

## 5.3 A Gallery of Solution Curves of Linear Systems

### Example 1

$$\begin{cases} x' = 6x - 7y = \frac{dx}{dt} \\ y' = x - 2y = \frac{dy}{dt} \end{cases} \quad (1)$$

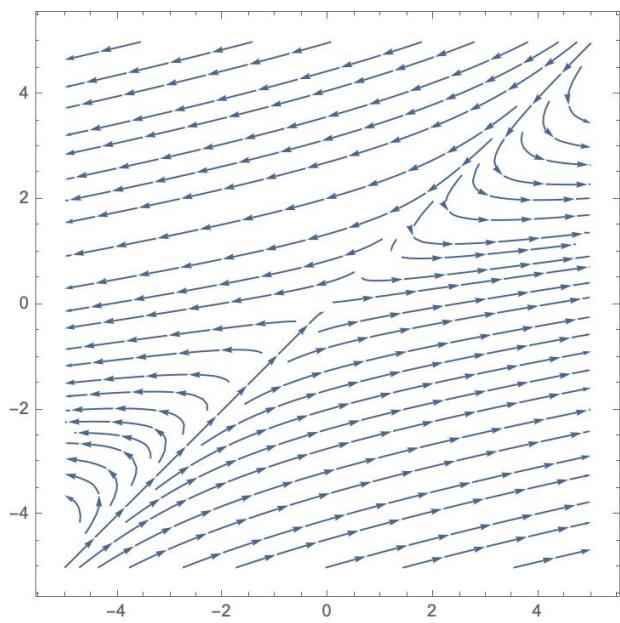
We have  $\mathbf{A} = \begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix}$ .

We have

**Eigenvalues:**  $\lambda_1 = 5, \lambda_2 = -1$ .

**Eigenvectors:**  $\mathbf{v}_1 = \begin{bmatrix} 7 \\ 1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

**Direction field:**



In Matlab, we use

```

1 | [x,y] = meshgrid(-3:0.3:3,-3:0.3:3);
2 | f1 = 6*x -7*y;
3 | f2 = x -2*y;
4 | quiver(x,y,f1,f2)

```

$$\frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{\frac{dy}{dx}}{\frac{dx}{dt}} = \frac{x-2y}{6x-7y}$$

At some point  $(x, y)$ , we can compute the slope of the line tangent to the solution curve

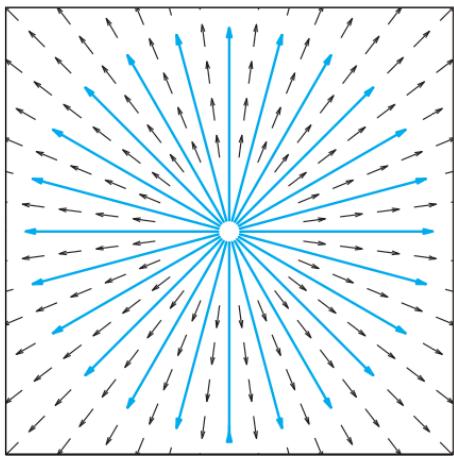
For example, if  $(x, y) = (1, 0)$ , then the slope

$$\frac{dy}{dx} = \frac{1-2 \cdot 0}{6 \cdot 1 - 7 \cdot 0} = \frac{1}{6}$$

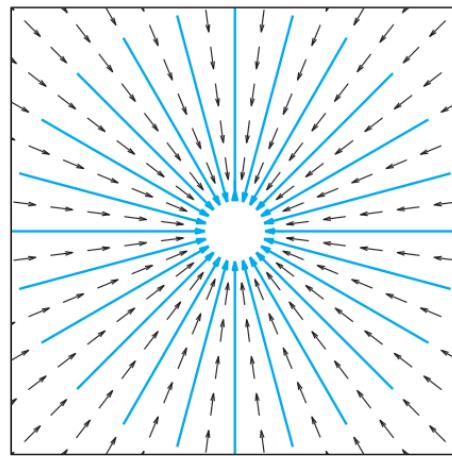
The general solution for this eqn is

$$\begin{bmatrix} x \\ y \end{bmatrix} = C_1 \begin{bmatrix} 7 \\ 1 \end{bmatrix} e^{5t} + C_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-t}$$

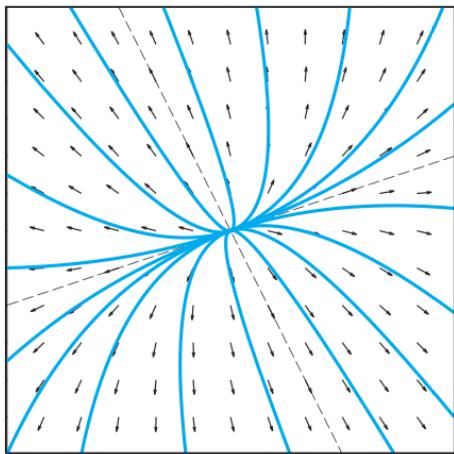
## Gallery of Typical Phase Portraits for the System $\mathbf{x}' = \mathbf{A}\mathbf{x}$ : Nodes



