

7. Paths and Curves, Cylindrical and Spherical Coordinate Systems

In this lecture, we will discuss

- Paths and Curves \mathbb{R}^2 and \mathbb{R}^3
- Cylindrical Coordinate Systems
- Spherical Coordinate Systems

Paths and Curves \mathbb{R}^2 and \mathbb{R}^3

Definition Path and Curve

A path in \mathbb{R}^3 (or \mathbb{R}^2) is a function $\mathbf{c} : [a, b] \rightarrow \mathbb{R}^3$ (or \mathbb{R}^2), whose domain is a subset $[a, b] \subseteq \mathbb{R}$. The image of \mathbf{c} is called a curve in \mathbb{R}^3 (or \mathbb{R}^2). The function \mathbf{c} is also known as a parametrization (or parametric representation or parametric equation) of the curve.

Definition Orientation

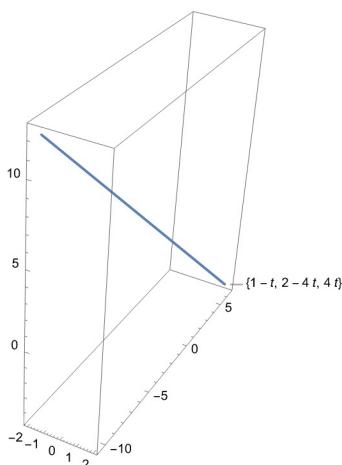
Let $\mathbf{c}(t) : [a, b] \rightarrow \mathbb{R}^3$ (or \mathbb{R}^2) be a path. The point $\mathbf{c}(a)$ is called the *initial point*, and we call $\mathbf{c}(b)$ the *terminal point* of \mathbf{c} . The initial and the terminal points are called the *endpoints* of \mathbf{c} . The direction corresponding to increasing values of t gives the positive orientation, whereas the *opposite direction* defines the *negative orientation* of \mathbf{c} .

• Parametric Representation of a Line and a Line Segment

Recall in **Lecture 1 Exercise 5**, the parametric equations of the line ℓ in \mathbb{R}^3 that contains a point $A = (1, 2, 0)$ and with direction of a vector $\mathbf{v} = (-1, -4, 4)$ is

$$\mathbf{r}(t) = \mathbf{a} + t\mathbf{v} = (1 - t, 2 - 4t, 4t), \quad t \in \mathbb{R}.$$

Taking $t \in [-1, 3]$, we get a line segment.



Example 1. (Related to WebWork Q4)

Find the point of intersection of the two lines L_1 and L_2 , where $L_1 = (5 + t, 1 - t, 8 - 3t)$ and $L_2 = (1 + 2s, -4 + s, 8 - 2s)$.

ANS. To find the point of intersection of L_1 and L_2 , we must find a point P that lies on both lines.

This means if the lines intersect, we must have

$$\begin{cases} 5+t = 1+2s \Rightarrow 4=2s-t \quad \textcircled{1} \\ 1-t = -4+s \Rightarrow 5=s+t \quad \textcircled{2} \\ 8-3t = 8-2s \Rightarrow 0=3t-2s \end{cases}$$

$$\textcircled{1} + \textcircled{2} \Rightarrow 9=3s \Rightarrow s=3$$

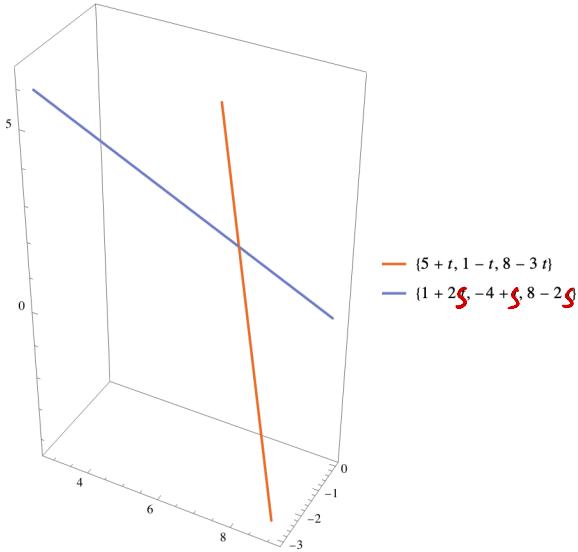
Plug $s=3$ into $\textcircled{2}$, we get $t=2$.

