"object category": ["Description of the object type and general shape.

Grasping strategy.", ...]

```
reasoning templates = {
                ["The image shows a <u>baseball</u>, which is spherical. Grasping it
"baseball":
                 as its center will ensure optimal balance.",
                 "The object is a <u>baseball</u>. Its round shape requires a <u>center</u>
                 grip for stability.", ...],
"cup":
                ["The object is a <u>cup</u>, which is generally cylindrical. An secure
                 way to grasp a cup is by its edge from the top and the rotation
                 angle should be such that the gripper is orthogonal to the
                 edge of the cup.",
                 "Recognized object is a <u>cup</u>. Its best grasped by targeting its
                 top edge, ensuring the gripper is perpendicular to its circular
                 opening.", ...],
"sunglasses": ["The object is a pair of sunglasses, with lenses and a frame.
                 Grasping the frame, away from the lenses, is safest.",
                 "Recognized sunglasses. It's essential to grasp its frame while
```

avoiding the delicate lenses.", ...],