

# **Chapter 7: Exploration in MAB**

## **(Continued)**

# Recap: MAB

**Interactive learning process:**

For  $t = 0 \rightarrow T - 1$

(# based on historical information)

1. Learner pulls arm  $I_t \in \{1, \dots, K\}$
2. Learner observes an i.i.d reward  $r_t \sim \nu_{I_t}$  of arm  $I_t$

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**Learning metric:**

$$\text{Regret}_T = T\mu^* - \sum_{t=0}^{T-1} \mu_{I_t}$$

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**The Explore and Commit Algorithm:**

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## The Explore and Commit Algorithm:

For  $k = 1 \rightarrow K$ : (# Exploration phase)

Pull arm- $k$   $N$  times, observe  $\{r_i\}_{i=1}^N \sim \nu_k$

Calculate arm  $k$ 's empirical mean:  $\hat{\mu}_k = \sum_{i=1}^N r_i/N$

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For  $t = NK \rightarrow T - 1$ : (# Exploitation phase)

Pull the best empirical arm, i.e.,  $I_t = \arg \max_{i \in [K]} \hat{\mu}_i$

# Recap: MAB

[Theorem] Fix  $\delta \in (0,1)$ , set  $N = \left( \frac{T\sqrt{\ln(K/\delta)}}{2K} \right)^{2/3}$ , with

probability at least  $1 - \delta$ , **Explore and Commit** has the following regret:

$$\text{Regret}_T \leq O\left(T^{2/3}K^{1/3} \cdot \ln^{1/3}(K/\delta)\right)$$

## Question for Today:

Can we design an algorithm that achieves  $\widetilde{O}(\sqrt{T})$  regret?

# Outline:

1. The upper Confidence Bound Algorithm
2. Analysis of UCB algorithm

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**We maintain the following statistics during the learning process:**

At the beginning of iteration  $t$ , for all  $i \in [K]$ , # of times we have tried arm  $i$ ,

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$$\text{i.e., } \hat{\mu}_t(i) = \sum_{\tau=0}^{t-1} \mathbf{1}\{I_\tau = i\} r_\tau / N_t(i)$$

## Recall the Tool for Building Confidence Interval:

[Hoeffding] Given a distribution  $\mu \in \Delta([0,1])$ , and  $N$  i.i.d samples  $\{r_i\}_{i=1}^N \sim \mu$ , w/ probability at least  $1 - \delta$ , we have:

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Thus, we know that for all iteration  $t$ , we have the for all  $i \in [K]$ , w/ prob  $1 - \delta$ ,