To find the point of intersection P , we just substitute $\begin{cases} s=3 \\ t=2 \end{cases}$ into either L_1 or L_2 .

For L_1 , we get

$$L_1 = (5+t, 1-t, 8-3t) = (7, -1, 2)$$

To double check the answer, we plug $s=3$ into $L_2 = (1+2s, -4+s, 8-2s) = (7, -1, 2)$ as expected.



- **Parameterization of a Circle and an Ellipse**

- The curve represented parametrically as

$$\mathbf{c}(t) = (r \cos t, r \sin t), \quad t \in [0, 2\pi]$$

(where $r > 0$) is the circle in \mathbb{R}^2 of radius r centered at the origin.

Generally,

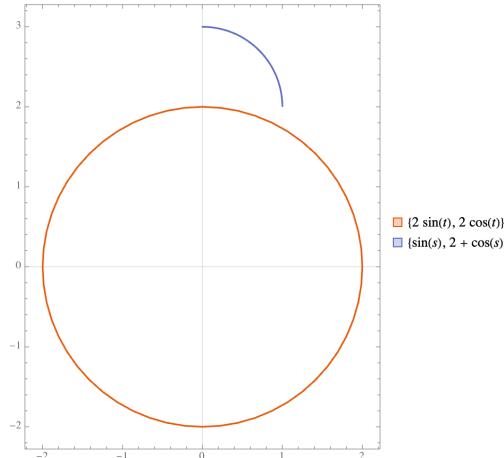
$$\mathbf{c}(t) = (x_0 + r \cos t, y_0 + r \sin t), \quad t \in [0, 2\pi]$$

is a parametric equations of circle of radius r centered at $C = (x_0, y_0)$.

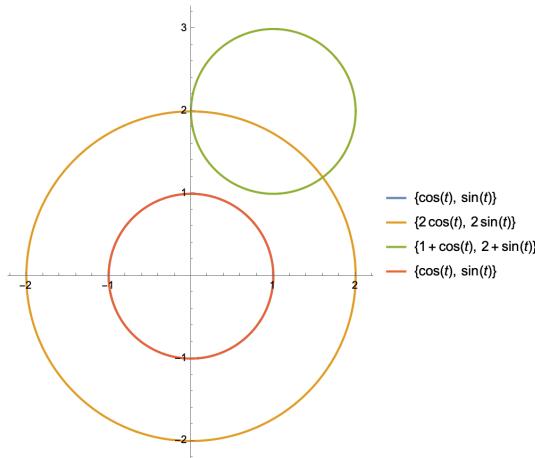
Below is the graph of two parametric equations.

The orange one is obtained by $(2 \cos t, 2 \sin t)$, $t \in [0, 2\pi]$.

The blue one is by $(\sin s, 2 + \cos s)$, $s \in [0, \pi/2]$. Notice that it is an arc of the circle centered at $(0, 2)$ with radius 1 with an angle range from 0 to $\pi/2$.

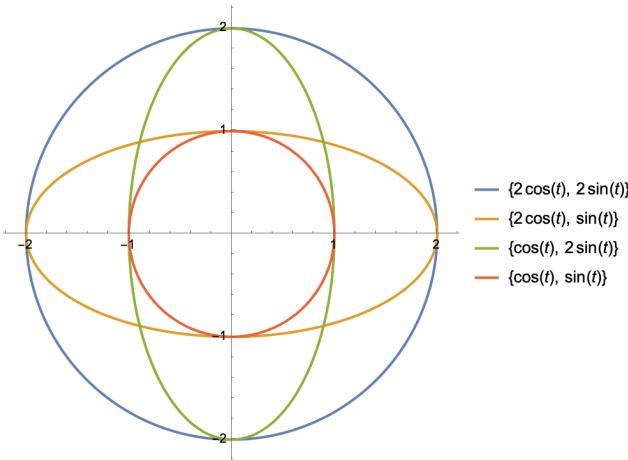


The following graph is an example of several circles with their corresponding parametric equations.



