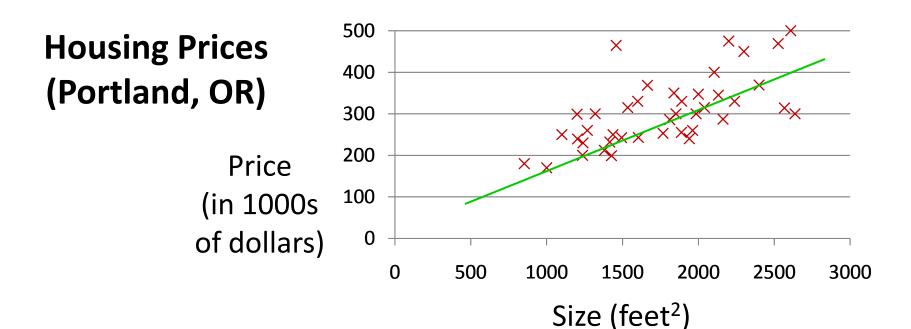


Machine Learning

Model representation



Supervised Learning

Given the "right answer" for each example in the data.

Regression Problem

Predict real-valued output

Training set of
housing prices
(Portland, OR)

Size in feet ² (x)	Price (\$) in 1000's (y)
2104	460 —
1416	232
1534	315 M=47
852	178
•••	•••

Notation:

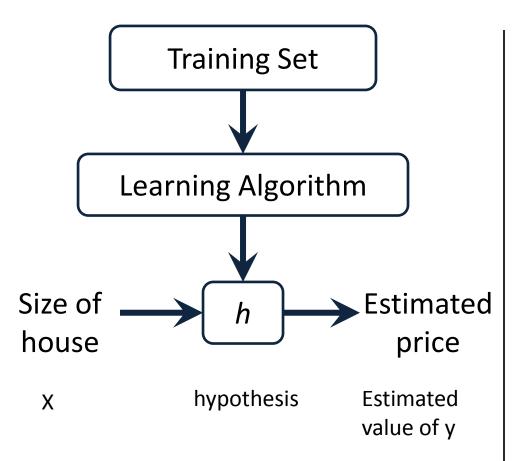
$$x^{(1)}$$
=2104

$$x^{(2)}$$
=1416

$$y^{(1)}$$
=460

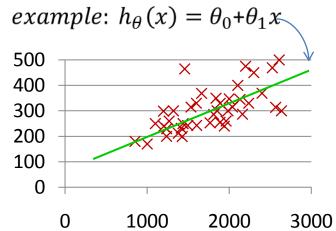
(x,y)-one training example
$$(x^{(i)}, y^{(i)})$$
-ith training example

$$(x^{(1)}, y^{(1)})$$
=(2104,460)

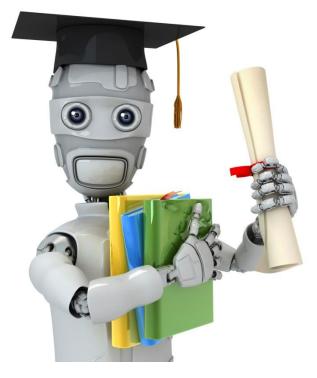


How do we represent *h* ?

h maps from x's to y's



Linear regression with one variable. Univariate linear regression.



Machine Learning

Linear regression with one variable

Cost function

Training Set

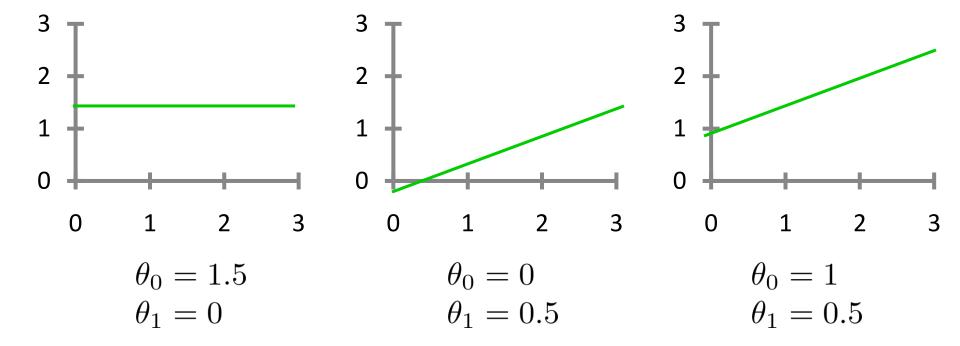
	Size in feet ² (x)	Price (\$) in 1000's (y)
•	2104	460
	1416	232
	1534	315
	852	178
	•••	•••

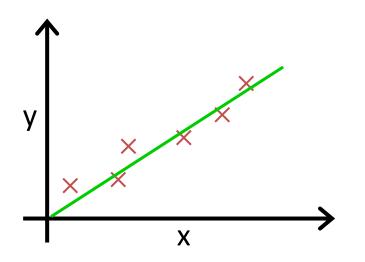
Hypothesis:
$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

 θ_i 's: Parameters

How to choose θ_i 's ?