$$|\hat{\mu}_t(i) - \mu_i| \leq \sqrt{\frac{\ln(KT/\delta)}{N_t(i)}}$$

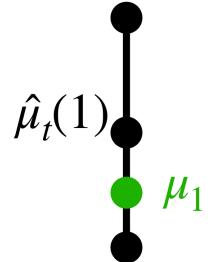
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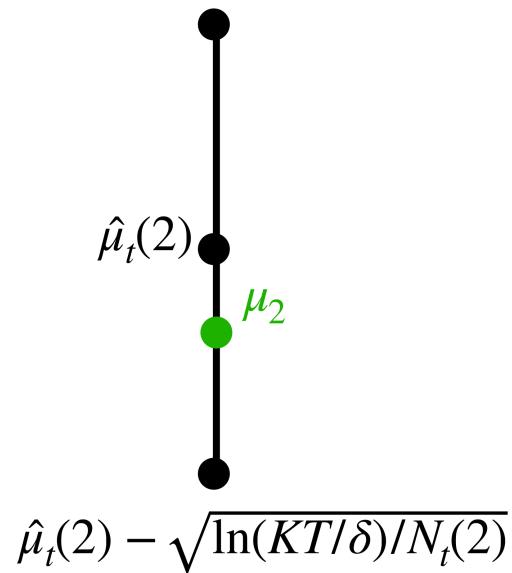
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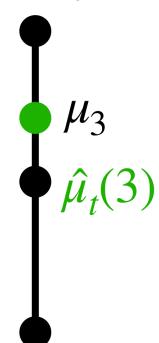
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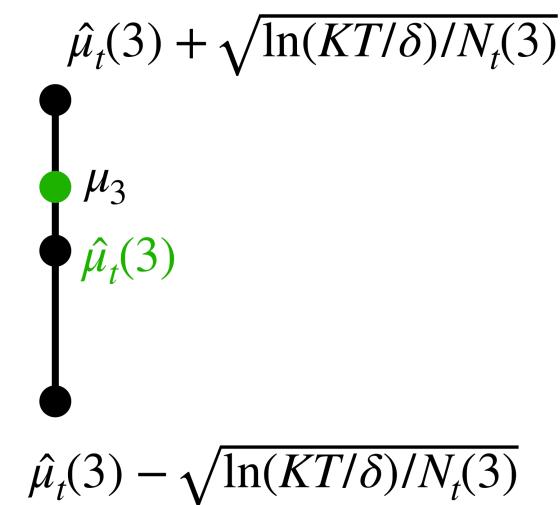
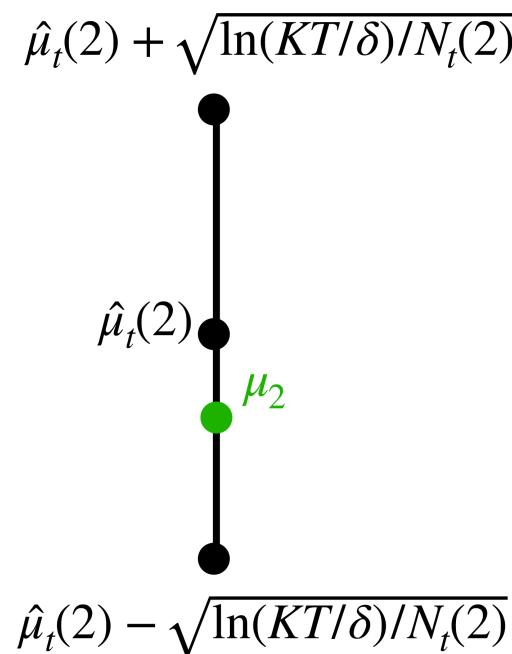
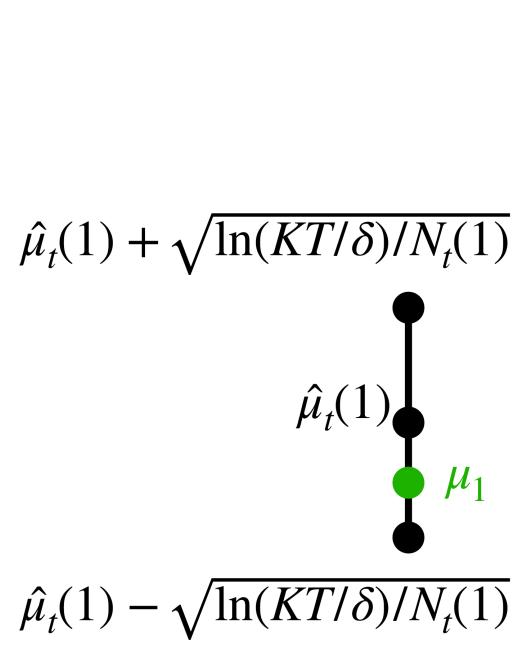
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Given the confidence interval, we pick arm that has the **highest Upper-Conf-Bound:**