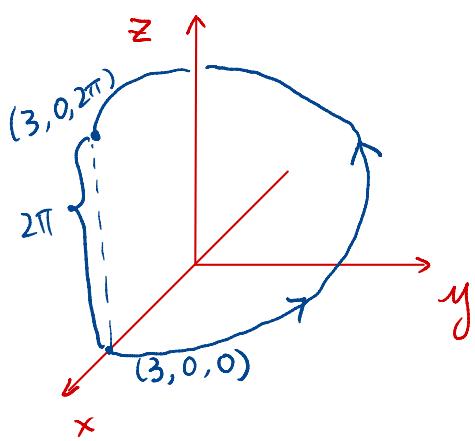
- The ellipse $x^2/a^2 + y^2/b^2 = 1$ (with semiaxes $a, b > 0$) can be parametrized as $c(t) = (a \cos t, b \sin t)$, $t \in [0, 2\pi]$.

The following graph is an example of taking different values of a and b .



Example 2. (Related to WebWork Q2)

Sketch the curve $\mathbf{c}(t) = (3 \cos t, 3 \sin t, t)$, $t \in [0, 2\pi]$.



ANS:- $x = 3 \cos t, y = 3 \sin t$
 implies $x^2 + y^2 = 9$, therefore
 the curve lies on the surface
 of the cylinder of radius 3.

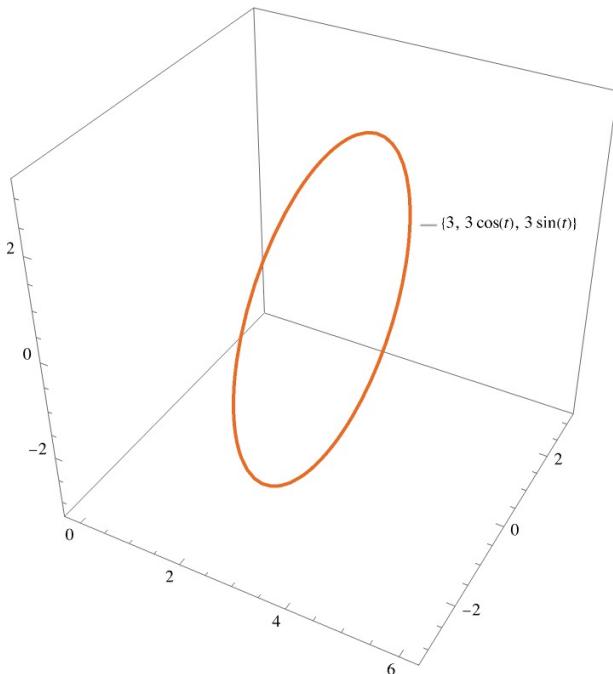
- Its projection onto the
 xy-plane (take $z=0$) is
 the circle of radius 3 oriented
 counter clockwise.

- As t increases, z coordinate
 will increase from 0 to 2π ,
 The initial point is $(3, 0, 0)$
 and the terminal point is
 $(3, 0, 2\pi)$.

Example 3. (Related to WebWork Q3)

The function $\mathbf{r}(t)$ traces a circle. Determine the radius, center, and plane containing the circle

$$\mathbf{r}(t) = 3\mathbf{i} + (3 \cos(t))\mathbf{j} + (3 \sin(t))\mathbf{k}$$



ANS; We have

$$x(t) = 3, y(t) = 3 \cos t, z(t) = 3 \sin t.$$

Thus

$$\begin{aligned}y^2 + z^2 &= 3^2 \cos^2 t + 3^2 \sin^2 t \\&= 3^2\end{aligned}$$

This is the equation of a circle
in the vertical plane $x=3$.

The circle is centered at
 $(3, 0, 0)$ and the radius is 3.