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$



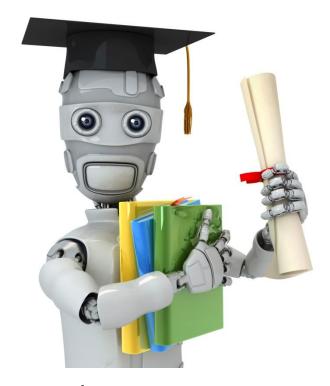


$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$

Idea: Choose θ_0, θ_1 so that $h_{\theta}(x)$ is close to y for our training examples (x,y)

$$\underset{\theta_0,\theta_1}{\text{minimize}} J(\theta_0,\theta_1)$$

Cost function



Machine Learning

Cost function intuition I

<u>Simplified</u>

Hypothesis:

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

Parameters:

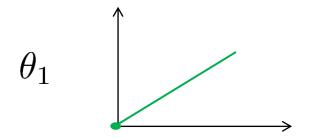
$$\theta_0, \theta_1$$

Cost Function:

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

Goal:
$$\underset{\theta_0,\theta_1}{\text{minimize}} J(\theta_0,\theta_1)$$

$h_{ heta}(x) = heta_1 x$ Set $heta_0 = 0$

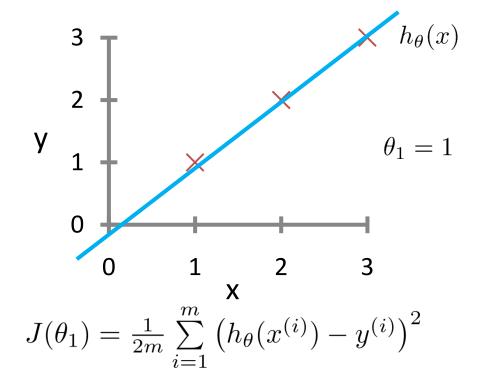


$$J(\theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

$$\underset{\theta_1}{\text{minimize}} J(\theta_1)$$

$$h_{ heta}(x)$$

(for fixed θ_1 , this is a function of x)



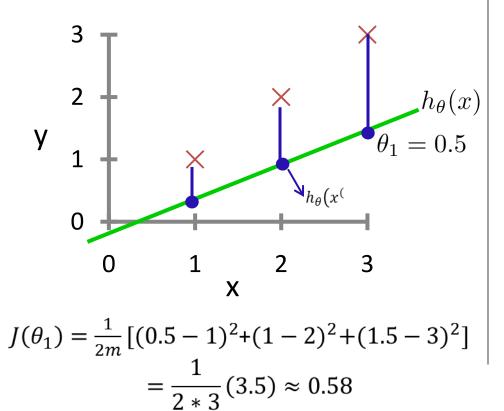
 $= \frac{1}{2m} \sum_{i=1}^{m} (\theta_1 x^{(i)} - y^{(i)})^2 = \frac{1}{2m} (0^2 + 0^2 + 0^2) = 0$

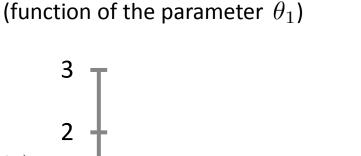
 $J(\theta_1)$ 0.5

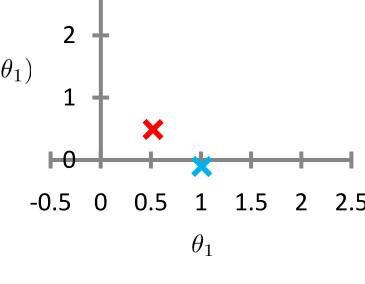
 $J(\theta_1)$

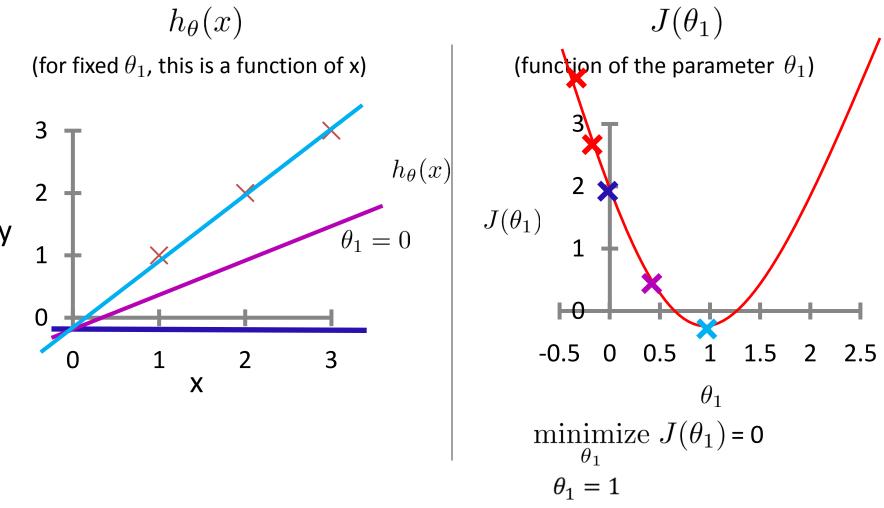
(function of the parameter θ_1)

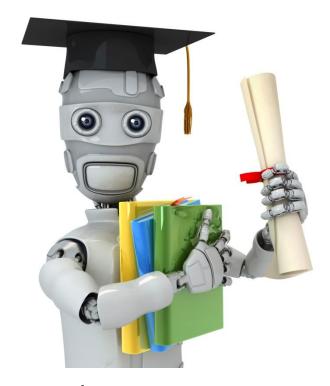
$$h_{ heta}(x)$$
 (for fixed $heta_1$, this is a function of x)











