## STAGE 3

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# 实验内容

## 作用域栈

frontend/scope/scopestack.py

• 新建 ScopeStack 类

```
class ScopeStack:
   def __init__(self) -> None:
       // 作用域栈
       self.scopes = []
   // 将扫描到的作用域入栈
   def push(self, scope: Scope) -> None:
       self.scopes.append(scope)
   // 栈顶作用域出栈
   def pop(self) -> None:
       self.scopes.pop()
   // 返回栈顶作用域
   def top(self) -> Scope:
       return self.scopes[-1]
   // 遍历作用域栈, 检查符号是否先前声明过
   def lookup(self, name: str) -> Optional[Symbol]:
       for scope in self.scopes[::-1]:
           if scope.containsKey(name):
               return scope.get(name)
       return None
```

### 符号表构建

frontend/typecheck/typer.py

• 将上下文信息 ctx 改为作用域栈类

#### frontend/typecheck/namer.py

- 将上下文信息 ctx 改为作用域栈类
- Block

```
def visitBlock(self, block: Block, ctx: ScopeStack) -> None:
# 新建一个局部作用域并入栈
ctx.push(Scope(ScopeKind.LOCAL))
for child in block:
    child.accept(self, ctx)
# 出栈
ctx.pop()
```

Declaration

```
def visitDeclaration(self, decl: Declaration, ctx: ScopeStack) -> None:
    // 检查当前作用域是否声明过该符号
    if ctx.top().lookup(decl.ident.value) == None:
        var = VarSymbol(decl.ident.value, decl.var_t.type)
        ctx.top().declare(var)
        decl.setattr("symbol", var)
        if decl.init_expr != NULL:
            decl.init_expr.accept(self, ctx)
    else:
        raise DecafDeclConflictError(str(decl.ident.value))
```

Identifier

```
def visitIdentifier(self, ident: Identifier, ctx: ScopeStack) -> None:
    // 检查全作用域内是否声明过符号
    if ctx.lookup(ident.value) == None:
        raise DecafUndefinedVarError(str(ident.value))
    ident.setattr("symbol", ctx.lookup(ident.value))
```

#### 寄存器分配

backend/dataflow/cfg.py

• 深度遍历邻接表, 找到可达节点

```
stack = []
self.reachable = []
stack.append(0)
while stack:
    top = stack.pop()
    self.reachable.append(top)
    for node in self.links[top][1]:
        if node not in self.reachable:
            stack.append(node)
```

```
def iterator(self):
    reachableNodes = []
    for n in self.reachable:
        reachableNodes.append(self.nodes[n])
    return iter(reachableNodes)
```

# 思考题