Cylindrical Coordinate Systems

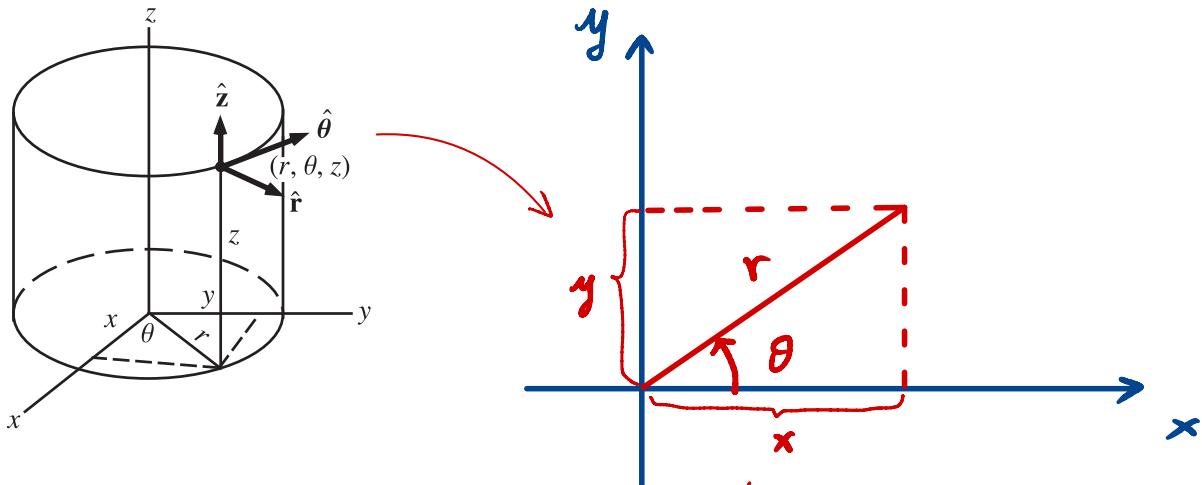
There are many ways of representing points in \mathbb{R}^3 other than using the Cartesian coordinates x, y , and z . Two commonly used sets of coordinates (e.g., in integration) are cylindrical and spherical coordinates.

Definition Cylindrical Coordinates r, θ, z

The cylindrical coordinates r, θ, z are related to Cartesian coordinates by

$$x = r \cos \theta, \quad y = r \sin \theta, \quad z = z,$$

where $0 \leq \theta < 2\pi$, and $r \geq 0$.



Note $\tan \theta = \frac{y}{x}$

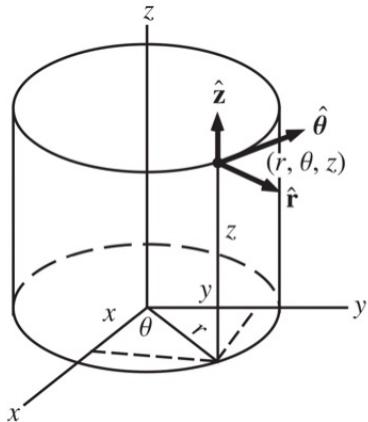
As $-\frac{\pi}{2} < \arctan \theta < \frac{\pi}{2}$, but we need $0 \leq \theta \leq 2\pi$, thus we have the formula computing θ in the table below.

From Cylindrical to Cartesian	From Cartesian to Cylindrical
$x = r \cos \theta$ $y = r \sin \theta$ $z = z$	$r = \sqrt{x^2 + y^2}$ $\theta = \begin{cases} \arctan(y/x) & \text{if } x > 0 \text{ and } y \geq 0 \\ \arctan(y/x) + \pi & \text{if } x < 0 \\ \arctan(y/x) + 2\pi & \text{if } x > 0 \text{ and } y < 0 \end{cases}$ $z = z$

Example 4. (Related to WebWork Q7)

Convert the following point from Cartesian (rectangular) to cylindrical coordinates:

$$(x, y, z) = (\sqrt{3}, -1, -5).$$



ANS: We are given

$$(x, y, z) = (\sqrt{3}, -1, -5)$$

$$\begin{aligned} r &= \sqrt{x^2 + y^2} = \sqrt{(\sqrt{3})^2 + (-1)^2} \\ &= \underline{\underline{2}} \end{aligned}$$