Machine Learning

Cost function intuition II

Hypothesis:
$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

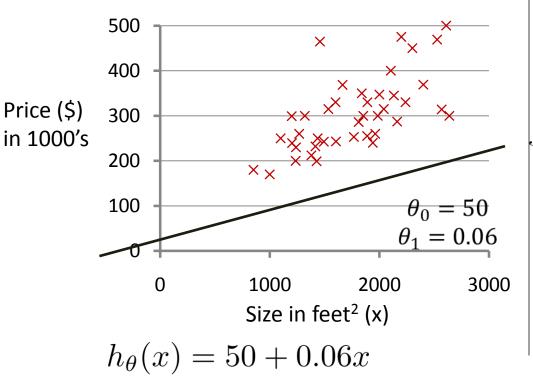
Parameters:
$$\theta_0, \theta_1$$

Cost Function:
$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

Goal:
$$\min_{\theta_0, \theta_1} \text{minimize } J(\theta_0, \theta_1)$$

$h_{\theta}(x)$

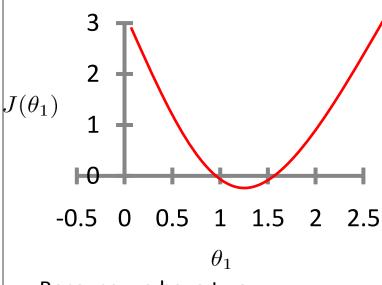
(for fixed θ_0, θ_1 , this is a function of x)



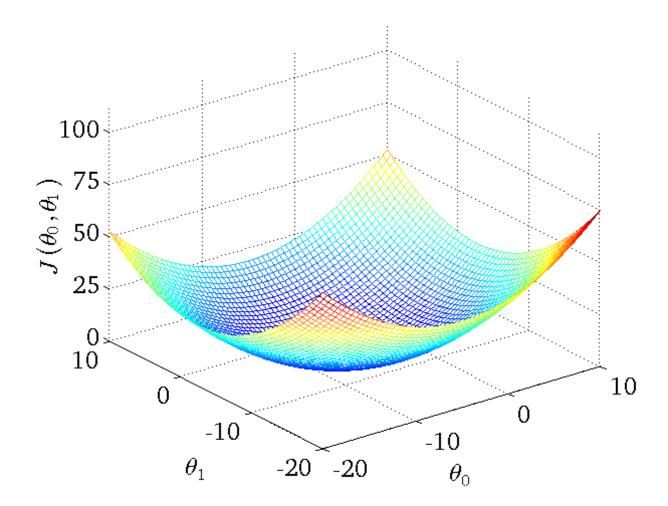
$$J(\theta_0,\theta_1)$$

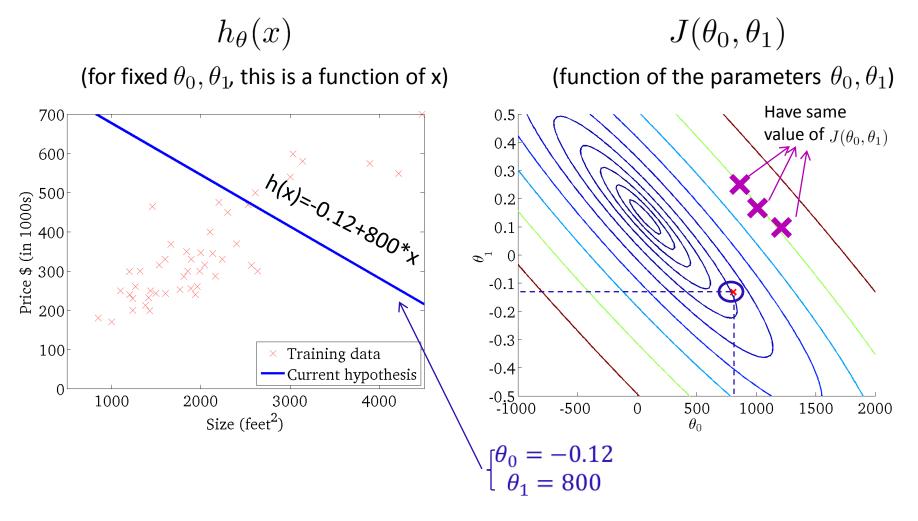
(function of the parameters $heta_0, heta_1$)

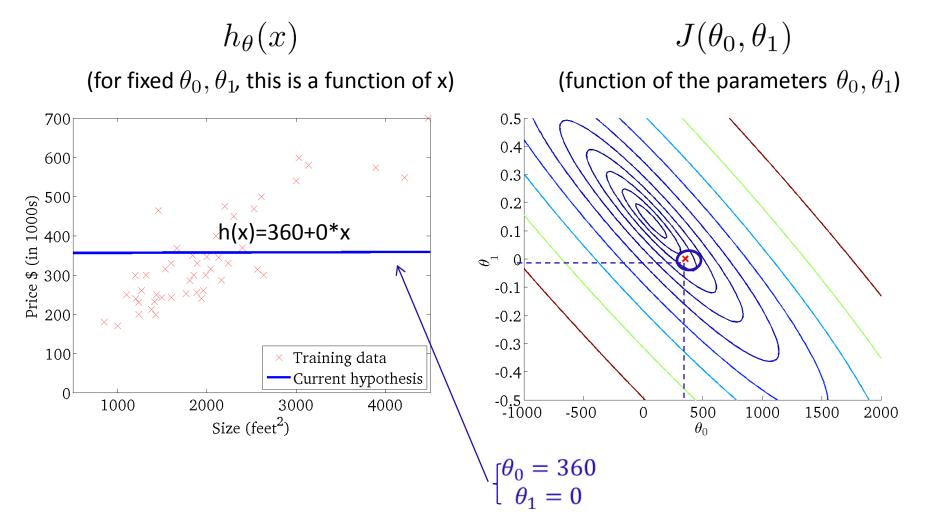
Cannot plot like this:



Because we have two parameters.