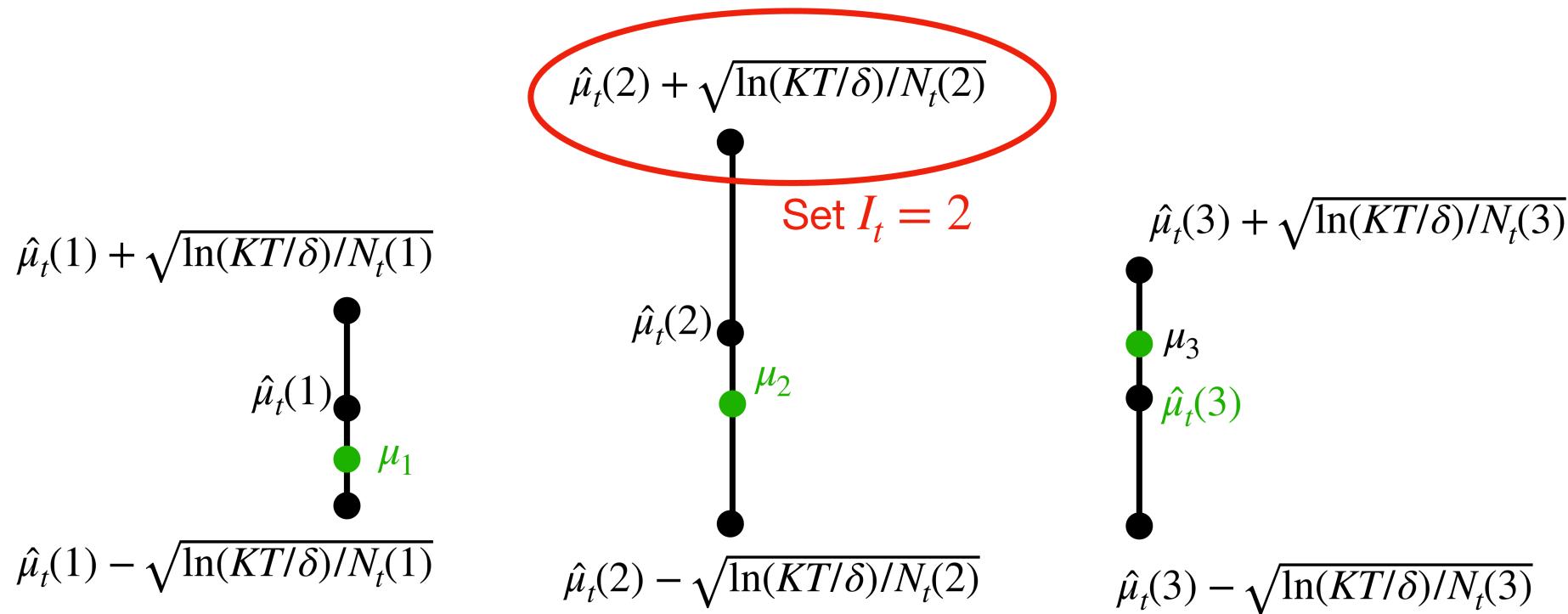
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For  $t = 0 \rightarrow T - 1$ :

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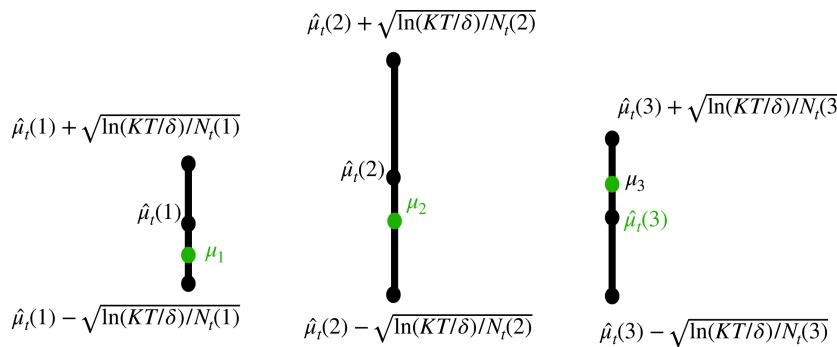
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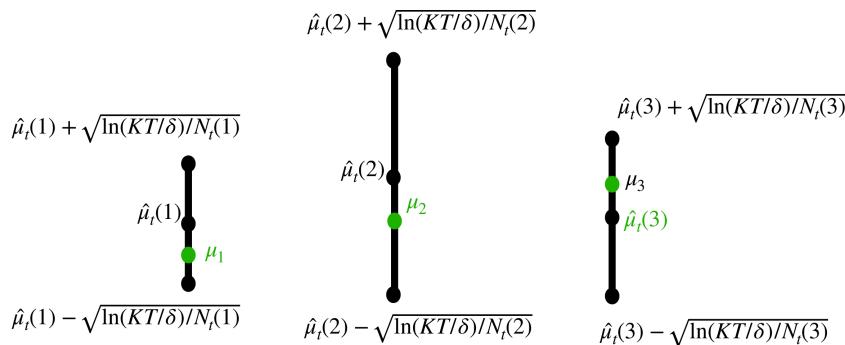