We know

$$\tan \theta = \frac{y}{x} = \frac{-1}{\sqrt{3}}$$

$$\arctan \theta = -\frac{\pi}{6}$$

Since $(x, y) = (\sqrt{3}, -1)$ lies on the fourth quadrant, $\frac{3\pi}{2} \leq \theta < 2\pi$. Thus

$$\underline{\underline{\theta = 2\pi + \arctan \theta = \frac{11\pi}{6}}}$$

$$\underline{\underline{z = -5}}$$

Exercise 5. (Related to WebWork Q10)

Convert the following point from cylindrical to Cartesian (rectangular) coordinates:

$$(r, \theta, z) = (3, \pi, -9.5).$$

Solution. We have $r = 3$, $\theta = \pi$, and $z = -9.5$. Thus,

$$x = r \cdot \cos(\theta) = 3 \cdot -1 = -3$$

$$y = r \cdot \sin(\theta) = 3 \cdot 0 = 0$$

$$z = -9.5$$

Spherical Coordinate Systems

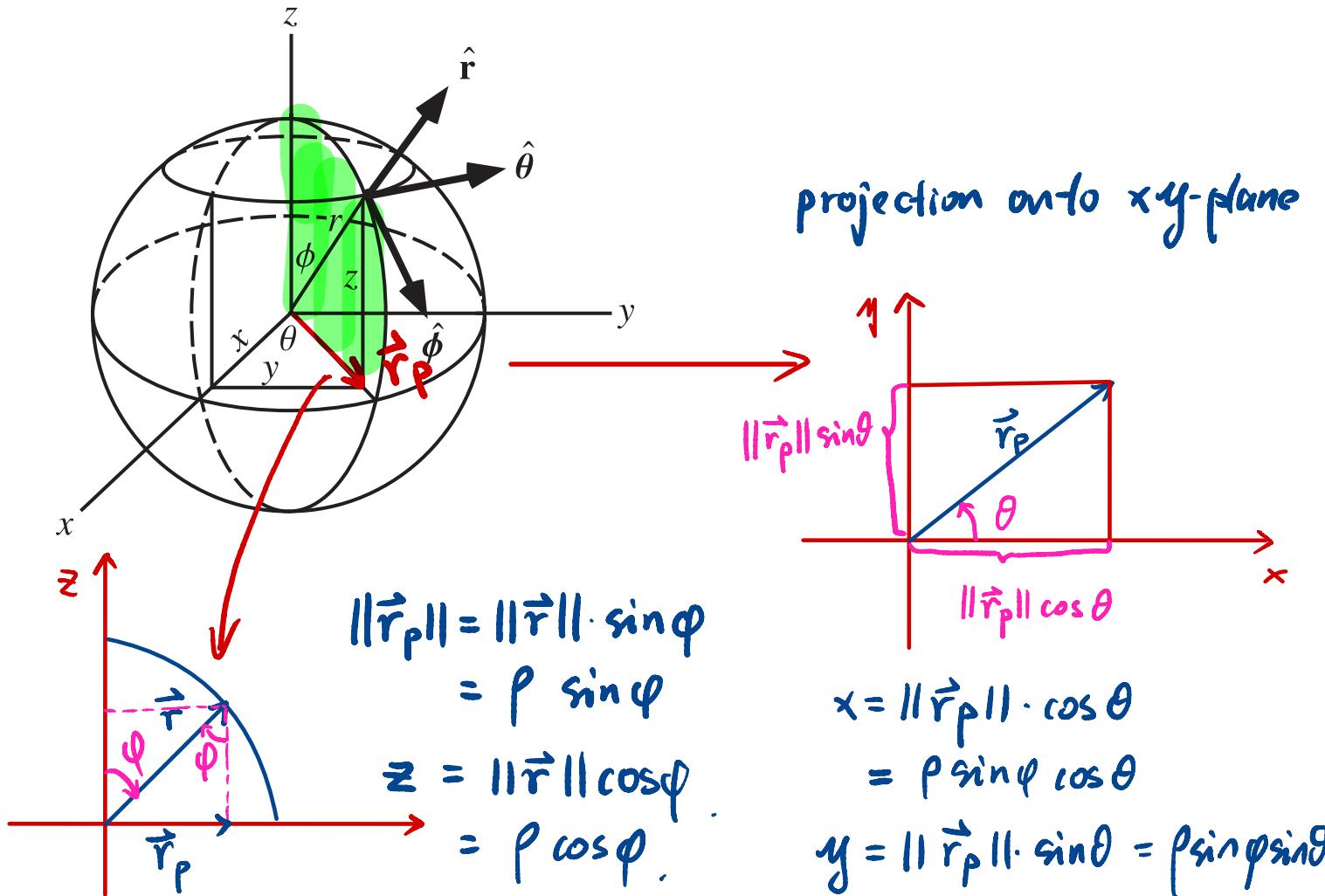
Definition Spherical Coordinates ρ, θ, ϕ