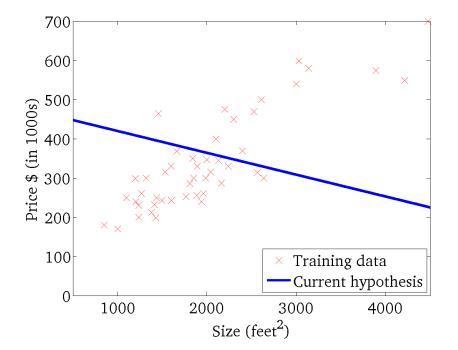






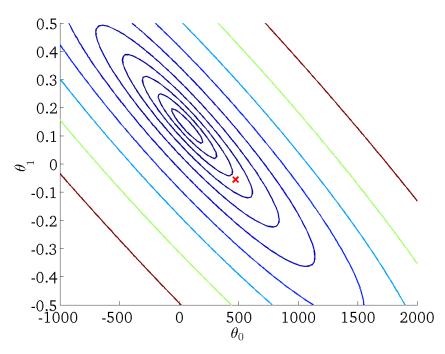


(for fixed θ_0 , θ_1 , this is a function of x)



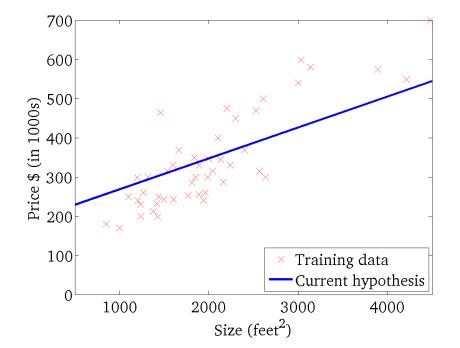
 $J(\theta_0, \theta_1)$

(function of the parameters $heta_0, heta_1$)



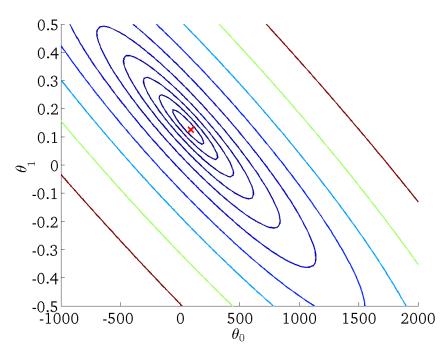


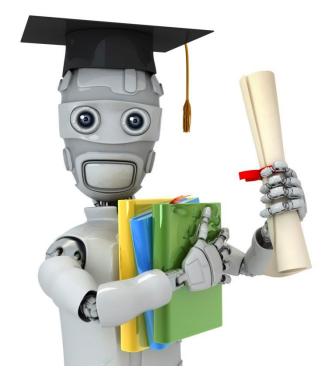
(for fixed θ_0 , θ_1 , this is a function of x)



 $J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)