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**“Reward Bonus”:**  $\sqrt{\frac{\ln(KT/\delta)}{N_t(i)}}$

## Outline:

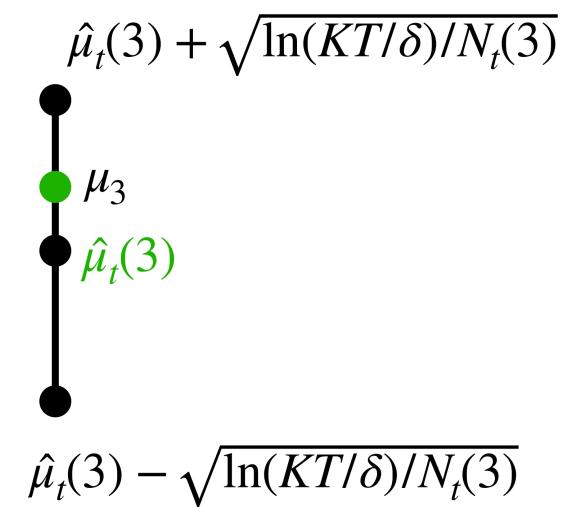
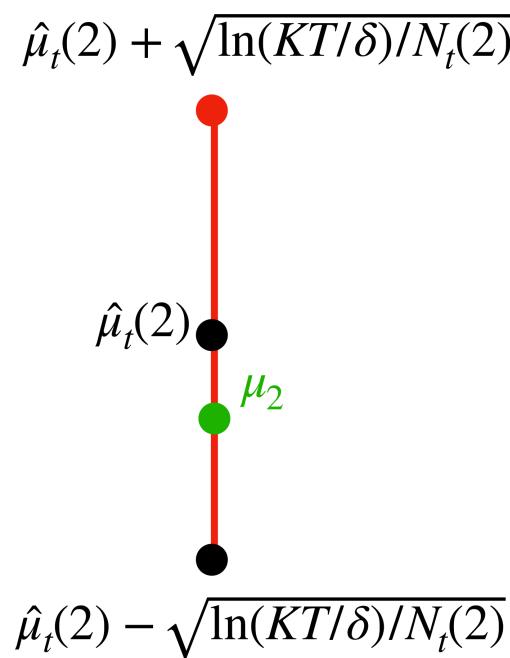
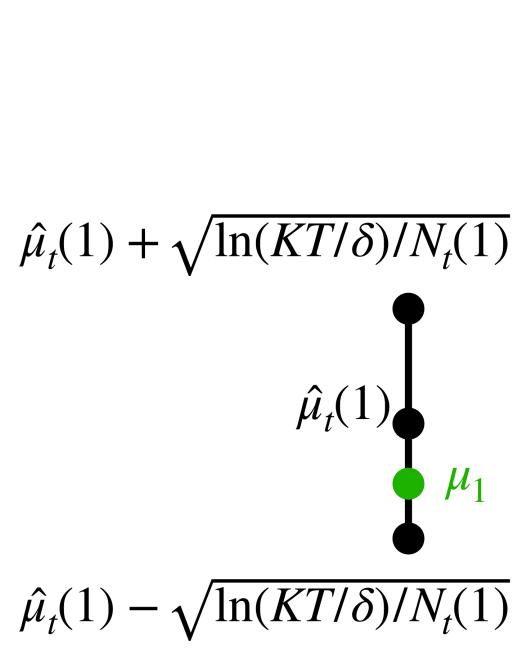


