

$$a) \quad C = \begin{bmatrix} X_{11} & 0 & \dots & 0 \\ 0 & X_{22} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & X_{NN} \end{bmatrix}, \quad Z = \begin{bmatrix} Z_{11} & Z_{12} & \dots & Z_{1N} \\ Z_{21} & Z_{22} & \dots & Z_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ Z_{N1} & Z_{N2} & \dots & Z_{NN} \end{bmatrix}.$$

$$\cancel{Z^T C Z}.$$

$$Z^T C Z = \begin{bmatrix} Z_{11}^2 X_{11} & \dots & 0 \\ 0 & Z_{22}^2 X_{22} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & Z_{NN}^2 X_{NN} \end{bmatrix} Z.$$

$$= \begin{bmatrix} Z_{11}^2 X_{11} & \dots & 0 \\ 0 & Z_{22}^2 X_{22} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & Z_{NN}^2 X_{NN} \end{bmatrix}$$

"  ~~$X_{11} \dots X_{NN}$~~   $C$  is non-negative, thus  ~~$X_{11} \dots X_{NN} > 0$~~  for all  $N$ .

$$\forall N, X_{11} \dots X_{NN} > 0,$$

$$\text{Thus, } Z_{11}^2 X_{11} \dots Z_{NN}^2 X_{NN} > 0 \text{ for all } N.$$

" if  $C$  non negative,  $Z^T C Z \geq 0, \forall Z$ .

b) Conversely, as above

$$\text{If } \cancel{Z^T X_{11} \dots Z} \forall N, Z_{11}^2 X_{11} \dots Z_{NN}^2 X_{NN} > 0, X_{11} \dots X_{NN} > 0.$$

" it's also true.

c). For  $C = [1, 1]$ , eigenvalues are  $C_1 = 0, C_2 = 2$ . ~~Thus,~~

"  $C$  is non negative, thus  $g$  convex holds.

d). Say ~~the~~ eigenvalues here are  $e_1, \dots, e_N$ .

~~$C_1 \dots C_N$~~   $\forall N$ , we have here  ~~$C_1 \dots C_N$~~

$$C_{11}^2 \cdot e_1 + \lambda \dots C_{NN}^2 (e_N + \lambda).$$

~~if  $\lambda$  is large enough to~~

" if  ~~$C_1 \dots C_N$~~   $\forall N, e_N \leq \lambda$ , it would be positive.

Thus,  $\lambda$  should be the ~~smaller~~ <sup>absolute</sup> value of the largest eigenvalue of  $C$ .

a)  $N \times 1$  vector  $x$ ,  $N \times N$  outer prod  $xx^T$  has all nonneg cv.

$$z^T xx^T z = (x^T z)^2 > 0. \text{ thus also non-negative for all eigenvalue } \overset{\text{for}}{xx^T}.$$

b)  $\sum_{p=1}^P \delta_p x_p x_p^T.$

$$z^T \left( \sum_{p=1}^P \delta_p x_p x_p^T \right) z = \sum_{p=1}^P \delta_p (x_p^T z)^2. \text{ is non-negative } \text{for all } z.$$

c)  $\sum_{p=1}^P \delta_p x_p x_p^T + \lambda I_{N \times N}$  where each  $\delta_p > 0$  &  $\lambda > 0$ . + ev.

$$= \sum_{p=1}^P \delta_p x_p x_p^T + \lambda I_{N \times N}$$

Thus all eigenvalues must be  $\geq \lambda$  since  $\lambda > 0$ , then eigenvalues  $> 0$ .

a)  $g(w) = \log(1 + e^{w^T w})$  stationary point.

$$g'(w) = \frac{2e^{w^T w}}{1 + e^{w^T w}} \cdot w = 0.$$

Since  $\frac{2e^{w^T w}}{1 + e^{w^T w}}$  must  $> 1$ , thus  $w = 0$ .

b)  $\nabla^2 g(w) = \frac{4e^{w^T w}}{(1 + e^{w^T w})^2} w w^T + \frac{2e^{w^T w}}{1 + e^{w^T w}} I_{N \times N}.$

$$\begin{aligned} z^T \nabla^2 g(w) z &= \frac{4e^{w^T w}}{(1 + e^{w^T w})^2} z^T w w^T z + \frac{2e^{w^T w}}{1 + e^{w^T w}} z^T z \\ &= \underbrace{\frac{4e^{w^T w}}{(1 + e^{w^T w})^2}}_{> 0} \underbrace{(z^T w)^2}_{> 0} + \underbrace{\frac{2e^{w^T w}}{1 + e^{w^T w}}}_{> 0} \underbrace{\|z\|_2^2}_{> 0}. \end{aligned}$$

$\therefore z^T \nabla^2 g(w) z > 0$  for all  $w$  &  $z$ .

