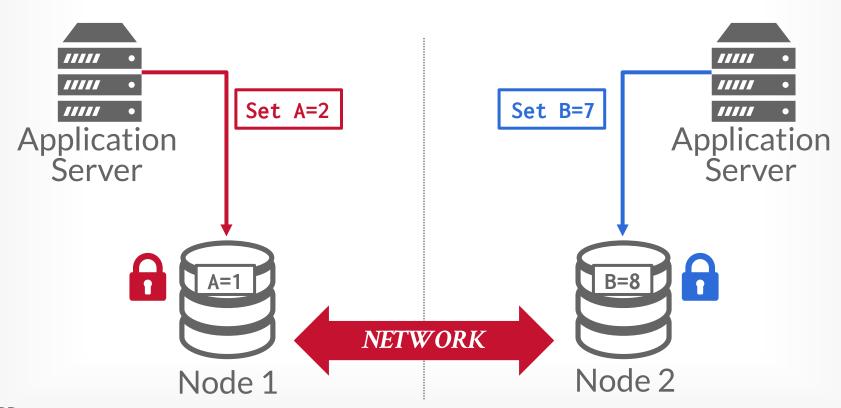
#### This is harder because of:

- $\rightarrow$  Replication.
- → Network Communication Overhead.
- → Node Failures (Permanent + Ephemeral).
- $\rightarrow$  Clock Skew.

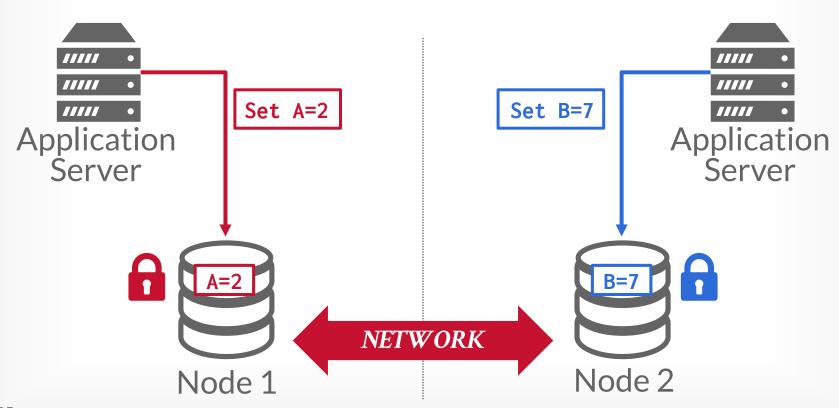




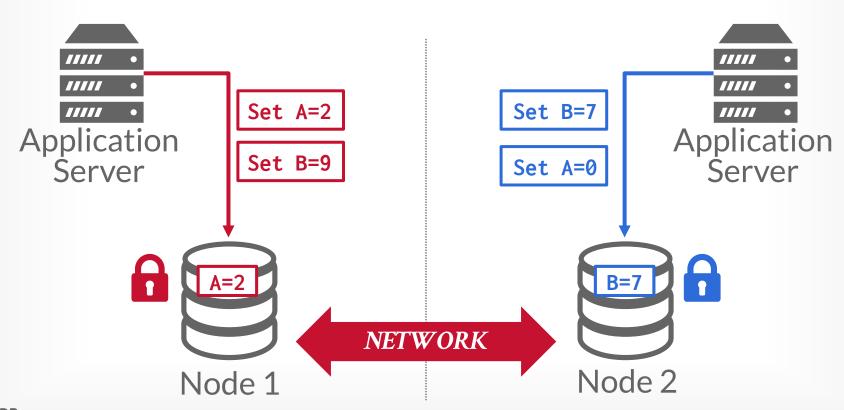




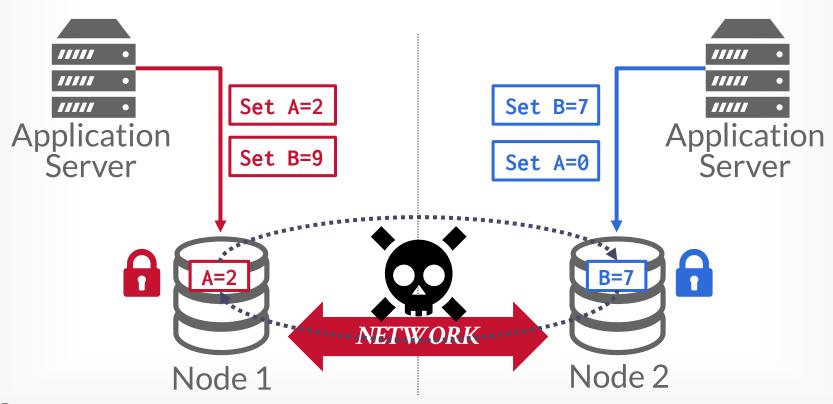




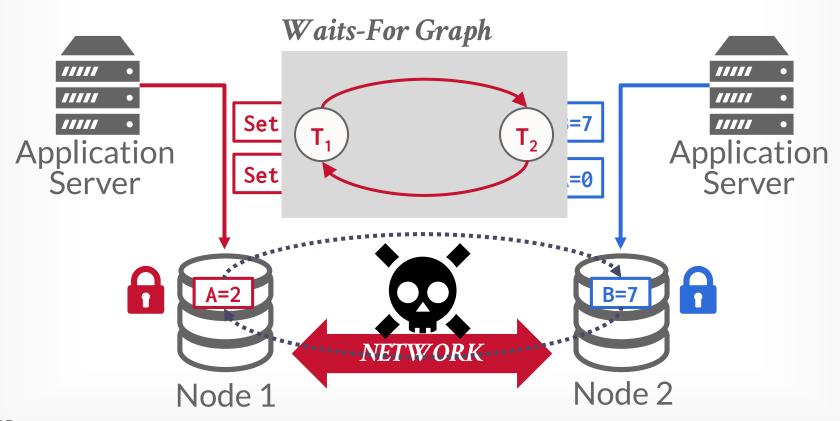














#### CONCLUSION

We have barely scratched the surface on distributed database systems...

It is **hard** to get this right.



### **NEXT CLASS**

Distributed OLTP Systems

Replication

**CAP** Theorem

Real-World Examples