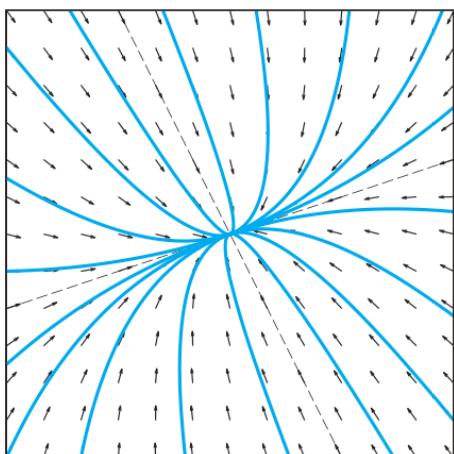
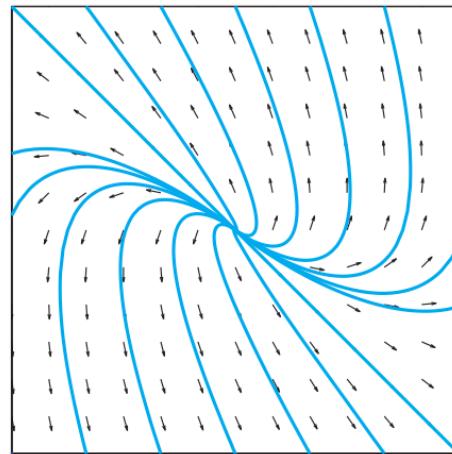
**Proper Nodal Source:** A repeated positive real eigenvalue with two linearly independent eigenvectors.



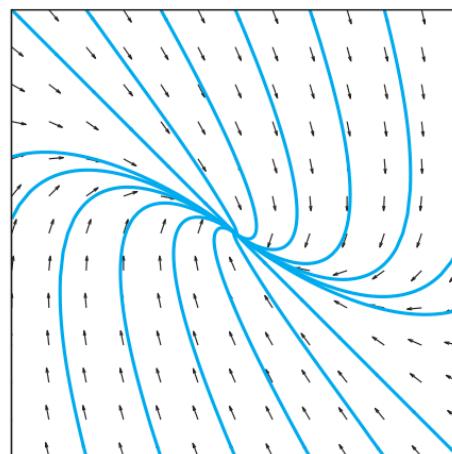
**Proper Nodal Sink:** A repeated negative real eigenvalue with two linearly independent eigenvectors.



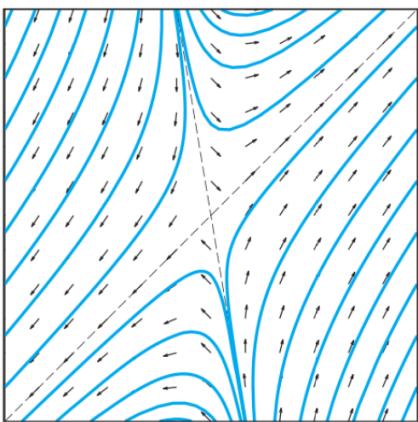
**Improper Nodal Source:** Distinct positive real eigenvalues (left) or a repeated positive real eigenvalue without two linearly independent eigenvectors (right).



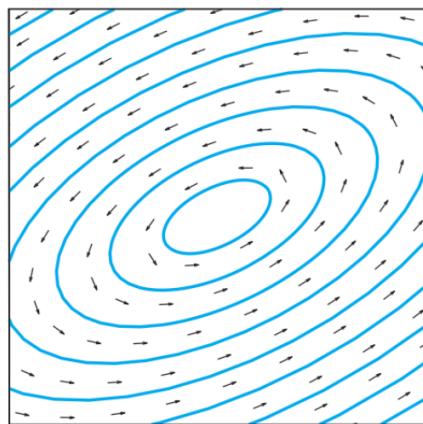
**Improper Nodal Sink:** Distinct negative real eigenvalues (left) or a repeated negative real eigenvalue without two linearly independent eigenvectors (right).



