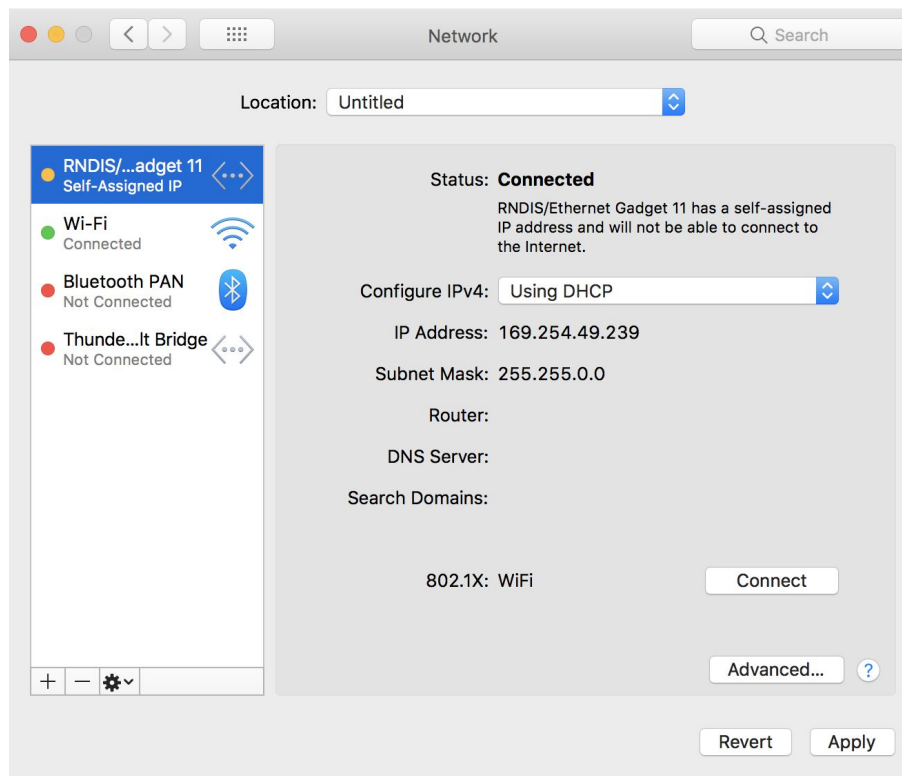


GelSight Drivers

Step 1: Connect to PC

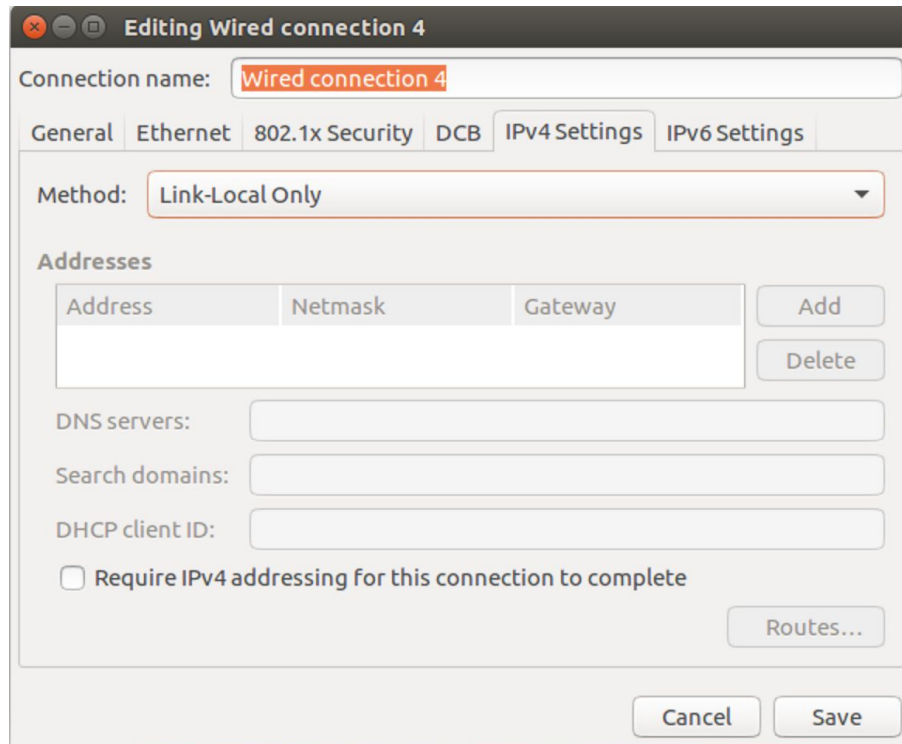
For **Mac**

- Connect the raspberry pi to the computer with USB; wait for 15 second for start
- Check **RNDIS/Ethernet Gadget** is connected in Network (if it doesn't show up, create a new network Location and apply. The RNDIS/Ethernet Gadget should show up automatically.)