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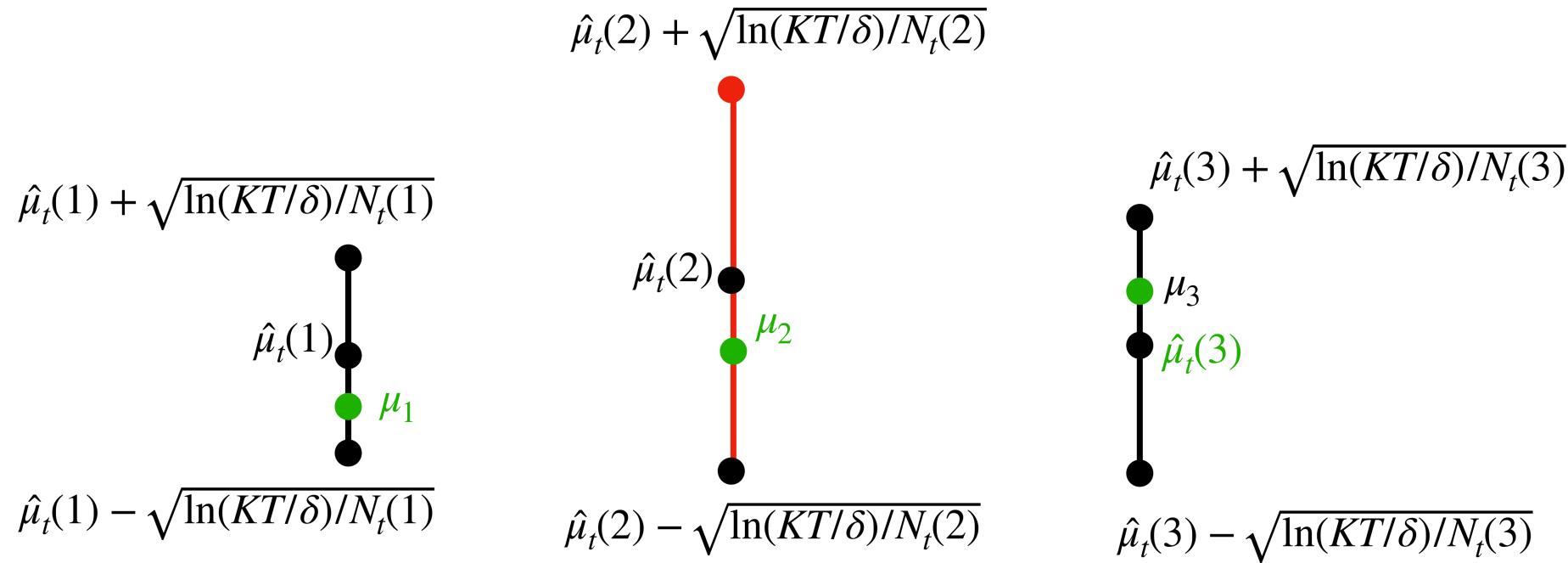
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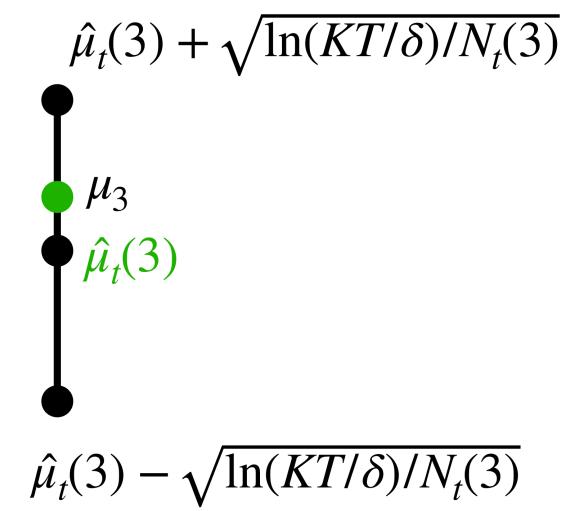
