Project4 Constrained Least Squares Filtering

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实验内容

(1) Image blurring by Motion Model:

Input: ImageOrg & H, a=0.1, b=0.1 and T=1

Output: ImageBlur

(2) Constrained Least Squares Filtering

Input: ImageBlur & H, a=0.1, b=0.1 and T=1, you may

estimate $\sigma^2 + \mu^2$

Output: ImageOrg

实验原理

(1) Image blurring by Motion Model

图像退化函数:

$$H(u,v) = \frac{T}{\pi(ua+vb)} \sin[\pi(ua+vb)]e^{-j\pi(ua+vb)}$$

生成的退化滤波器如下图所示:



关键代码如下图所示:

```
1. %退化函数
2. a = 0.1;
3. b = 0.1;
4. T = 1;
5. H = zeros([m,n]);
6. for u =1:m
7.
       for v = 1:n
8.
           u_t = u-0.5*m-1;
9.
           v_t = v_0.5*n_1;
10.
           temp = (u_t*a+v_t*b)*pi;
11.
           if temp == 0
12.
                H(u,v) = 1;
13.
               H(u,v)=T/temp*sin(temp)*exp(-1i*temp);
14.
15.
           end
16.
       end
17.end
```

(2) Constrained Least Squares Filtering

$$F(u,v) = \left[\frac{H^*(u,v)}{|H(u,v)|^2 + \gamma |P(u,v)^2|} \right] G(u,v)$$

自动求解最优γ的主要步骤:

- ①指定γ的一个初始值
- ②计算||y||²
- ③若满足 $||\gamma||^2 = ||\eta||^2 \pm a$,则停止;否则,若 $||\gamma||^2 < ||\eta||^2 \pm a$,增大 γ ,若 $||\gamma||^2 > ||\eta||^2 \pm a$,减小 γ ,然后返回步骤 2.

关键代码如下:

```
1. p =zeros([m,n]);
2. p(1:3,1:3) = [0,-1,0;-1,4,-1;0,-1,0];
3. p = myfftshift(p);
4. P = myDFT2(p);
5.
6. eta square = sum(m*n*(MU.^2+var));
7. Fc = zeros([m,n,d]);
8. gamma = 0.001;
9. eps = 1e6;
10.r_square = 0;
11. H c = conj(H);
12.while(r_square<eta_square-eps | | r_square>eta_square+eps)
       Fc = (H_c./(H_c.*H + gamma*abs(P).^2)).*G;
14. R = G-H.*Fc;
15.
       r = real(myIDFT2(R));
16.
       r = myfftshift(r);
       r_{square} = sum(sum(r.^2));
17.
18.
       if gamma == 0
19.
           break:
20.
       elseif r_square<eta_square-eps
           gamma = gamma*1.05;
21.
22.
       else
23.
           gamma = gamma*0.95;
24.
25.
       display(gamma);
26.
       display(eta_square-eps);
27.
       display(r_square);
28.end
```

(3) 图像噪声估计

根据教材 5.2.4 节算法,图像噪声方差可以由合理的恒定值灰度值的一小部分来估计。通过计算灰度值归一化直方图,可以得到条带的均值和方差:

$$\bar{z} = \sum_{i=0}^{L-1} z_i p_s(z_i)$$

$$\sigma^2 = \sum_{i=0}^{L-1} (z_i - \bar{z})^2 p_s(z_i)$$

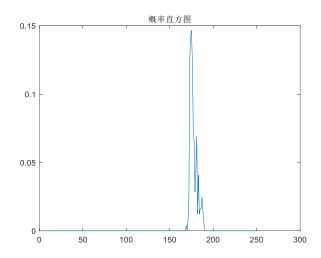
关键代码如下

```
1. Band = g(125:130,210:250);
2. [bm,bn] = size(Band);
3. figure;
4. imshow(uint8(Band));
5. title('小条带');
6. ps = zeros(1,256); %概率直方图
7. for i =1:bm
8. for j = 1:bn
           ps(Band(i,j)+1)=ps(Band(i,j)+1)+1;%统计每个灰度值出现的频率
10.
       end
11.end
12.ps = ps/(bm*bn);
13. mu = 0;
14. figure;
15.plot(0:255,ps);
16. title('概率直方图');
17. \mathbf{for} \ \mathbf{i} = 0:255
       mu = mu+i*ps(i+1); %计算均值
18.
19.end
20. var = 0;
21. for i = 0:255
       var = var+(i-mu)^2*ps(i+1); %计算噪声方差
22.
23.end
24.MU = mean(mean(Band-mean(Band(:)))); %计算噪声均值
```

选取的小条带如下如所示:

小条常

统计的概率图如下所示



实验结果

Task(1):

退化后的图像如下所示:



完整代码见 task1.m

Task(2):

使用估计的噪声方差均值迭代得到的γ值为: 0.0095, 此时的恢复效果 如下图所示:

恢复后图像 rocessing

另外手动指定一些γ的值, 观察恢复效果如下







γ 过大,恢复出来的图像比较模糊,γ太小,恢复出来的图像颗粒感就 比较重,应当适中。

完整代码见 task2.m