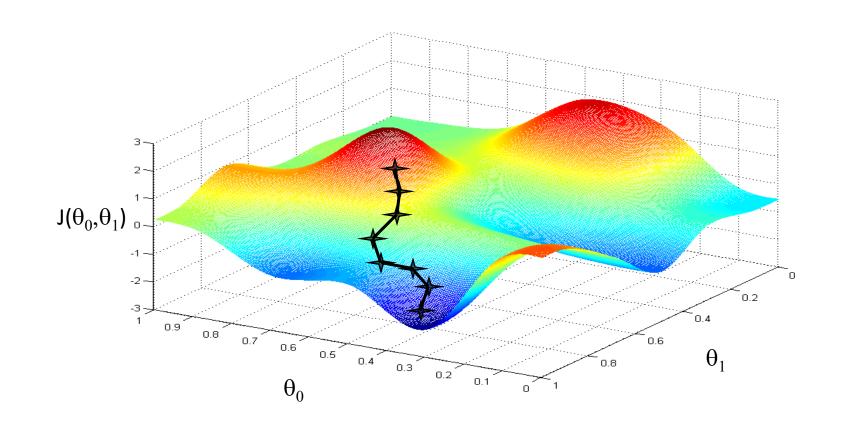
Machine Learning

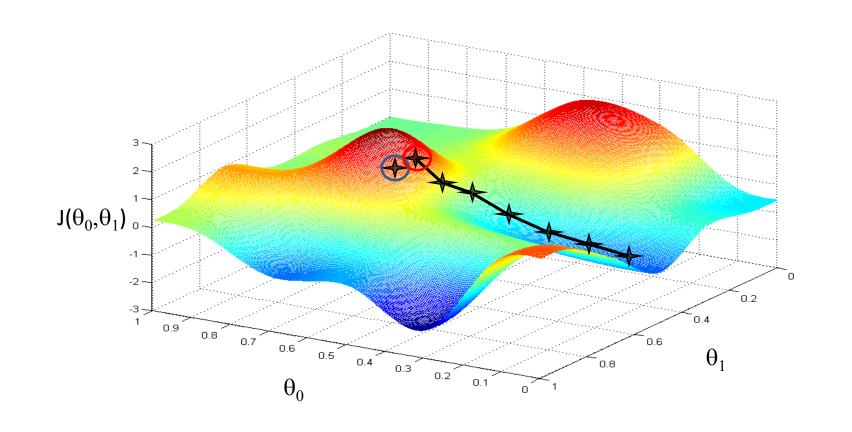
Gradient descent

Have some function $J(\theta_0,\theta_1)$ or $J(\theta_0,\theta_2,\theta_2,\dots,\theta_n)$ Want $\min_{\theta_0,\theta_1}J(\theta_0,\theta_1)$

Outline:

- Start with some θ_0, θ_1 e.g. $\theta_0 = 0, \theta_1 = 0$
- Keep changing $heta_0, heta_1$ to reduce $J(heta_0, heta_1)$ until we hopefully end up at a minimum





Gradient descent algorithm

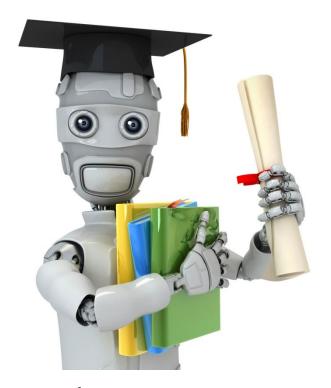
$$\begin{array}{l} \text{repeat until convergence } \{ \\ \theta_j := \theta_j - \bigcirc \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \ \ \text{(for } j=0 \text{ and } j=1) \\ \\ \} \\ \text{Learning rate} \end{array}$$
 Simultaneously update θ_0 and θ_1

Correct: Simultaneous update

$$\begin{aligned} & \operatorname{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) \\ & \operatorname{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1) \\ & \theta_0 := \operatorname{temp0} \\ & \theta_1 := \operatorname{temp1} \end{aligned}$$

Incorrect:

$$\begin{array}{l} \operatorname{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) \\ \theta_0 := \operatorname{temp0} \\ \operatorname{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1) \\ \theta_1 := \operatorname{temp1} \end{array}$$



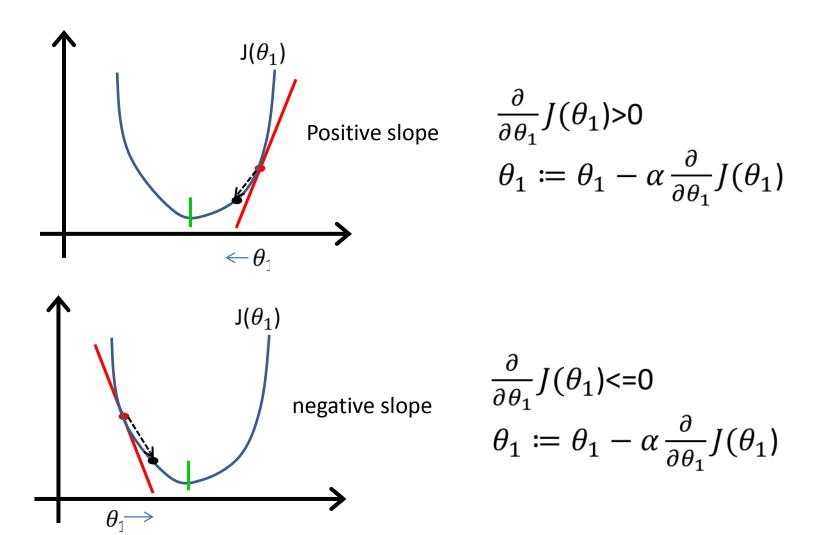
Machine Learning

Linear regression with one variable

Gradient descent intuition

Gradient descent algorithm

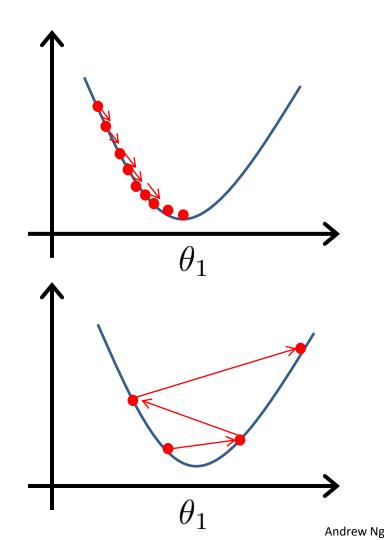
```
repeat until convergence { \theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \qquad \text{(simultaneously update } j = 0 \text{ and } j = 1) }
```



$$\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)$$

If α is too small, gradient descent can be slow.

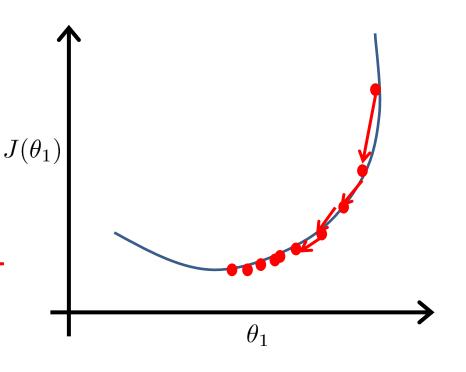
If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.