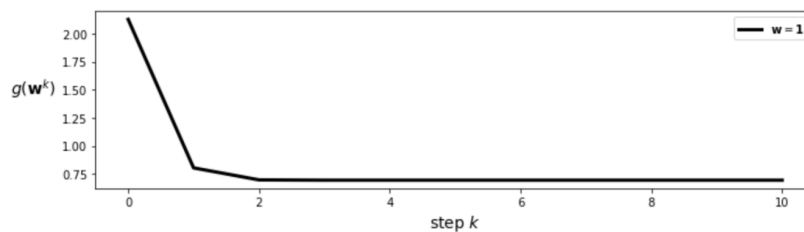
$\therefore g$  convex.



```
def newtons_method(g,maxx,w,**args):
    gradient = grad(g)
    h = hessian(g)
    e = 10**(-10)
    if 'epsilon' in args:
        e = args['epsilon']
    wh = [w]
    ch = [g(w)]
    for k in range(maxx):
        grade = gradient(w)
        he = h(w)
        he.shape = (int((np.size(he))*(0.5)),int((np.size(he))*(0.5)))
        a = he + e*np.eye(w.size)
        b = grade
        w = np.linalg.solve(a,np.dot(a,w) - b)
        wh.append(w)
        ch.append(g(w))
    return wh,ch
```

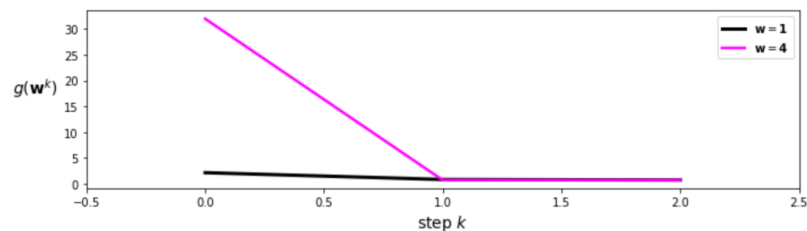
```
In [41]: g = lambda w: np.log(1 + np.exp(np.dot(w.T,w)))
w = np.ones((2,)); maxx = 10;
wh,ch = newtons_method(g,maxx,w)
static_plotter.plot_cost_histories([ch],start = 0,points = False,labels= [r'\mathbf{w}=\mathbf{1}$'])
```

```
In [41]: g = lambda w: np.log(1 + np.exp(np.dot(w.T,w)))
w = np.ones((2,)); maxx = 10;
wh,ch = newtons_method(g,maxx,w)
static_plotter.plot_cost_histories([ch],start = 0,points = False,labels= [r'\mathbf{w}=\mathbf{1}$'])
```



D

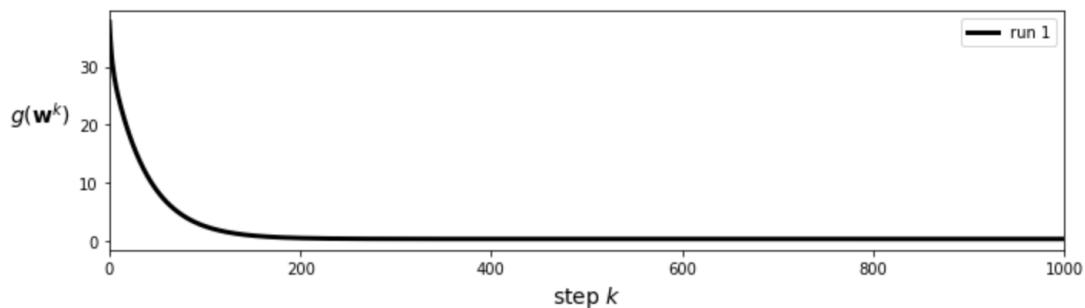
```
In [42]: w = np.ones((2,)); maxx = 2;
wh,ch = newtons_method(g,maxx,w)
w = 4*np.ones((2,)); maxx = 2;
wh2,ch2 = newtons_method(g,maxx,w)
static_plotter.plot_cost_histories([ch,ch2],start = 0,points= False,
labels = [r'\mathbf{w}=\mathbf{1}$',r'\mathbf{w}=\mathbf{4}$'])
```



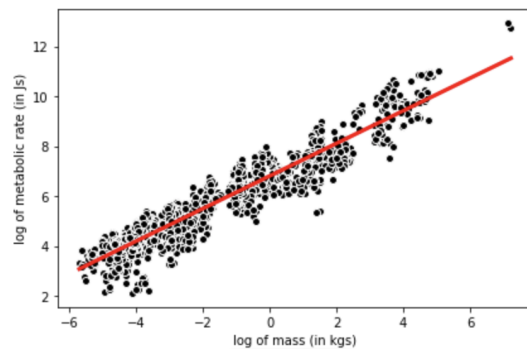
## 5.2

```
In [71]: csvname = 'mlrefined_exercises/ed_2/mlrefined_datasets/superlearn_datasets/kleibers_law_data.csv'
data = np.loadtxt(csvname,delimiter=',')
x = data[:,1:]
y = data[:,2:]
x = np.log(x)
y = np.log(y)

def new_gradient_descent(g,a,maxx,w):
    gradient = grad(g)
    wh = [w]
    ch = [g(w)]
    for k in range(maxx):
        grade = gradient(w)
        w = w - a*grade
        wh.append(w)
        ch.append(g(w))
    return wh,ch
def model(x,w):
    a = w[0] + np.dot(x.T,w[1:])
    return a.T
def least(w):
    cost = np.sum((model(x,w) - y)**2)
    return cost/float(np.size(y))
g = least
w = 0.1*np.random.randn(2,1)
maxx = 1000
a = 10*(-2)
wh, ch = new_gradient_descent(g,a,maxx,w)
static_plotter.plot_cost_histories([ch],start = 0,points = False,labels= ['run 1'])
```