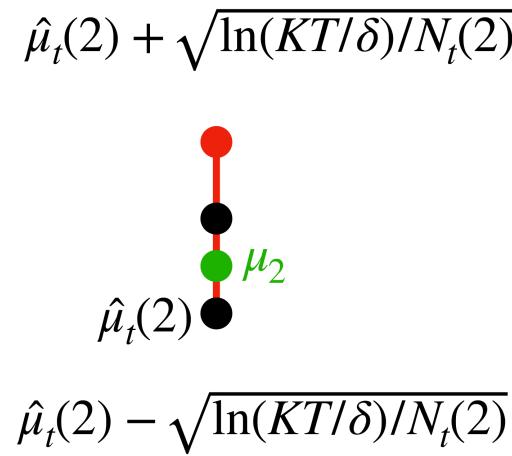
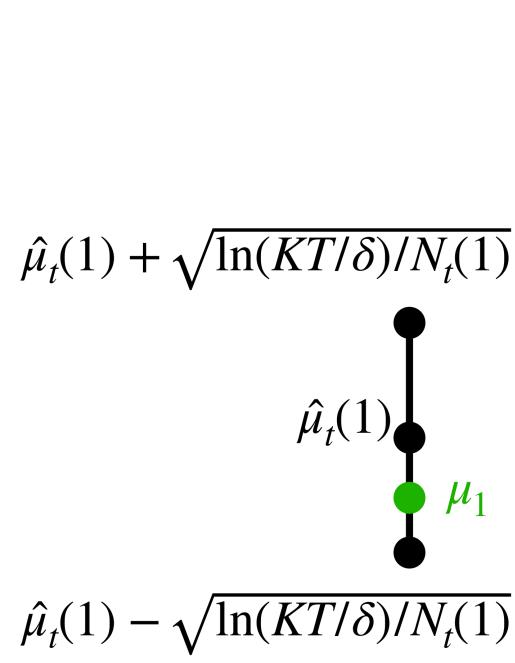
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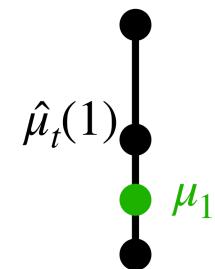


