

Practices before the class (April 14)

- (T/F) If \mathbf{x} is not in a subspace W , then $\mathbf{x} - \text{proj}_W \mathbf{x}$ is not zero.
- (T/F) The general least-squares problem is to find an \mathbf{x} that makes $A\mathbf{x}$ as close as possible to \mathbf{b} .
- (T/F) If \mathbf{b} is in the column space of A , then every solution of $A\mathbf{x} = \mathbf{b}$ is a least-squares solution.
- (T/F) A least-squares solution of $A\mathbf{x} = \mathbf{b}$ is a vector $\hat{\mathbf{x}}$ that satisfies $A\hat{\mathbf{x}} = \hat{\mathbf{b}}$, where $\hat{\mathbf{b}}$ is the orthogonal projection of \mathbf{b} onto $\text{Col } A$.
- (T/F) Any solution of $A^T A\mathbf{x} = A^T \mathbf{b}$ is a least-squares solution of $A\mathbf{x} = \mathbf{b}$.

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- (T/F) If \mathbf{x} is not in a subspace W , then $\mathbf{x} - \text{proj}_W \mathbf{x}$ is not zero. True. If \mathbf{x} is not in a subspace W , then \mathbf{x} cannot equal $\text{proj}_W \mathbf{x}$, because $\text{proj}_W \mathbf{x}$ is in W .
- (T/F) The general least-squares problem is to find an \mathbf{x} that makes $A\mathbf{x}$ as close as possible to \mathbf{b} . True.
- (T/F) If \mathbf{b} is in the column space of A , then every solution of $A\mathbf{x} = \mathbf{b}$ is a least-squares solution. True. If \mathbf{b} is in the column space of A , then $\|\mathbf{b} - A\mathbf{x}\| = 0$ for \mathbf{x} satisfying the equation $A\mathbf{x} = \mathbf{b}$.
- (T/F) A least-squares solution of $A\mathbf{x} = \mathbf{b}$ is a vector $\hat{\mathbf{x}}$ that satisfies $A\hat{\mathbf{x}} = \hat{\mathbf{b}}$, where $\hat{\mathbf{b}}$ is the orthogonal projection of \mathbf{b} onto $\text{Col } A$. True. See the notes for § 6.5.
- (T/F) Any solution of $A^T A\mathbf{x} = A^T \mathbf{b}$ is a least-squares solution of $A\mathbf{x} = \mathbf{b}$. True. Check Theorem 13.

6.5 Least-Squares Problems

- Think of Ax as an approximation to \mathbf{b} . The smaller the distance between \mathbf{b} and Ax , given by $\|\mathbf{b} - Ax\|$, the better the approximation.
- The **general least-squares problem** is to find an \mathbf{x} that makes $\|\mathbf{b} - Ax\|$ as small as possible.
- The adjective "least-squares" arises from the fact that $\|\mathbf{b} - Ax\|$ is the square root of a sum of squares.

Definition. If A is $m \times n$ and \mathbf{b} is in \mathbb{R}^m , a **least-squares solution** of $Ax = \mathbf{b}$ is an $\hat{\mathbf{x}}$ in \mathbb{R}^n such that

$$\|\mathbf{b} - A\hat{\mathbf{x}}\| \leq \|\mathbf{b} - Ax\|$$

for all \mathbf{x} in \mathbb{R}^n .

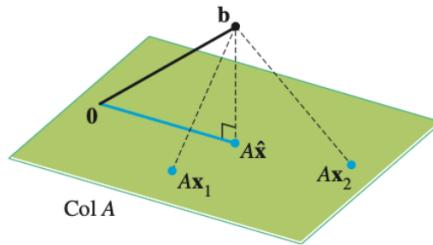


FIGURE 1 The vector \mathbf{b} is closer to $A\hat{\mathbf{x}}$ than to Ax for other \mathbf{x} .

Solution of the General Least-Squares Problem

The following steps help us to understand Theorem 13.