For **Linux**

- Connect the raspberry pi to the computer with USB; wait for 15 second for start
- Open Network Settings -> USB Ethernet (or Wired connection) -> Edit -> "IPv4 Setting" -> Method -> select "**Link Local only**"
- Check RNDIS/Ethernet Gadget is connected in Network



Step 2: Get Raw Images

Preview from browser:

<http://rpigelsight.local:8080/?action=stream>

Install library:

```
pip install opencv-python open3d pybind11
```

Load from python:

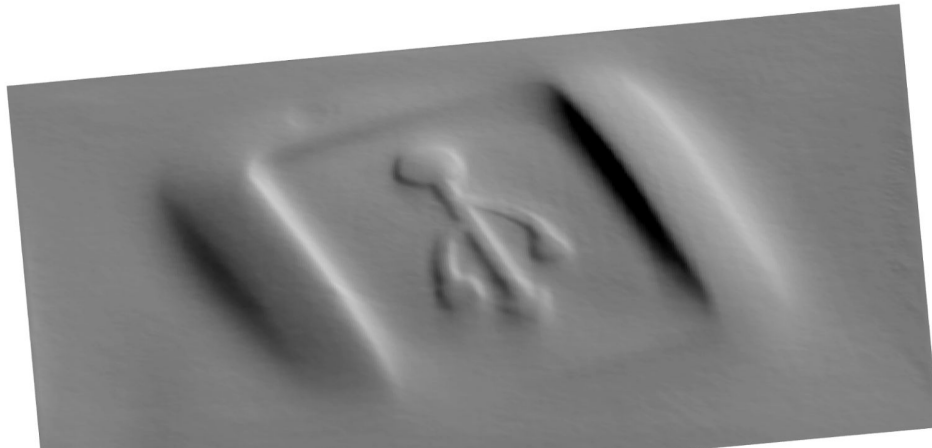
```
python gelsight_raw.py
```

Step 3: Get Estimated Depth

3D reconstruction:

```
python gelsight_3d.py
```

Examples:



3D Reconstruction of a USB plug

Step 4: Get Marker Displacement

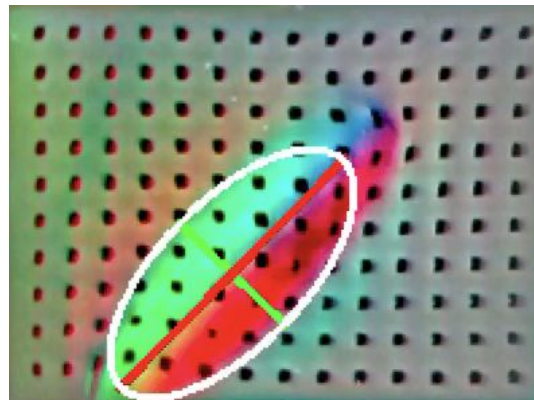
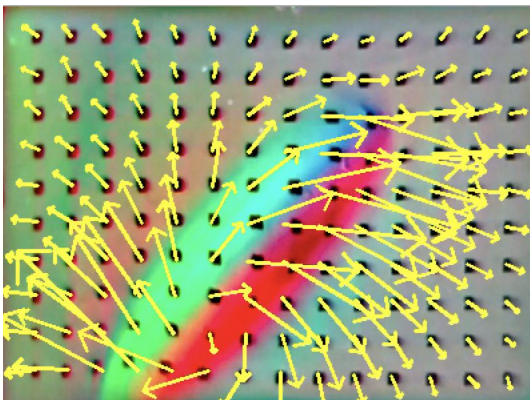
Compile marker tracking code:

```
cd src  
make
```

Marker tracking & pose:

```
python gelsight_examples.py
```

Examples:



Twisting a pen

Left: Marker Displacement; Right: Pose Estimation (for linear objects, like pen, cable)

Appendix:

Raspberry Pi Camera: The raspberry pi zero is preset to run **mjp_streamer** for streaming the video on start. The command is located in ~/.bashrc.

Connect to Raspberry Pi:

ssh pi@rpigelsight.local

password: gelsight