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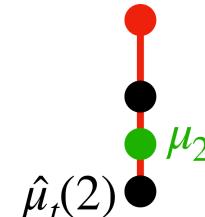
Case 2: it has low uncertainty, then it is simply a good arm, i.e., its true mean is high!

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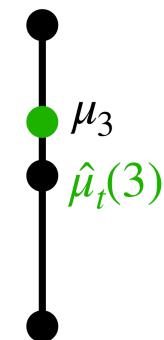


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# Explore and Exploration Tradeoff

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**Case 2:**  $I_t$  has small conf-interval, then it is simply a good arm, i.e., its true mean is pretty high!

Thus, we do exploitation in this case!

## Let's formalize the intuition

Denote the optimal arm  $I^* = \arg \max_{i \in [K]} \mu_i$ ; recall  $I_t = \arg \max_{i \in [K]} \hat{\mu}_t(i) + \sqrt{\frac{\ln(KT/\delta)}{N_t(i)}}$

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**Case 1:**  $N_t(I_t)$  is small  
(i.e., uncertainty about  $I_t$  is large);

We pay regret, BUT we **explore** here,  
as we just tried  $I_t$  at iter  $t$ !

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**Case 2:**  $N_t(I_t)$  is large, i.e., conf-interval of  $I_t$  is small,

Then we **exploit** here, as  $I_t$  is pretty good  
(the gap between  $\mu^*$  &  $\mu_{I_t}$  is small)!

## Let's formalize the intuition

Finally, let's add all per-iter regret together:

$$\begin{aligned}\text{Regret}_T &= \sum_{t=0}^{T-1} (\mu^* - \mu_{I_t}) \\ &\leq \sum_{t=0}^{T-1} 2\sqrt{\frac{\ln(TK/\delta)}{N_t(I_t)}} \\ &\leq 2\sqrt{\ln(TK/\delta)} \cdot \sum_{t=0}^{T-1} \sqrt{\frac{1}{N_t(I_t)}}\end{aligned}$$

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Lemma (optional):

$$\sum_{t=0}^{T-1} \sqrt{\frac{1}{N_t(I_t)}} \leq O(\sqrt{KT})$$

## UCB Regret:

[Theorem (informal)] With high probability, UCB has the following regret:

$$\text{Regret}_T = \widetilde{\mathcal{O}}\left(\sqrt{KT}\right)$$

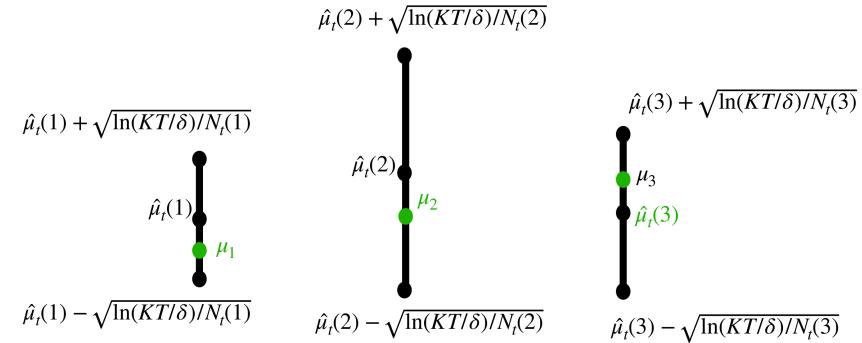
# Summary for Today:

**UCB algorithm: *Principle of Optimism in the face of Uncertainty***

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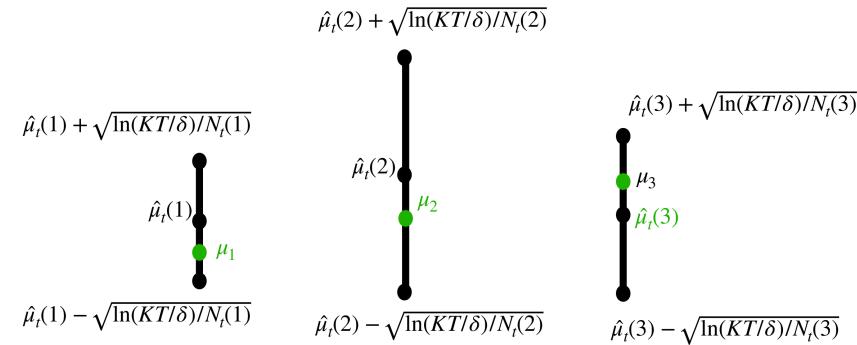
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**Analysis Intuition:**

Case 1: the arm  $I_t$  has high uncertainty (we explore)

Case 2: the arm  $I_t$  has low uncertainty, then it must be a near-optimal arm (i.e., exploit)

## Sample complexity vs. regret

$\alpha \in [0,1)$ :  $T^\alpha$  regret  $\rightarrow \epsilon^{\frac{1}{\alpha-1}}$  sample complexity

$\beta > 0$ :  $\epsilon^{-\beta}$  sample complexity  $\rightarrow T^{\frac{\beta}{\beta+1}}$  regret