- Given A and \mathbf{b} as above, apply the Best Approximation Theorem in Section 6.3 to the subspace $\text{Col } A$. Let

$$\hat{\mathbf{b}} = \text{proj}_{\text{Col } A} \mathbf{b}$$

- Because $\hat{\mathbf{b}}$ is in the column space of A , the equation $Ax = \hat{\mathbf{b}}$ is consistent, and there is an $\hat{\mathbf{x}}$ in \mathbb{R}^n such that

$$A\hat{\mathbf{x}} = \hat{\mathbf{b}} \tag{1}$$

- Since $\hat{\mathbf{b}}$ is the closest point in $\text{Col } A$ to \mathbf{b} , a vector $\hat{\mathbf{x}}$ is a least-squares solution of $Ax = \mathbf{b}$ if and only if $\hat{\mathbf{x}}$ satisfies (1).
- Such an $\hat{\mathbf{x}}$ in \mathbb{R}^n is a list of weights that will build $\hat{\mathbf{b}}$ out of the columns of A .

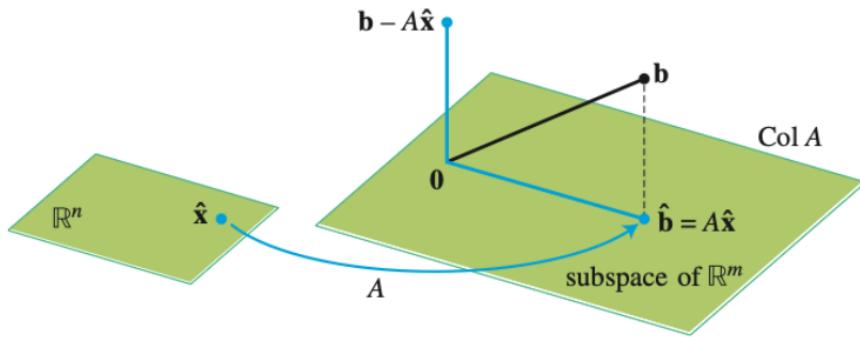


FIGURE 2 The least-squares solution $\hat{\mathbf{x}}$ is in \mathbb{R}^n .

- Suppose $\hat{\mathbf{x}}$ satisfies $A\hat{\mathbf{x}} = \hat{\mathbf{b}}$. By the **Orthogonal Decomposition Theorem** in Section 6.3, the projection $\hat{\mathbf{b}}$ has the property that $\mathbf{b} - \hat{\mathbf{b}}$ is orthogonal to $\text{Col } A$, so $\mathbf{b} - A\hat{\mathbf{x}}$ is orthogonal to each column of A .
- If \mathbf{a}_j is any column of A , then $\mathbf{a}_j \cdot (\mathbf{b} - A\hat{\mathbf{x}}) = 0$, and $\mathbf{a}_j^T(\mathbf{b} - A\hat{\mathbf{x}}) = 0$. Since each \mathbf{a}_j^T is a row of A^T ,

$$A^T(\mathbf{b} - A\hat{\mathbf{x}}) = \mathbf{0} \quad (2)$$

- Thus

$$A^T\mathbf{b} - A^TA\hat{\mathbf{x}} = \mathbf{0}$$

- These calculations show that each least-squares solution of $A\mathbf{x} = \mathbf{b}$ satisfies the equation

$$A^TA\mathbf{x} = A^T\mathbf{b} \quad (3)$$

The matrix equation (3) represents a system of equations called the **normal equations** for $A\mathbf{x} = \mathbf{b}$. A solution of (3) is often denoted by $\hat{\mathbf{x}}$.

Theorem 13 The set of least-squares solutions of $A\mathbf{x} = \mathbf{b}$ coincides with the nonempty set of solutions of the normal equations $A^TA\mathbf{x} = A^T\mathbf{b}$.

