

or to the system of equations

$$\begin{aligned}\gamma \cdot \phi &= \varepsilon_1 \\ \gamma'_k \cdot \phi &= i\varepsilon_{2k}, \quad k = 1, \dots, d.\end{aligned}\tag{16}$$

### 3 Solutions to the convolution equations: identification and well-posedness

#### 3.1 Identification

For identification the supports of the functions in the equations play an important role.

Recall that for a continuous function  $\psi(x)$  on  $R^d$  support is defined as the set  $W = \text{supp}(\psi)$ , such that

$$\psi(x) = \begin{cases} a \neq 0 & \text{for } x \in W \\ 0 & \text{for } x \in R^d \setminus W. \end{cases}$$

Support of a continuous function is an open set.

Since generalized functions can be considered as functionals on the space  $S$  support of a generalized function  $b \in S^*$  is defined as follows (Schwartz, 1966, p. 28). Denote by  $(b, \psi)$  the value of the functional  $b$  for  $\psi \in S$ . Consider open sets  $W$  with the property that for any  $\psi \in S : \text{supp}(\psi) = W$  the value of the functional  $(b, \psi) = 0$ ; then define the null set for  $b$  as the union