YANYU ZHANG

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EDUCATION

University of California, Riverside Ph.D. in Electrical Engineering, Advisor: Wei Ren	Sep. 2021 - Mar. 2025
Boston University M.S. in Electrical and Computer Engineering, Advisor: John Baillieul	Sep. 2019 - May 2021
University of Detroit Mercy B.S. in Robotics	Sep. 2018 - May 2019
Beijing University of Chemistry Technology B.S. in Robotics	Sep. 2015 - Jun. 2018
RESEARCH EXPERIENCE	
University of California, Riverside Research Assistant, Cooperative Vehicle Networks Laboratory (COVEN)	Sep. 2021 - Mar. 2025 Riverside, CA
 Cooperative visual-inertial odometry with points and lines NeRF-aided visual-inertial odometry 	
 Infrastructure-less cooperative SLAM for multi-user AR Extrinsic calibration between camera and LiDAR 	
Boston University Research Assistant, Boston University Robotics Laboratory	Jan. 2020 - May 2021 Boston, MA
• Motion planning, Optical flow, SLAM	,
INDUSTRY EXPERIENCE	
VisionNav Robotics USA Inc. Staff Algorithm Engineer, SLAM	Apr. 2025 - Present Remotely
• 3DGS-Aided SLAM, LiDAR-Inertial-Visual Odometry, SLAM	
VisionNav Robotics USA Inc. Algorithm Engineer Intern, SLAM	Dec. 2024 - Mar. 2025 Remotely
• LiDAR-Inertial Odometry, SLAM	
Mitsubishi Electric Research Laboratories (MERL)	Jan. 2023 - Apr. 2023 Cambridge, MA
Research Intern	Camorage, MA

ACADEMIC SCHOLARSHIPS AND AWARDS

• Fellowship: 2021-2022 UCR Dean's Distinguished Fellowship Award

• Travel Award: 2024 ACC Student Travel Award

• Travel Award: 2023 CCTA Student Travel Award

TEACHING EXPERIENCE

University of California, Riverside Teaching Assistant

Sep. 2022 - Dec. 2024Riverside, CA

- Fall 2024: EE005 Circuits and Electronics (Undergraduate Course)
- Summer 2024: EE005 Circuits and Electronics (Undergraduate Course)
- Spring 2024: EE132 Automatic Control (Graduate Course)
- Fall 2023: EE230 Mathematical Methods for Electrical Engineers (Graduate Course)
- Summer 2023: EE005 Circuits and Electronics (Undergraduate Course)
- Spring 2023: EE132 Automatic Control (Graduate Course)
- Fall 2022: EE230 Mathematical Methods for Electrical Engineers (Graduate Course)

Boston University

Jan. 2021 - May 2021

Teaching Assistant

Boston, MA

• Spring 2021: EC500 Building Software (Graduate Course)

PUBLICATIONS

- [11] J. Xu, D. Wang, Y. Zhang and W. Ren, "Multi-robot Dual Reinforcement Learning Framework for Hybrid Motion Planning" in *Proceedings of the American Control Conference (ACC)*, New Orleans, LA, USA, May 26 - May 29, 2026. (Under Review)
- [10] Y. Zhang, J. Xu and W. Ren, "PLK-Calib: Single-shot and Target-less LiDAR-Camera Extrinsic Calibration using Pluker Lines" in *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Hangzhou, China, Oct. 19 Oct. 25, 2025.
- [9] Y. Zhang, D. Wang, J. Xu, M. Liu, P. Zhu and W. Ren, "NeRF-VIO: Map-based Visual-Inertial Odometry with Initialization Leveraging Neural Radiance Fields" in *IEEE International Conference on Automation Science and Engineering (CASE)*, Los Angeles, CA, USA, Aug. 17 - Aug. 21, 2025.
- [8] Y. Zhang, "Towards AI-Aided Multi-User AR: Cooperative Visual-Inertial Odometry Enhanced by Point-Line Features and Neural Radiance Fields" in Doctoral dissertation, University of California, Riverside, 2025.
- [7] Y. Zhang, M. Greiff, W. Ren and K. Berntorp, "Distributed Road-Map Monitoring Using Onboard Sensors" in *Proceedings of the American Control Conference (ACC)*, Toronto, Canada, Jul. 8 - Jul. 12, 2024.
- [6] J. Xu, P. Zhu, Y. Zhang and W. Ren, "Cooperative 3-D Target State Estimation and Active Tracking" in Proceedings of the IEEE Conference on Decision and Control (CDC), Marina Bay Sands, Singapore, Dec. 13 - Dec. 15, 2023.
- [5] Y. Zhang, P. Zhu and W. Ren, "PL-CVIO: Point-Line Cooperative Visual-Inertial Odometry" in Proceedings of the IEEE Conference on Control Technology and Applications (CCTA), Bridgetown, Barbados, Aug. 16 - Aug. 18, 2023.
- [4] C. Boretti, P. Bich, Y. Zhang and J. Baillieul, "Visual Navigation Using Sparse Optical Flow and Time-to-Transit" in *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA)*, Philadelphia, PA, USA, May 23 May 27, 2022.
- [3] Y. Zhang, J. Song and S. Li, "3D Object Detection and Tracking Using Monocular Camera in CARLA" in *Proceedings of the IEEE International Conference on Electro Information Technology (EIT)*, Mt. Pleasant, MI, USA, May 14 May 15, 2021.
- [2] Y. Zhang and O. Alshaykh, "5G Utility Pole Planner Using Google Street View and Mask R-CNN" in Proceedings of the IEEE International Conference on Electro Information Technology (EIT), Chicago, IL, USA, Jul. 31 - Aug. 1, 2020.

[1] Y. Zhang, X. Wang, X. Wu, W. Zhang, M. Jiang and M. Al-Khassaweneh, "Intelligent Hotel ROS-based Service Robot" in *Proceedings of the IEEE International Conference on Electro Information Technology (EIT)*, Brookings, SD, USA, May 20 - May 22, 2019.

PATENTS

[1] Y. Zhang, R. Duan, Z. Zhao, H. Jing, Intelligent Tennis Ball Picking Robot and Control System, China patent CN201820308664.8.

PROFESSIONAL ACTIVITIES

Membership

- IEEE Membership
- IEEE Robotics and Automation Society Membership
- IEEE Control Systems Society Membership

Paper Reviewer

- IEEE Robotics and Automation Letters (RA-L)
- IEEE International Conference on Robotics and Automation (ICRA)
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
- IEEE International Conference on Automation Science and Engineering (CASE)
- IEEE Transactions on Control Systems Technology (TCST)
- American Control Conference (ACC)
- IEEE Conference on Decision and Control (CDC)
- IEEE Conference on Control Technology and Applications (CCTA)