Example 1 Find a least-squares solution of $A\mathbf{x} = \mathbf{b}$ by

(a) constructing the normal equations for $\hat{\mathbf{x}}$ and

(b) solving for $\hat{\mathbf{x}}$.

$$A = \begin{bmatrix} 2 & 1 \\ -2 & 0 \\ 2 & 3 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} -5 \\ 8 \\ 1 \end{bmatrix}$$

ANS: (a) The normal equation for $\hat{\mathbf{x}}$ is

$$\mathbf{A}^T \mathbf{A} \hat{\mathbf{x}} = \mathbf{A}^T \mathbf{b}$$

We compute

$$\mathbf{A}^T \mathbf{A} = \begin{bmatrix} 2 & -2 & 2 \\ 1 & 0 & 3 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ -2 & 0 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 12 & 8 \\ 8 & 10 \end{bmatrix}$$

$$\mathbf{A}^T \mathbf{b} = \begin{bmatrix} 2 & -2 & 2 \\ 1 & 0 & 3 \end{bmatrix} \begin{bmatrix} -5 \\ 8 \\ 1 \end{bmatrix} = \begin{bmatrix} -24 \\ -2 \end{bmatrix}$$

Thus the normal equations are

$$\begin{bmatrix} 12 & 8 \\ 8 & 10 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -24 \\ -2 \end{bmatrix}$$

The augmented matrix

$$\begin{bmatrix} 12 & 8 & -24 \\ 8 & 10 & -2 \end{bmatrix} \sim \begin{bmatrix} 3 & 2 & -6 \\ 4 & 5 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 5 \\ 3 & 2 & -6 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 5 \\ 0 & -7 & -21 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & -4 \\ 0 & 1 & 3 \end{bmatrix}$$

Thus $\hat{\mathbf{x}} = \begin{bmatrix} -4 \\ 3 \end{bmatrix}$ is the least-square solution

Example 2 Describe all least-squares solutions of the equation $A\mathbf{x} = \mathbf{b}$.

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 1 \\ 3 \\ 8 \\ 2 \end{bmatrix}$$

ANS: The normal equations are $A^T A \vec{x} = A^T \vec{b}$, where

$$A^T A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 0 \\ 2 & 0 & 2 \end{bmatrix}$$

$$A^T \vec{b} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 8 \\ 2 \end{bmatrix} = \begin{bmatrix} 14 \\ 4 \\ 10 \end{bmatrix}$$

The augmented matrix

$$\left[\begin{array}{ccc|c} 4 & 2 & 2 & 14 \\ 2 & 2 & 0 & 4 \\ 2 & 0 & 2 & 10 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 5 \\ 0 & 1 & -1 & -3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Thus

$$\begin{cases} x_1 = 5 - x_3 \\ x_2 = -3 + x_3 \\ x_3 = x_3 \end{cases}$$

$$\hat{\vec{x}} = \begin{bmatrix} 5 \\ -3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \text{ are the least-squares solutions to } A\vec{x} = \vec{b}$$

Theorem 14 Let A be an $m \times n$ matrix. The following statements are logically equivalent:

- The equation $A\mathbf{x} = \mathbf{b}$ has a unique least-squares solution for each \mathbf{b} in \mathbb{R}^m .
- The columns of A are linearly independent.
- The matrix $A^T A$ is invertible.

When these statements are true, the least-squares solution $\hat{\mathbf{x}}$ is given by

$$\hat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b}$$

Alternative Calculations of Least-Squares Solutions

The next example shows how to find a least-squares solution of $A\mathbf{x} = \mathbf{b}$ when the columns of A are orthogonal.

Example 3 Find (a) the orthogonal projection of \mathbf{b} onto $\text{Col } A$ and (b) a least-squares solution of $A\mathbf{x} = \mathbf{b}$.