The point $(x, y, z) \in \mathbb{R}^3$ is represented in *spherical coordinates* using the following data:

(a) Distance $\rho = \|\mathbf{r}\| = \sqrt{x^2 + y^2 + z^2} \geq 0$ from the origin.

(b) Angle $\theta(0 \leq \theta < 2\pi)$ in the xy -plane (measured counterclockwise) between the x -axis and the projection \mathbf{r}_p of the position vector $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ onto the xy -plane.

(c) Angle ϕ (in the plane containing the z -axis and the position vector \mathbf{r} , measured from the positive direction of the z -axis), $0 \leq \phi \leq \pi$. If a point lies on the z -axis, then $\phi = 0$ if $z \geq 0$ and $\phi = \pi$ if $z < 0$.

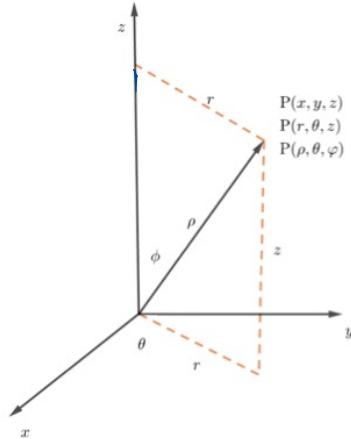


From Spherical to Cartesian	From Cartesian to Spherical
$x = \ \mathbf{r}_p\ \cos \theta = \rho \sin \phi \cos \theta$ $y = \ \mathbf{r}_p\ \sin \theta = \rho \sin \phi \sin \theta$ $z = \rho \cos \phi$.	$\rho = \sqrt{x^2 + y^2 + z^2}$ $\theta = \begin{cases} \arctan(y/x) & \text{if } x > 0 \text{ and } y \geq 0 \\ \arctan(y/x) + \pi & \text{if } x < 0 \\ \arctan(y/x) + 2\pi & \text{if } x > 0 \text{ and } y < 0 \end{cases}$ $\phi = \arccos(z/\rho)$.

Example 6. (Related to WebWork Q8)

Convert the following point from Cartesian (rectangular) to spherical coordinates:

$$(x, y, z) = \left(\frac{-5\sqrt{6}}{4}, \frac{-5\sqrt{2}}{4}, \frac{5\sqrt{2}}{2} \right).$$



Solution: We suggest to draw down the diagram on the left for this type of questions so that you can derive the formulae yourself

To find $P(\rho, \theta, \varphi)$, we have

$$\rho = \sqrt{x^2 + y^2 + z^2} = \sqrt{\frac{25 \times 6}{16} + \frac{25 \times 2}{16} + \frac{25 \times 2}{4}}$$

$$= \sqrt{\frac{25(6+2+8)}{16}} = 5$$

$$\tan \theta = \frac{y}{x} = \sqrt{\frac{2}{6}} = \sqrt{\frac{1}{3}}$$

As $y < 0$, $x < 0$, θ lies in the 3rd quadrant, thus $\pi < \theta < \frac{3\pi}{2}$

$$\theta = \arctan \frac{1}{\sqrt{3}} + \pi = \frac{7\pi}{6}$$

$$\cos \varphi = \frac{z}{\rho} = \frac{\frac{5\sqrt{2}}{2}}{5} = \frac{\sqrt{2}}{2}, \quad 0 \leq \varphi \leq \pi$$