## Gallery of Typical Phase Portraits for the System $\mathbf{x}' = \mathbf{Ax}$ : Saddles, Centers, Spirals, and Parallel Lines



**Saddle Point:** Real eigenvalues of opposite sign.



**Center:** Pure imaginary eigenvalues.

Consider

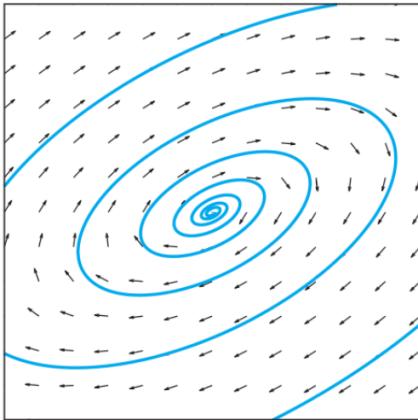
$$\begin{cases} x' = -2y \\ y' = \frac{1}{2}x \end{cases}$$

$$A = \begin{bmatrix} 0 & -2 \\ \frac{1}{2} & 0 \end{bmatrix}$$

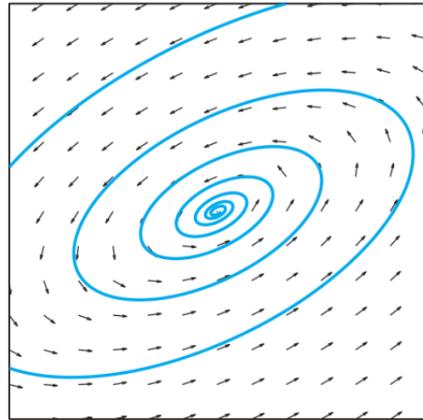
$$0 = |A - \lambda I| = \begin{vmatrix} \lambda & -2 \\ \frac{1}{2} & \lambda \end{vmatrix}$$

$$\Rightarrow \lambda^2 + 1 = 0$$

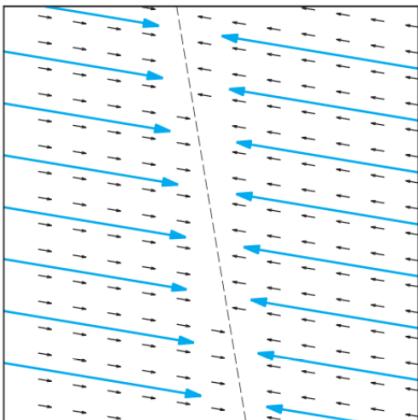
$$\lambda = \pm i$$



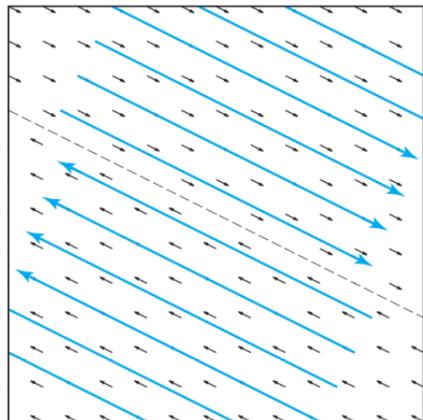
**Spiral Source:** Complex conjugate eigenvalues with positive real part.



**Spiral Sink:** Complex conjugate eigenvalues with negative real part.



**Parallel Lines:** One zero and one negative real eigenvalue. (If the nonzero eigenvalue is positive, then the trajectories flow *away* from the dotted line.)



**Parallel Lines:** A repeated zero eigenvalue without two linearly independent eigenvectors.

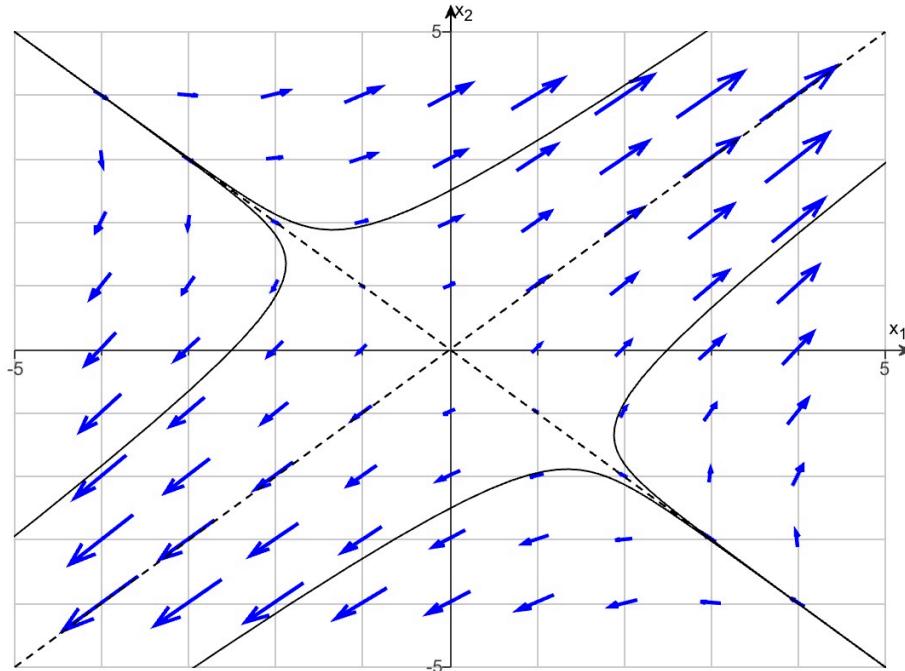
**Example 2** Categorize the eigenvalues and eigenvectors of the coefficient matrix  $\mathbf{A}$  according to the accompanying classifications and sketch the phase portrait of the system.