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \\ -1 & 1 & -1 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 2 \\ 5 \\ 6 \\ 6 \end{bmatrix}$$

ANS: Because the columns $\vec{a}_1, \vec{a}_2, \vec{a}_3$ for A are orthogonal,
the orthogonal projection of \vec{b} onto $\text{Col } A$ is

$$\begin{aligned} \hat{\mathbf{b}} = \text{proj}_{\text{Col } A} \vec{b} &= \frac{\langle \vec{b}, \vec{a}_1 \rangle}{\langle \vec{a}_1, \vec{a}_1 \rangle} \vec{a}_1 + \frac{\langle \vec{b}, \vec{a}_2 \rangle}{\langle \vec{a}_2, \vec{a}_2 \rangle} \vec{a}_2 + \frac{\langle \vec{b}, \vec{a}_3 \rangle}{\langle \vec{a}_3, \vec{a}_3 \rangle} \vec{a}_3 \\ &= \frac{1}{3} \vec{a}_1 + \frac{14}{3} \vec{a}_2 - \frac{5}{3} \vec{a}_3 \\ &= \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} + \frac{14}{3} \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix} - \frac{5}{3} \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix} \\ &= \begin{bmatrix} 5 \\ 2 \\ 3 \\ 6 \end{bmatrix} \end{aligned}$$

(b) We can solve

$$A\hat{\vec{x}} = \hat{\vec{b}}$$

to find the least squares solution

From the above equation

$$\hat{\vec{b}} = \frac{1}{3}\vec{a}_1 + \frac{14}{3}\vec{a}_2 - \frac{5}{3}\vec{a}_3$$

We know the solution $\hat{\vec{x}}$ is obtained from the weights:

$$\hat{\vec{x}} = \begin{bmatrix} 1/3 \\ 14/3 \\ -5/3 \end{bmatrix}$$

Theorem 15 Given an $m \times n$ matrix A with linearly independent columns, let $A = QR$ be a QR factorization of A as in Theorem 12. Then, for each \mathbf{b} in \mathbb{R}^m , the equation $A\mathbf{x} = \mathbf{b}$ has a unique least-squares solution, given by

$$\hat{\mathbf{x}} = R^{-1}Q^T\mathbf{b}$$

Example 4 Let $A = \begin{bmatrix} 2 & 1 \\ -3 & -4 \\ 3 & 2 \end{bmatrix}$, $\mathbf{b} = \begin{bmatrix} 5 \\ 4 \\ 4 \end{bmatrix}$, $\mathbf{u} = \begin{bmatrix} 4 \\ -5 \\ 4 \end{bmatrix}$, and $\mathbf{v} = \begin{bmatrix} 6 \\ -5 \\ -5 \end{bmatrix}$. Compute $A\mathbf{u}$ and $A\mathbf{v}$, and compare them with \mathbf{b} . Is it possible that at least one of \mathbf{u} or \mathbf{v} could be a least-squares solution of $A\mathbf{x} = \mathbf{b}$? (Answer this without computing a least-squares solution.)

ANS: $A\vec{u} = \begin{bmatrix} 2 & 1 \\ -3 & -4 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 4 \\ -5 \end{bmatrix} = \begin{bmatrix} 3 \\ 8 \\ 2 \end{bmatrix}$

$$\vec{b} - A\vec{u} = \begin{bmatrix} 5 \\ 4 \\ 4 \end{bmatrix} - \begin{bmatrix} 3 \\ 8 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ -4 \\ 2 \end{bmatrix} \text{ and } \|\vec{b} - A\vec{u}\| = \sqrt{24}$$

$$A\vec{v} = \begin{bmatrix} 2 & 1 \\ -3 & -4 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ -5 \end{bmatrix} = \begin{bmatrix} 7 \\ 2 \\ 8 \end{bmatrix}$$

$$\vec{b} - A\vec{v} = \begin{bmatrix} 5 \\ 4 \\ 4 \end{bmatrix} - \begin{bmatrix} 7 \\ 2 \\ 8 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \\ -4 \end{bmatrix} \text{ and } \|\vec{b} - A\vec{v}\| = \sqrt{24}$$

Notice that the columns of A are linearly independent
so $A\vec{x} = \vec{b}$ has a unique least-square solution by Thm 14.

Since $A\vec{u}$ and $A\vec{v}$ are equally close to \vec{b} , and the orthogonal projection is the unique closest point in $\text{Col}(A)$ to \vec{b} . Thus neither \vec{u} nor \vec{v} can be a least-squares solution to $A\vec{x} = \vec{b}$.