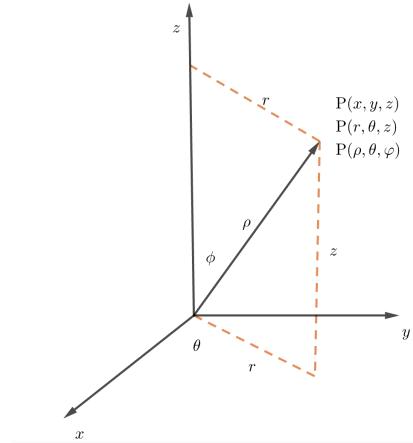
$$\Rightarrow \varphi = \arccos \frac{\sqrt{2}}{2} = \frac{\pi}{4},$$

Exercise 7. (Related to WebWork Q9)

Convert the following point from spherical to Cartesian (rectangular) coordinates:

$$(\rho, \theta, \phi) = \left(1, \frac{3\pi}{4}, \frac{5\pi}{3}\right).$$

Solution.



We are given that $\rho = 1$, $\theta = \frac{3\pi}{4}$, and $\phi = \frac{5\pi}{3}$. The relations between the spherical and rectangular coordinates imply

$$x = \rho \sin \phi \cos \theta = 1 \sin \frac{5\pi}{3} \cos \frac{3\pi}{4} = 1 \cdot \frac{-\sqrt{3}}{2} \cdot \frac{-\sqrt{2}}{2} = \frac{\sqrt{6}}{4}$$

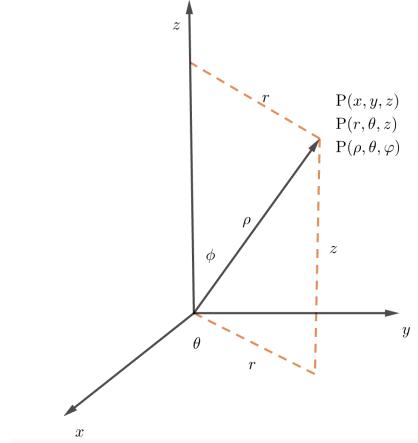
$$y = \rho \sin \phi \sin \theta = 1 \sin \frac{5\pi}{3} \sin \frac{3\pi}{4} = 1 \cdot \frac{-\sqrt{3}}{2} \cdot \frac{\sqrt{2}}{2} = -\frac{\sqrt{6}}{4}$$

$$z = \rho \cos \phi = 1 \cos \frac{5\pi}{3} = 1 \cdot \frac{1}{2} = \frac{1}{2}$$

Exercise 8. (Related to WebWork Q6)

What are the cylindrical coordinates of the point whose spherical coordinates are $(\rho, \theta, \phi) = \left(1, 1, \frac{5\pi}{6}\right)$?

Same as before, we can use right-triangle relationships to convert from one system to another.



From Spherical to Cylindrical	From Cylindrical to Spherical
$r = \rho \sin \phi$ $\theta = \theta$ $z = \rho \cos \phi$	$\rho = \sqrt{r^2 + z^2}$ $\theta = \theta$ $\phi = \arccos \left(\frac{z}{\sqrt{r^2 + z^2}} \right)$

Solution.

From Spherical to Cylindrical, we have

$$\begin{aligned} r &= \rho \sin \phi \\ \theta &= \theta \\ z &= \rho \cos \phi \end{aligned}$$

Thus

$$\begin{aligned} r &= 1 \cdot \sin \frac{5\pi}{6} = 0.5 \\ \theta &= 1 \\ z &= 1 \cdot \cos \frac{5\pi}{6} = -\frac{\sqrt{3}}{2} \approx -0.866025 \end{aligned}$$