$$\mathbf{x}' = \begin{bmatrix} 5 & 7 \\ 7 & 5 \end{bmatrix} \mathbf{x} \quad (2)$$

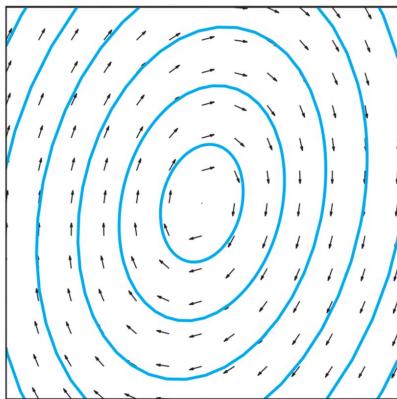
**Eigenvalues:**  $\lambda_1 = -2, \lambda_2 = 12$

**Eigenvectors:**  $\mathbf{v}_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$

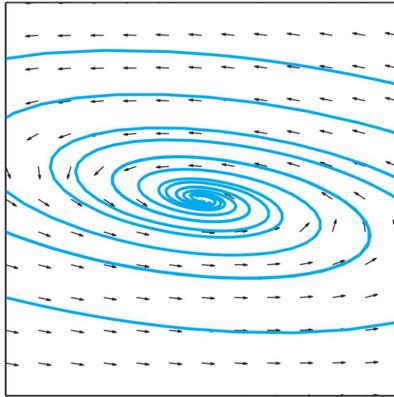
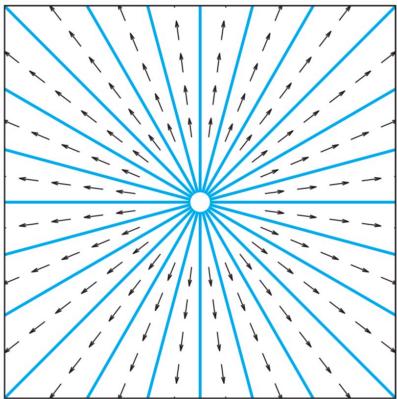
The system shows a saddle point and its eigenvalues are distinct, opposite sign real!



**Example 3** The phase portraits the following problems correspond to linear systems of the form  $\mathbf{x}' = \mathbf{Ax}$  in which the matrix  $\mathbf{A}$  has two linearly independent eigenvectors. Determine the nature of the eigenvalues and eigenvectors of each system.



Center  
pure imaginary eigenvalues



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Given

$$x' = \begin{pmatrix} 1 & \alpha \\ 3 & 1 \end{pmatrix} x \quad (3)$$

what are the values of  $\alpha$  if the origin is a saddle point in the phase plane?

- (A)  $\alpha > \frac{1}{3}$
- (B)  $\alpha < 0$
- (C)  $2 > \alpha > -2$
- (D)  $3 > \alpha > 1$
- (E)  $\alpha > \frac{1}{2}$

If the origin is a saddle point, then there are two real eigenvalues with opposite sign.

$$\textcircled{1} \quad 0 = |A - \lambda I| = \begin{vmatrix} 1-\lambda & \alpha \\ 3 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 - 3\alpha = \lambda^2 - 2\lambda + (1-3\alpha) = 0$$

$$(\lambda - \lambda_1)(\lambda - \lambda_2) = \lambda^2 - (\lambda_1 + \lambda_2)\lambda + \lambda_1\lambda_2$$

Let  $\lambda_1, \lambda_2$  be the eigenvalues of  $A$ . Then

•  $\textcircled{1}$  has two (distinct) real eigenvalues:

$$\Delta = b^2 - 4ac = (-2)^2 - 4(1-3\alpha) > 0$$

$$\Rightarrow 4 - 4 + 12\alpha > 0 \Rightarrow \alpha > 0$$

•  $\textcircled{1}$  has two solutions with opposite sign:

$$\lambda_1, \lambda_2 = 1-3\alpha < 0 \Rightarrow 1 < 3\alpha \Rightarrow \alpha > \frac{1}{3}$$

Thus we have

$$\left. \begin{array}{l} \alpha > 0 \\ \alpha > \frac{1}{3} \end{array} \right\} \Rightarrow \alpha > \frac{1}{3}$$