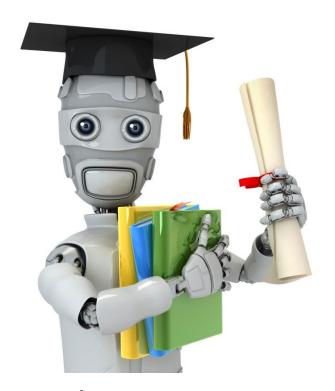


Gradient descent can converge to a local minimum, even with the learning rate α fixed.

$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$

As we approach a local minimum, gradient descent will automatically take smaller steps. So, no need to decrease α over time.





Machine Learning

Gradient descent for linear regression

Gradient descent algorithm

repeat until convergence { $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$ (for j = 1 and j = 0)

Linear Regression Model

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$

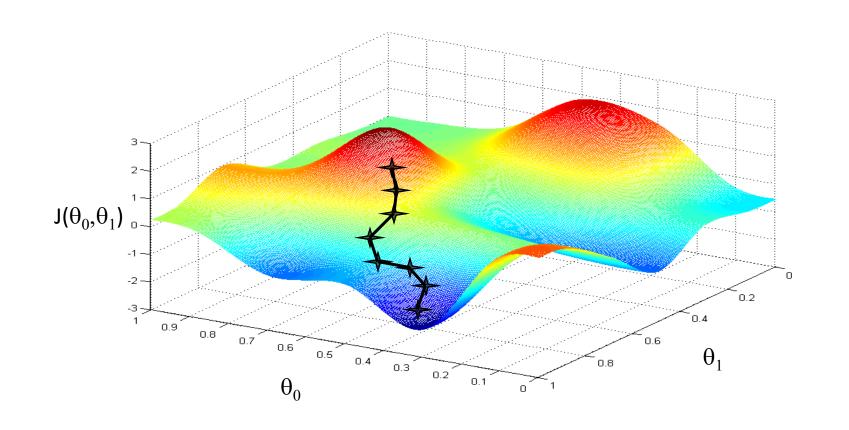
$$\frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) = \frac{\partial}{\partial \theta_j} \frac{1}{2m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)})^2$$
$$= \frac{\partial}{\partial \theta_j} \frac{1}{2m} \sum_{i=1}^m (\theta_0 + \theta_1 x^{(i)} - y^{(i)})^2$$

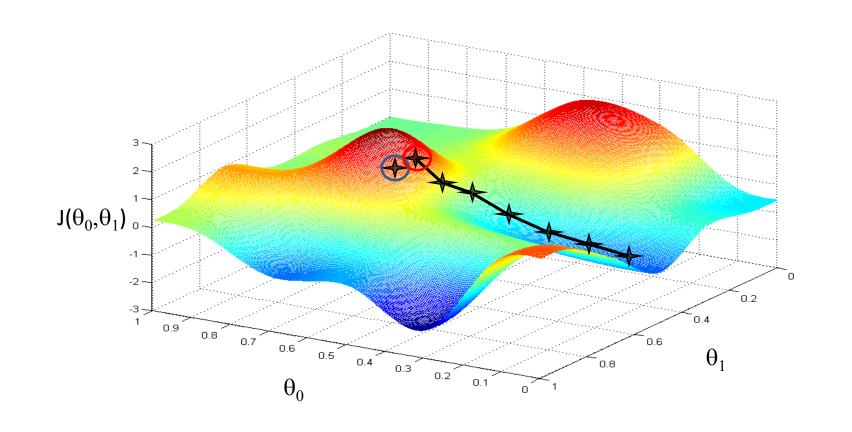
$$j = 0 : \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) = \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})$$

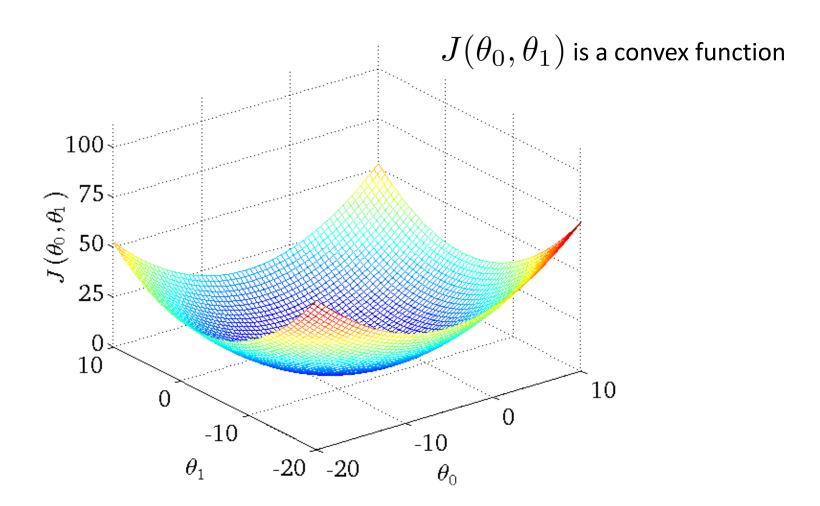
$$j = 1 : \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1) = \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) * x^{(i)}$$