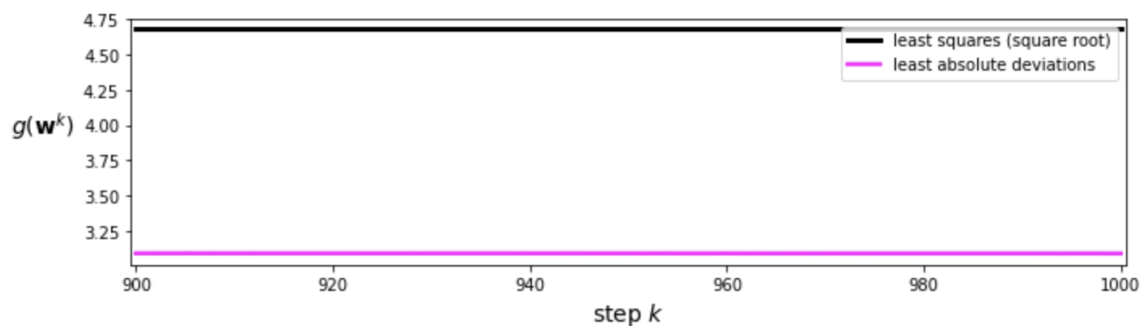
```
In [73]: s = np.linspace(np.min(x),np.max(x))
w = wh[-1]
t = w[0] + w[1]*s
figure = plt.figure()
plt.plot(s,t,linewidth = 3,color = 'r')
plt.scatter(x,y,linewidth = 1,c='k',edgecolor='w')
plt.xlabel('log of mass (in kgs)')
plt.ylabel('log of metabolic rate (in Js)')
plt.show()
```



## 5.9

```
In [74]: def normalize(x):
xmeans = np.nanmean(x,axis = 1)[:,np.newaxis]
xstds = np.nanstd(x,axis = 1)[:,np.newaxis]
ind = np.argwhere(xstds < 10*(-2))
if len(ind) > 0:
    ind = [v[0] for v in ind]
    ad = np.zeros((xstds.shape))
    ad[ind] = 1.0
    xstds += ad
ind = np.argwhere(np.isnan(x) == True)
for i in ind:
    x[i[0],i[1]] = xmeans[i[0]]
return lambda data: (data - xmeans)/xstds, lambda data: data*xstds + xmeans
```

```
In [82]: csvname = 'mlrefined_exercises/ed_2/mlrefined_datasets/superlearn_datasets/boston_housing.csv'
data = np.loadtxt(csvname,delimiter=',')
x = data[:-1,:]
y = data[-1,:]
norm,inverse_norm = normalize(x)
x = norm(x)
def model(x,w):
    a = w[0] + np.dot(x.T,w[1:])
    return a.T
def ls(w):
    cost = np.sum((model(x,w) - y)**2)
    return cost/float(np.size(y))
def lad(w):
    cost = np.sum(np.abs(model(x,w) - y))
    return cost/float(np.size(y))
g = ls
w = 0.1*np.random.randn(x.shape[0]+1,1)
maxx = 1000
a = 10*(-1)
wh1,ch1 = optimizers.gradient_descent(g,alpha_choice,max_its,w)
ch1 = [c**(0.5) for c in ch1]
g = lad
wh2,ch2 = optimizers.gradient_descent(g,a,maxx,w)
static_plotter.plot_cost_histories([ch1,ch2],start = 900,points = False,
    labels = ['least squares (square root)', 'least absolute deviations'])
```



```

In [83]: csvname = 'mlrefined_exercises/ed_2/mlrefined_datasets/superlearn_datasets/auto_data.csv'
data = np.loadtxt(csvname,delimiter=',')
x = data[:,1:]
y = data[:,0]
norm,inverse_norm = normalize(x)
x = norm(x)
g = ls;
w = 0.1*np.random.randn(x.shape[0]+1,1);
maxx = 1000;
a = 10*(-1);
wh1,ch1 = optimizers.gradient_descent(g,a,maxx,w)
ch1 = [c*(0.5) for c in ch1]
g = lad;
wh2,ch2 = optimizers.gradient_descent(g,alpha_choice,max_its,w)
static_plotter.plot_cost_histories([ch1,ch2],start = 900,points = False,
                                   labels = ['least squares (square root)', 'least absolute deviations'])

```