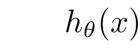
Gradient descent algorithm

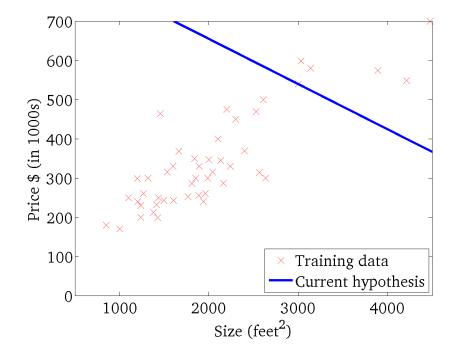
repeat until convergence { $\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_\theta(x^{(i)}) - y^{(i)} \right) \quad \text{update} \\ \theta_0 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_\theta(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)} \quad \text{simultaneously}$ }



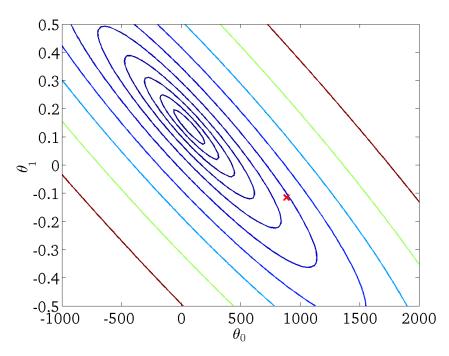


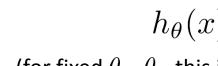


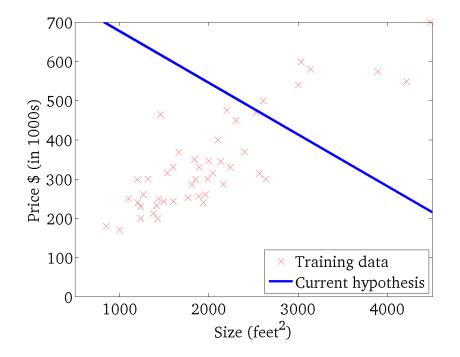




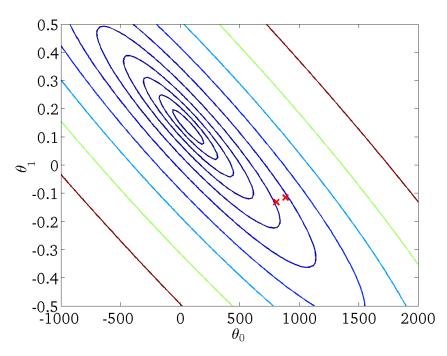
 $J(\theta_0, \theta_1)$



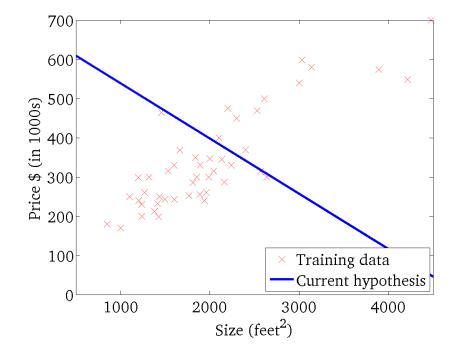




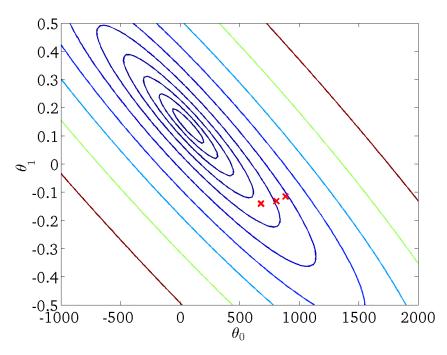
 $J(\theta_0, \theta_1)$



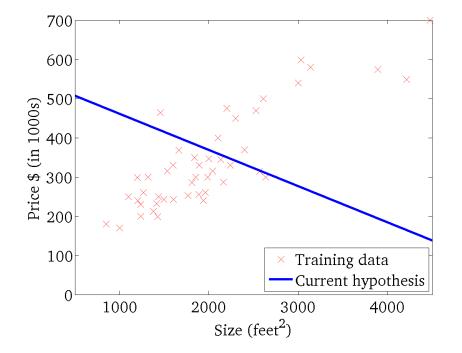




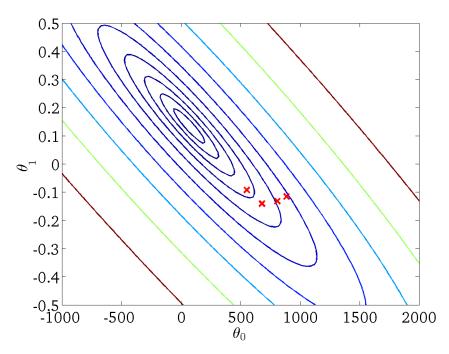
 $J(\theta_0, \theta_1)$



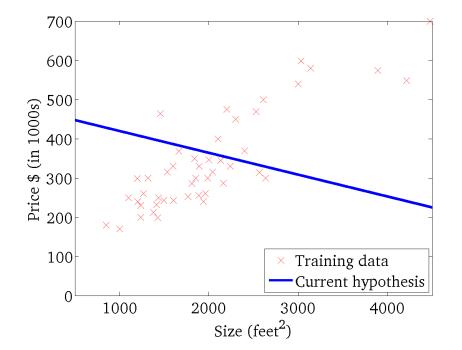




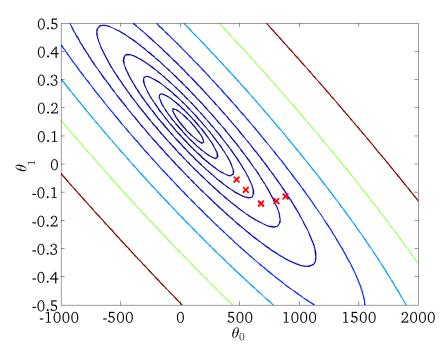
 $J(\theta_0, \theta_1)$



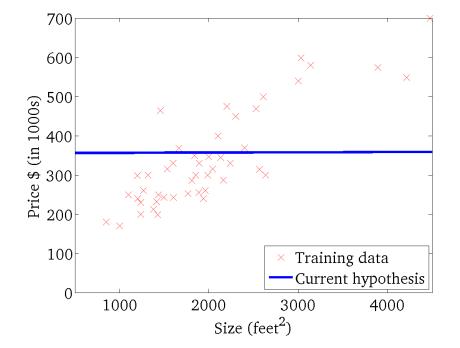




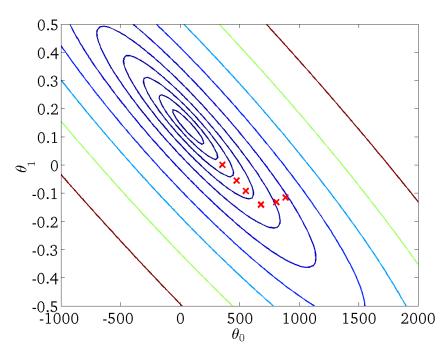
 $J(\theta_0, \theta_1)$



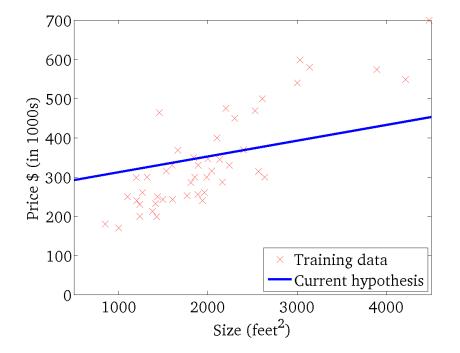




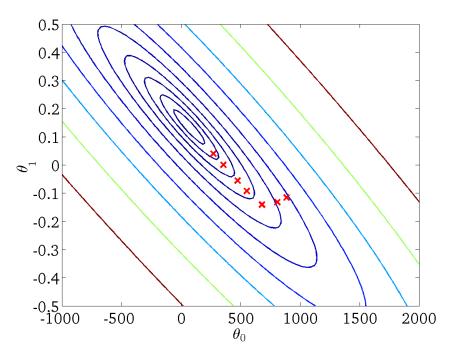
 $J(\theta_0, \theta_1)$



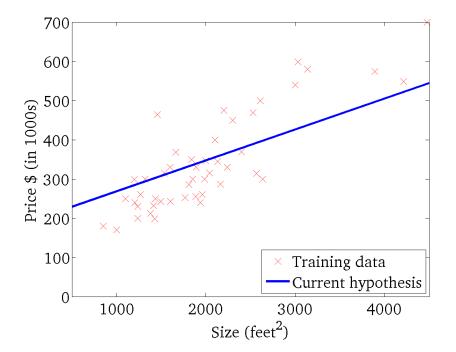




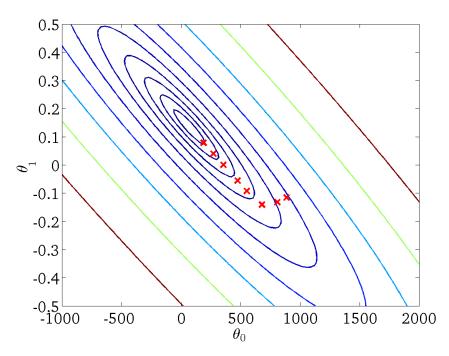
 $J(\theta_0, \theta_1)$



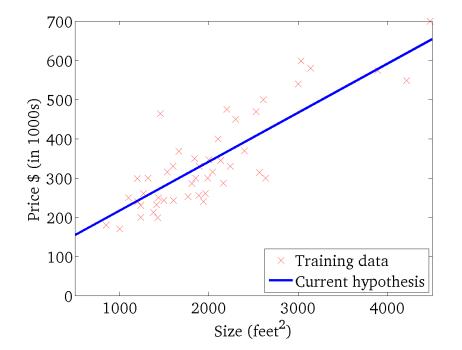




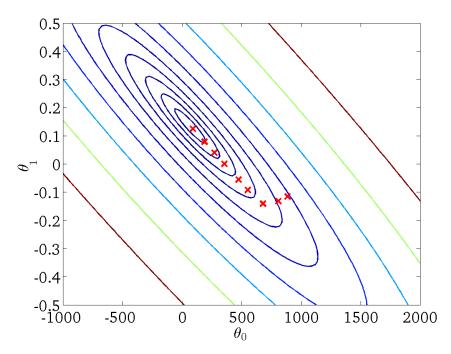
 $J(\theta_0, \theta_1)$







 $J(\theta_0, \theta_1)$



"Batch" Gradient Descent

"Batch": Each step of gradient descent uses all the training examples.

$$\sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^{2}$$